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Article S3DK: An Open Source Toolkit for Prototyping Synchrophasor Applications

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Abstract: Synchrophasor data contains a trove of information on the power system and its dynam-1 ics. These measurements have a high potential to unlock our ability to cope with changing system conditions and challenges posed by distributed and intermittent energy sources. While Phasor Measurement Units (PMUs) have seen a large deployment in the grid, their applications are limited 4 by the software platforms that are deployed in control centers to monitor the grid. In this paper, 5 we present an open source toolkit that enables fast prototyping of PMU applications. The toolkit 6 is akin to a software development kit (SDK) for synchrophasor applications, providing a number 7 of functionalities that enable high-level PMU application development within the LABVIEW environment. This Smart-grid Synchrophasor SDK (S3DK) proposes a paradigm based on the concept 9 of distributed applications, which allows development and deployment to be independent from 10 the existing software stack deployed in control centers and to leverage PMU data at any level of a 11 synchrophasor system hierarchy. This paper serves to introduce the S3DK, which is released as open 12 source software to facilitate broader and fast prototyping of synchrophasor applications. 13

Keywords: Power Systems; PMU; Synchrophasor; WAMS; Open Source

1. Introduction

The power grid is rapidly evolving with the addition of new technologies that relate to 16 the many facets of the grid operation. One notable development is the broad deployment 17 of measurement equipment, namely Phasor Measurement Units (PMUs). These units are 18 characterized primarily by their ability to synchronously "measure" synchrophasors: a 19 phasor representation of the three-phase system in the form of voltage and current (both 20 magnitude and angle estimates). The deployment of the technology was originally moti-21 vated by a need for higher-fidelity measurements than those available from conventional 22 Supervisory control and data acquisition (SCADA) systems, with the goal to capture evolv-23 ing grid dynamics across wide geographical regions [1], an effort that gained impetus in 24 the aftermath of the Northeast blackout of 2003 [2,3]. The time-synchronized and high-25 sample rate data was also as a means to facilitate more advanced computations to support 26 situational awareness through wide-area monitoring [4], so to accommodate the operation 27 of the grid with thinner security margins[5]. This is becoming especially relevant for the 28 changes that have happened in the grid in the past decades, such as the expansion of syn-29 chronously interconnected grids, and the influx of inverter-based intermittent generation 30 (e.g., renewables such as wind [6,7] and solar photovoltaic systems [8]). 31

Prior to the deployment of synchrophasor systems, grid operators relied primarily on SCADA systems, often coupled with a state estimation algorithm, to monitor and operate the grid. These tools do not allow for advanced monitoring functionalities as the measurements are collected in an asynchronous process, and only provide RMS values

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Copyright: © 2024 by the authors. Submitted to *Electronics* for possible open access publication under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). (i.e., amplitude) of the measured quantities. Synchrophasors, on the other hand, provide much richer measurements that enable the use of signal processing methods to extract more information, and combine measurements from several locations for more complex computations such as those in [9–12].

1.1. Motivation

The deployment of this technology stimulated the interest of both grid operators and 41 researchers to develop new algorithms and tools that harness these measurements into 42 actionable information for grid operation. The development of such applications at early 43 stages is fundamentally related to the ability of the research community to develop and 44 prototype their ideas. In the case of the power engineering community, its members do 45 not necessarily possess the skill-set for advanced software development. This highlights 46 the need for broadly available tools that abstract the complexity related to developing 47 software and handling real-time measurements, such that power engineering students and 48 researchers can access a user-friendly development environment to prototype applications 49 with minimal training effort. 50

Commercial tools that support synchrophasor measurements are based on the same 51 integrated and centralized architecture as traditional SCADA systems [13–16]. Hence, the development of new functionalities can only happen in close cooperation with their respec-53 tive vendors, primarily through procurement processes, incurring high integration costs¹. 54 This is not an attractive alternative for fundamental research or prototyping purposes, 55 which led to the development of various initiatives. There are a few notable contributions to the open-source synchrophasor applications community readily available [20], but the 57 majority lack a user-friendly development environment for advanced algorithms and inter-58 active user interfaces, hence, requiring advanced software development skills, even for the 59 implementation of early prototypes.

This motivated the development of a new SDK that focuses on the specific needs of the power engineering community by providing access to PMU measurements in a userfriendly development environment; enabling power engineers to develop and prototype custom PMU applications.

1.2. Previous Work and Contribution

The release of this SDK is the result of a several years long effort that started with the development of a data mediator for the IEEE C37.118.2 standard protocol [21] for synchrophasor networks communications. This data mediator, the STRON*g*²*rid* library [22], was developed to expose real-time PMU measurements through an Application Programming Interface (API) that could be further integrated into other applications. In particular, the API was populated with methods dedicated to its integration with LABVIEW in preparation of the development of the S3DK.

In this paper we present the Smart-grid Synchrophasor SDK (S3DK): an open source 73 LABVIEW extension that enables the development of PMU applications. It provides the 74 facilities to handle real-time PMU data, while the configuration is carried out through a 75 Graphical User Interfaces (GUIs), and allows to leverage LABVIEW and its numerous 76 toolboxes for signal processing, data analysis, and graphical outputs. The source code and 77 the compiled installation files were released as an open-source project to further facilitate 78 its adoption by researchers. Finally, to show how the S3DK can be leveraged by members 79 of the power engineering community, we also compiled a list of the prototype tools that were developed by the research team that developed the S3DK, as well as some prototype 81 tools that were developed by Grid Controller of India Limited, a utility company in India, 82 and other third parties. 83

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¹ See for example the case of the Grid Stability Awareness System (GSAS) [16] which integrated stability monitoring functions into OpenPDC with a cost of USD 3 Million [17], and other comparable cases [18,19].

This paper is organized as follows: in Section 2, we cover synchrophasor systems and different paradigms for developing PMU applications Section 3 presents the S3DK and its main components and functionalities. In Section 4, we introduce the PMU application template that was integrated in the library package to fast track the prototyping of applications and summarize several PMU application prototypes developed using the toolkit. In addition, prototypes of applications developed by a utility company are presented in Section 5 Finally, conclusion are drawn in Section 6.

2. Synchrophasor Systems and Applications

Through different grid modernization efforts, several grid operators have deployed 93 PMUs in their system to build a new monitoring system based on synchrophasors [23]. 94 These devices sample all three phases of the grid at a fixed high-sampling rate to estimate 95 a phasor representation of the phase voltages and currents at the fundamental frequency 96 thereby providing both magnitude and angle "measurements"). The phasor estimation is 97 performed synchronously across all devices using a common time reference (e.g., GPS) that 98 also provides the reference to compute phase angles, hence the name synchrophasor. This 99 particularity allows to use measurements from across the entire system and compute phase 100 angle differences that are alike to those in power flow computations (i.e., line power flow 101 equations). 102

2.1. Synchrophasor Systems

Traditional SCADA systems have a fully centralized architecture that is most often delivered by a single provider. The central server asynchronously collects all the measurements and present them in a single interface, and allow the operator to execute different monitoring and control actions. However, because the measurements in SCADA systems are polled asynchronously they need to be assisted by a state estimator to create a "snapshot" of observed and non-observable physical quantities (e.g., voltages, powers) in the grid.

Synchrophasor systems differ from the SCADA architecture in multiple aspects. Most 111 importantly, synchrophasor systems stream data from PMUs, and the data flows are orga-112 nized in a hierarchical system structure based on standardized communication protocols, 113 such as the IEEE C37.118. At the core of the system, the Phasor Data Concentrator (PDC), 114 is the component that collects and redistributes PMU measurements implementing the 115 communication protocol. PDCs are typically used to interface different actors of the grid, 116 such as private plant owners, regional grid operators, and the central system operator 117 (Independent System Operators (ISO), Transmission System Operators (TSO), etc.). Fig-118 ure 1 presents a typical hierarchical structure of the measurement data collection system of 119 synchrophasor systems. 120



Figure 1. Synchrophasor System Architecture

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PDCs support multiple outgoing connections, known as output streams, that allow to make use of the measurements at the different levels where they are placed for various kind of applications. There are two models for the application layer, i.e., where PMU applications are placed, that will be discussed in the following Section.

2.2. Applications Development Frameworks

The development of synchrophasor networks quickly stimulated the interest for 126 finding new PMU data applications [3]. While early development focused on data collection 127 and archival aspects for postmortem analysis of system disturbance event [2], the focus has 128 expanded to the development real-time applications that help the decision making for grid 129 operators [4], largely thanks to the advent of more processing power and higher throughput 130 communication networks. This resulted in the development of different frameworks for 131 developing synchrophasor applications that can either be part of the PDC platform [4,16,20], 132 or less commonly, take the form of distributed application systems [24]. 133

2.2.1. Centralized PDC-based Application Development

The prevailing centralized architecture is based on applications built in the PDC 135 component and resembles the infrastructure of existing Energy Management Services (EMS) 136 / SCADA systems. In this model, the PDC functionalities are extended through built-in 137 applications (e.g., plugins) that can take advantage of private Application Programming 138 Interfaces (APIs) offered by the PDC platform [25]. This approach allows for an unique 139 and consistent interface with the PDC that may allow faster and more granular access to 140 the measurement data, but comes at the cost of limiting the applications' scope to what 141 the PDC framework can support (e.g., limited signal processing functions, etc.) without additional developments into the platforms with substantial costs [16-19]. 143

For real-time application deployment, practically, this approach involves a single 144 location for all computation requirements, co-located with the super PDC or PDC [16]. 145 Thus, it has numerous implications for the development of applications by third parties 146 contributor. While computation limitations of running concurrent applications on a single 147 machine are no longer a source of concern, more difficulties can be expected for third 148 parties to develop applications on often insufficiently documented platforms or those with 149 a prohibitive cost to access. In particular, in an industrial setting, it is common in the power 150 industry for ISOs/TSOs to rely solely on a few external vendors to develop and deploy 151 their synchrophasor system, foregoing the possibility of broader third party contributions 152 and delays the deployment of applications for real-world utilization. 153

2.2.2. Distributed Application Development and Deployment

The distributed application development approach differs from its centralized coun-155 terpart by relying on a real-time data mediator that consumes a PDC stream and deliver 156 its content in a development environment. This also means that the application does not 157 need to reside in a single location, and multiple instances of real-time data mediators 158 can coexist and connect to any of the existing PMU/PDC system, as illustrated on Fig. 2. 159 The real-time data mediator is implemented to parse a standard communication protocol 160 (e.g., IEEE C37.118) into native datatypes of the chosen development environment [22]. 161 The standardized protocol ensures the compatibility with any of the existing PMU/PDC 162 systems. 163

This approach has many advantages for each party involved in the development and management of a synchrophasor system. From the system management perspective, it allows to focus the functionality of the synchrophasor system, and in particular the PDC, to data collection, management and redistribution. For synchrophasor applications it allows the deployment of a very modular infrastructure, which facilitates the deployment of more computational power, and new functionalities (i.e., new applications). This may also facilitate the creation of a very redundant system.

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Figure 2. Example of Distributed Application Architecture in Synchrophasor System

From the application development perspective, it allows the use of broadly available development environments that can feature very extensive computational and, in particular, signal processing capabilities. It also opens the development of new applications to any academics, researchers and software developer who no longer needs to specialize in custom proprietary software environments. Finally it facilitates the transition from a development / testing environment, to a deployment in the field, by allowing easily packaged applications.

2.2.3. Existing Frameworks

In this paper, we focus on open source frameworks that can be used for developing synchrophasor applications. There are a few notable contributions to the open-source community that are readily available, including the following :

- RIAPS [24] is a framework for developing distributed monitoring and control applications,
- GridAPPS [26] is a framework for developing Advanced Distribution Management
 Systems (ADMS) applications that combine both model simulations and measurements,
- The OpenPDC project [27] is an open-source PDC that can be extended with custom *Adapters* developed in C# to extend its functionalities and computations, 187
- Synchro-Measurement Application Development Framework (SADF) [28] is a framework to develop synchrophasor applications in MATLAB.

RIAPS and GridAPPS offer a generic framework for grid applications that feature a 190 communication facility. While these solutions do not explicitly support standardized syn-191 chrophasor streams [21], they provide tools that would allow such applications. OpenPDC 192 offers a framework to develop applications on the centralized PDC based model. While 193 it offers the possibility to develop new application using C#, this programming language 194 is not broadly adopted in the power engineering scientific community and lacks tool-195 boxes/libraries for advanced computations (e.g., signal processing, filtering, etc.). SADF 196 offers a real-time data mediator for MATLAB. This programming environment is widely 197 distributed in the scientific community, most engineers and researchers are acquainted to it, 198 and offers a vast ecosystem of toolboxes for advanced computation. However, while SADF 199 is open source software, it depends on MATLAB that requires costly licenses that becomes 200 prohibitive when using multiple of its toolboxes. Nevertheless, among these frameworks, 201 SADF is the closest solution to the S3DK presented in this paper. 202

3. S3DK: Smart-grid Synchrophasor SDK

The original concept of the Smart-grid Synchrophasor Software Development Kit was instigated to answer the needs of the research group led by the second author, to develop and test prototypes of various PMU applications. At the time (circa 2011) there was no readily available solution that allowed power system researchers, who often lack a

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Figure 3. S3DK Main User Interface

comprehensive background in computer science and programming, to do any sort of rapid 208 prototyping of synchrophasor applications. The academic community is more familiar with 209 high level programming languages that abstract much of the programming complexity, 210 such as MATLAB, and LABVIEW. In a attempt to make the application development the 211 most accessible to the power system research community, it was decided to develop a 212 software development kit (SDK) dedicated to synchrophasor applications. This vision was 213 shared by Statnett SF, the Norwegian Transmission System Operator, who supported the 214 development through different research projects [29]. 215

The Smart-grid Synchrophasor SDK (S3DK) was developed for the LABVIEW pro-216 gramming language that provides an environment facilitating the development of compu-217 tationally advanced applications with highly interactive graphical user interfaces (GUIs). 218 While both MATLAB, and LABVIEW offer an environment with powerful toolboxes for ad-219 vanced signal processing and computation functionalities, we selected the latter for its easy 220 approach to designing GUIs. This is of particular importance for the target audience that 221 is the power system academic community for fast prototyping of new idea and concepts 222 with minimal training. Furthermore, LABVIEW recently released a community edition 223 of its development suite that is free to use for non commercial use, expanding the target 224 audience of the SDK to additional potential users in the power engineering community². 225 Applications can also be compiled as standalone programs to be shared with external 226 partners for an easy deployment (see: https://www.ni.com/en/support/documentation/ 227 supplemental/19/introduction-to-the-labview-application-builder.html). 228

S3DK has three main components that are presented in the following Sections. The main goal is to present in summary fashion the most important components, while a comprehensive description of all the components and methods included in S3DK is available online at: https://alsetlab.github.io/S3DK/

3.1. Low-Level Communication

As described in the Section 2.2.2, the decentralized paradigm relies on a real-time data mediator (RTDM) to receive a stream of measurements, and to decode the communication protocol to deliver the data into a development environment. To this end, the S3DK leverages the STRON g^2rid Library [22], a RTDM that handles low-level communication tasks and decodes IEEE C37.118.2 protocol, in addition to provide additional low-level functionalities. This library is comprised by a separate C + + module that is compiled into a Dynamic Link Library (*DLL*) and used by the other components of the SDK.

² Since April 2020, National Instruments has released the LABVIEW Community Edition which is free of cost (for non-commercial use), which makes the use of S3DK a cost-free alternative for its potential users that lack a license for LabVIEW under certain conditions. For details see: https://www.ni.com/en/support/ documentation/supplemental/20/labview-community-edition-usage-details.html.



Figure 4. S3DK Main User Interface

The STRON g^2 rid library implements all the functionalities of an IEEE C37.118.2 client 241 to connect to a PMU / PDC stream(s) and to manage that connection. Furthermore, it was 242 developed to be extended to manage parallel connections to multiple measurement streams 243 synchronously, and streaming functionalities to emulate a PDC. The library handles the 244 communication and continuous polling of the measurement data, and an Application 245 Programming Interface (API) is implemented to make the measurements accessible into a 246 development environment. The API features a set of LABVIEW specific methods as it was 247 developed in conjunction with the rest of S3DK, but also features non specific methods and 248 can easily be extended to be used in other environments. 249

3.2. Graphical UI

The main user-facing component of S3DK is a LABVIEW *Virtual instrument* (VI) that implements the measurements data handling establishing a connection to a PDC stream and creating data buffers for further delivery in the development environment (i.e., LABVIEW). It has a GUI, depicted on Fig. 4, that lets the user setup the PDC stream, and configure some basic settings for the data handling such as batch size and various timeouts for late data and connection loss. The remainder of the interface is dedicated to managing the connection to the data stream, including some visualization of the activity level: 257

1.	Data Rate in samples per second,	258
2.	Software state machine status,	259
3.	General activity indicators,	260
4.	Connection status indicators,	261
5.	Timestamp of latest data frame received,	262
6.	Data Frame processing activity indicators,	263
7.	Access buffer writing activity indicators,	264
8.	Bad data rate indicator,	265
9.	Buttons to open additional windows for channel selection and seeing raw data,	266
10.	Bad data samples counter.	267
	In the background, the VI orchestrates the communication with the STRON g^2 rid library	268



Figure 5. S3DK Programming Blocks arranged in Palettes

The VI can be used manually through its GUI, or can be integrated in an automated workflow through a remote facility that is accessible through a separate VI that lets the user trigger all the available user inputs pragmatically. 273

3.3. Palettes and Programming Functionalities

S3DK was developed to provide a real-time data mediator for developing PMU applications. It was developed to be integrated into the LABVIEW development environment as "palettes" (i.e., collections of VIs, akin to a MATLAB toolbox or Python Library) organized into different sub-palettes by topic, shown in Fig. 5. The core functionalities of S3DK are embodied by the Graphical UI presented in the previous Section, and a few other VIs that allow its remote control, and the access to the access buffer and the queue for measurement delivery. These are grouped in the "Buffer and Queues" sub-palette.

A set of examples that demonstrate how to use the core functionalities from the "Buffer and Queues" sub-palette is available in the "Examples" sub-palette. 283

The development of these core functionalities required the development of several helper functions that were packaged into separate VIs. These include low level VIs that integrate with the $STRONg^2rid$ library API, as well as a set of data manipulation VIs. The latter were deemed useful for other applications and integrated in the "Utilities" subpalette.

The access buffer of the S3DK offers access to the measurements over a certain time horizon that is defined in the S3DK settings. The functionality relies on the LABVIEW TDMS file format to store the received measurements. The data logging was implemented in VIs, making the specific data structure used by S3DK available for the user in the "Write" sub-palette.

The "Time" sub-palette has a single VI converting the LABVIEW timestamp datatype into an ISO 8601 compliant string of characters. 296

Finally the last sub-palette is dedicated to a few examples that demonstrate the use of the VIs to access the measurements and remote control GUI. 298

4. Templates and Research Applications

The development of S3DK was quickly followed by the development of multiple PMU applications within the second author's research group. The access to real-time PMU measurements allowed to test new concepts and ideas for grid monitoring and control applications. We present in this Section a few notable examples. 303

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4.1. Templates

Templates were the first applications that were developed. A few examples are directly included with S3DK to demonstrate the use of the main blocks for simple applications and automation. 307

In order to further lower the entry barrier to developing and testing new ideas, we decided to develop a "Template PMU App" that provides the basis for developing generic PMU applications. This allows researchers to focus on the core algorithm to develop, rather than the data ingestion. The template is built upon LABVIEW's own "Continuous Measurement and Logging" sample project that provides a framework for acquiring data, logging it and processing it. Thus, the template was prepared by integrating S3DK in the data acquisition loop, using its queue functionality get the latest unread data.

In the original template, the logging and processing loops are independent tasks with 315 the measurements being sent independently to each loop. In the PMU application template, 316 the logging task was replaced by a dedicated buffer that can store a chosen number of PMU 317 measurements. The motivation of creating an additional buffer bypassing the built-in buffer 318 of S3DK arose from the speed of execution of the the built-in version that uses storage into 319 a local file to store the buffered measurements. This method allows to store large amounts 320 of data, but its access time was not suited to sub-second access due to the need to read the 321 data from a file stored on disk. The buffer provided in the template relies on storing the 322 measurement data in the memory, keeping its access time very short. Furthermore a index 323 functionality was integrated to allow tracking of which data has already been read by the 324 processing loop(s), as well as some highly customizable data delivery method (e.g., unread 325 data, past X samples, etc.) 326

Another contribution of this template app was to integrate a file reader to replay measurements saved into a CSV file. It was integrated in the data acquisition loop where the user can switch between reading a file or acquiring real-time data from S3DK. The template automates the flushing of the data currently in the buffer to replace with the new selected data, and automates the data reading to simulate "real-time" replay of the recorded measurement data akin to a live stream.

The template PMU app is distributed as a LABVIEW project as shown on Fig. 6

4.2. Monitoring Applications

As the first users of the S3DK, the research team led by the second author (graduate students, research engineers, post-docs, etc.) implemented a series of prototype applications demonstrating the different usages of PMU measurements for monitoring the grid.

Inspired by traditional monitoring solutions from grid control centers traditionally using SCADA measurements, a dashboard including a map of the Nordic Countries was developed to display real-time measurements of the system coming from PMUs that were deployed as part of the STRON g^2rid project[29]. The dashboard was primarily designed to display the frequency measured at different location, with configurable alarms for values exceeding the normal range of operation, i.e., [49.95 - 50.05 Hz]. A remote panel was also implemented by taking advantage of LABVIEW's built-in facilities for streaming data through a standard internet browser, as well as an iPad data dashboard.

Further developments focused on more advanced and more computationally intensive applications with the following applications: 347

- Monitoring Tool: a tool developed to detect power oscillations (e.g inter-area, subsynchronous, etc.). In particular, it was applied to a case of detection of wind-farm oscillations in [7].
- Mode Estimation: a tool developed to harness ambient measurements for small-signal stability monitoring by estimating the grid's modes of oscillation [30].
- Kalman Filter: a tool implementing a method for extracting steady state information from synchrophasor measurement, as presented in [31].

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Figure 6. Template PMU Application Project File Explorer

- Steady-State Model Synthesis: a tool that uses the Kalman Filter and estimates a T-equivalent circuit between a number of PMUs, being validated in a real-world distribution network in Switzerland [32].
- Voltage stability monitor: is a tool that allows measuring the voltage stability of distribution networks, being able to recognize if the instability is due to the transmission or distribution network [33].
- Feeder Dynamic Rating: is an application that uses PMU data in combination with other sensor data to provide dynamic ratings of distribution feeders [34]. 362

4.3. Control and Protection Applications

The early applications development focused on monitoring applications as these only require a single type of communication: a stream of measurements coming from the PDC that is handled by S3DK. As the research team developed the aforementioned applications and subsequently got more acquainted with S3DK, and the LABVIEW development environment, control and protection applications were the logical next step.

Note that control and protection applications not only need to read measurements, but also need a way to send control signals out to the power system (or its digital twin in the case of a simulation environment). This secondary communication channel is not part of S3DK, however, the S3DK served to acquire and process the data before being sent into different control loops, see [35] for details.

Notable examples of control applications are those dedicated to supplementary damping controls, including damping via load modulation and synchronous generator excitation system-based [35], and a STATCOM-based wide-area stabilizers in [36]. In addition, it has been used in testing a wide-area control system used as a transient stability booster [35].

Meanwhile, sample protection applications include an islanding detection and isolation scheme, and a synchronization scheme presented in [37], an automated microgrid clustering scheme in [38], an auto-reclosing scheme for active distribution networks [39], and a PMU-data assisted over-current protection device for feeders with solid-state transformers [40].



Figure 7. Oscillation Monitoring Dashboard

5. Industry Applications

5.1. Applications Developed at by Grid Controller of India Ltd.

Engineers from the Grid Controller of India Ltd's Northern Regional Load Dispatch Centre (NRLDC) leveraged S3DK to develop a set of monitoring applications, each answering a specific problem that presented itself in the operation of the Indian power grid.

5.1.1. Oscillation Monitoring

The main development focused on an application to detect inter-area oscillations, 380 as depicted on Fig. 7. The application monitors oscillations happening in the frequency 390 range [0.1 - 4] Hz, which covers inter-area modes and local modes. The main dashboard 391 features an indicator that turns from green to red when oscillations are detected, with two 392 accompanying displays showing the frequency of the dominant mode and the substation 393 where the amplitude is detected to be the highest. The remainder of the GUI is dedicated to 394 a map of the area being monitored by 35 PMUs in the north of India, with a dot indicating 395 the position of each PMU. The dots are color coded to represent the angle information from 396 the detected mode of oscillation, giving visual cues as to which buses in the system are 397 coherent during a low frequency oscillation event. 398

Thanks to S3DK, three different methods for oscillations detection were evaluated: Fast Fourier Transform (FFT), Prony Analysis, and Estimation of Signal Parameters by Rotational Invariance Technique (ESPRIT) [41]. Upon testing it was found that the Prony method was highly sensitive to noise, leading to many false positives, and while the other methods performed similarly, the FFT method was the most computationally efficient and retained as main implementation. The frequency spectrum computed for each PMU is displayed on a detailed view of the application as depicted on Fig. 8. More details on this application can be found in [42].

5.1.2. Other Applications

Additional applications were developed by the same engineering team in an attempt to assist the configuration and calibration of various protection schemes in the grid. Differently from the previous section, these applications were develop as prototypes that are not yet in the production environment:

Overflux Monitoring: The application displays the V/F value (as ratio of actual/nominal)₄₁₂ of selected buses in real-time, as shown on Fig. 9. An early warning alerts the operator when this ratio passes 1.10 (the overflux protection trips at 1.14).

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- Load Point Tracking: This application can display the load point (measured impedance)
 of a selected transmission line end in real-time in a polar diagram as shown on Fig. 10.
 This allows to monitor that the load point doesn't encroach the protection zone.
- Zero sequence voltage: This application displays the zero sequence voltage of a selected bus on a polar plane as shown on Fig. 11. It is helpful to monitor unbalances at the selected point of monitoring.



Figure 9. Transmission Line Overflux Monitoring Application

5.2. Other Industrial Applications

As described in [43], Statnett SF has used an early prototype of the S3DK for the development of several voltage stability and oscillation monitoring applications, while at the same time being particularly useful for the monitoring of High-Voltage direct current (HVDC) lines. Even though these application prototypes have not been deployed for regular use of operators, the authors of [43] highlight that they have helped in shaping the tools that are being used in the control room.



Figure 10. Load Point Tracking Application



Figure 11. Zero Sequence Monitoring Application

6. Conclusion

S3DK is a toolkitThe S3DK is a toolkit that was developed to facilitate the fast proto-
typing of synchrophasor applications. This paper aims to promote its release as an open
source project and to summarize its virtues and uses, so that other researchers may exploit
it for their own purposes. This paper also shows that the toolkit was instrumental in sup-
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porting the research activities having been used to develop a wide array of new applications 433 covering monitoring, control and protection application, which are documented in separate 434 publications cited in this paper. Lastly, an engineering team from an the Grid Controller 435 of India Ltd., an Indian grid operator, selected S3DK to develop applications answering 436 a set of problems faced in the control center to facilitate the operators' work of operating 437 the grid with minimal disturbances. It is important to note that these applications were 438 developed independently from the developers of the S3DK, which shows the potential of 439 S3DK in facilitating PMU prototyping in industry. 440

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and Emmett Williamson (online documentation development).444

Data Availability Statement: he code of the S3DK, and its precompiled LABVIEW packages are openly available in Github at https://github.com/ALSETLab/S3DK. 448

Conflicts of Interest: Author Shashank Tyagi was employed by the company EirGrid Group. The449remaining authors declare that the research was conducted in the absence of any commercial or450financial relationships that could be construed as a potential conflict of interest.451

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