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Fragmentation of wind-blown snow crystals

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COMOLA ET AL.: BLOWING SNOW FRAGMENTATION

Understanding the dynamics driving the transformation of snowfall crys-2 tals into blowing-snow particles is critical to correctly account for the energy 3 and mass balances in polar and alpine regions. Here, we propose a fragmen-4 tation theory of fractal snow crystals that explicitly links the size distribu-5 tion of blowing snow particles to that of falling snow crystals. We use dis-6 crete element modeling of the fragmentation process to support the assump-7 tions made in our theory. By combining this fragmentation model with a statistical-8 mechanics model of blowing-snow, we are able to reproduce the character-9 istic features of blowing-snow size distributions measured in the field and in 10 a wind tunnel. In particular, both model and measurements show the emer-11 gence of a self-similar scaling for large particle sizes and a systematic devi-12 ation from this scaling for small particle sizes. 13

1. Introduction

The size of snow surface particles plays an outsize role in determining the radiative 14 balance [Flanner and Zender, 2006] in polar and alpine regions. A key factor that deter-15 mines the size distribution of snow particles is the transformation of snowflakes once they 16 impact the surface. In particular, measurements [Sato et al., 2008] show that, even in 17 light winds, many snowflakes break upon collision with the surface, and that the number 18 of fragments increases with impact velocity. Fragmentation of snow crystals blown by 19 wind might explain the remarkable differences in size between snowflakes and blowing 20 snow particles [Gunn and Marshall, 1958; Schmidt, 1982]. Snowfall crystals are relatively 21 large, often in the range of $1 \sim 5$ mm depending on precipitation intensity, and generally 22 follow an exponential size distribution [Woods et al., 2008; Garrett and Yuter, 2014]. In 23 contrast, blowing-snow particles span the size range 50 \sim 500 μ m with a frequency dis-24 tribution well described by a gamma function [Nishimura and Nemoto, 2005; Nishimura 25 et al., 2014]. 26

Measurements [Legagneux et al., 2002] suggest that, when wind shatters large dendritic 27 crystals into small fragments, the specific surface area of a fresh snow cover significantly 28 decreases. Because specific surface area has been identified as one of the main controls 29 on the optical properties of snow surfaces [Domine et al., 2006], blowing-snow fragmen-30 tation may significantly reduce snow surface albedo in alpine and polar regions, and thus 31 play a key role in the energy budget. Furthermore, the size-distribution of deposited 32 snow partially determines the mechanical properties of alpine snow covers and thus their 33 vulnerability to wind erosion [Gallée et al., 2001] and avalanche danger [Gaume et al., 34

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³⁵ 2017]. Moreover, fragmentation processes intensify snow sublimation, which is not only
³⁶ responsible for a significant loss of snow mass in snow-covered regions [Lenaerts et al.,
³⁷ 2012; MacDonald et al., 2010], but also for bromine aerosols release and seasonal ozone
³⁸ depletion in Antarctica [Yang et al., 2008; Lieb-Lappen and Obbard, 2015].

Here, we propose that fragmentation of snow particles while they are blown by wind is the missing link that connects the size distribution of precipitating snowflakes to that of deposited snow crystals. Specifically, we propose a physical and mathematical description of snow fragmentation, based on the fractal geometry of dendritic snow crystals. We evaluate the assumptions of the theory through discrete element simulations of snow crystal breaking. We finally derive and apply a statistical-mechanics model of saltation, which incorporates the proposed fragmentation processes, to establish the missing connection between snowfall and blowing-snow size-distributions.

2. Snow crystal fragmentation

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When wind blows over a fresh snow cover, snow crystals are lifted through aerodynamic 47 or splash entrainment [Clifton and Lehning, 2008; Comola and Lehning, 2017], follow 48 ballistic trajectories in the saltation layer and eventually impact the surface, thereby pro-49 ducing smaller fragments [Sato et al., 2008]. Large fragments follow the same dynamics, 50 break further and progressively gain momentum until they are small enough to be trans-51 ported in suspension by turbulent eddies [Pomerov and Gray, 1990]. These fragmentation 52 processes are controlled by the kinetic energy and mechanical properties of the wind-53 blown sediment [Kok, 2011]. When subjected to impulsive forces, ice behaves as a brittle 54 material [Kirchner et al., 2001; Weiss, 2001], presenting a linearly elastic response up to a 55

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failure stress at which fracture occurs. In brittle objects, such as ice solids, crack propagation dynamics depend on the impact energy. Low energies generate the so-called damage regime, yielding a few fragments having size of the same order of the original object, while high energies produce the so-called shattering regime, yielding a full scale-invariant spectrum of fragment sizes [Kun and Herrmann, 1999].

The fragmentation dynamics of snow crystals are likely to be different from those of ice 61 solids, in large part because of the uncertain role played by their geometry. It is known 62 that snow crystals present extremely variable shapes, such as needles, columns, plates, 63 and dendrites, depending on temperature and humidity at the time of formation [Nakaya, 64 1954]. Because of such fascinating diversity, the development of a fragmentation theory 65 that applies to any crystal type seems prohibitive. Nevertheless, there exists a family of 66 snow crystals that present a common feature, that is, a fractal structure. A typical ex-67 ample are the dendritic crystals, which mostly form in conditions of supersaturation and temperature ranges $-22 \sim -10$ °C and $-3 \sim 0$ °C [Nakaya, 1954]. Dendritic crystals are 69 commonly observed in nature. It should not surprise, in fact, that one of earliest fractal 70 shapes to have been described is the so-called "Koch's snowflake" [Sugihara and May, 71 1990. Numerical and experimental studies were able to identify the fractal dimension 72 γ of dendritic snow crystals, which spans the range 1.9 \sim 2.5 depending on their spe-73 cific structure [Nittmann and Stanley, 1987; Heymsfield et al., 2010; Chukin et al., 2012; 74 Leinonen and Moisseev, 2015]. We hereafter exploit the fractal properties of dendritic 75 snow crystals to derive a fragmentation theory that links the size distribution of snowfall 76 crystals to that of blowing-snow particles. 77

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When a fractal crystal impacts the surface with sufficient energy, crack formation is 78 likely to take place at the connections between different branches, where sharp corners 79 yield local stress peaks. Accordingly, a fundamental role is played by the size distribution 80 of surface irregularities. Let us define the box-counting measure $M(\epsilon)$ as the number of 81 boxes of side-length ϵ needed to cover the fractal curve. A relevant property of fractals 82 is the scale invariance of the box-counting measure, i.e. $M(\lambda \epsilon) = \lambda^{-\gamma} M(\epsilon)$ [Weiss, 83 2001]. Let us then call D the size of the parent crystals, which is commonly defined 84 as the diameter of the circle of equivalent area [Schmidt, 1982; Nishimura and Nemoto, 85 2005; Gordon and Taylor, 2009, and λD the distance between adjacent cracks, with 86 $\lambda \in [0, 1]$. Assuming that cracks develop from sharp corners, where small curvatures 87 yield local stress peaks, crystal breaking acts by chipping surface irregularities off the 88 fractal contour. Because the distance between adjacent cracks defines the characteristic 89 size of the fragment, λ is hereafter referred to as the dimensionless fragment size. The 90 fragment size distribution resulting from the complete shattering of the fractal crystal 91 would be perfectly scale-invariant, such that the number $N(\lambda D)$ of fragments with size 92 λD is $\lambda^{-\gamma} N(D)$. Given that we are considering only one parent crystal, we would have 93 N(D) = 1 and $N(\lambda D) = \lambda^{-\gamma}$. However, it is sensible to assume that impact energies are 94 generally not large enough to yield a complete shattering, but rather a damage regime 95 characterized by crack formation at a few critical corners. Let us then call $p(\lambda)$ the 96 probability density function describing the likelihood of crack formations at distance λD 97 one from another. The total number of children crystals formed upon impact is therefore 98

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$$N = \int_0^1 N(\lambda D) \,\mathrm{d}\lambda = \int_0^1 \lambda^{-\gamma} p(\lambda) \,\mathrm{d}\lambda. \tag{1}$$

Equation (1) can be employed to estimate the number of fragments produced upon impact of a dendritic snow crystal, provided some reasonable assumptions on the probability distribution $p(\lambda)$ are made. Even though $p(\lambda)$ is not precisely known, it seems reasonable to assume that cracks develop from the sides of larger branches, which are more protruding and thus more subjected to large bending forces and local stress peaks. If we indicate with Λ the size of the larger branches, this assumption yields $p(\lambda) = \delta(\lambda - \Lambda)$, i.e., a Dirac delta function centered in Λ , such that

$$N = \Lambda^{-\gamma}.$$
 (2)

We perform numerical simulations of snow crystal fragmentation based on the discrete 106 element method (DEM) to evaluate whether equation (2) holds for a dendritic snow crys-107 tal. Figure 1a (ii) shows the simplified snow crystal model, whose geometry mimics that of 108 a real dendritic snowflake (Figure 1a (i)), formed of ice elements in contact through cohe-109 sive bonds (see also Figure S1 of the supporting information). The mechanical properties 110 of ice are used for the contact model [Petrovic, 2003; Gaume et al., 2015], yielding realis-111 tic deformations and stress distribution (details about the DEM are provided in section 112 1 of the supporting information [Cundall and Strack, 1979; Akyildiz et al., 1990; Itasca 113 Consulting Group, 2014; Steinkogler et al., 2015]). 114

¹¹⁵ We perform impact simulations with a flat surface for different values of impact speed v_i ¹¹⁶ and impact angle θ_i , computing the stress distribution (Figure 1a (iii)) and the fragment

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¹¹⁷ release (Figure 1a (iv)). Although the DEM approach would allow us to investigate the ¹¹⁸ fragmentation process in three dimensions, such simulations would present additional ¹¹⁹ degrees of freedom and require information on the three-dimensional structure of the ¹²⁰ snowflake. Because our purpose is to test a fragmentation theory derived from the fractal ¹²¹ properties of planar snowflakes, we chose to perform 2-D simulations to provide the best ¹²² trade-off between accuracy and complexity.

Figure 1b shows the cumulative distribution (CD) and the frequency distribution (FD, 123 in the inset) of the fragment sizes. We obtain the distributions from averaging the results 124 of 1000 impact simulations, presenting all possible combinations of 10 values of crystal 125 orientation $\beta_i \in [0^\circ, 60^\circ]$ (see Figure 1a (ii)), 10 values of impact velocity $v_i \in [0.5, 1.5]$ 126 m/s, and 10 values of impact angle $\theta_i \in [5^\circ, 15^\circ]$. The variability ranges of v_i and θ_i are 127 typical of snow saltation [Araoka and Maeno, 1981]. The frequency distribution highlights 128 that the majority of fragments presents $\lambda = 0.2 \sim 0.3$, with a mean value $\langle \lambda \rangle = 0.3$. If we 129 assign $\Lambda = 0.3$ in equation (2) it follows that, for a fractal dimension $\gamma = 2.1$ repersentative 130 of dendritic shapes, the number of fragments N is approximately 10. 131

Figures 1c and 1d show how $\langle \lambda \rangle$ and N vary with respect to impact velocity v_i and impact angle θ_i . Each value of $\langle \lambda \rangle$ and N is obtained by averaging the results of 10 impact simulations with different crystal orientations β_i . These results suggest that $\langle \lambda \rangle \approx 0.3$ and $N \approx 10$ are reasonable approximations in the range of impact velocities and impact angles typical of snow saltation [Araoka and Maeno, 1981] (we study the sensitivity of our results to these values in section 5).

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The DEM simulations thus suggest that equation (2) provides an effective prediction on the number of fragments produced upon breaking of a dendritic crystal. The results also indicate that crystal rebound does not take place under the tested impact conditions and that deposition only occurs for very low impact velocities ($\langle \lambda \rangle = 1$ and N = 0 for $v_i < 0.2 \text{ ms}^{-1}$, Figure 1c), which is consistent with experimental observations [Sato et al., 2008].

3. Blowing-snow fragmentation

In light of the observations of section 2, we propose a physical description of blowing-144 snow fragmentation as schematically represented in Figure 2. A large dendritic snowflake 145 of size D_0 , lifted from the surface through aerodynamic or splash entrainment, follows 146 a ballistic trajectory and eventually impacts the surface producing a number $N = \Lambda^{-\gamma}$ 147 of smaller fragments with size $D_1 = \Lambda D_0$. A fraction $\alpha(D_1)$ of these children crystals 148 moves to the suspension layer transported by turbulent eddies, while the remaining part 149 remains in saltation and eventually impacts the surface generating fragments of size $D_2 =$ 150 ΛD_1 . Given that crystals of size D_2 have a smaller inertia than crystals of size D_1 , 151 turbulent motions are more efficient in carrying them in suspension and thus $\alpha(D_2) > 0$ 152 $\alpha(D_1)$. Following this fragmentation pattern, the number of crystals of size $D_n = \Lambda D_{n-1}$ 153 generated at the n^{th} impact is 154

$$N(D_n) = N(D_{n-1}) [1 - \alpha (D_{n-1})] \Lambda^{-\gamma}.$$
(3)

An assumption underlying the proposed theory is the scale-invariance of the fragmentation process, that is, children crystals of any size present the same fractal geometry and

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thus experience the same fragmentation dynamics of their larger parent crystals. The 157 experimental studies by Sato et al. [2008] and our DEM simulations (Figure 1) suggest 158 that large crystals are too brittle to rebound without breaking and that deposition oc-159 curs in very light wind conditions, i.e., for surface shear stresses significantly below the 160 limit required to initiate snow transport. Accordingly, we assume that crystals of any size 161 experience fragmentation upon impact, neglecting deposition and rebound. In reality, 162 crystal fragments with size of the order of the smallest branches (around 50 μ m) present 163 a spheroidal shape rather than a fractal one [Gordon and Taylor, 2009]. Small-scale de-164 viations from the fractal theory are, in fact, typical of all geometries of nature Brown 165 et al., 2002]. The saltation dynamics of small ice fragments become then similar to those 166 of sand grains, which experience deposition and rebound rather than fragmentation [Kok 167 et al., 2012; Kobayashi, 1972]. Bearing this limitation in mind, we can still regard the 168 assumption of scale-invariance as adequate for the purpose of studying how fragmentation 169 processes transform the snowfall size-distribution, given the significant separation between 170 the size of large snowflakes and the length scale at which the fractal theory is expected 171 to fail. 172

4. Modeling blowing-snow fragmentation

We incorporate the proposed fragmentation process in a statistical-mechanics model of saltation. We cast the particle dynamics in a residence time distribution framework, which has been widely employed in stochastic formulations of water [Botter et al., 2011], contaminant [Benettin et al., 2013], and heat transport [Comola et al., 2015] in underground formations. Let us define the residence time of a crystal as the time elapsed between the

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start and the end of its motion in the saltation layer. Crystal motion can start when the crystal is entrained from the surface, through aerodynamic forces or splash, or when the crystal is formed upon fragmentation of a larger crystal. Conversely, the end of motion occurs when the crystal moves to the suspension layer carried by turbulence or when it impacts the surface, producing smaller fragments.

The number N(D, t) (m⁻²) of crystals of size D in saltation at time t can be expressed as the number of crystals whose motion starts at time t' and whose residence time is larger than t - t', for all t' < t, i.e.

$$N(D,t) = \int_{0}^{t} \left[E(D,t) + F(D,t) \right] P(t-t' \mid D) \, \mathrm{d}t'.$$
(4)

E(D,t) and F(D,t) (m⁻²s⁻¹) are surface entrainment and fragment production, i.e. the fluxes responsible for initiating crystal motion. P(t - t' | D) is the probability that the residence time of crystals of size D is larger than t - t'. We can differentiate equation (4) using Leibniz's rule to express the size-resolved mass balance equation (see section 2 of the supporting information for more details)

$$\frac{\mathrm{d}N(D,t)}{\mathrm{d}t} = E(D,t) + F(D,t) - S(D,t) - I(D,t).$$
(5)

On the right-hand side of equation (5), the two sink terms S(D, t) and I(D, t) (m⁻²s⁻¹) are the suspension flux and the impact rate of crystals of size D at time t. These two terms read

$$S(D,t) = \alpha(D) \int_0^t \left[E(D,t') + F(D,t') \right] p_S(t-t') \, \mathrm{d}t', \tag{6}$$

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$$I(D,t) = [1 - \alpha(D)] \int_0^t [E(D,t') + F(D,t')] p_I(t-t') dt'.$$
(7)

 $\alpha(D) \in [0,1]$ is the probability that a crystal of size D becomes suspended. Conversely, 194 $1 - \alpha(D)$ is the probability that a crystal of size D impacts the surface. Here, we assign 195 to $\alpha(D)$ the expression of the eddy-diffusivity correction for inertial particles with respect 196 to passive tracers [Csanady, 1963], given that the two quantities obey the same limits and 197 are governed by similar physics. In fact, the probability of becoming suspended is equal 198 to 1 in the limit of $D \to 0$, that is, for passive tracers, decreases as the settling velocity 199 becomes relevant compared to turbulent fluctuations, and reaches the lower value 0 in the 200 limit of $D \to \infty$. We therefore write 201

$$\alpha\left(D\right) = \left[1 + \frac{w_s^2\left(D\right)}{\sigma^2}\right]^{-\frac{1}{2}},\tag{8}$$

where $w_s(D)$ is the settling velocity of crystals of size D and σ^2 is the turbulence velocity variance (see section 2 of the supporting information for their analytical expressions [Pope, 2001; Stull, 2012]). Furthermore, $p_S(t - t')$ and $p_I(t - t')$ are the residence-time probability density functions of crystals moving to suspension and impacting the surface, respectively. If we assume that particles move independently from one another, it follows that the dynamics are well described by a Poisson process, yielding for $p_S(t - t')$ and $p_I(t - t')$ exponential residence time distributions.

We assume that the surface entrainment E(D,t), the first source term on the right-hand side of equation (5), samples uniformly from the size-distribution of crystals resting at the surface, according to the principle of equal mobility [Willetts, 1998]. Because we aim at

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establishing a link between the snowfall and blowing-snow size distributions, we consider 212 the typical situation in which drifting snow already starts during snowfall events. We 213 therefore simulate impact and fragmentation of snowfall crystals by applying equation (1) 214 to an exponential snowfall size-distribution bounded within 0.75 and 2 mm (dashed black 215 line in Figure S4 of the supporting information), which is typical of precipitation intensities 216 of the order of $\sim 0.3 \text{ mmh}^{-1}$ [Gunn and Marshall, 1958]. The resulting size-distribution 217 of surface crystals proves similar to that obtained by sieve analysis in very cold conditions 218 [Granberg, 1985] (dashed grey line in Figure S4 of the supporting information). It does 219 happen, sometimes, that low-wind snowfalls generate a snow cover that is eroded by 220 subsequent higher winds. In these cases, the size distribution of surface particles does not 221 only result from fragmentation of snowfall crystals, but also from the snow metamorphism 222 that takes place in the snow cover [Colbeck, 1982]. Although relevant in some situations, 223 the effect of snow metamorphism goes beyond the scope of this work and is thus not 224 included in our model. 225

The second source term in equation (5) is the fragment production rate F(D, t), which, following equation (1), reads

$$F(D,t) = \int_0^1 I\left(\frac{D}{\lambda}, t\right) \lambda^{-\gamma} p(\lambda) \,\mathrm{d}\lambda.$$
(9)

If we assume again that $p(\lambda) = \delta(\lambda - \Lambda)$, we obtain $F(D, t) = I(D/\Lambda, t) \Lambda^{-\gamma}$.

We solve equation (5) numerically, letting the system evolve until a stationary condition is reached (see section 3 of the supporting information for more details on the transient

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²³¹ process). We then compute the size-distribution of blowing-snow by normalizing N(D,t)²³² in stationary conditions.

5. Model results

We first perform a model simulation using $\gamma = 2.1$ and $\Lambda = 0.3$, which are representative 233 of the dendritic snow crystal considered in section 2. In our simulations, we set a lower 234 threshold of 10 µm to the particle size, assuming that any smaller crystal disappears 235 through sublimation. To evaluate the model results, we analyze all known published 236 datasets of blowing-snow size distributions, collected from field campaigns in the United 237 States [Schmidt, 1982], Canada [Gordon and Taylor, 2009], French Alps [Nishimura et al., 238 2014], and Antarctica [Nishimura and Nemoto, 2005] (see section 5 of the supporting 239 information for more details). It is worth noting that the snowflake shape for the different 240 measurements is unknown, and likely presents a mix of fractal and non-fractal snow types. 241 We only consider size-distribution measurements within the saltation height, which is 242 approximately of the order of 15 cm [Gordon et al., 2009; Nishimura and Nemoto, 2005]. 243 If several saltation measurements are available for the same dataset, we average them 244 to obtain the mean size-distribution. Additionally, we present the blowing-snow size-245 distribution that we measured in wind tunnel tests. We carried out the experiments over 246 a post-snowfall surface at the Institute for Snow and Avalanche Research (SLF/WSL) in 247 Davos, Switzerland, at 1670 m above sea level [Clifton et al., 2006]. We obtain the blowing-248 snow size-distribution by averaging three series of measurements within the saltation layer, 249 namely at 10, 17, and 30 mm above the surface. 250

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Figure 3 shows the size-distribution dN/dD as obtained from the fragmentation model 251 (grey dashed line) and dataset analyses (colored dots). The measured size-distributions, 252 which are commonly approximated by a gamma function, are well reproduced by the 253 proposed fragmentation theory. In particular, results highlight that blowing-snow size-254 distributions display a power-law scaling for the largest crystal sizes $(D > 200 \ \mu m)$ and 255 a systematic deviation from this self-similar scaling for smaller sizes. Interestingly, the 256 power-law exponent seems to be approximately 2.1, suggesting that the fractal dimension 257 is indeed a control on snow crystal fragmentation. The deviation from the power-law 258 indicates that there exists an under-production of fragments smaller than 200 μ m, that 259 is, not all the small branches are chipped off the crystal contour. In fact, as shown in 260 Figure 2, the fragmentation process yields small fragments only after multiple impacts, 261 when a significant number of the larger fragments has already moved to suspension with 262 smaller branches still attached. It is worth noting, however, that the small-scale deviation 263 observed in the measured size-distributions may in part be due to the rapid sublimation 264 of the smallest ice fragments [Groot Zwaaftink et al., 2011]. 265

²⁶⁶ The results thus suggest that a fractal power-law scaling emerges in the size range for ²⁶⁷ which turbulent eddies are not efficiently carrying crystals in suspension $(200 - 500 \ \mu\text{m})$. ²⁶⁸ On the contrary, below 200 μ m, turbulence starts to be efficient in removing crystals from ²⁶⁹ the saltation layer and reducing the production of smaller fragments. As a result, the ²⁷⁰ peak of the blowing-snow size-distributions lies at ~ 100 μ m, where there is the optimal ²⁷¹ trade-off between the two described mechanisms.

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We further perform a sensitivity analysis of the model results to variations in the fractal 272 dimension γ , within the range suggested by measurements, and fragment size Λ , within the 273 range suggested by the DEM simulations. The purpose of this analysis is to test whether 274 variations in the dendritic structure (different γ values) and in the impact conditions 275 (different Λ values) may significantly alter the blowing-snow size distribution. Figures 3b 276 and 3c suggest that varying γ and Λ produces significant quantitative variations in the 277 results. Despite this quantitative sensitivity, the main qualitative features of the results 278 seem robust relative to reasonable variations in γ and Λ . 279

6. Discussion and conclusions

We proposed a fragmentation theory for snow crystals to test the hypothesis that frag-280 mentation processes constitute the missing link between the seemingly inconsistent size 281 distributions of snowfall and blowing-snow. A key assumption underlying our model is 282 that the fragment size and the fragment number follow from the power-law distribution of 283 surface irregularities typical of fractal geometries. We used discrete element simulations 284 of snow crystal breaking to explicitly test this assumption. These simulations indicated 285 that the theoretical results in terms of fragment size and number is indeed representa-286 tive of a dendritic snowflake geometry (Figure 1). The results of a statistical-mechanics 287 model of saltation, accounting for the proposed fragmentation theory, are consistent with 288 measurements (Figure 3a). 289

²⁹⁰ Our results suggest that the self-similarity of snow crystals shapes the blowing-snow ²⁹¹ size-distribution. In particular, our model predicts, and measurements support, a self-²⁹² similar scaling for crystal sizes larger than 200 μ m (Figure 3). The deviation from the

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²⁹³ power-law observed at the lower end of crystal size is due to the relatively large turbulent-²⁹⁴ diffusivity of particles smaller than 200 μ m, which are efficiently transported in suspension ²⁹⁵ and are thus less likely to produce smaller fragments upon impact.

Overall, our analysis suggests that fragmentation processes can indeed transform an exponential snowfall distribution into the so-called gamma distribution of blowing-snow. In particular, the typical features of a gamma distribution emerge, on one side, from the fractal geometry and, on the other side, from the interactions between inertial particles and turbulent eddies.

Further analyses show that these features are conserved for a wide range of fractal 301 dimensions and fragment sizes (Figures 3b and 3c). This suggests that the proposed 302 fragmentation dynamics may hold for a wide range of dendritic snowflakes and impact 303 conditions. It is worth noting that some commonly observed snow crystals, such as needles 304 and plates, do not present the fractal structure considered in our theory. Figure 3a 305 indicates, however, that our model can reproduce several measured size distributions, 306 which may have resulted from fragmentation of snowflakes with different shapes. This 307 suggests that our theory may still provide an effective prediction of the size and number 308 of fragments produced by non-dendritic crystals, although the assumptions on which the 309 theory rests are not supposed to hold for these shapes. 310

Our work also points toward the need of accurate estimations for the typical time- and length-scale necessary to complete the transition from the size-distribution of snowfall to that of blowing-snow. This will clarify the need of accounting for fragmentation processes

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in snow transport models and in climate models, in order to improve the predictions of surface mass and energy balances in snow-covered regions.

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Figure 1. (a) Illustration of the DEM simulations: i) real snowflake (credit: Satoshi Yanagi, http://www1.odn.ne.jp/snow-crystals/page1_E.html), ii) simplified DEM description, iii) ratio between tensile stress σ in bonds and at the moment of the impact and tensile strength of ice σ_r , iv) fragmented snowflake (each level of grey represents a fragment). In the snow crystal model, the radius of the largest elements is 50 µm, while the radius of the smallest ones is 12.5 µm. (b) Cumulative size distribution (CD) of the dimensionless fragment size λ and corresponding frequency distribution (FD). (c) Influence of impact velocity and (d) impact angle on the average dimensionless fragment size $\langle \lambda \rangle$ and number of fragments N. The grey bands identify the ranges of impact velocity and impact angle typical of snow saltation, i.e., $0.5 < v_i < 1.5$ m/s and $5^{\circ} < \theta_i < 15^{\circ}$ [Araoka and Maeno, 1981].

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Figure 2. Schematic representation of the fragmentation process during saltation. Each crystal impact leads to formation of fragments having size equal to Λ times the original size. The number of children crystals follows from the scale-invariance property. Small fragments, formed after repeated impacts, are likely to be caught by turbulent eddies and transported to the suspension layer.

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Figure 3. (a) Size-distribution of saltating snow crystals, modeled with the proposed fragmentation theory (dashed grey line), reported in published datasets [Gordon and Taylor, 2009; Nishimura et al., 2014; Nishimura and Nemoto, 2005; Schmidt, 1982], and measured in the SLF wind tunnel in Davos, Switzerland (colored dots). Because the normalized distributions are sensitive to the specific range of sizes measured by the instruments, we rescaled the distributions such that all of them are tangent to a unique power-law (black dashed line) in the range where they show a scale-invariant behavior (200 ~ 500 μ m). (b) Sensitivity analysis of the modeled blowing-snow size distribution to the fractal dimension γ . (c) Sensitivity analysis of the modeled blowing-snow size distribution to the dimensionless fragment size Λ .

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