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SOTRM: A PROGRAM TO GENERATE FIRST AND SECOND ORDER
MATRIX ELEMENTS BY TRACKING CHARGED PARTICLES IN A
SPECIFIED MAGNETIC FIELD

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May 12, 1970

ABSTRACT

A CDC 6600, FORTRAN IV program SOTRM is described. SOTRM generates first and second order transformation elements by integrating numerically through a specified magnetic field. It can also be used for ray tracing. Data input is described and an illustrative example is presented. The results obtained can be used in a matrix beam transport program.

I. INTRODUCTION

Program SOTRM is a CDC 6600, FORTRAN IV program that generates first and second order transformation elements by integrating numerically through a specified magnetic field a specific set of rays which are then used in an appropriate elimination scheme [1]. It can also ray trace up to 30 nearby rays while integrating for the central orbit. For the purpose of evaluating the significance of the generated elements, it has the ability to apply a previously generated set of elements to the initial conditions of the nearby rays currently being obtained by integration and thus compare the integrated values of the solution with those obtained by applying the transformation.

This program consists of a number of subroutines and should be easily adaptable to various physical problems. We shall give in the following sections brief descriptions of these routines that should help in understanding the program and its subroutines, an explanation of the necessary data input, and a simple test example. It is assumed that the reader is familiar with the development given in [1]; however, the program is easy to use and if the 'black box' approach is taken, it should be possible to set up problems and run the program without consulting [1].

The necessary data input is given in Table III, sample test data is given in Table IV, the resultant output in Table V, and the program listing in Table VI.

II. PROGRAM AND SUBPROGRAM DESCRIPTIONS

The main program is

PROGRAM SOTRM(INPUT,OUTPUT,TAPE1)

and it is a driving program for subroutine SOTRMI which actually generates the desired quantities. The sole purpose of SOTRM is to input data that is used in SOTRMI and to call and execute that subroutine under user control. If it is desired to incorporate SOTRMI into some user written program, then SOTRM may be discarded.

The main program is built in the style:

```

control:= read; if control= -1 then STOP else
if control=1 then
begin comment whatever happens when control=1. See the input section;
end else
if control=2 then
begin whatever happens when control=2;
.
.
.
end else
.
.
.

```

The main program is, essentially, described by the data input so we shall describe it no further here.

```

SUBROUTINE SOTRMI(SØ1,Z1,PI,V,W,PR,PI)
RREAL SØ1,Z1(1),PI(1),V(5,5),W(5,5,5),PR(1)
INTEGER PI(1)

```

This subroutine generates a first order matrix V, and a second order matrix W.

It can also ray trace one reference ray and up to 30 nearby rays. All necessary values are supplied and returned in the argument list; the variables appearing there are described in Table I.

There are a number of labeled commons in SOTRMI that are used for communicating with the subprograms and their names and associated variables are given in Table II.

Once it sets all the initial conditions, SOTRMI is basically a calling routine for the integration routines. Presently, the Lawrence Radiation Laboratory library routine ZAM [2] is used to carry out this integration. The integration loop will be executed until the program is shut off. The three variables in the common block LIMIT allow the user to control this shut off. The integration loop is exited from and the final values calculated whenever $S\theta \geq S\theta_{MAX}$ or the number of passes through the loop is greater than MAX. Thus, any criteria can be used to delimit the integration range and then one of the variables in LIMIT may be used to actually exit from the loop.

The action taken with regard to matrix generation and printout while integrating will depend on the values of the variables appearing in the integer parameter vector PI. These are explained in the section giving the data input to the driving program SOTRM.

SOTRMI is built so that upon entry, the values in $S\theta$, ZI, PI are the initial values and upon exit, all arguments have their final value. In general, successive calls to SOTRMI will generate cumulative results valid over the range of a particular call. The exact effect can be ascertained by consulting Table I.

Subroutines ZINIT and ZFINAL are used to establish respectively the

initial values of the solution vector upon entry into SOTRMI and the current, or final, values of the solution vector corresponding to S_0 , or to S_01 upon exit from SOTRMI. It should be remembered that the nearby rays have coordinates $(\delta x_1, \delta \theta_1, \delta x_2, \delta \theta_2, \delta P/P)$ external to SOTRMI, but we are integrating $(\delta x_1, \delta P_1, \delta x_2, \delta P_2)$, thus these two routines perform the necessary transformations.

Subroutine SF generates second order elements using either equation (20) or equation (21) of [1]. The initial values chosen for this elimination are as given in subroutine SETZ which actually sets the initial conditions when generating matrix elements. This subroutine uses the values $(A(1), \dots, A(5))$ located in common YAFS. If we use the dimension less coordinates $(\delta x_1/\rho, \delta \theta_1, \delta x_2/\rho, \delta \theta_2, \delta P/P_0)$ where ρ is the radius of curvature of the reference particle, then for a uniform field, we have an optimum choice of $(.01, .1, .01, .1, .0001)$ for the value of the vector A.

Subroutine FIELD is expected to set the magnetic field values in the common block FIELD corresponding to the current value of the integration variable S_0 . The units are MKS.

Subroutine GAUSS takes a position vector R corresponding to S_0 and returns the value in gauss of the three field components g_1, g_2, g_3 . For the reference particle, these are in the global coordinate system; for the nearby particle, they are in the local coordinate system; that is, the moving trihedral.

Subroutine FUNC(S_0, Z, F) evaluates the right hand side of the differential equation $DZ = F(Z(s_0))$. See [1], equations (2) and (10).

The purpose of the remaining subroutines used in SOTRMI can be ascertained from the program source listing. In practice, it should be

possible to treat a variety of cases by making appropriate changes to the two field routines FIELD and GAUSS. The integration routines can be changed by substituting another integration package for ZAM [2].

III. PROGRAM CONTROL AND DATA INPUT FOR SOTRM

PROGRAM SOTRM (INPUT,OUTPUT,TAPE1)

This program drives SOTRM1 and can be used to ray trace or to generate transfer matrix elements or a combination of these tasks.

The program is controlled by inputting a quantity S that determines what the program will do. In Table III are given the values of S and the corresponding card, or cards, read and the action taken. S = - 1.0 stops the program and S = 99.0 calls the subroutine SOTRM1.

The program always reads S and after executing the selected section it will again read S. Thus, one can do as many cases as desired. Schematically, we have

```
L1:  S := read;
      execute the appropriate section;
      go to L1;
```

A few comments about SOTRM1 are in order here. The vector Z contains the values of the solution corresponding to S \emptyset . Before calling SOTRM1, S = 99, the user must be sure that these values are properly set. Upon exit from SOTRM1, the values in Z will correspond to the value of S \emptyset which existed at the time of exit. Thus, two consecutive calls to SOTRM1 will be cumulative unless the user resets the values in the Z vector. This feature, while possibly annoying in some cases, allows one to have some control when integrating through a series of elements.

However, when generating matrix elements, the subroutine SETZ will store the perturbations in Z upon each entry into SOTRM1. Thus, the

generation of the matrices is not cumulative, but correspond instead to the range of integration within one call to SOTRMI. The final value of the solution vector used to generate the matrix elements does, however, reside in Z upon exit from SOTRMI. The initial values used to start the integration loop in SOTRMI are stored in the common block ZSAVE, should they be desired. When checking the integrated values against those obtained from the generated transformation elements, subroutine APTRAN applies the transformation to the values in ZSAVE.

IV. SAMPLE DATA INPUT AND CORRESPONDING OUTPUT

To illustrate the program data input and output, we use as an example a 510.72 MeV proton reference particle which moves in a circle in a uniform field of one meter. The data for these examples are given in Table IV.

In Example 1, we generate a transfer matrix corresponding to a 45° bend. Example 2 traces a reference ray and two nearby rays through a 45° bend. Example 3 generates a matrix correspond to a 45° bend, saves the matrix and subsequently applies it to three nearby rays to check against the integrated values. The output of the program SOTRM for these three examples is presented in Table V.

In Example 3, the values ZTRAN represent the values $(\delta x_1, \delta \theta_1, \delta x_2, \delta \theta_2, \delta P/P)$ obtained by applying the transformation to the initial values. Whereas, ZSOLN gives the values obtained by integration. In the first case, the solution was used to obtain the transformation, thus the two columns are essentially identical. However, the next pass applies the transformation to an arbitrary nearby ray and the results are seen to be somewhat different which is, of course, expected.

Table I

SOTRMI Argument List

<u>Variable</u>	<u>Comment</u>
SØ1	The initial value of the independent variable at the time SOTRMI is called. The final value of the independent variable upon exit from SOTRMI.
Z1	This vector contains the values of the coordinates of the reference ray and the nearby rays corresponding to the value of SØ1 upon entry and exit. It is the same as Z in SOTRMI and must be set as indicated on the card C4 input to SOTRMI. Note: When generating matrix elements, SOTRMI will place the initial conditions in Z1, thus, destroying any previously set values. The matrix is, therefore, not cumulative for successive calls to SOTRMI.
P1	This vector contains the momentum perturbation $\delta P/P_0$ of the nearby particles. It is the same as P in SOTRMI and must be set as indicated on the card C2 input to SOTRMI. The dimensions of P1 and Z1 must be large enough to hold the required information. Presently P1 has up to 30 elements and Z1 up to $4 \times 31 = 124$ elements.
V(5,5)	Upon exit from SOTRMI, the first order elements of the transfer matrix corresponding to the value of SØ1 are stored here if these values have been asked for.
W(5,5,5)	Upon exit from SOTRMI, the second order elements of the transfer matrix corresponding to the value of SØ1 are stored here if those values have been asked for. The

Table I - contd.

<u>Variable</u>	<u>Comment</u>
	nearby rays are assumed to be a vector $y = (\delta x_1 [\text{cm}], \delta \theta_1 [\text{mr}], \delta x_2 [\text{cm}], \delta \theta_2 [\text{mr}], \delta P/P_0)$ and these arrays can be applied directly as
	$y_i = \sum_j V_{ij} y_j^{(o)} + \sum_{j,k} W_{ijk} y_j^{(o)} y_k^{(o)}$
PR	This is a real parameter vector the values of which are param (1), ..., param (4) of SOTRM. See the card A2 input to SOTRM.
PI	This is an integer parameter vector the values of which are param (5), ..., param (8) of SOTRM. See the card A2 input of SOTRM.

Table II

SOTRM Tabled Common Blocks

<u>Common Block</u>	<u>Variable</u>	<u>Comment</u>
CASES	NUM	The number of rays, including the reference ray, that are being tracked. Present limit 31.
	L	Global counter
	K	Global counter
CHARGE	Q	Charge [MKS] of the reference particle and of nearby particles.
MOM	P0	Momentum [MKS] of the reference particle.
	P(40)	Momentum, $1 + \delta P/P_0$, of the nearby particles.
FIELD	BB02	Field $B_2(r_1, 0, r_2)$ [Webers] on the reference orbit. It is assumed that the field is only in the two direction [1]. See the figure for the card B input to SOTRM to obtain the axis orientation.
	BB1(40)	The B_1 component of the field on the nearby orbit at the current value of the independent variable $S0$.
	BB2(40)	The B_2 component of the field on the nearby orbit.
	BB3(40)	The B_3 component of the field on the nearby orbit.
SOLN	Z(164)	The current value of the solution vector. It's value corresponds to equations (3) and (9) of [1]. The units are [MKS].
DER	F(164)	The righthand side of the equation $DZ = F(Z)$. These values are defined by equations (2) and (10) of [1]

Table II - contd.

<u>Common Block</u>	<u>Variable</u>	<u>Comment</u>
PARAM	CONST(8)	Contains the conversion factors from external units to internal [MKS] units.
LIMIT	SØ	Current value of the independent variable.
	SØMAX	The maximum allowed value of SØ.
	MAX	The maximum total number of steps allowed in the integration process.
YAFS	YP(5)	The current $y(+t^{(j)})$ vector for the elimination process [1].
	YM(5)	The current $y(-t^{(j)})$ vector for the elimination process [1].
	A(5)	The perturbation values (δx_1 [cm], $\delta \theta_1$ [mr], δx_2 [cm], $\delta \theta_2$ [mr], $\delta P/P_0$) used when constructing the first and second order matrix elements.
	U(5,5)	The first order matrix correspond to the current value of SØ.
	S(5,5,5)	The second order matrix corresponding to the current value of SØ.
WORK	COUNT	The number of function evaluations used in the integration process to move from SØ1 to the current value of SØ.
	STEP	The current number of maximum step sizes taken.
INIT	ZSAVE(15Ø)	Saves the initial values (δx_1 , $\delta \theta_1$, δx_2 , $\delta \theta_2$, $\delta P/P_0$) if all nearby rays corresponding to SØ1 upon entry into SOTRMI.

Table III

Data Input to SOTRM
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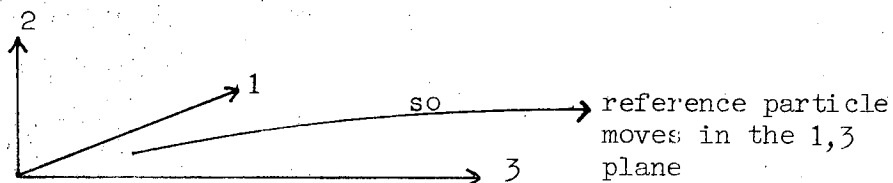
<u>Value of S</u>	<u>Card</u>	<u>Parameters Read</u>	<u>Format</u>
1	A1	K	E10.0
	A2	(I, PARAM(I), I = 1, K)	(I5, 5X, E15.0)
		param(1) = Q = signed number of charges	
		param(2) = detsin = max. step size [cm]	
		param(3) = s0 max = max. arc length [m]	
		param(4) = S01 = initial arc length [m]	
		param(5) = option	
		0 ray trace.	
		1 first order matrix.	
		- 1 first order matrix, second order trace.	
		2 first order and second order matrices, asymmetric.	
		3 first order and second order matrices, symmetric.	
		param(6) = num = number of rays including the center reference ray. May be set to 1 if generating matrix elements. Value \leq 31.	
		param(7) = max = maximum number of steps that can be taken, includes all step adjustments of the variable step size integrator.	
		param(8) = nprint	
		= 0 No print out of ray trace or of matrix generation.	

Table III - contd.

Value of S	Card	Parameters Read	Format
		param(8) = nprint (continued)	
		> 0	Print out every nprint steps, will also print initial and final values.
		< 0	Same as > 0 except that the matrix elements will be stored on Tape 1 if generating elements or will be read from Tape 1 and applied to the initial conditions if ray tracing.

*A2
(continued)*

2	B	(low lim(i), uplim(i), I = 1, 3)	(8E10.0)
---	---	----------------------------------	----------



low lim (i) The lower limit of the reference particle [m].

up lim (i) The upper limit of the reference particle [m].

3	C		
(3V3.1)	C1	K	(I5)
	C2	(I,P(i),I = 1,K)	(I5,5X,E15.0)

P(i) = momentum of the nearby particle $\delta P/P_0$.

We have to have read in (num -1) of these at least once.

Table III -contd.

Value of S	Card	Parameters Read	Format
(3V3.2)	C3	L	I5
	C4	(I, Z(i), i = 1,L)	(I5,5X,E15.0)
		Z(1) = reference ray Pc [mev]	
		Z(2) = angle [deg]	
		Z(3) = starting x_1 [meters]	
		Z(4) = starting x_3 [meters]	
		Z(5) = δx_1 [cm]	
		Z(6) = θ_1 [milliradian]	
	Z(7) = δx_2 [cm]		
	Z(8) = θ_2 [milliradian]		
4	D	(A1(I, J), J = 1,10), I = 1,10) (A2(I, J), J = 1,10), I = 1,10) Input row wise 5 items / card the matrix A1 and then the matrix A2. These can be used as one wishes, but are presently used with F. Selph field	(5E10.0)
5	E		
(5V5.1)	E1	K	(I5)
	E2	(I,J,A1(I,J),L=1,K)	(J5,I5,E15.0)
(5V5.2)	E3	K	(I5)
	E4	(I,J,A2(I,J),L=1,K)	(I5,I5,E15.0)
Allows one to change values of the individual elements of A1 or A2 or both.			

Table III - contd.

Value of S	Card	Parameters Read	Format
6	F1	K	(I5)
	F2	(I,A(I),L = 1,K)	(I5,5X,E15.0)
		$A(1) = \delta x_1$ [cm] $A(2) = \delta x_1'$ [mr] $A(3) = \delta x_2$ [cm] $A(4) = \delta x_2'$ [mr] $A(5) = \delta p/p$	These are the magnitude of the perturbation for the derivative calculation. They are nominally set by data statements as
			$\left. \begin{array}{l} .01 \text{ [cm]} \\ .1 \text{ [mr]} \\ .01 \text{ [cm]} \\ .1 \text{ [mr]} \\ .0001 \end{array} \right\}$

Table IV

SAMPLE INPUT DATA

	EXAMPLE 1		EXAMPLE 3
1.0		1.0	
8		8	
1	1.0	1	1.0
2	1.5707963267949	2	1.5707963267949
3	30.0	3	30.0
4	0.0	4	0.0
5	3.0	5	3.0
6	1.0	6	1.0
7	50.0	7	50.0
8	50.0	8	-50.0
3.2		3.2	
4		4	
1	510.72	1	510.72
2	90.0	2	90.0
3	2.0	3	2.0
4	1.0	4	1.0
99.0		99.0	
-1.		1.0	
		2	
		5	0.0
1.0		6	4.0
8		3.1	
1	1.0	3	
2	1.5707963267949	1	.01
3	30.0	2	.05
4	0.0	3	.10
5	0.0	3.2	
6	3.0	16	
7	50.0	1	510.72
8	50.0	2	90.0
3.2		3	2.0
12		4	1.0
1	510.72	5	.5
2	90.0	6	5.0
3	2.0	7	.5
4	1.0	8	5.0
5	1.0	9	1.0
6	0.0	10	10.0
7	0.0	11	1.0
8	0.0	12	10.0
9	0.0	13	5.0
10	0.	14	20.0
11	1.0	15	5.0
12	5.0	16	20.0
3.1		99.0	
2		-1.0	
1	.01		
2	.01		
99.0			
-1.0			

TABLE V

PROGRAM OUTPUT EXAMPLES 1 - 3

EXAMPLE 1

```

CONTROL= 1.000
NUMBER OF PARAMETERS READ = 8
C= 1.00000000
DELSIN= 1.57079633 (CM)
SOMAX= 30.000000 (M)
SOJ= 0.000000 (H)
OPTION= 3.00000000
NUM= 1.00000000
MAX= 50.00000000
NPRINT= 50.00000000

CONTROL= 3.200
NUMBER OF PARAMETERS READ = 4
Z( 1)= 510.7200000(MEV) Z( 2)= 90.0000000( DEG) Z( 3)= 2.0000000( M) Z( 4)= 1.0000000( M)
Z(
CONTROL= 99.000

```

START OF SOTRMI

1 THE FOLLOWING HEADINGS ARE TO BE USED FOR COL. 1-7

I	SO(METER)	K	1	2	3	4	5	6	7
0	0.00000	0	5.1072000E+02	-8.7594838E-13	2.0000000E+00	1.0000000E+00	9.0000000E+01	1	
		U(1,J)	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(2,J)	0.0000000E+00	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(3,J)	0.0000000E+00	0.0000000E+00	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(4,J)	0.0000000E+00	0.0000000E+00	0.0000000E+00	1.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(5,J)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	1.0000000E+00	0.0000000E+00	
		S(1,1,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,2,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,3,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,4,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,5,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,1,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,2,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,3,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,4,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,5,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(3,1,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(3,2,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	

TABLE V - contd.

Example 1 - contd.

S(3,3,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(3,4,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(3,5,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(4,1,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(4,2,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(4,3,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(4,4,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(4,5,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(5,1,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(5,2,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(5,3,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(5,4,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
S(5,5,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
0	3.6113357E+02	3.6113358E+02	2.7071067E+02	1.2928932E+00	4.5000000E+01	110	
U(1,J)	7.0710678E-01	7.0710678E-02	0.000000E+00	0.000000E+00	0.000000E+00	2.9289322E+01	
U(2,J)	-7.0710678E+00	7.0710678E-01	0.000000E+00	0.000000E+00	0.000000E+00	7.0710679E+02	
U(3,J)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
U(4,J)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
U(5,J)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(1,1,K)	-2.4999979E-03	2.4999991E-04	-8.4703295E-18	-4.3512594E-11	-4.3512594E-11	2.4999991E-01	
S(1,2,K)	2.4999991E-04	1.0355356E-05	4.2351647E-19	-2.4701251E-12	-2.4701251E-12	1.0355328E-02	
S(1,3,K)	-8.4703295E-18	4.2351647E-19	0.000000E+00	-4.2351647E-19	-8.4703295E-16	-8.4703295E-16	
S(1,4,K)	-4.3512594E-11	-2.4701251E-12	-4.2351647E-19	1.4644661E-05	-3.0758907E-09	-2.4703295E-09	
S(1,5,K)	2.4999991E-01	1.0355328E-02	-8.4703295E-16	-3.0758907E-09	-2.4703295E-09	-2.4703295E-09	
S(2,1,K)	4.6447290E-08	-1.7405893E-09	1.2924697E-22	-8.8496523E-10	3.5355317E+00	3.5355317E+00	
S(2,2,K)	-1.7405893E-09	-3.5355301E-04	-1.3552527E-17	7.5073929E-11	-2.2711833E-07	-2.2711833E-07	
S(2,3,K)	1.2924697E-22	-1.3552527E-17	0.000000E+00	-6.7762636E-18	-2.7105054E-14	-2.7105054E-14	
S(2,4,K)	-8.8496523E-10	-7.5073929E-11	-6.7762636E-18	3.5355329E-04	-8.5854197E-08	-8.5854197E-08	
S(2,5,K)	3.5355317E+00	-2.2711833E-07	-2.7105054E-14	-8.5854197E-08	-7.0710708E+02	-7.0710708E+02	
S(3,1,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(3,2,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(3,3,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(3,4,K)	3.5355339E-04	1.4644661E-05	0.000000E+00	0.000000E+00	0.000000E+00	3.9145690E-03	
S(3,5,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(4,1,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(4,2,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(4,3,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(4,4,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(4,5,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(5,1,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(5,2,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(5,3,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(5,4,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	
S(5,5,K)	-1.2621774E-23	-1.2621774E-24	-1.2621774E-23	-1.2621774E-24	-3.5527137E-07	-3.5527137E-07	

50 .78540

END OF SOTRMI

CONTROL= -1.000

...END OF COMPUTATIONS...

TABLE V - contd.

EXAMPLE 2

CONTROL= 1.000
 NUMBER OF PARAMETERS READ = 8

C= 1.0000000
 DELSIN= 1.57079633 (CM)
 SOMAX= 30.0000000 (M)
 SOL= 0.0000000 (M)
 OPTICN= 0.0000000
 NUM= 3.0000000
 MAX= 50.0000000
 NPRINT= 50.0000000

CONTROL= 3.200
 NUMBER OF PARAMETERS READ = 12

Z(1)= 510.7200000(MEV) Z(2)= 90.0000000(DEG) Z(3)= 2.0000000(M) Z(4)= 1.0000000(M)
 Z(5)= 1.0000000(CM) Z(6)= 0.0000000(MR) Z(7)= 0.0000000(CM) Z(8)= 0.0000000(MR)
 Z(9)= 0.0000000(CM) Z(10)= 0.0000000(MR) Z(11)= 1.0000000(CM) Z(12)= 5.0000000(MR)

CONTROL= 3.100
 NUMBER OF PARAMETERS READ = 2

P(1)= -.0100000 DELTA P/PO
 P(2)= .0100000 DELTA P/PO

CONTROL= 99.000

START OF SOTRMI

1 THE FOLLOWING HEADINGS ARE TO BE USED FOR COL. 1-7

K= 0	PX(MEV/C)	PY(MEV/C)	X(CM)	Y(CM)	X(M)	Y(M)	THETA(DEG)	DP/PO	DPX/PO	DPY/PO
K=(1,NUM-1)	X(J)	Y(J)	X(MR)	Y(MR)	X(M)	Y(M)	DP/PO	DPX/PO	DPY/PO	DPY/PO
U(I,J) / J=	1	2	3	4	5	6	7	8	9	10
S(I,J,K) / K=	1	2	3	4	5	6	7	8	9	10
1	1	2	3	4	5	6	7	8	9	10
0	5.1072000E+02	-8.7594073E-13	2.0000000E+00	1.0000000E+00	9.0000000E+01	1.0000000E+00	1.0000000E-02	0.0000000E+00	0.0000000E+00	0.0000000E+00
1	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	1.0000000E-02	0.0000000E+00	0.0000000E+00	0.0000000E+00
2	0.0000000E+00	0.0000000E+00	1.0000000E+00	1.0000000E+00	5.0000000E+00	5.0000000E+00	1.0000000E-02	0.0000000E+00	0.0000000E+00	5.0499790E-03
50	0.36113357E+02	3.6113358E+02	2.7071065E+00	1.2928932E+00	4.5000000E+01	1.0000000E+00	1.0000000E-02	0.0000000E+00	0.0000000E+00	0.0000000E+00
1	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	1.0000000E-02	0.0000000E+00	0.0000000E+00	0.0000000E+00
2	2.9005438E-C1	6.9923628E+00	1.3930933E+00	5.0000000E+00	1.0000000E+00	1.0000000E+00	1.0000000E-02	7.0621466E-C3	5.0499790E-03	5.0499790E-03

END OF SOTRMI

CONTROL= -1.000

TABLE V - cont'd.

...END OF COMPUTATIONS...

CONTROL= 1.000
 NUMBER OF PARAMETERS READ = 8
 Q= 1.00000000
 DELSIN= 1.57079633 (CM)
 SOMAX= 30.0000000 (M)
 SOL= C.0000000 (M)
 OPTION= 3.0000000
 NUM= 1.00000000
 MAX= 50.0000000
 NPRINT= -50.0000000

CONTROL= 3.200
 NUMBER OF PARAMETERS READ = 4

Z(1)= 510.720000(MEV) Z(2)= 90.0000000(DEG) Z(3)= 2.0000000(M) Z(4)= 1.0000000(M)

CONTROL= 99.000

START OF SOTRMI

1 THE FOLLOWING HEADINGS ARE TO BE USED FOR CCL. 1-7

I	S0(METER)	K	PX(MEV/C)			PY(MEV/C)			X(M)			Y(M)			THETA(DEG)			FUNC CALLS		
			X(CH)	Z	K=	X(CH)	Z	K=	X(CH)	Z	K=	Y(CH)	Z	K=	DP/PO	DP/PO	DP/PO	DPX/PO	DPY/PO	
0	0.00000	0	5.1072000E+02	-8.7594838E-13	2.0000000E+00	1.0000000E+00	9.0000000E+01	1												
		U(1,J)	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(2,J)	0.0000000E+00	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(3,J)	0.0000000E+00	0.0000000E+00	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(4,J)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		U(5,J)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	1.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,1,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,2,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,3,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,4,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(1,5,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,1,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,2,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,3,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	
		S(2,4,K)	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	0.0000000E+00	

TABLE V - contd.

EXAMPLE 3 - contd.

	ZTRAN	ZSCLN	ZTRAN	ZSCLN	ZTRAN	ZSCLN	ZTRAN	ZSCLN
S(5,2,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-1.2621774E-24
S(5,3,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-1.2621774E-23
S(5,4,K)	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-1.2621774E-24
S(5,5,K)	-1.2621774E-23	-1.2621774E-24	-1.2621774E-24	-1.2621774E-23	-1.2621774E-23	-1.2621774E-23	-1.2621774E-24	-3.5527137E-C7
	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
7.0708178E-03	7.0708178E-03	7.0711714E-03	7.0711714E-03	7.0711714E-03	7.0711714E-03	7.0711714E-03	7.0711714E-03	7.0711714E-03
-7.0710678E-02	-7.0710678E-02	7.0707142E-02	7.0707142E-02	7.0707142E-02	7.0707142E-02	7.0707142E-02	7.0710678E-02	7.0710678E-02
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
-1.4644658E-07	-1.4644658E-07	2.9286822E-03	2.9286822E-03	2.9286822E-03	2.9286822E-03	2.9286822E-03	-7.0713178E-03	-7.0713178E-03
-3.5355329E-06	-3.5355329E-06	7.0703608E-02	7.0703608E-02	7.0703608E-02	7.0703608E-02	7.0703608E-02	7.0710678E-02	7.0710678E-02
7.8539817E-03	7.8539817E-03	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
1.000000E-01	1.000000E-01	1.000000E-04	1.000000E-04	1.000000E-04	1.000000E-04	1.000000E-04	0.000000E+00	0.000000E+00
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
-7.0709643E-03	-7.0709643E-03	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-1.4644658E-07	-1.4644658E-07
-7.0714214E-02	-7.0714214E-02	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-3.5355329E-06	-3.5355329E-06
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-7.8539817E-03	-7.8539817E-03
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-1.000000E-01	-1.000000E-01
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
-2.9291822E-03	-2.9291822E-03	1.4142489E-02	1.4142489E-02	1.4142489E-02	1.4142489E-02	1.4142489E-02	7.0708178E-03	7.0708178E-03
-7.0717750E-02	-7.0717750E-02	-3.5358089E-06	-3.5358089E-06	-3.5358089E-06	-3.5358089E-06	-3.5358089E-06	-7.0710678E-02	-7.0710678E-02
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	1.000000E-02	1.000000E-02
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
-1.000000E-04	-1.000000E-04	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
7.0706714E-03	7.0706714E-03	0.000000E-02	0.000000E-02	0.000000E-02	0.000000E-02	0.000000E-02	7.0711714E-03	7.0711714E-03
-7.0714214E-02	-7.0714214E-02	7.0294368E-10	7.0294368E-10	7.0294368E-10	7.0294368E-10	7.0294368E-10	7.0707142E-02	7.0707142E-02
7.8546888E-03	7.8546888E-03	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	1.000000E-02	1.000000E-02
1.000000E-01	1.000000E-01	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
7.0710249E-03	7.0710249E-03	1.000000E-02	1.000000E-02	1.000000E-02	1.000000E-02	1.000000E-02	-1.4644658E-07	-1.4644658E-07
7.0703607E-02	7.0703607E-02	1.4141075E-01	1.4141075E-01	1.4141075E-01	1.4141075E-01	1.4141075E-01	-3.5355329E-06	-3.5355329E-06
7.8542745E-03	7.8542745E-03	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	1.7853982E-02	1.7853982E-02
1.000000E-01	1.000000E-01	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	1.000000E-01	1.000000E-01
0.000000E+00	0.000000E+00	1.000000E-04	1.000000E-04	1.000000E-04	1.000000E-04	1.000000E-04	0.000000E+00	0.000000E+00
2.9286822E-03	2.9286822E-03	2.9285358E-03	2.9285358E-03	2.9285358E-03	2.9285358E-03	2.9285358E-03	-1.4141782E-02	-1.4141782E-02
7.0703608E-02	7.0703608E-02	7.0703607E-02	7.0703607E-02	7.0703607E-02	7.0703607E-02	7.0703607E-02	-3.5355329E-06	-3.5355329E-06
1.000000E-02	1.000000E-02	7.8540599E-03	7.8540599E-03	7.8540599E-03	7.8540599E-03	7.8540599E-03	0.000000E+00	0.000000E+00
0.000000E+00	0.000000E+00	1.000000E-01	1.000000E-01	1.000000E-01	1.000000E-01	1.000000E-01	0.000000E+00	0.000000E+00
1.000000E-04	1.000000E-04	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
-7.0713178E-03	-7.0713178E-03	7.0714642E-03	7.0714642E-03	7.0714642E-03	7.0714642E-03	7.0714642E-03	-1.000000E-02	-1.000000E-02
7.0710678E-02	7.0710678E-02	7.0707143E-02	7.0707143E-02	7.0707143E-02	7.0707143E-02	7.0707143E-02	-7.0852371E-10	-7.0852371E-10
-1.000000E-02	-1.000000E-02	-7.8532745E-03	-7.8532745E-03	-7.8532745E-03	-7.8532745E-03	-7.8532745E-03	0.000000E+00	0.000000E+00
0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00

TABLE V - contd.

EXAMPLE 3 - contd.

```

0      0.0000000E+00  0.0000000E+00  0.0000000E+00  0.0000000E+00  -1.0000000E-04  -1.0000000E-04
-7.0709643E-03  -7.0709643E-03  -7.0711107E-03  -7.0711107E-03  -9.9999394E-03  -9.9999394E-03
-7.0714214E-02  -7.0714214E-02  -7.0717749E-02  -7.0717749E-02  -1.4143196E-01  -1.4143196E-01
-1.0000000E-02  -1.0000000E-02  -7.8536888E-03  -7.8536888E-03  0.0000000E+00  0.0000000E+00
0.0000000E+00  0.0000000E+00  -1.0000000E-01  -1.0000000E-01  0.0000000E+00  0.0000000E+00
0.0000000E+00  0.0000000E+00  0.0000000E+00  0.0000000E+00  -1.0000000E-04  -1.0000000E-04
0      -1.4644658E-07  -1.4644658E-07  -2.9291822E-03  -2.9291822E-03  -2.9293287E-03  -2.9293287E-03
-3.535329E-06  -3.535329E-06  -7.0717750E-02  -7.0717750E-02  -7.0721286E-02  -7.0721286E-02
-1.7853982E-02  -1.7853982E-02  -1.0000000E-02  -1.0000000E-02  -7.8539034E-03  -7.8539034E-03
-1.0000000E-01  -1.0000000E-01  0.0000000E+00  0.0000000E+00  -1.0000000E-01  -1.0000000E-01
0.0000000E+00  0.0000000E+00  -1.0000000E-04  -1.0000000E-04  -1.0000000E-04  -1.0000000E-04
END OF SOTRMI

CONTROL= 1.000
NUMBER OF PARAMETERS READ = 2
Q=
DEL SIN= 1.6000000
SOMAX= 1.57079633 (CM)
SOL= .78539816 (M)
OPTICN= 0.6000000
NUM= 4.0000000
MAX= 50.0000000
NPRINT= -50.0000000

CONTROL= 3.100
NUMBER OF PARAMETERS READ = 3
PI 1)= .0100000 DELTA P/PO
PI 2)= .0500000 DELTA P/PO
PI 3)= .1000000 DELTA P/PO

CONTROL= 3.200
NUMBER OF PARAMETERS READ = 16
Z( 1)= 510.7200000(MEY) Z( 2)= 90.0000000(DEG) Z( 3)= 2.0000000(M) Z( 4)= 1.0000000(M)
Z( 5)= .5000000(CM) Z( 6)= 5.0000000(MR) Z( 7)= .5000000(CM) Z( 8)= 5.0000000(MR)
Z( 9)= 1.0000000(CM) Z( 10)= 10.0000000(MR) Z( 11)= 1.0000000(CM) Z( 12)= 10.0000000(MR)
Z( 13)= 5.0000000(CM) Z( 14)= 20.0000000(MR) Z( 15)= 5.0000000(CM) Z( 16)= 20.0000000(MR)

CONTROL= 99.000
START OF SOTRMI
I THE FOLLOWING HEADINGS ARE TO BE USED FOR CCL. 1-7
K= 0
PX(MEY/C) PY(MEY/C) X(M) Y(M) THETA(DEG) FLNC CALLS

```

TABLE V - contd.

EXAMPLE 3 - contd.

K=(I,NUM-I) U(I,J) / J= S(I,J,K) / K=	X(ICM)	X (MR)	Y(ICM)	Y (MR)	DP/PO	DPX/PO	DPY/PO
1	1	2	3	4	5		
2	1	2	3	4	5		
3	1	2	3	4	5	6	7
0	5.1072000E+02	-8.7594838E-13	2.0000000E+00	1.0000000E+00	9.0000000E+01		
1	5.0000000E-01	5.0000000E+00	5.0000000E-01	5.0000000E+00	1.0000000E-02	5.0499158E-C3	5.0499790E-C3
01	1.0000000E+00	1.0000000E+00	1.0000000E-02	1.0000000E-02	1.0000000E-02		
3	5.0000000E+00	2.0000000E+01	5.0000000E+00	2.0000000E+01	1.0000000E-01	2.1994134E-02	2.1998533E-02

ZTRAN	ZSCLN	ZTRAN	ZSCLN	ZTRAN	ZSCLN
5.0000000E-01	5.0000000E-01	1.0000000E+00	1.0000000E+00	5.0000000E+00	5.0000000E+00
5.0000000E+00	5.0000000E+00	1.0000000E+01	1.0000000E+01	2.0000000E+01	2.0000000E+01
5.0000000E-01	5.0000000E-01	1.0000000E+00	1.0000000E+00	5.0000000E+00	5.0000000E+00
5.0000000E+00	5.0000000E+00	1.0000000E+01	1.0000000E+01	2.0000000E+01	2.0000000E+01
1.0000000E-02	1.0000000E-02	5.0000000E-02	5.0000000E-02	1.0000000E-01	1.0000000E-01
0	1.57080	0	3.6113357E+02	3.6113358E+02	2.7071068E+00
1	1.0015650E+00	7.0184714E+00	8.9560510E-01	5.0000000E+00	1.0000000E-02
2	2.8556731E+00	3.3945505E+01	1.7993120E+00	1.0000000E+01	5.0000000E-02
3	7.9123469E+00	4.6022222E+01	6.6705157E+00	2.0000000E+01	1.0000000E-01
					1.0000000E+01
					4.5000000E+01
					1.0000000E-02
					7.0885093E-C3
					3.5634154E-C2
					5.0596455E-02
					2.1998533E-02

ZTRAN	ZSCLN	ZTRAN	ZSCLN	ZTRAN	ZSCLN
1.0015533E+00	1.0015650E+00	2.8536060E+00	2.8556731E+00	7.9058851E+00	7.9123469E+00
7.0180348E+00	7.0184714E+00	3.3870414E+01	3.3945505E+01	4.5667909E+01	4.6022222E+01
8.9559054E-01	8.9560510E-01	1.7993127E+00	1.7995120E+00	6.6688810E+00	6.6705157E+00
5.0000000E+00	5.0000000E+00	1.0000000E+01	1.0000000E+01	2.0000000E+01	2.0000000E+01
1.0000000E-02	1.0000000E-02	4.9999999E-02	5.0000000E-02	9.9999996E-02	1.0000000E-01
0					

END OF SOTRMI

CONTROL= -1.000

...END OF COMPUTATIONS...

TABLE VI

PROGRAM LISTING

```

PROGRAM SOTRM(INPUT=300,OUTPUT=1000,TAPE1=1000,TAPE60=INPUT,TAPE61 SOTRM.2
              = OUTPUT) SOTRM.3
* COMMENT THIS IS A CALLING PROGRAM FOR SOTRM1. SEE UCRL 19823. SOTRM.4
* BEGIN SOTRM.5
      REAL S SOTRM.6
      INTEGER K,L,I,MAXRAY,NUM,N4,NUM1 SOTRM.7
      REAL P(40),Z(164),PARAM(10),PR(4),LOW LIM,UP LIM,DUM,A, SOTRM.8
      A1,A2,M1(5,5),M2(5,5,5),U,V SOTRM.9
      INTEGER H1( 9),H2( 9),PI(5) SOTRM.10
      INTEGER TEXT(13) SOTRM.11
      LOGICAL START SOTRM.12
      COMMON /BOUND/ LOW LIM(3),UP LIM(3) SOTRM.13
      /YAFS/ DUM(10),A(5),U(5,5),V(5,5,5) SOTRM.14
      /TAME/ A1(10,10), A2(10,10) SOTRM.15
      /PARAM/ CONST(8) SOTRM.16
      DATA START/.TRUE./,MAXRAY/31/, (H1(I),I=1,8)/3H Q=, SOTRM.17
      8H DELSIN=,7H SOMAX=,5H SO1=,8H OPTICN=,5H NUM=, SOTRM.18
      5H MAX=,8H NPRINT=/, (H2(I),I=1,8)/1H ,5H (CM), SOTRM.19
      2*4H (M),4*1H / SOTRM.20
      PRINT 2998 SOTRM.21
1      READ 4001, S $ PRINT 12 ,S $ IF(S.EQ.-1.) 2,4 SOTRM.22
2      PRINT 5000$ STOP SOTRM.23
4      IF(S.EQ.1.) 100,199 SOTRM.24
*      BEGIN SOTRM.25
100      READ 4002, K, (I,PARAM(I),L=1,K) SOTRM.26
          IF(PARAM(8).LT.0.0) REWIND 1 SOTRM.27
          IF(START) 102,108 SOTRM.28
          BEGIN SOTRM.29
102      IF(K.NE.8) 104,106 SOTRM.30
          BEGIN SOTRM.31
104      PRINT 9000,K $ STOP SOTRM.32
9000      FORMAT (///*1 K=*I3* YOU HAVE NOT SET*, SOTRM.33
          * ALL THE INITIAL PARAMETERS*///) SOTRM.34
106      CONTINUE SOTRM.35
          END SOTRM.36
          START=.FALSE. SOTRM.37
108      CONTINUE SOTRM.38
*      END SOTRM.39
          NUM=PARAM(6) SOTRM.40
          NUM1=NUM-1 SOTRM.41
          N4=4*NUM SOTRM.42
          PRINT 2999,K SOTRM.43
          PRINT 3000 , ((H1(I),PARAM(I),H2(I)),I=1,8) SOTRM.44
          IF(PARAM(6).GT.MAXRAY) 110,112 SOTRM.45
          BEGIN SOTRM.46
110      PRINT 9001,PARAM(7)$ STOP SOTRM.47
9001      FORMAT(///* TOO MANY RAYS,NUM=*F10.6///) SOTRM.48
112      CONTINUE SOTRM.49
          END SOTRM.50
114      DO 114 I=1,4,1 SOTRM.51
          PR(I)= PARAM(I) SOTRM.52
          DO 116 I= 1,4,1 SOTRM.53
          PI(I)= PARAM(I+4)+SIGN(0.0005,PARAM(I+4)) SOTRM.54
116      GO TO 1 SOTRM.55

```

TABLE VI - contd.

199	CONTINUE	SOTRM.56
*	END ELSE	SOTRM.57
	IF(S.EQ.2.) 200,299	SOTRM.58
*	BEGIN	SOTRM.59
200	READ 4001, (LOW LIM(I),UP LIM(I),I=1,3)	SOTRM.60
	PRINT 3004, (I,LOW LIM(I), I,UP LIM(I),I=1,3)	SOTRM.61
	GOTO 1	SOTRM.62
299	CONTINUE	SOTRM.63
*	END ELSE	SOTRM.64
	IF(S.GE.3..AND.S.LT.4.) 300, 399	SOTRM.65
300	IF(S.EQ.3.0.OR.S.EQ.3.1) 302,304	SOTRM.66
*	BEGIN	SOTRM.67
302	READ 4002,K,((I,P(I),I=1,K,1)	SOTRM.68
	PRINT 2999,K	SOTRM.69
	PRINT 3006,((I,P(I),I=1,NUM1,1)	SOTRM.70
*	END	SOTRM.71
304	IF(S.EQ.3.0.OR.S.EQ.3.2) 306,308	SOTRM.72
*	BEGIN	SOTRM.73
306	READ 4002,L,((I,Z(I),I=1,L,1)	SOTRM.74
	PRINT 2999,L	SOTRM.75
	PRINT 3008, (I,Z(I),I=1,N4,1)	SOTRM.76
*	END	SOTRM.77
308	GOTO1	SOTRM.78
399	CONTINUE	SOTRM.79
*	END ELSE	SOTRM.80
	IF(S.EQ.4.) 400,499	SOTRM.81
*	BEGIN COMMENT INPUT A1 AND A2,F.SELPH FIELD, 5 ITEMS/CARD	SOTRM.82
400	READ 4008,(((A1(I,J),J=1,10),I=1,10),	SOTRM.83
	((A2(I,J),J=1,10),I=1,10)	SOTRM.84
	PRINT 3010,(((A1(I,J),J=1,10),I=1,10)	SOTRM.85
	PRINT 3011,(((A2(I,J),J=1,10),I=1,10)	SOTRM.86
	GOTO 1	SOTRM.87
499	CONTINUE	SOTRM.88
*	END ELSE	SOTRM.89
	IF(S.GE.5..AND.S.LT.6.) 500,599	SOTRM.90
*	BEGIN COMMENT CHANGE A1 OR A2 OR BOTH	SOTRM.91
500	IF(S.EQ.5..OR.S.EQ.5.1)	SOTRM.92
	READ 4010, K,(((I,J,A1(I,J)),L=1,K)\$ PRINT 2999,K	SOTRM.93
	IF(S.EQ.5..OR.S.EQ.5.2)	SOTRM.94
	READ 4010, K,(((I,J,A2(I,J)),L=1,K)\$ PRINT 2999,K	SOTRM.95
	PRINT 3010,(((A1(I,J),J=1,10),I=1,10)	SOTRM.96
	PRINT 3011,(((A2(I,J),J=1,10),I=1,10)	SOTRM.97
	GOTO 1	SOTRM.98
599	CONTINUE	SOTRM.99
*	END ELSE	SOTRM.100
	IF(S.EQ.6.) 600,699	SOTRM.101
*	BEGIN COMMENT INPUT INCREMENTS	SOTRM.102
600	READ 4002, K,(((I,A(I)),L=1,K)\$ PRINT 2999,K	SOTRM.103
	PRINT 3012, ((L,A(L)),L=1,5)	SOTRM.104
	GOTO 1	SOTRM.105
699	CONTINUE	SOTRM.106
*	END ELSE	SOTRM.107
	IF(S.EQ.7) 800,899	SOTRM.108
*	BEGIN COMMENT INPUT TEXT THAT IDENTIFIES THE TABLES AND	SOTRM.109

TABLE VI - contd.

```

LOGICAL  BOOL1,BOOL2,LAST,TEXT
COMMON  /CASES/ NUM,L,K
.        /CHARGE/ Q /MDM/ PO,P(40)
.        /FIELD/ BB02,BB1(40),BB2(40),BB3(40)
.        /SOLN/ Z(164) /DER/F(164)
.        /PARAM/ CONST( 8)
.        /LIMIT/ SO,SOMAX,MAX
.        /YAFS/ YP( 5),YM( 5),A( 5),U(5,5),S(5,5,5)
.        /WORK/ COUNT,STEP
COMMON  /INIT/ ZSAVE(150)
DATA    (CONST(I),I=1,7) /1.602072E-19,.5343922E-21,1.,1.E-2,
.        1.E-3,1.74532925199433E-2,1.E-4/,
.        (A(I),I=1,5,1)/ .01,.1,.01,.1,.0001/
DOUBLE PRECISION T,DELSO
EXTERNAL FUNC
DIMENSION EPS(6)
ASSIGN 50 TO LOOP$ ASSIGN 10000 TO FIN
ASSIGN 200 TO NXTSTP
Q=PR(1)*CONST(1)$ DELSO= PR(2)*CONST(4)$ SO= SO1*CONST(3)
SOMAX= PR(3)*CONST(3)$ COUNT=0
COMMENT SET THE INITIAL CONDITIONS OF THE REFERENCE RAY
*
*
PO=Z1(1)*CONST(2)
Z(1)= SIN(Z1(2)*CONST(6))$ Z(2)= COS(Z1(2)*CONST(6))
Z(3)= Z1(3)*CONST(3)$ Z(4)= Z1(4)*CONST(3)
*
*
NPRINT= IABS(PI(4))
NUM=PI(2) $ NUM1=NUM-1 $ N=4*NUM $ MAX=PI(3)
4 IF(PI(1).NE.0) 6,10
*
*
BEGIN COMMENT SET THE INITIAL CONDITIONS OF THE NEAR BY RAYS
FOR GENERATION OF U AND S
6 IF(PI(1).EQ.1.OR.PI(1).EQ.-1) NUM=11
IF(PI(1).EQ.2) NUM= 21
IF(PI(1).EQ.3) NUM= 31
NUM1=NUM-1$ N=4*NUM$ MAX=PI(3)
CALL SETZ(Z1,P1)
*
*
END
10 IF(NUM1.GT.0) CALL ZINIT(P1,Z1)
CALL SAVEZP(ZSAVE,Z1,P1,PI)
*
*
COMMENT INTEGRATION AND PRINT LOOP
16 STEP= 0$ PRCNT= 0$ LAST= .FALSE.$ TEXT= .TRUE.
IF(NPRINT.NE.0) PRINT 4000
CALL INTO(4*NUM,SO,FUNC,Z,F,F,DELSO)
*
*
LOOP..
50 DO 500 I1= 1,MAX
*
*
BEGIN
IF(SO.GE.SOMAX) 46,48
*
*
BEGIN
46 MAX= I1-1$ GOTO 500
*
*
END
48 IF(NPRINT.NE.0.OR.LAST) 52,200
*
*
BEGIN
52 IF(.NOT.LAST.AND..NOT.TEXT) GOTO NXTSTP
SOOUT= SO/CONST(3)$ K=0.
SOTRMI.11
SOTRMI.12
SOTRMI.13
SOTRMI.14
SOTRMI.15
SOTRMI.16
SOTRMI.17
SOTRMI.18
SOTRMI.19
SOTRMI.20
SOTRMI.21
SOTRMI.22
SOTRMI.23
SOTRMI.24
SOTRMI.25
SOTRMI.26
SOTRMI.27
SOTRMI.28
SOTRMI.29
SOTRMI.30
SOTRMI.31
SOTRMI.32
SOTRMI.33
SOTRMI.34
SOTRMI.35
SOTRMI.36
SOTRMI.37
SOTRMI.38
SOTRMI.39
SOTRMI.40
SOTRMI.41
SOTRMI.42
SOTRMI.43
SOTRMI.44
SOTRMI.45
SOTRMI.46
SOTRMI.47
SOTRMI.48
SOTRMI.49
SOTRMI.50
SOTRMI.51
SOTRMI.52
SOTRMI.53
SOTRMI.54
SOTRMI.55
SOTRMI.56
SOTRMI.57
SOTRMI.58
SOTRMI.59
SOTRMI.60
SOTRMI.61
SOTRMI.62
SOTRMI.63
SOTRMI.64

```

TABLE VI - contd.

```

*          IF(TEXT) 54, 60
*          BEGIN COMMENT OUTPUT REFERENCE RAY
54          IF(ABS(Z(1)).GT.1.) 55,56
55          ZOUT(5)= Z(1)+ 1000. $ GOTO 58
56          ZOUT(5)= ASIN(Z(1))/CONST(6)
58          CONTINUE
          ZOUT(1)= (Z(1)/CONST(2))* P0
          ZOUT(2)=(Z(2)/CONST(2))*P0
          ZOUT(3)= Z(3)/CONST(3)
          ZOUT(4)= Z(4)/CONST(3)
          PRINT 4002, STEP,S0OUT,K,(ZOUT(L),L=1,5),
          COUNT
*          END
60          IF(LAST) 62,64
*          BEGIN COMMENT SET THE FINAL CONDITIONS OF THE
*          REFERENCE RAY
62          Z1(2)=ATAN2(Z(1),Z(2))/CONST(6)
          Z1(3)=Z(3)/CONST(3)
          Z1(4)=Z(4)/CONST(3)
          S01=S0OUT
*          END
64          IF(PI(1).EQ.0.A.NUM1.NE.0) 66,74
*          BEGIN
66          DO 72 K=1,NUM1
*          BEGIN
          L=4*K$ CALL ZFINAL(ZOUT,0)
          ZOUT(6)= Z(L+2)$ ZOUT(7)= Z(L+4)
          ZOUT(5)= P(K)-1.
          IF(TEXT) PRINT 4004,K,(ZOUT(I),I=1,7)
          IF(LAST) 68,72
*          COMMENT SET FINAL CONDITIONS OF THE NEARBY
*          RAYS
68          DO 70 I= 1,4
70          Z1(L+1)= ZOUT(I)
72          CONTINUE
*          END
73          IF(PI(4).LT.0.AND.TEXT) CALL APTRAN(0)
          IF(LAST) GO TO FIN
          GO TO NXISTP
*          END
74          IF(ABS(PI(1)).GT.0) 76,100
*          BEGIN
76          DO 86 KK=1,5
*          BEGIN
          L=4*KK
          K=KK
          CALL ZFINAL(YP,0)
          K=KK+5
          CALL ZFINAL(YM,20)
          CALL YPYM5(KK,5,5)
77          DO 78 I=1,5
78          U(I,KK)=(YP(I)-YM(I))/(2.0*A(KK))
          IF(PI(1).NE.1) 80,84
          DO 82 I=1,5

```

```

SOTRM1.65
SOTRM1.66
SOTRM1.67
SOTRM1.68
SOTRM1.69
SOTRM1.70
SOTRM1.71
SOTRM1.72
SOTRM1.73
SOTRM1.74
SOTRM1.75
SOTRM1.76
SOTRM1.77
SOTRM1.78
SOTRM1.79
SOTRM1.80
SOTRM1.81
SOTRM1.82
SOTRM1.83
SOTRM1.84
SOTRM1.85
SOTRM1.86
SOTRM1.87
SOTRM1.88
SOTRM1.89
SOTRM1.90
SOTRM1.91
SOTRM1.92
SOTRM1.93
SOTRM1.94
SOTRM1.95
SOTRM1.96
SOTRM1.97
SOTRM1.98
SOTRM1.99
SOTRM1.100
SOTRM1.101
SOTRM1.102
SOTRM1.103
SOTRM1.104
SOTRM1.105
SOTRM1.106
SOTRM1.107
SOTRM1.108
SOTRM1.109
SOTRM1.110
SOTRM1.111
SOTRM1.112
SOTRM1.113
SOTRM1.114
SOTRM1.115
SOTRM1.116
SOTRM1.117
SOTRM1.118

```

TABLE VI - contd.

```

      S(I, KK, KK) = (YP(I) + YM(I)) / (2.0 * A(KK)) SOTRM1.119
      **2) SOTRM1.120
      CONTINUE SOTRM1.121
      CONTINUE SOTRM1.122
      CONTINUE SOTRM1.123
*
      END SOTRM1.124
      IF(TEXT.AND.PI(1).NE.0) 88,100 SOTRM1.125
*
      BEGIN SOTRM1.126
      88 PRINT 4006, ((I, (U(I, K), K=1, 5)), I=1, 5) SOTRM1.127
      PRINT 4010 SOTRM1.128
      IF(PI(1).EQ.-1) SOTRM1.129
      PRINT 4007, SOTRM1.130
      ((I, (S(I, K, K), K=1, 5)), I=1, 5) SOTRM1.131
      IF(PI(4).LT.0.A.PI(1).LE.1) SOTRM1.132
      CALL APTRAN(1, PI(1)) SOTRM1.133
*
      END SOTRM1.134
*
      END SOTRM1.135
      IF(PI(1).GT.1) 102,104 SOTRM1.136
*
      BEGIN SOTRM1.137
      102 CALL SF(4, 44, 10, 1) $ CALL SF(3, 60, 14, 2) SOTRM1.138
      CALL SF(2, 72, 17, 3) $ CALL SF(1, 80, 19, 4) SOTRM1.139
      IF(TEXT) 103, 104 SOTRM1.140
*
      BEGIN SOTRM1.141
      103 PRINT 4008, SOTRM1.142
      ((I, J, (S(I, J, K), K=1, 5)), J=1, 5), I=1, 5 SOTRM1.143
      ) SOTRM1.144
      IF(PI(4).LT.0) CALL APTRAN(1, PI(1)) SOTRM1.145
*
      END SOTRM1.146
*
      END SOTRM1.147
      IF(LAST) GOTO 509 SOTRM1.148
*
      END SOTRM1.149
      NXTSTP.. SOTRM1.150
      CALL INT(SO, FUNC, Z, F, T, BOOL1) $ TEXT = .FALSE. SOTRM1.151
      IF(BOOL1) 202, 204 SOTRM1.152
*
      BEGIN SOTRM1.153
      202 STEP = STEP + 1 SOTRM1.154
      PRTCNT = PRTCNT + 1 $ IF(PRTCNT.EQ.NPRINT) 203, 204 SOTRM1.155
*
      BEGIN SOTRM1.156
      203 TEXT = .TRUE. $ PRTCNT = 0 SOTRM1.157
*
      END SOTRM1.158
*
      END SOTRM1.159
      CONTINUE SOTRM1.160
      CONTINUE SOTRM1.161
*
      END OF LOOP SOTRM1.162
      IF(.NOT.LAST) 501, 508 SOTRM1.163
*
      BEGIN SOTRM1.164
      501 IF(NPRINT.EQ.0) 502, 504 SOTRM1.165
      502 TEXT = .FALSE. $ GOTO 506 SOTRM1.166
      504 TEXT = .TRUE. SOTRM1.167
      506 LAST = .TRUE. $ MAX = 2 $ SOMAX = SOMAX + .05 SOTRM1.168
      GOTO LOOP SOTRM1.169
      CONTINUE SOTRM1.170
*
      END SOTRM1.171
      IF(PI(1).NE.0) 510, 512 SOTRM1.172

```

TABLE VI - contd.

```

*          BEGIN
510          CO 511 I=1,5,1
              CO 511 J=1,5,1
              V(I,J)=U(I,J)
511          IF(PI(1).EQ.-1) W(I,J,J)= S(I,J,J)
512          CONTINUE
*          END
          IF(PI(1).GT.1) 514,518
514          DO 516 I=1,5,1
              DO 516 J=1,5,1
              DO 516 K=1,5,1
516          W(I,J,K)= S(I,J,K)
518          CONTINUE
*          FIN..
10000 RETURN
*
4000 FORMAT(*1 THE FOLLOWING HEADINGS ARE TO BE USED FOR COL. 1-7*//
          . 19X,*K= 0*,11X,*PX(MEV/C)*,4X,*PY(MEV/C)*,9X,*X(M)*,9X,
          . *Y(M)*,5X,*THETA(DEG)*,4X,*FUNC CALLS*/19X,*K=(1,NUM-1)*,
          . 6X,*X(CM)*,10X,*X (MR)*,8X,*Y(CM)*,9X,*Y (MR)*,5X,*DP/PC*,
          . 12X,*DPX/PO*,8X,*DPY/PO*/20X,*U(I,J)*,3X,*/ J=*,4X,*1*,13X,
          . *2*,13X,*3*,13X,*4*,13X,*5*/20X,*S(I,J,K) / K=*,4X,*1*,13X,
          . *2*,13X,*3*,13X,*4*,13X,*5*///5X,*I*,3X,*SO(METER)*
          . ,2X,*K*,14X,
          . *1*,13X,*2*,13X,*3*,13X,*4*,13X,*5*,13X,*6*,13X,*7*//)
4002 FORMAT(1X,I5,1X,F10.5,2X,I3, 5E15.7,I14)
4004 FORMAT(19X,I3,7E15.7)
4006 FORMAT(20X,*U(*I1*,J)*4X,5E15.7)
4007 FORMAT(20X,*S(*I1*,K,K)*, 2X,5E15.7)
4008 FORMAT(20X,*S(*I1*,*I1*,K)*2X,5E15.7)
4010 FORMAT(/)
          END

          SUBROUTINE ZINIT(P1,Z1)
          REAL P1(1),Z1(1)
          COMMENT ZINIT ESTABLISHES THE INITIAL VALUES
          * OF THE NEAR BY RAYS. THESE ARE ORIGINALLY FURNISHED
          * AS Z1(L+1) CM, Z1(L+2) MR, Z1(L+3) CM, Z1(L+4) MR.
          * THESE ARE CHANGED TO Z1(L+1) M, Z1(L+2) DELTA P(K)/PO,
          * Z1(L+3) M, Z1(L+4) DELTA P(K)/PC. THE INPUT MOMENTUM
          * P(K) IN UNITS OF DELTA P(K)/PO IS CHANGED TO 1+DELTA P(K)
          * /PO
          *
          * BEGIN
          INTEGER K,L,N,NUM1,NUM
          REAL P,PO,CONST
          COMMON /CASES/NUM,L,K
          . /MOM/ PO,P(40 )
          . /PARAM/ CONST(8)
          . /SOLN/ Z(164)
          NUM1= NUM-1$ N= 4*NUM
          DO 10 K=1,NUM1,1
          * BEGIN
          P(K)= P1(K)+1.0

```

```

SOTRM1.173
SOTRM1.174
SOTRM1.175
SOTRM1.176
SOTRM1.177
SOTRM1.178
SOTRM1.179
SOTRM1.180
SOTRM1.181
SOTRM1.182
SOTRM1.183
SOTRM1.184
SOTRM1.185
SOTRM1.186
SOTRM1.187
SOTRM1.188
SOTRM1.189
SOTRM1.190
SOTRM1.191
SOTRM1.192
SOTRM1.193
SOTRM1.194
SOTRM1.195
SOTRM1.196
SOTRM1.197
SOTRM1.198
SOTRM1.199
SOTRM1.200
SOTRM1.201
SOTRM1.202
SOTRM1.203
SOTRM1.204
SOTRM1.205
SOTRM1.206
ZINIT.2
ZINIT.3
ZINIT.4
ZINIT.5
ZINIT.6
ZINIT.7
ZINIT.8
ZINIT.9
ZINIT.10
ZINIT.11
ZINIT.12
ZINIT.13
ZINIT.14
ZINIT.15
ZINIT.16
ZINIT.17
ZINIT.18
ZINIT.19
ZINIT.20
ZINIT.21

```

TABLE VI - contd.

```

L=4*K
Z(L+2)= Z1(L+2)* CONST(5)
Z(L+4)= Z1(L+4)* CONST(5)
Z(L+2)= P(K)*COS(Z(L+4))*SIN(Z(L+2))
Z(L+4)= P(K)*SIN(Z(L+4))
Z(L+1)= Z1(L+1)*CONST(4)
Z(L+3)= Z1(L+3)*CONST(4)
CONTINUE
10  *      END
      RETURN
      END
SUBROUTINE ZFINAL(Y,M)$ REAL Y(1)$ INTEGER M
* COMMENT ZFINAL ESTABLISHES THE FINAL CONDITIONS OF ANY NEARBY RAY
* IT IS THE INVERSE OF ZINIT EXCEPT THAT IT WORKS ONE
* RAY AT A TIME.
* BEGIN
      INTEGER N,NUM,L,K
      REAL PO,P,Z,CONST
      COMMON /CASES/ NUM,L,K
      .      /MOM/ PO,P(40)
      .      /SOLN/ Z(164)
      .      /PARAM/ CONST(8)
      N=M
      Y(4)=ASIN(Z(L+N+4)/P(K))
      Y(2)=ASIN(Z(L+N+2)/(P(K)*COS(Y(4))))/CONST(5)
      Y(4)=Y(4)/CONST(5)
      Y(1)=Z(L+N+1)/CONST(4)
      Y(3)=Z(L+N+3)/CONST(4)
      RETURN
      END
SUBROUTINE SF(N1,N2,N3,N4)$ INTEGER N1,N2,N3,N4
* COMMENT SF OBTAINS THE OFF DIAGONAL ELEMENTS OF THE SECOND ORDER
* TRANSFER MATRIX
* BEGIN
      INTEGER M1,M2,M3,M4,K,K1,L,NUM,I,I1,KK
      REAL Z,PO,P,YP,YM,A,U,S
      COMMON /CASES/ NUM,L,K
      .      /SOLN/ Z(164) /MOM/ PO,P(40)
      .      /YAFS/ YP(5),YM(5),A(5),U(5,5),S(5,5,5)
      M1=N1$ M2=N2$ M3= N3$ M4=N4
      IF(NUM.EQ.21) 2,20
      COMMENT ASYMMETRIC SOLN
      DO 10 KK=1,M1,1
      BEGIN
          L= 4*KK-4
          K= KK+M3
          CALL ZFINAL(YP,M2)
          CALL YPYM5(KK+M3,10,M1+M3)
          K1= KK+M4
          DO 10 I=1,5,1

```

ZINIT.22
ZINIT.23
ZINIT.24
ZINIT.25
ZINIT.26
ZINIT.27
ZINIT.28
ZINIT.29
ZINIT.30
ZINIT.31
ZINIT.32
ZINIT.33
ZINIT.34
ZFINAL.2
ZFINAL.3
ZFINAL.4
ZFINAL.5
ZFINAL.6
ZFINAL.7
ZFINAL.8
ZFINAL.9
ZFINAL.10
ZFINAL.11
ZFINAL.12
ZFINAL.13
ZFINAL.14
ZFINAL.15
ZFINAL.16
ZFINAL.17
ZFINAL.18
ZFINAL.19
ZFINAL.20
ZFINAL.21
ZFINAL.22
SF.2
SF.3
SF.4
SF.5
SF.6
SF.7
SF.8
SF.9
SF.10
SF.11
SF.12
SF.13
SF.14
SF.15
SF.16
SF.17
SF.18
SF.19
SF.20
SF.21

TABLE VI - contd.

```

*          BEGIN
*          S(I,M4,K1)=
*          (YP(I)-A(M4)*U(I,M4)- A(K1)*U(I,K1)
*          -S(I,M4,M4)*(A(M4)**2)-S(I,K1,K1)*(A(K1)**2))/
*          (2.*A(M4)*A(K1))
10         S(I,K1,M4)=S(I,M4,K1)
*          CONTINUE
*          END
*          END
*          RETURN
*          COMMENT SYMMETRIC SOLUTION
*          DO 30 KK=1,M1,1
*          BEGIN
*          L=4*KK-4
*          K=KK+M3
*          CALL ZFINAL(YP,M2)
*          K= K+10
*          CALL ZFINAL(YM,M2+40)
*          K1=KK+M4
*          CALL YPYM5(KK+M3,10,M1+M3)
*          DO 30 I=1,5,1
*          BEGIN
*          S(I,M4,K1)=
*          (YP(I)+YM(I)-2.0*(S(I,M4,M4)*A(M4)**2
*          +S(I,K1,K1)*A(K1)**2))/(4.0*A(M4)*A(K1))
*          S(I,K1,M4)= S(I,M4,K1)
30         CONTINUE
*          END
*          END
*          RETURN
*          END

SUBROUTINE SETZ(Z,P)
REAL Z(1),P(1)
* COMMENT SETZ SETS THE NEAR BY RAYS FOR GENERATION OF THE FIRST
* ORDER MATRIX F AND THE SECOND ORDER MATRIX S
* BEGIN
INTEGER NUM1,NUM,K,N,L
REAL PO,YP,YM,A,U,S,CONST
COMMON /CASES/ NUM,L,K
/ YAFS/ YP( 5 ),YM( 5 ),A( 5 ),U(5,5),S(5,5,5)
/ PARAM/ CONST(8)
NUM1= NUM-1$ N= 4*NUM
DO 10 K=5,N,1
10    Z(K)= 0.
DO 12 K=1,NUM1,1
12    P(K)= 0.0
Z(5)=A(1)
Z(10)=A(2)
Z(15)=A(3)
Z(20)=A(4)
Z(25)=-Z(5)$Z(30)=-Z(10)$Z(35)=-Z(15)$Z(40)=-Z(20)
P(5)=P(5)+A(5)
SETZ.2
SETZ.3
SETZ.4
SETZ.5
SETZ.6
SETZ.7
SETZ.8
SETZ.9
SETZ.10
SETZ.11
SETZ.12
SETZ.13
SETZ.14
SETZ.15
SETZ.16
SETZ.17
SETZ.18
SETZ.19
SETZ.20
SETZ.21
SETZ.22

```

TABLE VI - contd.

```

P(10)=P(10)-A(5)
IF(NUM.GT.11) 14, 30
BEGIN
14      DO 16 K=45,57,4
        Z(K)= Z(5)
16      Z(K+40)=-Z(5)
        Z(46)= Z(10)$ Z(86)=-Z(10)
        DO 18 K=62,70,4
        Z(K)= Z(10)
18      Z(K+40)= -Z(10)
        DO 20 K= 51,75,12
        Z(K)= Z(15)
20      Z(K+40)=-Z(15)
        Z(79)= Z(15)$ Z(119)=-Z(15)
        DO 22 K= 68,84,8
        Z(K)= Z(20)
22      Z(K+40)= -Z(20)
        Z(56)=Z(20)$ Z(96)=-Z(20)
        DO 24 K= 14,20,3
        P(K)= P(5)
24      P(K+10)=P(10)
        P(19)= P(5)
        P(29)=P(10)
*      END
30      CONTINUE
RETURN
END

SUBROUTINE FUNC(SO,Z,F)$ REAL SO$ REAL Z(1),F(1)
* COMMENT FUNC COMPUTES THE RIGHT HAND SIDE OF THE DIFFERENTIAL
* EQUATION DZ(SO)=F(Z(SO)) WHERE Z IS IN R**(4*NUM).
* Z(1) TO Z(4) ARE THE REFERENCE RAY AND Z(4*K+1) TO
* Z(4*K+4),K IN (1,...,NUM-1),ARE THE NEARBY RAYS.
* BEGIN
  INTEGER K,K1,NUM,L,COUNT
  REAL QBAR,ABAR,BB3K,WK,DELP3,QBARWK,Q,PO,P,BB02,BB1,BB2,BB3
  COMMON /CASES/ NUM,L,K
  /CHARGE/ Q
  /MGM/ PO,P(40)
  /FIELD/ BB02,BB1(40),BB2(40),BB3(40)
  /WORK/COUNT,STEP
* COMMENT ESTABLISH THE FIELD AT THE CURRENT POSITION IN SPACE
CALL FIELD $ COUNT= COUNT +1
QBAR= Q/PO$ ABAR= QBAR * BB02
* COMMENT REFERENCE RAY
F(1)= -1.*ABAR*Z(2)$ F(2)= ABAR*Z(1)
F(3)= Z(1)$ F(4)= Z(2)$ K1= NUM-1
IF(K1.EQ.0) RETURN
DO 10 K=1,K1,1
* BEGIN
  L=4*K$ DELP3= SQRT(P(K)**2-Z(L+2)**2-Z(L+4)**2)
  WK= DELP3/(1+Z(L+1)*ABAR)$ QBARWK= QBAR/WK
  F(L+2)=(QBARWK) *(Z(L+4)*BB3(K)-DELP3*BB2(K))

```

SETZ.23
 SETZ.24
 SETZ.25
 SETZ.26
 SETZ.27
 SETZ.28
 SETZ.29
 SETZ.30
 SETZ.31
 SETZ.32
 SETZ.33
 SETZ.34
 SETZ.35
 SETZ.36
 SETZ.37
 SETZ.38
 SETZ.39
 SETZ.40
 SETZ.41
 SETZ.42
 SETZ.43
 SETZ.44
 SETZ.45
 SETZ.46
 SETZ.47
 SETZ.48
 SETZ.49
 SETZ.50
 SETZ.51
 FUNC.2
 FUNC.3
 FUNC.4
 FUNC.5
 FUNC.6
 FUNC.7
 FUNC.8
 FUNC.9
 FUNC.10
 FUNC.11
 FUNC.12
 FUNC.13
 FUNC.14
 FUNC.15
 FUNC.16
 FUNC.17
 FUNC.18
 FUNC.19
 FUNC.20
 FUNC.21
 FUNC.22
 FUNC.23
 FUNC.24
 FUNC.25
 FUNC.26

TABLE VI - contd.

```

      +ABAR*DELP3
      F(L+4)=(QBARWK) *(DELP3*BB1(K)-Z(L+2)*BB3(K))
      F(L+1)=Z(L+2)/WK
      F(L+3)=Z(L+4)/WK
10    CONTINUE
*    END
      RETURN
      END

SUBROUTINE YPYM5(M,N,A5)
INTEGER M,N,A5
*    BEGIN COMMENT YP(5) AND YM(5) ARE SET EXACTLY FOR THE FIRST
*    STEP. ALL OTHER STEPS ARE SET USING THE CALCULATED
*    VALUES OF THE MOMENTUM P.
      COMMON /CASES/ NUM,L,K
      COMMON /YAFS/ YP(5),YM(5),A(5),U(5,5),S(5,5,5)
      COMMON /WORK/ COUNT,STEP /MOM/ PO,P(40)
      REAL YP,YM,A,P
      INTEGER STEP,NUM
      IF(STEP.EQ.0 .A. M.EQ.A5) 2,4
*    BEGIN
2      YP(5)= A(5)
      YM(5)= -A(5)
      RETURN
*    END ELSE
*    BEGIN
4      YP(5)= P(M)-1.0
      IF(M+N.GT.10 .A. NUM.EQ.21) RETURN
      YM(5)=P(M+N)-1.0
      RETURN
*    END
      END

SUBROUTINE SAVEZP(ZSAVE,Z1,P1,PI)
REAL ZSAVE(1),Z1(1),P1(1),PI(1)
*    BEGIN
*    COMMENT THE INITIAL VALUSE Z1,P1 THAT SOTRM1 WAS CALLED
*    WITH ARE SAVED
      INTEGER NUM,L,K,NUM1
      COMMON /CASES/ NUM,L,K
      NUM1= NUM-1
      DO 20 L= 1,NUM1,1
      DO 18 K= 1,4,1
*    BEGIN
18      ZSAVE(5*L-5+K)= Z1(4*L+K)
20      ZSAVE(5*L)= P1(L)
*    END
      RETURN
      END

SUBROUTINE CUTRT(TEXT,R,T)

```

```

FUNC.27
FUNC.28
FUNC.29
FUNC.30
FUNC.31
FUNC.32
FUNC.33
FUNC.34
FUNC.35
FUNC.36
YPYM5.2
YPYM5.3
YPYM5.4
YPYM5.5
YPYM5.6
YPYM5.7
YPYM5.8
YPYM5.9
YPYM5.10
YPYM5.11
YPYM5.12
YPYM5.13
YPYM5.14
YPYM5.15
YPYM5.16
YPYM5.17
YPYM5.18
YPYM5.19
YPYM5.20
YPYM5.21
YPYM5.22
YPYM5.23
YPYM5.24
YPYM5.25
YPYM5.26
SAVEZP.2
SAVEZP.3
SAVEZP.4
SAVEZP.5
SAVEZP.6
SAVEZP.7
SAVEZP.8
SAVEZP.9
SAVEZP.10
SAVEZP.11
SAVEZP.12
SAVEZP.13
SAVEZP.14
SAVEZP.15
SAVEZP.16
SAVEZP.17
SAVEZP.18
SAVEZP.19
CUTRT.2

```

TABLE VI - contd.

```

INTEG ER TEXT
REAL R(5,5),T(5,5,5)
* BEGIN COMMENT THIS ROUTINE REQUIRES EXTENDED FORTRAN OUTPUT. SEE
* UCRL 19463. IT OUTPUTS THE FIRST AND SECOND ORDER ELEMENTS
* IN A TABLE LIKE THAT APPEARING IN UCRL 19182. IT CAN BE
* DELETED OR REPLACED. IT IS CALLED FROM PROGRAM SOTRM
INTEG ER I,J,K,N
CALL OUTMODE(1HS)
CALL PLIM(10,130)
CALL PAGE
CALL S(TEXT) $ CALL LINES(1)
CALL S(1CH(*R(J,K)*)) $ CALL LINES(1)
CALL S(14H(* J / K =*))
DO 10 J=1,5,1
* BEGIN
      CALL SPACES(8)
      CALL OUTI(J,1)
      CALL SPACES(8)
10
* END
CALL LINES(1)
DO 22 I=1,5,1
DO 20 J=1,5,1
      IF(J.EQ.1) CALL SPACES(11)
      IF(R(I,J).EQ.0)
        CALL S(21H(* 0.0000000E 00*))
      IF(R(I,J).NE.0)
        CALL OUTR(R(I,J),.FALSE.,17,7)
20      CONTINUE
22      CALL LINES(1)
* END
CALL LINES(2)
CALL S(12H(*T(I,J,K)*)) $ CALL LINES(1)
CALL S(14H(* I/ J/ K =*))
DO 30 I= 1,5,1
* BEGIN
      CALL SPACES(8)
      CALL OUTI(I,1)
      CALL SPACES(8)
30
* END
CALL LINES(1)
DO 44 I=1,5,1
DO 42 J= 1,5,1
DO 40 K= J,5,1
* BEGIN
      IF(J.EQ.K) 32,38
      BEGIN
32          CALL OUTI(I,2)
          CALL OUTI(J,3)
          CALL SPACES(5)
          CALL SPACES(17*(J-1))
* END
38      CONTINUE
      IF(T(I,J,K).EQ.0.0)
        CALL S(21H(* 0.0000000E 00*))

```

```

OUTRT.3
OUTRT.4
OUTRT.5
OUTRT.6
OUTRT.7
OUTRT.8
OUTRT.9
OUTRT.10
OUTRT.11
OUTRT.12
OUTRT.13
OUTRT.14
OUTRT.15
OUTRT.16
OUTRT.17
OUTRT.18
OUTRT.19
OUTRT.20
OUTRT.21
OUTRT.22
OUTRT.23
OUTRT.24
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OUTRT.28
OUTRT.29
OUTRT.30
OUTRT.31
OUTRT.32
OUTRT.33
OUTRT.34
OUTRT.35
OUTRT.36
OUTRT.37
OUTRT.38
OUTRT.39
OUTRT.40
OUTRT.41
OUTRT.42
OUTRT.43
OUTRT.44
OUTRT.45
OUTRT.46
OUTRT.47
OUTRT.48
OUTRT.49
OUTRT.50
OUTRT.51
OUTRT.52
OUTRT.53
OUTRT.54
OUTRT.55
OUTRT.56

```

TABLE VI - contd.

	IF(T(I,J,K).NE.0.0)	OUTRT.57
	CALL OUTR(T(I,J,K),.FALSE.,17,7)	OUTRT.58
40	CONTINUE	OUTRT.59
42	CALL LINES(1)	OUTRT.60
44	CONTINUE	OUTRT.61
*	END	OUTRT.62
	CALL PAGE	OUTRT.63
	CALL S(13H(*END OUTRT*))	OUTRT.64
	CALL LINES(1)	OUTRT.65
	RETURN	OUTRT.66
	END	OUTRT.67
		OUTRT.68
		OUTRT.69
	SUBROUTINE APTRAN(II,KKEY)	APTRAN.2
	INTEGER II,KKEY,STEP	APTRAN.3
*		APTRAN.4
*	THIS ROUTINE APPLIES THE TRANSFER MATRIX CORRESPONDING TO THE VALUE	APTRAN.5
*	OF KEY TO THE NEARBY RAYS.	APTRAN.6
*		APTRAN.7
	COMMON /INIT/ ZSAVE(150)	APTRAN.8
	COMMON /CASES/ NUM,L,K	APTRAN.9
	COMMON /MOM/ PO,P(40) /YAFS/ YP(5),YM(5),A(5),U(5,5),S(5,5,5)	APTRAN.10
	COMMON /WORK/ COUNT,STEP	APTRAN.11
	DIMENSION ZTRAN(150),ZSOLN(150),V(5)	APTRAN.12
	IF(II.EQ.0) 4,8	APTRAN.13
4	READ(1) LSTP,KEY,U,S	APTRAN.14
	IF(STEP.NE.LSTP) 720,9	APTRAN.15
720	PRINT 731,STEP,LSTP	APTRAN.16
731	FORMAT(*OHRONG STEP ON DISK. STEP =*I10,5X*LSTP =*I10)	APTRAN.17
	RETURN	APTRAN.18
8	KEY= KKEY	APTRAN.19
	WRITE(1) STEP,KEY,U,S	APTRAN.20
9	CCONTINUE	APTRAN.21
	NUM1=NUM-1	APTRAN.22
	DO 20 L=1,NUM1	APTRAN.23
	M=5*L-5	APTRAN.24
	DO 20 I=1,5	APTRAN.25
	SUM1=0.0	APTRAN.26
	SUM2=0.0	APTRAN.27
	DO 12 J=1,5	APTRAN.28
	SUM1=SUM1+U(I,J)*ZSAVE(M+J)	APTRAN.29
	IF(KEY.EQ.1.OR.KEY.EQ.-1) GO TO 12	APTRAN.30
	DO 10 K=1,5	APTRAN.31
	SUM2=SUM2+S(I,J,K)*ZSAVE(M+J)*ZSAVE(M+K)	APTRAN.32
10	CONTINUE	APTRAN.33
12	CONTINUE	APTRAN.34
	IF(KEY.GT.0) GO TO 17	APTRAN.35
	DO 15 J=1,5	APTRAN.36
15	SUM2=SUM2+S(I,J,J)*ZSAVE(M+J)*ZSAVE(M+J)	APTRAN.37
17	ZTRAN(M+I)=SUM1+SUM2	APTRAN.38
20	CONTINUE	APTRAN.39
	V(5)=0.0	APTRAN.40
	DO 30 KK=1,NUM1	APTRAN.41
	L=4*KK	APTRAN.42

TABLE VI - contd.

	K=KK	APTRAN.43
	CALL ZFINAL(V,0)	APTRAN.44
	DC 30 J=1,5	APTRAN.45
	ZSOLN(5*KK+J-5)=V(J)	APTRAN.46
30	CONTINUE	APTRAN.47
	DO 40 I=1,NUM1	APTRAN.48
40	ZSOLN(5*I)=P(I)-1.0	APTRAN.49
	N=5*NUM1	APTRAN.50
	IF(N.EQ.15*(N/15)) GO TO 45	APTRAN.51
	NN=15*(N/15)+1	APTRAN.52
	GO TO 50	APTRAN.53
45	NN=N-14	APTRAN.54
50	PRINT 55	APTRAN.55
55	FORMAT(///11X5HZTRAN,10X5HZSOLN,15X5HZTRAN,10X5HZSCLN,15X5HZTRAN, 110X5HZSOLN)	APTRAN.56
	DO 90 I=1,NN,15	APTRAN.57
	DO 70 J=1,5	APTRAN.58
	K=I-1+J	APTRAN.59
	L=K+10	APTRAN.60
	PRINT 60,(ZTRAN(M),ZSOLN(M),M=K,L,5)	APTRAN.61
60	FORMAT(5X2E15.7,5X2E15.7,5X2E15.7)	APTRAN.62
70	CONTINUE	APTRAN.63
	PRINT 80	APTRAN.64
80	FORMAT(1H0)	APTRAN.65
90	CONTINUE	APTRAN.66
	RETURN	APTRAN.67
	END	APTRAN.68
		APTRAN.69
		APTRAN.70
		APTRAN.71
	FORTRAN IV SUBROUTINE INTO(NG,X,DERI ,Y,F,T,HPRO)	ZAM.2
*	COMMENT THIS IS THE LRL INTEGRATOR ZAM. SEE LRL COMPUTER CENTER	ZAM.3
*	WRITE UP FOR ZAM D2 BKY ZAM.	ZAM.4
	COMMON /INTC/ IPMX,AREF,EMAX,SSSR,HFAC,SWAM,SWEX	ZAM.5
	COMMON /INTP/ HPR,XX,N,EUB,ELB,IP,IT,NRKS,SWIN	ZAM.6
	DIMENSION Y(1),F(1),T(8,1)	ZAM.7
	LOGICAL SWAM,SWEX,SWIN	ZAM.8
	INTEGER HFAC	ZAM.9
	DOUBLE PRECISION T,HPRO,HPR,XX	ZAM.10
	DATA IPMX,AREF,EMAX,SSSR,HFAC,SWAM,SWEX	ZAM.11
	\$ /16384 ,1.0,1.0E-8 ,100.0,2,.TRUE.,.TRUE./	ZAM.12
*	COMMENT NOTE THAT EMAX= 10E-8 IS PROBABLY TOO SMALL FOR EXPERIMEN-	ZAM.13
*	TAL DATA, EMAX= 10E-6 IS PROBABLY BETTER.	ZAM.14
C		ZAM.15
	HPR=HPRO	ZAM.16
	XX=DBLE(X)	ZAM.17
	N=NO	ZAM.18
	EUB=EMAX	ZAM.19
	ELB=EMAX/SSSR	ZAM.20
	IP=1	ZAM.21
	IT=0	ZAM.22
	NRKS=0	ZAM.23
	SWIN=SWEX	ZAM.24
	CALL DERI (X,Y,F)	ZAM.25
	DC 9 I=1,N	ZAM.26

TABLE VI - contd.

	T(5,I)=DBLE(Y(I))	ZAM.27
9	CONTINUE	ZAM.28
	RETURN	ZAM.29
	END	ZAM.30
	SUBROUTINE INT(X,DERI ,Y,F,T,SWPR	ZAM.31
X)	ZAM.32
	COMMON /INTC/ IPMX,AREF,EMAX,SSSR,HFAC,SWAM,SWEX	ZAM.33
	COMMON /INTP/ HPR,XX,N,EUB,ELB,IP,IT,NRKS,SWIN	ZAM.34
C		ZAM.35
	DIMENSION Y(1),F(1),T(8,1)	ZAM.36
	LOGICAL SWAM,SWEX,SWIN	ZAM.37
	LOGICAL SWPR	ZAM.38
	INTEGER HFAC	ZAM.39
	DOUBLE PRECISION T,HPR,XX	ZAM.40
	DCUBLE PRECISION D,H	ZAM.41
6000	FORMAT (36H0 CANNOT DECREASE H BECAUSE OF HMIN. ,1PE16.8,I20)	ZAM.42
C		ZAM.43
1	CONTINUE	ZAM.44
	SWPR=.FALSE.	ZAM.45
	TEST=0.0	ZAM.46
	H=HPR/DBLE(FLOAT(IP*24))	ZAM.47
	IF ((NRKS .LT. 3) .OR. (.NOT. SWAM)) GO TO 200	ZAM.48
C		ZAM.49
C	ADAMS-MOULTON STEP.	ZAM.50
100	CONTINUE	ZAM.51
	DC 109 I=1,N	ZAM.52
	D=DBLE(F(I))	ZAM.53
	T(4,I)=D	ZAM.54
	Y(I)=SNGL(T(5,I)+H*(ZAM.55
X	55.000*D-59.000*T(3,I)+37.000*T(2,I)- 9.000*T(1,I))	ZAM.56
109	CONTINUE	ZAM.57
	X=SNGL(XX+24.000*H)	ZAM.58
	CALL DERI (X,Y,F)	ZAM.59
	DC 119 I=1,N	ZAM.60
	D=DBLE(F(I))	ZAM.61
	D=(T(5,I)+H*(ZAM.62
	9.000*D+19.000*T(4,I)- 5.000*T(3,I)+ T(2,I))	ZAM.64
	T(6,I)=D	ZAM.65
	E=ABS(SNGL(D)-Y(I))/14.0	ZAM.66
	TEST=AMAX1(E/AMAX1(AREF,ABS(SNGL(D))),TEST)	ZAM.67
119	CONTINUE	ZAM.68
C		ZAM.69
	GO TO 300	ZAM.70
C		ZAM.71
C	ZCNNEVELD STEP.	ZAM.72
200	CONTINUE	ZAM.73
	DC 209 I=1,N	ZAM.74
	D=DBLE(F(I))	ZAM.75
	T(4,I)=D	ZAM.76
C	1	ZAM.77
	Y(I)=SNGL(T(5,I)+H*(ZAM.78
X	12.000*D	ZAM.79
209	CONTINUE	ZAM.80

TABLE VI - contd.

	X=SNGL (XX+12.000*H)	ZAM.81
	CALL DERI (X,Y,F)	ZAM.82
	DC 219 I=1,N	ZAM.83
	D=DBLE(F(I))	ZAM.84
	T(6,I)=D	ZAM.85
C	2	ZAM.86
	Y(I)=SNGL(T(5,I)+H*(ZAM.87
X	12.000*D	ZAM.88
219	CONTINUE	ZAM.89
	CALL DERI (X,Y,F)	ZAM.90
	DC 229 I=1,N	ZAM.91
	D=DBLE(F(I))	ZAM.92
	T(7,I)=D	ZAM.93
C	3	ZAM.94
	Y(I)=SNGL(T(5,I)+H*(ZAM.95
X	24.000*D	ZAM.96
229	CONTINUE	ZAM.97
	X=SNGL (XX+24.000*H)	ZAM.98
	CALL DERI (X,Y,F)	ZAM.99
	DC 239 I=1,N	ZAM.100
	D=DBLE(F(I))	ZAM.101
	T(8,I)=D	ZAM.102
C	4	ZAM.103
	Y(I)=SNGL(T(5,I)+H*(ZAM.104
X	3.7500*T(4,I)+5.2500*T(6,I)+9.7500*T(7,I)-0.7500*D	ZAM.105
239	CONTINUE	ZAM.106
	X=SNGL (XX+18.000*H)	ZAM.107
	CALL DERI (X,Y,F)	ZAM.108
	DC 249 I=1,N	ZAM.109
	D=DBLE(F(I))	ZAM.110
	E=ABS(SNGL(H*(ZAM.111
X	-16.000*T(4,I)+48.000*T(6,I)+48.000*T(7,I)+48.000*T(8,I)	ZAM.112
X	-128.000*D	ZAM.113
C	5	ZAM.114
	D=(T(5,I)+H*(ZAM.115
X	4.000*T(4,I)+ 8.000*T(6,I)+ 8.000*T(7,I)+ 4.000*T(8,I)	ZAM.116
X)	ZAM.117
	T(6,I)=D	ZAM.118
	TEST=AMAX1(E/AMAX1(AREF,ABS(SNGL(D))),TEST)	ZAM.119
249	CONTINUE	ZAM.120
C		ZAM.121
C	BOTH ADAMS-MOULTON AND ZONNEVELD METHODS CONTINUE FROM HERE.	ZAM.122
300	CONTINUE	ZAM.123
	X=SNGL (XX+24.000*H)	ZAM.124
	IF (TEST .LE. EUB) GO TO 310	ZAM.125
	IF (IP*HFAC .GT. IPMX) GO TO 309	ZAM.126
C		ZAM.127
C	REPEAT STEP WITH SMALLER H.	ZAM.128
	NRKS=0	ZAM.129
	IP=IP*HFAC	ZAM.130
	IT=IT*HFAC	ZAM.131
	DC 305 I=1,N	ZAM.132
	Y(I)=SNGL(T(5,I))	ZAM.133
	F(I)=SNGL(T(4,I))	ZAM.134

TABLE VI - contd.

305	CONTINUE	ZAM.135
	GO TO 1	ZAM.136
C		ZAM.137
C	CANNOT DECREASE H BECAUSE OF HMIN.	ZAM.138
309	CONTINUE	ZAM.139
	IF (.NOT. SWIN) GO TO 310	ZAM.140
	PRINT 6000, X,IPMX	ZAM.141
	SWIN=.FALSE.	ZAM.142
C		ZAM.143
310	CONTINUE	ZAM.144
C		ZAM.145
C		ZAM.146
C	ACCEPT CURRENT STEP.	ZAM.147
C		ZAM.148
C	XX STILL HAS NOT BEEN CHANGED SINCE ENTRY.	ZAM.149
C	YY(XX) IS STILL IN T(5,).	ZAM.150
C	F(YY) IS IN T(4,).	ZAM.151
C		ZAM.152
	IT=IT+1	ZAM.153
	XX=XX+HPR/CBLE(FLOAT(IP))	ZAM.154
	NRKS=MINO(NRKS+1,4)	ZAM.155
	DO 319 I=1,N	ZAM.156
	D=T(6,I)	ZAM.157
	T(5,I)=D	ZAM.158
	Y(I)=SNGL(D)	ZAM.159
319	CONTINUE	ZAM.160
	X=SNGL(XX)	ZAM.161
	CALL CER1 (X,Y,F)	ZAM.162
	IF (IT .LT. IP) GO TO 320	ZAM.163
C		ZAM.164
C	X IS A MULTIPLE OF HPRINT.	ZAM.165
	SWPR=.TRUE.	ZAM.166
	IT=IT-IP	ZAM.167
C		ZAM.168
320	CONTINUE	ZAM.169
	IF (TEST .GE. ELB) GO TO 330	ZAM.170
	IF (MOD(IP,HFAC)+MOD(IT,HFAC) .NE. 0) GO TO 330	ZAM.171
C		ZAM.172
C	PROCEED TO NEXT STEP WITH LARGER H, USING ZONNEVELD METHOD.	ZAM.173
	NRKS=0	ZAM.174
	IP=IP/HFAC	ZAM.175
	IT=IT/HFAC	ZAM.176
	RETURN	ZAM.177
C		ZAM.178
C		ZAM.179
C	PROCEED TO NEXT STEP WITH SAME H.	ZAM.180
330	CONTINUE	ZAM.181
	DO 339 I=1,N	ZAM.182
	T(1,I)=T(2,I)	ZAM.183
	T(2,I)=T(3,I)	ZAM.184
	T(3,I)=T(4,I)	ZAM.185
339	CONTINUE	ZAM.186
	RETURN	ZAM.187
	END	ZAM.188

TABLE VI - contd.

```

SUBROUTINE FIELD
COMMENT THIS ROUTINE ESTABLISHES THE FIELD AT THE CURRENT
      POSITION OF THE REFERENCE PARTICLE AND THE NEARBY
      PARTICLES. THE ORIGIN IS THE ORIGIN OF THE REFERENCE
      PARTICLE. THE ACTUAL FIELD IN GAUSS IS SUPPLIED BY THE
      SUBROUTINE GAUSS.
BEGIN
  INTEGER K,K1,L,NUM
  REAL    Z4K,R,PO,P,BB02,BB1,BB2,BB3,Z,G,CCNST
  DIMENSION R(3),G(3)
  COMMON  /CASES/ NUM,L,K
          /MOM/ PO,P(40)
          /FIELD/BB02,BB1(40),BB2(40),BB3(40)
          /SOLN/ Z(164)
          /PARAM/ CONST(8)
  K1=NUM-1
  COMMENT THE POSITION OF THE REFERENCE ORBIT IN THE GLOBAL
  COORDINATE SYSTEM IS R(1),R(2),R(3). SEE FIGURE 1 UCRL
  19182.
  R(1)= Z(3)
  R(2)= 0.0
  R(3)= Z(4)
  CALL GAUSS(R,G)
  BB02= G(2) * CONST(7)
  IF(K1.EQ.0) RETURN
  DO 10 K=1,K1,1
  BEGIN
    L=4*K$ Z4K= Z(L+1)
    COMMENT SEE UCRL 19182 FIGURE 1. WE ARE TRANSFORMING
    FROM THE PRIMED TO THE GLOBAL UNPRIMED COORDINATE
    SYSTEM.
    R(1)= ( Z(3)+Z4K * Z(2) )
    R(2)= ( Z(L+3) )
    R(3)= ( Z(4)- Z4K * Z(1) )
    CALL GAUSS(R,G)
    COMMENT NOTE THAT THE FIELD HERE, BB1(K)...BB3(K),
    REFERS TO THE FIELD COMPONENTS IN THE PRIMED
    COORDINATE SYSTEM. SEE UCRL 19182 FIGURE 1.
    BB1(K)= G(1)* CONST(7)
    BB2(K)= G(2)* CONST(7)
    BB3(K)= G(3)* CONST(7)
  10
  END
RETURN
END

SUBROUTINE GAUSS(R,G)$ REAL R(1),G(1)
COMMENT
$ THIS VERSION OF GAUSS SETS A CONSTANT FIELD = 17.036E4 GAUSS
C WHICH CORRESPONDS TO A RADIUS OF 1 METER FOR PC= 510.72
$ FOR A PROTON

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ZAM.189
ZAM.190
FIELD1.2
FIELD1.3
FIELD1.4
FIELD1.5
FIELD1.6
FIELD1.7
FIELD1.8
FIELD1.9
FIELD1.10
FIELD1.11
FIELD1.12
FIELD1.13
FIELD1.14
FIELD1.15
FIELD1.16
FIELD1.17
FIELD1.18
FIELD1.19
FIELD1.20
FIELD1.21
FIELD1.22
FIELD1.23
FIELD1.24
FIELD1.25
FIELD1.26
FIELD1.27
FIELD1.28
FIELD1.29
FIELD1.30
FIELD1.31
FIELD1.32
FIELD1.33
FIELD1.34
FIELD1.35
FIELD1.36
FIELD1.37
FIELD1.38
FIELD1.39
FIELD1.40
FIELD1.41
FIELD1.42
FIELD1.43
FIELD1.44
FIELD1.45
FIELD1.46
FIELD1.47
GAUSS1.2
GAUSS1.3
GAUSS1.4
GAUSS1.5
GAUSS1.6
GAUSS1.7

TABLE VI - contd.

```

*      BEGIN
      REAL C,PO,P
      COMMON/CHARGE/ Q
      /MOM / PO,P(40)
      G(1)=C.
      G(2)=(PO/Q)*1.E4
      G(3)=C.
RETURN
END

SUBROUTINE FIELD
*      COMMENT THIS ROUTINE ESTABLISHES THE FIELD AT THE CURRENT
*      POSITION OF THE REFERENCE PARTICLE AND THE NEARBY
*      PARTICLES. THE ORIGIN IS THE ORIGIN OF THE REFERENCE
*      PARTICLE. THE ACTUAL FIELD IN GAUSS IS SUPPLIED BY THE
*      SUBROUTINE GAUSS.
*      BEGIN COMMENT THIS VERSION OF FIELD CAN BE USED WITH AN IDEAL
*      SEXTUPLE AND AN IDEAL QUADRUPOLE. IT ASSUMES THAT THE
*      REFERENCE ORBIT HAS FIELD ZERO.
      INTEGER K,K1,L,NUM
      REAL Z4K,R,PO,P,BB02,BB1,BB2,BB3,Z,G,CONST
      DIMENSION R(3),G(3)
      COMMON /CASES/ NUM,L,K
      /MOM/ PO,P(40)
      /FIELD/BB02,BB1(40),BB2(40),BB3(40)
      /SOLN/ Z(164)
      /PARAM/ CONST(8)
      K1=NUM-1
*      COMMENT THE REFERENCE ORBIT FIELD IS SET TO ZERO.
      BB02= 0.0
      IF(K1.EQ.0) RETURN
      DO 10 K=1,K1,1
*      BEGIN
          L=4*K$ Z4K= Z(L+1)
*      COMMENT R(1) AND R(2) GIVE THE DISPLACEMENT IN METERS
*      IN THE PRIMED SYSTEM. SEE FIGURE 1 UCRL 19182.
          R(1)=Z(L+1)
          R(2)=Z(L+3)
          CALL GAUSS(R,G)
          BB1(K)= G(1)* CONST(7)
          BB2(K)= G(2)* CONST(7)
          BB3(K)= G(3)* CONST(7)
10
*      END
RETURN
END

SUBROUTINE GAUSS(R,G)$ REAL R(1),G(1)
*      BEGIN
*      COMMENT THIS ROUTINE FURNISHES THE IDEAL QUADRUPOLE FIELD
*      USED AS AN EXAMPLE IN UCRL 19182.
      REAL C,PO,P
      REAL PO

```

GAUSS1.8
GAUSS1.9
GAUSS1.10
GAUSS1.11
GAUSS1.12
GAUSS1.13
GAUSS1.14
GAUSS1.15
GAUSS1.16
GAUSS1.17
GAUSS1.18
FIELD2.2
FIELD2.3
FIELD2.4
FIELD2.5
FIELD2.6
FIELD2.7
FIELD2.8
FIELD2.9
FIELD2.10
FIELD2.11
FIELD2.12
FIELD2.13
FIELD2.14
FIELD2.15
FIELD2.16
FIELD2.17
FIELD2.18
FIELD2.19
FIELD2.20
FIELD2.21
FIELD2.22
FIELD2.23
FIELD2.24
FIELD2.25
FIELD2.26
FIELD2.27
FIELD2.28
FIELD2.29
FIELD2.30
FIELD2.31
FIELD2.32
FIELD2.33
FIELD2.34
FIELD2.35
FIELD2.36
FIELD2.37
FIELD2.38
GAUSS2.2
GAUSS2.3
GAUSS2.4
GAUSS2.5
GAUSS2.6
GAUSS2.7

TABLE VI - contd.

```

COMMON/CHARGE/ Q
      /MOM      / P0,P(40)
BO=(PC/Q)*1.E4/2.0
G(1)= BO*R(2)/.0508
G(2)= BO*R(1)/.0508
G(3)=C.0
RETURN
END

```

GAUSS2.8
GAUSS2.9
GAUSS2.10
GAUSS2.11
GAUSS2.12
GAUSS2.13
GAUSS2.14
GAUSS2.15
GAUSS2.16
GAUSS2.17

```

SUBROUTINE GAUSS(R,G)$ REAL R(1),G(1)
BEGIN

```

*
*
*

COMMENT THIS ROUTINE FURNISHES THE IDEAL SEXTUPOLE FIELD
USED AS AN EXAMPLE IN UCRL 19182.

```

REAL C,PC,P
REAL BO

```

GAUSS3.2
GAUSS3.3
GAUSS3.4
GAUSS3.5
GAUSS3.6
GAUSS3.7
GAUSS3.8
GAUSS3.9
GAUSS3.10
GAUSS3.11
GAUSS3.12
GAUSS3.13
GAUSS3.14
GAUSS3.15
GAUSS3.16
GAUSS3.17

```

COMMON/CHARGE/ Q
      /MOM      / P0,P(40)
BO= (P0/Q)*1.0E4/10.0
G(1)= (2.0*BO*R(1)*R(2))/(.0508**2)
G(2)= (BO*(R(1)**2-R(2)**2))/(.0508**2)
G(3)= 0.0
RETURN

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- [2] D2 BKY ZAM, Computer Center Library, Lawrence Radiation Laboratory, Berkeley, Ca.

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