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Author

Lampert, C.M.

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A SOLAR TEST COLLECTOR FOR EVALUATION OF BOTH SELECTIVE AND NON-SELECTIVE ABSORBERS

Carl M. Lampert and Jack Washburn

Materials and Molecular Research Division, Lawrence Berkeley Laboratory and Department of Materials Science and Mineral Engineering, College of Engineering; University of California Berkeley, California 94720

ABSTRACT

A solar test collector was designed for the testing of thermally absorbing coatings under controlled conditions. The design consisted of a collector fed by a controlled temperature fluid within the range of 25-90°C (77-194°F). This temperature was maintained by a custom electronic controller. A small variable flow pump circulated water through three collector pipes at selected flow rates. Strip heaters coupled with a differential temperature controller compensated for edge losses associated with small collectors. Detailed design and operation data were presented and three black chrome and one non-selective absorber were analyzed in detail by test collector measurements. Results showed Efficiencies as high as 77% and 75% ($\Delta T = 0$) were obtained respectively for 1.0 µm black chrome on copper and nickel plated steel. The lowest loss coefficients were about 3.8 W/m²⁰C for all black chrome/metal surfaces with the highest being 8.4 W/m²⁰C for the black paint/metal sample.

1. EXPERIMENTAL APPARATUS AND PROCEDURES

A solar test collector was designed so that certain collector parameters could be held constant or controlled and yet different coatings could be tested. This design allows different types of selective and non-selective surfaces to be tested and evaluated in terms of collection efficiency under various operating temperatures and flow rates. Results for various Chromonyx coatings will be presented later and compared with those for a black painted surface.

In this study the collector was used to compare different types of black chrome (Chromonyx), supplied by Marshaw Chemical Co., and a black painted surface. These surfaces are representative of both selective and non-selective coatings and optical values of these coatings can be correlated to test collector data.

The main components of the collector consist of a body and cover, which houses three absorber pipes; a controlled temperature water bath; and a variable-flow pump. The collector body is designed to permit easy removal of collector pipes. The body can be set any desired tilt angle with respect to the sun, to suit the season of the year. The collector pipes consist of a metallic material (e.g., copper or steel), although not a stringent requirement, coated with a selective or non-selective surface. Of the three parallel pipes, the center pipe is the critically controlled and monitored one. The purpose of the two outside pipes is to restrict the amount of heat lost from the sides of the central pipe. Furthermore, controlled temperature heating stripes are placed under the two outside pipes to reduce overall edge losses. In this fashion, a small collector can simulate large collector surroundings along the central pipe. This simulation is achieved by a differential temperature controller which maintains constant temperatures at all pipe outlets by turning on strip heaters when required. Across the central pipe both inlet and outlet temperatures are recorded with better than one degree (^OC) accuracy.

The collector is fed by a controlled temperature bath which supplies a fluid at a set, adjustable temperature in the range 25-90°C. This temperature is maintained by a custom electronic controller. A small variable-flow pump circulates water through three collector pipes according to a specified but adjustable flow rate. The fluid from the collector is passed into a cooling bath and is recirculated to the controlled temperature water bath. Simultaneous measurements are made of solar radiation, ambient temperature, wind direction and velocity. The flow chart for the collector, showing the significant features described, is depicted in Fig. 1. A photograph of complete test apparatus is shown in Fig. 2. A detailed account of the total collector design is described elsewhere [1].

1.1. Controller System

The controller makes decisions and operates various heaters to compensate for outer collector pipe losses, and to regulate inlet water temperature.

The strip heater control system obtains its signals from the collector pipe outlet thermocouples. The outer pipe signals are compared to that of the central test pipe. Depending upon the difference in signals the heaters will turn on or off independently.

Another circuit controls the water heater element. In this case the thermocouple signal is obtained at the inlet of the central pipe. This signal is compared to a set, adjustable voltage, calibrated in degrees. When the inlet temperature is lower than the set temperature, the water heater will operate. When the inlet temperature appears the same or greater (probably it will never greater than the set temperature) the heater will be off. The complete control diagram is depicted in Fig. 3. The accuracy of the controller is about +0.5°C for each channel.

2. EXPERIMENTAL COLLECTOR RESULTS

The test collector results were obtained under clear sky conditions with wind velocity below 1.50 m/s from the northwest or west. Also, these results were obtained with solar radiation typically between approximately 600 to 1000 W/m^2 and with steady flow rates (for water) within the range of 2.45-49.2 L/hr. Typical inlet temperatures of 30, 35, 40, 45, 50 and 60°C were used for the tests.

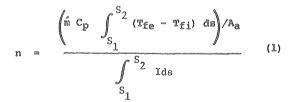
The types of surfaces tested were three selective absorbers of the Chromonyx black chrome type and one non-selective absorber of a commercial black spray paint. The non-selective absorber is made by Cal Custom/Hawk Company and it contains 4.8% black iron oxide in a modified silicone resin.

The designations and specifications of the absorbers are as follows:

- Rl 1.0 micron of black chrome on 12.7 microns of nickel on cold rolled mild steel.
- R16 1.0 micron of black chrome on mild steel.
- R9 1.0 micron of black chrome on copper.
- HP1 a thick coating (several hundred microns) of heat proof black paint on galvanized steel.

2.1 Calculation of Collector Efficiency

Another equivalent expression for instantaneous efficiency which is used for experimental data (a NBS proposed standard) is the following equation [2].



where S_1 and S_2 represent limits of a time interval such as 0, 15-30 minutes;

 \mathbb{A}_{a} = the frontal area, receiving or aperture area (\mathbb{m}^{2}) ;

 C_{D} = the heat capacity of the fluid (J/kg ^{O}C);

- \dot{m} = the mass flow rate (kg/sec).
- T_{fi} = inlet fluid temperature (^OC) T_{fe} = exit fluid temperature (^OC)
- I solar radiation per unit time per unit area (w/m²)

In Figures 4a-4d are shown the test collector results for the aforementioned samples. All lines are curve fit by a linear regression least squares approximation to represent the relationships of each of the curves; they are plotted in Fig. 5.

The equations, slopes and intercepts are shown in Table 1.

2.2 Calculation of Reflectance Parameters

By integration of $(1-r_W)$ where r_W is near-normal hemispherical spectral reflectance, over the solar spectrum the integrated absorptance (a_i) is obtained. Also, by integration of $(1-r_W)$ over the 100^OC blackbody spectrum the integrated emittance (e_i) is obtained. The higher the ratio of these values (a_i/e_i) the greater the selectivity.

The integrated results are shown in Table 2 for 20° C measurements. From these results one can calculate the effective transmission absorption product (ta)_e for the test collector. Also, the collector performance coefficient (F') and the loss coefficient (U_L) may be obtained [3]. These results are summarized in Table 3.

2.3 Discussion of Results

In some cases the scatter in the data points is representative of a situation one might expect for experimental conditions which would vary slightly with time. A true but very difficult procedure would be to control all collector parameters, except for insolation and resultant temperature differences, in such a way so they are time invariant. This might be achieved by the use of a completely simulated (fixed environment) collector.

An overall view of the data reveals that for the selective black chrome surface the data points for efficiency are mainly between 50-70%. These values indicate, under near optimal conditions, the efficiency at which the collector usually operates. The non-selective paint has 40-60% efficiency under the same conditions. The efficiency on the y-intercept is not a realistic operating point because the collector is at the ambient temperature ($\overline{T} = T_{g}$ or $\Delta T=0$). Frequently, this intercept value is mistakenly reported as optimum efficiency.



In reality, the curve fit for the data points is not linear except in the central region. Near the region of the y-intercept the curve should flatten out and in the region of the x-intercept the curve should dip downward. These effects occur because the loss coefficient (U_L) is a function of temperature. At higher temperatures the loss coefficient increases and at lower temperatures it decreases. The slope ratio between black paint and black chrome is approximately 2, which indicates that black paint will not perform as efficiently as black chrome at a given temperature. Also, the difference in x-axis intercept shows that black chrome will function at higher temperatures than black paint.

The black chrome plated copper pipe exhibits the highest net efficiency. This effect is due partially to the difference in thermal conductivity between copper and steel. Of the pipes tested, the copper pipe has approximately 2.5 the thermal conductance of the steel pipe. Choosing copper rather than steel for pipe material would depend upon the relative cost of materials and collector fluid flow rates (absorber heat transfer rate).

The effect of nickel plating steel creates only a slight rise in both the loss coefficient and efficiency of the absorber over that of black chrome directly on steel. (See Fig. 5).

3. CONCLUSIONS

A solar test collector has been designed and constructed which was used to measure the efficiency of four collector surfaces -- three selective black chrome and one non-selective black paint. This collector was compensated for edge losses and measures differential pipe temperatures with 1ºC accuracy. The absolute uncertainty of the collector measurements of efficiency are about 10% (for example a value of 60% efficiency could vary from 54-66%), while it has a few percent uncertainty in reproducibility and is limited by the accuracy of the mass flow rate measurement. The collector typically operates at low flow rates (0-49 L/hr) up to temperatures of 100°C at atmospheric pressure. The collector is designed so collector pipes may be removed with ease and it has the ability to regulate the fluid inlet temperatures within 1°C accuracy. The inlet temperatures are adjustable (25-90°C) and are maintained by an electronic controller. The collector includes a manual tilting stand for orientation to the sun.

The four surfaces tested (R1, R9, R16 and MP1) are representative of a range of possible combina-

tions. The loss coefficients for these four surfaces show that black paint has about a factor of two times greater loss than for the black chrome samples. The loss coefficient for the black chrome samples was about the same--3.8 W/m² ^OC for all three. Black chrome on copper was the most efficient of the surfaces tested; probably, this is due to reflectance and high thermal conductivity of copper. Black chrome on nickel-plated steel and steel substrates had comparable properties. The effect of nickel plating steel accounted for only a 0.04 rise in efficiency for the absorber. Nickel plating may not be cost effective in light of this result. For the low flow rates at which the collector operated, the effect of the high thermal conductivity of copper is not a greater as it could be in promoting high heat transfer rates.

Spectral reflectance measurements are used to obtain optical parameters such as solar absorptance and infrared emittance. The best solar selectivity characteristics were exhibited by 1.0 micron of black chrome on copper $(a_i/e_i = 18.5)$. Almost all combinations showed good selectivity. The effect of the nickel layer was marginal in promoting higher selectivity for the steel samples and it degraded selectivity on the copper samples.

4. ACKNOWLEDGMENTS

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5. REFERENCES

- C. M. Lampert, J. Washburn, LBL-6974, July 1978.
- [2] NBS-National Bureau of Standards, U.S. Dept. of Commerce, Development of Proposed Standards for Testing Solar Collectors and Thermal Storage Devices, Technical Note, 899, 1976.
- [3] J. A. Duffie and W. A. Beckman, Solar Energy Thermal Processes, Wiley, New York, 1974.

Туре	Figure Number	Equation	Correlation Coefficient	
Rl	8a	= -3.6x + 0.75	$r^2 = 0.992$	
R16	8b	= -3.3x + 0.71	$r^2 = 0.973$	
R9	8c	= -3.5x + 0.77	$r^2 = 0.979$	
HP1	8đ	= -6.8x + 0.66	$r^2 = 0.971$	

Table 1. Collection efficiency parameters of Figs. 4 and 5.

Туре	Slope (-F'UL) (W/ ^O Cm ²)	y Intercept (F'(ta) _e)	x intercept (^O Cm ² /W)
Rl	-3.6	0.75	0.208
R16	-3.3	0.71	0.214
R9	-3.5	0.77	0.222
HPl	-6.8	0.66	0.097

Table	2.	Integrated	reflectance	parameters.

	Rl	R9	R16	HPl	
ai	0.958	0.942	0.92	0.95	
ei	0.070	0.051	0.070	0.832	
a _i /e _i	13.7	18.5	13.1	1.14	

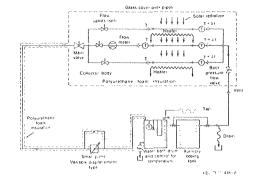


Fig. 1. Solar test collector flow chart.

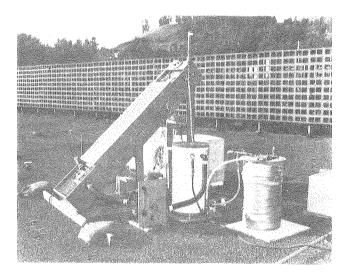


Fig. 2. Solar test collector in operation, side view. CBB 770-9662

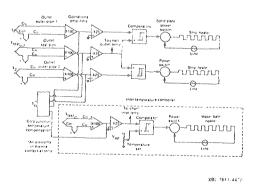
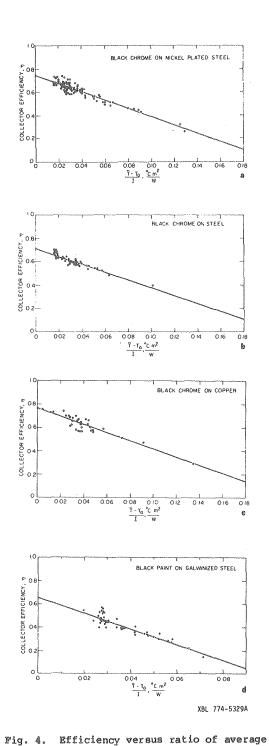


Fig. 3. Electronic control design showing how string heaters and waterbath temperature are controlled automatically.

Table 3. Collector performance and loss coefficients

200339030000000000000000000000000000000	Rl	R16	R9	HP1
(ta) _e	0.818	0.791	0.807	0.819
F°	0.916	0.898	0.954	0.806
υL	3.9	3.8	3.7	8.4 (W/ ^O Cm ²)



- temperature above ambient and solar radiation.
 - a) Black chrome on nickel plated steel
 (R1).
 - b) Black chrome on Steel (R16).
 - c) Black chrome on Copper (R9).
 - d) Black paint on galvanized steel (HP1).

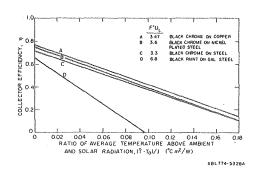


Fig. 5. Comparative efficiency plots for absorber surfaces in Fig. 4. F' and $U_{\rm L}$ are respectively the collector performance and loss coefficients.

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