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EMBEDDINGS AND HYPERPLANES OF THE LIE GEOMETRY $A_{n,\{1,n\}}(\mathbb{F})$

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Abstract. In this paper we consider a family of projective embeddings of the geometry $A_{n,\{1,n\}}(\mathbb{F})$ of point-hyperplane flags of $\text{PG}(n, \mathbb{F})$. The natural embedding ε_{nat} is one of them. It maps every point-hyperplane flag (p, H) onto the vector-line $\langle \mathbf{x} \otimes \xi \rangle$, where \mathbf{x} is a representative vector of p and ξ is a linear functional describing H . The other embeddings have been discovered more than two decads ago by Thas and Van Maldeghem for the case $n = 2$ and recently generalized to any n by De Schepper, Schillewaert and Van Maldeghem. They are obtained as twistings of ε_{nat} by non-trivial automorphisms of \mathbb{F} . Explicitly, for $\sigma \in \text{Aut}(\mathbb{F}) \setminus \{\text{id}_{\mathbb{F}}\}$, the twisting ε_{σ} of ε_{nat} by σ maps (p, H) onto $\langle \mathbf{x}^{\sigma} \otimes \xi \rangle$. We shall prove that, when $\text{Aut}(\mathbb{F}) \neq \{\text{id}_{\mathbb{F}}\}$, a geometric hyperplane \mathcal{H} of $A_{n,\{1,n\}}(\mathbb{F})$ arises from ε_{nat} and at least one of its twistings or from at least two distinct twistings of ε_{nat} if and only if $\mathcal{H} = \{(p, H) \in A_{n,\{1,n\}}(\mathbb{F}) \mid p \in A \text{ or } a \in H\}$ for a possibly non-incident point-hyperplane pair (a, A) of $\text{PG}(n, \mathbb{F})$. We call these hyperplanes quasi-singular hyperplanes. With the help of this result we shall prove that if $|\text{Aut}(\mathbb{F})| > 1$ then $A_{n,\{1,n\}}(\mathbb{F})$ admits no absolutely universal embedding.

Keywords. Lie geometries, Segre varieties, embeddings, hyperplanes

Mathematics Subject Classifications. 51A45, 20F40, 15A69

1. Introduction

Lie geometries have been intensively studied over the last fifty years. Referring the reader to [DSSVM24, Section 2] for a precise definition, we only recall that Lie geometries are point-line geometries obtained from buildings associated with Chevalley groups by choosing as points the elements of a given type or the flags of a particular type. For instance, flags of size 2 are chosen as points for the Lie geometries $A_{n,\{1,n\}}(\mathbb{F})$ and $D_{n,\{n-1,n\}}(\mathbb{F})$, associated with the groups $\text{SL}(n+1, \mathbb{F})$ and $\Omega^+(2n, \mathbb{F})$ respectively. The points of $A_{n,\{1,n\}}(\mathbb{F})$ are indeed the point-hyperplane flags of $\text{PG}(n, \mathbb{F})$ while the points of $D_{n,\{n-1,n\}}(\mathbb{F})$ are the flags of type $\{n-1, n\}$ of

the building of type D_n defined over the field \mathbb{F} (equivalently, the $(n - 2)$ -dimensional singular subspaces of the hyperbolic quadric $\mathcal{Q}^+(2n - 1, \mathbb{F})$).

Most Lie geometries admit a projective embedding (they are *embeddable*, for short), namely they can be realized as full subgeometries of suitable projective spaces. For instance, both $A_{n,\{1,n\}}(\mathbb{F})$ and $D_{n,\{n-1,n\}}(\mathbb{F})$ are embeddable. In particular, $A_{n,\{1,n\}}(\mathbb{F})$ admits in general several different embeddings. One of them yields the adjoint representation of $\mathrm{SL}(n + 1, \mathbb{F})$.

For many embeddable Lie geometries a projective embedding is known, called the *absolutely universal embedding*, such that all projective embeddings of the given geometry can be obtained as projections from it. The absolutely universal embedding, when it exists, is therefore the best one, in the sense that in some ways it embodies all information we can derive on the given geometry from any of its projective embeddings.

Kasikova and Shult [KE01] give far reaching sufficient conditions for the existence of the absolutely universal embedding of an embeddable point-line geometry. In order to explain what those conditions mean for a Lie geometry we recall the following general property of Lie geometries: let Γ be a Lie geometry but neither a projective space nor a generalized m -gon with $m > 4$; then Γ admits a family \mathcal{S} of convex subspaces, isomorphic to non-degenerate polar spaces of rank at least 2 and called *symps*, such that if p and q are points of Γ at distance 2 with at least two common neighbors, then p and q belong to the same member of \mathcal{S} . For embeddable Lie geometries other than projective spaces or generalized polygons the conditions found by Kasikova and Shult ultimately amount to the following: *symps* are not grids.

This condition fails to hold in $A_{n,\{1,n\}}(\mathbb{F})$ as well as in $D_{n,\{n-1,n\}}(\mathbb{F})$. Indeed in both of these geometries all *symps* are grids. Of course, this failure is not enough to conclude that in general $A_{n,\{1,n\}}(\mathbb{F})$ and $D_{n,\{n-1,n\}}(\mathbb{F})$ fail to admit the absolutely universal embedding. However this is precisely the case for $A_{n,\{1,n\}}(\mathbb{F})$. Indeed, as we shall prove in this paper (Corollary 1.15), if the field \mathbb{F} admits non-trivial automorphisms then $A_{n,\{1,n\}}(\mathbb{F})$ admits no absolutely universal embedding. We do not know if the same conclusions hold true for $D_{n,\{n-1,n\}}(\mathbb{F})$ ($n > 3$ of course, since $D_{3,\{2,3\}}(\mathbb{F})$ is the same as $A_{3,\{1,3\}}(\mathbb{F})$).

1.1. Basic properties of the geometry $A_{n,\{1,n\}}(\mathbb{F})$

Following a well established notation, we denote by $A_{n,\{1,n\}}(\mathbb{F})$ the geometry of point-hyperplane flags of the projective geometry $\mathrm{PG}(n, \mathbb{F})$, for $n \geq 2$ and \mathbb{F} a given field.

Explicitly, $A_{n,\{1,n\}}(\mathbb{F})$ is the point-line geometry the points of which are the ordered pairs (p, H) where p and H are a point and a hyperplane of $\mathrm{PG}(n, \mathbb{F})$ respectively and $p \in H$; the lines of $A_{n,\{1,n\}}(\mathbb{F})$ are the sets $\{(p, H) \mid p \in \ell\}$ for ℓ a line of $\mathrm{PG}(n, \mathbb{F})$ and H a hyperplane of $\mathrm{PG}(n, \mathbb{F})$ containing ℓ and the sets $\{(p, H) \mid H \supseteq L\}$ for L a sub-hyperplane of $\mathrm{PG}(n, \mathbb{F})$ (namely a subspace of $\mathrm{PG}(n, \mathbb{F})$ of codimension 2) and p a point of L . Accordingly, two points (p, H) and (q, K) of $A_{n,\{1,n\}}(\mathbb{F})$ are collinear if and only if either $p = q$ or $H = K$. Let $p \neq q$ and $H \neq K$. If either $p \in K$ or $q \in H$, then (p, H) and (q, K) are at distance 2, otherwise they are at distance 3. Thus, the diameter of the collinearity graph of $A_{n,\{1,n\}}(\mathbb{F})$ is equal to 3.

1.1.1 Maximal singular subspaces

Given a point a of $\text{PG}(n, \mathbb{F})$, let \mathcal{M}_a be the set of pairs (a, H) with H a hyperplane of $\text{PG}(n, \mathbb{F})$ containing a . This set is a maximal singular subspace of $A_{n, \{1, n\}}(\mathbb{F})$, namely a subspace of the point-line geometry $A_{n, \{1, n\}}(\mathbb{F})$ all points of which are mutually collinear and maximal with respect to this property. Dually, for a hyperplane A of $\text{PG}(n, \mathbb{F})$, the set $\mathcal{M}_A := \{(p, A) \mid p \in A\}$ is a maximal singular subspace of $A_{n, \{1, n\}}(\mathbb{F})$. We say that \mathcal{M}_a and \mathcal{M}_A are *based* at a and A respectively. Every maximal singular subspace of $A_{n, \{1, n\}}(\mathbb{F})$ admits one of these two descriptions. Thus, the maximal singular subspaces of $A_{n, \{1, n\}}(\mathbb{F})$ are partitioned in two families: those which are based at a point and those based at a hyperplane. Two distinct maximal singular subspaces have at most one point in common; they meet in a point only if they do not belong to the same family. Moreover, if \mathcal{M} is a maximal singular subspace of $A_{n, \{1, n\}}(\mathbb{F})$ and (p, H) a point of $A_{n, \{1, n\}}(\mathbb{F})$ exterior to \mathcal{M} , then (p, H) is collinear with at most one point of \mathcal{M} .

1.1.2 The natural embedding and its twistings

It is well known that $A_{n, \{1, n\}}(\mathbb{F})$ admits a (full) projective embedding in the projective space $\text{PG}(M_{n+1}^0(\mathbb{F}))$ of the vector space $M_{n+1}^0(\mathbb{F})$ of null-traced square matrices of order $n + 1$ with entries in \mathbb{F} , which yields the adjoint representation of the special linear group $\text{SL}(n + 1, \mathbb{F})$. We call it the *natural embedding* of $A_{n, \{1, n\}}(\mathbb{F})$ and we denote it by the symbol ε_{nat} .

Explicitly, recall that $M_{n+1}^0(\mathbb{F})$ is a hyperplane of the vector space $M_{n+1}(\mathbb{F})$ of square matrices of order $n + 1$ with entries in \mathbb{F} and the latter is canonically isomorphic to the tensor product $V \otimes V^*$, where $V = V(n + 1, \mathbb{F})$ and V^* is the dual of V . The pure tensors $\mathbf{x} \otimes \xi$ of $V \otimes V^*$, with \mathbf{x} and ξ non-zero vectors of V and V^* respectively, yield the matrices of $M_{n+1}(\mathbb{F})$ of rank 1. With \mathbf{x} and ξ as above, let $[\mathbf{x}]$ and $[\xi]$ be the point and the hyperplane of $\text{PG}(n, \mathbb{F})$ represented by \mathbf{x} and ξ . Then $([\mathbf{x}], [\xi])$ is a point of $A_{n, \{1, n\}}(\mathbb{F})$ if and only if $\xi(\mathbf{x}) = 0$. The pure tensor $\mathbf{x} \otimes \xi$, regarded as a square matrix of $M_{n+1}(\mathbb{F})$ of rank 1, is null-traced if and only if $\xi(\mathbf{x}) = 0$. The natural embedding

$$\varepsilon_{\text{nat}} : A_{n, \{1, n\}}(\mathbb{F}) \rightarrow \text{PG}(M_{n+1}^0(\mathbb{F}))$$

maps the point $([\mathbf{x}], [\xi])$ of $A_{n, \{1, n\}}(\mathbb{F})$ onto the point $[\mathbf{x} \otimes \xi]$ of $\text{PG}(M_{n+1}^0(\mathbb{F}))$.

Suppose now that \mathbb{F} admits non-trivial automorphisms and let σ be one of them. We can define a *twisted* version ε_σ of ε_{nat} as follows (De Schepper, Schillewaert and Van Maldeghem [DSSVM24]; also Thas and Van Maldeghem [TVM00a, Part III]):

$$\begin{aligned} \varepsilon_\sigma : A_{n, \{1, n\}}(\mathbb{F}) &\rightarrow \text{PG}(M_{n+1}(\mathbb{F})) \\ ([\mathbf{x}], [\xi]) &\rightarrow [\mathbf{x}^\sigma \otimes \xi] \end{aligned}$$

where if $\mathbf{x} = (x_i) = (x_i)_{i=0}^n$ then $\mathbf{x}^\sigma = (x_i^\sigma)_{i=0}^n$. This mapping is indeed a projective embedding of $A_{n, \{1, n\}}(\mathbb{F})$ in $\text{PG}(M_{n+1}(\mathbb{F}))$. Note that $\dim(\varepsilon_\sigma) = \dim(\varepsilon_{\text{nat}}) + 1$.

A dual ε_σ^* of ε_σ can also be defined, which maps every point $([\mathbf{x}], [\xi])$ of $A_{n, \{1, n\}}(\mathbb{F})$ onto the point $[\mathbf{x} \otimes \xi^\sigma]$ of $\text{PG}(M_{n+1}(\mathbb{F}))$. However, as $\varepsilon_\sigma^* \cong \varepsilon_{\sigma^{-1}}$, we can safely ignore these dual twistings.

1.1.3 Quasi-singular hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$

Given a point a and a hyperplane A of $\text{PG}(n, \mathbb{F})$, possibly $a \notin A$, let $\mathcal{H}_{a,A}$ be the set of points (p, H) of $A_{n,\{1,n\}}(\mathbb{F})$ collinear with at least one point of the union $\mathcal{M}_a \cup \mathcal{M}_A$ of the maximal singular subspaces \mathcal{M}_a and \mathcal{M}_A . In other words, $(p, H) \in \mathcal{H}_{a,A}$ if and only if either $p \in A$ or $a \in H$. It is proved in [Pas24] that $\mathcal{H}_{a,A}$ is a geometric hyperplane of $A_{n,\{1,n\}}(\mathbb{F})$. Following [Pas24], we call the hyperplanes as $\mathcal{H}_{a,A}$ *quasi-singular* hyperplanes. When $a \in A$ then $\mathcal{H}_{a,A}$ is the set of points of $A_{n,\{1,n\}}(\mathbb{F})$ at non-maximal distance from the point (a, A) . We call it a *singular* hyperplane.

1.2. Embeddings and hyperplanes of point-line geometries

In this subsection we recall some basics on projective embeddings and geometric hyperplanes of point-lines geometries. We will stick to what is necessary in order to understand the remaining parts of this introduction. A little more of information on this matter will be given in Section 2.3.

Throughout this subsection Γ is an arbitrary point-line geometry as defined in Shult [Shu11], but we assume that the lines of Γ are subsets of the set of points of Γ , henceforth denoted by \mathcal{P} . We also assume Γ to be connected.

As in Shult [Shu95], a *projective embedding* of Γ (an *embedding* of Γ for short) is an injective mapping ε from the point-set \mathcal{P} of Γ to the point-set of a desarguesian projective space Σ such that $\varepsilon(\mathcal{P})$ spans Σ and $\varepsilon(\ell) := \{\varepsilon(p)\}_{p \in \ell}$ is a line of Σ , for every line ℓ of Γ . The dimension of Σ is the *dimension* $\dim(\varepsilon)$ of ε .

1.2.1 Morphisms of embeddings

We refer to Faure and Frölicher [FF00, Definition 6.2.1] for the definition of morphisms of projective geometries. Given two projective spaces Σ_1 and Σ_2 and embeddings $\varepsilon_1 : \Gamma \rightarrow \Sigma_1$ and $\varepsilon_2 : \Gamma \rightarrow \Sigma_2$ of Γ , a *morphism* from ε_1 to ε_2 is morphism of projective geometries $\phi : \Sigma_1 \rightarrow \Sigma_2$ such that $\varepsilon_2 = \phi \cdot \varepsilon_1$. If ϕ is a morphism from ε_1 to ε_2 we write $\phi : \varepsilon_1 \rightarrow \varepsilon_2$, we say that ε_1 *covers* ε_2 and we write $\varepsilon_1 \geq \varepsilon_2$, also $\varepsilon_2 \leq \varepsilon_1$. Note that, as Γ is connected by assumption, if a morphism $\phi : \varepsilon_1 \rightarrow \varepsilon_2$ exists then ϕ is uniquely determined by the condition $\varepsilon_2 = \phi \cdot \varepsilon_1$. This condition also forces $\phi : \Sigma_1 \rightarrow \Sigma_2$ to be surjective. So, if ϕ is injective then it is an isomorphism. If this is the case then we say that ε_1 and ε_2 are *isomorphic* and we write $\varepsilon_1 \cong \varepsilon_2$. Note that $\varepsilon_1 \cong \varepsilon_2$ if and only if $\varepsilon_1 \geq \varepsilon_2 \geq \varepsilon_1$.

1.2.2 Relatively and absolutely universal embeddings

Following Shult [Shu95], we say that an embedding ε of a point-line geometry Γ is *relatively universal* if every morphism from an embedding of Γ to ε is an isomorphism. An embedding ε is said to be *absolutely universal* if it covers all embeddings of Γ . Clearly, the absolutely universal embedding, if it exists, is unique up to isomorphisms and it is relatively universal. The converse is false in general. Indeed, as proved by Ronan [Ron87], every embedding ε of a point-line geometry Γ is covered by a relatively universal embedding, uniquely determined by ε up to isomorphisms and characterized by the property of covering all covers of ε . We call it the

universal cover of ε . So, Γ admits the absolutely universal embedding if and only if it admits a unique relatively universal embedding (unique up to isomorphisms, of course).

Remark 1.1. The previous definition of the absolutely universal embedding is more restrictive than in [Shu95], where an embedding of Γ is said to be absolutely universal if it covers all embeddings of Γ defined over the same division ring as ε itself. If Γ admits embeddings defined over different division rings then it cannot admit the absolutely universal embedding as we have defined it but some of its embeddings could be absolutely universal in the sense of Shult [Shu95].

1.2.3 Hyperplanes and embeddings

A subspace of a point-line geometry Γ is a subset X of the point-set \mathcal{P} of Γ such that, for every line ℓ of Γ , if $|\ell \cap X| > 1$ then $\ell \subseteq X$. A proper subspace of Γ is said to be a *geometric hyperplane* of Γ (a *hyperplane* of Γ for short) if every line of Γ meets it non-trivially. Equivalently, a hyperplane of Γ is a proper subset \mathcal{H} of \mathcal{P} such that, for every line ℓ of Γ , either $\ell \subseteq \mathcal{H}$ or $|\ell \cap \mathcal{H}| = 1$.

Assuming that Γ is embeddable, let $\varepsilon : \Gamma \rightarrow \Sigma$ be an embedding of Γ in a projective space Σ . We say that a hyperplane \mathcal{H} of Γ *arises from* ε if $\varepsilon(\mathcal{H})$ spans a projective hyperplane H of Σ and $\mathcal{H} = \varepsilon^{-1}(H)$. Conversely, if H is a projective hyperplane of Σ then $\varepsilon^{-1}(H)$ is a hyperplane of Γ and $\varepsilon(\varepsilon^{-1}(H)) = H \cap \varepsilon(\mathcal{P})$, but in general $\varepsilon^{-1}(H)$ does not arise from ε . Indeed $\varepsilon^{-1}(H)$ arises from ε if and only if $\langle H \cap \varepsilon(\mathcal{P}) \rangle = H$. The following is proved in [Pas24, Proposition 1.1].

Proposition 1.2. *Given an embedding $\varepsilon : \Gamma \rightarrow \Sigma$ of Γ and a hyperplane \mathcal{H} of Γ , if \mathcal{H} is a maximal subspace of Γ then either \mathcal{H} arises from ε or $\varepsilon(\mathcal{H})$ spans Σ . In particular, given a projective hyperplane H of Σ , suppose that $\varepsilon^{-1}(H)$ is a maximal subspace of Γ . Then $H \cap \varepsilon(\mathcal{P})$ spans H .*

Remark 1.3. A subspace S of Γ is said to *arise from* an embedding $\varepsilon : \Gamma \rightarrow \Sigma$ if $S = \varepsilon^{-1}(\langle \varepsilon(S) \rangle)$. A hyperplane \mathcal{H} of Γ arises from ε as a hyperplane precisely when it arises from ε as a subspace of Γ and $\varepsilon(\mathcal{H})$ spans a hyperplane of Σ .

1.2.4 Generating rank and relatively universal embeddings

The intersection of an arbitrary family of subspaces of Γ is still a subspace of Γ . For a subset X of \mathcal{P} , let $\langle X \rangle$ be the smallest subspace of Γ containing X , namely $\langle X \rangle$ is the intersection of all subspaces of Γ which contain X . If $\langle X \rangle = \Gamma$ then we say that X *generates* Γ . The *generating rank* $\text{grk}(\Gamma)$ of Γ is the minimum cardinality of a generating set of Γ . Clearly, if ε is a projective embedding of Γ then $\dim(\varepsilon) + 1 \leq \text{grk}(\Gamma)$. Consequently,

Proposition 1.4. *If $\dim(\varepsilon) + 1 = \text{grk}(\Gamma) < \infty$ then ε is relatively universal.*

1.3. Back to embeddings and hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$

1.3.1 Absolutely and relatively universal embeddings of $A_{n,\{1,n\}}(\mathbb{F})$

As we shall prove in this paper (Corollary 1.15), when $|\text{Aut}(\mathbb{F})| > 1$ the geometry $A_{n,\{1,n\}}(\mathbb{F})$ admits no absolutely universal embedding. We might wonder if ε_{nat} and its twistings are relatively universal and the condition $|\text{Aut}(\mathbb{F})| = 1$ is sufficient for ε_{nat} to be absolutely universal.

The answer is negative in general for both these questions (see below, Result 1.8). We mention below what is known about these two issues.

Result 1.5 (Blok and Pasini [BP03]). *If \mathbb{F} is a prime field and $n > 2$ then ε_{nat} is absolutely universal.*

Result 1.6 (Thas and Van Maldeghem [TVM00a]). *Let \mathbb{F} be finite and $n = 2$. Then both ε_{nat} and its twistings are relatively universal. Accordingly, if \mathbb{F} is non-prime then $A_{2,\{1,2\}}(\mathbb{F})$ admits no absolutely universal embedding. On the other hand, if \mathbb{F} is prime then ε_{nat} is absolutely universal.*

Result 1.7 (Völklein [Völ89]). *Let $n \geq 2$ and suppose that \mathbb{F} is either perfect of positive characteristic or algebraic over the field \mathbb{Q} of rational numbers. Then ε_{nat} is relatively universal.*

Result 1.8 (Smith and Völklein [SV89]). *Let $n = 2$. Then ε_{nat} is relatively universal if and only if the field \mathbb{F} is either perfect of positive characteristic or algebraic over \mathbb{Q} .*

Result 1.8 makes it clear that the triviality of $\text{Aut}(\mathbb{F})$ is not sufficient for ε_{nat} to be relatively universal. For instance, the automorphism group of the field \mathbb{R} of real numbers is trivial. Nevertheless, in view of Result 1.8, the natural embedding of $A_{2,\{1,2\}}(\mathbb{R})$ is not relatively universal.

An explicit description of the universal cover of the natural embedding ε_{nat} of $A_{2,\{1,2\}}(\mathbb{F})$ is missing in [SV89]. We have lately obtained such a description, also proving that the conclusions of Result 1.8 hold true for any $n \geq 2$. We shall devote an appropriate paper to these results.

Finally, suppose that \mathbb{F} is a simple extension of its prime subfield. Then $\text{grk}(A_{n,\{1,n\}}(\mathbb{F})) \leq (n+1)^2$, as proved in [BP01]. However $\dim(\varepsilon_\sigma) = (n+1)^2 - 1$ for every non trivial automorphism σ of \mathbb{F} . Proposition 1.4 thus implies the following:

Result 1.9. *Let \mathbb{F} be a simple (possibly non-algebraic) extension of its prime subfield. Then all twistings of ε_{nat} are relatively universal and either ε_{nat} itself is relatively universal or its universal cover has dimension just one unit more than $\dim(\varepsilon_{\text{nat}})$.*

Accordingly, if \mathbb{F} is a simple algebraic extension of its prime subfield then both ε_{nat} and all of its twistings are relatively universal, as we see by combining Result 1.9 with Result 1.7. On the other hand, let \mathbb{F} be a simple transcendental extension of its prime subfield. Then all twistings of ε_{nat} are relatively universal but ε_{nat} is not.

1.3.2 Hyperplanes and embeddings of $A_{n,\{1,n\}}(\mathbb{F})$

The following is proved in [Pas24, Theorem 1.5]:

Result 1.10. *All hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ are maximal subspaces.*

Therefore, in view of Proposition 1.2,

Corollary 1.11. *For every projective embedding $\varepsilon : A_{n,\{1,n\}}(\mathbb{F}) \rightarrow \Sigma$, the hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ which arise from ε are precisely the ε -preimages of the projective hyperplanes of Σ .*

1.4. Main results

In view of the next theorem it is convenient to slightly modify our notation. The natural embedding ε_{nat} of $A_{n,\{1,n\}}(\mathbb{F})$ can be regarded as a borderline case of twisting, namely the twisting of ε_{nat} by the identity automorphism $\text{id}_{\mathbb{F}}$ of \mathbb{F} . Accordingly, henceforth we will also denote ε_{nat} by the symbol $\varepsilon_{\text{id}_{\mathbb{F}}}$. With this notation, $\varepsilon_{\text{nat}} = \varepsilon_{\text{id}_{\mathbb{F}}}$ is a member of the set $\{\varepsilon_{\sigma}\}_{\sigma \in \text{Aut}(\mathbb{F})}$.

Theorem 1.12. *Suppose that $|\text{Aut}(\mathbb{F})| > 1$ and let \mathcal{H} be a geometric hyperplane of $A_{n,\{1,n\}}(\mathbb{F})$.*

- (1) *If \mathcal{H} is quasi-singular then \mathcal{H} arises from ε_{σ} for every $\sigma \in \text{Aut}(\mathbb{F})$.*
- (2) *If \mathcal{H} is not quasi-singular then \mathcal{H} arises from ε_{σ} for at most one $\sigma \in \text{Aut}(\mathbb{F})$.*

Claim (1) of Theorem 1.12 will be proved at the end of Section 3. Claim (2) will be proved in Section 4.

As we shall see in Section 3, for every $\sigma \in \text{Aut}(\mathbb{F})$ many hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ exist which arise from ε_{σ} but are not quasi-singular. Therefore Theorem 1.12 implies the following.

Corollary 1.13. *Let $|\text{Aut}(\mathbb{F})| > 1$. Then $\varepsilon_{\sigma} \not\cong \varepsilon_{\rho}$ for any choice of distinct automorphism σ and ρ of \mathbb{F} .*

The following is the second main result of this paper. We shall prove it in Section 5 with the help of Theorem 1.12.

Theorem 1.14. *For any two distinct automorphisms σ and ρ of \mathbb{F} , no projective embedding of $A_{n,\{1,n\}}(\mathbb{F})$ covers both ε_{σ} and ε_{ρ} .*

The next corollary immediately follows from Theorem 1.14.

Corollary 1.15. *If $|\text{Aut}(\mathbb{F})| > 1$ then $A_{n,\{1,n\}}(\mathbb{F})$ admits no absolutely universal embedding.*

Organization of the paper. In Section 2 we fix some notation for vectors, tensors, matrices and projective points, we recall some basics on semi-polynomials and we add some information on embeddings and hyperplanes of point-line geometries, as a completion of Section 1.2.

In Section 3 we describe the hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ which arise from ε_{σ} for $\sigma \in \text{Aut}(\mathbb{F})$. We will do it with the help of a symmetric bilinear form, called the *saturation form* in [Pas24]. We have exploited that form in [Pas24, Section 1.3.1] in order to describe the hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ which arise from ε_{nat} . Section 3 is indeed a survey of Sections 1.3.1 and 2.2 of [Pas24], with the addition of a straightforward generalization to ε_{σ} for $\sigma \neq \text{id}_{\mathbb{F}}$.

A proof of Claim (1) of Theorem 1.12 will also be given at the end of Section 3. Claim (2) of Theorem 1.12 will be proved in Section 4. Section 5 is devoted to the proof of Theorem 1.14.

In the last section of this paper we shall consider quotients (namely morphic images) of ε_{nat} and its twistings, focusing on the polarized ones, an embedding of $A_{n,\{1,n\}}(\mathbb{F})$ being called *polarized* when all singular hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ arise from it. In particular, we shall generalize a little piece of the main result of the triad of papers [TVM00a] by J. A. Thas and H. Van Maldeghem.

2. Preliminaries

2.1. Notation to be used throughout this paper

We denote the vectors of $V = V(n+1, \mathbb{F})$ by low case boldface roman letters and the vectors of its dual V^* by low case greek letters, but we denote both the null-vector of V and the null-vector of V^* by the symbol 0 . Most of the matrices to be considered in this paper are square matrices of order $n+1$. We denote them by capital roman letters. In particular, O and I are the null square matrix and the identity matrix of order $n+1$, respectively. Scalars will be denoted by roman or greek low case letters.

The symbols $M_{n+1}(\mathbb{F})$ and $M_{n+1}^0(\mathbb{F})$ denote respectively the vector space of all square matrices of order $n+1$ with entries in \mathbb{F} and the hyperplane of $M_{n+1}(\mathbb{F})$ formed by the null-traced matrices, as in Section 1.1.2.

Recall that $M_{n+1}(\mathbb{F}) \cong V \otimes V^*$. Explicitly, for every pure tensor $\mathbf{x} \otimes \xi$, let $f(\mathbf{x} \otimes \xi) : V \rightarrow V$ be the linear mapping which maps every vector $\mathbf{w} \in V$ onto $\mathbf{x} \cdot \xi(\mathbf{w})$. The function which maps every pure vector $\mathbf{x} \otimes \xi \in V \otimes V^*$ onto $f(\mathbf{x} \otimes \xi)$ extends by linearity to an isomorphism f from $V \otimes V^*$ to the vector space $\mathcal{L}(V)$ of the linear mappings from V to V . For every choice of a basis $E = (\mathbf{e}_i)_{i=0}^n$ of V , the mapping $\mu_E : \mathcal{L}(V) \rightarrow M_{n+1}(\mathbb{F})$ which maps every linear mapping of V onto its representative matrix with respect to E is an isomorphism of vector spaces from $\mathcal{L}(V)$ to $M_{n+1}(\mathbb{F})$ and composition $\nu_E := \mu_E \cdot f$ is an isomorphism from $V \otimes V^*$ to $M_{n+1}(\mathbb{F})$.

With E as above, let $E^* = (\eta_i)_{i=0}^n$ be the basis of V^* dual to E . So, $\eta_i(\mathbf{e}_j) = \delta_{i,j}$ (Kronecker symbol) for any choice of $i, j = 0, 1, \dots, n$. The pure tensors $\mathbf{e}_i \otimes \eta_j$ form a basis of $V \otimes V^*$, henceforth denoted by $E \otimes E^*$. The isomorphism ν_E maps $\mathbf{e}_i \otimes \eta_j$ onto the matrix $E_{i,j}$ with all null entries but the (i, j) entry, which is 1. In short, ν_E maps $E \otimes E^*$ onto the natural basis $(E_{i,j})_{i,j=0}^n$ of $M_{n+1}(\mathbb{F})$. Accordingly, ν_E maps a generic vector $\sum_{i,j=0}^n m_{i,j} \mathbf{e}_i \otimes \eta_j$ of $V \otimes V^*$ onto the matrix $M = (m_{i,j})_{i,j=0}^n = \sum_{i,j=0}^n m_{i,j} E_{i,j}$.

For the sake of accuracy, $V \otimes V^*$ and $M_{n+1}(\mathbb{F})$ are different objects. However henceforth, stressing on the isomorphism $\nu_E : V \otimes V^* \rightarrow M_{n+1}(\mathbb{F})$, we will take the liberty of regarding $V \otimes V^*$ and $M_{n+1}(\mathbb{F})$ as the same thing, thus freely switching from the matrix notation to the tensor notation and conversely, whenever these changes of notation will be convenient.

We also assume that $E = (\mathbf{e}_i)_{i=0}^n$ is the natural basis of V . Accordingly, a vector $\mathbf{x} = \sum_{i=0}^n \mathbf{e}_i x_i$ of V is the same as the $(n+1)$ -tuple $(x_i)_{i=0}^n$ of its coordinates with respect to E , this $(n+1)$ -tuple being regarded as a column, namely an $(n+1) \times 1$ matrix. Similarly, every vector $\xi = \sum_{i=0}^n \xi_i \eta_i \in V^*$ is the $1 \times (n+1)$ matrix $(\xi_0, \xi_1, \dots, \xi_n)$. Thus, the scalar $\xi(\mathbf{x})$ is the same as the row-times-column product $\xi \mathbf{x}$ and, for a matrix $M \in M_{n+1}(\mathbb{F})$, the product $\xi M \mathbf{x}$ is the product of the row ξ times M times the column \mathbf{x} . The tensor $\mathbf{x} \otimes \xi$ is the same as the column-times-row product $\mathbf{x} \xi$.

We denote by $\text{Pure}(V \otimes V^*)$ ($= \text{Pure}(M_{n+1}(\mathbb{F}))$) the set of pure tensors of $V \otimes V^* = M_{n+1}(\mathbb{F})$, with the convention that the null vector O of $V \otimes V^*$ is not included in that set. So, $\text{Pure}(M_{n+1}(\mathbb{F}))$ is the set of matrices of $M_{n+1}(\mathbb{F})$ of rank 1. The hyperplane $M_{n+1}^0(\mathbb{F})$ of $M_{n+1}(\mathbb{F})$ will also be denoted by $(V \otimes V^*)_0$ and we set $\text{Pure}((V \otimes V^*)_0) := \text{Pure}(V \otimes V^*) \cap (V \otimes V^*)_0$. So, $\text{Pure}(M_{n+1}^0(\mathbb{F}))$ ($= \text{Pure}((V \otimes V^*)_0)$) is the set of null-traced matrices of $M_{n+1}(\mathbb{F})$ of rank 1, namely the set of pure tensors $\mathbf{x} \otimes \xi$ with $\xi(\mathbf{x}) = 0$.

Given two non-zero vectors $\mathbf{x}, \mathbf{y} \in V$, if \mathbf{x} and \mathbf{y} are proportional we write $\mathbf{x} \equiv \mathbf{y}$. We use that same notation for vectors of V^* and matrices of $M_{n+1}(\mathbb{F})$. For instance, for a matrix $M \in M_{n+1}(\mathbb{F}) \setminus \{O\}$, when writing $M \equiv I$ we mean that M is a scalar matrix.

When we need to distinguish between a non-zero vector \mathbf{x} of V and the point of $\text{PG}(V) = \text{PG}(n, \mathbb{F})$ represented by it, we denote the latter by $[\mathbf{x}]$. We extend this convention to subsets of V : if $X \subseteq V \setminus \{0\}$ then $[X] := \{[\mathbf{x}] \mid \mathbf{x} \in X\}$. The same conventions will be adopted for vectors and subsets of V^* and $V \otimes V^*$. In particular, if $\xi \in V^* \setminus \{0\}$ then $[\xi]$ is the point of $\text{PG}(V^*)$ which corresponds to the hyperplane $[\text{Ker}(\xi)]$ of $\text{PG}(V)$. In the sequel we shall freely take $[\xi]$ as a name for $[\text{Ker}(\xi)]$.

2.2. Semi-polynomials

Let $\mathfrak{M}(\mathbb{F})$ be the module over the ring \mathbb{Z} of integers with $\text{Aut}(\mathbb{F})$ as a basis, namely the elements of $\mathfrak{M}(\mathbb{F})$ are finite formal combinations $\sum_{\sigma \in \text{Aut}(\mathbb{F})} k_\sigma \sigma$ with $k_\sigma \in \mathbb{Z}$ for every $\sigma \in \text{Aut}(\mathbb{F})$ and $k_\sigma = 0$ for all but at most a finite number of choices of $\sigma \in \text{Aut}(\mathbb{F})$. Put

$$\mathfrak{M}^+(\mathbb{F}) := \left\{ \sum_{\sigma \in \text{Aut}(\mathbb{F})} k_\sigma \sigma \mid k_\sigma \geq 0 \text{ for every } \sigma \in \text{Aut}(\mathbb{F}) \right\}.$$

The sum $w(\gamma) := \sum_{\sigma \in \text{Aut}(\mathbb{F})} k_\sigma$ will be called the *weight* of an element $\gamma = \sum_{\sigma \in \text{Aut}(\mathbb{F})} k_\sigma \sigma$ of $\mathfrak{M}^+(\mathbb{F})$. Given $\gamma = \sum_{i=1}^r k_i \sigma_i \in \mathfrak{M}^+(\mathbb{F})$ and $t \in \mathbb{F}$, the exponentiation t^γ stands for $\prod_{i=1}^r (t^{k_i})^{\sigma_i}$.

Note that, regarded $\mathfrak{M}(\mathbb{F})$ as an additive monoid, $\mathfrak{M}^+(\mathbb{F})$ is a submonoid of $\mathfrak{M}(\mathbb{F})$. However $\mathfrak{M}^+(\mathbb{F})$ is not yet the structure we need. Indeed it can happen that $\mathfrak{M}^+(\mathbb{F})$ contains distinct elements γ_1 and γ_2 such that $t^{\gamma_1} = t^{\gamma_2}$ for every $t \in \mathbb{F}$. (This is indeed always the case when \mathbb{F} is finite.) In view of what we are going to do in the sequel, this possibility would cause some troubles. We need to counteract its effects.

So, let \sim be the relation defined on $\mathfrak{M}^+(\mathbb{F})$ by the following clause: $\gamma_1 \sim \gamma_2$ if and only if $t^{\gamma_1} = t^{\gamma_2}$ for every $t \in \mathbb{F}$. Then \sim is a congruence relation of $\mathfrak{M}^+(\mathbb{F})$, namely it is an equivalence relation and it is preserved when taking sums. The quotient $\mathfrak{M}^{[+]}(\mathbb{F}) := \mathfrak{M}^+(\mathbb{F}) / \sim$ is the structure we need. The elements of $\mathfrak{M}^{[+]}(\mathbb{F})$ are the equivalence classes of \sim . For $\gamma \in \mathfrak{M}^+(\mathbb{F})$, we denote by $[\gamma]$ the class of \sim which contains γ . The sum of $\mathfrak{M}^{[+]}(\mathbb{F})$ is defined as follows: $[\gamma_1] + [\gamma_2] := [\gamma_1 + \gamma_2]$, for any two elements γ_1, γ_2 of $\mathfrak{M}^+(\mathbb{F})$. The *weight* $w(X)$ of a class X of \sim is the minimum among the weights of its elements. For instance, if X contains $k \cdot \text{id}_{\mathbb{F}}$ for $0 \leq k < |\mathbb{F}|$ then $k = w(X)$. Note that if \mathbb{F} is finite then $w(X) < |\mathbb{F}|$, for every $X \in \mathfrak{M}^{[+]}(\mathbb{F})$.

We are now ready to define semi-monomials and semi-polynomials. A (non-null) *semi-monomial* (over \mathbb{F}) in the unknowns t_1, \dots, t_m is a formal product

$$M = a \cdot t_1^{X_1} \dots t_m^{X_m}$$

where $X_1, \dots, X_m \in \mathfrak{M}^{[+]}(\mathbb{F})$ and $a \in \mathbb{F} \setminus \{0\}$. The *type* of M is the m -tuple (X_1, \dots, X_m) . We allow $X = 0$ (the null element of $\mathfrak{M}^{[+]}(\mathbb{F})$) and we put $t^0 := 1$, as usual. We also admit the null monomial as a semi-monomial in whatever set of unknown we like, giving it \emptyset as its type.

A (non-null) *semi-polynomial* (over \mathbb{F}) in the unknowns t_1, \dots, t_m is a formal sum $P = M_1 + \dots + M_s$ of non-null semi-monomials (over \mathbb{F}) in those unknowns, no two of which have the same type. The *degree* $\deg(P)$ of P is defined as the maximum $\max_{i=1}^s \deg(M_i)$. We allow P to be the null semi-monomial, henceforth also called the *null semi-polynomial*.

The following statement will be freely used throughout Section 4.2. We believe this statement is well known. However, as we couldn't find any mention of it in the literature, we shall provide a proof here, so that the reader can save the trouble of looking for it in the literature.

Theorem 2.1 (Identity Principle). *Let $P = P(t_1, \dots, t_m)$ be a non-null semi-polynomial over \mathbb{F} in the unknowns t_1, \dots, t_m . Then $P(c_1, \dots, c_m) \neq 0$ for at least one m -tuple $(c_1, \dots, c_m) \in \mathbb{F}^m$.*

Proof. The proof exploits a double induction, on the number m of unknowns of P and the number s of semi-monomials of P . Let $m = 1$. If $s = 1$ there is nothing to prove. Suppose $s = 2$. So $P = P(t) = at^X + bt^Y$ with X, Y distinct elements of $\mathfrak{M}^{[+]}(\mathbb{F})$ and $a, b \in \mathbb{F} \setminus \{0\}$. By way of contradiction, suppose that $P(c) = 0$ for every $c \in \mathbb{F}$. Then with $c = 1$ we get $a + b = 0$. It follows that $c^X = c^Y$ for every $c \in \mathbb{F}$. Hence $X = Y$ by the definition of $\mathfrak{M}^{[+]}(\mathbb{F})$, contradicting the assumption that no two semi-monomials of the same semi-polynomial have the same type. This fixes the case $m = 1$ and $s = 2$.

Still with $m = 1$, suppose now that $s > 2$. Now $P(t) = a_1 t^{X_1} + \dots + a_s t^{X_s}$ where $a_i \neq 0$ for every $i = 1, \dots, s$ and $X_i \neq X_j$ for any choice of $i, j = 1, 2, \dots, s$ with $i \neq j$. With no loss, we can assume that $a_s = 1$. For a contradiction, suppose that $P(c) = 0$ for every $c \in \mathbb{F}$. Then $c^{X_s} = -\sum_{i=1}^{s-1} a_i c^{X_i}$ for every $c \in \mathbb{F}$. Therefore, for every choice of $c, d \in \mathbb{F}$ we have

$$\left(\sum_{i=1}^{s-1} a_i c^{X_i}\right) \left(\sum_{i=1}^{s-1} a_i d^{X_i}\right) = c^{X_s} d^{X_s} = (cd)^{X_s} = -\sum_{i=1}^{s-1} a_i (cd)^{X_i}.$$

Put $f(d) := \sum_{i=1}^{s-1} a_i d^{X_i}$. Then, for every choice of d , we have $a_i f(d) = -a_i d^{X_i}$ by the inductive hypothesis on the semi-polynomial $\sum_{i=1}^{s-1} a_i (f(d) + d^{X_i}) t^{X_i}$. Equivalently, since $a_i \neq 0$ by assumption, $f(d) = -d^{X_i}$. This holds for every $d \in \mathbb{F}$ and every $i = 1, \dots, s-1$. Accordingly, $d^{X_i} = d^{X_j}$ for every $d \in \mathbb{F}$ and every $i, j = 1, \dots, s-1$ with $i \neq j$. This forces $X_i = X_j$ by the definition of $\mathfrak{M}^{[+]}(\mathbb{F})$, contradicting the assumption that $X_i \neq X_j$ if $i \neq j$. By induction, the statement of the theorem holds true when $m = 1$.

Let now $m > 1$. Then $P(t_1, \dots, t_m) = \sum_{j=1}^r P_j(t_1, \dots, t_{m-1}) t_m^{X_j}$ for suitable semi-polynomials P_1, \dots, P_r in the unknowns t_1, \dots, t_{m-1} and suitable pairwise distinct elements $X_1, \dots, X_r \in \mathfrak{M}^{[+]}(\mathbb{F})$.

For a contradiction, suppose $P(c_1, \dots, c_{m-1}, c_m) = 0$ for every choice of $(c_1, \dots, c_m) \in \mathbb{F}^m$. For every $(m-1)$ -tuple $\mathbf{c} = (c_i)_{i=1}^{m-1} \in \mathbb{F}^{m-1}$, put $P_{\mathbf{c}}(t) = P(c_1, \dots, c_{m-1}, t)$. Then $P_{\mathbf{c}}(c) = 0$ for every $c \in \mathbb{F}$. Hence $P_j(c_1, \dots, c_{m-1}) = 0$ for every $j = 1, \dots, r$, by the previous paragraph. However \mathbf{c} is an arbitrary $(m-1)$ -tuple in \mathbb{F}^{m-1} . Therefore, by the inductive hypothesis, P_j is null for every $j = 1, \dots, r$. Hence P is null as well, contradicting the assumption that P is not the null semi-polynomial. \square

2.3. Addendum to Section 1.2

As in Section 1.2, throughout this subsection Γ is a connected point-line geometry and \mathcal{P} is its point-set.

2.3.1 Morphisms and quotients of embeddings

Given two projective embeddings $\varepsilon_1 : \Gamma \rightarrow \Sigma_1$ and $\varepsilon_2 : \Gamma \rightarrow \Sigma_2$, suppose that $\varepsilon_1 \geq \varepsilon_2$ and let $\phi : \Sigma_1 \rightarrow \Sigma_2$ be the morphism from ε_1 to ε_2 . Let $K := \text{Ker}(\phi)$ be the kernel of ϕ (defined as in [FF00, Definition 6.1.1]) and π_K the projection of Σ_1 onto the star Σ_1/K of K in Σ_1 . Then K satisfies the following property

$$K \cap \langle \varepsilon_1(p), \varepsilon_1(q) \rangle = \emptyset, \forall p, q \in \mathcal{P} \tag{2.1}$$

and the mapping $\varepsilon_1/K := \pi_K \cdot \varepsilon_1$ is an embedding of Γ isomorphic to ε_2 . We call ε_1/K the *quotient* of ε_1 over K . Following a well established custom, we also say that ε_2 is a *quotient* of ε_1 , as if ε_2 was the same as ε_1/K . Admittedly, this is an abuse, but it is harmless.

Note that (2.1) characterizes the subspaces K of Σ such that the mapping $\varepsilon_1/K = \pi_K \cdot \varepsilon_1$ is an embedding of Γ . We say that a subspace K of Σ_1 *defines a quotient* of ε_1 if it satisfies (2.1).

2.3.2 More information on hyperplanes and embeddings

Let ε_1 and ε_2 be two projective embeddings of Γ . Clearly, if $\varepsilon_1 \cong \varepsilon_2$ then a hyperplane of Γ arises from ε_1 if and only if it arises from ε_2 . More generally the following holds.

Proposition 2.2. *Given a projective embedding $\varepsilon : \Gamma \rightarrow \Sigma$ let K be a subspace of Σ defining a quotient of ε . Then all hyperplanes of Γ which arise from ε/K and are maximal as subspaces of Γ also arise from ε .*

Proof. Let \mathcal{H} be a hyperplane of Γ such that \mathcal{H} is a maximal subspace of Γ and its ε/K -image $(\varepsilon/K)(\mathcal{H})$ spans a projective hyperplane H of Σ/K . As \mathcal{H} is a maximal subspace of Γ , the ε/K -preimage of H is equal to \mathcal{H} . The preimage $H' := \pi_K^{-1}(H) = \langle \varepsilon(\mathcal{H}) \cup K \rangle$ of H by the projection π_K of Σ onto Σ/K is a hyperplane of Σ and $\mathcal{H} = \varepsilon^{-1}(H')$. It remains to prove that $H' = \langle \varepsilon(\mathcal{H}) \rangle$. For a contradiction, suppose that $\langle \varepsilon(\mathcal{H}) \rangle \subsetneq H'$. Hence $\langle \varepsilon(\mathcal{H} \cup \{p\}) \rangle \subsetneq \Sigma$ for every point p of Γ . This holds even if $p \notin \mathcal{H}$. However, if $p \notin \mathcal{H}$ then $\mathcal{H} \cup \{p\}$ generates Γ , by the maximality of \mathcal{H} . So, $\varepsilon(\mathcal{P})$ does not span Σ . This contradicts the definition of embedding. Therefore $H' = \langle \varepsilon(\mathcal{H}) \rangle$. \square

Proposition 2.3. *Given a projective embedding $\varepsilon : \Gamma \rightarrow \Sigma$ of Γ and a subspace K of Σ , suppose that K defines a quotient of ε . A hyperplane \mathcal{H} of Γ arises from ε/K if and only if it arises from ε and the span of $\varepsilon(\mathcal{H})$ in Σ contains K .*

Proof. The ‘only if’ part is implicit in the proof of Proposition 2.2. The ‘if’ part is obvious. \square

3. The saturation form

Let $f : M_{n+1}(\mathbb{F}) \times M_{n+1}(\mathbb{F}) \rightarrow \mathbb{F}$ be the symmetric bilinear form defined as follows:

$$f(X, Y) := \text{trace}(XY) \text{ for any two matrices } X, Y \in M_{n+1}(\mathbb{F}), \quad (3.1)$$

where XY is the usual row-times-column product. So, with $X = (x_{i,j})_{i,j=0}^n$ and $Y = (y_{i,j})_{i,j=0}^n$ we have

$$f((x_{i,j})_{i,j=0}^n, (y_{i,j})_{i,j=0}^n) = \sum_{i,j} x_{i,j} y_{j,i}. \quad (3.2)$$

In particular, when X and Y have rank 1, namely they are pure tensors, say $X = \mathbf{x} \otimes \xi$ and $Y = \mathbf{y} \otimes v$, then

$$f(\mathbf{x} \otimes \xi, \mathbf{y} \otimes v) = v(\mathbf{x})\xi(\mathbf{y}). \quad (3.3)$$

Following [Pas24], we call f the *saturation form* of $M_{n+1}(\mathbb{F})$.

As noticed in [Pas24, Section 2.2], the form f is non-degenerate. We denote by \mathcal{S}_f the set of f -isotropic vectors of $M_{n+1}(\mathbb{F})$, namely the set of matrices $X \in M_{n+1}(\mathbb{F})$ such that $f(X, X) = 0$.

If $\text{rank}(X) = 1$, namely $X = \mathbf{x} \otimes \xi \in \text{Pure}(V \otimes V^*)$, then $f(X, X) = (\xi(\mathbf{x}))^2$ by formula (3.3). Hence $f(X, X) = 0$ if and only if $\xi(\mathbf{x}) = 0$, namely $X \in M_{n+1}^0(\mathbb{F})$. Accordingly,

$$\mathcal{S}_f \cap \text{Pure}(V \otimes V^*) = \text{Pure}((V \otimes V^*)_0).$$

$\text{Pure}((V \otimes V^*)_0)$ spans $(V \otimes V^*)_0$. Note also that $[\text{Pure}((V \otimes V^*)_0)] = \varepsilon_{\text{nat}}(\mathcal{P})$, where \mathcal{P} stands for the set of points of $A_{n,\{1,n\}}(\mathbb{F})$. On the other hand, let $\sigma \in \text{Aut}(\mathbb{F}) \setminus \{\text{id}_{\mathbb{F}}\}$. Then $\varepsilon_{\sigma}(\mathcal{P}) = [P_{\sigma}]$ where

$$P_{\sigma} := \{\mathbf{x}^{\sigma} \otimes \xi \mid \mathbf{x} \otimes \xi \in \text{Pure}((V \otimes V^*)_0)\}.$$

The set P_{σ} contains $\mathbf{e}_i \otimes \eta_j$ and $(\mathbf{e}_i + \mathbf{e}_j) \otimes (\eta_i - \eta_j)$ for every choice of $i \neq j$. These vectors span $(V \otimes V^*)_0$. However P_{σ} also contains pure tensors exterior to $(V \otimes V^*)_0$. For instance, $(\mathbf{e}_0 t^{\sigma} + \mathbf{e}_1) \otimes (\eta_0 - t\eta_1)$ with $t \in \mathbb{F}$ such that $t^{\sigma} \neq t$ is one of them. Therefore P_{σ} spans $V \otimes V^*$, namely $\varepsilon_{\sigma}(\mathcal{P})$ spans $\text{PG}(M_{n+1}(\mathbb{F}))$.

Let \perp_f be the orthogonality relation associated to f . As f is non-degenerate, the hyperplanes of $M_{n+1}(\mathbb{F})$ are the perps M^{\perp_f} for $M \in M_{n+1}(\mathbb{F}) \setminus \{O\}$ and, for two matrices $M, N \in M_{n+1}(\mathbb{F}) \setminus \{O\}$, we have $M^{\perp_f} = N^{\perp_f}$ if and only if $M \equiv N$. It is clear from formula (3.1) that $I^{\perp_f} = M_{n+1}^0(\mathbb{F})$. Therefore, for $M \in M_{n+1}(\mathbb{F}) \setminus \{O\}$, we have $M^{\perp_f} = M_{n+1}^0(\mathbb{F})$ if and only if $M \equiv I$.

Every hyperplane of $M_{n+1}^0(\mathbb{F})$ is the intersection of $M_{n+1}^0(\mathbb{F})$ with a hyperplane M^{\perp_f} of $M_{n+1}(\mathbb{F})$ for a suitable matrix $M \notin \langle I \rangle$. Of course the equality $M^{\perp_f} \cap M_{n+1}^0(\mathbb{F}) = N^{\perp_f} \cap M_{n+1}^0(\mathbb{F})$ does not imply that $M \equiv N$. The next statement follows from well known properties of the polarities associated to non-degenerate reflexive bilinear forms.

Proposition 3.1. *For $M, N \in M_{n+1}(\mathbb{F}) \setminus \{O\}$, we have $M^{\perp_f} \cap M_{n+1}^0(\mathbb{F}) = N^{\perp_f} \cap M_{n+1}^0(\mathbb{F})$ if and only if $\langle M, I \rangle = \langle N, I \rangle$.*

When $X \in \text{Pure}(V \otimes V^*)$, namely $X \in M_{n+1}(\mathbb{F})$ has rank equal to 1, the orthogonality condition $X \perp_f M$ admits an easy formulation. Indeed formula (3.2) yields the following.

Proposition 3.2. *Let $\mathbf{x} \in V \setminus \{0\}$, $\xi \in V^* \setminus \{0\}$ and $M \in M_{n+1}(\mathbb{F})$. Then $(\mathbf{x} \otimes \xi) \perp_f M$ if and only if $\xi M \mathbf{x} = 0$.*

3.1. The hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ which arise from ε_{nat}

For $M \in M_{n+1}(\mathbb{F}) \setminus \{\lambda I\}_{\lambda \in \mathbb{F}}$, we put

$$\begin{aligned} \mathcal{H}_{M, \text{id}_{\mathbb{F}}} &:= \varepsilon_{\text{nat}}^{-1}([M^{\perp f} \cap M_{n+1}^0(\mathbb{F})]) \\ &= \{([\mathbf{x}], [\xi]) \in \mathcal{P} \mid \xi M \mathbf{x} = 0\}. \end{aligned} \tag{3.4}$$

(Note that $M^{\perp f} \cap \text{Pure}(V \otimes V^*) = \{\mathbf{x} \otimes \xi \neq 0 \mid \xi M \mathbf{x} = 0\}$, by Proposition 3.2.) So, $\mathcal{H}_{M, \text{id}_{\mathbb{F}}}$ is a geometric hyperplane of $A_{n,\{1,n\}}(\mathbb{F})$. By Corollary 1.11, it arises from ε_{nat} .

In particular, let $\text{rank}(M) = 1$, say $M = \mathbf{a} \otimes \alpha$ for a pure tensor $\mathbf{a} \otimes \alpha \in \text{Pure}(V \otimes V^*)$. By Proposition 3.1, if $\mathcal{H}_{\mathbf{a} \otimes \alpha, \text{id}_{\mathbb{F}}} = \mathcal{H}_{\mathbf{b} \otimes \beta, \text{id}_{\mathbb{F}}}$ then $\mathbf{b} \otimes \beta \in \langle \mathbf{a} \otimes \alpha, I \rangle$. However, all rank 1 matrices contained in $\langle \mathbf{a} \otimes \alpha, I \rangle$ are proportional to $\mathbf{a} \otimes \alpha$. Hence $\mathcal{H}_{\mathbf{a} \otimes \alpha, \text{id}_{\mathbb{F}}} = \mathcal{H}_{\mathbf{b} \otimes \beta, \text{id}_{\mathbb{F}}}$ if and only if $\mathbf{a} \otimes \alpha$ and $\mathbf{b} \otimes \beta$ are proportional, namely they correspond to the same pair (a, A) , where $a = [\mathbf{a}]$ and $A = [\alpha]$ are the point and the hyperplane of $\text{PG}(n, \mathbb{F})$ represented by \mathbf{a} and α respectively. In fact, as proved in [Pas24, Proposition 1.3],

$$\mathcal{H}_{\mathbf{a} \otimes \alpha, \text{id}_{\mathbb{F}}} = \mathcal{H}_{a, A}, \tag{3.5}$$

where $\mathcal{H}_{a, A}$ is the quasi-singular hyperplane associated to the pair (a, A) as defined in Section 1.1.3.

3.2. The hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ which arise from ε_{σ}

Let $\sigma \in \text{Aut}(\mathbb{F}) \setminus \{\text{id}_{\mathbb{F}}\}$. Now, for $M \in M_{n+1}(\mathbb{F}) \setminus \{\lambda I\}_{\lambda \in \mathbb{F}}$ we have

$$[M^{\perp f}] \cap \varepsilon_{\sigma}(\mathcal{P}) = \{[\mathbf{x} \otimes \xi] \mid \mathbf{x} \neq 0 \neq \xi, \xi(\mathbf{x}) = 0 \text{ and } \xi M \mathbf{x}^{\sigma} = 0\}.$$

We put

$$\begin{aligned} \mathcal{H}_{M, \sigma} &:= \varepsilon_{\sigma}^{-1}([M^{\perp f} \cap M_{n+1}(\mathbb{F})]) \\ &= \{([\mathbf{x}], [\xi]) \in \mathcal{P} \mid \xi M \mathbf{x}^{\sigma} = 0\}. \end{aligned} \tag{3.6}$$

The set $\mathcal{H}_{M, \sigma}$ is a geometric hyperplane of $A_{n,\{1,n\}}(\mathbb{F})$. By Corollary 1.11, it arises from ε_{σ} .

In particular, let $M = \mathbf{a} \otimes \alpha$ for $\mathbf{a} \otimes \alpha \in \text{Pure}(V \otimes V^*)$. Put $a = [\mathbf{a}]$ and $A := [\alpha^{\sigma^{-1}}]$.

Proposition 3.3. *With a and A as above, we have $\mathcal{H}_{\mathbf{a} \otimes \alpha, \sigma} = \mathcal{H}_{a, A}$.*

Proof. By (3.3) and (3.6) a point $([\mathbf{x}], [\xi])$ of $A_{n,\{1,n\}}(\mathbb{F})$ belongs to $\mathcal{H}_{\mathbf{a} \otimes \alpha, \sigma}$ if and only if $\alpha(\mathbf{x}^{\sigma})\xi(\mathbf{a}) = 0$. The latter is equivalent to $\alpha^{\sigma^{-1}}(\mathbf{x})\xi(\mathbf{a}) = 0$ which in turn characterizes the points of $\mathcal{H}_{\mathbf{a} \otimes \alpha^{\sigma^{-1}}, \text{id}_{\mathbb{F}}}$, by (3.4). Therefore $\mathcal{H}_{\mathbf{a} \otimes \alpha, \sigma} = \mathcal{H}_{\mathbf{a} \otimes \alpha^{\sigma^{-1}}, \text{id}_{\mathbb{F}}}$. However, with $a = [\mathbf{a}]$ and $A = [\alpha^{\sigma^{-1}}]$, we have $\mathcal{H}_{\mathbf{a} \otimes \alpha^{\sigma^{-1}}, \text{id}_{\mathbb{F}}} = \mathcal{H}_{a, A}$ by (3.5). Hence $\mathcal{H}_{\mathbf{a} \otimes \alpha, \sigma} = \mathcal{H}_{a, A}$, as claimed. \square

Proof of Theorem 1.12, Claim (1). Claim (1) of Theorem 1.12 immediately follows from (3.5) and Proposition 3.3. \square

4. Proof of Theorem 1.12, Claim (2)

In view of (3.5) of Section 3.1 and Proposition 3.3, Claim (2) of Theorem 1.12 amounts to the following:

Proposition 4.1. *Let ρ and σ be distinct automorphisms of \mathbb{F} with $\sigma \neq \text{id}_{\mathbb{F}}$ and let $M, N \in M_{n+1}(\mathbb{F}) \setminus \{O\}$ be such that*

$$\xi M \mathbf{x}^\rho = 0 \text{ if and only if } \xi N \mathbf{x}^\sigma = 0 \quad (4.1)$$

for every null-traced pure tensor $\mathbf{x} \otimes \xi \in \text{Pure}((V \otimes V^*)_0)$. Then $\text{rank}(N) = 1$.

Indeed, (4.1) restricted to the pairs (\mathbf{x}, ξ) such that $\xi(\mathbf{x}) = 0$ is equivalent to the equality $\mathcal{H}_{M,\rho} = \mathcal{H}_{N,\sigma}$. By Proposition 3.3 and since $\sigma \neq \text{id}_{\mathbb{F}}$ by assumption, $\text{rank}(N) = 1$ if and only if $\mathcal{H}_{N,\sigma}$ is quasi-singular. If $\rho \neq \text{id}_{\mathbb{F}}$ the same holds true for M and $\mathcal{H}_{M,\rho}$. In contrast, let $\rho = \text{id}_{\mathbb{F}}$. Then $\mathcal{H}_{M+\lambda I,\rho} = \mathcal{H}_{M,\rho}$ for every $\lambda \in \mathbb{F}$. If $\mathcal{H}_{M,\rho}$ is quasi-singular then $\text{rank}(M + \lambda I) = 1$ for exactly one choice of λ .

Condition (4.1) of Proposition 4.1 can be rephrased as follows:

$$\langle \mathbf{x}, M \mathbf{x}^\rho \rangle = \langle \mathbf{x}, N \mathbf{x}^\sigma \rangle, \forall \mathbf{x} \in V. \quad (4.2)$$

4.1. Proof of Proposition 4.1 in the case $n \geq 3$

In this and the next subsection σ, ρ, M and N satisfy the hypotheses of Proposition 4.1. In the present subsection we assume that $n > 2$.

Lemma 4.2. *We have $\dim \langle \mathbf{x}, \mathbf{y}, M \mathbf{x}^\rho, M \mathbf{y}^\rho \rangle = \dim \langle \mathbf{x}, \mathbf{y}, N \mathbf{x}^\sigma, N \mathbf{y}^\sigma \rangle \leq 3$ for every choice of $\mathbf{x}, \mathbf{y} \in V$.*

Proof. The equality $\dim \langle \mathbf{x}, \mathbf{y}, M \mathbf{x}^\rho, M \mathbf{y}^\rho \rangle = \dim \langle \mathbf{x}, \mathbf{y}, N \mathbf{x}^\sigma, N \mathbf{y}^\sigma \rangle$ follows from (4.2). We shall prove that $\dim \langle \mathbf{x}, \mathbf{y}, M \mathbf{x}^\rho, M \mathbf{y}^\rho \rangle \leq 3$ for every choice of $\mathbf{x}, \mathbf{y} \in V$. By (4.2), for every $\mathbf{x} \in V$ there exist scalars $\lambda_{\mathbf{x}}, \mu_{\mathbf{x}} \in \mathbb{F}$ such that

$$N \mathbf{x}^\sigma = \mathbf{x} \lambda_{\mathbf{x}} + M \mathbf{x}^\rho \mu_{\mathbf{x}}. \quad (4.3)$$

Hence

$$\begin{aligned} N(\mathbf{x} + \mathbf{y})^\sigma &= \mathbf{x} \lambda_{\mathbf{x}} + \mathbf{y} \lambda_{\mathbf{y}} + M \mathbf{x}^\rho \mu_{\mathbf{x}} + M \mathbf{y}^\rho \mu_{\mathbf{y}} \\ &= (\mathbf{x} + \mathbf{y}) \lambda_{\mathbf{x}+\mathbf{y}} + M(\mathbf{x} + \mathbf{y})^\rho \mu_{\mathbf{x}+\mathbf{y}}. \end{aligned} \quad (4.4)$$

For a contradiction, suppose that $\mathbf{x}, \mathbf{y} \in V$ exist such that $\dim \langle \mathbf{x}, \mathbf{y}, M \mathbf{x}^\rho, M \mathbf{y}^\rho \rangle = 4$. Then (4.4) implies that $\lambda_{\mathbf{x}} = \lambda_{\mathbf{x}+\mathbf{y}} = \lambda_{\mathbf{y}}$ and $\mu_{\mathbf{x}} = \mu_{\mathbf{x}+\mathbf{y}} = \mu_{\mathbf{y}}$. Hence $\lambda_{\mathbf{x}} = \lambda_{\mathbf{y}}$ and $\mu_{\mathbf{x}} = \mu_{\mathbf{y}}$. Similarly, $\lambda_{\mathbf{x}t} = \lambda_{\mathbf{y}}$ and $\mu_{\mathbf{x}t} = \mu_{\mathbf{y}}$ for every $t \in \mathbb{F}^* := \mathbb{F} \setminus \{0\}$. Therefore $\lambda_{\mathbf{x}t} = \lambda_{\mathbf{x}}$ and $\mu_{\mathbf{x}t} = \mu_{\mathbf{x}}$ for every $t \in \mathbb{F}^*$. So, with $\lambda := \lambda_{\mathbf{x}}$ and $\mu := \mu_{\mathbf{x}}$, for every $t \in \mathbb{F}$ we have

$$\begin{aligned} \mathbf{x}t\lambda + M \mathbf{x}^\rho t^\rho \mu &= \mathbf{x}t\lambda_{\mathbf{x}t} + M \mathbf{x}^\rho t^\rho \mu_{\mathbf{x}t} = N(\mathbf{x}t)^\sigma = \\ &= N \mathbf{x}^\sigma t^\sigma = (\mathbf{x} \lambda_{\mathbf{x}} + M \mathbf{x}^\rho \mu_{\mathbf{x}}) t^\sigma = \mathbf{x}t^\sigma \lambda + M \mathbf{x}^\rho t^\sigma \mu. \end{aligned}$$

Therefore,

$$\mathbf{x}t\lambda + M \mathbf{x}^\rho t^\rho \mu = \mathbf{x}t^\sigma \lambda + M \mathbf{x}^\rho t^\sigma \mu, \forall t \in \mathbb{F}. \quad (4.5)$$

However \mathbf{x} and $M\mathbf{x}^\rho$ are non-proportional, since $\dim\langle \mathbf{x}, \mathbf{y}, M\mathbf{x}^\rho, M\mathbf{y}^\rho \rangle = 4$ by assumption. So, (4.5) implies that

$$t\lambda = t^\sigma\lambda \text{ and } t^\rho\mu = t^\sigma\mu \text{ for every } t \in \mathbb{F}. \tag{4.6}$$

If both λ and μ are null then from the equality $N\mathbf{x}^\sigma = \mathbf{x}\lambda + M\mathbf{x}^\rho\mu$ we obtain that $N\mathbf{x}^\sigma = 0$. Hence $\dim\langle \mathbf{x}, \mathbf{y}, N\mathbf{x}^\sigma, N\mathbf{y}^\sigma \rangle \leq 3$. However $\dim\langle \mathbf{x}, \mathbf{y}, N\mathbf{x}^\sigma, N\mathbf{y}^\sigma \rangle = \dim\langle \mathbf{x}, \mathbf{y}, M\mathbf{x}^\rho, M\mathbf{y}^\rho \rangle$ and the latter is equal to 4 by assumption; we end up with a contradiction. In order to avoid it, we are forced to admit that at least one of λ or μ is different from 0. If $\lambda \neq 0$ then the first equation of (4.6) yields $\sigma = \text{id}_{\mathbb{F}}$ while if $\mu \neq 0$ then we obtain $\rho = \sigma$. In either of these two cases we contradict the assumptions made on σ and ρ . \square

Lemma 4.3. *Let $\mathbf{a} \in V$ be such that $N\mathbf{a}^\sigma \notin \langle \mathbf{a} \rangle$. Then the 2-subspace $L_{\mathbf{a}} := \langle \mathbf{a}, N\mathbf{a}^\sigma \rangle$ of V contains $N\mathbf{x}^\sigma$ for every $\mathbf{x} \in V$.*

Proof. As $L_{\mathbf{a}} \subsetneq V$, the set $V \setminus L_{\mathbf{a}}$ spans V . So, in order to prove that $N\mathbf{x}^\sigma \in L_{\mathbf{a}}$ for every $\mathbf{x} \in V$ it is sufficient to prove that this is the case for every $\mathbf{x} \in V \setminus L_{\mathbf{a}}$.

Let $\mathbf{x} \in V \setminus L_{\mathbf{a}}$. By Lemma 4.2, there exists a unique scalar $\lambda_{\mathbf{x}} \in \mathbb{F}$ and a unique vector $v_{\mathbf{x}} \in L_{\mathbf{a}}$ such that

$$N\mathbf{x}^\sigma = \mathbf{x}\lambda_{\mathbf{x}} + v_{\mathbf{x}}. \tag{4.7}$$

As $n \geq 3$, a vector $\mathbf{y} \in V$ also exists such that $\dim\langle \mathbf{x}, \mathbf{y}, L_{\mathbf{a}} \rangle = 4$. According to (4.7), scalars $\lambda_{\mathbf{y}}$ and $\lambda_{\mathbf{x}+\mathbf{y}}$ and vectors $v_{\mathbf{y}}, v_{\mathbf{x}+\mathbf{y}} \in L_{\mathbf{a}}$ exist such that

$$\begin{aligned} N\mathbf{y}^\sigma &= \mathbf{y}\lambda_{\mathbf{y}} + v_{\mathbf{y}}, \\ N(\mathbf{x} + \mathbf{y})^\sigma &= (\mathbf{x} + \mathbf{y})\lambda_{\mathbf{x}+\mathbf{y}} + v_{\mathbf{x}+\mathbf{y}} = \\ &= N\mathbf{x}^\sigma + N\mathbf{y}^\sigma = \mathbf{x}\lambda_{\mathbf{x}} + \mathbf{y}\lambda_{\mathbf{y}} + v_{\mathbf{x}} + v_{\mathbf{y}}. \end{aligned} \tag{4.8}$$

The last two equations of (4.8) yield $\lambda_{\mathbf{x}} = \lambda_{\mathbf{y}}$ ($= \lambda_{\mathbf{x}+\mathbf{y}}$). Similarly, $\lambda_{\mathbf{x}t} = \lambda_{\mathbf{y}}$ for every $t \in \mathbb{F}^*$. Consequently, $\lambda_{\mathbf{x}t} = \lambda_{\mathbf{x}}$ for every $t \in \mathbb{F}^*$. On the other hand, $N(\mathbf{x}t)^\sigma = N\mathbf{x}^\sigma t^\sigma = \mathbf{x}\lambda_{\mathbf{x}}t^\sigma + v_{\mathbf{x}}t^\sigma$. Hence $t\lambda_{\mathbf{x}t} = \lambda_{\mathbf{x}}t^\sigma$, namely $\lambda_{\mathbf{x}t} = \lambda_{\mathbf{x}}t^{\sigma-1}$. However $\lambda_{\mathbf{x}t} = \lambda_{\mathbf{x}}$, as previously proved. So, if $\lambda_{\mathbf{x}} \neq 0$ we obtain that $t^{\sigma-1} = 1$ for every $t \in \mathbb{F}^*$, namely $\sigma = \text{id}_{\mathbb{F}}$, while $\sigma \neq \text{id}_{\mathbb{F}}$ by assumption. Therefore $\lambda_{\mathbf{x}} = 0$ and (4.7) implies that $N\mathbf{x}^\sigma \in L_{\mathbf{a}}$. \square

Lemma 4.4. *Suppose that $N\mathbf{a}^\sigma \notin \langle \mathbf{a} \rangle$ for at least one vector $\mathbf{a} \in V \setminus \{0\}$. Then $\text{rank}(N) = 1$.*

Proof. With \mathbf{a} as in the hypotheses of the lemma, Lemma 4.3 implies that the image $\text{Im}(f)$ of the semilinear mapping $f : \mathbf{x} \rightarrow N\mathbf{x}^\sigma$ is a subspace of $L_{\mathbf{a}} = \langle \mathbf{a}, N\mathbf{a}^\sigma \rangle$. Hence the kernel $K := \text{Ker}(f)$ of f (which is the σ^{-1} -image of the kernel of N) has dimension $\dim(K) \geq n - 1$ (≥ 2 since $n \geq 3$ by assumption). We claim that $L_{\mathbf{a}} \not\supseteq K$. This is obvious when $n > 3$. When $n = 3$ the claim follows from the fact that $N\mathbf{a}^\sigma \neq 0$, since $N\mathbf{a}^\sigma \notin \langle \mathbf{a} \rangle$ by assumption.

Pick a vector $\mathbf{k} \in K \setminus L_{\mathbf{a}}$ and put $\mathbf{b} := \mathbf{a} + \mathbf{k}$. Then $N\mathbf{b}^\sigma = N\mathbf{a}^\sigma \neq \mathbf{b}$. By Lemma 4.3 with \mathbf{a} replaced by \mathbf{b} we obtain that $\text{Im}(f) \subseteq L_{\mathbf{b}} := \langle \mathbf{b}, N\mathbf{b}^\sigma \rangle = \langle \mathbf{b}, N\mathbf{a}^\sigma \rangle$. Therefore $\text{Im}(f) \subseteq L_{\mathbf{a}} \cap L_{\mathbf{b}} = \langle N\mathbf{a}^\sigma \rangle$. Accordingly, $\text{rank}(N) = 1$. \square

In order to finish the proof of Proposition 4.1 when $n \geq 3$ the following case remains to be considered: $N\mathbf{a}^\sigma \in \langle \mathbf{a} \rangle$ for every $\mathbf{a} \in V$. In this case N is diagonal, say $N = \text{diag}(n_0, n_1, \dots, n_n)$. We are assuming that for every vector $\mathbf{x} = (x_i)_{i=0}^n$ of V there

exists a scalar $\lambda \in \mathbb{F}$ such that $n_i x_i^\sigma = x_i \lambda$ for every $i = 0, 1, \dots, n$. It is easily to see that this can happen only if $N = O$. However $N \neq O$ by assumption. Hence the hypothesis of Lemma 4.4 holds true and $\text{rank}(N) = 1$ by that lemma.

4.2. The case $n = 2$

Throughout this subsection $n = 2$. In this case condition (4.2) is equivalent to the following two conditions, where $(\mathbf{x}, M\mathbf{x}^\rho, N\mathbf{x}^\sigma)$ is the 3×3 matrix with \mathbf{x} , $M\mathbf{x}^\rho$ and $N\mathbf{x}^\sigma$ as the columns:

$$\det(\mathbf{x}, M\mathbf{x}^\rho, N\mathbf{x}^\sigma) = 0, \forall \mathbf{x} \in V; \quad (4.9)$$

$$M\mathbf{x}^\rho \in \langle \mathbf{x} \rangle \text{ if and only if } N\mathbf{x}^\sigma \in \langle \mathbf{x} \rangle, \forall \mathbf{x} \in V. \quad (4.10)$$

Let $m_{i,j}$ and $n_{i,j}$ be the (i, j) -entries of M and N respectively. For $\{i, j, k\} = \{0, 1, 2\}$, by (4.9) with $\mathbf{x} = \mathbf{e}_k$ we obtain that

$$m_{i,k}n_{j,k} = m_{j,k}n_{i,k}. \quad (4.11)$$

Equality (4.11) shows that there exist a matrix $R = (r_{i,j})_{i,j=0}^2 \in M_3(\mathbb{F})$ and diagonal matrices

$$\begin{aligned} \Delta_M &= \text{diag}(\mu_0, \mu_1, \mu_2), & \Delta_N &= \text{diag}(\nu_0, \nu_1, \nu_2), \\ D_M &= \text{diag}(m_0, m_1, m_2), & D_N &= \text{diag}(n_0, n_1, n_2) \end{aligned}$$

such that $r_{i,i} = 0$ for every $i = 0, 1, 2$ and

$$M = R\Delta_M + D_M, N = R\Delta_N + D_N. \quad (4.12)$$

So, if $\mathbf{r}_k = (r_{i,k})_{i=0}^2$, $\mathbf{m}_k = (m_{i,k})_{i=0}^2$ and $\mathbf{n}_k = (n_{i,k})_{i=0}^2$ are the $(k+1)$ -th columns of R , M and N respectively, we have $m_{i,k} = r_{i,k}\mu_k$ for every $i \neq k$, $n_{i,k} = r_{i,k}\nu_k$ for every $i \neq k$, $m_k = m_{k,k}$ and $n_k = n_{k,k}$ for every $k = 0, 1, 2$. Moreover (4.10) implies that we can choose R , Δ_M and Δ_N in such a way that

$$\mathbf{r}_k \neq 0 \text{ if and only if } \mu_k \neq 0 \text{ if and only if } \nu_k \neq 0. \quad (4.13)$$

A matrix R as above will be called a *skeleton* of the pair (M, N) . Henceforth R will always stand for a given skeleton of (M, N) . We warn that if $R \neq O$ then R is not uniquely determined by M and N . Indeed M and N determine R up to right multiplication RD with $D = \text{diag}(\lambda_0, \lambda_1, \lambda_2)$ such that, for $k \in \{0, 1, 2\}$, if $\mathbf{r}_k \neq 0$ then $\lambda_k \neq 0$.

Suppose firstly that $R = O$. Then $M = D_M$ and $N = D_N$. With the help of the Identity Principle for semi-polynomials (Theorem 2.1) we see that $N \equiv \mathbf{e}_k \otimes \eta_k$ for some $k \in \{0, 1, 2\}$. Hence $\text{rank}(N) = 1$. For the rest of this subsection we assume that $R \neq O$.

4.2.1 The case where $R \neq O$ but two columns of R are null

Suppose $R \neq O$ but two of its columns are null. To fix ideas, let $\mathbf{r}_0 \neq 0 = \mathbf{r}_1 = \mathbf{r}_2$. If $\mathbf{r}_0 \neq \mathbf{e}_1$, we can replace the natural basis $E = (\mathbf{e}_0, \mathbf{e}_1, \mathbf{e}_2)$ of V with a new basis $E' = (\mathbf{e}'_0, \mathbf{e}'_1, \mathbf{e}'_2)$ such that $\mathbf{e}'_0 = \mathbf{e}_0$, $\mathbf{e}'_1 = \mathbf{r}_0$ and $\langle \mathbf{e}'_1, \mathbf{e}'_2 \rangle = \langle \mathbf{e}_1, \mathbf{e}_2 \rangle$. (Recall that $\mathbf{r}_0 \in \langle \mathbf{e}_1, \mathbf{e}_2 \rangle$, since $r_{0,0} = 0$). If $C \in M_3(\mathbb{F})$ is the matrix of this change of bases, then we must replace M and N in (4.2)

with $C^{-1}MC^\rho$ and $C^{-1}NC^\sigma$ respectively. However $C^{-1}NC^\sigma$ and N have the same rank. Hence there is no loss in assuming that $\mathbf{r}_0 = \mathbf{e}_1$.

So, let $\mathbf{r}_0 = \mathbf{e}_1$. Accordingly, $R = E_{1,0} = \mathbf{e}_1 \otimes \eta_0$. From (4.9) with $\mathbf{x} = (x_i)_{i=0}^2$ we obtain

$$\begin{aligned} \det(\mathbf{x}, M\mathbf{x}^\rho, N\mathbf{x}^\sigma) &= \\ &= x_0^{\rho+\sigma}x_2(m_0\nu_0 - n_0\mu_0) + x_0^{1+\rho}x_2^\sigma n_2\mu_0 - x_0^{1+\sigma}x_2^\rho m_2\nu_0 + \\ &+ x_0^\rho m_0(x_1^\sigma x_2 n_1 - x_2^\sigma x_1 n_2) + x_0^\sigma n_0(x_2^\rho x_1 m_2 - x_1^\rho x_2 m_1) + \\ &+ x_0(x_1^\rho x_2^\sigma m_1 n_2 - x_1^\sigma x_2^\rho m_2 n_1) = 0. \end{aligned} \tag{4.14}$$

Suppose firstly that $\rho \neq \text{id}_{\mathbb{F}}$. Then from (4.14) and Identity Principle (Theorem 2.1) and recalling that $\mu_0 \neq 0 \neq \nu_0$ (by (4.13), since $\mathbf{r}_0 \neq 0$), we get $m_0\nu_0 = n_0\mu_0$, $n_2 = m_2 = 0$ and $m_0n_1 = n_0m_1 = 0$. As $\mu_0 \neq 0 \neq \nu_0$, either $m_0 = n_0 = 0$ or $m_0 \neq 0 \neq n_0$. In the latter case $m_1 = n_1 = 0$. In both cases $\text{rank}(M) = \text{rank}(N) = 1$.

Let now $\rho = \text{id}_{\mathbb{F}}$. Then $x_0^{\rho+\sigma} = x_0^{1+\sigma}$, $x_0^{1+\rho} = x_0^2$ and $x_i^\rho = x_i$ for $i = 0, 1, 2$. Accordingly, some of the semi-monomial that occur in (4.14) group together to form one single semi-monomial. Thus we obtain the following:

$$\begin{aligned} \det(\mathbf{x}, M\mathbf{x}^\rho, N\mathbf{x}^\sigma) &= x_0^{1+\sigma}x_2(m_0\nu_0 - n_0\mu_0 - m_2\nu_0) + \\ &+ x_0^\sigma x_1 x_2 n_0(m_2 - m_1) + x_0^2 x_2^\sigma n_2 \mu_0 + \\ &+ x_0 x_1^\sigma x_2 n_1(m_0 - m_2) + x_0 x_1 x_2^\sigma n_2(m_1 - m_0) = 0. \end{aligned} \tag{4.15}$$

No two of the five semi-monomials which appear in (4.15) have the same type. (This is still the case when \mathbb{F} is perfect of characteristic 2 and $\sigma : t \mapsto t^2$ is its Frobenius automorphism.) The Identity Principle now yields the following:

$$\begin{aligned} (m_0 - m_2)\nu_0 &= \mu_0 n_0, \\ (m_i - m_0)n_j &= 0 \text{ for } \{i, j\} = \{1, 2\}, \\ (m_i - m_j)n_0 &= 0 \text{ for } \{i, j\} = \{1, 2\}, \\ \mu_0 n_2 &= 0. \end{aligned} \tag{4.16}$$

However $\mu_0 \neq 0$. So, the last condition of (4.16) implies that $n_2 = 0$. Suppose that $n_1 \neq 0$. Then $m_2 = m_0$ by the second of (4.16). The first equation of (4.16) now yields $\mu_0 n_0 = 0$, hence $n_0 = 0$ because $\mu_0 \neq 0$. Therefore at least one of n_0 or n_1 is equal to 0. Consequently $\text{rank}(N) = 1$.

Remark 4.5. It is clear from the above that the relations we can deduce by the Identity Principle from the equation $\det(\mathbf{x}, M\mathbf{x}^\rho, N\mathbf{x}^\sigma) = 0$ under the assumption that $\rho \neq \text{id}_{\mathbb{F}}$ are always stronger than those we get when $\rho = \text{id}_{\mathbb{F}}$. Consequently, whatever constraint we obtain on N under the hypothesis that $\rho = \text{id}_{\mathbb{F}}$, the same and possibly more can be obtained if we assume that $\rho \neq \text{id}_{\mathbb{F}}$. In view of this, when we aim at proving something on N and the examination of the case $\rho = \text{id}_{\mathbb{F}}$ is enough to reach the conclusions we want, then we can safely neglect the case $\rho \neq \text{id}_{\mathbb{F}}$, thus saving lots of computations. In the next subsection we shall take advantage of this shortcut.

4.2.2 The case where at most one column of R is null

Suppose that at most one column of R is null. To fix ideas, let $\mathbf{r}_i \neq 0$ for $i \leq s$ where $s \in \{1, 2\}$ and $\mathbf{r}_2 = 0$ if $s = 1$. Therefore $\mu_i \neq 0 = \mu_j$ and $\nu_i \neq 0 = \nu_j$ for $i \leq s < j$. Accordingly, $\mathbf{n}_i \neq 0$ for every choice of $i \leq s$.

Lemma 4.6. *If $\mathbf{n}_i \equiv \mathbf{n}_j$ for every choice of $i < j \leq s$ then $\text{rank}(N) = 1$.*

Proof. Suppose that $\mathbf{n}_i \equiv \mathbf{n}_j$ for every choice of $i < j \leq s$. If $s = 2$ then clearly $\text{rank}(N) = 1$. Suppose $s = 1$. By (4.9) we obtain the following

$$\begin{aligned} \det(\mathbf{x}, M\mathbf{x}^\rho, N\mathbf{x}^\sigma) &= \\ &= n_2(r_{1,0}\mu_0x_0^{\rho+1} - r_{0,1}\mu_1x_1^{\rho+1} + m_1x_0x_1^\rho - m_0x_0^\rho x_1)x_2^\sigma + \\ &+ P_\rho(x_0, x_1)x_2^\rho + P_1(x_0, x_1)x_2 + P_0(x_0, x_1) = 0 \end{aligned} \quad (4.17)$$

for suitable semi-polynomials P_ρ , P_1 and P_0 in the unknowns x_0 and x_1 . By the Identity principle, either $n_2 = 0$ or

$$r_{1,0}\mu_0x_0^{\rho+1} - r_{0,1}\mu_1x_1^{\rho+1} + m_1x_0x_1^\rho - m_0x_0^\rho x_1 = 0 \quad (4.18)$$

for every choice of x_0 and x_1 . The Identity Principle applied to (4.18) implies that $r_{1,0} = r_{0,1} = 0$ (recall that $\mu_0 \neq 0 \neq \mu_1$ by (4.13), since by assumption neither \mathbf{r}_0 nor \mathbf{r}_1 are null). We also obtain that $m_1 = m_0$ ($= 0$ if $\rho \neq \text{id}_{\mathbb{F}}$), but we are not going to exploit this information.

Summarizing, either $n_2 = 0$ or $r_{0,1} = r_{1,0} = 0$. If $n_2 = 0$ then $\text{rank}(N) = 1$ because $\mathbf{n}_0 \equiv \mathbf{n}_1$. Suppose that $n_2 \neq 0$. Then $r_{0,1} = r_{1,0} = 0$. Accordingly, $n_{0,1} = n_{1,0} = 0$ and therefore $n_0 = n_1 = 0$ since $\mathbf{n}_0 \equiv \mathbf{n}_1$. Consequently, the first two rows of N are null. Hence $\text{rank}(N) = 1$. \square

Lemma 4.7. *We have $\mathbf{n}_0 \not\equiv \mathbf{n}_1$ if and only if $\mathbf{r}_0 = \mathbf{e}_1$, $\mathbf{r}_1 = \mathbf{e}_0$ and $n_0n_1 \neq \nu_0\nu_1$.*

Proof. Suppose that $\rho = \text{id}_{\mathbb{F}}$. By (4.9) with $\mathbf{x} \in \langle \mathbf{e}_0, \mathbf{e}_1 \rangle$ we obtain the following relations:

$$\begin{aligned} r_{2,1}r_{1,0}\nu_1 &= r_{2,0}n_1, \\ r_{2,0}(\nu_0(m_1 - m_0) + \mu_0n_0) &= r_{2,1}r_{1,0}\mu_1\nu_0, \\ r_{2,1}(\nu_1(m_0 - m_1) + \mu_1n_1) &= r_{2,0}r_{0,1}\mu_0\nu_1, \\ r_{2,0}r_{0,1}\nu_0 &= r_{2,1}n_0. \end{aligned} \quad (4.19)$$

Suppose that $r_{1,0} \neq 0$. Then $n_{2,1} = r_{2,1}\nu_1 = r_{2,0}n_1/r_{1,0} = r_{2,0}\nu_0n_1/r_{1,0}\nu_0 = n_{2,0}\lambda_{0,1}$, where $\lambda_{0,1} := n_1/n_{1,0}$. Trivially, $n_{1,1} = n_1 = n_{1,0}\lambda_{0,1}$. Therefore

$$n_{i,1} = n_{i,0}\lambda_{0,1} \text{ for } i \in \{1, 2\}, \text{ where } \lambda_{0,1} = \frac{n_1}{n_{1,0}}. \quad (4.20)$$

Similarly, if $r_{0,1} \neq 0$ then by exploiting the last equation of (4.19) we obtain:

$$n_{i,0} = n_{i,1}\lambda_{1,0} \text{ for } i \in \{0, 2\}, \text{ where } \lambda_{1,0} = \frac{n_0}{n_{0,1}}. \quad (4.21)$$

By (4.20), if $n_{2,1} \neq 0$ then $\lambda_{0,1} \neq 0$ and $n_{2,0} \neq 0$. Similarly, by (4.21), if $n_{2,0} \neq 0$ then $\lambda_{1,0} \neq 0 \neq n_{2,1}$. So, either $\lambda_{0,1} \neq 0 \neq \lambda_{1,0}$ and $n_{2,1} \neq 0 \neq n_{2,0}$, or $n_{2,0} = n_{2,1} = 0$, hence $r_{2,0} = r_{2,1} = 0$. In the latter case, up to replace ν_0, ν_1, μ_0 and μ_1 with suitable non-zero scalars, we can assume that $\mathbf{r}_0 = \mathbf{e}_1$ and $\mathbf{r}_1 = \mathbf{e}_0$.

Suppose the first case occurs: $n_{2,0} \neq 0 \neq n_{2,1}$. Then $\lambda_{1,0} \neq 0 \neq \lambda_{0,1}$ and $n_{2,1} = n_{2,0}\lambda_{0,1} = n_{2,1}\lambda_{1,0}\lambda_{0,1}$. Therefore $\lambda_{1,0}\lambda_{0,1} = 1$. Hence $n_{1,1} = n_{1,0} \cdot n_{0,1}/n_0 = n_{1,0}\lambda_{1,0}^{-1} = n_{1,0}\lambda_{0,1}$. So, $n_{i,1} = n_{i,0}\lambda_{0,1}$ for every i , namely $\mathbf{n}_1 = \mathbf{n}_0\lambda_{0,1}$. In this case $\mathbf{n}_1 \equiv \mathbf{n}_0$.

In the second case, where $\mathbf{r}_0 = \mathbf{e}_1$ and $\mathbf{r}_1 = \mathbf{e}_0$, we have $\mathbf{n}_1 \equiv \mathbf{n}_0$ if and only if $n_0n_1 = n_{0,1}n_{1,0}$ ($= \nu_1\nu_0$, since $r_{0,1} = r_{1,0} = 1$), as claimed in the statement of the lemma.

Suppose now that at least one of $r_{1,0}$ or $r_{0,1}$ is null. Let $r_{1,0} = 0$, to fix ideas. Then $r_{2,0} \neq 0$, since $\mathbf{r}_0 \neq 0$ by assumption. The first and second equation of (4.19) now yield $n_1 = 0$ and $m_0 - m_1 = \mu_0n_0/\nu_0$ respectively. As $n_1 = 0$, the third equation of (4.19) yields

$$r_{2,1}(m_0 - m_1) = r_{2,0}r_{0,1}\mu_0. \tag{4.22}$$

Suppose that $r_{0,1} \neq 0$. Then $m_0 \neq m_1$, otherwise (4.22) forces $r_{2,0} = 0$ while $r_{2,0} \neq 0$. Hence $r_{2,1} = r_{2,0}r_{0,1}\mu_0/(m_0 - m_1)$. However $m_0 - m_1 = \mu_0n_0/\nu_0$. We claim that $n_0 \neq 0$ and $r_{i,1} = r_{i,0}r_{0,1}\nu_0/n_0$, namely $n_{i,1} = n_{i,0} \cdot n_{0,1}/n_0$. This holds for $i = 2$ as well as for $i = 0$, as we already know from (4.21). However this relation also holds for $i = 1$, as $n_{1,1} = n_1 = 0$ and $n_{1,0} = r_{1,0}\nu_0 = 0$, since $r_{1,0} = 0$ by assumption. So, $\mathbf{n}_1 \equiv \mathbf{n}_0$.

On the other hand, still assuming that $r_{1,0} = 0$, suppose that $r_{0,1} = 0$. Then $r_{2,1} \neq 0$ since $\mathbf{r}_1 \neq 0$ and, by the fourth equation of (4.19), we also have $n_0 = 0$. So, $\mathbf{r}_0 = \mathbf{r}_1 = \mathbf{e}_2$, $\mathbf{n}_0 = \mathbf{e}_2\nu_0$ and $\mathbf{n}_1 = \mathbf{e}_2\nu_1$. Again, $\mathbf{n}_0 \equiv \mathbf{n}_1$.

We have proved that the statement of the lemma holds true when $\rho = \text{id}_{\mathbb{F}}$. By Remark 4.5, the same holds when $\rho \neq \text{id}_{\mathbb{F}}$. □

Lemma 4.8. *Let $\mathbf{r}_0 = \mathbf{e}_1$, $\mathbf{r}_1 = \mathbf{e}_0$ and $\mathbf{r}_2 = 0$. Then $\mathbf{n}_0 \equiv \mathbf{n}_1$.*

Proof. Suppose firstly that $\rho = \text{id}_{\mathbb{F}}$. By (4.9) we obtain that $n_2 = 0$ and

$$\begin{aligned} \nu_0(m_0 - m_2) &= \mu_0n_0, & \nu_1(m_1 - m_2) &= \mu_1n_1. \\ n_0(m_1 - m_2) &= \mu_1\nu_0, & n_1(m_0 - m_2) &= \mu_0\nu_1. \end{aligned} \tag{4.23}$$

The third and fourth equation of (4.23) imply $n_1 \neq 0 \neq n_0$. From the first and fourth equation (the second and the third) we obtain $m_0 - m_2 = \mu_0n_0/\nu_0 = \mu_0\nu_1/n_1$ (respectively $m_1 - m_2 = \mu_1n_1/\nu_1 = \mu_1\nu_0/n_0$). Hence $n_0/\nu_0 = \nu_1/n_1$, namely $n_0n_1 = \nu_0\nu_1$. Therefore $\mathbf{n}_0 \equiv \mathbf{n}_1$, by Lemma 4.7. In view of Remark 4.5, we can omit the examination of the case $\rho \neq \text{id}_{\mathbb{F}}$. □

Lemma 4.9. *We have $\mathbf{n}_0 \equiv \mathbf{n}_1$.*

Proof. For a contradiction, suppose that $\mathbf{n}_0 \not\equiv \mathbf{n}_1$. Then $\mathbf{r}_0 = \mathbf{e}_1$ and $\mathbf{r}_1 = \mathbf{e}_0$ by Lemma 4.7. The column \mathbf{n}_2 , which is non-null by Lemma 4.8, cannot be proportional to both \mathbf{n}_0 and \mathbf{n}_1 . Therefore, by Lemma 4.7, either $\mathbf{r}_0 = \mathbf{e}_2$ and $\mathbf{r}_2 = \mathbf{e}_0$ or $\mathbf{r}_1 = \mathbf{e}_2$ and $\mathbf{r}_2 = \mathbf{e}_1$. Each of these two cases crashes against the fact that $\mathbf{r}_0 = \mathbf{e}_1$ and $\mathbf{r}_1 = \mathbf{e}_0$. □

End of the proof of Proposition 4.1. If $s = 1$ the conclusion $\text{rank}(N) = 1$ follows from Lemmas 4.6 and 4.9. When $s = 2$ the same argument used to conclude that $\mathbf{n}_0 \equiv \mathbf{n}_1$ also yields $\mathbf{n}_1 \equiv \mathbf{n}_2$. Again, $\text{rank}(N) = 1$ by Lemma 4.6. □

5. Proof of Theorem 1.14

In the proof of the next lemma \perp is the collinearity relation of $A_{n,\{1,n\}}(\mathbb{F})$ and, for a point (x, X) of $A_{n,\{1,n\}}(\mathbb{F})$, $(x, X)^\perp = \mathcal{M}_x \cup \mathcal{M}_X$ is the set of points of $A_{n,\{1,n\}}(\mathbb{F})$ collinear with (x, X) or equal to it. Recall that two points (x, X) and (y, Y) of $A_{n,\{1,n\}}(\mathbb{F})$ are collinear if and only if either $x = y$ or $X = Y$; they are at distance at most 2 if and only if $x \in Y$ or $y \in X$.

Lemma 5.1. *Let (a, A) and (b, B) be points of $A_{n,\{1,n\}}(\mathbb{F})$ at distance 3 in the collinearity graph of $A_{n,\{1,n\}}(\mathbb{F})$. Then $\mathcal{H}_{a,A} \cap \mathcal{H}_{b,B}$, which is a hyperplane of the singular hyperplane $\mathcal{H}_{a,A}$ of $A_{n,\{1,n\}}(\mathbb{F})$, is a maximal subspace of $\mathcal{H}_{a,A}$.*

Proof. Put $\mathcal{H} := \mathcal{H}_{a,A}$, $\mathcal{I} := \mathcal{H}_{a,A} \cap \mathcal{H}_{b,B}$ and $\mathcal{C} := \mathcal{H} \setminus \mathcal{I}$. We shall prove that \perp induces a connected graph on \mathcal{C} . The conclusion will follow from Shult [Shu11, Lemma 4.1.1].

Recall that, for a point (p, H) of $A_{n,\{1,n\}}(\mathbb{F})$, the hyperplane $\mathcal{H}_{p,H}$ is the set of points at distance at most 2 from (p, H) . Accordingly, \mathcal{H} is the set of points at distance at most 2 from (a, A) and \mathcal{I} is the set of points at distance at most 2 from both (a, A) and (b, B) . Hence $(a, A) \in \mathcal{C}$, as (b, B) has distance 3 from (a, A) by assumption. We shall prove that every point $(c, C) \in \mathcal{C}$ can be connected to (a, A) by a path fully contained in \mathcal{C} .

If either $(c, C) \perp (a, A)$ or $(c, C)^\perp \cap (a, A)^\perp \not\subseteq \mathcal{I}$ there is nothing to prove. Suppose that (c, C) is at distance 2 from (a, A) . Up to duality, we can assume that $c \in A$. Then $(c, A) \in (a, A)^\perp \cap (c, C)^\perp$. As both (a, A) and (c, C) are at distance 3 from (b, B) (recall that $(c, C) \in \mathcal{C}$), neither $b \in A$ nor $c \in B$. Accordingly, (c, A) is at distance 3 from (b, B) , namely $(c, A) \in \mathcal{C}$. Hence $(c, C) \perp (c, A) \perp (a, A)$ is a path in \mathcal{C} from (c, C) to (a, A) . \square

Throughout the rest of this section we assume that $|\text{Aut}(\mathbb{F})| > 1$. For $\sigma \in \text{Aut}(\mathbb{F})$, if \mathcal{H} is a hyperplane of $A_{n,\{1,n\}}(\mathbb{F})$ which arises from σ , we denote by $\varepsilon_{\sigma|\mathcal{H}}$ the embedding of \mathcal{H} in $\langle \varepsilon_\sigma(\mathcal{H}) \rangle$ induced by ε_σ on \mathcal{H} .

Recall that, by Theorem 1.12, the quasi-singular hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ arise from ε_σ for every $\sigma \in \text{Aut}(\mathbb{F})$ while the hyperplanes which are not quasi-singular arise from ε_σ for at most one $\sigma \in \text{Aut}(\mathbb{F})$. Recall also that $\varepsilon_{\text{nat}} = \varepsilon_\sigma$ with $\sigma = \text{id}_{\mathbb{F}}$.

Lemma 5.2. *For every singular hyperplane \mathcal{H}_1 of $A_{n,\{1,n\}}(\mathbb{F})$ there exists a hyperplane \mathcal{H}_2 of $A_{n,\{1,n\}}(\mathbb{F})$ such that:*

- (1) *the intersection $\mathcal{H}_1 \cap \mathcal{H}_2$ is maximal as a subspace of \mathcal{H}_1 and, regarded as a hyperplane of \mathcal{H}_1 , it arises from $\varepsilon_{\sigma|\mathcal{H}_1}$ for every $\sigma \in \text{Aut}(\mathbb{F})$;*
- (2) *the hyperplane \mathcal{H}_2 arises from ε_ρ for a unique $\rho \in \text{Aut}(\mathbb{F})$ and $\mathcal{H}_1 \cap \mathcal{H}_2$, regarded as a hyperplane of \mathcal{H}_2 , arises from $\varepsilon_{\rho|\mathcal{H}_2}$.*

Proof. Given two points (a, A) and (b, B) of $A_{n,\{1,n\}}(\mathbb{F})$ at distance 3, let $\mathcal{H}_1 = \mathcal{H}_{a,A}$ and $\mathcal{H}'_1 = \mathcal{H}_{b,B}$. Then \mathcal{H}_1 and \mathcal{H}'_1 arise from ε_σ for every $\sigma \in \text{Aut}(\mathbb{F})$. Moreover $\mathcal{H}_1 \cap \mathcal{H}'_1 = \varepsilon_\sigma^{-1}(\langle \varepsilon_\sigma(\mathcal{H}_1) \rangle \cap \langle \varepsilon_\sigma(\mathcal{H}'_1) \rangle)$. By Lemma 5.1 the subspace $\mathcal{K} := \mathcal{H}_1 \cap \mathcal{H}'_1$ is a hyperplane as well as a maximal subspace of both \mathcal{H}_1 and \mathcal{H}'_1 . Hence \mathcal{K} arises from both $\varepsilon_{\sigma|\mathcal{H}_1}$ and $\varepsilon_{\sigma|\mathcal{H}'_1}$ by Proposition 1.2. Explicitly, for every $\sigma \in \text{Aut}(\mathbb{F})$ we have

$$\langle \varepsilon_\sigma(\mathcal{K}) \rangle = \langle \varepsilon_\sigma(\mathcal{H}_1) \rangle \cap \langle \varepsilon_\sigma(\mathcal{H}'_1) \rangle \text{ and } \mathcal{K} = \varepsilon_\sigma^{-1}(\langle \varepsilon_\sigma(\mathcal{K}) \rangle). \quad (5.1)$$

Let \mathbf{a} and \mathbf{b} be representative vectors of a and b respectively and α and β linear functional describing A and B and choose an automorphism $\rho \in \text{Aut}(\mathbb{F})$. We know from Section 3.1 and Proposition 3.3 that $\mathcal{H}_1 = \mathcal{H}_{\mathbf{a} \otimes \alpha^\rho, \rho}$ and $\mathcal{H}'_1 = \mathcal{H}_{\mathbf{b} \otimes \beta^\rho, \rho}$. As we have chosen (a, A) and (b, B) at mutual distance 3, neither $\mathbf{a} \equiv \mathbf{b}$ nor $\alpha \equiv \beta$. Hence all matrices of $\langle \mathbf{a} \otimes \alpha^\rho, \mathbf{b} \otimes \beta^\rho \rangle$ have rank 2 except those which are proportional to either $\mathbf{a} \otimes \alpha^\rho$ or $\mathbf{b} \otimes \beta^\rho$. Let M be one of the matrices of $\langle \mathbf{a} \otimes \alpha^\rho, \mathbf{b} \otimes \beta^\rho \rangle$ of rank 2 and put $\mathcal{H}_2 := \mathcal{H}_{M, \rho}$ (notation as in Section 3.2). Then \mathcal{H}_2 is not quasi-singular. Hence it arises from ε_ρ but it does not arise from ε_σ for any $\sigma \neq \rho$, by Theorem 1.12. Moreover $\mathcal{H}_2 \cap \mathcal{H}_1 = \mathcal{H}_2 \cap \mathcal{H}'_1 = \mathcal{H}_1 \cap \mathcal{H}'_1 = \mathcal{K}$. These equalities combined with (5.1) show that the hyperplane $\mathcal{H}_1 \cap \mathcal{H}_2$ of \mathcal{H}_2 arises from $\varepsilon_{\rho|_{\mathcal{H}_2}}$. \square

Lemma 5.3. *Given $\mathcal{H}_1, \mathcal{H}_2$ and ρ as in the statement of Lemma 5.2 and chosen an automorphism σ of \mathbb{F} different from ρ , there exists a hyperplane \mathcal{H}_3 of $A_{n, \{1, n\}}(\mathbb{F})$ which arises from ε_σ but not from ε_ρ and such that $\mathcal{H}_3 \cap \mathcal{H}_2$ properly contains $\mathcal{H}_1 \cap \mathcal{H}_2$. Moreover, $\mathcal{H}_1 \cap \mathcal{H}_3 = \mathcal{H}_1 \cap \mathcal{H}_2$ and $\varepsilon_\sigma(\mathcal{H}_1 \cap \mathcal{H}_2)$ spans $\langle \varepsilon_\sigma(\mathcal{H}_1) \rangle \cap \langle \varepsilon_\sigma(\mathcal{H}_3) \rangle$ while $\varepsilon_\sigma(\mathcal{H}_3 \cap \mathcal{H}_2)$ spans $\langle \varepsilon_\sigma(\mathcal{H}_3) \rangle$.*

Proof. Let Σ_σ be the codomain of ε_σ , namely $\Sigma_\sigma = \text{PG}(M_{n+1}^0(\mathbb{F}))$ if $\sigma = \text{id}_\mathbb{F}$ and $\Sigma_\sigma = \text{PG}(M_{n+1}(\mathbb{F}))$ otherwise.

Let \mathcal{X} be the collection of subspaces X of \mathcal{H}_2 which contain $\mathcal{H}_1 \cap \mathcal{H}_2$ and such that $\varepsilon_\sigma(X)$ does not span Σ_σ . Note that $\mathcal{H}_1 \cap \mathcal{H}_2 \in \mathcal{X}$. By Zorn's Lemma we can see that every member of \mathcal{X} is contained in a maximal member of \mathcal{X} . Let $X \in \mathcal{X}$ be one of them. We claim that $X \subsetneq \mathcal{H}_2$. Indeed if otherwise then $\varepsilon_\sigma(\mathcal{H}_2)$ is contained in a hyperplane H of Σ_σ . Hence $\varepsilon_\sigma^{-1}(H)$ is a hyperplane of $A_{n, \{1, n\}}(\mathbb{F})$ and contains \mathcal{H}_2 . However the hyperplanes of $A_{n, \{1, n\}}(\mathbb{F})$ are maximal subspaces. Therefore $\mathcal{H}_2 = \varepsilon_\sigma^{-1}(H)$. Consequently, \mathcal{H}_2 arises from both ε_ρ and ε_σ . This contradicts condition (2) of Lemma 5.2.

So, $X \subsetneq \mathcal{H}_2$. Pick $x \in \mathcal{H}_2 \setminus X$. Then $\varepsilon_\sigma(X \cup \{x\})$ spans Σ_σ , by the maximality of X in \mathcal{X} . This shows that $H := \langle \varepsilon_\sigma(X) \rangle$ is a hyperplane of Σ_σ . Put $\mathcal{H}_3 := \varepsilon_\sigma^{-1}(H)$. Then \mathcal{H}_3 is a hyperplane of $A_{n, \{1, n\}}(\mathbb{F})$ and arises from ε_σ . As \mathcal{H}_2 does not arise from ε_σ , we have $\mathcal{H}_3 \neq \mathcal{H}_2$. The intersection $\mathcal{H}_3 \cap \mathcal{H}_2$ contains X . It cannot be larger than X , otherwise $\varepsilon_\sigma(\mathcal{H}_3 \cap \mathcal{H}_2)$ spans Σ_σ by the maximality of X , while $\varepsilon_\sigma(\mathcal{H}_3 \cap \mathcal{H}_2)$ is contained in the hyperplane H of Σ_σ , by definition of \mathcal{H}_3 . Therefore $\mathcal{H}_3 \cap \mathcal{H}_2 = X$.

We claim that $X \supsetneq \mathcal{H}_1 \cap \mathcal{H}_2$. Indeed $\varepsilon_\sigma(\mathcal{H}_1 \cap \mathcal{H}_2)$ spans a hyperplane of the hyperplane $\langle \varepsilon_\sigma(\mathcal{H}_1) \rangle$ of Σ_σ (by (1) of Lemma 5.2) while $\varepsilon_\sigma(X)$ spans the hyperplane $H = \langle \varepsilon_\sigma(\mathcal{H}_3) \rangle$ of Σ_σ .

We have $\langle \varepsilon_\sigma(\mathcal{H}_3 \cap \mathcal{H}_2) \rangle = \langle \varepsilon_\sigma(\mathcal{H}_3) \rangle$ by definition of \mathcal{H}_3 . On the other hand, $\langle \varepsilon_\sigma(\mathcal{H}_3 \cap \mathcal{H}_1) \rangle$ contains $\langle \varepsilon_\sigma(\mathcal{H}_1 \cap \mathcal{H}_2) \rangle$, which is a hyperplane of $\langle \varepsilon_\sigma(\mathcal{H}_1) \rangle$ by (1) of Lemma 5.2. As $\mathcal{H}_1 \cap \mathcal{H}_2 \subsetneq \mathcal{H}_3$, the subspace $\langle \varepsilon_\sigma(\mathcal{H}_1 \cap \mathcal{H}_2) \rangle$ is also a hyperplane of $\langle \varepsilon_\sigma(\mathcal{H}_3) \rangle$ and must be the same as $\langle \varepsilon_\sigma(\mathcal{H}_1) \rangle \cap \langle \varepsilon_\sigma(\mathcal{H}_3) \rangle$. Consequently, $\mathcal{H}_1 \cap \mathcal{H}_2 = \mathcal{H}_1 \cap \mathcal{H}_3$.

It remains to prove that \mathcal{H}_3 does not arise from ε_ρ . Suppose the contrary. Then $\mathcal{H}_3 = \varepsilon_\rho^{-1}(H_3)$ for a projective hyperplane $H_3 = \langle \varepsilon_\rho(\mathcal{H}_3) \rangle$ of Σ_ρ , where Σ_ρ is defined just as Σ_σ but for replacing σ with ρ . Similarly, $\mathcal{H}_2 = \varepsilon_\rho^{-1}(H_2)$ and $\mathcal{H}_1 = \varepsilon_\rho^{-1}(H_1)$ for hyperplanes $H_2 = \langle \varepsilon_\rho(\mathcal{H}_2) \rangle$ and $H_1 = \langle \varepsilon_\rho(\mathcal{H}_2) \rangle$ of Σ_ρ , since \mathcal{H}_2 arises from ε_ρ by assumption while \mathcal{H}_1 , being singular, arises from ε_{nat} and each of its twistings. Accordingly, $\mathcal{H}_3 \cap \mathcal{H}_2 = \varepsilon_\rho^{-1}(H_3 \cap H_2)$ and $\mathcal{H}_1 \cap \mathcal{H}_2 = \varepsilon_\rho^{-1}(H_1 \cap H_2)$. Moreover, $H_1 \cap H_2 = \langle \varepsilon_\rho(\mathcal{H}_1 \cap \mathcal{H}_2) \rangle$ by condition (2) of Lemma 5.2. On the other hand, as previously noticed, the hyperplane $X = \mathcal{H}_3 \cap \mathcal{H}_2$ of \mathcal{H}_2 properly contains $\mathcal{H}_1 \cap \mathcal{H}_2$. Hence $\langle \varepsilon_\rho(X) \rangle$, which is contained in $H_3 \cap H_2$,

properly contains $H_1 \cap H_2$. It follows that $H_3 \cap H_2 = H_2$, namely $H_3 = H_2$. Consequently $\mathcal{H}_3 = \mathcal{H}_2$. However this cannot be. Indeed \mathcal{H}_3 arises from ε_σ while, by assumption, \mathcal{H}_2 does not. \square

End of the proof of Theorem 1.14. For a contradiction, suppose that $A_{n,\{1,n\}}(\mathbb{F})$ admits an embedding $\tilde{\varepsilon} : A_{n,\{1,n\}}(\mathbb{F}) \rightarrow \tilde{\Sigma}$ which covers both ε_σ and ε_ρ for two distinct automorphisms σ and ρ of \mathbb{F} . If a hyperplane \mathcal{H} arises from ε_σ or ε_ρ then it also arises from $\tilde{\varepsilon}$, by Proposition 2.2 and since all hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ are maximal subspaces [Pas24, Theorem 1.5]. The restriction $\tilde{\varepsilon}|_{\mathcal{H}}$ of $\tilde{\varepsilon}$ to \mathcal{H} covers $\varepsilon_{\sigma|_{\mathcal{H}}}$. Consequently, if \mathcal{K} is a hyperplane of \mathcal{H} which arises from $\varepsilon_{\sigma|_{\mathcal{H}}}$ and is maximal as a subspace of \mathcal{H} , then \mathcal{K} also arises from $\tilde{\varepsilon}|_{\mathcal{H}}$, by Proposition 2.2. Of course, the same claims hold true for the embedding ε_ρ and the hyperplanes which arise from it.

Let now $\mathcal{H}_1, \mathcal{H}_2$ and \mathcal{H}_3 be as in Lemmas 5.2 and 5.3. The singular hyperplane \mathcal{H}_1 arises from both ε_σ and ε_ρ , the hyperplane \mathcal{H}_2 arises from ε_ρ and \mathcal{H}_3 arises from ε_σ . Hence each of these hyperplanes arises from $\tilde{\varepsilon}$. Moreover, the hyperplane $\mathcal{K} := \mathcal{H}_1 \cap \mathcal{H}_2$ of \mathcal{H}_1 arises from $\tilde{\varepsilon}|_{\mathcal{H}_1}$, by condition (1) of Lemma 5.2. It follows that $K := \langle \tilde{\varepsilon}(\mathcal{K}) \rangle$ is a hyperplane of the hyperplane $H_1 := \langle \tilde{\varepsilon}(\mathcal{H}_1) \rangle$ of $\tilde{\Sigma}$. Moreover K is also contained in the hyperplanes $H_2 := \langle \tilde{\varepsilon}(\mathcal{H}_2) \rangle$ and $H_3 := \langle \tilde{\varepsilon}(\mathcal{H}_3) \rangle$. Clearly K is a hyperplane of both H_2 and H_3 . Moreover, $H_2 \neq H_3$, since $\mathcal{H}_2 \neq \mathcal{H}_3$. Therefore $H_2 \cap H_3 = K$. However this conclusion crashes against the fact that, as stated in Lemma 5.3, the intersection $\mathcal{H}_2 \cap \mathcal{H}_3$ properly contains $\mathcal{K} = \mathcal{H}_1 \cap \mathcal{H}_2 = \mathcal{H}_1 \cap \mathcal{H}_3$. Therefore no embedding of $A_{n,\{1,n\}}(\mathbb{F})$ covers both ε_σ and ε_ρ . \square

6. Quotients of ε_{nat} and its twistings

Consider $\varepsilon_\sigma : A_{n,\{1,n\}}(\mathbb{F}) \rightarrow \text{PG}(W)$ with $\sigma \in \text{Aut}(\mathbb{F})$, where $W = M_{n+1}^0(\mathbb{F})$ if $\sigma = \text{id}_{\mathbb{F}}$ and $W = M_{n+1}(\mathbb{F})$ otherwise.

Lemma 6.1. *Let S be a subspace of W . If all matrices of $S \setminus \{O\}$ have rank at least 3 then the corresponding subspace $[S]$ of $\text{PG}(W)$ defines a quotient of ε_σ . When $\sigma = \text{id}_{\mathbb{F}}$ the converse also holds: $[S]$ defines a quotient of ε_{nat} only if all matrices of $S \setminus \{O\}$ have rank at least 3.*

Proof. The ε_σ -images of the points of $A_{n,\{1,n\}}(\mathbb{F})$ are represented by matrices of rank 1. The sum of two matrices of rank 1 has rank at most 2. The first claim of the lemma follows from this remark and condition (2.1) of Section 2.3.1. Turning to the second claim, every null-traced matrix of rank 1 represents the ε_{nat} -image of a point of $A_{n,\{1,n\}}(\mathbb{F})$. The second claim of the lemma follows from the well known fact that every matrix of rank 2 is the sum of two matrices of rank 1. \square

By the first part of Lemma 6.1, for every non-singular matrix $M \in W$, the point $[M]$ of $\text{PG}(W)$ defines a quotient of ε_σ . In particular, $\varepsilon_\sigma/[I]$ is defined for every $\sigma \neq \text{id}_{\mathbb{F}}$ while $\varepsilon_{\text{nat}}/[I]$ is defined if and only if $\text{char}(\mathbb{F})$ is positive and divides $n+1$. Indeed $\text{trace}(I) = 0$ if and only if $\text{char}(\mathbb{F})$ is positive and divides $n+1$.

Following Steinbach and Van Maldeghem [SVM04] (also Thas and Van Maldeghem [TVM06]) we say that an embedding of $A_{n,\{1,n\}}(\mathbb{F})$ is *polarized* if all singular hyperplanes of $A_{n,\{1,n\}}(\mathbb{F})$ arise from it. For instance, as we know from Theorem 1.12, the natural embedding of $A_{n,\{1,n\}}(\mathbb{F})$ and all of its twistings are polarized.

Remark 6.2. We warn the reader that the embeddings we say to be polarized are called full weak embeddings in [TVM00a].

Theorem 6.3. *If $\sigma \in \text{Aut}(\mathbb{F}) \setminus \{\text{id}_{\mathbb{F}}\}$ or $\sigma = \text{id}_{\mathbb{F}}$ but either $\text{char}(\mathbb{F}) = 0$ or $\text{char}(\mathbb{F})$ is positive and prime to $n + 1$, then no proper quotient of ε_{σ} is polarized. When $\text{char}(\mathbb{F})$ is positive and divides $n + 1$ then $\varepsilon_{\text{nat}}/[I]$ is the unique polarized proper quotient of ε_{nat} .*

Proof. Let S be a subspace of W such that $[S]$ defines a polarized proper quotient of ε_{σ} and let M belong to S . By Proposition 3.3, for every pure tensor $\mathbf{a} \otimes \alpha \in \text{Pure}((V \otimes V^*)_0)$ the matrix M belongs to the hyperplane $H_{\mathbf{a} \otimes \alpha, \sigma}$ of W spanned by the pure tensors $\mathbf{x} \otimes \xi \in W$ such that $\xi(\mathbf{a})\alpha^{\sigma}(\mathbf{x}) = 0$. By Proposition 3.3 we have $H_{\mathbf{a} \otimes \alpha, \sigma} = ((\mathbf{a} \otimes \alpha^{\sigma})^{\perp_f}) \cap W (= (\mathbf{a} \otimes \alpha^{\sigma})^{\perp_f}$ when $\sigma \neq \text{id}_{\mathbb{F}}$). Hence $M \in H_{\mathbf{a} \otimes \alpha, \sigma}$ if and only if $\mathbf{a} \otimes \alpha^{\sigma} \perp_f M$ if and only if $\alpha^{\sigma} M \mathbf{a} = 0$. When $\sigma \neq \text{id}_{\mathbb{F}}$ the latter condition holds for every $\mathbf{a} \otimes \alpha \in \text{Pure}((V \otimes V^*)_0)$ if and only if $M = O$.

Let $\sigma = \text{id}_{\mathbb{F}}$. Then $\alpha M \mathbf{a} = 0$ for every $\mathbf{a} \otimes \alpha \in \text{Pure}((V \otimes V^*)_0)$ if and only if $M \in \langle I \rangle$. However $M \in W$ and in this case $W = M_{n+1}^0(\mathbb{F}) = (V \otimes V^*)_0$. Hence $M \neq O$ only if $\text{trace}(I) = 0$, namely $\text{char}(\mathbb{F})$ is positive and divides $n + 1$. \square

Remark 6.4. The following is implicit in the proof of Theorem 6.3: given two non-null matrices M and N , the hyperplane $\mathcal{H}_{N, \sigma}$ arises from $\varepsilon_{\sigma}/[M]$ if and only if $N \perp_f M$. In particular, assuming that $\varepsilon_{\text{nat}}/[I]$ exists, the hyperplane $\mathcal{H}_{\mathbf{a} \otimes \alpha, \text{id}_{\mathbb{F}}}$ arises from $\varepsilon_{\text{nat}}/[I]$ if and only if $\alpha I \mathbf{a} = 0$, namely $\alpha(\mathbf{a}) = 0$. Consequently, the quasi-singular hyperplanes of $A_{n, \{1, n\}}(\mathbb{F})$ which arise from $\varepsilon_{\text{nat}}/[I]$ are precisely the singular ones.

The following have also been proved by Thas and Van Maldeghem [TVM00a, TVM00b].

Result 6.5 (Thas and Van Maldeghem [TVM00a]). *Let \mathbb{F} be finite. Then, up to isomorphisms, the natural embedding ε_{nat} , its twistings and the quotient $\varepsilon_{\text{nat}}/[I]$ (when $\text{char}(\mathbb{F}) = 3$) are the unique polarized embeddings of $A_{2, \{1, 2\}}(\mathbb{F})$.*

Result 6.6 (Thas and Van Maldeghem [TVM00b]). *Let \mathbb{F} be finite. Then:*

- (1) *All 8-dimensional embeddings of $A_{2, \{1, 2\}}(\mathbb{F})$ are polarized (hence all of them are known, by Result 6.5).*
- (2) *If \mathbb{F} is prime then all embeddings of $A_{2, \{1, 2\}}(\mathbb{F})$ are polarized (hence they are known).*
- (3) *Let ε be an embedding of $A_{2, \{1, 2\}}(\mathbb{F})$ with dimension $\dim(\varepsilon) = d \geq 7$. Suppose moreover that for every anti-flag (p, L) of $\text{PG}(2, \mathbb{F})$ the ε -image of the set of points (x, X) of $A_{2, \{1, 2\}}(\mathbb{F})$ such that $x \in L$ and $p \in X$ is contained in a projective plane of $\text{PG}(d, \mathbb{F})$. Then ε is polarized (whence known).*

We guess these two results can be generalized to $A_{n, \{1, n\}}(\mathbb{F})$ for any $n \geq 2$ and \mathbb{F} taken from a suitable class of possibly infinite fields. Perhaps, the class of fields which are either algebraic over their prime subfield or perfect of positive characteristic could meet this requirement.

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