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Shallow Crustal Shear Velocity and V_p/V_s Across Southern California: Joint Inversion of Short-Period Rayleigh Wave Ellipticity, Phase Velocity, and Teleseismic Receiver Functions

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24 **Abstract**

25 Near-surface seismic velocity structure plays a critical role in ground motion
26 amplification during large earthquakes. In particular, the local V_p/V_s ratio strongly
27 influences the amplitude of Rayleigh waves. Previous studies have separately imaged 3D
28 seismic velocity and V_p/V_s ratio at seismogenic depth, but lack regional coverage and/or fail
29 to constrain the shallowest structure. Here, we combine three datasets with complementary
30 sensitivity in a Bayesian joint inversion for shallow crustal shear velocity and near-surface
31 V_p/V_s ratio across Southern California. Receiver functions – including with an apparent
32 delayed initial peak in sedimentary basins, and long considered a nuisance in receiver
33 function imaging studies – highly correlate with short-period Rayleigh wave ellipticity
34 measurements and require the inclusion of a V_p/V_s parameter. The updated model includes
35 near-surface low shear velocity more in line with geotechnical layer estimates, and generally
36 lower than expected V_p/V_s outside the basins suggesting widespread shallow fracturing
37 and/or groundwater undersaturation.

38

39 **1 Introduction**

40 Southern California has a long history of seismic imaging studies at all scales, from
41 regional tomography (e.g., Fang et al., 2016; Lee et al., 2014; Qiu et al., 2019; Tape et al.,
42 2009), to local-scale basin and fault-zone structure (e.g., Allam et al., 2014; Fuis et al., 2001,
43 2017; Süß & Shaw, 2003), and multi-scale joint inversions of multiple datasets (Berg et al.,
44 2018; Bennington et al., 2015). A primary motivation for these works is the significant
45 seismic hazard posed by the San Andreas fault system, and the related need for physics-based
46 hazard assessment of the region (Graves et al., 2011; Vidale & Helmberger, 1988). For the
47 past 25 years, the Southern California Earthquake Center has developed and maintained
48 multiple Community Velocity Models (CVM) with seismic hazard assessment as one of the

49 explicit goals (Chen et al., 2007; Lee et al., 2014; Magistrale et al., 1996; Plesch et al., 2007;
50 Suss & Shaw, 2003; Tape et al., 2009). Despite the long history and contributions from a
51 large community of researchers, there are still several shortcomings to the Southern
52 California CVM. In particular, near-surface velocity structure (<1km depth), and
53 corresponding ratio of compressional to shear velocity (V_p/V_s), remain poorly resolved at
54 regional scales. Shallow structure is well-known to exert strong influence on the co-seismic
55 ground motion (e.g., Graves et al., 2011), while local V_p/V_s ratio can produce amplification
56 by a factor of three (Yang & Sato, 2000) even for sites already subject to amplification due to
57 low local shear wave velocity (e.g., basins). To address these issues, several versions of the
58 CVM (Lee et al., 2014; Plesch et al., 2007) include a shallow layer constrained by very local-
59 scale geotechnical studies; this ad hoc layer creates various edge effects and other artifacts
60 (Figure S1) in the model and wavefield simulations (Taborda et al., 2016).

61 Measurements of V_p/V_s for southern California generally fall into three categories: low-
62 resolution volumetric averages (e.g., Allam et al., 2014; Hauksson, 2000; Lin et al., 2007),
63 localized measurements at seismogenic depth (e.g., Lin & Shearer, 2007; Lin, 2020; Zhang &
64 Lin, 2014), and localized near-surface measurements from boreholes (Boore et al., 2003;
65 Shaw et al., 2015 and references therein) or temporary seismic arrays (e.g., Murphy et al.,
66 2010). The latter category is the most important for seismic hazard, but the extremely local
67 nature is difficult to implement in physics-based assessments. Though there are many models
68 which independently constrain V_p and/or V_s (e.g., Lee et al., 2014; Lin et al., 2010;
69 Schmandt & Humphreys, 2010; Tanimoto & Sheldrake, 2002), naïvely dividing V_p by V_s
70 models obtained with different data of differing resolution results in extreme inaccuracies and
71 numerical artifacts (e.g., Allam & Ben-Zion, 2012). In addition, because most methods
72 measure V_p/V_s at depth from earthquake sources, they lead to overestimations of V_p/V_s ratio
73 under near-surface stress conditions (Zaitsev et al., 2017).

74 In order to provide a model with resolution of V_s and V_p/V_s in the upper few km, we
75 combine the complementary sensitivities of Rayleigh-wave phase velocities (upper crust),
76 ellipticity (upper few km), and the initial pulse of teleseismic receiver functions (shallow
77 V_p/V_s ratio and shallow interfaces) to create a self-consistent model at the regional scale
78 across southern California. The idea to combine receiver functions and surface wave data in a
79 Bayesian joint inversion to determine V_s and V_p/V_s is relatively new (Dreiling et al., 2020;
80 Ojo et al., 2019), and only recently shown to be promising in resolving near-surface V_s and
81 V_p/V_s in sediments (Li et al., 2019). By including V_p/V_s as a parameter we are able to fit
82 receiver functions on a regional scale for the first time across 231 Southern California
83 stations, including in basins where receiver functions have long been discarded as nuisance
84 signals or “corrected” with ad-hoc models, as reverberations overprint Moho and other
85 crustal signatures (e.g., Yeck et al., 2013). The results, presented in Section 3 and discussed
86 in Section 4 below, include a map of V_p/V_s across the region and 3D shear-velocity (V_s)
87 model with very low near-surface velocities in basins more in line with previous
88 measurements of shallow, local V_s .

89

90 **2 Data and Methods**

91 2.1 Ambient Noise Surface Wave Measurements

92 We process three-component broadband stations (Figure 1a) identically to Berg et al.
93 (2018), except to apply an initial band-pass filter to all continuous recordings of 0.5 to 170 s
94 periods (instead of 5 to 150 s) to avoid frequency-band edge effects. We retain relative
95 amplitude information during cross-correlation to measure Rayleigh-wave ellipticity, or
96 horizontal-to-vertical (H/V) ratios (Berg et al., 2018; Lin et al., 2014). The isotropic H/V
97 ratio and uncertainty are determined from the mean and standard deviation of the mean,
98 respectively, for each station with at least 20 measurements remaining after removing

99 outliers; more details can be found in Berg et al. (2018). In addition to Rayleigh-wave H/V
100 ratio measurements from 6 to 10 s periods, we use 3 to 10 s periods Rayleigh-wave phase
101 velocities from previous ambient-noise-based eikonal tomography (Qiu et al., 2019) extracted
102 at the inversion grid point nearest to each station.

103 104 2.2 Receiver Functions

105 We obtain receiver functions, which capture near-station structural contrasts via P to
106 S conversions and reverberations (Langston, 1977; Ligorria & Ammon, 1999; Vinnik, 1977).
107 We analyze P and P_{diff} arrivals and their coda from all teleseismic events from January 2004
108 to August 2020 with $M_w > 5.1$ and epicentral distances 28° to 150° via the time domain
109 iterative method of Ligorria and Ammon (1999) with a Gaussian filter factor of 3 (i.e., a
110 pulse width of 1 s). We apply automated processing based on previous work (Schulte-Pelkum
111 & Mahan, 2014a; 2014b) including basic quality control steps, correction to a standard ray
112 parameter of 0.06 s/km, and receiver function binning by back-azimuth; see Schulte-Pelkum
113 & Mahan (2014a; 2014b) for details. The final isotropic receiver function consists of the
114 mean of all back-azimuths for stations with a minimum of 14 individual receiver functions.
115 To focus on shallow structure, we only consider the first 2 s of each receiver function. In
116 sedimentary basins the initial pulse is delayed due to the superposition of direct P and larger
117 amplitude sediment Ps conversions, as the large velocity contrast at the sediment base
118 refracts rays to nearly-vertical incidence (Li et al., 2019; Schulte-Pelkum et al., 2017). Larger
119 delay times of the initial receiver function pulse are clearly observed in basin stations (Figure
120 1b).

121 122 2.3 Monte Carlo Joint Inversion

123 We leverage the complementary sensitivities of the Rayleigh phase velocity, H/V ratio,
124 and receiver function datasets through a Markov Chain Monte Carlo (MCMC) joint inversion

125 at each station to efficiently and effectively explore the parameter space, quantify model
126 uncertainty, and avoid local minima (Berg et al., 2018; Roy & Romanowicz, 2017; Shen &
127 Ritzwoller, 2016). Our MCMC model for each station consists of a top linear layer over a
128 crustal layer with initial V_s from Berg et al. (2018) and initial V_p/V_s from the Brocher (2005)
129 empirical relationship. Crustal V_s is parameterized with ten cubic B-splines with asymmetric
130 density higher in the shallower crust (Berg et al., 2018). We perturb eight free parameters
131 (Table S1), including the V_s in the top linear layer and the upper four B-splines in the crust,
132 as well as the thickness and V_p/V_s in the top linear layer. The a priori distribution is formed
133 by Gaussian probability with empirically chosen widths to fully sample the model space (see
134 Table S1). We impose three prior constraints: a maximum V_s of 4.9km/s, a positive jump
135 from the bottom of the top linear layer into the crustal layer, and a V_p/V_s ratio greater than 1.

136 The inversion explores the a priori distribution following the Metropolis algorithm (Shen
137 et al., 2012) with misfit characterized as root-mean-square between data and model
138 predictions with empirically chosen weights of 30%, 30%, and 40% for phase velocities, H/V
139 ratios, and receiver functions respectively. Models with misfit less than 1.5 of the minimum
140 misfit are included in the posterior distribution, and we require the posterior to contain more
141 than 300 models for the station to be included in the final results. On average, there are
142 ~2000 models in each posterior. Details about the number of iterations, avoiding the edges of
143 prior distributions, and data uncertainties can be found in previous works (Berg et al., 2018,
144 2020; Shen et al., 2012).

145 Our final model is formed by the mean of the model parameters in the posterior, except in
146 cases where the mean results in a misfit value higher than that in the posterior (i.e., higher
147 than 1.5 times the absolute minimum misfit). This generally occurs where the posterior
148 models have bimodal distribution, and in these instances our final model is the model with
149 minimum misfit.

150 Figure 2 shows the 1-D inversion result for station RUS (star, Figure 1c), including the
151 full prior and posterior distributions and data fits, and the effects of the inclusion of the
152 receiver function data. When the receiver function data (Figure 2c) are not used, the shallow
153 structure and V_p/V_s ratio (Figure 2a, 2b) are poorly constrained by the inversion, though the
154 Rayleigh wave ellipticity and phase velocity (Figure 2d, 2e) are equally well-fit in either
155 case. By incorporating receiver functions, not only do we gain better constraint on the near-
156 surface layered interface structure (Allam et al., 2017; Langston, 1979; Shen & Ritzwoller,
157 2016; Ward & Lin, 2018), but the complementary dataset results in a tighter distribution of
158 results in both the V_s and the V_p/V_s model space (Figure 2a, 2b). Thus receiver function data
159 are most sensitive to the near-surface velocity and V_p/V_s ratio, justifies the inclusion of the
160 latter, and demonstrates receiver function utility when included in this inversion.

161

162 **3 Results**

163 3.1 Rayleigh-Wave Ellipticity and Receiver Function Measurements

164 As in previous work (Berg et al., 2018), as 7 s period (Figure 1a) we observe high H/V
165 ratios in sedimentary basins including the Los Angeles, Central Valley, Salton Trough, and
166 Ventura basins; we observe low H/V ratios in mountainous regions such as the Sierra Nevada
167 and Peninsular Ranges. The surface patterns of soft sediment compared to hard bedrock are
168 also evident from the Wills & Clahan (2006) V_s30 map of the region (Figure 1c).

169 From the map of receiver function initial pulse delay time (Figure 1b), we see similar
170 patterns to those of the H/V ratio map (Figure 1a) and the V_s30 map (Figure 1c). We observe
171 earlier arrivals of the initial receiver function pulse in crystalline rock, including in the
172 Peninsular and Sierra Nevada Ranges, and later arrivals in sedimentary basins, including the
173 Los Angeles basin and the Salton Trough. The superposition of direct P and larger amplitude
174 P-to-S conversions in sedimentary basins, from the bedrock interface and reverberations
175 within, yields delayed and more-intricate initial pulses in the receiver functions (Li et al.,

176 2019; Schulte-Pelkum et al., 2017; Yeck et al., 2013). Although typically ignored for their
177 complexity (e.g., Allam et al., 2017), we directly compare the receiver function delay times
178 to the short-period H/V ratios as both have shallow sensitivity. We observe strong correlation
179 values (mean correlation coefficient 0.76) between 6-10 s period H/V ratios and receiver
180 function delay times; higher H/V ratios correspond to later receiver function initial pulse
181 times (Figure 1d), which in turn correspond to lower V_{s30} areas.

182

183 3.2 Shear Velocity Model

184 Figures 3a and 3b show the V_s velocity MCMC inversion result at 0 km and 1 km
185 depths, respectively, interpolated onto the underlying map, with a cross-section shown in
186 Figure 3d. Major features include low- V_s sedimentary basins such as the Los Angeles basin,
187 Central Valley, Ventura basin, and Salton Trough. We also observe the high- V_s Peninsular
188 and Sierra Nevada Ranges. Less prominent features include the Indian Wells Valley (Figures
189 3a and 3b) east of the Sierra Nevada, shallow Antelope Valley (Figure 3a) in the northwest
190 corner of the Mojave desert, and the low- V_s Coast Ranges (Figure 3a). The northwest section
191 of the Eastern California Shear Zone (ECSZ; Figure 3a) is observed as a broad low velocity
192 zone at the surface, and strong across-fault contrasts in velocity are observed on the southern
193 San Andreas, San Jacinto, and Elsinore faults (Figures 3a and 3b). In comparison to our
194 previous Berg et al. (2018) model (i.e., our starting model), we have stronger constraint to the
195 near-surface (see Figure S2 for the standard deviation of the posterior, and Figure S3 for
196 misfits) with V_s values slower in areas of soft sediments (e.g., Salton Trough, LA and Central
197 Valley basins) and faster in regions of crystalline rock (e.g., Sierra Nevada and Peninsular
198 Ranges). A direct comparison of starting (red triangles, Figure 2a) to final model (yellow
199 squares, Figure 2a), shows that the most prominent changes occur in the upper few km.

200 Further direct comparison to the CVMS are provided in Figure S1, where the impact of each
201 of these geologic regions and similarities of our model results are visible.

202 In Figure 3c we show depth to V_s of 3km/s as an approximate basin depth map, based
203 on the empirical V_p/V_s relationship (Brocher, 2005) and previous observations in the LA
204 basin (Süss & Shaw, 2003). We observe a greater depth to 3km/s in the southeast portion of
205 the LA and Ventura basins, and mid-range depths for the Central Valley and in the Salton
206 Trough. This (Figure 3c, Figure S1a) agrees with previous studies (Berg et al., 2018; Fletcher
207 & Erdem, 2017; Fliedner et al., 2000; Fuis et al., 2017; Han et al., 2016; Livers et al., 2012;
208 Ma & Clayton; 2016; Magistrale et al., 1996). The Antelope Valley and Indian Wells Valley
209 are shallower, fitting previous active-source studies (Lutter et al., 2004; Tape et al., 2010).

210

211 3.3 V_p/V_s in the Near Surface

212 While V_p/V_s in the top linear layer is resolved for every station, we analyze only
213 those stations with a prominent layer thickness (>0.75 km) and with low normalized standard
214 deviation of the V_p/V_s in the posterior (<0.15) to avoid including less reliable results. Figure
215 4a shows the V_p/V_s at stations satisfying these criteria, and the interpolated map. Figure 4b
216 shows a scatter plot of the top linear layer average V_s compared to V_p/V_s value (circles) and
217 the Brocher (2005) estimate (line). We observe high scatter around the Brocher-predicted
218 V_p/V_s value skewed towards lower V_p/V_s (Figure 4b), particularly for areas with higher V_s
219 values. Figure S4 shows the map of the normalized standard deviation of V_p/V_s and map-
220 view of average V_s in the top linear layer.

221 We observe higher V_p/V_s in the Salton Trough, eastern LA basin, Central Valley,
222 Indian Wells Valley, Antelope Valley, and in the ESCZ with corresponding slower
223 sediments. We observe lower V_p/V_s in the Sierra Nevada mountains, in the center of the
224 Mojave desert, and in the Peninsular Ranges. Additionally, we see a transition from higher

225 Vp/Vs near the San Andreas fault to low Vp/Vs along the San Jacinto and Elsinore faults.
226 These observations are consistent with previous studies (Fang et al., 2019; Lin et al., 2007),
227 and discussed in detail in the following section.

228 229 **4 Discussion**

230 4.1 Mountains and Mojave Desert

231 Compared to Berg et al. (2018), we observe faster near-surface Vs values in the Sierra
232 Nevada and Peninsular Ranges (Figures 3a, 3b, and S4), similar to the CVMS geotechnical
233 layer (GTL) (Shaw et al., 2015). Though the Vp/Vs ratio of rocks can vary significantly with
234 fluid content and fracture density (Shearer, 1988; Karato & Jung, 1998), Christensen (1996)
235 suggests that composition controls the general properties of igneous rock; felsic (e.g., granite)
236 rocks have relatively low Vp/Vs ratio (<1.7) and high silica content ($>65\%$), while mafic
237 (e.g., basalt) rocks have higher Vp/Vs ratios (>1.8) and lower silica content ($<45\%$). In the
238 Sierra Nevada Range, we observe lower Vp/Vs consistent with Cretaceous granitic rocks
239 (Irwin, 1990) at the surface and previous studies (Hauksson, 2000; Lin et al., 2007; Murphy
240 et al., 2010). Consistent to previous studies (Fang et al., 2019; Hauksson, 2000), we resolve,
241 in the southernmost portion of our study, the northern extent of the complex mafic Peninsular
242 Ranges batholith containing an abundance of gabbros (Gastil et al., 1975; Hauksson, 2000;
243 Kimbrough & Grove, 2005; Langenheim & Jachens, 2000; Wetmore et al., 2003) with
244 corresponding relatively higher (~ 1.8) Vp/Vs ratios. We also observe the transition to the
245 northeast into more quartz-rich granitic material (Gastil et al., 1975; Hauksson, 2000;
246 Kimbrough & Grove, 2005; Wetmore et al., 2003), including into the fast-Vs low-Vp/Vs
247 Cretaceous plutons (Morton & Kennedy, 2005) between the Elsinore and San Jacinto faults.
248 Relatively low Vp/Vs ratios in the Mojave Desert between Antelope Valley (previously
249 observed by Hauksson, 2000 & Murphy et al., 2010) and the ECSZ likely correspond to

250 Precambrian metamorphic and plutonic rocks with values consistent to lab measurements
251 (McCaffree Pellerin & Christensen, 1998).

252 Similar to previous studies, we observe higher V_p/V_s (Figure 4a) in portions of the
253 San Andreas fault (Fang et al., 2019; Murphy et al., 2010) and in the ECSZ (Hauksson, 2000;
254 Lin et al., 2007) where slower V_s is also observed (Figure 3a). S-waves are particularly
255 sensitive to reduction in velocity within a fault damage zone due to the high fracture density
256 (Catchings et al., 2014, 2020; Mitchell & Faulkner, 2009), as observed along the Mojave
257 section of the San Andreas Fault (Fang et al., 2019; Murphy et al., 2010). Similarly, the
258 ECSZ contains low- V_s and high- V_p/V_s which we interpret as widespread aligned fractures
259 created by the broad region of strike-slip deformation (Sauber et al., 1986).

260 More generally in our model, stations outside of sedimentary basins have low V_p/V_s
261 (< 1.75) ratios (Figures 4a and 4b). While these values are lower than anticipated from
262 previous imaging (Hauksson, 2000) and laboratory (Christensen, 1996) studies, recent work
263 (Zaitsev et al., 2017) shows that low V_p/V_s and a negative Poisson ratio ($V_p/V_s < 1.42$) is
264 not an exotic result and has been observed in a significant portion of experimental data
265 samples (~45%) at low confining stress (i.e., surface conditions). Previous southern
266 California imaging studies have observed higher V_p/V_s ratios likely due to greater depth
267 sensitivity (Hauksson, 2000; Lin & Shearer, 2007; Lin et al., 2007). The low V_p/V_s ratios
268 obtained in the present model suggest widespread fracturing and/or poor consolidation with
269 little-to-no fluid saturation (Avseth & Bachrach, 2005; Bachrach et al., 2000; Shearer, 1988)
270 in the near-surface crust of Southern California outside of major basins.

271 272 273 4.2 Basins

274 Major basins in Southern California are clearly observed as regions of high V_p/V_s
275 and reduced V_s (Figure 3a), lower than previous imaging work (Berg et al., 2018; Lee et al.,

276 2014; Tape et al., 2010) and more in line with estimates of V_s 30/GTL (Figure S1ffy, Shaw et
277 al., 2015). These include the Salton Trough, Central Valley, and Los Angeles and Ventura
278 basins. We do not observe the San Bernardino Basin – likely because of station coverage and
279 overall shallow basement depth (Anderson et al., 2004) – but the nearby Cajon and Banning
280 Passes are visible as low- V_s high- V_p/V_s areas.

281 The high V_p/V_s ratios (Figure 4a) seen in all basins are consistent with fluid-saturated
282 measurements and observed in previous studies (Fang et al., 2019; Hauksson, 2000;
283 Hauksson & Haase, 1997; Lin et al., 2007; Murphy et al., 2010). In the LA basin (Figure S4)
284 we observe strong similarities in V_s to the GTL, which is well-constrained via dense borehole
285 measurements (Shaw et al., 2015). Although we have limited horizontal resolution due to
286 station coverage, we observe that the deepest part of the LA basin (Figure 3c) lies between
287 the Newport-Inglewood and Whittier faults (20-50km distance in Figure 3d). This portion of
288 the LA basin coincides with relatively higher V_p/V_s ratios, potentially related to the
289 shallower water table (CA DWR, 2017; WRD, 2017), and is consistent to previous studies
290 based on borehole measurements (Hauksson & Haase, 1997) and local earthquakes (Lin et
291 al., 2007). North of the Hollywood fault, in the Santa Monica mountains between the LA and
292 Ventura basins, we observe low V_p/V_s similar to borehole studies (Hauksson & Haase,
293 1997). The Santa Monica mountains contain Mesozoic igneous and metamorphic granitic
294 rocks (Lutter et al., 2004; Murphy et al., 2010), and the region adjacent to the Hollywood
295 fault contains granitic and dioritic plutonic rocks (Hildenbrand et al., 2001).

296

297 **5 Conclusions**

298 We apply Markov Chain Monte Carlo inversion of short-period Rayleigh-wave phase
299 velocity and ellipticity with early-time (0-2 s) receiver functions to determine shallow V_s
300 (<10 km) and near-surface V_p/V_s ratios. We observe V_s values near the surface that more

301 closely resemble borehole and exploration studies in the Los Angeles basin, and higher V_s in
302 the Peninsular and Sierra Nevada Ranges near the surface. Our low V_p/V_s ratio results
303 outside of fluid-saturated basins correspond to mafic material in the Peninsular Ranges, felsic
304 material in the Sierra Nevada Ranges and granitic regions, and significantly overall low
305 V_p/V_s suggests widespread shallow fracturing and/or groundwater undersaturation.

306
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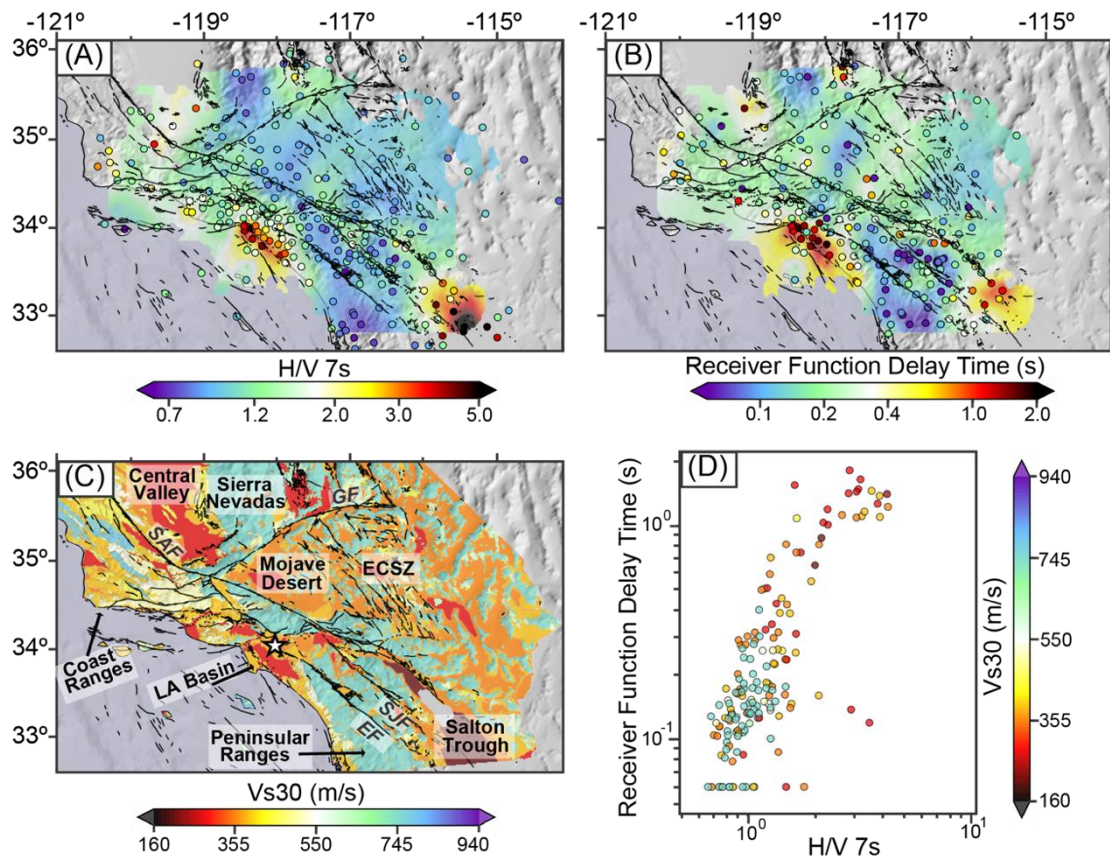
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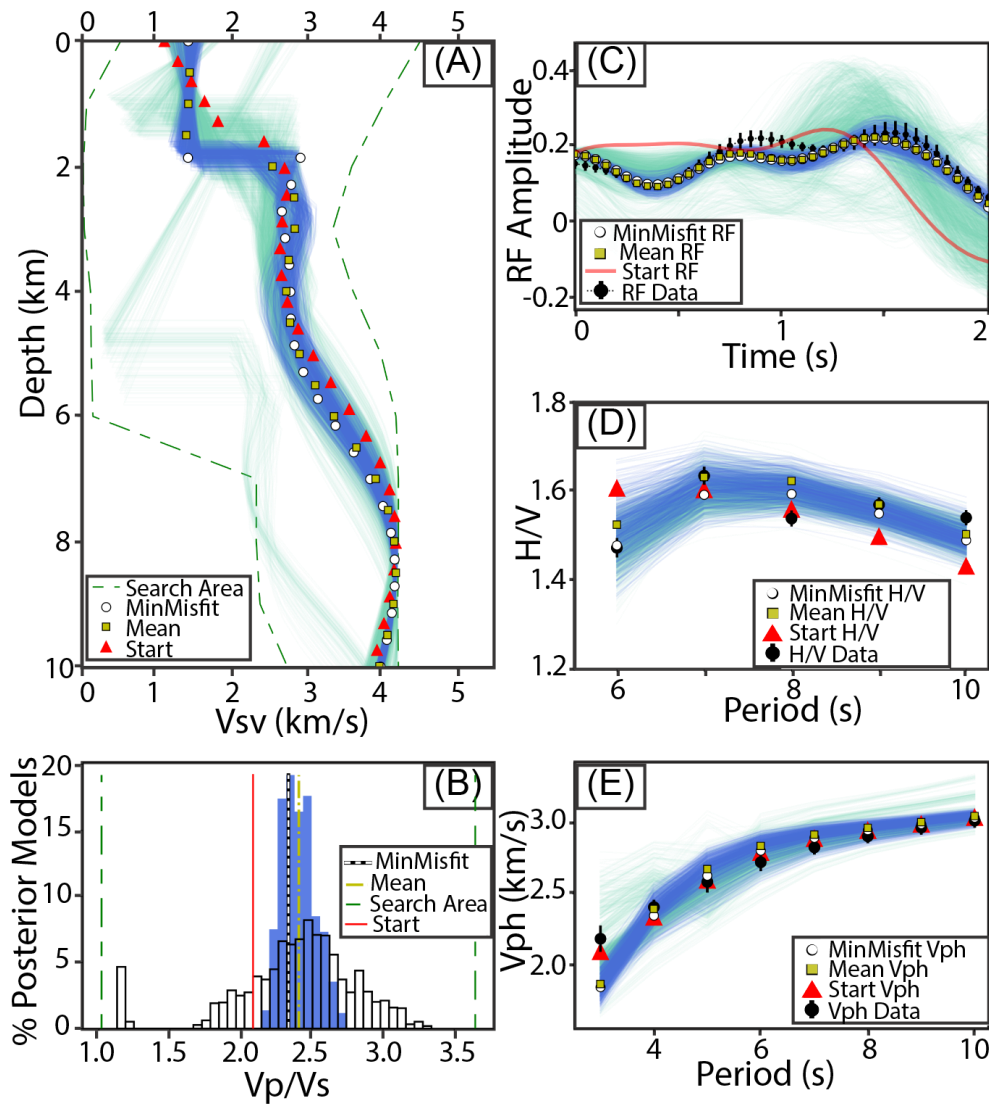
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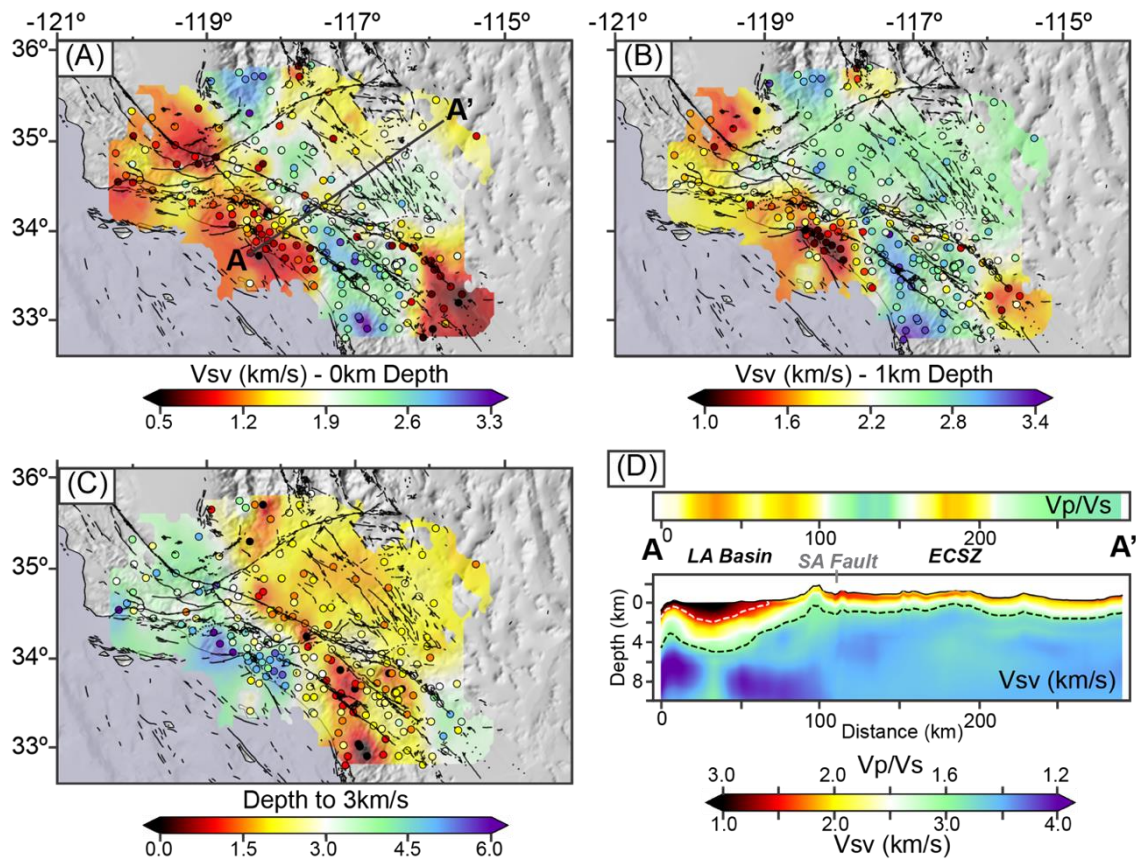
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616 **Figure 1.** Maps showing data at each station (circle) and Gaussian-smoothed, with $\frac{3}{4}$ width
 617 corresponding to the distance to the nearest three stations, onto the underlying map for (a)
 618 H/V at 7 s period and (b) receiver function initial pulse delay time. (c) Vs30 map (Wills &
 619 Clahan, 2006) with station RUS marked as a star and main geological features and major
 620 faults labeled, including the San Andreas (SAF), Garlock (GF), San Jacinto (SJF), and
 621 Elsinore (EF) faults. (d) Scatter plot of each station's H/V at 7 s period and receiver function
 622 delay time (s) from (a) and (b), colored according to the Vs30 (m/s) nearest to that station.
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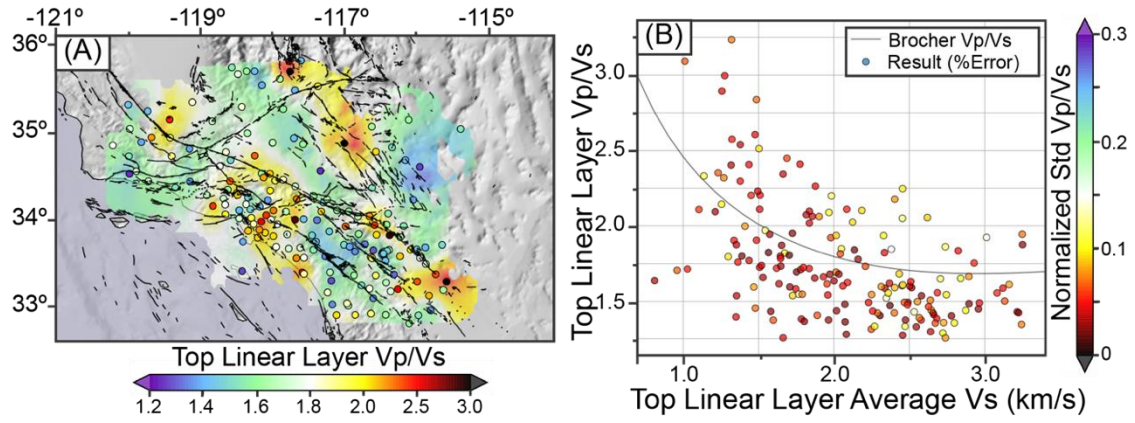
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Figure 2. MCMC joint inversion results for station RUS (white star, Figure 1c) including (a, b) search area (green dashed lines), posterior results when incorporating Rayleigh-wave phase velocity and H/V data only ((a) light green or (b) transparent) and all datasets (blue), as well as the starting model (red), minimum misfit model from the posterior (white), and mean model from the posterior (yellow) for both (a) shear velocity (V_s) results of the top 10km and (b) V_p/V_s results of the top linear layer. Data (black) and forward model results for the posterior sets, starting, mean, and minimum misfit models for (c) receiver functions, (d) H/V, and (e) phase velocities.



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Figure 3. Vs results at each station, with Gaussian-smoothed (see Figure 1 description) underlying map, at (a) the surface and (b) 1 km depths, and (c) depth to 3 km/s. (d) Cross-section A-A' for Vp/Vs ratio in the top linear layer (top) and Vs to 10 km depth (bottom), including white dashed line at 1.5 km/s and black dashed line at 3 km/s.



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Figure 4. Vp/Vs results from the top linear layer as a (a) map at each station, with Gaussian-smoothed (see Figure 1 description) underlying map, and (b) scatter plot from each station of average Vs in the top linear layer versus Vp/Vs of the top linear layer.

Figure1.

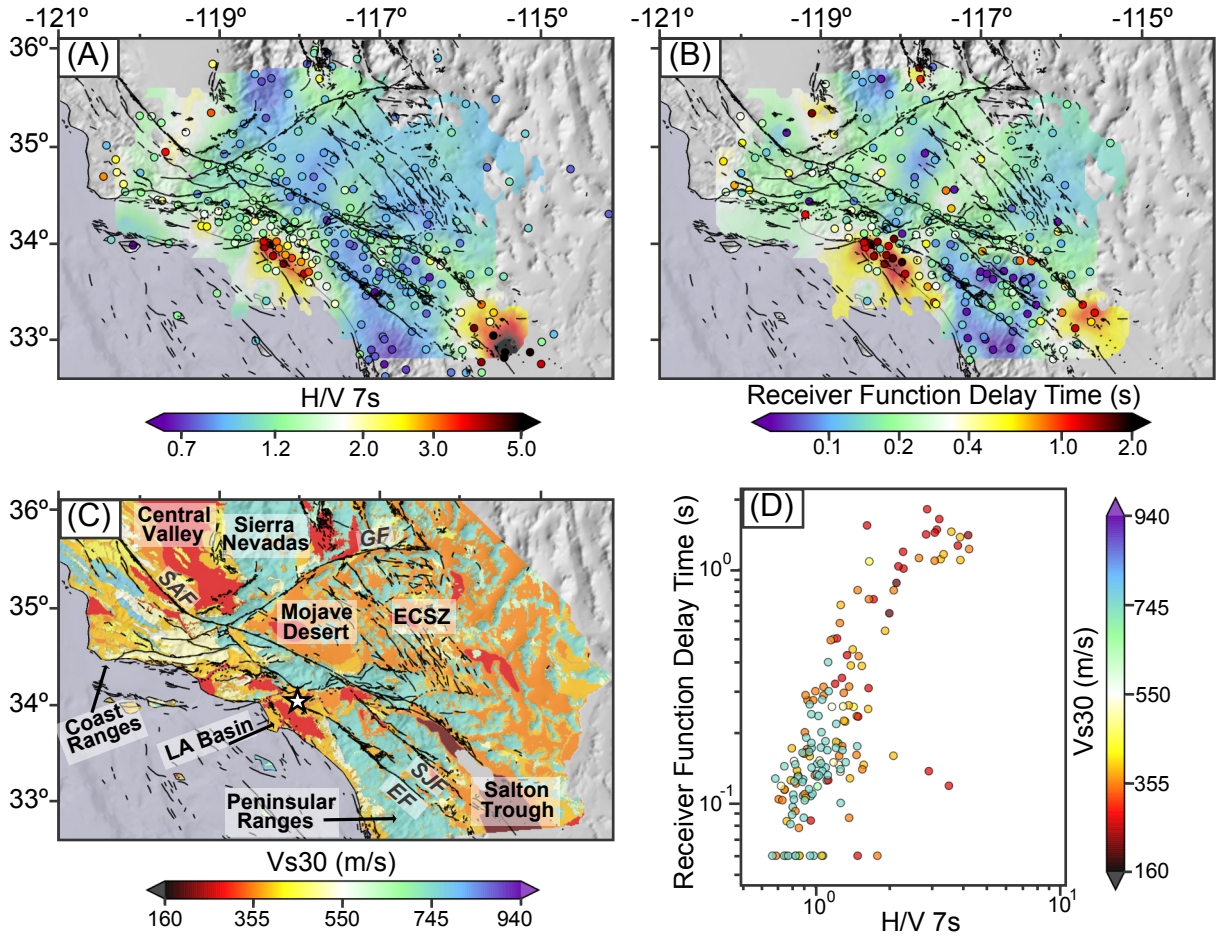


Figure2.

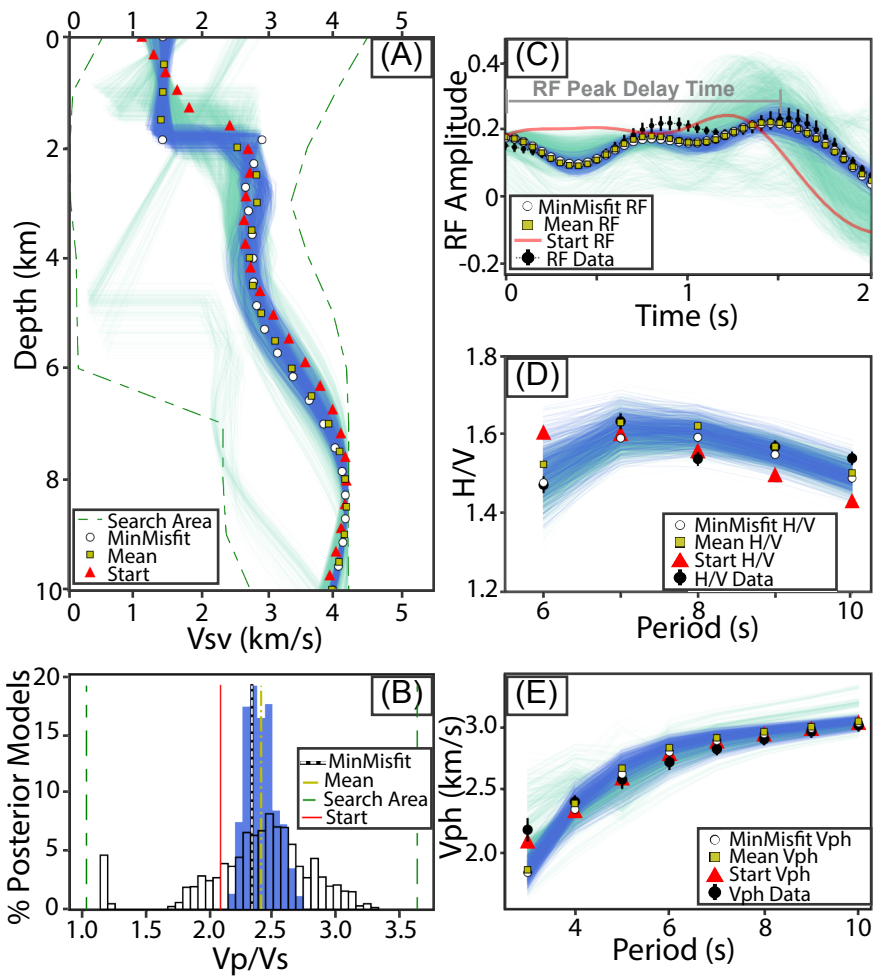


Figure 3.

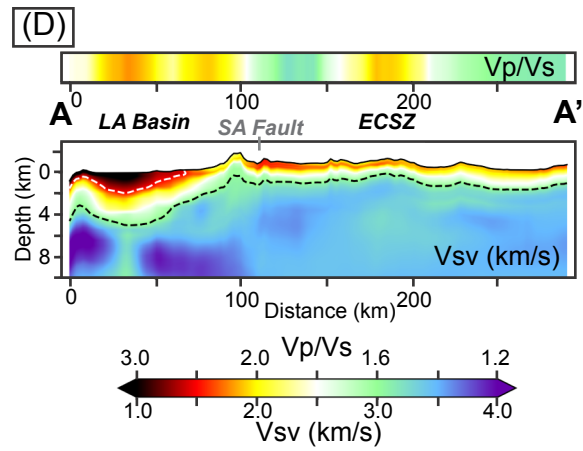
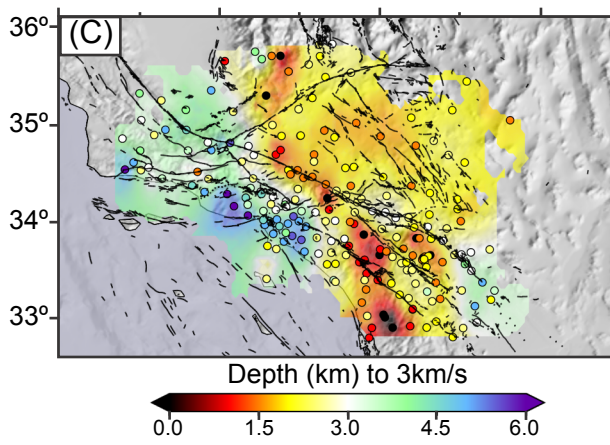
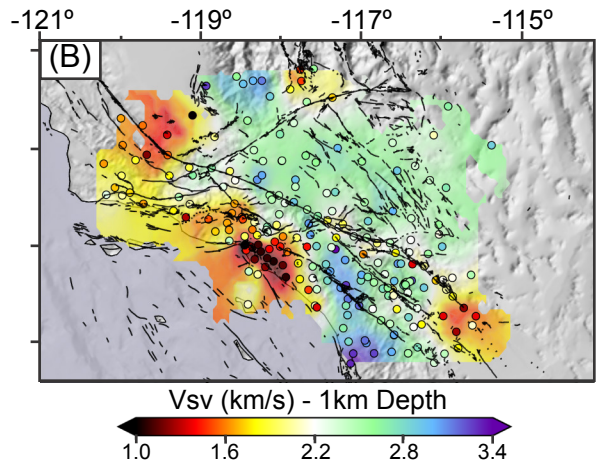
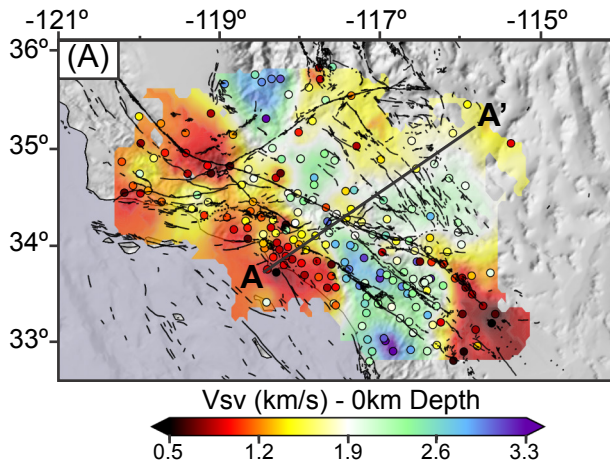


Figure4.

