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E.R. Close, D.W. Merrill, and H.H. Holmes

July 1995



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Implementation of a New Algorithm for Density Equalizing Map Projections (DEMP)

E.R. Close, D.W. Merrill and H.H. Holmes

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July 1995

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1. Introduction and Task Description

1.1 PAREP project

The purpose of the PAREP (Populations at Risk to Environmental Pollution) Project at Lawrence Berkeley National Laboratory (LBNL), an ongoing Department of Energy (DOE) project since 1978, is to develop resources (data, computing techniques, and biostatistical methodology) applicable to DOE's needs. Specifically, the PAREP project has developed techniques for statistically analyzing disease distributions in the vicinity of supposed environmental hazards. Such techniques can be applied to assess the health risks in populations residing near DOE installations, provided adequate small-area health data are available.

The FY 1994 task descriptions for the PAREP project were determined in discussions at LBNL on 11/2/93. The FY94 PAREP Work Authorization specified three major tasks: a prototype small area study, a feasibility study for obtaining small-area data, and preservation of the PAREP data archive. The complete FY94 work plan, and the subtasks accomplished to date, were included in the Cumulative FY94 progress report (reference 1).

1.2 Prototype Small Area Study

Task 1, the prototype small area study, demonstrated the use of PAREP data and methodology for similar studies around DOE sites. This task consisted of the following milestones:

- Obtain, document, and organize the small-area data needed for study task report by 12/15/93 (reference 2).
- Manipulate map files to make them useful task report by 1/15/94 (reference 3).
- Implement new Russian algorithm for density equalizing map projections (DEMP) technical report by 4/1/94 (reference 4).
- Integrate data inputs (numerators, denominators, maps) task report by 5/94.
- Develop nearest neighbor techniques for geographic data analysis task report by 5/94.

A draft project report on the prototype four-county small-area study (reference 10) was due 8/31/94. The final DOE report was published on 1/2/95 (reference 13). A condensed version was presented at a CDC/ATSDR Symposium on 1/25/95 (reference 11) and submitted for publication on 4/1/95 (reference 14).

The present report (reference 4) is the users' manual and the task completion report for the third subtask: implemention of the new Russian algorithm for density equalizing map projections (DEMP). The latest version is available in the World Wide Web (WWW) at the URL listed in reference 4. Additional program modifications are described in Appendix E of reference 13.

For the prototype small area study, a four-county area in California (Fresno, Kings, Kern and Tulare) was selected because of the availability at LBNL of small-area health data. The data used were 401 childhood cancer cases reported between 1980 and 1988, from a study conducted by the California State Department of Health Services (DHS) (references 5 and 6). The study was initiated to investigate questions raised by a reported childhood cancer cluster in the community of McFarland, California.

The first draft interim report (reference 5) examined childhood cancer rates by cancer site, age, sex, race/ethnicity (Anglo, Hispanic and other), county, and land

use (rural vs. urban, and agricultural vs. non-agricultural). The calculation of population at risk is described in detail. Observed rates were found to be consistent with rates reported in other studies; the only significant departure from uniformity was that rates among children in urban non-agricultural areas are slightly higher than those in rural non-agricultural areas. The urban non-agricultural rates are comparable to urban rates elsewhere in California. Rates in agricultural areas are not elevated.

Interim report #2 (reference 6) examined the differences among geographic areas in greater detail. The four-county study area was subdivided into 101 communities. For each community the observed number of cases was compared with the number expected, assuming the underlying cancer rate to be uniform. Based on the Poisson distribution, six of the 101 communities had rates that fell outside 95% confidence limits (three with more cases than expected and three with fewer cases than expected). The result is consistent with the null hypothesis of uniform underlying rates. One community (McFarland) had an elevated rate outside the 99% confidence limit, exactly what would have been expected from chance alone.

The purpose of the prototype LBNL four-county study (references 10, 11, 13, 14) was to test the applicability of the technique of density equalizing map projections (DEMP) for analyzing small area disease distributions near DOE installations or other potential environmental hazards. Although the four-county study area is not near a DOE installation, the DEMP technique can be similarly applied in any area where adequate small-area health data exist. Valuable insight was gained by applying the technique to a real data set with its specific problems, rather than to a set of imaginary computer-generated cases.

Regarding the significance of the McFarland childhood cancer cluster, a statistically significant effect was reported in references 13 and 14, based on the results from a k'th nearest neighbor analysis. Due to uncertainties in the population data used, no epidemiologic conclusions can be drawn at the present time. A revised analysis is in progress (reference 15). Regardless of the final conclusions of the LBNL study, comparing the results from the LBNL analysis and the earlier DHS analysis will provide valuable insight for future studies of reported disease clusters around supposed environmental hazards.

1.3 Density Equalizing Map Projections (DEMP)

Density equalizing map projections (DEMP) have been used at LBNL to investigate geographic disease distributions in the vicinity of supposed environmental hazards. In a DEMP transformation, boundaries of geographic subareas (for example census tracts) are transformed so that population density is uniform over the entire transformed map. On the transformed map, the statistical analysis of the distribution of disease cases is simplified because the confounding effect of population density has been removed.

1.3.1 1988 LBNL Algorithm

The first LBNL algorithm, published in 1988 (reference 7), employed a radial expansion or contraction relative to the centroid of each subarea in the map. The radial transformation changed the area but not the shape of the particular subarea in question, while changing the shape but not the area of all other subareas. The resulting map depended on the arbitrary order in which the subareas were transformed; in addition, it was possible for subarea boundaries to overlap after the transformation. Case locations were transformed along with subarea boundaries during the DEMP transformation.

1.3.2 1991 LBNL Algorithm

A second LBNL algorithm, completed in 1991 (reference 8), subdivided the map into triangles. As a function of all the coordinates of all the triangle vertices, we defined (1) a constraint function H which vanishes only when each triangle reaches its desired target area, and (2) an objective function G which measures overall distortion relative to the original map. A minimization program adjusted all the vertex coordinates so as to minimize G subject to the constraint H=0. The final solution defined a linear transformation for each triangle, which was applied to all the case locations within that particular triangle. With the 1991 LBNL algorithm, solutions were uniquely defined and overlapping boundaries were avoided; however, the time required for computation was prohibitive. To limit computation time, considerable geographic detail had to be sacrificed.

1.3.3 1993 Russian Algorithm

In 1993 a new algorithm was published by Gusein-Zade and Tikunov (reference 9), in which the vector translation of each geographic map coordinate is calculated from the expansion or contraction of each infinitesimal area in the entire map. The translation due to a given subarea is calculated as a line integral around the boundary of that subarea. Convergence is achieved in a small number of iterations. Case locations are transformed along with subarea boundaries during the DEMP transformation. The present report describes the LBNL implementation of the algorithm described in reference 9.

2. Description of Russian Algorithm

2.1 Basic Features

The LBNL program RLInt (Russian Line Integral) is a direct implementation of the constructive algorithm described in Ref 9. A full description of this implementation is given below in Section 6, "The LBNL Implementation of the Russian Algorithm." A derivation of the line integral which is the basis of this algorithm is given in Appendix A, "Integral Transformation and Correction Factors." The basic features of this algorithm are that it is global in nature, the transformation applied at each iteration step depends on all regions in the map, and it is quadratic in the number of points used to represent the region boundaries. This latter statement means that if we double the number of boundary points, or equivalently the number of regions, the amount of computational work increases by about four times. It also appears to converge rather quickly to the target values, say in 10 to 20 iterations. The exact value is dependent on the initial map and the required accuracy of the final map.

2.2 Summary of the Algorithm

The authors of reference 9 describe the general problem of constructing cartograms and then describe, in a heuristic manner, the construction of an integral mapping algorithm. We include in this LBNL report a derivation of that algorithm and also the derivation of some special cases (see Appendix A).

In the present section we present an overview of the reasoning that leads to the line integral representation of the mapping.

We note that the mapping as initially conceived is continuous, but that it is applied as a discrete mapping. The discrete mapping has generated the results presented in this report and has led to the conclusions obtained. This is noted here because some of the results that we present and some of the conclusions that we derive may appear to be at variance with those that would be expected of the continuous mapping. We believe that there are no real contradictions implied by these differences.

The Russian authors start out with an infinitesimal transformation of a small region. The global region D has a density function defined on it, $\rho(x',y')$. The transformation makes the final density in the infinitesimal region equal to the target value, $\rho_f(x',y')=\rho_f$ (a constant). An arbitrary reference point z=(x,y) exterior to the infinitesimal region is chosen. The point z=(x,y) is any point in the region. The density at this point, $\rho(x,y)$, does not change. To summarize, a transformation is defined that maps the global region so that for all points inside the infinitesimal region, the density becomes constant, and for all points outside the infinitesimal region, the density does not change. However, the region does change in shape; the region points move.

If we observe the point z, the point moves due to the transformation that maps the infinitesimal region centered at (x',y'). If we now center the infinitesimal region at a new point in the plane, a new (x',y'), and reapply the transformation, the point z will again be displaced. If this is done for all points in the plane, (except for point z), we will in the end have a resultant position for z that corresponds to applying all the transformations to all the infinitesimal regions.

Another, and possibly better, way of understanding this is the following. Cover the region D with non-overlapping infinitesimal regions $\Delta x \Delta y$. Select a point z in the region for reference. Exclude that point's region from all the others. In each of the other infinitesimal regions apply the above described transformation. The global region will change in shape and the point z will move to a position determined by the sum of all the translations applied to each infinitesimal region. In each of the small regions the density will be the chosen constant target density ρ_f .

The constructive algorithm that the authors describe particularizes the transformation to that of a dilation of an infinitesimal circle that has the same area as $\Delta x \Delta y$. The principal interest is in the effect of this transformation on the point z. The authors show that the effect on the point z of transforming one infinitesimal

region is given by $\left(\frac{\rho}{\rho_f}-1\right)\frac{\vec{r}\Delta x\Delta y}{2\pi r^2}$ where \vec{r} is the vector from any point in the

infinitesimal region $\Delta x \Delta y$ to the reference point z, $\rho = \rho(x', y')$ is the density at (x', y'), and ρ_f is the target density in the region $\Delta x \Delta y$ after the mapping. The transformation is applied to all the infinitesimal regions that cover D and the resultant push on the point z is the vector sum of the individual pushes from each region. When the limit is taken as the regions shrink to zero and their number

becomes infinite, this sum becomes $\int_{D} \left(\frac{\rho}{\rho_f} - 1\right) \frac{\vec{r} dx dy}{2\pi r^2}$. This integral is the basic formula

used to define the mapping. The region D is assumed to be the union of a collection of subregions D_i . In this case the integral can be written as the sum of integrals over each of the subregions. Within each subregion the density is assumed to be a constant ρ_i , and the constant target density is ρ_{f_i} . This allows the density coefficient to be placed outside the integral. The transformation then becomes

$$\sum_{D_i} \left(\frac{\rho_i}{\rho_{f_i}} - 1 \right) \int_{D_i} \frac{\vec{r} dx dy}{2\pi r^2}.$$

The authors then recognize that the area integrals that define the x and the y components of the transformation vector can be replaced by line integrals around the region boundaries. This application of Stoke's theorem results in the transformation vector being defined by

$$\Delta z = (\Delta x, \Delta y) = \sum_{D_i} \left(\frac{\rho_i}{\rho_{f_i}} - 1 \right) \left(\frac{1}{4\pi} \right) \left(-\oint_{D_i} \ln[(x - x')^2 + (y - y')^2] dy', \oint_{D_i} \ln[(x - x')^2 + (y - y')^2] dx' \right)$$

A detailed derivation of this result is given in Section A.2 of Appendix A.

Having derived this integral transformation the authors then proceed to use it to complete the one-parameter family of transformations $h_t(z)$ which transform the density $\rho(z)$ to the constant density $\rho_f(z)$ as the parameter t goes from 0 to 1, continuously. It is this discussion that leads to the discrete, iterative transformation. In that realization of the transformation the above interval from 0 to 1 is subdivided into N equal subintervals, e.g., 10, and the above transformation is applied in 10 equal steps. This sequence of transformation can be written as

$$z_{i} = z_{i-1} + c_{i}\Delta z_{i-1};$$

$$z_{0} = z;$$

$$\Delta z_{i-1} = (\Delta x_{i-1}, \Delta y_{i-1});$$

$$c_{i} = 1/(N - i + 1);$$

$$i = 1, 2, ... N$$

At each step of the transformation the resultant transformation vector is constructed from the current values of the regions' boundaries and densities. In this report we refer to the iterative transformation, with c_i as defined above, as the Russian algorithm.

We noted at the beginning of this section that this iterative sequence, which is a discrete realization of the continuous transformation, does not necessarily map as expected. For example it does not give the best convergence rate when applied to the test maps presented in this report. However, there is no question that the transformation must be applied repeatedly to generate a sequence of resultant maps that converge to the desired target densities in the subregions of the final map.

3. Preparation of Input files

The input files required by the Russian Line Integral program RLInt are described in Section B.1 of Appendix B. Two input files are required: a map data file RLInt.dat, and a parameter file RLInt.par.

Construction of the parameter file RLInt.par is a trivial task. Examples are given in Section C.2.1 of Appendix C.

The map file RLInt.dat is considerably more complex and is normally constructed with a computer program. The method chosen will depend on the format of the input data available. Three basic inputs are required:

boundary points (x-y coordinates of polygon boundaries); population data corresponding to the same polygon boundaries; non-boundary points (x-y coordinates).

3.1 Definitions and conventions

The boundary points should be in a right-handed Cartesian coordinate system (x increasing left to right, y increasing upward). The x- and y-coordinates should have equal size (for example, kilometers, not degrees of longitude and latitude). For small regions of the earth's surface, most common projections are suitable.

Simple polygons, either land and water polygons, are described counter-clockwise. We define these polygons as having positive area. Polygons which are traced clockwise have negative area.

A doughnut-shaped region (for example a county with a lake, or a lake with an island) can be described in one of two ways, as illustrated in Figure 42 (Section B.2.1).

- (a) One can describe the doughnut "hole" (unshaded) with an additional clockwise polygon. This representation corresponds to the left portion of Figure 42, if the diagonal "cut" is ignored. The lake within a county (unshaded) has positive area and is described counter-clockwise. The county (shaded) is described by two polygons: the counter-clockwise outer boundary, and the clockwise lake boundary. Its net land area is equal to the area of the clockwise outer boundary, minus that of the counterclockwise inner boundary.
- (b) One can "slice" the doughnut as shown in the right portion of Figure 42 so that the doughnut region (shaded) is simply connected.

The two representations are computationally equivalent. The net contribution from the "slice" is zero because it is traversed in both directions.

Optionally, for completeness, the entire region may be described by a clockwise external boundary. In this case, every line segment in the entire map is traced in both directions, and the net area of the entire map is zero. This representation corresponds to the DIME (Dual Independent Map Encoding) format developed by the Census Bureau, in which every segment is identified by its two adjacent polygons. The clockwise external boundary (the boundary of the surrounding "ocean") is optional because it is explicitly ignored in the RLInt calculation.

The entire map area should be covered by non-overlapping polygons. To ensure that this condition is met, it is sufficient to require that:

- every polygon must have net positive area;
- · no polygon has boundary segments that intersect each other; and
- the net sum of all the polygon areas (including lakes) is equal and opposite to the (negative) area of the exterior boundary.

The target areas of the polygons should be specified in the same units as the coordinates of the polygon boundaries. For example, if coordinates are given in kilometers, target areas must be given in square kilometers.

Target areas must be positive or zero. A negative value indicates that the area is free to float during the density equalization process.

Boundary points and non-boundary points must be expressed in the same units.

3.2 Recommendations

In principle any map file satisfying the criteria above is a valid input file for RLInt. In practice, however, the following additional guidelines are useful.

Include no more detail than necessary. Computation time increases approximately as as the square of the number of boundary points in the map file.

On the other hand, density equalization cannot be achieved if the polygons have too few boundary points. For example, a map composed entirely of triangles cannot be density equalized as easily as the corresponding hexagon map obtained by bisecting all the triangle boundaries. An example is given in Section 7.

As described in Section 8, the algorithm breaks down (i.e., the computation is invalid and will not converge) if polygon boundaries begin to overlap during the transformation. To avoid this occurrence, provide enough iterations and provide enough geographic detail in the troublesome areas. Sparsely populated areas, which shrink to narrow slivers between more populous areas, tend to give the greatest problems.

If water regions with unspecified target area become negative, it may be necessary to constrain their target areas to be exactly zero. If islands or other coastline areas overlap each other, it may be necessary to fill the intervening regions with water polygons whose target area is zero.

Numerical precision may be a problem if the map coordinates have large numeric values. Use a coordinate system whose origin (0,0) is not too far from the center of the map. If coordinate values are large compared with 1, use the map scaling parameter iara described in section 6.3.4.

Convergence is improved and distortion is minimized, if all the target areas are normalized so that total target land area is equal to the initial land area.

For some applications only the total (adjusted) area of each polygon is of importance. This is true for the mapping applications described in reference 9. The authors of

that paper included considerable geographic detail in each polygon boundary, and did not check for local variations in magnification.

For other applications, notably case mapping in public health applications, it is important that all portions of a given polygon receive the same magnification. Nonuniformities of magnification are automatically avoided in a map composed entirely of triangles, as was done in reference 8 and in the Vermont triangle map of Section 7.2.1. However, maps composed entirely of triangles do not converge easily. Hexagon maps are a convenient compromise in applications where uniformity of magnification is required. Regions that are highly distorted by density equalization can be further triangulated as necessary.

3.3 Map file construction

The physical format of the map file RLInt.dat is defined in Section B.1.1 of Appendix B. A complete example is provided in Section C.2.2 of Appendix C.

How the map file is constructed will depend on the format of the input data available. That discussion is outside the scope of this report. Construction of map files at LBNL is described in detail in reference 3. Programs are described which convert map files among a variety of formats, including:

- SEEDIS MAPEDIT format (polygon)
- National Planning Data Corporation (polygons)
- NICKEL (segments of polygons)
- DIME (inter-polygon segments)
- EDIME (linked geocodes, points, and segments)
- FDIME (enhanced EDIME, with calculated areas)
- TIGER (linked nodes and chains)
- SPlus (linked geocodes, chains, and polygons)
- CL3 (polygon: the format of RLInt.dat)

The CL3 output subroutines can be easily integrated with input routines that read the user's own map files and population data.

In addition, utility programs are described which:

- Obtain population data from SEEDIS or from 1990 Census CD-ROMs
- convert the population and case data for use with the map files
- correct certain types of map errors
- · remove "slivers" due to boundary mismatching
- remove unnecessary geographic detail
- perform a Delaunay triangulation
- subdivide segments to produce hexagon maps or provide additional detail;
- display map files with the use of SPlus.

Numerous examples are provided via WWW.

4. Pathological Regions

In general the maps to which the transformation is applied have regions for which the target area is positive. However, there are regions for which this is not the case. There are also regions that we want to let float; i.e., we don't care what their areas are, or what their shapes become as long as they don't "get into trouble." We say that these regions are pathological; there is something about them that is different, non-standard, and which we must be able to handle. We discuss some of the pathologies in this section.

4.1 Regions With Negative Initial Area

These regions are special in that their boundaries are never used to construct the translation vector. Their boundaries could be entered as non-boundary points, and they would be mapped to wherever the transformation takes them. However, it is more natural to leave them as regions in the map because they are used by the associated mapping programs described in Section 3.3. For the maps that we are interested in there are two regions that fall into this classification.

4.1.1 External Boundary

For all the examples presented in this report, the first region appearing in the file RLInt.dat is really the sum of all the subregions. This region furnishes a total region area and an external boundary. The total region area is preserved as the map is transformed. This is true only if the target areas in the input file have been scaled to preserve total area. The maps that we consider in this report have that feature. This scaling is a way of controlling the map size and ensuring that the spread in target areas is not too great; some areas shrink and some grow in size.

As long as the transformation is proceeding correctly, the external boundary will be identical to that obtained from the outer subregions. If the map is badly distorted this may not be the case, and this discrepancy will be visible in the final map. Also, the total area of the subregions should be the same (in absolute value) as that of the external boundary. If the map deteriorates in quality the sum of the subregion areas will begin to differ from that of the external boundary. Describing the boundary of this region in clockwise order implies that the area is negative.

4.1.2 Holes

Holes include both holes in land regions (lakes) and holes in water regions, which are islands. Holes can be nested, for example an island in a lake, or a lake in an island.

A hole in a region can be represented as a separate region with negative area (with boundary described clockwise). However, this means that to get the proper region area this negative area must be subtracted from the total region area. Presently, this is not done by the program; so there would be a problem if the hole were furnished this way.

One way to place a hole in a region is to define a region with a cut. We have shown, how this can be done in Figure 42, "How to Use a Cut for Generating a Doughnut Region," which is in Appendix B, Section B.2.1 of this report. When this is done the line integral along the cut cancels, the area of the regions is correctly represented, and the hole has boundary points that represent the inner boundary of the region. In principle, there is no problem with furnishing a number of holes. In practice, we have to be

conscious of the fact that these holes have the possibility of drifting on top of, or into, one another. The holes have separate boundary points which are the inner boundary points of the region. There is no coding in the current version of RLInt to ensure that these boundaries do not overlap as they are transformed.

4.2 Zero Population Land Areas

The algorithm described in reference 9 requires a magnification coefficient calculated as

$$(M-1) = \left(\frac{\text{current region density}}{\text{target region density}} - 1\right)$$
 In the maps we need to consider there are land

areas for which the target region area (i.e. the population) is zero and the target region density is infinite. In order to avoid this problem we have defined instead

$$(M-1) = \left(\frac{\text{target region area}}{\text{current region area}} - 1\right)$$
 Zero target area is accepted as valid input to the program. If the current region area happens to go negative while shrinking to zero

program. If the current region area happens to go negative while shrinking to zero we penalize it in the HSum function by including it in the error result. The

magnification coefficient
$$(M-1) = \left(\frac{\text{target region area}}{\text{current region area}} - 1\right)$$
 is undefined for regions

with current area and target area both zero. Problems are avoided by using a small positive value instead of zero in the denominator if the current region area is zero.

4.3 Water Areas (target area unspecified)

Since our maps are of real geographical areas, we have to be able to handle regions such as lakes, or those which behave in the mapping as lakes. We call these regions water areas. If they are small, one may choose to specify the target area as zero, exactly like unpopulated land areas. For larger water areas it is preferable to leave the area free to float, which is done by providing a negative target area. Such areas are mapped, but they do not enter into the calculations. They are simply pushed around and fall where they fall. Their areas are calculated, locally, and have whatever values they have. However, as long as they do not "get into trouble," they are ignored. They can have a problem if their boundaries intersect or if they turn upside down; in the latter case, their calculated area changes from positive to negative.

Note that when the region areas are added up to get the total area, no account whatsoever is taken of the water areas. If a water area is not included in the region, or total area, it will stay not included. If it was included in the original region area data, it will not be taken out. These areas are ignored, except for being mapped. They could alternately be mapped as non-boundary points. Again, as with holes, there is the possibility of them going partially or completely out of their region, or overlapping with other water areas.

4.4 Areas With Present Area Negative

Normal regions (those other than holes and the external boundary) are described counterclockwise in the initial map, so that their initial area is positive. It is possible, in the course of mapping, that their area becomes negative. If this should happen, they continue to be mapped, but the present version of RLInt no longer uses them in constructing the translation vector. They do not enter into the calculation of the RMS function; however, they are included (penalized) in the Hsum function. Should these regions again become positive in area, they are re-included in the construction

of the translation vector. As we discuss in Section 8, "Future Work Required" the program should be modified later to prevent normal regions from going negative. Additionally, regions with either positive or negative area can have intersecting boundaries, which are illegal. Currently no check is made to trap and correct this illegal mapping.

4.5 Islands and Inlets

In the course of mapping, it is possible for islands to overlap each other, or for land areas on two sides of a narrow inlet to overlap each other. If this occurs, it can be prevented by filling the intervening water area with triangles and requiring that no triangle have negative area.

5. Illegal Boundary Crossings and Negative Magnifications

5.1 The Problem

The line integral algorithm that we have implemented in program RLInt has the potential to distort maps to the point that regions have boundaries that cross upon themselves, or in the worst case the regions fold over completely and the areas are definitely negative. In the maps that we transform, regions will always have target areas that are positive, or possibly zero; there are no negative target areas. Thus, a

region for which the magnification $M = \left(\frac{targetArea}{currentArea}\right)$ becomes negative is not

properly defined. It once had a positive magnification, but during the mapping process it was mapped into a region with a negative area. Also, before reaching that stage it is possible that a region has boundaries that cross. We show such a region in Figure 1, "Illegal Region."

In this figure on the left we show a region that is legal and on the right the same region after it has pushed into illegal configuration. note that the region has a boundary segment, 5, that crosses another boundary segment, 3. The total area is positive, but the small triangular area at the top traversed in clockwise direction and the area contribution line segment subtracts from the total Ιn area. effect the region's is the area algebraic sum of

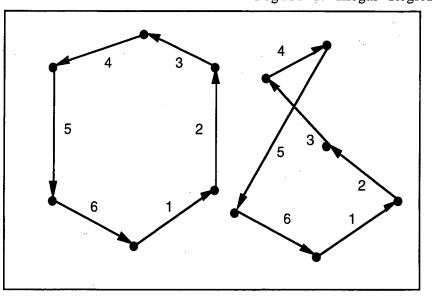


Figure 1. Illegal Region

positive and a negative area. We can see from the above picture that the present area (and hence the magnification) can go negative, even without the whole boundary of the region folding over.

We discuss below in Section 8.3.1, "Illegal Boundary Crossings," what one might to do to prevent this type of mapping. Presently illegal boundary crossings are not detected, except by visual examination of the resultant map. The examples shown in this report have some regions in some of the maps that do in fact have such illegal crossings.

5.2 A Modified Algorithm

The problem of illegal boundary crossings and negative areas arises from two different aspects of the mapping. The first, and probably the most important, is the fact that this is a discrete representation of a continuous mapping. It is discrete in that the boundaries are represented by a finite number of boundary points. We ignore the missing boundary points and assume that these points are connected by straight lines. This representation permits the evaluation of the line integral in

closed form, but it does not really represent the boundaries of the regions. One solution is to furnish more boundary points, which greatly would increase the calculation time.

Another aspect of the mapping that we have discretized is the mapping step. In principle, the transformation from the initial map to the final map is continuous. This continuous transformation has been replaced by a finite number of steps. In the original Russian mapping algorithm the interval was sudivided into equal steps, 10 or so. As is shown in Section 7.2 of this report, it turns out in practice that the full step, fixed point, mapping converges more quickly than the Russian algorithm in those cases where it can be applied without leading to boundary crossings or negative areas.

Our investigation of the properties of this integral mapping has shown that when applied to a simple circular region, it generates too strong a push for points near the boundary, inside and outside. For the case of a circle, the correct push can be simply calculated by knowing what the final area of the circle must be. We have tried scaling the displacement vector so that the push inside the circle, and on the boundary points, is exactly correct in the case of a circle. This scaling is discussed in Section 7.1 of this report.

The push from a particular region depends primarily upon its area. One can construct a circle having the same area and centroid as the polygon. We define R to be the radius of the circle, and r to be the radial distance of the point being pushed.

Inside the circle the correct scaling factor is $\frac{(2\sqrt{M}-1)}{(M-1)}$, which has been verified

both theoretically and experimentally. For points inside the circle (r less than R) the scaling factor does not depend on r or R. For points outside, the correct scaling factor is

$$\frac{\sqrt{(r^2 + R^2(M-1))} - r}{R^2(M-1)/(2r)}$$

See Section 7.1, "Circle Expansion With and Without Scaling," for a discussion of these scale factors.

We have not investigated the effect of using this modified algorithm. The present version of RLInt could easily implement this scaling. Should the input data structure be changed from polygons to boundary line segments (DIME format) it might require a little more work to apply this type of scaling.

For real problems with a large number of polygons and a large number of iterations the scaling does not make much difference. In most of our work we choose to ignore it for reasons of comparability with the implementation of reference 9.

6. The LBNL Implementation of the Russian Algorithm

6.1 Overview of the LBNL Implementation

At LBNL the Fortran program RLInt (Russian Line Integral) is a straightforward implementation of the cartogram mapping described in reference 9. The derivation of the area integral that generates the mapping is described in Appendix A, "Integral Transformation and Correction Factors," of this report. Appendix A also shows how this area integral can be replaced by line integrals around the boundaries of the regions that make up the map. This line integral representation is what has been implemented in RLInt.

For the purpose of understanding the LBNL implementation of the mapping algorithm it is convenient to consider the original map to be a region D that is composed of N subregions D_k . We thus have that $D = \sum_{k=1}^{N} D_k$. We assume that the

regions do not overlap. In each region we have a current quantity and a target quantity. The object of the transformation is to change the regions D_k so that after the completion of the mapping the current quantities are the same as the target quantities. In the original Russian algorithm the quantities used were the current and target densities of the subregion, respectively ρ_k and ρ . We choose to represent the mapping coefficient (M-1) as $(A-A_k)/A_k$ rather than $(\rho_k-\rho)/\rho$ because the target density ρ is undefined for a region of zero target area, i.e. zero population.

In principle the transformation that takes the map from its original configuration to its final configuration is continuous. This is not the case for the numerical implementation of the mapping, however. The discrete transformation, as given in reference 9, divides the transformation into equal steps. For example 10 steps might be used. In that case the transformation is generated and only 1/10-th of the transformation is applied on the first step, then the image from that application is used to generate a new mapping and for that mapping 1/9-th of the transformation is applied. This is repeated until the full number of steps, 10 for this example, has been taken. After that, fixed point iterations are applied until the difference between the current region quantities and the target quantities is less than a prescribed error. By fixed point or full step iterations we mean that the full transformation is applied. In this report we refer to a mapping where the step sizes are (for example) 1/10, 1/9, ..., 1/2, 1, as the Russian algorithm.

A close examination of the results obtained when this algorithm is applied to test regions has caused us to incorporate some optional modifications to the Russian algorithm. In particular, we have the option of scaling the transformation so that it correctly maps (in a single full step) the interior of a circular region. See Section 7.1 "Circle Expansion With and Without Scaling." We have also found it useful to choose an optional fixed size subdivision of the mapping step. We have chosen 1/2 as a convenient, suitable value. For this type of subdivision and 10 transformation steps, we would take for each step exactly 1/2 of the generated transformation. In this report we refer to a mapping where the step sizes are 1/2, 1/2, ..., as the binary algorithm.

The results of applying these different mappings are described in Section 7.2.2, "The 44-Region Vermont Hexagon Map," of this report.

The transformation that we have implemented is global in nature, meaning that the transformation applied to any point in the map depends on all the other points in the map. In principle, one would have to do the area integral for each region and apply the result to all the points in the map. The fact that the area integral is represented by a line integral around the region boundaries means that one needs to map only the boundaries. Furthermore the boundaries are represented by line segments, so in practice only the line segments need be mapped. In practice, what we really transform are the end points of the line segments. We calculate the mapping transformation from the line segments that have these endpoints, then we map only the end points to new positions. The simplifying assumption is made that straight line segments between these new end points represent the correct new boundary; these are used to generate the transformation for the next step in the discrete mapping.

We have put into RLInt the ability to map arbitrary points; i.e., non-boundary points. If these points coincide with the end points of the boundary segments, they are mapped exactly as the boundary points. If they are anywhere else in the map, they will move to wherever the transformation takes them. The maps to be transformed have such non-boundary points that we wish to keep track of. The only difference of these points from the boundary points is that they do not generate any of the map transformations; they do not push on other points.

The mapping algorithm as described in Appendix A has some numerical limitations. The basic problem is overflow during the calculation of the analytic function that gives the line integral along one of the boundary segments. The length L of the segment, and also the distance of the mapped point z from this line segment, cannot become too large. The limit on these values depends on the computer that is being used. To avoid these problems the map is scaled to the unit square (|x| <=1, |y| <=1). This scaling is done automatically by the program and it can be applied to all the input maps. Thus, large maps are shrunk and small maps expanded. This allows the program to work within a predefined range of numerical values.

6.2 Logical Structure of Program RLInt

The program RLInt consists of a main program, RLInt, and a mapping subroutine rtrans. It also has two housekeeping subroutines: one that writes files and one that deletes files.

The main program RLInt reads parameter data and map data from disk files. It initializes program variables and then calls the subroutine rtrans to perform the transformation that takes the initial map to the final map. Upon completion of this mapping task it writes requested reports and then exits.

The subroutine rtrans is the LBNL implementation of the Russian line integral algorithm. The basic inputs to rtrans are: the number of regions, the end points of the segments that define the boundaries of these regions, the number of such points for each region, the total number of non-boundary points, the coordinates of these non-boundary points, the current areas of the regions (calculated from the boundary points), and the target areas of the regions. In addition, we specify the desired error to be met, the number of transformation steps to apply, the type of transformation step (Russian or binary), and the number of fixed point full step iterations to perform.

The data are read and rtrans performs the requested mapping. Upon completion of the mapping, the program returns the transformed map. In principle, the returned

map is suitable as an input map that can be used to continue the mapping. This, of course, is not done if the map has converged. However, it is possible to stop after a specified number of steps, then use the intermediate map as a starting point for continuing the mapping.

As it performs the mapping sequence, rtrans can write reports about the intermediate maps. It also keeps track of badly distorted regions and can generate a history of the discrete mapping steps. These reports and history are controlled by parameters that are specified in a parameter file, as are the number and type of iterations and the scaling of the mapping function.

Calculating the full step transformation is straightforward. The k-th region, with N_k boundary points, is D_k (k = 1, 2,..., N). The i-th boundary point of D_k is z_i^k ($i = 1, 2,..., N_k$). The transformation vector Δz_i^k for this point is the sum of the line integral contributions from all the segments that make up the boundaries of all the regions. See Appendix A.3, "Line Integral Evaluations," which describes the evaluation of the line integral along these line segments. In an identical way, the subroutine also constructs transformation vectors for all the non-boundary points, if there are any.

At this point, we have the original map points z_i^k and the transformation vector Δz_i^k for each of these points. At each step of the iteration, the present area of each region is available. Before applying the transformation, all current region areas are compared with the target region areas. If the map has converged (i.e., if the global error criterion for the final map has been met) then the transformation is not applied; the subroutine considers the current map to be the last map in the sequence so it exits, returning control the calling program.

The calculation of each transformation vector Δz_i^k requires the value of the line integral around all the boundaries of all the regions. The current area of each of the local regions is also calculated as described in Appendix A.5, "Calculation of Region Areas." These areas are used to check whether the error criterion has been met. At this stage, we have the current map and the transformation vectors that produced the map from the preceding map. It is thus possible to go back one full step any time during the mapping process. This can be useful, as we will see below, in the discussion of the results.

This subroutine's primary task is to construct the transformation vectors and perform the discrete transformation mapping of the furnished maps. It also writes intermediate reports as requested, and checks on the convergence criterion. Optionally (if scaling is requested) it scales the input map to the unit square, and upon exit unscales the resultant map so that it will have the correct values for the boundary point coordinates and transformation vectors, along with the correct areas.

6.3 Program Options

The program RLInt has a number of parameters that allow the user to select different options for a given run. RLInt has two input files, RLInt.par and RLInt.dat. If desired, there can be some input from the terminal to control the program calculation. The file RLInt.par is a parameter file that allows the user to set the available program options. In the following sections we describe these option parameters. Appendix B, "Description of RLInt I/O Files," includes complete examples of the files RLInt.par and RLInt.dat. Both files are read using FORTRAN list directed

read statements. A fuller explanation of how that effects the data input is given below in Appendix B.

We will now list and describe the available parameters.

Additional program options implemented in late 1994 are described in Reference 13.

6.3.1 Transformation Iterations:

There are two iteration loops in the discrete mapping. The outer loop is the number of fixed point iterations. The inner loop is the number of mapping steps in the transformation. In real time the inner loop is completed first: the transformation is divided into a specific number of steps; then at the end of these steps there are applied a specific number of fixed point iterations.

The two parameters that control these loops are:

As an example let maxit = 5; then the transformation is divided into 5 equal steps. This means that the transformation vector is applied 5 times to transform (the initial) map 0 into map 1 $(0 \to 1)$; then $1 \to 2$, $2 \to 3$, $3 \to 4$, and $4 \to 5$. The fraction of the full transformation vector that is applied at each step depends on another flag which is described below. The parameter maxit simply tells how many times the inner transformation loop is executed.

If maxit0 = 3, then after applying 5 (maxit) transformations, 3 fixed point iterations are applied. For each of these iterations the full transformation vector is applied to get maps 6, 7, and 8. These three fixed point full step mappings perform the steps $5 \rightarrow 6, 6 \rightarrow 7$, and $7 \rightarrow 8$.

The total number of iterations taken is the sum (maxit + maxit 0). We assume in this example that nothing has caused the mapping to stop before completion of both loops. The mapping will stop prior to this limit if convergence is achieved. If maxit 0 = maxit = 0, then the final map is the initial input map; no mapping is performed. This is useful for checking the input map data.

The parameter itstp can be used to stop the program before the completion of the two loops. Setting itstp=1 will force a stop after exactly one iteration, in this example one transformation iteration. If instead itstp = 7, exactly 7 iterations will be taken: 5 transformations followed by 2 fixed point iterations.

6.3.2 Controlling the Type of Transformation Step

The transformation mapping can be done in two different ways. One method (used in reference 9) is to divide the transformation into maxit equal steps. In this case the first mapping applies $1/(\max it)$ of the transformation vector. In the next step, it uses $1/(\max it-1)$, and then $1/(\max it-2)$ until on the (maxit)th step it uses 1/1 to arrive at the final point in the sequence of mappings. The step size ci for iteration it is $1/(\max it-it+1)$.

The other choice is to again perform the transformation mapping in N steps, but at each step take exactly 1/2 of the current transformation vector to arrive at the next map in the sequence.

These choices are controlled by the parameter

```
iciset 0 step size = 1/(\text{maxit} - \text{it} + 1), (it = 1,2,...maxit)

1 step size = 1/2, (it = 1,2,...maxit)
```

Note that this choice only applies during the execution of the inner transformation loop. After maxit transformations have been taken, maxit 0 fixed point iterations will be taken with step size ci = 1/1.

6.3.3 Type of Integral Scaling

Two types of scaling are available when evaluating the line integral contribution from the boundary segments. See Section 7.1, "Circle Expansion With and Without Scaling," of this report. The original algorithm, as given in reference 9, we call unscaled; the LBNL version of the algorithm, with the scaling coefficient $2(\sqrt{M}-1)/(M-1)$ we call scaled or HH. M is the current subregion magnification, equal to (target area/current area).

The parameter that controls this scaling is:

iscale -0 line integral unscaled

1 line integral scaled

6.3.4 Map Scaling

Calculation of the line integral along a boundary line segment can produce results that exceed the numerical precision of the computer being used. This happens in calculating a quantity that depends on (a) the length of the current boundary line segment and (b) the distance of the mapped point from the line segment. The problem can be avoided by optionally scaling the map to the unit square (|x| < 1, |y| < 1). The scaling is with respect to the origin (x = 0, y = 0) rather than the map centroid; this is not a problem for maps that are approximately centered about the origin. The scaling is internal only and is not reflected in input or output files.

The parameter that controls this scaling is:

iara 0 no internal map scaling, possibility of overflow failure 1 map scaled internally so that |x|<=1, |y|<=1.

6.3.5 Transformation Reset

As the transformation is applied there is the potential of creating badly distorted regions: in particular, regions with negative areas or with boundaries that cross upon themselves. This has led us to include a parameter that allows us to optionally back up one complete step and continue again from that point in the mapping sequence. The criterion for applying this reset has not been selected, and the algorithm that is to be applied after resetting the transformation has not been decided upon. Thus, in the file RLInt.par the parameter ireset should not be changed from its default value of 0. The present version simply excludes the regions that have a negative area when calculating the transformation vector and does not include them in the RMS function error calculation. (The Hsum function never includes regions that have negative (unspecified) original area. However, it does include the regions for which the area goes negative; i.e., it penalizes these areas. See Section 6.4, "Convergence Criteria."

The parameter that controls the reset is:

ireset 0 Negative areas are skipped and do not push.

Negative areas cause a resetting to the top of the iteration loop, acting as a new initial value of the map points. This sets the points back to the values they had at the previous iteration and then starts the iteration outer loop exactly like the initial entry. NOTE: the value

of itstp used to stop the program is the total number of iterations done. If a reset happens, the iteration counter in the program, it0it, is not reset and the program will stop when itstp iterations have been completed. Thus, setting itstp to a positive value is a way to ensure that the program will not forever reset and continue to iterate.

6.3.6 Output/Reports

There are a number of print options for this program. Some of them control output to the standard output device, input from standard input, and the creation of files during and at the end of the current run. The output files will be described in the next section. We give a short summary of the I/O parameters and then list the parameters with a short summary of their function. A detailed description of these files is given in Appendix B, "Description of RLInt I/O Files." A complete example is given in Appendix C, "Example of Complete Run I/O." In the following summary, the symbol * refers to files associated with the program flags. It is not the symbol for any text string. When files are deleted, only the files written by the program RLInt are deleted; no other files are deleted.

Summary of icheck, idisk, isum, inow

- icheck Information for tables is stored internally; files containing tables are written at the end of the run. Files: RLInt.out.sum, RLInt.out.plot
- idisk If idisk > 0, one set of files RLInt.*.NNNN is written after every idisk iterations. NNNN is the iteration number. Files: RLInt.out.NNNN, RLInt.sum.NNNN, RLInt.plot.NNNN. If idisk = 0, files RLInt.out and RLInt.plot are written after the last iteration.
- isum If idisk \neq 0, a summary file is written which contains information for each region. The information in this file is for the same iterations selected by idisk. It is written after the last iteration. File: RLInt.sum
- inow If inow > 0, after every inow iterations two files are updated that contain the current iteration information. Each update overwrites the previous information. Files: RLInt.out.now, RLInt.plot.now

Parameters icheck, idisk, inow are independent; isum is a summary for the files selected with idisk, and is written only when idisk is set to write files.

List of I/O parameters and their function:

- iprint controls the amount of information written to standard output. iprint is basically a simple tool to see what is happening.
- iprint = 0 no output is written.
 - > 0 print information from the top and bottom of the fixed point and transformation loops. Helps to track the mapping iterations,
 - > 1 print some loop information
 - > 5 print a list of skipped regions on stdout.

- itable = 0no tables printed (tables are from internally saved results)
 - print tables and all input data points; all mapped points = 1 after the mapping is done.
 - print tables, but no input points, no mapped points = 2
 - print tables and an additional plot table; no input points, >= 3 no mapped points
- in rtrans, do not save results for printing itable tables icheck 0
 - 1 do save results

This saving of results takes space and time. For small maps it is convenient to save and see the convergence, etc. For large maps the space required can be excessive. When = 0 there are no results to print in the corresponding tables, so the program will not print these tables.

If itable >= 1 the information written will be on files: RLInt.out.sum RLInt.out.plot

To get these files, the results must be saved with icheck; then the files must be printed with itable>=1.

NOTE: To save space and time set icheck = 0 and idisk=1. The files written to disk at each iteration can be used to construct tables and plot maps. Alternatively, the inow flag can be used to get a dynamic set of files, updated at selected iteration steps.

If this is done, the parameter statements that reserve storage

```
parameter (jjmax = 60) ! save up to jjmax iterations
parameter (ddmax = 280)
                         ! save up to ddmax regions
parameter (aamax = 3000) ! save up to aamax boundary points
parameter (bbmax = 10) ! save up to bbmax boundary points
```

can have minimum values when the program is compiled. If icheck>0 it is necessary that the above statements define values large enough to save the results. When saving data the values of ddmax, aamax, bbmax cannot be exceeded. However, the value of jjmax can be exceeded; the program simply start writing over the already stored information. In the example above with jjmax=60, if 70 iterations were taken, only iteration 0 and iterations 11-70 would be available for the tables.

After completing the call to rtrans the following files are idisk 0 written:

> RLInt.out can be used as an input file RLInt.dat continuing the mapping.

> RLInt.plot a comma delimited file that can be used to plot mapped points.

> > 25

NO intermediate disk files *.NNNN are written; no final summary file RLInt.sum (isum = 1) is written.

idisk >0 If iteration NNNN is a multiple of idisk, write files *.NNNN:

RLInt.out.NNNN current state of map, suitable as RLInt.dat for a subsequent run

RLInt.plot.NNNN comma delimited file suitable for plotting maps.

RLInt.sum.NNNN summary file of convergence, areas, etc.
RLInt.sum summary file for complete run (isum = 1)

NNNN is the iteration count. the sum of it+it0. For example,

NNNN = 0000 initial values, same as input data

NNNN = 0001 after 1 complete iteration

There are 3 files:

RLInt.out.NNNN

RLInt.plot.NNNN

RLInt.sum.NNNN

for each iteration. The information in these files can be used to construct maps or tables.

<u>idisk</u>	Write after these iteration
1	0, 1, 2, 3,
2	0, 2, 4, 6,
3	0, 3, 6, 9,
: -1	iteration 1 only
-2	iteration 2 only
-3	iteration 3 only

These files are opened, written, and closed within the program. Thus, they are available after each iteration for use by other applications running in parallel with RLInt.

isum 0 no output summary file is written.

1 summary file RLInt.sum is written.

For each region the file RLInt.sum has information for all iterations. The files RLInt.sum.NNNN have information only for iteration NNNN. The isum=1 option is useful if it is desired to see what happens to the regions as the iteration proceeds. If there are a lot of regions, and a lot of iterations for which output is requested, this file can be rather large. The iterations recorded are the same iterations NNNN as for the idisk flag. This file is written only when idisk output is written.

inow 0 no dynamic output files written

>0 write files

RLInt.sum.now

RLInt.out.now

RLInt.plot.now

These files contain the current map information, the same as on the RLInt.*.NNNN files. However, these files are rewritten after every inow iterations, starting with iteration 0. The writing of these files is completely independent of the files written with idisk. The idisk files can be saved for future use. The inow files are updated as

the run progresses; at the completion of the run they contain information from only the last iteration.

nfdel <0 NO files are deleted

NNNN

Delete all output files written from a previous run, including files *.0000 through *.NNNN. This was put in because it can be confusing to know what files the program has created. If the *.NNNN files are meant to be saved, they should be moved somewhere else or renamed. This is an inclusive delete of all files in the range. Only files written by program RLInt are deleted. There is no problem if the files do not exist.

iprmpt 0 no interactive prompting during the run

≠0 Interactive prompting to check data before doing the transformation

6.4 Convergence Criteria

6.4.1 Relationship Between the RMS and Hsum Functions

The current version of the program RLInt uses a root-mean-square error criterion for determining when the mapping has converged. In the output and elsewhere in this report we refer to this quantity as the RMS function. The RMS function is defined to be

$$RMS = \sqrt{\sum_{k=1}^{N} \frac{(M_k - 1)^2}{N}}$$

where N is the number of contributing regions and M_k is the subregion magnification which is defined as (target area)/(current area) of the region k. Regions that have negative magnification do not contribute to RMS function, nor do permanently skipped regions. The only regions that contribute are regions that are used to construct the transformation vector.

The mapping coefficient for the line integral that generates the transformation vector contains the quantity (M_k-1) . The size of the transformation vector generated from a particular region depends on this coefficient and also on the area of the region. The current definition of the RMS error function ignores the size of the region.

A more suitable quantity that includes the size of the region is what we refer to as the h function: or Hsum in the program output and the text of this report. This Hsum function was used as a measure of convergence in reference 8. At present it is not used as a convergence criterion in RLInt. However, it is calculated and printed along with the value of the RMS function. For the well-behaved maps that we have used as examples, the behavior of Hsum as a function of the number of iterations is qualitatively the same as that of the RMS function. The value of the RMS function after convergence reflects the numerical precision of the calculation. The Hsum function is approximately equal to the square of the RMS function. Thus, the Hsum function will indicate $\approx 10^{-10}$ when the RMS function gives $\approx 10^{-5}$.

The following definition of Hsum is used in the present version of RLInt. There are three cases that determine the evaluation of the local value h_{ν} for the region D_{ν} that

contributes to HSum. The function $HSum = \sum_{k}^{N} h_{k}$, where this sum is over all contributing regions.

Case 1. The final target area $A_f^k > 0$ (land areas, with population > 0)

$$h_k = \left(\frac{A_f^k}{A_{tot}}\right) \left(\frac{A^k - A_f^k}{A_f^k}\right)^2$$

where A^k is the region current area, and A_{tot} is the total initial land area, the sum of all the land subregion areas. In the input data, we normalize the target areas A_f^k so that $\sum_{k=1}^{N} A_f^k = A_{f,tot} = A_{tot}$ (total target area = total initial area)

Case 2. The final target area $A_f^k = 0$ (land with zero population; i.e., with target area fixed at zero)

$$h_k = \left(\frac{A_f^{\min}}{A_{tot}}\right) \left(\frac{A^k}{A_f^{\min}}\right)^2$$

where A_f^{\min} is the minimum nonzero target area A_f^k , among all regions k. (Specified target areas A_f^k are never negative.)

Case 3. The target area $A_f^k < 0$ (water polygons of unspecified target area)

$$h_k = \left(\frac{A_f^{\min}}{A_{tot}}\right) \left(\frac{\min(0, A^k)}{A_f^{\min}}\right)^2$$

In each case, the error h_k is the square of a relative error weighted by a fractional area. In the first case, the squared relative error is $\left(\frac{A^k-A_f^k}{A_f^k}\right)^2$ and the weight is $\left(\frac{A_f^k}{A_{tot}}\right)$. In the second case, where the target area is zero, the squared relative error is $\left(\frac{A^k}{A_f^{\min}}\right)^2$ and the weight is $\left(\frac{A_f^{\min}}{A_{tot}}\right)$. In the third case, the squared relative error is $\left(\frac{\min(0,A^k)}{A_f^{\min}}\right)^2$ and the weight is $\left(\frac{A_f^{\min}}{A_{tot}}\right)$. There is no contribution to Hsum unless the present area A^k is negative.

To summarize, the Hsum function calculates the squared relative error of the current region area, as compared to the target area, and then weights the result with respect to the fraction of the total area that the region occupies. The basic differences between the Hsum function and the RMS function are: (a) Hsum treats in a

reasonable manner regions that have a target area of zero; (b) Hsum penalizes regions of unspecified target area when their area goes negative; and (c) Hsum weights the region contribution by its area (relative to total area).

We observed above that the square of RMS function is of the same order of magnitude as the Hsum function. This follows from the above definition; there is no square root in the Hsum function. Since neither function is used for minimization, we could probably use absolute values or square roots instead of squares. However, the time spent in the calculation of these quantities is not great and they are probably better understood in their present form. Even in the domain of illegal configurations (negative areas) Hsum and its derivatives are continuous as a function of the boundary point coordinates.

6.4.2 Discussion of Machine Precision

The subroutine rtrans that constructs the mapping transformation vector is written in single precision Fortran. When run on a binary 32 bit computer such as a Sun Sparc station, the numerical precision is ≈ 7 significant figures. This is completely adequate for construction of a transformed map. However, this precision should be kept in mind.

As noted in Appendix A.3, "Line Integral Evaluations," there can be a problem with numerical overflow when calculating the line integral. This problem has been fixed by scaling the map to a unit square (|x|<=1, |y|<=1).

This scaling implies that the largest possible distance between any two map points is $2\sqrt{2}$. In the calculation there are times when we must use a numerical value that is not zero but which for all practical purposes is equivalent to zero. Since our coordinates range in magnitude from 0 to 1 and since the calculations are single precision, points closer to each other than $\approx 10^{-5}$, are assumed to concide, and areas less than $\approx 10^{-10}$ are assumed to be zero.

There is no problem in having points at the origin, with zero values. The above distance limit is on the distances between points. Target areas can be specified as zero, but to avoid numerical problems, we use the cutoff described above.

The transformation is constructed by integrating around boundaries of individual regions. When transforming a point, it is necessary to determine whether it lies on a boundary segment. This is done by measuring its distance from the boundary points that define the ends of the current line segment. Presently we check only the end points of the segment. When the distance is less than 10^{-5} the points are assumed coincident and the line integral is evaluated as an improper integral.

Two adjacent regions defined in RLInt.dat by two separate sets of points actually have coincident points, the ones along the common boundary. If for some reason the above check fails to identify the points as coincident, the regions will come "unglued" and can drift apart or overlap as they are mapped. This should be kept in mind if it appears that the mapping does not correctly map adjacent regions. Also, non-boundary points that coincide with line segment end points should remain coincident with these points. If they do not, then the above check is failing.

The point of this discussion is that there can be problems numerically. For the maps that we have run, the limits chosen appear to be suitable. If the precision of the calculation is other than what we have assumed, then the above limits should be

modified. These limits can be found in parameter statements in the subroutine rtrans that constructs and applies the mapping. The statements are:

parameter (zeroa = 1.0e-10) ! single precision area zero parameter (zero = 1.0e-5) ! 4-5 significant figures

There is another reason for keeping the calculation precision in mind. If the maximum coordinate (scaled) has magnitude 1 and the minimum non-zero coordinate is $\approx 10^{-5}$, then the coordinate range of integers is from 1 to 100,000. If the actual coordinate range is 1 to 1,000,000, the scaling will mean that all coordinates that are less than 10 will effectively be zero by the program. In that case a point, that had coordinates (5,5) would be effectively coincident with a point that originally had coordinates (0,0), or with a point that originally had coordinates (10,10). If a relative precision of $\approx 10^{-5}$ in coordinate distances is inadequate, it will be necessary to use a computer with an extended exponent range, or to use double precision and change the above numerical definitions of zero.

This precision also enters into the limit set for convergence of the mapping. The basic quantity in the mapping is (M-1) where M is the magnification. In single precision, there is no way that this can get much smaller than $\approx 10^{-5}$. To ask for more precision is not reasonable and will cause the mapping to generate meaningless numerical noise. The quality of the final map will simply deteriorate. One indication of this deterioration is that the current total area begins to disagree with the initial total area. This, of course, applies only to maps for which the areas are scaled to preserve the total map area.

7. Summary of Results

7.1 Circle Expansion With and Without Scaling

The integral mapping algorithm as given in reference 9 can develop problems when applied to regions composed of polygons. Polygon areas do not always converge to the right values, and they can even become negative (polygon completely or partially upside down). "Partially upside down" means that a polygon has become so distorted that its boundary crosses itself.

To better understand the behavior of this mapping, we applied it to a simple circular region of radius R for region magnifications M that covered a wide range of values. A close examination of the resulting images shows that the displacement is too great for points that are on or near the circle boundary.

The original derivation of the integral mapping is based on a mapping that is exactly correct for a circle. For this mapping, the mapped circle is required to have a radius R_f that gives the correct target area, while the exterior points are mapped in a way that preserves local areas. Following a suggestion by Harvard Holmes, we have scaled the integral formula so that it produces this same linear mapping inside the circle; that is, the mapped circle has the specified target area. We refer to this scaling as HH scaling. We then applied the scaled and unscaled integral mapping to a circle for comparison with the expected mapping.

The three mappings (expected, unscaled integral, and scaled integral) have the following form.

(1)
$$r_f = (R_f/R)r$$
 $r \le R$ within circle, expected
$$r_f = \sqrt{r^2 + (R_f^2 + R^2)}$$
 $r \ge R$ outside circle, expected

(2)
$$r_f = r + \frac{1}{2\pi}(M-1)\int \frac{\vec{\xi}}{\xi^2} dS$$
 unscaled integral calculation

(3)
$$r_f = r + \frac{(2\sqrt{M} - 1)}{(M - 1)} \frac{1}{2\pi} (M - 1) \int \frac{\vec{\xi}}{\xi^2} dS$$
 scaled (HH) integral calculation

where $r = \sqrt{x^2 + y^2}$ is the distance from the center of the circle of the point to be mapped and

$$\frac{\vec{\xi}}{\xi^2} = \left(\frac{(x-x')}{(x-x')^2 + (y-y')^2}, \frac{(y-y')}{(x-x')^2 + (y-y')^2}\right); dS = dx'dy'$$

These mappings are illustrated in Figure 2, "Circle of Radius 1 Mappings" for magnifications of M=16 and M=1/8. For each magnification we show the displacement (push) generated by the circle on the points along the x axis and also the final position of the points. In each graph are three cases which are labeled expected, unscaled, and scaled. "Expected" refers to (1) above; namely the displacement that expands or contracts the circle so as to yield the correct target area. "Unscaled" refers to (2) above (the original Russian integral as given in reference 9). "Scaled"

refers to (3) above: namely the modification of (2) that is necessary to obtain agreement with (1) for points inside the circle.

From these graphs, we see that for magnifications less than unity and points inside the circle, the unscaled mapping undershoots and the scaled mapping is correct. For points outside the circle, both formulas approach asymptotically the expected mapping. In other words, the integral mapping does not shrink the circle enough, whereas the scaled mapping shrinks the circle to exactly the right size for a given magnification. The problem is not serious for points that are far from the boundary of the circle.

Even more interesting is the behavior of the mapping when the magnification M is greater than 1. (A magnification of 1 means that there is no expansion or contraction of the circle; the image point is the same as the original point.)

For a magnification M>1, we see that the integral mapping pushes too hard: the displacements for points inside the circle are too large. Again, the scaled mapping is exactly right for points inside the circle. For both mappings, points outside the circle have, displacements that approach asymptotically the exact mapping. An examination of the graphs of the final radius shows that there is a problem with both unscaled and scaled integral mappings.

The problem with these mappings is that they fold the outer region into the inner region. This is evident from the M=16 graph. The curves show that for points outside the boundary of the circle there is a region that maps to positions interior to the image circle, and vice versa. The mapping has caused the region to fold upon itself.

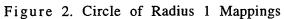
The authors of reference 9 present an algorithm that divides the mapping into discrete steps. Instead of taking a full step, as was done for the cases shown in these graphs, a fraction of a full step is taken. For example, the mapping can be divided into 10 equal steps. Then 1/10 of the distance is taken for the first step, 1/9 for the second, and so on. For large M, this ameliorates but does not really "cure" the problem. The subdivision that is necessary to avoid folding is simply too small.

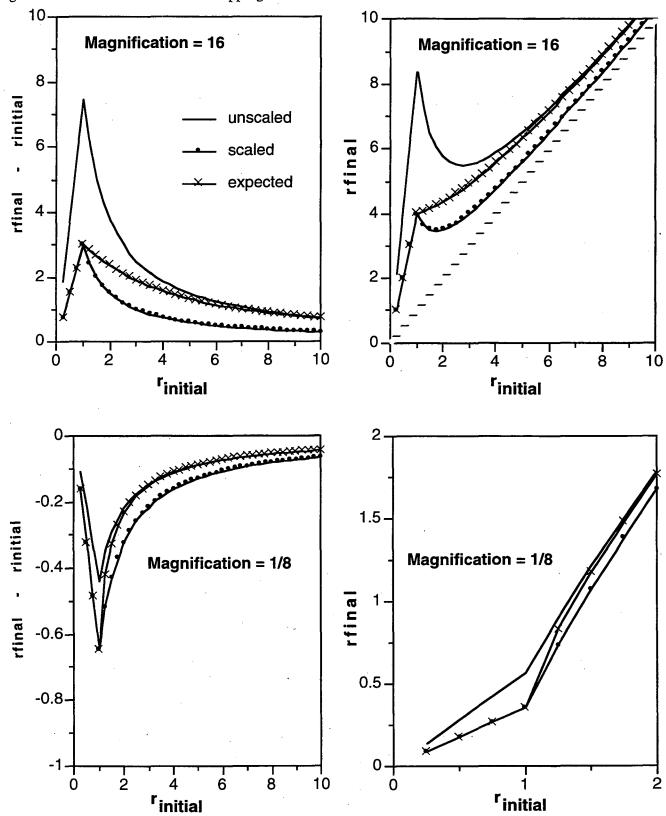
We have found that applying the scaled integral mapping to maps composed of many polygons does occasionally eliminate the extreme boundary distortions that lead to negative area, or boundaries that cross upon themselves.

We note that for points outside the circle a better correction would be an r-dependent correction which gives exactly the expected displacements, for areal magnification M of a circle with radius R. One method would be to use the local polygon area A, a quantity readily available, to calculate an effective polygon radius $R = \sqrt{A/\pi}$. This would produce an r-dependent scale factor of the form

$$\frac{r_{final} - r_{initial})_{exp\ ected}}{(r_{final} - r_{initial})_{unscaled}} = \frac{\sqrt{(r^2 + R^2(M-1)) - r}}{R^2(M-1)/(2r)}.$$

In this case r is the present distance from the center of the equivalent circle to the point being pushed that is outside the local polygon. So far we have not tried a dependent correction factor that depends upon r.





7.2 Vermont Maps

Vermont maps have been used as input to the program RLInt in order to understand the behavior of the mapping algorithm. The Vermont maps have been created at two different levels of detail: with 44 regions and 104 regions.

In each case, the regions are triangular or hexagonal subregions of the 14 counties of Vermont. In the triangular maps, each subregion is a triangle. In the hexagonal maps, each subregion is a hexagon, created by subdividing the sides of the triangle.

We discuss first the 44-region maps. Before density equalization, the (initial) map configuration is identical for the triangle and hexagon maps. The only difference is the addition of more points in the hexagon maps. In each map the entire state is subdivided into 43 smaller regions. These are identified as regions 2-44 in the example of Appendix C.

The first region in both the triangle and hexagon map is the external state boundary. This region, region 1 in Appendix C, is flagged so that it does not contribute to the generation of the transformation vector. The region 1 boundary coincides with the outer boundary of the 43 subregions. The area of the global region (the entire state) is equal to the sum of the areas of the subregions. There are no zero-area regions, no water regions, nothing that should cause any problems with either the triangle or hexagon map.

We wished to compare the convergence behavior of the triangle map to that of the hexagon map. In addition, using the hexagon map, we wanted to study the behavior of several variations of the mapping algorithm. In our tests, the number of transformations and the number of fixed point iterations were varied, while the total number of iterations was fixed at 20.

The object of the mapping is to change the area of each subregion from its present value to a final target value. In the input data file, the target areas were first scaled so that the total target area of the final map was the same as that of the initial map.

The labeling conventions of the graphs is summarized in Table 1.

Table 1. Graph Labels

Label	Scaling	Step size	number of transformation steps	no. of fixed point iterations
HH0.5.1010	НН	1/2	10	10
HH0.5.2000	нн	1/2	20	0
HH1d1.20	нн	1	. 0	20
HH1d10.10	НН	1/10	10	10
HH1d20.00	нн	1/20	20	0

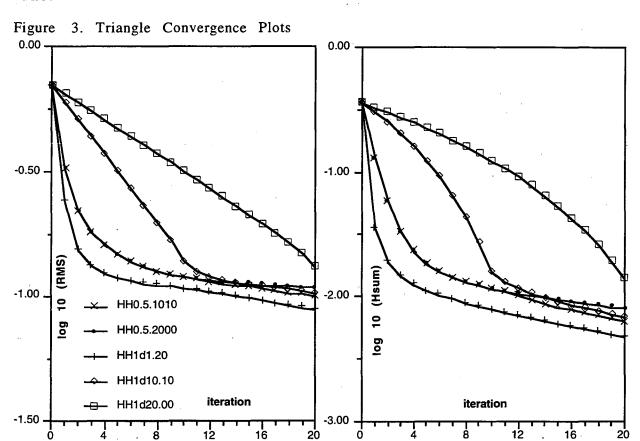
HH scaling was used throughout, as described in Section 7.1.

The step size, or transformation subdivision, was 1/2 in the first two runs. In the first run, 10 transformation steps were taken, followed by 10 fixed point iterations. In the second run, 20 transformation steps were taken. The third run had no transformation subdivision; 20 fixed point iterations, or full steps, were made.

In the fourth and fifth runs, the transformation was divided into 10 and 20 equal steps, respectively. In the fourth run, 10 transformations were applied, in which the step size was 1/10, 1/9,...,1. The remaining iterations were fixed point iterations that applied the full transformation vector. In the fifth run, 20 steps were taken, with the step size being 1/20, 1/19,....,1.

7.2.1 The 44-Region Vermont Triangle Map

The 44-region triangle map has a total of 126 subregion boundary points. Each point is shared by at least two triangles. In Figure 3, "Triangle Convergence Plots," we show the values of the RMS function and of the Hsum function, from the initial map at iteration 0 to the final map at iteration 20. The legend in the graph identifies the five runs.



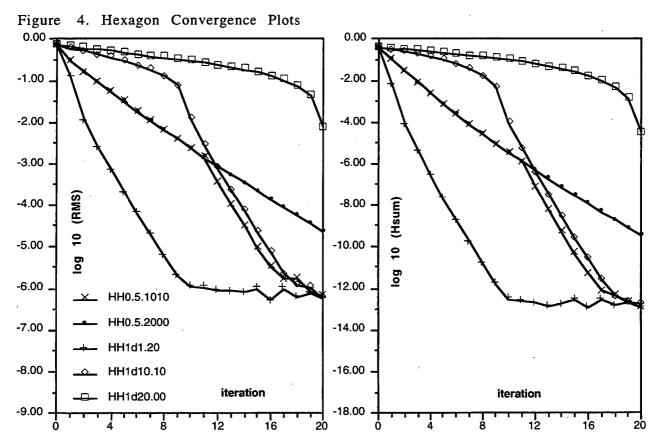
We see from Figure 3 that convergence was worst for the fifth run where the transformation was subdivided into 20 equal steps and no fixed point iterations were taken. The convergence was best for the third run, where the interval was not subdivided, and 20 full steps or fixed point iterations were taken. The other cases fall between these two.

Improvement is slow once the RMS. error reaches about 10^{-1} . Also, for fixed point iterations (the third run), most of the improvement occurred in the first 8 or so iterations. The RMS function and the Hsum function have similar behavior; the minor differences are due to the way they are defined.

7.2.2 The 44-Region Vermont Hexagon Map

In Figure 4, "Hexagon Convergence Plots," we show results for the 44-region hexagon map. The only difference between the triangle runs and the hexagon runs is the initial map. The graphs show the effect of supplying more boundary points. The triangle map is a tightly constrained problem; in the hexagon map, there are more points and therefore more degrees of freedom.

The mapping has achieved full single-precision convergence in 10 iterations. As with the triangle maps, fixed point iterations (run 3) had the best convergence, and equal subdivisions (runs 4 and 5) had the worst. Mapping with step size 1/2 (runs 1 and 2) is intermediate, as for the triangle maps. In every run, convergence improves as soon as fixed point mapping, with step size equal to 1, begins. We note that the last step in the 20-step transformation (the fifth run) is really a full step or fixed point mapping.



Comparison of Full-step vs. Equal Interval Transformations

The original Russian algorithm (reference 9) gives a heuristic argument for dividing the transformation into a sequence of partial step transformations. They make a choice of equal intervals. However, we have shown that for the Vermont maps convergence is much faster when the full transformation is applied at each step. For the simple and well behaved maps that we have used, there seems to be no reason to not apply the full step mapping; i.e., to use the fixed point algorithm.

Comparison of Equal Interval vs. 1/2 Step Transformations

We have also shown the result of using a constant step size equal to 1/2. This choice produces faster convergence than the equal interval subdivision. Of course, for the maps in question the only real benefit of 1/2 over equal-interval subdivision is that the 1/2 interval is closer to a full 1/1 step than is the equal-interval mapping.

However, in Section 7.3 we shall describe other runs where it is not possible to take the full 1/1 mapping on the first step. Taking that step causes some areas to become negative as a result of illegal crossing of boundaries. Where this problem occurs, it generally occurs during first few iterations. This can be avoided by subdividing the interval. This information has led us to use step size 1/2 for the first 2 or 3 iterations, and then continue with full step mappings.

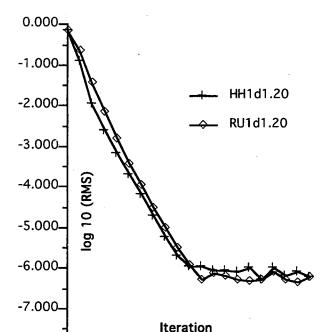
In summary, it appears that the mapping should be applied with as large a step size as possible that does not cause areas to become negative.

Comparison of Russian Scaling vs. HH Scaling

In Figure 5 below, "Comparison of HH Scaling to Russian Scaling," we compare the results with and without scaling (HH and RU respectively) for runs with 20 fixed point iterations. No significant differences are noted.

In runs with step size 1/2 (not shown here), the HH scaling has helped prevent areas from becoming negative, and it has improved convergence somewhat. The HH scaling appears to be slightly beneficial in most of the cases we have tested, and we have used it rather consistently.

In larger problems, most points are far from the boundary of any individual region. There is one in the asymptotic region of Figure 2, where the unscaled algorithm is closer to the expected than is the HH-scaled algorithm. Unless one applies an r-dependent scaling factor, which we have not done, the HH scaling should probably be avoided. In any event, the choice does not strongly affect the final solution, but only the rate of convergence.



-8.000

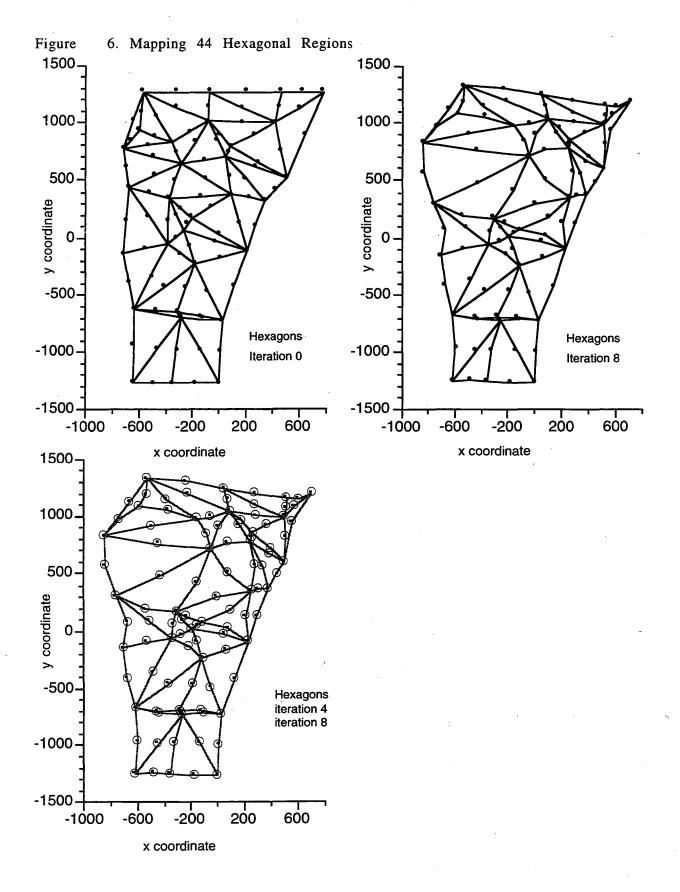
Figure 5. Comparison of HH Scaling to Russian Scaling

16

Region Maps

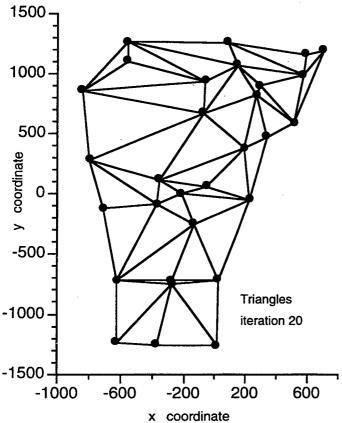
The following pages display the resulting maps for the 44-region Vermont example. The upper left inset of Figure 6, "Mapping 44 Hexagonal Regions," shows the initial boundaries of the 44 regions. There are boundary points at all the triangle vertices and at the midpoints of the triangle sides. Superposed on the map is the region 1 boundary, the boundary of the entire state.

The upper right inset shows the map after application of 8 fixed point iterations, with HH scaling. This map has fully converged, within the limits of single precision computation. In the lower inset, we show the final map after eight iterations. Superimposed on that map is the result after four iterations. For all practical purposes, the two maps are identical. The fact that the dots and circles do not exactly coincide is due to the resolution of the printed graph. Expanded views show agreement of the coordinate values to approximately three significant figures.



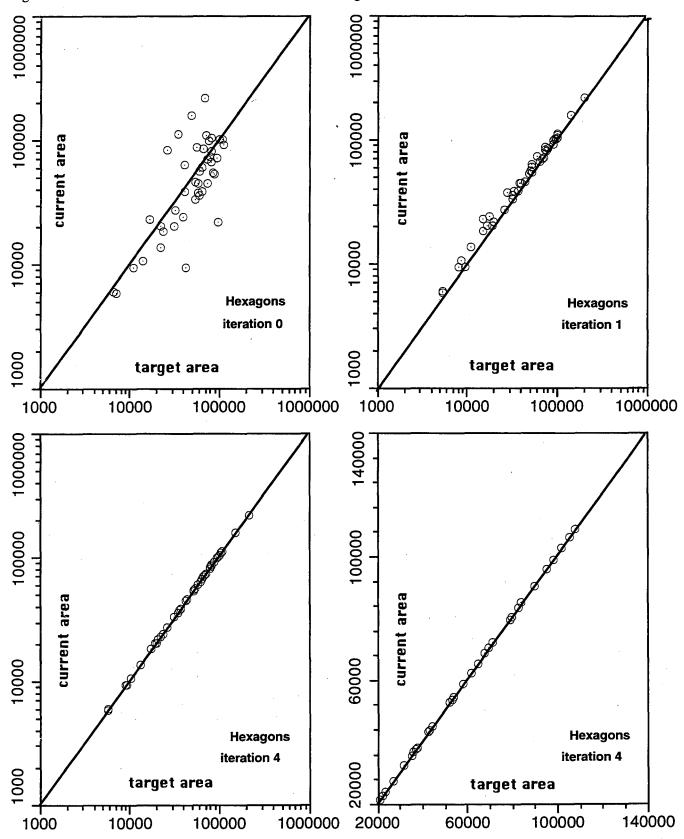
In Figure 7, "Mapping 44 Triangular Regions,," we show the same 44-region Vermont map after 20 fixed point iterations. The only difference between the hexagon maps of Figure 6 and the triangle map of Figure 7 is the initial map; the points in Figure 7 do not include the midpoints of the triangle sides. As we saw in Figure 3, the triangle map does not fully converge; final values of RMS are around 0.1. In Figure 7 the region boundaries are, by necessity, straight lines. The hexagon map of Figure 6 has more degrees of freedom and converges to an RMS value that is zero within single precision machine accuracy.

Figure 7. Mapping 44 Triangular Regions



In the next graph, Figure 8,"Scatter Plots of Current Area and Final Area," we plot as a scatter plot the target area along the x axis and the current area along the y axis. The top two graphs are for the initial map, iteration 0, and the map after exactly one fixed point mapping. The lower left graph shows the results after four fixed point mappings. We show in the lower right graph and expanded range of the map at four iterations. The fourth iteration is quite linear in the plot, the points do lie on the line but the printing resolution shows them slightly off of the line. The RMS function at four iterations is $\approx 10^{-3}$, which gives about 3 significant figures for the region subareas.

Figure 8. Scatter Plots of Current Area and Target Area



The final graphs of this section, Figure 9, "Convergence of the Hexagon Mapping," show that the map was fully converged at the 8th iteration. We have plotted here the average, over all 44 regions, of the absolute value of the magnification error for each step in the iteration. The standard deviation of that value is also plotted. In the top graph, we plot the standard deviation, as scaled by the size of the average. We see that there is a distinct dip at 8 iterations. Further iterations cause a spread in this value. The iterations past 8, on this particular map, generate noise. This can also be seen in the above plots of the RMS function and the Hsum function. Further convergence also tends to destroy the accuracy of the total area, as obtained by adding up all the subregions. All of this indicates a deterioration of the quality of the map. To summarize: it is detrimental to the quality of the map to attempt to converge past the inherent accuracy of the algorithm.

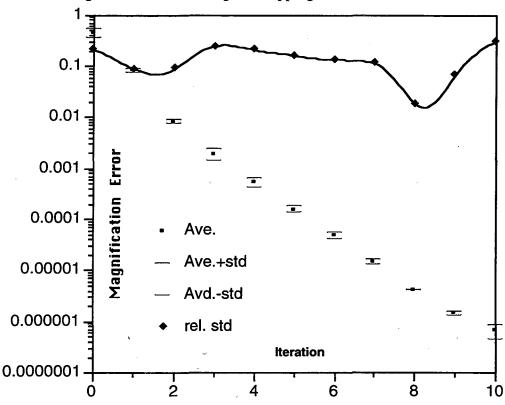


Figure 9. Convergence of the Hexagon Mapping

7.3 Runs on 44- and 104-Region Vermont Hexagon Maps

We present in this section results from RLInt runs on Vermont hexagon population maps. There are two basic maps; a 44-region map and a 104-region map. These two maps are essentially the same, except for the different number of regions. They are referred to as hexagon maps because each of the subregion triangles has 6 boundary points, 3 vertices and each side has a midpoint.

For each map there are seven population categories. These are referred to as:

- 1. pop80 = total population: white + black + asianpi + indian + other
- 2. white = white population
- 3. other = pop80 white black asianpi indian
- 4. spanish = hispanic

(includes some members of all 5 races: white, black, asianpi, indian, other)

- 5. asianpi = asian and pacific islanders
- 6. indian = american indian, eskimo and aleut
- 7. black = black population

The initial map in each of these seven categories is the same basic 104-region, or 44-region, map. The target areas are adjusted to reflect the map category. The maps, as listed above, are in the order of increasing non-uniformity of the initial population density, *i.e.*, deviations of initial area from the target area. This is reflected in the value of the Hsum function and can be seen in the scatter plots shown below. In he Table 2 below the initial values of the RMS and Hsum functions for these seven cases are shown.

Table 2. Vermont Hexagon Map RMS and Hsum Function Values.

Category	log ₁₀ (RMS) 44 Regions	log ₁₀ (Hsum) 44 Regions	log ₁₀ (RMS) 104 Regions	log ₁₀ (Hsum) 104 Regions
pop80	-0.153	-0.446	-0.191	-0.324
white	-0.156	-0.450	-0.194	-0.327
other	0.053	-0.040	0.009	-0.034
spanish	0.061	0.064	0.049	0.140
asianpi	0.228	0.121	0.161	0.196
indian	0.161	0.164	0.086	0.201
black	0.164	0.207	0.104	0.286

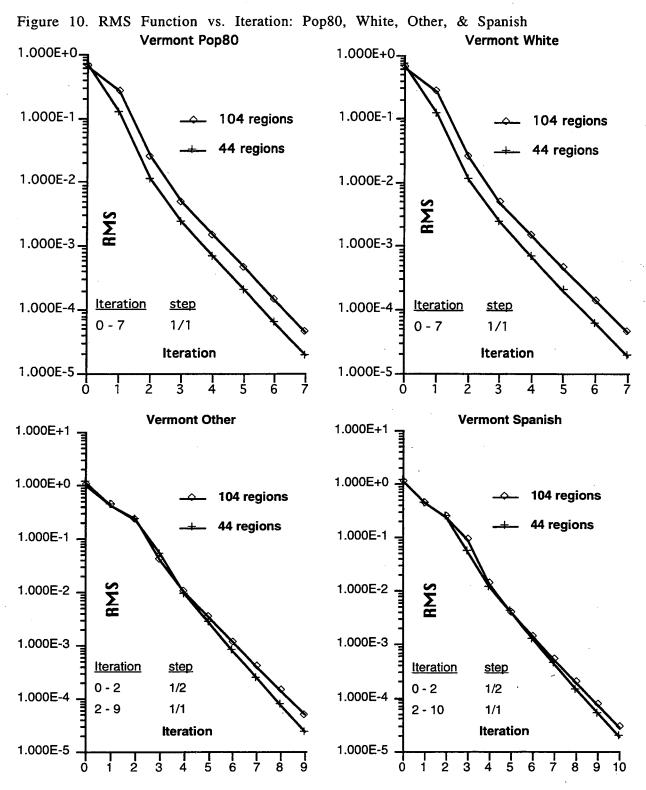
The program RLInt has been run on each of these categories for the 44-region and the 104-region maps. The results of these runs are presented in the form of graphs and pictures in the sections that follow. The quantities of interest are the rate of convergence, and the final maps. We also are interested in the behavior of the mapping as the final map becomes further from the initial map. We shall look first at the convergence of the mappings.

7.3.1 RMS Convergence

In the graphs below, the values of the RMS function are plotted on a logarithmic scale as the map is transformed. For each of the seven population categories there is a graph showing the convergence of the 44-region and the 104-region mappings. In each case the run is interupted when the value of the RMS function is less than the requested converged value of 5×10^{-5} . The maps that meet this error criterion are considered to be fully converged.

The pop80 and White mappings have been run with all iteration steps taken as fixed point iterations; the full step is taken at each transformation. The step size in these graphs is noted as 1/1. This was done because the fastest convergence is obtained when the mapping step is as large as is practical.

The mappings Other and Spanish have been run with the first 2 iterations set to the binary option, transformation step size of 1/2, and the rest of the mappings as fixed point, full mapping step 1/1, mappings. For these maps, the first two steps were changed to the binary 1/2 option because the fixed point mappings caused regions to be lost due to negative areas. In the runs shown no regions were lost; the mappings proceeded with no noticeable anomalies or difficulties. Figure 10, "RMS Function vs. Iteration, Pop80, White, Other, & Spanish," shows the value of the RMS function for these mappings.



The Asianpi, Indian, and Black mappings were done with the transformation interval fixed at 1/2 for all the iterations The reason for this is that the previous (1/2, 1/2, 1,1) subdivision produced lost regions due to negative triangles. Running the program RLInt with the binary 1/2 mapping option for the full set of mappings produced good convergence and no regions were lost. The RMS function values for these categories are shown in Figure 11, "RMS Function vs. Iteration, Asianpi, Indian, & Black."

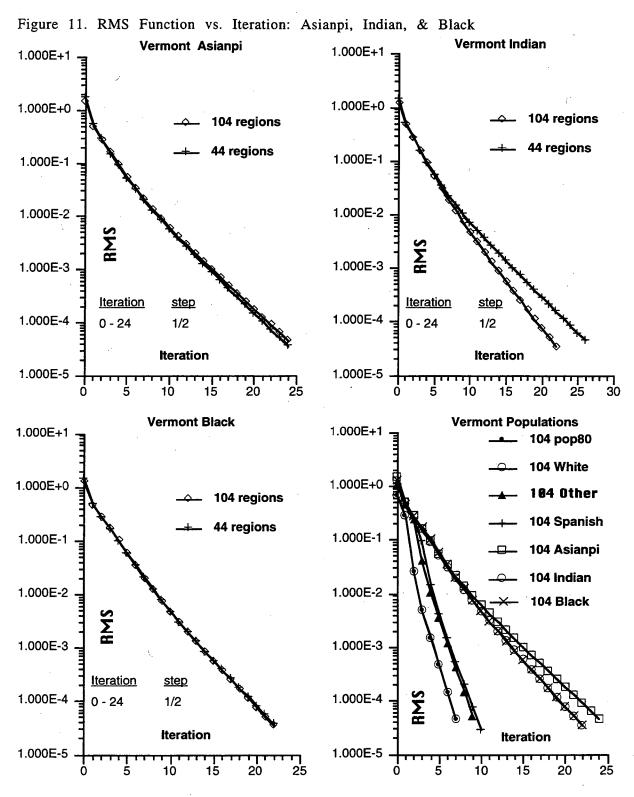
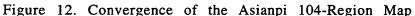
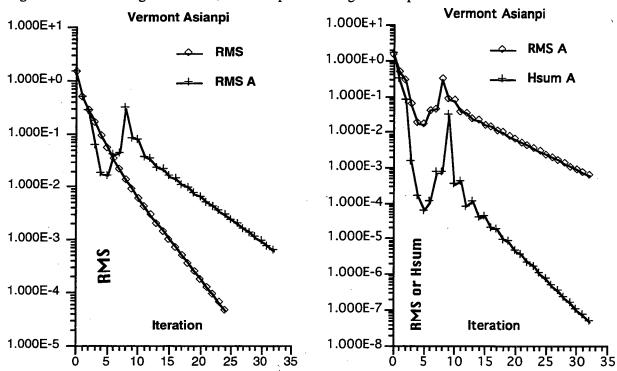


Figure 11 also shows a graph that summarizes all seven categories for the 104-region map. It is interesting to observe from this graph that the convergence rate increases significantly when fixed point iterations are taken. If the first three categories had been run using the binary 1/2 option for all the iterations, their convergence curves would be much closer to the last three categories. No attempt was made in

running the Asianpi, Indian, and Black maps to determine if the mapping could be switched to fixed point after a suitable number of binary steps, for example 10 steps.

In Figure 12, "Convergence of the Asianpi 104 Region Map," we show why we changed the mapping to the binary 1/2 option, and we also compare the RMS and Hsum functions. The graph labeled RMS is the above Asianpi run in which all the mapping steps use the binary 1/2 option. The graph RMS A is the same initial map; however, only the first two steps used the binary 1/2 option, the rest used the full fixed point iteration. The RMS A graph shows that during iterations 5-10 there were some problems. The resultant map has missing regions. The other graph in Figure 12 shows that the RMS and the Hsum functions both indicate that there is a problem in this region.





The question arises as to what the behavior of the original Russian mapping would be on the Asianpi map. We have run this case and used a subdivision of ten intervals (1/10, 1/9, ..., 1/2, 1/1, then 1/1 ten times) before applying the fixed point mapping. These convergence results are shown in Figure 13,"Asianpi Convergence vs. Iteration Count."

In this graph, we have shown the convergence for different choices of the mapping parameters. For the first map, labeled RU 10@1/10, the original Russian algorithm, as implemented in program RLInt, was applied to the initial map. The subdivision interval was 1/10 which gives 10 equal divisions for the transformation. After that, 21 fixed point mappings are applied. This mapping appears to have converged to ≈ 4 x 10^{-3} after about 13 iterations. The remaining iterations do no significantly improve the error and in fact lead to a deterioration of the quality of the map. This deterioration shows up in the total area; the calculated area begins to disgree with the original total area. The target areas are scaled so that the total area is always the same as the starting total area.

The next mapping, labeled HH 10@1/10, is the same except that the HH scaling was used. This finally began to converge at about iteration 15, and it appears that the

final error criteria of $5.0 ext{ } 10^{-5}$ could have eventually been met. All these mappings have been stopped at exactly 32 iterations. We note that no regions were lost due to negative areas.

The map labeled HH 10@1/2 has 10 binary transformations, instead of 10 equal interval transformations, and has HH scaling. It converges through iteration 15 and then begins to diverge until iteration 25 at which time it again starts to converge. Its final value is the worst of the maps. However, iteration 15 would have been the best converged map. No regions were lost during this run.

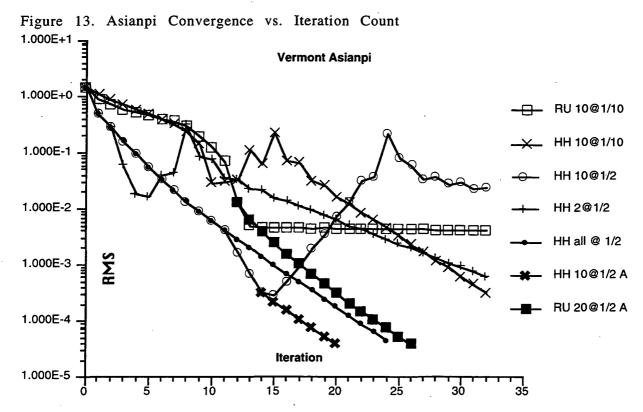
We have included the runs HH 2@1/2 and HH all @ 1/2 for comparison. The HH 2@1/2 run was discussed above as the RMS A run. This run lost regions. It had the first two iterations with the binary 1/2 mapping option and the rest using the fixed point mapping. The HH all @ 1/2 is the mapping that we discussed above, all the iterations were with the binary 1/2 option. The convergence is smooth and steady.

The RLInt program has the ability to restart from any previous mapping step, should that be desired. For example it is interesting to restart the HH 10@1/2 mapping at step 15 and use the binary 1/2 option. The output for this run had been requested every two iterations, so the closest output file available was RLInt.out.0014. This file was copied to the input file RLInt.dat and the mapping continued for exactly 10 more binary 1/2 mappings. These results are labeled as HH 10@1/2 A. This continued run quickly converged to less than the requested error.

We have also restarted the RU 10@1/10 mapping at iteration 12. The binary 1/2 mapping option was set and the iteration continued with only this type of transformation. This mapping is labeled RU 20@1/2 A. We see that this mapping also continues to converge until it meets the convergence criterion.

We note that for this continued mapping, the slope of the binary 1/2 mappings is the about same as that of the original mapping that took all the steps as binary 1/2 mappings. Also, the slope of the full step mapping, when converging well, is about the same for the maps with different starting options after they shift to the full step, fixed point iteration.

The Asianpi map has been used to illustrate how the RLInt parameters can generate different results. At the present time we have not developed a convergence strategy that would automatically determine what to do when regions are lost, or when the mapping began to diverge after a period of convergence. It would appear that the binary 1/2 option is a good choice when it is not possible to apply the full fixed point iteration.



7.3.2 Area Scatter Plot Convergence

In the previous section we presented and discussed convergence results using the RMS function as an indicator as to how the mapping converged as the successive transformed maps were generated. In the present section we show scatter plots of the region areas. Each region has a current area and a target area. The initial map, referred to here as iteration 0, has the initial region areas. The final map has the current areas, which are the converged region areas. In principal a fully converged map has, to machine precision, each current region area equal to the corresponding target area. The target areas have been scaled so that the total area of the map is constant; the initial map and the final converged map have the same total area, as do approximately all the intermediate maps. Each of the seven population categories has the same starting map; only the target areas are different.

For each of the seven population categories of the 104-region map we show, in Figures 14-20, four area scatter plots: the initial map, two intermediate maps, and the fully converged map. We note that an intermediate map that has converged to $\approx 10^{-3}$ has an area scatter plot that is all but indistinguishable from the fully converged map. All the region areas for such a map are correct to about 3 significant figures of accuracy. Their area scatter plots and their region maps appear visually identical to those of the fully converged map.

Figure 14. Area Scatter Plots for Vermont Pop80

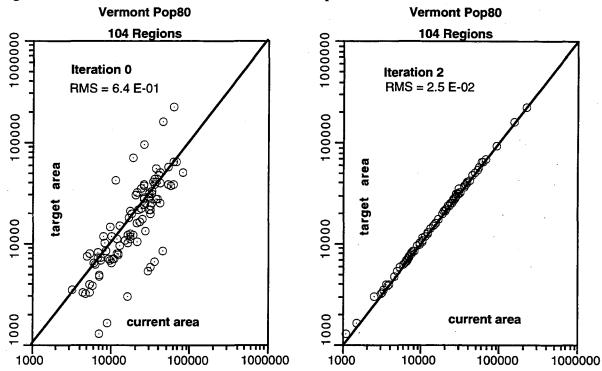


Figure 14. Area Scatter Plots for Vermont Pop80

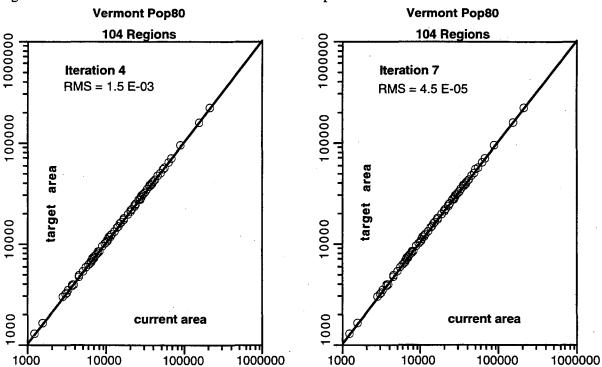


Figure 15. Area Scatter Plots for Vermont White

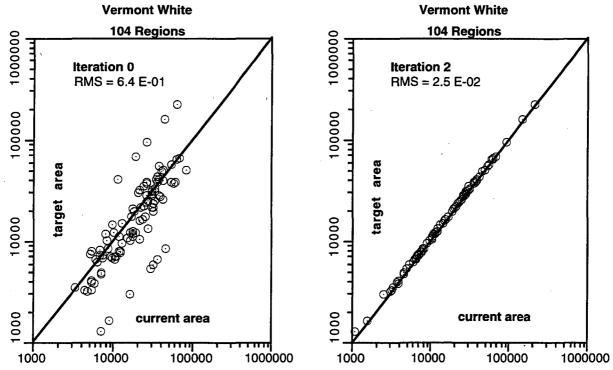


Figure 15. Area Scatter Plots for Vermont White

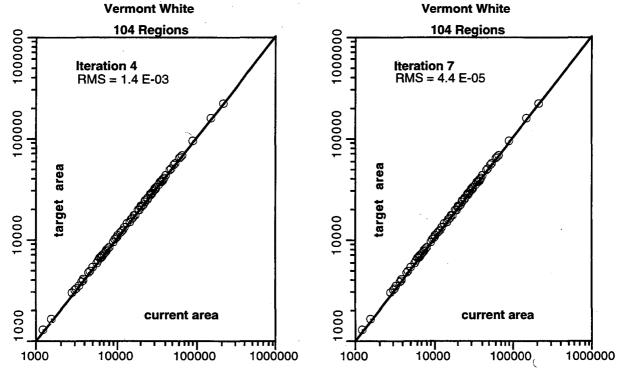


Figure 16. Area Scatter Plots for Vermont Other

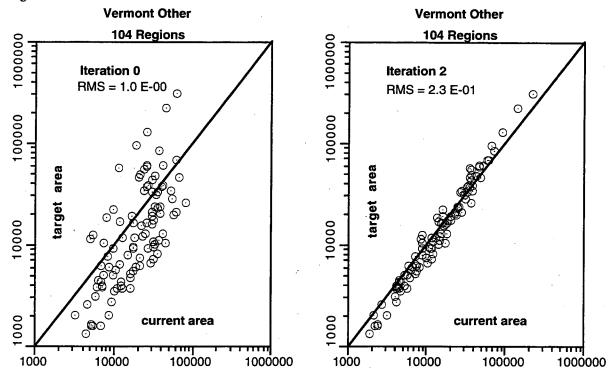


Figure 16. Area Scatter Plots for Vermont Other

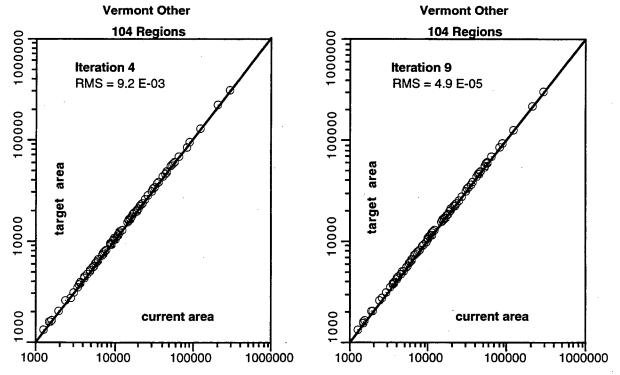


Figure 17. Area Scatter Plots for Vermont Spanish

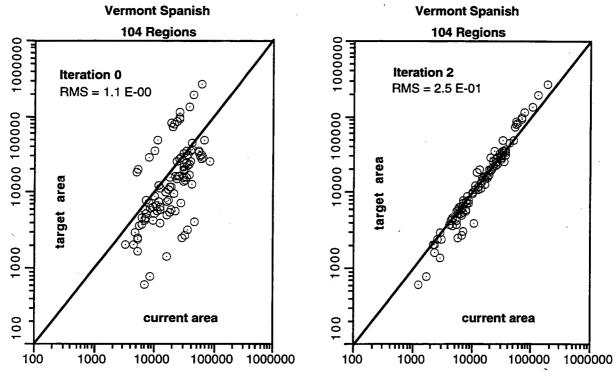


Figure 17. Area Scatter Plots for Vermont Spanish

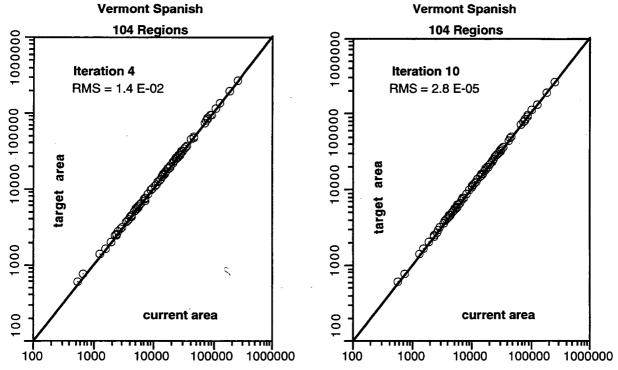


Figure 18. Area Scatter Plots for Vermont Asianpi

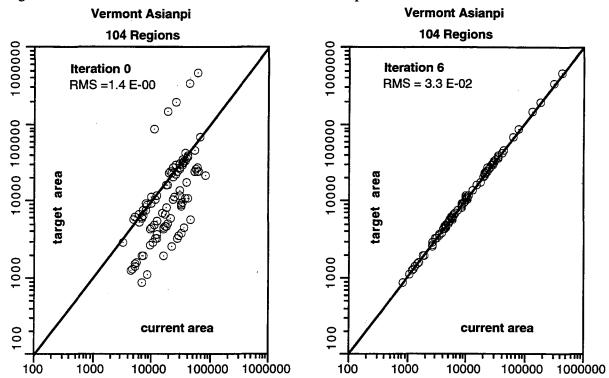


Figure 18. Area Scatter Plots for Vermont Asianpi

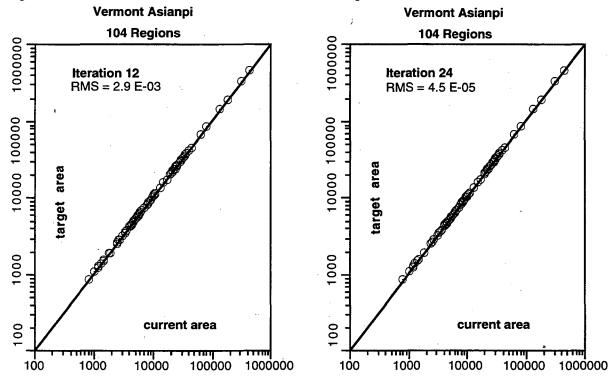


Figure 19. Area Scatter Plots for Vermont Indian

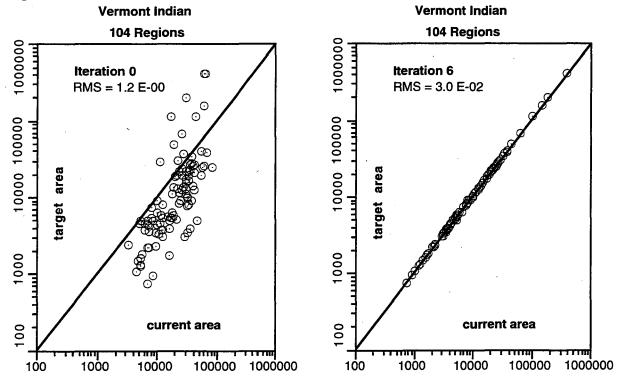


Figure 19. Area Scatter Plots for Vermont Indian

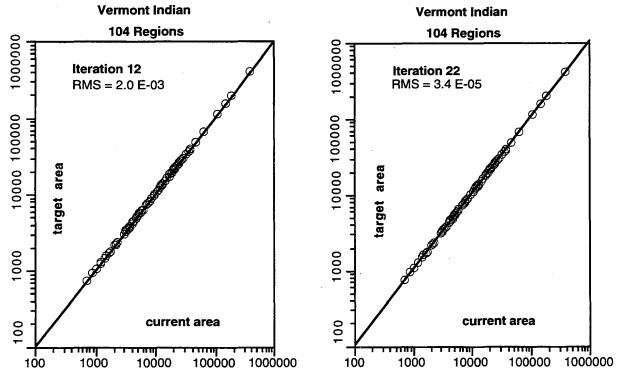


Figure 20. Area Scatter Plots for Vermont Black

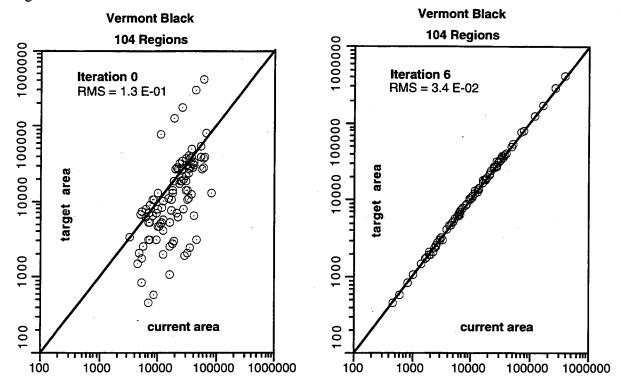
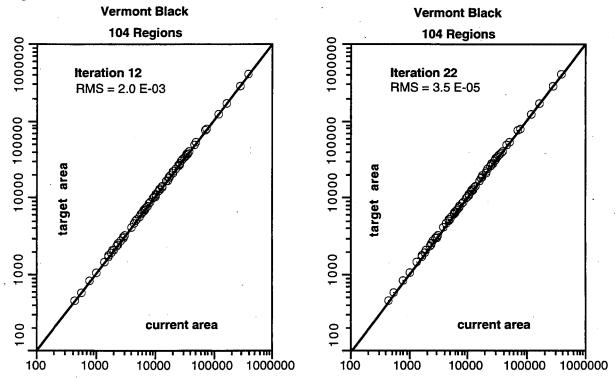


Figure 20. Area Scatter Plots for Vermont Black

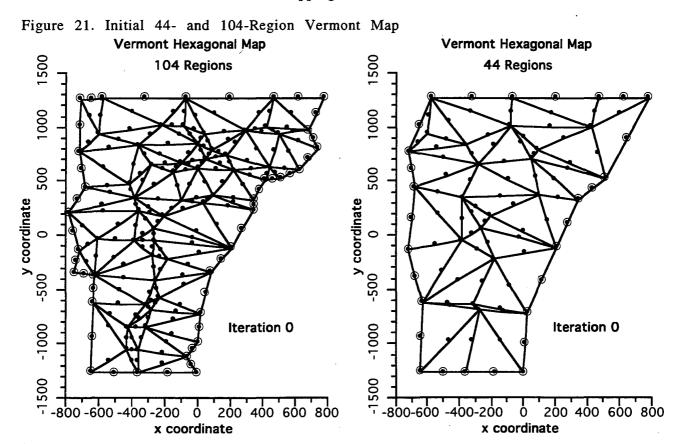


7.3.3 Initial and Final Region Maps

We have in the above sections discussed the convergence of the mappings. In this section we show the initial and final maps for the 44- and 104-region Vermont

hexagon maps. Our principal interest is the quality of the maps. The runs that we show here do not have any regions lost due to negative areas. This does not, however, mean that all the regions in the final map are satisfactory. In the present version of the program RLInt there is no check for folded boundaries; *i.e.*, boundaries that interesect themselves. Such regions could have positive net areas, but such a region has been improperly mapped. The region plots that we present will show if there are any such cases in the final maps.

We first show the initial maps. All seven population categories start with the same initial map. The difference for these maps is the target population. We repeat that the target areas have been scaled so that the final total area of the map is the same as the initial area. Figure 21 shows the initial 44- and 104-region maps. There are actually 43 and 103 distinct subregions; the first region is the outer boundary of all the subregions. We have included this special region in the maps shown below to verify that the outer boundary is correctly represented. The mapping translation vector is applied to the outer boundary, but the boundary points of this region never contribute to the construction of mapping vector.



A close examination of these initial maps shows that they are not identical, but they are quite close to being the same. The outer boundary of the 104-region map has more detail and more correctly reflects the true outer boundary of the original Vermont map.

In Figures 22-35 below, the final map and an expanded view for each of the seven population categories are shown. For each category, we present the 44-region and the 104-region final maps along with an expanded view. The expanded view is in a region that could cause problems. We have noted that none of the maps had negative area regions. However, there are only six boundary points for each triangular

region and as the regions are transformed, it is possible for a boundary to cross itself. In the final maps, the boundary points are not shown. These points are at the ends of

Figure 22. Final Mapping 44 Regions pop80 Vermont Hexagonal Map Vermont Hexagonal Map 1500 1500 44 Regions 44 Regions pop80 Iteration 7 1000 1300 500 1100 y coordinate -500 o e y coordinate 900 1100 700 -1000 pop80 Iteration 7 005 1-1200 500 200 800 400 600 -800 800 400 -400 x coordinate x coordinate

the straight lines that represent the regions boundaries.

No regions are lost, and there are no boundary crossings.

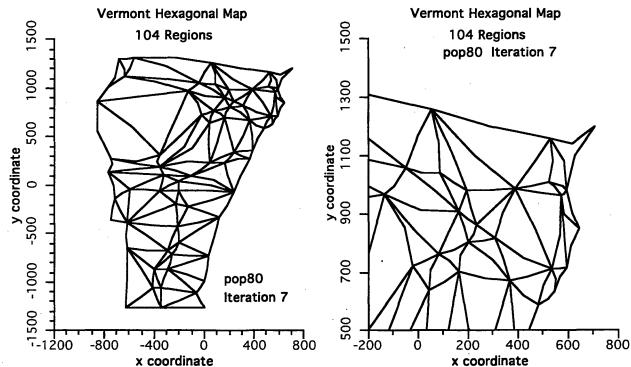


Figure 23. Final Mapping 104 Regions pop80

No regions are lost, and there are no boundary crossings.

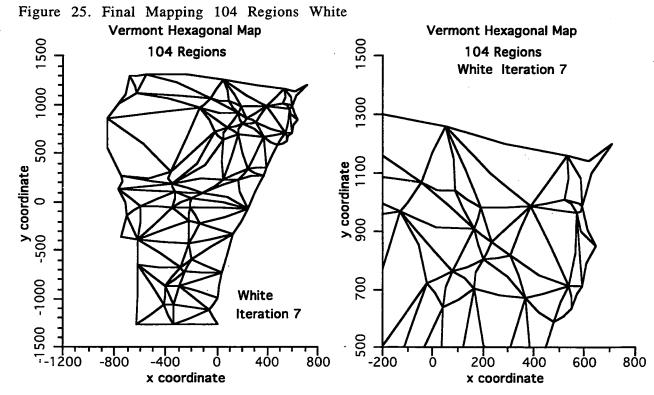
Vermont Hexagonal Map Vermont Hexagonal Map 1500 1000 1500 44 Regions 44 Regions White Iteration 7 1300 200 y coordinate 900 1100 y coordinate -500 0 = --1000 700 White Iteration 7 200 500 200 800 T-1200 400 -800 800 400 600 -400

x coordinate

Figure 24. Final Mapping 44 Regions White

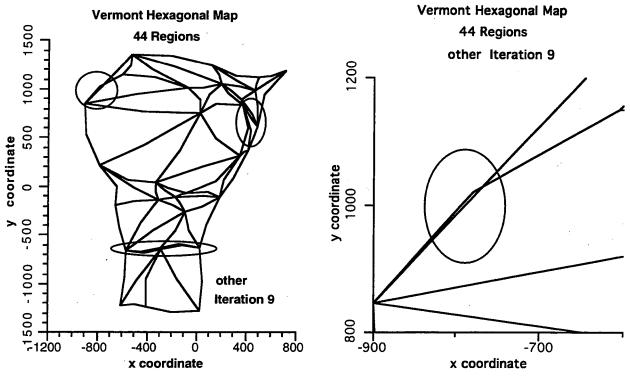
No regions are lost, and there are no boundary crossings.

x coordinate



No regions are lost, and there are no boundary crossings.

Figure 26. Final Mapping 44 Regions Other

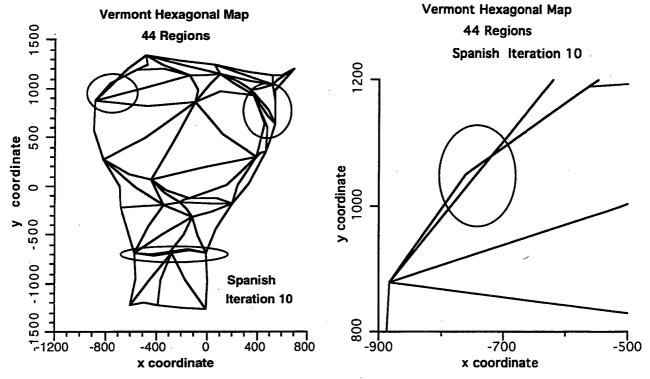


No regions are lost, but there is a region that folds upon itself. For the 104-region map, this region comes close to folding, but does not. The other circled regions do not fold.

Figure 27. Final Mapping 104 Regions Other Vermont Hexagonal Map Vermont Hexagonal Map 1500 104 Regions 104 Regions Other Iteration 9 1000 500 y coordinate -500 ο ε΄ y coordinate -1000 Other Iteration 9 200 850 -850 -750 T-1200 -800 400 800 -400 x coordinate x coordinate

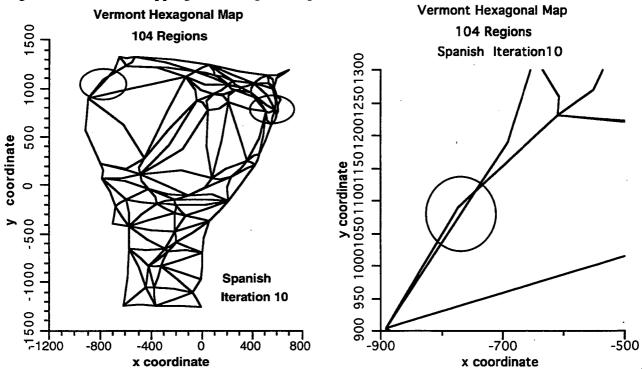
No regions are lost, and there are no boundary crossings. However, there is a region that comes close to folding upon itself.

Figure 28. Final Mapping 44 Regions Spanish



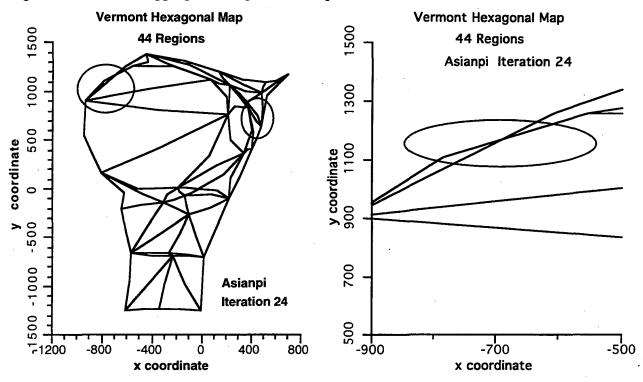
No regions are lost. There is one region with a boundary crossing. The other circled regions do not cross, although on the full scale map, they appear as if they might.

Figure 29. Final Mapping 104 Regions Spanish



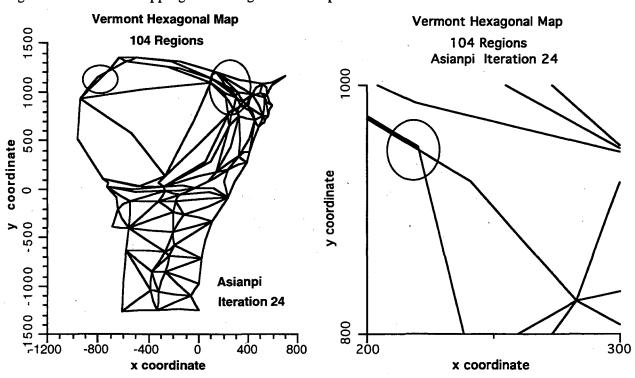
No regions are lost. There is a boundary that crosses itself. The other circled region does not cross, but comes close to doing so.

Figure 30. Final Mapping 44 Regions Asianpi



No regions are lost, but there is one region that has a boundary that crosses. The upper left circle is expanded, the upper right circle region does not cross. However, it does cross in the 104-region map.

Figure 31. Final Mapping 104 Regions Asianpi



No regions are lost, but there are two regions that have boundaries that cross. The area in the upper right circle is expanded to show the boundaries crossing in the full map.

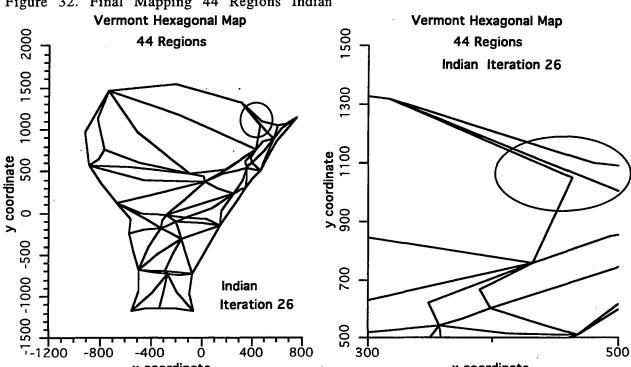
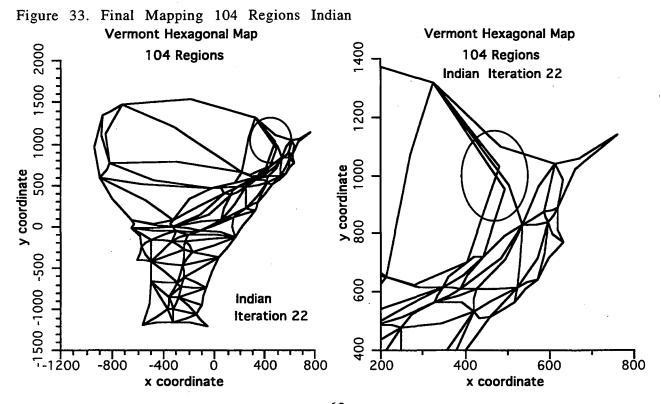


Figure 32. Final Mapping 44 Regions Indian

x coordinate

No regions lost. The circled, expanded region does not cross; but it does cross in the 104-region map. There are no boundaries that cross in the 44-region map.

x coordinate



No regions are lost. However, there is an illegal boundary crossing which is circled in the expanded plot. A close examination of the map shows that this is the only such region.

Figure 34. Final Mapping 44 Regions Black Vermont Hexagonal Map Vermont Hexagonal Map 1500 44 Regions 44 Regions Black Iteration 22 1000 1300 200 y coordinate 900 1100 1100 y coordinate -500 0 57 -1000 200 Black Iteration 22 -1200 900 -500 400 800 -700 -800 -400 x coordinate x coordinate

No lost regions. The circled region has a boundary crossing. No other regions have boundaries that cross.

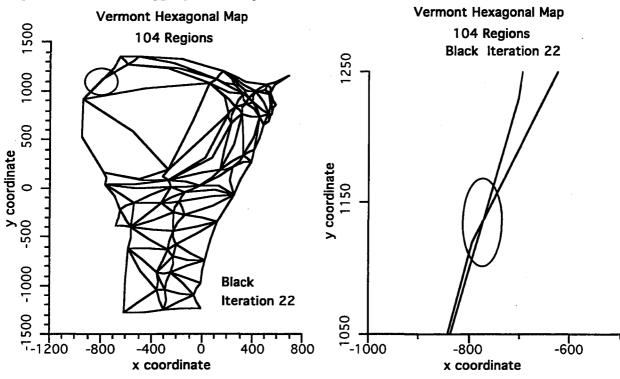


Figure 35. Final Mapping 104 Regions Black

No lost regions. However, the expanded view shows that there is a region with a boundary that crosses. The same region had this problem in the 44-region map.

The final maps that we have shown in detail above indicate that there can be a boundary crossing problem with the mappings. Presently there is no checking done to detect these crossings and hence no strategy for preventing such crossings. Increasing the number of points in each boundary should help prevent the occurrence of these crossings. It is seen from the above maps that increasing the number of regions, while keeping the same six points per boundary does not necessarily prevent crossings. Again, the basic difference in the 104-region maps and the 44-region maps is the number of regions that make up the total map.

We should also note that simply looking at the convergence, or the area scatter plots of the maps is not sufficient. The maps shown above all converged well and the scatter plots have no regions that are far from the target areas. It is necessary to visually inspect the maps to determine whether they are satisfactory. There is sufficient output from the program to do this as the mapping proceeds from iteration to iteration. Alternately an algorithm for detecting boundary crossings could be implemented.

7.4 Timing Comparisons

In this section we examine the time that it takes to perform the mappings. This can be measured in different ways. For example, we can measure the time that it takes to construct the translation vector for one point in the map. Alternatively, we can measure the time that it takes to complete one full mapping iteration to obtain the next map in the sequence of transformed maps. Or we could determine how the time varies as the number of regions in the map increases. And finally, we could measure the time it takes to go from the initial to the final map; i.e., how many iterations it takes to converge a map. In the sections that follow we discuss these different times.

7.4.1 Timing the Line Integral Mapping Algorithm

In line integral algorithm the construction of the translation vector for any point in the map requires that the pushes from all the boundary line segments be calculated and summed. The number of boundary segments in each subregion D_k is equal to the number of points used to represent the boundary.

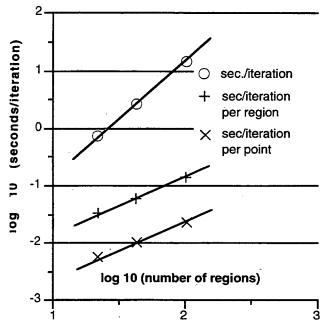
For the hexagonal maps of this report there are six points per boundary, hence six segments per boundary. The current version of RLInt has a full set of boundary points for each region. Thus, a 44-region map contains 264 points, 6x44 points that are mapped. The first region for this map does not enter into generating the transformation vector, so there only 258 boundary points that generate a push from their associated line segments; 43 regions enter into the construction of the mapping.

The 104-region map contains 624 points, 6x104 points that are mapped. Again, the first region of this map does not enter into the generation of the transformation vector; there are in this case 618 boundary line segments.

We expect that the time taken to generate a transformation for each point to be a linear function of the number of boundary segments; those that enter into the construction of the translation vector. Since the number of segments approximates the number of points, we also expect that the time for generating one complete iteration to vary as the square of the number of boundary segments that generate a push. In the simple hexagon cases that we have run the number of points is directly proportional to the number of regions. If we double the number of regions, we double the number of boundary line segments. We have therefore plotted the results as a function of the number of regions in the map. In general, the number of points can vary for each boundary region.

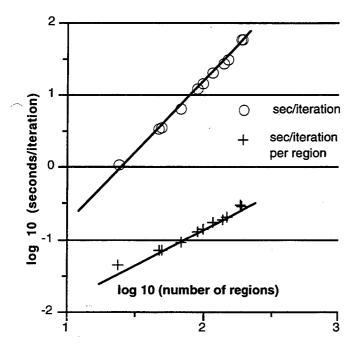
In Figure 36, "Timing for Hexagon Regions," we plot three quantities: the seconds per complete iteration, the seconds per iteration per region, and the seconds per iteration per point. The data points are for 22, 43 and 103 regions. We note that we have correctly taken the number regions that enter into generation of the translation vector. For timing purposes region 1 has been omitted. These plotted results do not contain non-pushing regions, or other non-boundary points.

Figure 36. Timing for Hexagon Regions



We have plotted the logarithmic values of the number of regions and the time in seconds. For reference we have plotted on this graph a line for which the slope is 2 and a line for which the slope is 1. From this log-log plot we see that the seconds per iteration varies as the square of the number of regions, as expected. The time per iteration per region and the time per iteration per point vary linearly with the number of regions. This graph simply verifies what we already know about the algorithm. It is, however, useful in that it can be used to predict the time for hexagon maps that contain different numbers of regions.

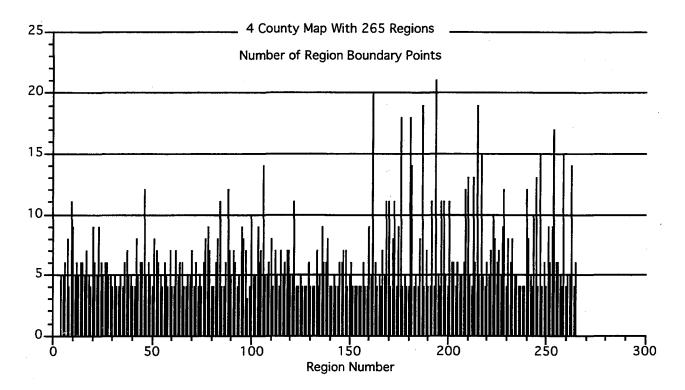
Figure 37. Timing of 4-County Map



The above results were obtained from uniformly defined hexagon maps. These maps had no anomalous regions and all the regions had 6 points per boundary. We show in the next graph the same type of results for maps in which the regions do not all have the same number of boundary points. We used a 4-county map that has 265 regions. This map has been used here strictly for timing. It has been run for subsets of these regions. During the runs, the mapping was adjusted so that no regions were lost. The only quantity of interest during the runs was the time to complete a fixed number of iterations. These results were combined with previous runs for this map in which regions were lost. This collection of runs yields qualitatively the same quadratic dependence on the number of regions and the same linear dependence on the number of points.

In the next two graphs, Figure 38, "Number of Points in Each Region for the 4 County Map," and Figure 39, "Cumulative Number of Points for the 4 County Map," we show the number of boundary points for each region and the cumulative number of points as the number of regions goes from 1 to 265. We have in the previous graph plotted the results versus the number of regions. We see from the next two graphs that the total number of points in the map is close to linearly dependent on the number of regions. This confirms that the plotting the timing as a function of the number of regions is reasonable for this map even though the number of boundary points for any given region is not constant.

Figure 38. Number of Points in Each Region for the 4-County Map



 4 County Map With 265 Regions -**Cumulative Number of Boundary Points** 3<u>0</u>0

Figure 39. Cumulative Number of Points for the 4 County Map

Region Number

In reference 12, LBL 32640, times are given for some particular maps. In Figure 20, p. 32 of that report a value of ≈500 seconds per iteration is given for a map labeled SF. This is for a SPARC 2 machine listed at 16 mips, million instructions per second. The characteristics of this map are given on p.3 of the cited report. The map has 270 point, 502 triangles and 771 segments. For the purpose of making a timing estimate, we will assume that the triangles have 6 points, as in our hexagon map. This would be equivalent to running a hexagon map with 502 regions; a total of 3012 points.

We assume that the time per iteration scales quadratically with the number of regions. Going from 103 regions to 502 regions is a factor of 5, so we estimate a factor of 25 increase in time for this map. The time for the 103 region hexagon map is 14.42 seconds/iteration. The time per iteration for the 502 region SF map should be about 360 seconds per iteration on a SPARC 10, instead of a SPARC 2. It is not possible to obtain an absolute ratio of times for these two machines on the original SF map runs without rerunning the examples. However, it seems reasonable to estimate a factor of 2-4 increase in speed on the SPARC 10. If we use 3 as our number for the speed increase, then the 500 seconds per iteration become more like 160-170 seconds per iteration. We have about a factor of 2.2 increase in time per iteration. However, that is not the complete story. The rest is how many iterations are needed to converge. We shall address this in the next section of this report.

The other map referenced in that report is the Alameda map. Details are given on p. 4 of the cited report. This map has 1090 triangles and 1670 segments. For our purposes we consider it to be a hexagonal map of 1090 regions. The ratio 1090/103 is about 10. Thus, for the line integral algorithm the time per iteration for this map should be about 1442 seconds, or about 24 minutes per iteration. On p. 8 of reference 12, the time given is 40 minutes, on a VAX 6610 at 35 mips. A direct comparison of this VAX run with SPARC 10 runs given in this report is not possible without rerunning the original problem However, it would not be unreasonable to take the VAX as being within 25% of the SPARC 10. That is the 40 probably would not reduce to less that 35 minutes for the Alameda map. Again, the estimated number of iterations for the

original run to converge is 100 to 300 iterations. This probably would not be the case with the line integral algorithm. Again this will be addressed in the next section.

7.4.2 Number of Iterations Required for Convergence

We have in the previous section determined the time per iteration as a function of the number of iterations, the number of mapping steps. This, as expected, is quadratic with respect to the number of boundary points. We have also shown that it is close to that with respect to the number of regions; even when the number of boundary points per region is not constant.

In this section, we are interested in how many iterations it takes to obtain convergence. This will determine the actual total time that it takes to generate the final map. Above in Section 7, "Summary of Results," we have shown graphs of the convergence of the maps.

It is necessary to decide what it means for a map to have "converged." It has been noted previously that the single precision program RLInt cannot be expected to get the RMS function much smaller than 10^{-6} , in practice we stop at 5.0×10^{-5} . However, we see from the graphs presented in Section 7.3.2,"Area Scatter Plot Convergence," that 10^{-3} gives an area scatter plot that is visually quite good and that the maps at this stage of convergence look quite the same as those further in the sequence. If the maps look satisfactory, and if the scatter plots do not specify regions that are far from the line of convergence, we can estimate that an RMS function value of 10^{-3} , equivalently an Hsum function of about 10^{-6} , has about 3-4 significant figures in the current area. Whether this is enough accuracy for analyzing the final map quantities will depend on the map and what it represents. Further convergence will lead to better agreement with the target areas.

Referring to Figure 10 and Figure 11 in Section 7.3.1, "RMS Convergence," we see that the number of iterations needed to reach full convergence did not vary significantly with the number of regions, at least not for the 44- and 104-region hexagonal maps. However, this quantity did depend on how far the map was away from a converged value. This measure of difficulty could be seen by looking at the initial Hsum function value. As this value became larger, the number of iterations needed became more. And there could be some difficulties with partially upside down triangles, regions with boundaries that crossed. In fact, for some races, we had to change to the binary 1/2 option to obtain good convergence and not have negative triangles.

Our comment that the total number of iterations is not dependent on the number of regions does not mean that as the number of regions becomes large, there will not be an increase in the required number of iterations. But it does not appear that this parameter in itself is a strong factor for determining the number of required iterations to reach convergence. The mapping is global in nature and appears to converge rather fast.

We refer now to the Vermont Populations graph in Figure 11, Section 7.3.1, "RMS Convergence," in which the seven Vermont maps are plotted. From that graph, we see that the full step (fixed point) iteration RMS value converged by a factor of 100(2 significant figures) every 5 iterations or 0.4 decade per interation. The binary 1/2 option maps converged very smoothly at 0.18 decade per iteration, very close to 2 significant figures per 10 iterations. The first three maps, pop80, White, and Other, converged in 7-10 iterations for an average convergence rate of about 0.5 decades per iteration. The last 4 maps, Spanish, Asianpi, Indian, and Black converged in 22 to 24 iterations for an average convergence rate of about 0.2 decades per iteration.

To summarize, the maps with lower initial RMS gained about 0.4 to 0.5 decade of RMS per interation. Those that had a higher Hsum value gained about 0.25 decade per interation The maximum that we can ask for in this single precision program is an RMS of the order of 10⁻⁵, or 5 significant figures.

The hexagon maps are simple and well-behaved. We have run triangle maps, described in Section 7.2.1,"The 44-Region Vermont Triangle Map," and concluded that it is necessary to have the additional degrees of freedom that the addition of the segment midpoint gives. It is also to be noted that this algorithm may need even more boundary points to accurately represent the region boundaries and to prevent boundary crossings. We have not investigated this aspect of the mapping in detail.

It is interesting to estimate the time required to converge the 502 region map and the Alameda map of 1090 regions when mapped with RLInt. For this purpose, as was done in the previous section, we assume that the maps are triangularized with six points per triangle. We assume that each region has all six points, again as was done in the previous section. We make the estimate for converging three and for converging four decades. Where this take us with regard to the number of significant figures in the final, current, areas depends on where we start. If we start with an RMS on the order of 10, then we still arrive in the four decade case with an RMS of 10^{-3} . We use this range simply as an example, other ranges are easily calculated. We take the worst case of 0.2 decades per iteration and we arrive 15-20 iterations. Translated to total time we have for the San Francisco map 360 x (15 or 20). This gives a range of 1.5- 2.0 hours. A similar estimate on the Alameda map would be 1442 x (15 or 20). This gives 6-8 hours for converging 3-4 decades.

In summary: An estimate for running the San Francisco map through 4 decades of convergence is about 2 hours of computing. This assumes 20 iterations. A similar estimate on the Alameda map yields 8 hours. On p. 8 of the cited LBNL report the estimate it "about 6 to 9 days." Even if our estimate is off by a factor of 2-3, this is considerable better that the "6 to 9 days" previously estimated.

As a final comment on convergence, we should refer to Figure 13, "Asianpi Convergence vs. Iteration Count," of Section 7.3.1. This graph shows that convergence is not "guaranteed" with any particular choice of the mapping options. There is a discussion of this graph in that section; we will not repeat it here. Suffice it to say that the convergence of the map must be monitored in general, and if difficulties arise, action must be taken. It seems that it should be possible to restart at some point in the sequence with a choice that causes the map to continue to converge and which maintains the quality of the resultant map. Presently, this monitoring and restarting is done manually.

8. Future Work Required

The LBNL implementation of the Russian line integral algorithm is fairly complete. Test cases have been run to insure the accuracy of the algorithm in that it correctly evaluates the required line integral and that it can take real maps and produce output that is basically correct and useful. However, future work is required to complete this implementation. We discuss in this section some of those tasks.

8.1 Input Maps for the 4-County Area

The preparation of the input maps is described in references 3 and 10. These steps include the following: correction of map errors, removal of excess geographic detail, insertion of connecting segments to eliminate doughnut-shaped polygons, and triangulation of the resulting polygons.

8.2 Handling of Pathological Conditions

As long as the transformation that is applied generates a valid map there is no problem. However, problems with the resultant map can begin to appear. We discuss below in the Section 8.3 "Program Improvements," some problems that should be taken care of with regard to illegal regions. However, it may be that we are unable to prevent the transformation from generating a map that has problem regions. For example, it may be that a water region drifts out of the region that it belongs in, but the rest of the map is satisfactory.

8.2.1 Correction Within DEMP program

The most natural way to correct while inside the DEMP program is to try to adjust the mapping so that each transformation produces a valid map that has no pathological conditions. Some of the additions that can help to prevent this are discussed in Section 8.3, "Program Improvements."

If this is not possible, then it probably is the case that we have found the undesirable condition by examining the resultant map from outside the DEMP program. In that case, it makes sense to try and correct it from outside. This use of the word "outside" however, can refer to an interactive update of the parameters that define the mapping algorithm. The map is examined external to the DEMP program in some way, a problem is found, the DEMP program is interrupted, and then mapping parameters adjusted.

This type of correction requires a map viewing interface and some type of user interaction interface with the DEMP program. It also requires some criteria to be used in making the decisions on what to modify in the mapping algorithm. A restart from a good map can then be done. Again this is in some sense using the DEMP program to prevent the anomalous mapping.

8.2.2 Correction Outside the DEMP Program

The identification of a map problem that is to be corrected outside the DEMP program probably was done outside of the program. The basic item in hand is the present map and possibly saved intermediate maps. In this case, the map can be adjusted and modified. The offending region, or map, problems can be removed. For example, a misplaced water region could be put back where it belonged. If the regions' sizes were modified, or their boundaries moved, it would be necessary to somehow correctly adjust neighboring regions and their associated data. This modification could in all probability be considered a special mapping. The DEMP program is not set

up to do this. To insure that the corrections are correctly done will require a special correction/mapping program. It would be very helpful if this could be done visually and graphically, The simplest way to change a region is to drag its boundary. If this were done, then all the region characteristics would be automatically updated; as too would those of the neighboring regions. Proper, consistent correction of these maps is not trivial.

8.3 Program Improvements

The present version of RLInt is complete in that it can input map data, calculate transformed maps, print reports, and output final maps. It has a number of parameter options that allow the user to select how the mapping will be performed and what output will be generated. However, there are areas in which future work would be beneficial. We discuss some of these areas in this section.

8.3.1 Elimination of Duplicate Boundary Points

The program RLInt uses the line integral algorithm in its simplest, most direct form. To evaluate the line integral around each region the program simply marches around the region's boundary points and accumulates the resultant translation vector contributions from each boundary line segment. Each region boundary is considered to be totally separate with a separate collection of boundary points.

This use of separate regions has the advantage of simplicity and has helped ensure that the line integral around each region is taken in the proper direction. It also

makes for easy housekeeping in the program. However, it has the disadvantage of duplicating Figure 40. Shared Region shared Boundary points for regions with boundaries. For large maps with many regions, this is an inefficient way to process the data. In the present program version, the total number of points is directly proportional to the number of boundaries and the number of points on each boundary. In actual practice, the maps may have many less boundary points because of common boundaries.

Only the line segments that make up the boundaries are required to evaluate the line integral. If we know for each line segment which regions share it as a boundary segment, and if we can determine which directions to assign to the line segment, we can simply accumulate the Region 1 $(A/A_f - 1)$ $(B/B_f - 1)$ Region 2

translation vector contributions as needed. We can illustrate this with Figure 40, "Shared Region Boundary"

We see from this figure that the diagonal segment common to Region 1 and Region 2 is traversed in two directions. Currently these two regions are considered to be totally separate and require 6 points for their definition. This is unnecessary: only 4 points are required. Also, the line integral calculation along the diagonal is done twice, once for each boundary. This is not necessary; the integral can be evaluated once and the result multiplied by the coefficient $(A_f/A - B_f/B)$. We have assumed that the integral is evaluated from left to right, which is the correct direction for Region 1 but not for Region 2. The current areas are A and B and the target areas are Af and Bf This modification would also eliminate some of the checking done to ensure that coincident boundary points, the points on the segment common to both regions in Figure 40, stay coincident.

Implementation of this modification will reduce the calculations needed for evaluating the line integral, it will reduce the storage required for data points, but it will require careful housekeeping to insure that the integrals are properly done.

8.3.2 Illegal Boundary Crossings and Poor Convergence

The assumption is made here that the initial maps are furnished with no illegal boundary crossings, i.e., that the starting map is correctly defined. This assumption has proved to be not necessarily true. Also, the line integral algorithm has the potential of creating transformed regions with boundaries that cross themselves. They have been referred to as regions with folded boundaries, or partially upside down regions. We have seen some mild examples of this problem in the maps shown and discussed in this report. In the worst case, the region is turned over and the area becomes completely negative. We note that a region can have positive, or negative area with only part of the region being upside down; the area calculation gives the net (algebraic) area of the region.

We have also seen that the convergence of the mapping can go from good to bad, and in fact to divergent. This can be associated with the creation of crossed boundaries, or regions lost due to negative boundaries. However, it is possible for the convergence to deteriorate without there being such problems.

The line integral algorithm is such that a negative area is not pushed back into a positive area. Instead, each point is reflected back through the origin - equivalent to a 180° rotation. We need instead a reflection through an arbitrary straight line. These problems need to be addressed and a strategy developed and implemented for dealing with them.

Illegal Boundary Crossings

The region boundaries are polygons with straight line segments. It is possible to implement an algorithm that will detect when a polygonal region has a boundary that crosses itself. The translation vector that takes the map forward one full iteration vector is available in the present version of RLInt. Currently the regions are mapped sequentially by constructing the translation vectors for their boundary points and then applying the translation. It is rather easy to check at that time whether a region has any boundaries that cross. If a region has boundary problems, corrective action can be taken at that step in the process.

There are choices to be made in developing a corrective strategy. The simplest would be to simply not push that region's points so strongly. This, however, causes problems because of shared boundary segments; fixing one region's boundary can cause some very troublesome house keeping problems in updating other regions that have been already mapped.

A simple, and possibly best, solution is to stop the current mapping construction and readjust the fraction of the translation vector that will be taken for all the regions. After doing this, it is not necessary to reconstruct all the translation vectors. It is only necessary to change the coefficient that multiplies the vectors and then again apply them to the boundary points. This process can be repeated until the boundaries do not have crossing problems. At this point, a decision must be made as to whether to continue to use the current value of the coefficient, and if so for how long. This,

while possibly time consuming, is easily done with the current program. In a sense, it is analogous to the automatic step size adjustment used in the integration of ordinary differential equations, particularly systems that are classified as "stiff."

In any case, an algorithm that detects illegal region boundaries should be implemented, and a correction strategy should be decided upon and implemented. This will prevent the construction of maps with illegal boundary crossings and will also insure that furnished maps are in fact correctly constructed.

Non-Boundary Points on Boundary Line Segments

The points that are used to construct the translation vector are the boundary points (segments) of the regions. It is possible to map points that are not boundary points. There is presently in RLInt the capability of doing this. The data set RLInt.dat can contain these non-boundary points and they are mapped along with the boundary points. There is, however, no checking to determine whether these points land on a boundary segment. If they happen to coincide with a boundary point, they will stay attached to the boundary points. But if they happen to land on one of the line segments, they will presently not get the right push from that line segment. A point on a line segment should have the push generated from the value of the improper line integral along that segment. Currently RLInt only recognizes when a point lands on one of the line segment end points. This should eventually be corrected.

Convergence Monitoring

The convergence graphs shown in Section 7.3.1, "RMS Convergence," of this report show that the convergence rate can vary dramatically depending on what mapping and translation parameters are chosen. There are two monitoring functions, RMS and Hsum, that can be used to determine how well the process is converging. If the map being transformed has no anomalous regions, no zero areas, the behavior of these two functions is basically the same. However, the Hsum function penalizes regions that go negative and it also takes into account the relative areas of the regions. Thus, it probably is the better function to use for automatic monitoring of the mapping convergence.

The problem is two-fold. We have to decide when the process is not converging, or converging poorly, and we have to decide what to do when that is the case. Examples provide some guidance for determining the quality of the convergence. We see from these examples that when all is going well the convergence is monotonic and with a fairly constant slope on a log scale of convergence (Hsum or RMS) versus iterations. The actual rate (slope) of convergence depends to some extent on the number of regions and to a greater extent on the inital value of Hsum or RMS. However, the two properties monotonic convergence and constant slope seem to be a reasonable criterion for recognizing success.

Once it has been determined that the process is not converging well it becomes a task of deciding what to do. There is much information available at each step of the calculation. The RMS and Hsum functions furnish an average of the area errors for the regions. The individual region area errors, magnification errors, are available. The parameter options selected for the mapping (fixed point, binary interval, equal interval, unscaled or HH scaled) are available and can be easily changed to new values. Also, the mapping can be restarted at the current step, or it can be regressed one full step and restarted at that step; all without exiting the subroutine rtrans that is constructing the mapping sequence. It is also possible to drop regions that are causing a problem and to pick them up again later.

Summary

It will take some learning with test cases to determine what strategy is appropriate for both the convergence and boundary crossing problems. We should keep in mind that intermediate maps are available. The maps can be viewed as the mapping progresses and decisions can be based upon how these maps look. It is quite possible that the best correction for both the boundary crossing problem and the poor convergence problem can be obtained by user interaction that is based on looking at the maps as they are generated. If this is the case, some work will have to be devoted to establishing an interactive user interface with RLInt that is suitable for this type of corrective action.

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Appendix A Integral Transformation and Correction Factors

A.1 Introduction

We derive in this Appendix the basic line integral that defines the mapping transformation. This derivation follows that of reference 9, but is given here in more detail. We also include the explicit evaluation of the line integral used in the program RLInt; this is not in reference 9 which simply gives the result as an indefinite integral. We also evaluate explicitly the area integral for the special case of the circle. This result has been useful in checking the program calculations and also in understanding the mapping. Finally we include in this Appendix a derivation of the local region area calculation. This too is done by means of a line integral.

A.2 Derivation of the Mapping Integrals

We have given a general overview of the mapping derivation in Section 2.2, "Summary of the Algorithm."

The original area of an arbitrarily small circular cell is given by

$$\Delta S = \pi R^2$$

and the radius of the cell is

$$R = \left(\sqrt{\Delta S}/\pi\right)$$

The present density within the cell is given by

0

Outside the cell the original density is

 $\rho_{\scriptscriptstyle f}$

We wish to preserve the present density (ρ_f) outside the cell while expanding the cell to achieve target density ρ_f inside as well.

The target area of the cell is

$$(\Delta S)_f = \rho \Delta S/\rho_f$$

which means that the final (target) radius of the cell is

$$R_f = \sqrt{(\Delta S)_f / \pi}$$

Let z = (x, y) denote the present coordinates of an arbitrary point in the (x, y) plane.

$$z' = (x', y')$$
 is the center of the cell

the present coordinates of an arbitrary point outside the cell are

$$z = (x, y)$$

and the final coordinates of the arbitrary point outside the cell, to be determined, are $z_f = (x_f, y_f)$

The radius vector from the center of the cell (x',y') to the present arbitrary point (x,y) is

$$z - z' = (x - x', y - y')$$

and the radius vector from the center of the cell (x', y') to the final position (x_f, y_f) of the arbitrary point outside the cell is given by

$$z_f - z' = \left(x_f - x', y_f - y'\right)$$

The vector of translation of z is

$$z_f - z = (x_f - x, y_f - y)$$

The initial distance of z from z' is

$$r = |z - z'| = \sqrt{(x - x')^2 + (y - y')^2}$$

and the final distance of z_f from z' is

$$r_f = |z_f - z'| = \sqrt{(x_f - x')^2 + (y_f - y')^2}$$

We define ϕ , the initial angle of z relative to z', as

$$\phi = \tan^{-1}((y-y')/(x-x'))$$

We note here that it is necessary when obtaining the numerical value of this angle to take into account the signs of (y-y') and (x-x'). This is done by using the Fortran intrinsic function atan2.

We also define ϕ_f the final angle of z_f relative to z', as

$$\phi_f = \tan^{-1} \left(\left(y_f - y' \right) / \left(x_f - x' \right) \right)$$

A radial transformation that changes the density from ρ to ρ_f everywhere inside the cell, and maintains constant density ρ_f outside the cell, is:

$$\phi_f = \phi$$

$$r_f = \left(R_f / R \right) r$$
 for $r \le R$
$$r_f = \sqrt{r^2 + R_f^2 - R^2}$$
 for $r \ge R$

We let R be infinitesimally small so that only the equation for $r \ge R$ applies. Keeping in mind that $\phi_f = \phi$ we can write:

$$z_f - z = (z_f - z') - (z - z')$$

$$= (z_f - z')[|z_f - z'|/|z_f - z'| - 1]$$

$$= (z - z')[(r_f/r) - 1]$$

$$= (z - z')[\sqrt{r^2 + R_f^2 - R^2}/r - 1]$$

$$= (z - z')[\sqrt{1 + (R_f^2 - R^2)/r^2} - 1]$$

$$= (z - z')[\sqrt{1 + ((\Delta S)_f - \Delta S)/(\pi r^2)} - 1]$$

$$= (z - z')[\sqrt{1 + (\rho/\rho_f - 1)\Delta S/(\pi r^2)} - 1]$$

Ignoring terms of order $(\Delta S)^2$ allows us to write,

$$z_{f} - z = (z - z') \left[1 + (\rho/\rho_{f} - 1) \Delta S / (2\pi r^{2}) - 1 \right]$$

$$z_{f} - z = (z - z') (\rho/\rho_{f} - 1) \Delta S / (2\pi r^{2})$$

Now consider the plane to consist of an infinitely large number of circular cells, each having an infinitesimal area ΔS and centered at a different point z'. The individual cells (which overlap) are arranged so that the total area of the cells in a given region is equal to the area of that region.

For every point z' in the domain D, except z, we perform this transformation. The translation vector $z_f - z$ is obtained as the sum of the translation vectors from all the infinitesimal regions in D, namely over all values of z'. We now let dS be the limit of ΔS as ΔS goes to zero. The sum becomes an integral over the domain D and the resultant translation vector for $z_f - z$ is

$$(z_f - z) = \frac{1}{2\pi} \int_{D} \left(\frac{\rho - \rho_f}{\rho_f} \right) \frac{(z - z')}{r^2} dS$$

Assume that ρ has a constant value ρ_k over a sub domain D_k . Then the contribution from the subdomain D_k , to the vector of translation is

$$(z_f - z)_k = \frac{1}{2\pi} \left(\frac{\rho_k - \rho_f}{\rho_f} \right) \int_{D_k} \frac{z - z'}{r^2} dS$$

The equation above gives

$$(x_f - x)_k = \frac{1}{2\pi} \left(\frac{\rho_k - \rho_f}{\rho_f} \right) \int_{D_t} \frac{x - x'}{(x - x')^2 + (y - y')^2} dS$$

$$(y_f - y)_k = \frac{1}{2\pi} \left(\frac{\rho_k - \rho_f}{\rho_f} \right) \int_{D_t} \frac{y - y'}{(x - x')^2 + (y - y')^2} dS$$

We now have two area integrals, one for the x contribution and one for the y contribution. It is important to keep in mind that dS = dx'dy' and that the integration is with respect to the variables x' and y'. The final density ρ_f , referred to elsewhere in this report as the target density, is the density which the infinitesimal regions are to achieve. This is the final density of the region D_k . If the subregions that make up the global region each have different final densities, then the final density in the above formulas should actually be written as $\rho_f^{(k)}$.

We know from Stoke's Theorem, Lass, Vector and Tensor Analysis, McGraw-Hill Book Inc., 1950, p.109, that given a vector \vec{V} , that we can write

$$\oint_C \vec{V} \bullet d\vec{s} = \int_D curl\vec{V} \bullet \vec{dS}$$

This says that integrating the tangential component of the vector \vec{V} around the boundary C of the region D gives the same results as integrating the normal component of the vector $curl\vec{V}$ throughout the closed region D. This line integral is to be taken in the counter clockwise direction around the boundary C of the region D.

If we define the vectors

$$\vec{V} = (V_x, V_y, V_z)$$

$$\left(curl\vec{V}\right)_z = \frac{\partial V_y}{\partial x'} - \frac{\partial V_x}{\partial y'}$$

$$d\vec{s} = (dx', dy', dz')$$

$$d\vec{S} = (0, 0, dS)$$

$$(\vec{dS})_z = dS$$

and if we choose the components of an arbitrary $ec{V}$ to be

$$V_{x'} = \frac{1}{2} \ln \left[(x - x')^2 + (y - y')^2 \right]$$

$$V_{y'} = 0$$

$$V_{z'} = 0$$

then from the definition of $curl\vec{V}$ we have

$$\left(curl\vec{V}\right)_{z} = -\frac{\partial V_{x}}{\partial y'} = \frac{\left(y - y'\right)}{\left(x - x'\right)^{2} + \left(y - y'\right)^{2}}$$

For this particular vector Stoke's Theorem gives:

$$\oint_C V_x dx' = \oint_D \left(curl \vec{V} \right)_z \left(\vec{dS} \right)_z = -\oint_D \frac{\partial V_x}{\partial y'} dS$$

$$\frac{1}{2} \oint_C \ln \left[(x - x')^2 + (y - y')^2 \right] dx' = \int_D \frac{(y - y')}{(x - x')^2 + (y - y')^2} dS$$

In a similar manner if we define the arbitrary vector V to be

$$V_x = 0$$

$$V_y = -\frac{1}{2} \ln \left[(x - x')^2 + (y - y')^2 \right]$$

$$V_{z'} = 0$$

then we have that

$$\left(curl\vec{V}\right)_{z'} = \frac{\partial V_{y'}}{\partial x'} = \frac{(x-x')}{(x-x')^2 + (y-y')^2}$$

and Stoke's Theorem gives

$$\oint_{C} V_{y} dy' = \oint_{D} \left(curl \vec{V} \right)_{z} \left(\vec{d}S \right)_{z} = \oint_{D} \frac{\partial V_{y}}{\partial x'} dS$$

$$-\frac{1}{2} \oint_{C} \ln \left[(x - x')^{2} + (y - y')^{2} \right] dy' = \int_{D} \frac{(x - x')}{(x - x')^{2} + (y - y')^{2}} dS$$

This allows us to write for the subdomain D_{ν}

$$(x_f - x)_k = -\frac{(\rho_k - \rho_f)}{4\pi\rho_f} \oint_{C_k} \ln[(x - x')^2 + (y - y')^2] dy' = -\left(\frac{\rho_k - \rho_f}{4\pi\rho_f}\right) \oint_{C_k} \ln(r^2) dy'$$

and

$$(y_f - y)_k = + \frac{(\rho_k - \rho_f)}{4\pi\rho_f} \oint_{C_k} \ln[(x - x')^2 + (y - y')^2] dx' = + \left(\frac{\rho_k - \rho_f}{4\pi\rho_f}\right) \oint_{C_k} \ln(r^2) dx'$$

where $r^2 = (x - x')^2 + (y - y')^2$.

The total translation vector is obtained by summing the translation vectors from each of the subdomains D_k :

$$(x_f - x) = \sum_{k} (x_f - x)_k$$

$$(y_f - y) = \sum_{k} (y_f - y)_k$$

We keep in mind that ρ_k is the final, or target, density of the region D_k around which the integral is taken.

A.3 Line Integral Evaluations

The boundaries of the subregions are represented by line segments. For the purpose of obtaining a closed form solution of the line integral we assume in this section that a particular segment has length L. To obtain the contribution from the line segment L to the translation vector, we must evaluate the line integrals

$$\int_{0}^{L} \ln((x-x')^{2} + (y-y')^{2}) dx', \quad \int_{0}^{L} \ln((x-x')^{2} + (y-y')^{2}) dy'$$

Functionally there is no difference in the two integrals. In reference 9, an indefinite integral formula was given as the value of the integral; however, the indefinite integral formula must be made specific for us to evaluate the line integral numerically.

There is a problem with the above representation when the line along which we are integrating includes the point (x'=x, y'=y). At that point, the integrand $\ln((x-x')^2+(y-y')^2)$ becomes infinite. Analytically, the line integral remains finite, but it cannot be evaluated numerically.

This problem can be avoided by using the arc length ds as the integration variable. We can write the above line integrals as

$$\int_{0}^{L} \ln((x-x')^{2} + (y-y')^{2}) \cos(\alpha) ds, \quad \int_{0}^{L} \ln((x-x')^{2} + (y-y')^{2}) \sin(\alpha) ds$$

where α is the angle of the line segment relative to the x axis, measured in a counter clockwise direction. Since the angle α is fixed for each line segment, we shall ignore it in the derivation below. We must, however, remember that the result is multiplied by either $\sin \alpha$ or $\cos \alpha$.

There are, in general, four cases to examine: the point (x,y) is not on the line segment L; the point (x,y) is one of the line segment end points, i.e., $(x,y) = (x_1,y_1)$, or $(x,y) = (x_2,y_2)$; and the point (x,y) is an arbitrary point along the line, but not one of the end points. When the point (x,y) is on the line (three of the four cases) the integral is an improper integral since the integrand becomes negatively infinite. However, the integral does have a finite value. We derive below the formulas used in RLInt for each of these four cases.

A.3.1 Point z not on Line

Start with the basic integral along the line, $z = (x, y) \neq (x', y')$,

$$\int_{0}^{L} \ln((x-x')^{2} + (y-y')^{2}) ds$$

where ds is the differential arc length along the line segment.

We have that

$$x' = x_1 + s\cos\alpha$$

$$y' = y_1 + s \sin \alpha$$

where s is the distance from the left end point of the line segment (x_1, y_1) to the current point (x', y'). This allow us to write the integral as

$$\int_{0}^{L} \ln \left(\left(x - x_{1} - s \cos \alpha \right)^{2} + \left(y - y_{1} - s \sin \alpha \right)^{2} \right) ds$$

where L is the line segment length.

Complete the square and collect terms to express the integral as

$$\int_{0}^{L} \ln(a^2 + 2sb + s^2) ds$$

where

$$a^{2} = (x - x_{1})^{2} + (y - y_{1})^{2}$$

$$b = -[(x - x_1)\cos\alpha + (y - y_1)\sin\alpha]$$

The above integral can be written as

$$\int_{0}^{L} \ln(a^{2}-b^{2}+(s+b)^{2})ds$$

Make the change of variables $\xi = s + b$ with $ds = d\xi$ and define $\beta^2 = a^2 - b^2$. This give the formula

$$\int_{b}^{L+b} \ln(\beta^{2} + \xi^{2}) ds = \left[\xi \ln(\beta^{2} + \xi^{2}) - 2\xi + 2 \tan^{-1} \left(\frac{\xi}{\beta} \right) \right]_{b}^{L+b}$$

This later result can be found in tables of integrals. Note that we have assumed that β is constant, which is true for a line segment.

If we perform the indicated algebra we can write

$$\int_{0}^{L} \ln((x-x')^{2} + (y-y')^{2}) ds = \ln\left(\frac{t_{2}}{t_{1}}\right) - 2L + 2\beta \tan^{-1}\left(\frac{L\beta}{\beta^{2} + \xi_{1}\xi_{2}}\right)$$

where

$$t_1 = (\beta^2 + \xi_1^2)^{\xi_1}$$
; $\xi_1 = b$

$$t_2 = (\beta^2 + \xi_2^2)^{\xi_2}$$
; $\xi_2 = b + L$

To arrive at the above expression we have used the trigonometric identity

$$\tan^{-1} u_2 \pm \tan^{-1} u_1 = \tan^{-1} \left[\frac{u_2 \pm u_1}{1 \mp u_2 u_1} \right]$$

Also, we note that numerically we must use the function $atan2(L\beta,\beta^2+\xi_1\xi_2)$ to insure that we get the correct quadrant sign. The principal valued inverse tangent function atan does not always give a suitable answer for the above expression.

Numerically there is a problem with the evaluation of t_2/t_1 ; it is easy to get overflow, i.e., infinite results. A somewhat better result can be obtained. We can write

$$t_2 = (\beta^2 + (L+b)^2)^{L+b}$$
$$t_1 = (\beta^2 + b^2)^b$$

and perform the algebra and substitute $\beta^2 + b^2 = a^2$ to arrive at

$$\frac{t_2}{t_1} = \left[\frac{a^2 + L(L+2b)}{a^2} \right]^b \left(a^2 + L(L+2b) \right)^L$$

It is this expression that is used in the program RLInt when evaluating the line integral along a segment. This does not cure the overflow problem. That has been done by scaling the problem so that the largest value of any point coordinate is 1 in absolute value. This keeps the maximum distance less than $2\sqrt{2}$. When this is done there is no overflow problem when run on machines with the standard exponent range for 32 bit numbers.

A.3.2 Point z at the Left End of the Line Segment

In this case $z = (x, y) = (x_1, y_1)$ and the integral becomes

$$\int_{0}^{L} \ln((-s\cos\alpha)^{2} + (-s\sin\alpha)^{2}) ds$$

This integral reduces to the improper integral

$$\int_{0}^{L} \ln s^2 ds = 2 \int_{0}^{L} \ln s ds$$

We can now write

$$2\int_{0}^{L} \ln s ds = 2\left(\int_{0}^{1} \ln s ds + \int_{1}^{L} \ln s ds\right) \quad 0 \le L \le 1$$

Both integrals are given in tables of integrals as

$$2\int_{1}^{L} \ln s ds = 2[s \ln s - s]_{1}^{L} = 2[L \ln L - L + 1]$$
$$2\int_{1}^{1} \ln s ds = -2$$

Adding these two quantities gives us the value of the line integral as

$$2[L \ln L - L]$$
 for $0 \le L \le 1$

We note that

$$\lim_{L\to 0} (L\ln L) = 0$$

A.3.3 Point z at the Right End of the Line Segment

In this case $z = (x, y) = (x_2, y_2)$ and the integral becomes

$$\int_{0}^{L} \ln((x_{2} - x_{1} - s\cos\alpha)^{2} + (y_{2} - y_{1} - s\sin\alpha)^{2})ds$$

We note that

$$x_2 = x_1 + L\cos\alpha, \ y_2 = y_1 + L\sin\alpha$$

Substituting this into the above integrand and doing the algebra gives

$$\int_{0}^{L} \ln((L-s)^{2}) ds$$

Change the variable to

$$\xi = L - s$$
; $-ds = d\xi$

and the integral can be written, after a little algebra, as

$$\int_{0}^{L} \ln \xi^2 ds = 2 \int_{0}^{L} \ln \xi d\xi$$

Functionally this is the same as before, so again we get the same answer.

$$2[L \ln L - L]$$
 for $0 \le L \le 1$

A.3.4 Point z Between the Left and Right End of the Line Segment

Let $L = L_1 + L_2$ with the point in question at the right end of L_1 , which is also the left end of L_2 . We have that the integral can be considered to be the sum of the integral along L_1 , plus the integral along L_2 . This means that the value of the integral along the segment can be written as

$$L = 2(L_1 \ln L_1 - L_1) + 2(L_2 \ln L_2 - L_2) = 2(L_1 \ln L_1 + L_2 \ln L_2 - L)$$

with

$$L = L_1 + L_2$$
, $0 \le L$, $0 \le L_1$, $0 \le L_2$

The current version of RLInt does not check whether the point z lies on a line segment, so this expression is not currently used.

A.4 Special Case: Domain is a Circle of Radius R

A.4.1 Some Examples

Here we derive the result stated in Section 7.1. The original integral representation of the mapping does not map a simple circle in the manner expected. This has been noted above in Section 7.1, "Circle Expansion With and Without Scaling." We derive here (1) the final radius r_f and the translation vector $r_f - r$ of a point initially at distance r from the origin, due to the expansion, or contraction of a circle of radius R centered at the origin. We also find (2) the final radius and translation vector by explicitly evaluating the line integral for a circle. The first of these translation vectors we call the Expected translation vector and the second one, from the area integral, we call the Calculated translation vector.

In Table 3, "Mapping a Circle," we compare these translation vectors for a circle of radius R = 2 and for a circle of radius R = 1. The areal magnification factor M is defined as

$$M = \frac{\rho}{\rho_f} = \frac{A_f}{A}$$

where ρ is the initial density of the circle and ρ_f is the target density of the circle. The correction factor C is simply the ratio of the *Expected* to the *Calculated* value for the translation vector $(r_f - r)$.

Table 3. Mapping a Circle

R	M	r	r_f Expected	r_f	$r_f - r$ Expected	$r_f - r$ Calculated	$C = \frac{\left(r_f - r\right)_{\text{exp}t.}}{\left(r_f - r\right)_{calc.}}$
2	2	1	1.414	1.5	0.414	0.5	0.828
2	2	2	2.828	3.0	0.828	1.0	0.828
2 2	2	4	4.472	4.5	0.472	0.5	0.944
1	0	0.5	0.0	0.25	-0.5	-0.25	2.000
1	0	1	0.0	0.5	-1.0	-0.5	2.000
1	0	2	1.732	1.75	-0.268	-0.25	1.072
1	0.5	0.5	0.354	0.375	-0.146	-0.125	1.168
1	0.5	1	0.707	0.75	-0.293	-0.25	1.172
1	0.5	. 2	1.871	1.875	-0.129	-0.125	1.032
1	2	0.5	0.707	0.75	0.207	0.25	0.828
1	2	1	1.414	1.5	0.414	0.5	0.828
1	2	2	2.236	2.25	0.236	0.25	0.944
1	8	0.5	1.414	2.25	0.914	1.75	0.522
1	8	1	2.828	4.5	1.828	3.5	0.522
1	8	2	3.317	3.75	1.317	1.75	0.753

We see from this table that the values calculated from the area integral are larger near the edge of the circle than those that we get from the simple expansion, or contraction of the circle.

A.4.2 The Expected Translation Vector

The Expected quantities are arrived at by the simple expansion, or contraction, of a circle. In order to produce the correct areas we need to satisfy the following relations. The original area of the circle is $A = \pi R^2$; the final area, $A_f = M\pi R^2$. For points inside the circle, $r \le R$, we require that $r_f / (\sqrt{M}R) = r/R$. For points outside the circle, $r \ge R$, we require that $\pi r_f^2 - M\pi R^2 = \pi r^2 - \pi R^2$.

From this we obtain the Expected final positions as:

$$r_f = r\sqrt{M} \qquad \qquad r \le R$$

$$r_f = \sqrt{r^2 + (M-1)R^2} \qquad \qquad r \ge R$$

$$r_f = R\sqrt{M} \qquad \qquad r = R$$

The Expected translation vectors are:

$$r_f - r = r\left(\sqrt{M} - 1\right) \qquad r \le R$$

$$r_f - r = \sqrt{r^2 + (M - 1)R^2} - r \qquad r \ge R$$

$$r_f - r = R\left(\sqrt{M} - 1\right) \qquad r = R$$

A.4.3 The Calculated Translation Vector

The line integral can be evaluated explicitly in the special case where the contour of integration is a circle.

Evaluation of the Area Integral for a Circle:

There are two distinct cases that we treat separately. The first is when the point z for which the translation vector is being constructed lies outside the circle and the other is when the point z lies inside the circle.

The Point z is Outside the Circle on the X Axis:

The boundary of integration is a circle. We place the origin at the center of the circle and assume that the point z lies on the positive x-axis (x > R, y = 0). To evaluate the line integral we transform x' and y' to polar coordinates:

$$x' = R\cos(\theta)$$

$$y' = R\sin(\theta)$$

$$dL = Rd\theta$$

$$dx' = dLdx'/dL = -R\sin(\theta)d\theta$$

$$dy' = dLdy'/dL = R\cos(\theta)d\theta$$

$$x - x' = x - R\cos(\theta)$$

$$y - y' = -R\sin(\theta)$$

Using the above we can write

$$r^{2} = (x - x')^{2} + (y - y')^{2}$$
$$r^{2} = (x - R\cos(\theta))^{2} + (R\sin(\theta))^{2}$$

Perform the algebra and simplify to obtain

$$r^{2} = x^{2} \left(1 - 2a \cos(\theta) + a^{2} \right)$$
$$a = R/x \quad (a < 1)$$

This gives us

$$\ln(r^2) = 2\ln(x) + \ln(1 - 2a\cos(\theta) + a^2)$$

The line integrals around the circle R are equal to

$$\oint_C \ln(r^2) dy' = R \int_{-\pi}^{\pi} \ln(r^2) \cos(\theta) d\theta$$

$$\oint_C \ln(r^2) dx' = R \int_{-\pi}^{\pi} \ln(r^2) \sin(\theta) d\theta$$

The X-component of Translation Vector:

We start from the basic relation

$$(x_f - x) = -\frac{1}{4\pi} \frac{\rho - \rho_f}{\rho_f} \oint_c \ln(r^2) dy'$$

$$(x_f - x) = -\frac{R}{4\pi} \frac{\rho - \rho_f}{\rho_f} \int_{-\pi}^{\pi} \ln(r^2) \cos(\theta) d\theta$$

$$(x_f - x) = -\frac{R}{4\pi} \frac{\rho - \rho_f}{\rho_f} \int_{-\pi}^{\pi} (2\ln(x) + \ln(1 - 2a\cos(\theta) + a^2)) \cos(\theta) d\theta$$

The first term of this integral vanishes because

$$\int_{-\pi}^{\pi} \cos(\theta) d\theta = 0$$

This leaves the integral

$$(x_f - x) = -\frac{R}{4\pi} \frac{\rho - \rho_f}{\rho_f} \int_{-\pi}^{\pi} (\ln(1 - 2a\cos(\theta) + a^2)) \cos(\theta) d\theta$$

Because $\cos(-\theta) = \cos(\theta)$, the integrand is an even function of θ and we can write

$$\left(x_f - x\right) = -\frac{R}{2\pi} \frac{\rho - \rho_f}{\rho_f} \int_0^{\pi} \left(\ln\left(1 - 2a\cos(\theta) + a^2\right)\right) \cos(\theta) d\theta$$

From Eq. 865.74 in Dwight's Tables of Integrals we obtain

$$\int_{0}^{\pi} \left(\ln \left(1 - 2a \cos(\theta) + a^{2} \right) \right) \cos(\theta) d\theta = -\pi a \text{ for } 0 < a < 1$$

Thus we arrive at

$$(x_f - x) = -\frac{R}{2\pi} \frac{\rho - \rho_f}{\rho_f} (-\pi a)$$
 where $a = R/x$

which becomes

$$(x_f - x) = \frac{R^2}{2x} \frac{\rho - \rho_f}{\rho_f} = \frac{R^2}{2x} (M - 1)$$

where

$$M = \frac{\rho}{\rho_f} = \frac{\text{original density of } D}{\text{target density of } D} = \frac{\text{target area of } D}{\text{original area of } D} = \frac{A_f}{A}$$

The Y-component of Translation Vector:

We again start from the basic integral

$$(y_f - y) = +\frac{1}{4\pi} \frac{\rho - \rho_f}{\rho_f} \oint \ln(r^2) dx'$$

which becomes

$$(y_f - y) = -\frac{R}{4\pi} \frac{\rho - \rho_f}{\rho_f} \int_{-\pi}^{\pi} \ln(r^2) \sin(\theta) d\theta$$

Because the integrand is an odd function of θ , the integral from $-\pi \le \theta \le \pi$ is zero.

$$(y_f - y) = 0$$

The Point z is Inside the Circle on the X Axis:

We have

$$(x < R, y = 0)$$

We start from the expression for r which is

$$r^{2} = (x - R\cos(\theta))^{2} + (R\sin(\theta))^{2}$$

Perform the algebra and simplify to obtain

$$r^2 = R^2 \left(1 - 2b \cos(\theta) + b^2 \right)$$

with

$$b = x/R \quad (b < 1)$$

Taking the logarithm we get

$$\ln(r^2) = 2\ln(R) + \ln(1 - 2b\cos(\theta) + b^2)$$

The X-component of the Translation Vector:

We again start with the integral that gives the x component of the translation vector.

$$(x_f - x) = -\frac{R}{4\pi} \frac{\rho - \rho_f}{\rho_f} \int_{-\pi}^{\pi} \ln(r^2) \cos(\theta) d\theta$$

Substituting we obtain

$$\left(x_f - x\right) = -\frac{R}{4\pi} \frac{\rho - \rho_f}{\rho_f} \int_{-\pi}^{\pi} \left(2\ln(R) + \ln\left(1 - 2b\cos(\theta) + b^2\right)\right) \cos(\theta) d\theta$$

This integral is functionally the same as the previous X-component translation vector integral. Instead of ln(x) we have ln(R) and instead of a = R/x (a < 1), we have b = x/R (b < 1). Thus we can write

$$(x_f - x) = -\frac{R}{2\pi} \frac{\rho - \rho_f}{\rho_f} (-\pi b)$$
 where $b = x/R$

which becomes

$$(x_f - x) = \frac{x}{2} \frac{\rho - \rho_f}{\rho_f} = \frac{x}{2} (M - 1)$$

The Y-component of the Translation Vector:

The integral can be written as

$$(y_f - y) = -\frac{R}{4\pi} \frac{\rho - \rho_f}{\rho_f} \int_{-\pi}^{\pi} \ln(r^2) \sin(\theta) d\theta$$

Because the integrand is an odd function of θ , the integral from $-\pi \le \theta \le \pi$ is zero. This gives

$$(y_f - y) = 0$$

The Calculated Results for a Circle:

In summary, for a point lying on the positive X-axis,

$$(x_f - x) = \frac{R^2}{2x}(M - 1)$$
 if $x \ge R$

$$(x_f - x) = \frac{x}{2}(M - 1)$$
 if $x \le R$

$$(x_f - x) = \frac{R}{2}(M - 1)$$
 if $x = R$

The symmetry of a circle allows us to write these results as follows.

The Calculated translation vectors:

$$(r_f - r) = \frac{R^2}{2r}(M - 1)$$
 if $r \ge R$

$$(r_f - r) = \frac{r}{2}(M - 1)$$
 if $r \le R$

$$(r_f - r) = \frac{R}{2}(M - 1)$$
 if $r = R$

We use these results to get the calculated radius r_f :

$$r_{f} = \frac{2r^{2} + R^{2}(M-1)}{2r}$$
 if $r \ge R$

$$r_{f} = \frac{r(M+1)}{2}$$
 if $r \le R$

$$r_{f} = \frac{R}{2}(M+1)$$
 if $r = R$

A.4.4 The Correction factor

In order to compare the *Expected* and the *Calculated* values for the mapping of a circle we define a *Correction Factor* C as the ratio $\frac{\left(r_f - r\right)_{\text{expected}}}{\left(r_f - r\right)_{\text{calculated}}}$.

The Correction Factor becomes:

$$C = \frac{\left(\sqrt{M} - 1\right)}{(M - 1)/2}$$
 if $r \le R$

$$C = \frac{\sqrt{r^2 + (M - 1)R^2} - r}{\frac{R^2}{2r}(M - 1)}$$
 if $r \ge R$

The first expression, which is independent of r and R, is the HH scaling factor described in this report. Where the HH scaling has been applied, the factor $C = \frac{\left(\sqrt{M_k} - 1\right)}{\left(M_k - 1\right)/2} \text{ has been applied to } all \text{ translation vectors } \left(r_f - r\right) \text{ associated with a given subdomain } D_k$. An improved correction (which has not been implemented) might use the same expression for points inside D_k , and a more complicated form for points outside D_k :

$$C_{k} = \frac{\sqrt{r_{k}^{2} + (M_{k} - 1)R_{k}^{2}} - r_{k}}{\frac{R_{k}^{2}}{2r_{k}}(M_{k} - 1)}$$

where πR_k^2 is the area of subdomain D_k , and r_k is the distance of the point z from the centroid of D_k .

A.5. Calculation of Region Areas

The calculation of the translation vector requires that we evaluate the contribution from each region D_k . We also need to know the area of each of these regions. It is convenient to accumulate that area from the boundary line segments. We derive below formulas that express the region area as a line integral.

We again use Stoke's Theorem

$$\int_{D} curl\vec{V} \cdot d\vec{S} = \oint_{C} \vec{V} \cdot d\vec{S}$$

and the notation of section A.2.

This time we chose the vector to be

$$\vec{V} = V_{y} \cdot \vec{i} + V_{y} \cdot \vec{j} + V_{z} \cdot \vec{k} = -y' \vec{i} + 0 \vec{j} + 0 \vec{k}$$

where \vec{i} , \vec{j} , and \vec{k} are unit vectors.

For this vector we have

$$curl\vec{V} = \vec{k} \left(\frac{\partial V_{y'}}{\partial x'} - \frac{\partial V_{x'}}{\partial y'} \right) = 1\vec{k}$$

This gives

$$\int_{D} dS = \text{ area of } D = -\oint_{C} y' \cos(\alpha) ds = -\sum_{k=0}^{L_{k}} \int_{0}^{L_{k}} y' \cos(\alpha) ds$$

The line integral along any boundary segment $L = L_k$ can be written as

$$-\int_{0}^{L} (y_1 + y)\cos(\alpha)ds = -\int_{0}^{L} y_1\cos(\alpha)ds - \int_{0}^{L} y\cos(\alpha)ds$$

If we define

$$y = s \sin \alpha$$

these two integrals can be evaluated to give

$$-y_1 L \cos \alpha - \frac{L^2}{2} \sin \alpha \cos \alpha = -y_1 (x_2 - x_1) - \frac{1}{2} (x_2 - x_1) (y_2 - y_1)$$

Summing over all the n line segments k which define a subdomain boundary yields:

$$area = \frac{1}{2} \sum_{k=1}^{n} (x_{1k} - x_{2k}) (y_{1k} + y_{2k})$$

If we choose the vector instead to be

$$\vec{V} = V_{x'}\vec{i} + V_{y'}\vec{j} + V_{z'}\vec{k} = 0\vec{i} + x'\vec{j} + 0\vec{k}$$

the same analysis gives the area as

$$area = \frac{1}{2} \sum_{k=1}^{n} (x_{1k} + x_{2k}) (y_{2k} - y_{1k})$$

In RLInt, the area contribution from line segment k is evaluated at the same time as the contribution of that segment to the displacement vector of all the points z.

Because the n segments bounding any polygon are connected, we can define

$$x_k = x_{1k} = x_{2,k-1}$$
 $(k = 2,3,...n)$

$$x_1 = x_{11} = x_{2n}$$

and similar expressions for y.

With this substitution, both formulas for area given above reduce to:

$$area = \frac{1}{2} \sum_{k=1}^{n} x_k y_{k+1} - x_{k+1} \dot{y}_k$$

Appendix B Description of RLInt I/O Files

B.1 Parameter and cl3 Data Files

The basic RLInt data files are:

File Name Contents

RLInt.dat the map data input file RLInt.par the parameter input file

The parameters set in file RLInt.par were described above in Section 6.3, "Program Options." The file RLInt.dat is described in the next section below. These data files are read with FORTRAN list directed read statements. This is, essentially, field free and the data that are numeric values simply appear as standard Fortran constants. The header lines and the skipped lines are alphanumeric information. This information is not read by RLInt but is useful to identify the data and organize the data file.

The data on each line are read from left to right; the fields are separated by one or more blanks, or a comma. Numeric data fields can, in principle, be skipped by furnishing an empty field that is terminated with a comma. This, however, is not advisable because no attempt is made to define a default setting for each parameter.

The list is read until completed. This means that when two items are to be read, the two items can appear on one line, or on more than one line. However, it is best to follow the example furnished here by having one set of data on each line.

The data appearing to the right of the required variable values are regarded as a comment. No comments may be placed between data fields.

B.1.1 Map Data File RLInt.dat (cl3 format)

The program reads one map data file RLInt.dat. The data file shown below in Figure 41, "Input Data File RLInt.dat," is a complete, valid data set. It has been taken from the first 4 regions of the 44-region Vermont case (a complete listing of this 44-region Vermont case is given in Appendix C.2.2, "File RLInt.dat" below). In Figure 41, we have changed the number of regions to 4. This region number is simply used as an identifier for the region. The program does not care that the last region is 44 and that no intermediate region numbers exist.

The first two lines are header cards that can contain any information. The next line furnishes the requested error limit. For this version of RLInt this is the RMS error which will be tolerated in the magnification M. RLInt will stop when the RMS value of (M-1) is less than this value. Next comes the number of regions, in this case, four. This is followed by the region data, in this case, four sets of data.

Each region data set begins with a header card containing arbitrary information. It is customary (but not required) to include the geocodes (state, county, etc.) identifying the region.

The next two lines of region data are used by RLInt and are important. They contain target area, population, original area present area, present magnification

Their meaning is described below. The information after these numerical fields is a comment.

The region data set then has a line that indicates the number of boundary points in this region (excluding the repeated end point). This is followed by the x,y coordinates for each of the boundary points. Their order is important (see discussion below).

After the complete set of boundary data sets (in this case, four), there are two lines of comments which can contain any alphanumeric information. The program skips them.

Next come the data for the non-boundary points. These begin with one comment line, for example, "Non-boundary points." Then comes the number of non-boundary points and after that the x,y coordinates for each of the points (in the same coordinate system). The example shown contains zero non-boundary points.

The final data line for this type of data is a comment card, for example, the comment "End of non-boundary points."

After reading these data, the program continues to process data lines looking for some additional specific information. The program searches for text specified in the source code. For the present version of RLInt it is

```
parameter (info0 = 'tract information follows:')
parameter (info1 = 'longitude')
parameter (info2 = 'latitude')
parameter (info3 = 'number of map units')
```

The program expects to find this information and copies it to some of the output files. If this information is not found, there could be an error when output files are written.

B.1.2 Comments on the Region Data

There are some flags associated with the region data. The program takes different actions depending on the value of the region data it reads. In the data set there are lines containing target area and present area. We describe here the possible values of these data fields.

When the region has a negative target area (usually -999), it is flagged as a region to be skipped. These regions are pushed, but their boundaries never generate a push. For example, in the Vermont data set given below the first region is so flagged. This region is the total region, the sum of the individual regions, and it would constitute double counting for it to contribute to the transformation vector. The population of this area, though not used by RLInt, is also equal to -999.

For this region the original area and the present magnification are also specified as negative values. A region that originally had a positive magnification can, because of being pushed during the mapping, later have a negative area. Regions for which the magnification becomes negative are always skipped when constructing the transformation vector. Should a region with a magnification that has become negative later become positive, it would normally be re-included in the construction of the mapping vector. The purpose of specifying the original area as negative is to ensure that this area is permanently excluded from contributing to the mapping.

As mentioned earlier, the population data field is not used by the program RLInt. However, a value must be present. The original area of the region is used in constructing the Hsum function. See Section 6.4, "Convergence Criteria," for a definition of that function. The present area, in the initial map, agrees with the original area. If the program does exactly zero mappings because itstp in the

parameter data is zero, then this area on the output files will agree with the original area, if the data have been correctly furnished.

Present area is included in RLInt.dat, but is not used by the program; present areas are recalculated from the region boundaries. The present magnification, defined as (target area / current area) for each of the regions, becomes 1 when the mapping has perfectly converged. In practice a converged mapping has values that meet the prescribed error criterion. This quantity must be present, but the program uses its own calculated value. For the identity mapping, itstp = 0, the program output files have a value that agrees with the input value from this data file.

The region boundary data are furnished as a set of points that are the end points of the line segments that represent the region. The order of these points is important. The algorithm is basically a line integral around the region boundary. The program is blind and simply assumes that the boundary points are furnished in the correct order, from the first line of data input to the last line. If the regions points are furnished in a counter clockwise direction around the boundary, the current area will be positive. If they are furnished in a clockwise direction around the boundary the current area will be negative. If they represent a boundary that crosses itself, the current area will be correctly calculated and could be positive, negative or zero: it is an algebraic sum. Note that in the Vermont example the area furnished for the first region is negative. The region boundary points are furnished in a clockwise direction. The initial point should not be repeated in RLInt.dat; the polygon is closed automatically by the program.

Figure 41. Input Data File RLInt.dat

```
DEMP input file in CLOSE3 format
vt_500k2_hex.cl3 Mar 10, 1994
 1e-6 Convergence RMS error Single precision convergence
        5 # poly, # codes (seq,st,cy,...poly)
 -9.9900000E+02 -9.9900000E+02 -2.4621430E+06 target area UNSPEC., pop., orig. area
 -2.4621430E+06 -9.9900000E+02 pres. area, magnification UNSPEC.
             number of points
      11
            -1273
      -1
     -180
             -1270
     -358
             -1266
     -501
             -1265
     -644
             -1263
     -638
              -942
     -632
              -621
     -675
              -381
              149
              439
              605
     -718
              771
              1018
     -574
              1266
     -322
              1266
     -70
             1266
     201
             1269
     473
              1273
     627
             1272
     781
              1271
     647
              895
     513
              519
     429
              420
              103
              -116
              420
```

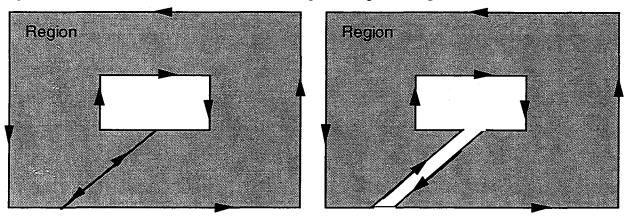
```
50
Region
 4.3502570E+04 9.0367021E+03 5.9097500E+04 target area, pop., orig. area 5.9097500E+04 7.3611528E-01 pres. area, pres. magnification
             number of points
                193
     -384
                -52
     -383
                145
     -381
                343
                391
     -530
     -679
                439
Region
 1.0403520E+04 2.1611021E+03 1.4133000E+04 target area, pop., orig. area 1.4133000E+04 7.3611528E-01 pres. area, pres. magnification
             number of points
     -321
                202
     -261
-235
                62
                119
     -209
                176
                259
     -295
     -381
                343
  egion 44 50 27 0 -4
2.7773094E+04 2.0310211E+04 1.0881800E+05 target area, pop., orig. area
Region
 1.0881800E+05 8.9850098E-01 pres. area, pres. magnification
             number of points
              -170
     -182
               -223
              -473
      -80
      23
              -723
     116
              -420
     209
              -116
End of the boundary points, skip this line
skip this line
Non-Boundary points
         # of these points
End of non-boundary points
tract information follows:
              longitude in degrees at (x=0)
 43.87635 latitude in degrees at (y=0)
      10 number of map units in one kilometer
     -718 minimum x (map units)
     781 maximum x (map units)
    -1273 minimum y (map units)
    1273 maximum y (map units)
```

The basic region data thave been described above. There is an attempt to check that the amount of data will not overflow program storage. Also, the runs made have been with array bounds checking, to check further that no storage violations occur. In principle, RLInt checks the number of regions and the number of data points to see whether the allocated storage is sufficient. However, the program does not check for all possible errors in RLInt.dat and RLInt.par. It is very important that the input data be verified, to the extent that is practical. One easy, quick check is to take exactly one iteration and verify that the output data sets agree with the input data sets with regard to points, areas, etc.

Each region boundary must be completely defined as a separate polygon. RLInt is inefficient in that common boundaries are stored twice. Furthermore, the line integrals corresponding to each line segment are evaluated twice, which is unnecessary. In the future, RLInt could be modified to reduce storage requirements and execution time.

A region boundary should be stored counter clockwise for positive area or clockwise for negative area. A hole in a region can be obtained by making a cut to the inner (hole) boundary, traversing the hole boundary clockwise, and then traversing the same cut back out to the outer boundary. The line integral along the cut will cancel out. An example is shown below.

Figure 42. How to Use a Cut for Generating a Doughnut Region



The inner boundary appears to be traversed in a direction that is opposite to the outer boundary. However, it can seen from the figure that the (net) region boundary is traversed in one direction only, counter clockwise. The area calculated for this region will be that of the shaded region in the figure and the line integrals along the cut will cancel. The location of the cut is immaterial as long as it joins the inner and outer boundaries.

A discussion of machine precision, which also pertains to the data input, is given in Section 6.4.2, "Discussion of Machine Precision." We note here that the map is normally scaled by the program to avoid numerical difficulties. If the map is not scaled (see the description of the parameter file data), then it must fit in a rectangle whose diagonal is not larger than about 11 or 12. The scaling does not center the origin at the map center; it simply fits the map into a square of side ± 1 . This means that the maps must be reasonably well centered about the origin of their coordinates. This is a minor restriction that can be handled in a number of ways. Map coordinates can be in any right-handed Cartesian coordinate system. That is, x and y must have the same units, with x increasing to the right and y increasing upward. The units are arbitrary.

B.2 Output Files

B.2.1 Description of Output files

The principal goal of program RLInt is to transform a given initial map into a final map. We have discussed above the basic input file that defines the initial map. We now give descriptions of the output files that can be generated during the run. We note that the generation of output files is controlled by the settings of parameters in the parameter data file RLInt.par. A complete example file is included in Appendix C.2.1, "File RLInt.par."

For each file that the program can produce, we summarize below its purpose and contents.

B.2.2 Basic Output Files

These files are the basic, minimal output from a mapping run. The files described in Sections B.2.3 and B.2.4 can be optionally obtained by setting the parameters in RLInt.par. See Section 6.3, "Program Options."

File Name

Contents

RLInt.out

This file is created if idisk = 0.

Created after the call to rtrans, this file is the current state of the boundary points and the non-boundary points. It can be thought of as the image that the mapping produces of the input file RLInt.dat. To continue the mapping from the present state, copy this file to the file RLInt.dat and run the program. The output file RLInt.out has essentially the same format as RLInt.dat file listed in Section C.2.2.

RLInt.plot

This file is created if idisk = 0.

This file contains basically the same information as RLInt.out, furnished in a comma delimited form that is convenient for input into a plotting program. The regions can be plotted from this file. This file is not suitable as a RLInt data input file; it does not have the required format. The areas and magnifications are omitted from the region data in this file. Only the coordinates of the region boundary points and the non-boundary points are included. In RLInt.plot, the boundary points include closure points so that when plotted as line segments there is no gap between the last point and the first point.

RLInt.out.msg

This file is always produced.

As the iterations are performed, regions may be dropped (negative magnification) or recovered (if magnification returns to positive). This information is logged in this file. Other information pertaining to the progress of the mapping can also be logged here.

stdout

This is the standard output file and is always produced.

It includes both a summary and a log of the mapping run. The contents of this file can vary, depending on the setting of the parameters in the program parameter file.

This file can be redirected to a disk file and saved, if that is desired. When this is done, the program can be run as a batch, or background process, if the parameters are set so that no input from the standard input file stdin is requested (iprmpt = 0).

B.2.3 Internally Stored Output Files

The next set of files is written when information is stored internally. If requested, the program will save information at each step of the mapping for printing after the mapping subroutine rtrans has completed. It is not necessary to store this information. A parameter can be set to skip that step, saving the time and space required to save the results. See Section 6.3.6, "Output/Reports," for a description of the parameter settings.

The following tables are created if icheck = 1 and itable ≥ 1 .

File Name

Contents

RLInt.out.sum

When information is stored internally during the run (icheck = 1), this file can be requested as program output. It contains, in table form, information at each iteration step including the RMS relative error and HSum and, for each region, the magnification, the current area (arak), the target area (ara0k), and the region's relative error (M_k-1) . Only areas with positive magnifications are included in the RMS sum

$$\left(\sqrt{\frac{1}{n}\sum_{k=1}^{n}(M_k-1)^2}\right)$$
. The tables are generated for each

step in the mapping. If there are ten mappings, there are ten tables, each containing information for all the regions. A map with many regions and many steps requires a lot of disk space. If disk space is insufficient, the program warns the user of that fact.

Following these tables, there is an iteration history, giving the x-y coordinates for every boundary point and non-boundary point. The initial coordinates and the values after the last eight iterations are listed. An example is given in Section C.3.3

RLInt.out.plot

This file is produced if information has been stored internally during the run (icheck = 1). It contains for each iteration step: an iteration history for each region, including the region number, the iteration number, the region magnification, present area and target area, relative error M_k-1 , and (for the map as a whole) the RMS relative error, HSum, the target map area and the current total map area. It is comma delimited and can be used to plot a region's behavior as a function of the iteration count. It also contains the region boundaries from iteration 0 and the last few iterations. The difference between RLInt.out.plot and RLInt.out.sum is that the former gives the behavior of each region as a function of the mapping steps. RLInt.out.sum has a table for each step that describes all the regions for that step. RLInt.out.plot (Section C.3.4) contains a table for each region, listing the iteration history for that region. RLInt.out.sum (Section C.3.3) contains a table for each iteration, listing the values from each region for that step.

B.2.4 Intermediate Mapping Files

The next files are obtained when the program parameters have been set to produce disk file output at intermediate steps in the mapping (idisk > 0). They are not created unless requested. When idisk > 0, the files RLInt.out and RLInt.plot files are not created; they would be redundant with RLInt.*.NNNN. See Section 6.3.6, "Output/Reports," for details on setting the parameters.

File Name

Contents

RLInt.sum

This file is created if isum = 1.

For each region there is a table showing the state of the region for each requested output step of the iteration. The quantities tabulated are the iteration counts, current area (areak), target area (area0k), current magnification, and relative magnification error (eps). There is a summary of the RMS magnification error including the iteration count, the number of dropped regions and the number of regions remaining that contribute to the transformation vector. The function The number of dropped regions Hsum is also given. includes the regions with target area -999, which never enter into the translation vector. This is a comma delimited table; the tables can be plotted to see the convergence of any particular region as the iteration proceeds. RLInt.sum contains information for the complete run and is not completed (written) until the current mapping is complete. This is written from the subroutine rtrans just before it returns control to the main program. This file collects as a summary the information written in each of the NNNN files described below.

RLInt.sum.NNNN

This file is created if isum = 1 and idisk > 0.

The file shows the state of all the regions at step NNNN of the mapping. The file is comma delimited and corresponds to the file RLInt.sum after step NNNN. For each region it includes the area (areak), the target area (area0k), the magnification (Magk) and the region magnification relative error (Mrelerk). The NNNN files are written after steps which are specified by the parameter idisk. See Section 6.3.6, "Output/Reports', for a description of the parameters that control this writing.

RLInt.out.NNNN

This file is created if idisk > 0.

This is the RLInt.out file at iteration NNNN. The file is suitable for use as an input file RLInt.dat. It is a little different from RLInt.out in that it contains the pushes that produced the current points. If necessary, one could go back one iteration by subtracting these values from the current points. The "push" data follow and are not used by the program. Tract summary information, also not used by RLInt, is written at the end of the file.

RLInt.plot.NNNN

This file is created if idisk > 0.

This is the RLInt.plot file at iteration NNNN. The file can be used to make plots of the regions after iteration NNNN. The "pushes" are also included in this file. It is a comma delimited file.

RLInt.*.now

RLInt.out.now and RLInt.plot.now are written if inow > 0; also, RLInt.sum.now is written if inow > 0 and isum > 0. They are copies of the lastest version of RLInt.*.NNNN and are updated as the run proceeds.

These files are readable during the run and can furnish a dynamic window into the progress of the mapping; for example, they could be used interactively to display the regions as the run progresses.

*.zzz

Files that end in .zzz are temporary binary files, which are deleted at the end of the run. Should they be left over from a run that aborts, they can be deleted, though that is not necessary.

Appendix C. Example of Complete Run

C.1 Description of Example Run

In this appendix the Vermont pop80 44-region map is provided as a complete example. The parameter file RLInt.par and the initial map data file RLInt.dat are given in their entirety. The program output from this run includes the files RLInt.std, RLInt.msg, RLInt.out.sum, and RLInt.out.plot. This run requested intermediate output at each iteration step (idisk = 1), which is not presented in this report. The RMS error criterion was specified as $5x10^{-5}$, which was achieved in seven iterations. This run took 24.6 seconds on a Sun SPARC 10. The RMS function was equal to 0.703 initially and 0.000019 after seven iterations.

This example can be used to test the program RLInt. It also furnishes an example that can be used with other DEMP algorithms, for comparison with RLInt.

C.2 Data input Files

C.2.1 File RLInt.par

The parameter file specifies iprint = 10 to produce intermediate output; itable = 10 to create the internally stored tables RLInt.out.sum and RLInt.out.plot; maxit0 = 20 to have a maximum of 20 fixed point iterations; maxit = 0 to have no partial step transformations; istp = 16 to stop after 16 iterations, (provided convergence is not obtained sooner). The mapping has HH scaling (iscale = 1); the data region is scaled into the ± 1 square to avoid overflow (iara = 1); icheck = 1 to save results for files RLInt.out.sum and RLInt.out.plot. There is no resetting of the mapping done (ireset should be left at 0 because not fully implemented). The Russian style of partial transformation mapping is selected (iciset = 0); however, these steps are skipped because maxit = 0. Intermediate disk output is requested at every iteration step (idisk = 1); a final summary file of this output at the end of the run is requested (isum = 1); no dynamic (overwritten) output files are requested (inow = 0). The program will erase all RLInt files up to NNNN = 16 (nfdel = 16). No interactive prompting is requested; the program just reads the data and executes (iprmpt = 0).

```
Data Parameter File RLInt.par Parameter File: RLInt.par for program test23.f

10 iprint 0 no print, > 0 is print out Print Flag
10 itable table to RLInt.out.sum, RLInt.out.plot
20 maxit0 iteration max. Fixed point
10 maxit iteration max. Fixed point
11 iscale 10 Russian, 1 HHH Transformation
12 iscale 10 Russian, 1 HHH Transformation scaling
12 icheck 10 no save, 1 save Result saving flag (in core)
13 iciset 10 Russian, 1 ci = 1/2
14 idisk 10 no intermediate disk output, <>0 output mod(idisk)
15 isum 10 no disk summary file, 1 write output (idisk.ne.0)
15 inow 16 no file deletes, >=0 delete RLInt previous run files
16 nfdel <0 no file deletes, >=0 delete RLInt previous run files
16 iprmpt 17 on interactive prompting, <>0 prompting
18 parameter data
```

C.2.2 File RLInt.dat

This file contains the data for the Vermont pop80 44-region map, in the cl3 format described in the body of this report. The file is complete and was used to generate the Vermont pop80 44-region results described in the body of this report.

vt_500k2_hex_pop80.cl3	Region 6 50 3 0 1
5e-5 Convergence RMS error 44 5 # poly, # codes (seq,st,cy,poly)	64912.10 13484.06 82468.50 targ area, pop, orig area 82468.50 0.7871139 current area and magnification
Region 1 0 0 0 1	6 number of points
-999.0000 -999.0000 -2462143. targ area, pop, orig area	-501 -1265
-2462143999.0000 current area and magnification 30 number of points	-358 -1266 -318 -978
11 -998	-277 -690
-1 -1273 -180 -1270	-461 -977 -644 -1263
-358 -1266	Region 7 50 3 0 -1
-501 -1265	5712.873 1186.724 7258.000 targ area, pop, orig area
-644 -1263 -638 -942	7258.000 0.7871139 current area and magnification
-632 -621	6 number of points -455 -656
-675 -381	-277 -690
-718 -140 -699 149	-296 -666 -314 -642
-679 439	-473 -632
-699 605	-632 -621 -632 -632 -632 -632 -632 -632 -632 -632
-718 771 -646 1018	Region 8 50 3 0 -2 89897.45 18674.22 114211.5 targ area, pop, orig area
-574 1266	114211.5 0.7871138 current area and magnification
-322 1266 -70 1266	6 number of points
201 1269	-638 -942 -644 -1263
473 1273	-461 -977
627 1272 781 1271	-277 -690 -455 -656
647 895	-632 -621
513 519	Region 9 50 5 0 1
429 420 345 322	13138.90 2729.318 22680.00 targ area, pop, orig area 22680.00 0.5793167 current area and magnification
277 103	6 number of points
209 -116	282 611
116 -420 23 -723	513 519 300 653
Region 2 50 1 0 1	88 788
43502.57 9036.702 59097.50 targ area, pop, orig area 59097.50 0.7361153 current area and magnification	70 746 52 704
6 number of points	Region 10 50 5 0 -1
-532 193	23599.05 4902.183 40736.00 targ area, pop, orig area
-384 -52 -383 145	40736.00 0.5793168 current area and magnification 6 number of points
-381 343	198 513
-530 391 -570 430	52 704 74 536
-679 439 Region 3 50 1 0 -1	96 368
10403.52 2161.102 14133.00 targ area, pop, orig area	220 345
14133.00 0.7361153 current area and magnification 6 number of points	345 322 Region 11 50 5 0 -2
-321 202	35294.58 7331.672 60924.50 targ area, pop, orig area
-261 62	60924.50 0.5793167 current area and magnification
-235 119 -209 176	6 number of points 282 611
-295 259	52 704
-381 343 Region 4 50 1 0 -2	198 513 345 322
69868.76 14513.70 94915.50 targ area, pop, orig area	429 420
94915.50 0.7361153 current area and magnification	513 519 Project 12 50 5 0 2
6 number of points -532 193	Region 12 50 5 0 -3 52206.87 10844.83 90118.00 targ area, pop, orig area
-679 439	90118.00 0.5793167 current area and magnification
-699 149 -718 -140	6 number of points 300 653
-551 -96 ×	513 519
-384 -52	469 758
Region 5 50 1 0 -3 17785.28 3694.501 24161.00 targ area, pop, orig area	426 998 257 893
24161.00 0.7361153 current area and magnification	88 788
6 number of points	Region 13 50 7 0 1
-383 145 -384 -52	108316.1 22500.29 35476.50 targ area, pop, orig area 35476.50 3.053179 current area and magnification
-323 5	6 number of points
-261 62 -321 202	-320 739 -359 832
-381 343	-539 801
•	-718 771 -499 709
	-499 709 -280 647
	Region 14 50 7 0-1
	153025.3 31787.64 50120.00 targ area, pop, orig area 50120.00 3.053179 current area and magnification
	6 number of points
	-480 543 -679 439
	-530 391
	-381 343
	-331 495

Region 15 50 7 0 -2	Region 24 50 15 0 -1
80135.27 16646.34 26246.50 targ area, pop, orig area	26848.85 5577.257 32771.00 targ area, pop, orig area
26246.50 3.053179 current area and magnification 6 number of points	32771.00 0.8192868 current area and magnification 6 number of points
-539 801	-320 739
-359 832	-280 647
-481 884 -602 937	-181 828 -81 1010
-660 854	-220 921
-718 771	-359 832
Region 16 50 7 0 -3	Region 25 50 15 0 -2
214702.6 44599.73 70321.00 targ area, pop, orig area	9106.372 1891.648 11115.00 targ area, pop, orig area
70321.00 3.053179 current area and magnification 6 number of points	11115.00 0.8192868 current area and magnification 6 number of points
-480 543	-15 857
-280 647	52 704
-499 709 ·	70 746
-718 771 -699 605	88 788 3 899
-679 439	-81 1010
Region 17 50 9 0 1	Region 26 50 17 0 1
21137.01 4390.749 97019.00 targ area, pop, orig area	53283.30 11068.43 84585.00 targ area, pop, orig area
97019.00 0.2178647 current area and magnification	84585.00 0.6299380 current area and magnification
6 number of points 469 758	6 number of points 0 30
513 519	209 -116
647 895	152 126
781 1271	96 368
603 1134	-57 272 200 136
426 998 Perion 18 50 0 0 1	-209 176 Pagion 27 50 17 0 1
Region 18 50 9 0 -1 9253.693 1922.251 42474.50 targ area, pop. orig area	Region 27 50 17 0-1 36390.58 7559.341 57768.50 targ area, pop, orig area
42474.50 0.2178647 current area and magnification	57768.50 0.6299381 current area and magnification
6 number of points	6 number of points
603 1134	152 126
781 1271 627 1272	209 -116 277 103
473 1273	345 322
449 1135	220 345
426 998	96 368 .
Region 19 50 11 0 1	Region 28 50 17 0 -2
71803.52 14915.60 79505.50 targ area, pop, orig area	19791.39 4111.226 31418.00 targ area, pop, orig area
79505.50 0.9031265 current area and magnification 6 number of points	31418.00 0.6299380 current area and magnification 6 number of points
-220 921	0 30
-81 1010	-209 176 -235 119
-328 1138	
-574 1266 467 1040	-261 62 -26 -27
-467 1049 -359 832	209 -116
Region 20 50 11 0-1	Region 29 50 19 0 1
58262.50 12102.75 64512.00 targ area, pop, orig area	32066.51 6661.111 55315.50 targ area, pop, orig area
64512.00 0.9031265 current area and magnification	55315.50 0.5797020 current area and magnification
6 number of points -328 1138	6 number of points 3 899
-81 1010	88 788
-76 1138	257 893
-70 1266	426 998
-322 1266 -574 1266	172 1004
-574 1266 Region 21 50 11 0 -2	-81 1010 Region 30 50 19 0 -1
37402.98 7769.646 41415.00 targ area, pop, orig area	43075.92 8948.074 74307.00 targ area, pop, orig area
41415.00 0.9031265 current area and magnification	74307.00 0.5797021 current area and magnification
6 number of points	6 number of points
-481 884 -350 832	178 1132 426 998
-359 832 -467 1049	449 1135
-574 1266	473 1273
-588 1101	201 1269
-602 937	-70 1266
Region 22 50 13 0 1 22206.93 4613.000 16729.00 targ area, pop, orig area	Region 31 50 19 0 -2 37697.45 7830.814 65029.00 targ area, pop, orig area
16729.00 1.327451 current area and magnification	65029.00 0.5797021 current area and magnification
6 number of points	6 number of points
-660 854	172 1004
-602 937	426 998
-588 1101 -574 1266	178 1132 -70 1266
-646 1018	-76 1138
-718 771	-81 1010
Region 23 50 15 0 1	Region 32 50 21 0 1
44760.91 9298.095 54634.00 targ area, pop, orig area	102431.0 21277.78 84194.50 targ area, pop, orig area
54634.00 0.8192868 current area and magnification	84194.50 1.216599 current area and magnification
6 number of points -114 675	6 number of points
-114 675 52 704	6 number of points -508 -337 -384 -52
-114 675 52 704 -15 857	6 number of points -508 -337 -384 -52 -551 -96
-114 675 52 704	6 number of points -508 -337 -384 -52

Region 33 50 21 0 -1 82874.13 17215.28 68119.50 targ area, pop, orig area 68119.50 1.216599 current area and magnification 6 number of points	Region 42 50 27 0 -2 19783.64 4109.617 22018.50 targ area, pop, orig area 22018.50 0.8985010 current area and magnification 6 number of points
-407 -422 -632 -621 -473 -632	-283 -138 -182 -223 -222 -81
-314 -642 -248 -433 -182 -223	-261 62 -323 5 -384-52
Region 34 50 21 0 -2 95576.66 19853.95 78560.50 targ area, pop, orig area 78560.50 1.216599 current area and magnification 6 number of points	Region 43 50 27 0 -3 68190.84 14165.14 75894.00 targ area, pop. orig area 75894.00 0.8985010 current area and magnification 6 number of points
-508 -337 -632 -621	-80 -473 -182 -223 -248 -433
-407 -422 -182 -223 -283 -138	-246 -433 -314 -642 -146 -683
-384 -52 Region 35 50 23 0 1	23 -723 Region 44 50 27 0 -4 97773.09 20310.21 108818.0 targ area, pop. orig area
105689.3 21954.62 71336.50 targ area, pop, orig area 71336.50 1.481560 current area and magnification 6 number of points	108818.0 0.8985010 current area and magnification 6 number of points
-143 355 96 368	13 -170 -182 -223
-92 507 -280 647 -331 495	-80 -473 23 -723 116 -420
-381 343 Region 36 50 23 0 -1	209 -116 End of the boundary points, skip this line
62020.32 12883.36 41861.50 targ area, pop. orig area 41861.50 1.481560 current area and magnification	skip this line Non-Boundary points
6 number of points -143 355	0 # of these points End of non-boundary points
-381 343 -295 259	geoarea information follows: seq no, 3 geocodes, no of polygons,
-209 176 -57 272	pop, target area, present area, mag-1, hterm 1 50 1 0 4
96 368 Region 37 50 23 0 -2	29406.00 141560.1 192307.0 -0.2638846 7.3886313E-03 2 50 3 0 3
84509.66 17555.02 57041.00 targ area, pop, orig area 57041.00 1.481560 current area and magnification	33345.00 160522.4 203938.0 -0.2128861 4.7691595E-03 3 50 5 0 4
6 number of points -92 507	25808.00 124239.4 214458.5 -0.4206832 2.6608735E-02 4 50 7 0 4
96 368 74 536	115534.0 556179.3 182164.0 2.053179 0.1021529 5 50 9 0 2
52 704 -114 675	6313.000 30390.71 139493.5 -0.7821354 0.1590808 6 50 11 0 3
-280 647 Region 38 50 25 0 1	34788.00 167469.0 185432.5 -9.6873462E-02 7.8258879E-04 7 50 13 0 1
79167.30 16445.26 82890.00 targ area, pop, orig area 82890.00 0.9550886 current area and magnification	4613.000 22206.93 16729.00 0.3274510 5.4882118E-04 8 50 15 0 3
6 number of points 11 -998 23 -723	16767.00 80716.14 98520.00 -0.1807132 1.5949785E-03 9 50 17 0 3 22739.00 109465.3 173771.5 -0.3700620 1.5343217E-02
-127 -707 -277 -690	10 50 19 0 3 23440.00 112839.9 194651.5 -0.4202979 2.4090962E-02
-139 -982 -1 -1273	11 50 21 0 3 58347.00 280881.8 230874.5 0.2165995 3.6160119E-03
Region 39 50 25 0 -1 98627.71 20487.74 103265.5 targ area, pop, orig area	12 50 23 0 3 52393.00 252219.3 170239.0 0.4815599 1.0822490E-02
103265.5 0.9550887 current area and magnification 6 number of points	13 50 25 0 2 36933.00 177795.0 186155.5 -4.4911265E-02 1.5967226E-04
-180 -1270 -1 -1273	14 50 27 0 5 51030.00 245657.8 273408.5 -0.1014990 1.2732196E-03
-139 -982 -277 -690	0.2178647 minimum magnification 3.053179 maximum magnification
-318 -978 -358 -1266	0.00000E+00 hsum (polygons) 0.00000E+00 log10(hsum) (polygons)
Region 40 50 27 0 1 54005.30 11218.41 60106.00 targ area, pop. orig area	0.3582322 hsum (geoareas) -0.4458354 log10(hsum) (geoareas)
60106.00 0.8985010 current area and magnification 6 number of points 13 -170	511456.0 total population 2462143. original land area
209 -116 -26 -27	2462143. target land area 2462143. present land area 0.0000E+00 present water area
-261 62 -222 -81	2462143. present total area -2462143. external boundary area incl islands
-182 -223 Region 41 50 27 0 -1	14 number of (land) geoareas 43 normal land polygons (normal geocodes, orig area gt 0)
5904.949 1226.623 6572.000 targ area, pop, orig area 6572.000 0.8985010 current area and magnification	0 holes in land polygons (normal geocodes, orig area it 0) 43 total land polygons
6 number of points -146 -683	0 water polygons (zero geocodes, orig area gt 0) 1 ext boundary incl islands (zero geocodes, orig area lt 0)
-314 -642 -296 -666	44 total polygons incl ext boundary -72.47850 longitude in degrees at (x=0)
-277 -690 -127 -707	43.87635 latitude in degrees at (y=0) 10 number of map units in one kilometer
23 -723	-718 minimum x (map units) 781 maximum x (map units)
	-1273 minimum y (map units) 1273 maximum y (map units)

C.3 Data output Files

C.3.1 File RLInt.std

Output File: RLInt.out.0001

This is output that appears on standard output. In this run, it was redirected to the file RLInt.std.

```
Output File: RLInt.plot.0001
Update all Boundary point pushes
All Non-boundary point pushes
All points a & b have been updated
Copyright (c) 1995 The Regents of the University of California BEGIN RLInt
 Initialize
                                                                                                                                                      Bottom of transformation loop
OPEN file RLInt.par
Parameter File: RLInt.par for program test23.f
Debug Printing Flag, iprint = 10
Convergence Table Flag, itable = 10
                                                                                                                                                    Bottom of fixed point loop
                                                                                                                                                   Top of Fixed point loop: it0 = 2
Top of Transformation loop:it = 0
                                                                                                                                                       iteration = 2
ci = 1.00000
   Fixed point iteration max.
                                                     maxit0 =
   Transformation iteration max. maxit =
                                                                                                                                                        c1
Calculate areas, 11115
Check for stopping:
RMS = 1.101E-02
= 7.054E-1
2.462E
                                              itstp = 16
   Stop at iteration
                                                                                                                                                        Calculate areas, magnifications, errors
   Transformation scaling.
                                                    iscale =
                                               ira = 1
icheck =
   Data scaling flag
   Data saving flag
                                                                                                                                                                                              7.054E-05
   Negative magnification flag
                                                      ireset =
                                                                                                                                                                                              2.462E+06
2.460E+06
                                                                                                                                                        Total Present Area = 2.460F
Output File: RLInt.sum.0002
Output File: RLInt.out.0002
   Coefficient flag
                                              iciset =
   Disk files flag
                                             idisk =
   Disk files flag
                                             isum =
  Disk files flag inow = 0
No.of <>.NNNN files to delete nfdel =
                                                                                                                                                        Output File: RLInt.plot.0002
Update all Boundary point pushes
All Non-boundary point pushes
All points a & b have been updated
Prompting flag
CLOSE file: RLInt.par
                                               iprmpt =
                                                                                                                                                   Bottom of transformation loop
Bottom of fixed point loop
 OPEN file RLInt.dat
   DEMP input file in CLOSE3 format
   1 Average density rho0 (not used)
Convergence relative error = 5.0E-0
                                                                                                                                                  Top of Fixed point loop: it0 = 3
Top of Transformation loop:it = 0
                                                                    5.0E-05
Number of regions, maxd = 44
Number of non-boundary points maxib =
CLOSE file: RLInt.dat
                                                                                                                                                       iteration = 3
ci = 1.00000
                                                                                                                                                       Calculate areas, Illies
Check for stopping:
RMS = 2.402E-03
= 3.627E-06
2.462E+0
                                                                                                                                                        Calculate areas, magnifications, errors
DELETE All RLInt output files:
   RLInt.out
                                                                                                                                                        Total Target Area = 2.462E+06
Total Present Area = 2.462E+06
Output File: RLInt.sum.0003
   RLInt.out.rnsg
   RLInt.out.now
RLInt.out.plot
                                                                                                                                                        Output File: RLInt.out.0003
Output File: RLInt.plot.0003
Update all Boundary point pushes
All Non-boundary point pushes
   RLInt.out.sum
   RLInt.plot
RLInt.plot.now
                                                                                                                                                     All points a & b have been updated
Bottom of transformation loop
   RLInt.sum.now
   The above list of files has been deleted
DELETF. files:
                                                                                                                                                   Bottom of fixed point loop
   RLInt.sum.0000 thru RLInt.sum.0016
RLInt.out.0000 thru RLInt.sum.0016
RLInt.plot.0000 thru RLInt.plot.0016
                                                                                                                                                   Top of Fixed point loop:
                                                                                                                                                     Top of Transformation loop:it = 0
  The above list of files has been deleted
                                                                                                                                                       iteration = 4
ci = 1.00000
                                                                                                                                                       Calculate areas, magnifications, errors
BEGIN rtrans
                                                                                                                                                      Calculate areas, magnifications, error. Check for stopping:

RMS = 6.802E-04

DMhsum = 2.697E-07

Total Target Area = 2.462E+06

Output File: RLInt.sum.0004

Output File: RLInt.out.0004

Output File: RLInt.plot.0004

Update all Boundary point pushes

All Non-boundary point pushes

All points a & b have been updated

Bottom of transformation loop
LOG File: RLInt.out.msg
Skipping region 1 Target area -999
Top of Fixed point loop: it0 = 0
Top of Transformation loop:it = 0
    iteration = 0
ci = 1.00000
    Calculate areas, magnifications, errors
     Check for stopping:

RMS = 7.034E-01

DMhsum = 3.582E-0
                                          3.582E-01
2.462E+06
2.462E+06
    DMhsum
   DMhsum = 3.582E-01
Total Target Area = 2.462E+06
Total Present Area = 2.462E+06
Output File: RLInt.sum.0000
Output File: RLInt.out.0000
Output File: RLInt.plot.0000
Update all Boundary point pushes
All Non-boundary point pushes
All points a & b have been updated
Bottom of transformation loop
                                                                                                                                                     Bottom of transformation loop
                                                                                                                                                  Bottom of fixed point loop
                                                                                                                                                  Top of Fixed point loop:
                                                                                                                                                                                                 it0 = 5
                                                                                                                                                     Top of Transformation loop:it =
                                                                                                                                                      iteration = 5
ci = 1.00000
  Bottom of transformation loop
                                                                                                                                                       Calculate areas, magnifications, errors
                                                                                                                                                       Check for stopping:
RMS = 2.035E-04
Bottom of fixed point loop
                                                                                                                                                       Top of Fixed point loop:
  Top of Transformation loop: t = 0
    iteration = 1
ci = 1.00000
                                                                                                                                                        Output File: RLInt.out.0005
Output File: RLInt.plot.0005
Update all Boundary point pushes
    Calculate areas, magnifications, errors
    Check for stopping:

RMS = 1.231E-01

DMhsum = 5.795E-
    DMhsum = 5.795E-03
Total Target Area = 2.462E+06
Total Present Area = 2.344E+06
Output File: RLInt.sum.0001
Output File: PLI Tet and Occ.
                                                                                                                                                     All Non-boundary point pushes
All points a & b have been updated
Bottom of transformation loop
                                                                                                                                                  Bottom of fixed point loop
```

```
Top of Fixed point loop:
                                                                                                                  DMhsum
                                                                                                                                          = 1.721E-10
   op of Transformation loop:it =
                                                                                                                   Total Target Area = 2.462E+06
Total Present Area = 2.462E+06
Output File: RLInt.sum.0007
   iteration = 6
ci = 1.00000
    Calculate areas, magnifications, errors
                                                                                                                    Output File: RLInt.out.0007
   Check for stopping:
RMS = 6.187E-05
DMbsum = 1.905E-09
Total Target Area = 2.462E+06
Output File: RLInt.sum.0006
                                                                                                              Output File: RLInt.plot.0007
GOTO DONE
                                                                                                               Transformation Converged:
                                                                                                                 RMS Magnification error 0th step
                                                                                                                                                             = 7.03E-01
    Output File: RLInt.out.0006
Output File: RLInt.plot.0006
                                                                                                                RMS Magnification error all regions = 1.90E-05
DM h function = 1.72E-10
Requested error = 5.00E-05
   Update all Boundary point pushes
All Non-boundary point pushes
All points a & b have been updated
                                                                                                                 Total Target area
                                                                                                                 Total Current area
                                                                                                                                                       = 2.46E+06
  Bottom of transformation loop
                                                                                                                 Number of non-skipped regions
Bottom of fixed point loop
                                                                                                                 Transformation iterations taken
                                                                                                                Fixed point iterations taken
                                                                                                                Mapping coefficient ci
Output File: RLInt.sum
Top of Fixed point loop:
                                   it0 = 7
                                                                                                                                                          = 1.00E+00
  Top of Transformation loop:it =
  iteration = 7
ci = 1.00000
                                                                                                              END rtrans
                                                                                                                Convergence Table on File: RLInt.out.sum
Plot Tables on File: RLInt out plot
   Calculate areas, magnifications, errors
   END RLInt
```

C.3.2 File RLInt.msg

This file contains messages that indicate which regions were lost due to negative magnifications. If the regions were later recovered, that information would be reported here. For this run, no regions were lost.

```
RMS Magnification error 0th step = 7.03E-01
RMS Magnification error all regions = 1.90E-05
DM h function = 1.72E-10
Requested error = 5.00E-05
Total Target area = 2.46E+06
Total Current area = 2.46E+06
Number of non-skipped regions
Transformation iterations taken = 0
Fixed point iterations taken = 7
Mapping coefficient ci = 1.00E+00
```

END FILE: RLInt.out.msg

C.3.3 File RLInt.out.sum

This file was written from data stored internally during the run by specifying icheck = 1. The first section describes each region after each iteration. The second section provides initial boundary point coordinates, and values after each of the seven steps. In this example there were no non-boundary points.

```
File: RLInt.out.sum
Input scale flag iara = 1
Target RMS error: relerr = 5.00E-05
Achieved RMS error reler = 1.90E-05
DM h function
                              dmhsum = 1.72E-10
Target total area aretot = 2.46E+06
Current total area arctot = 2.46E+06
 Scaling flag
                           iscale =
Convergence Table:
                                   DMhsum trgtArea curntArea
  k armag
                       arak
                                           ara0k
                                                             reler
0 0 0 1.0000 7.03E-01 3.58E-01 2.46E+06 2.46E+06 1 0.0004 -2462142.750000 -999.000000 0.00E+00
                                                                                                                                                            16728.990234
                                                                                                                                                                                        22206.929688 3.27E-01
         0.7361
0.7361
                          59097.500000
14132.995117
                                                       43502.570312 -2.64E-01
10403.519531 -2.64E-01
                                                                                                                                           0.8193
0.8193
                                                                                                                                                            54633.984375
32771.000000
                                                                                                                                                                                        44760.910156 -1.81E-01
26848.849609 -1.81E-01
          0.7361
                           94915.492188
                                                       69868.757812 -2.64E-01
                                                                                                                                                            11115.009766
                                                                                                                                                                                          9106.372070 -1.81E-01
                                                       17785.279297 -2.64E-01
64912.101562 -2.13E-01
5712.873047 -2.13E-01
                                                                                                                                                                                        53283.296875 -3.70E-01
36390.578125 -3.70E-01
19791.390625 -3.70E-01
         0.7361
0.7871
                          24161.001953
82468.515625
                                                                                                                                                            84585.000000
57768.496094
                                                                                                                                           0.6299
                                                                                                                                           0.6299
                                                                                                                                   28
29
30
31
32
                                                                                                                                           0.6299
                                                                                                                                                            31417.994141
         0.7871
                                                      5712.873047 -2.13E-01
89897.453125 -2.13E-01
13138.900391 -4.21E-01
23599.050781 -4.21E-01
35294.578125 -4.21E-01
52206.871094 -4.21E-01
108316.101562 2.05E+00
153025.296875 2.05E+00
80135.273438 2.05E+00
2114702.578125 2.05E+00
21137.009766 -7.82E-01
9253.693359 -7.82E-01
71803 523438 -9 69E-02
                                                                                                                                                                                        32066.509766 -4.20E-01
43075.921875 -4.20E-01
37697.449219 -4.20E-01
         0.7871
0.5793
                                                                                                                                           0.5797
                                                                                                                                                            55315.519531
74307.007812
                          114211.500000
                           22679.982422
          0.5793
0.5793
0.5793
                            40736.007812
                                                                                                                                           0.5797
                                                                                                                                                            65028.988281
                                                                                                                                                                                        102431.000000 2.17E-01
82874.132812 2.17E-01
95576.656250 2.17E-01
                            60924.488281
                                                                                                                                           1.2166
                                                                                                                                                            84194.492188
68119.492188
                                                                                                                                   33
34
35
                           90118.023438
                                                                                                                                           1.2166
          3.0532
                                                                                                                                            1.2166
                                                                                                                                                            78560.515625
                                                                                                                                                                                       93376.05020 2.17E-01
105689.296875 4.82E-01
62020.320312 4.82E-01
84509.656250 4.82E-01
79167.296875 -4.49E-02
                                                                                                                                           1.4816
1.4816
          3.0532
                            50120.003906
                                                                                                                                                            71336.500000
                           26246.525391
70321.007812
                                                                                                                                   36
37
          3.0532
                                                                                                                                                            41861 507812
          3.0532
                                                                                                                                           1.4816
                                                                                                                                                            57041.000000
          0.2179
0.2179
                           97019.007812
42474.476562
 17
                                                                                                                                           0.9551
                                                                                                                                                            82889.992188
 18
                                                                                                                                   39
40
                                                                                                                                           0.9551
0.8985
                                                                                                                                                           103265.500000
                                                                                                                                                                                        98627.710938 -4.49E-02
54005.296875 -1.01E-01
          0.9031
                            79505.476562
                                                        71803.523438 -9.69E-02
                                                                                                                                                            60106.000000
          0.9031
                                                         58262.500000 -9.69E-02
                                                                                                                                                                                         5904.949219 -1.02E-01
          0.9031
                           41414.976562
                                                        37402.980469 -9.69E-02
                                                                                                                                           0.8985
                                                                                                                                                            22018.498047
                                                                                                                                                                                        19783.640625 -1.01E-01
```

```
0.8985
                               75893.976562
                                                                68190.843750 -1.01E-01
                                                                                                                                                     3 3 0 1.0000 2.40E-03 3.63E-06 2.46E+06 2.46E+06
                              108818.000000 97773.093750 -1.01E-01
1.23E-01 5.80E-03 2.46E+06 2.34E+06
344419.500000 -999.000000 0.00E+00
  44
            0.8985
                                                                                                                                                               0.0004 -2462122.750000
1.0017 43426.726562
                                                                                                                                                                                                                     -999.000000 0.00E+00
           0 1.0000
                                                                                                                                                                                                                   43502.570312 1.75E-03
10403.519531 -3.94E-03
           0.0004 -2344419.500000
                                                                                                                                                                0.9961
                                                                                                                                                                                   10444.639648
                                                             43502.570312 1.21E-01
10403.519531 1.86E-01
69868.757812 -2.36E-02
                              38803.429688
8769.461914
                                                                                                                                                               0.9977
                                                                                                                                                                                  70027.601562
17754.642578
                                                                                                                                                                                                                   69868.757812 -2.27E-03
                                                                                                                                                                                                                   17785.279297 1.73E-03
64912.101562 4.23E-04
                                                                                                                                                               1 0017
          1.1863
                                                                                                                                                       5
6
7
8
9
           0.9764
                               71558.140625
                                                                                                                                                               1.0004
                                                                                                                                                                                  64884.664062
                               15245.409180
66174.273438
5509.504883
                                                                                                                                                                                  5707.528809
90079.250000
13141.357422
                                                                                                                                                                                                                   5712.873047 9.36E-04
89897.453125 -2.02E-03
13138.900391 -1.87E-04
            1.1666
                                                               17785.279297 1.67E-01
                                                                                                                                                               1.0009
   6
7
                                                               64912.101562 -1.91E-02
5712.873047 3.69E-02
                                                                                                                                                               0.9980
           0.9809
           1.0369
                                                                                                                                                                                                                   13138,900391 - 1,87E-04
23599.050781 - 5,44E-04
35294,578125 - 1,33E-03
52206.871094 3.06E-05
108316.101562 3.04E-03
153025.296875 - 3,94E-04
80135.273438 - 1,04E-03
214702.578125 - 4,03E-04
21137.009766 - 3,83E-04
2523,693359 - 3,43E-03
                               93183.234375
11340.939453
                                                               89897.453125 -3.53E-02
           0.9647
                                                                                                                                                      10
                                                                                                                                                                0.9995
                                                                                                                                                                                    23611.896484
  9
10
                                                               13138.900391 1.59E-01
23599.050781 2.98E-01
            1.1585
                                                                                                                                                      11
12
                                                                                                                                                                0.9987
                                                                                                                                                                                   35341.726562
52205.269531
                               18183.488281
                                                                                                                                                                1.0000
           1 2978
                                                              23599.050781 2.98E-01
35294.578125 8.27E-02
52206.871094 6.11E-02
108316.101562 5.88E-02
153025.296875 4.61E-02
80135.273438 6.01E-02
214702.578125 4.08E-02
21137.009766 3.41E-02
9253.693359 -6.53E-02
71803.523438 1.70E-01
                               32599.457031
49199.953125
102300.976562
                                                                                                                                                                                  107987.851562
153085.562500
80218.375000
                                                                                                                                                       13
                                                                                                                                                                 1.0030
   11
            1.0827
                                                                                                                                                      14
15
16
17
                                                                                                                                                                0.9996
0.9990
0.9996
            1.0611
  13
            1.0588
                               146281.968750
75592.703125
            1.0461
                                                                                                                                                                                  214789.171875
  14
                                                                                                                                                                                   21145.109375
9285.530273
71697.773438
58246.238281
                                                                                                                                                               0.9996
0.9966
1.0015
            1.0601
                                                                                                                                                                                                                  21137.009766 - 3.83E-04
9253.693359 - 3.43E-03
71803.523438 1.47E-03
58262.500000 2.79E-04
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108316.101562 1.98E-05
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95567.078125
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89897.453125 -3.27E-05
13138.900391 -4.58E-05
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153025.296875 -2.24E-05
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35295.480469
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95575.601562
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                             108308.484375
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80137.742188
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79167.296875 -4.47E-06
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79167.656250
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 15
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54005.296875 -2.68E-06
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19783.640625 -2.40E-05
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37405.714844
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Boundary Point Table Boundary 1

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ax
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ay
                  -322.000000
ax
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ах
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av
      ay

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Boundary 6
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                              78.182632
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                                                                  76.774734
                                                                               76.756378
                                                       507.790741 507.733887
ay
    507.000000
                 512.946716
                              508.816864
                                           507.994446
                                                                                  507.718323
                                                                                               507.713623
ax
    368.000000
                 361.859772
                              352.452942
                                           352.307251
                                                        352.267914
                                                                     352.252960
                                                                                  352.248505
                                                                                               352.246674
ay
     74.000000
    536.000000
                 572.173950
                              574.971558
                                           575.066589
                                                        575.050232
                                                                     575.041565
                                                                                  575.038818
                                                                                               575.037903
ay
                                                                     247.617966
783.742004
ay
    704.000000
                 769.339233
                              783.263855
                                           783.671753
                                                        783.728882
                                                                                  783.745422
                                                                                               783,745972
                                                        69.724442 69.697433 69.689407 69.687378
770.064392 770.149475 770.175110 770.182617
                                                      69.724442
    675.000000
                 755.483582
                              768.849915
                                           769.781677
ay
                                           52.822388 -52.798317 -52.795628 -52.795059 -52.794598
710.542847 710.507568 710.502686 710.502075 710.502075
                             -53.034142
710.897400
                 -51.421230
705.234070
                                          -52.822388
    647.000000
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Boundary 38
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9.322116 4 5
9.396812
                                                     6 .7
9.402699 9.402502 9.401915 9.401873
     11.000000
                  8.010808
                             -994.324402 -994.410400 -994.368408 -994.356445 -994.353333 -994.352722
   -998.000000
                 -982.087769
ay
   23.000000 26.617027 28.680613 28.622435 28.587276 28.576437 28.572962 28.572025 -723.000000 -707.588257 -722.452820 -722.578003 -722.544495 -722.536255 -722.534424 -722.534119
ay
   ay
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Boundary 39
   0 1 2 3 4 5 6 7
-180.000000 -179.251083 -180.738571 -180.834335 -180.842010 -180.842087 -180.841232 -180.841125
ay -1270.000000 -1246.014648 -1257.106323 -1257.591919 -1257.660156 -1257.675415 -1257.678955 -1257.679932
ay
   -318.000000 -319.687927 -325.392242 -326.105316 -326.237579 -326.264709 -326.270142 -326.271240 -978.000000 -968.853210 -980.549438 -980.512024 -980.437012 -980.416077 -980.410645 -980.409363
ax -358.000000 -355.371552 -359.046722 -359.479065 -359.556396 -359.571442 -359.574585 -359.575073 ay -1266.000000 -1235.484741 -1244.872681 -1245.121094 -1245.151611 -1245.161133 -1245.163940 -1245.164795
Boundary 40

    40.397327
    47.077961
    47.209564
    47.236458
    47.241711
    47.242321
    47.242126

    -1.861507
    -21.052298
    -21.294720
    -21.272797
    -21.274035
    -21.277149
    -21.279043

   -27.000000
   -261.000000 -187.053116 -191.146149 -191.519791 -191.607437 -191.631821 -191.638718 -191.64 62.000000 36.286488 13.835632 13.257878 13.234482 13.234234 13.235188 13.23523
   -222.000000 -153.503540 -157.642044 -158.251389 -158.408966 -158.451126 -158.462402 -158.46
-81.000000 -73.347336 -94.987000 -95.391586 -95.403290 -95.405991 -95.406517 -95.406982
   Boundary 41
   ay
   ax
ay
   ay

        -127.000000
        -112.740776
        -112.962563
        -112.839760
        -112.801254
        -112.790840
        -112.787933
        -112.786957

        -707.000000
        -700.784973
        -716.116394
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        -716.314819
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ay
Boundary 42
   ay
  av
   ay
   ay
   ay
   -384.000000 -330.976868 -343.208038 -343.614410 -343.660553 -343.669586 -343.671082 -343.671356 -52.000000 -41.876698 -63.767120 -64.073174 -64.068443 -64.068176 -64.068214 -64.068535
av
Boundary 43
   ay
  ay

    -248.000000
    -188.887939
    -189.167221
    -188.532028
    -188.359543
    -188.314621
    -188.302673
    -188.299805

    -433.000000
    -442.524170
    -461.321655
    -461.857910
    -461.925507
    -461.944611
    -461.950134
    -461.952118
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-146.000000 -128.640656 -128.992996 -128.832031 -128.781937 -128.768738 -128.764771 -128.763474 -683.000000 -679.829102 -693.909485 -693.836060 -693.737000 -693.709351 -693.701782 -693.699829
      -683.000000
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        23 000000
     -723.000000
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Boundary 44
                       2 3 4 5 6 7
56.299335 62.890556 62.987972 62.997253 62.997810 62.997349 62.996777
-143.784943 -164.867798 -165.372009 -165.411942 -165.422195 -165.424576 -165.425293
        13 000000
      -170.000000
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                       -113.201660 -114.481316 -114.470642 -114.467087 -114.465126 -114.463890 -114.463287 -209.930298 -231.222107 -231.471878 -231.453506 -231.447540 -231.445206 -231.44458
      -182 000000
ay
      -223.000000

      -48.133102
      -48.384205
      -48.444397
      -48.477474
      -48.488392
      -48.491611
      -48.492336

      -465.602417
      -484.198853
      -484.643280
      -484.687897
      -484.700714
      -484.704437
      -484.705750

       -80 000000
      -473.000000
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                                                                                                                28.572962
     -723.000000
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                       126.679756 133.631180 133.651718 133.631989 133.626266 133.624680 133.624588 -396.886841 -414.914215 -415.272400 -415.289917 -415.295074 -415.296661 -415.297424
      -420.000000
ay
                        -116.000000
Non-Boundary Point Table
                                           5
                                                   6
End of Convergence Tables
```

C.3.4 File RLInt.out.plot

0.

This is a comma delimited table that is useful for making plots. It contains region information and the regions' boundaries at the initial and final iteration. created by specifying icheck = 1.

```
File: RLInt.out.plot
  Input scale flag iara =
  Target RMS error: relerr = 5.00E-05
  Achieved RMS error reler = 1.90E-05
DM h function dmhsum = 1.72E-10
  Target total area aretot = 2.46E+06
Current total area arctot = 2.46E+06
Scaling flag iscale = 1
/ Delimited Convergence Table
       ci j armag arak arak ara0k reler RMS DMhsum trgtArea curtArea (1.0000, 0, 7.3612E-01, 1.413300E+04, 1.040352E+04,-2.64E-01, 7.03E-01, 3.58E-01, 2.4621E+06, 2.4621E+06, 1.0000, 1, 1.1863E+00, 8.769462E+03, 1.040352E+04, 1.86E-01, 1.23E-01, 5.80E-03, 2.4621E+06, 2.3444E+06, 1.0000, 2, 9.9486E-01, 1.045726E+04, 1.040352E+04,-5.14E-03, 1.10E-02, 7.05E-05, 2.4621E+06, 2.4598E+06, 1.0000, 3, 9.9606E-01, 1.044464E+04, 1.040352E+04,-5.14E-03, 1.10E-02, 7.05E-05, 2.4621E+06, 2.4621E+06, 1.0000, 4, 9.9855E-01, 1.041859E+04, 1.040352E+04,-3.94E-03, 2.40E-03, 3.63E-06, 2.4621E+06, 2.4621E+06, 1.0000, 5, 9.9952E-01, 1.040856E+04, 1.040352E+04,-1.45E-03, 6.80E-04, 2.70E-07, 2.4621E+06, 2.4621E+06, 1.0000, 6, 9.9985E-01, 1.040513E+04, 1.040352E+04,-1.55E-04, 6.19E-05, 1.91E-09, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9995E-01, 1.040400E+04, 1.040352E+04,-4.66E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 
                                               ci j armag arak ara0k reler RMS DMhsum rgtArea curtArea 1.0000, 0, 7.3612E-01, 9.491549E+04, 6.986876E+04,-2.64E-01, 7.03E-01, 3.58E-01, 2.4621E+06, 2.4621E+06, 1.0000, 1, 9.7639E-01, 7.155814E+04, 6.986876E+04,-2.36E-02, 1.23E-01, 5.80E-03, 2.4621E+06, 2.3444E+06, 1.0000, 2, 9.8977E-01, 7.059095E+04, 6.986876E+04,-1.02E-02, 1.10E-02, 7.05E-05, 2.4621E+06, 2.4598E+06, 1.0000, 3, 9.9773E-01, 7.002760E+04, 6.986876E+04,-2.27E-03, 2.40E-03, 3.63E-06, 2.4621E+06, 2.4621E+06, 1.0000, 4, 9.9951E-01, 6.990314E+04, 6.986876E+04,-4.92E-04, 6.80E-04, 2.70E-07, 2.4621E+06, 2.4621E+06, 1.0000, 5, 9.9989E-01, 6.987611E+04, 6.986876E+04,-1.05E-04, 2.04E-04, 2.23E-08, 2.4621E+06, 2.4621E+06, 1.0000, 6, 9.9998E-01, 6.987036E+04, 6.986876E+04,-2.29E-05, 6.19E-05, 1.91E-09, 2.4621E+06, 2.4621E+06,
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4, 7, 0, 1.0000, 7, 9.9999E-01, 6.986916E+04, 6.986876E+04,-5.60E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06,
        ci j ,armag ,arak ,ara0k ,reler ,RMS ,DMhsum ,trgtArea ,curtArea  
1.0000, 0, 7.8711E-01, 8.246852E+04, 6.491210E+04,-2.13E-01, 7.03E-01, 3.58E-01, 2.4621E+06, 2.4621E+06, 1.0000, 1, 9.8093E-01, 6.617427E+04, 6.491210E+04,-1.91E-02, 1.23E-01, 5.80E-03, 2.4621E+06, 2.3444E+06, 1.0000, 2, 9.9979E-01, 6.492579E+04, 6.491210E+04,-2.11E-04, 1.10E-02, 7.05E-05, 2.4621E+06, 2.4598E+06, 1.0000, 3, 1.0004E+00, 6.488466E+04, 6.491210E+04, 4.23E-04, 2.40E-03, 3.63E-06, 2.4621E+06, 2.4621E+06, 1.0000, 4, 1.0002E+00, 6.490000E+04, 6.491210E+04, 1.87E-04, 6.80E-04, 2.70E-07, 2.4621E+06, 2.4621E+06, 1.0000, 5, 1.0001E+00, 6.490809E+04, 6.491210E+04, 6.19E-05, 2.04E-04, 2.23E-08, 2.4621E+06, 2.4621E+06, 1.0000, 6, 1.0000E+00, 6.491078E+04, 6.491210E+04, 2.04E-05, 6.19E-05, 1.91E-09, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 6.491161E+04, 6.491210E+04, 7.51E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.462
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1.0000, 0, 9.0313E-01, 4.141498E+04, 3.740298E+04,-9.69E-02, 7.03E-01, 3.58E-01, 2.4621E+06, 2.4621E+06, 1.0000, 1, 1.0981E+00, 3.406064E+04, 3.740298E+04, 9.81E-02, 1.23E-01, 5.80E-03, 2.4621E+06, 2.3444E+06, 1.0000, 2, 9.9467E-01, 3.760534E+04, 3.740298E+04, 5.33E-03, 1.10E-02, 7.05E-05, 2.4621E+06, 2.4598E+06, 1.0000, 3, 9.9674E-01, 3.752546E+04, 3.740298E+04,-5.326E-03, 2.40E-03, 3.63E-06, 2.4621E+06, 2.4621E+06, 1.0000, 4, 9.9902E-01, 3.743952E+04, 3.740298E+04,-9.76E-04, 6.80E-04, 2.70E-07, 2.4621E+06, 2.4621E+06, 1.0000, 5, 9.9973E-01, 3.741324E+04, 3.740298E+04,-2.74E-04, 2.04E-04, 2.23E-08, 2.4621E+06, 2.4621E+06, 1.0000, 6, 9.9993E-01, 3.740571E+04, 3.740298E+04,-7.18E-05, 1.90E-05, 1.91E-09, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 9.9998E-01, 3.740377E+04, 3.740298E+04,-2.10E-05, 1.90E-05, 1.72E-10, 2.4621E+06, 2
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1.0000, 0, 1.3275E+00, 1.672899E+04, 2.220693E+04, 3.27E-01, 7.03E-01, 3.58E-01, 2.4621E+06, 2.4621E+06, 1.0000, 1, 1.4521E+00, 1.529326E+04, 2.220693E+04, 4.52E-01, 1.23E-01, 5.80E-03, 2.4621E+06, 2.3444E+06, 1.0000, 2, 1.0406E+00, 2.134088E+04, 2.220693E+04, 4.06E-02, 1.10E-02, 7.05E-05, 2.4621E+06, 2.4598E+06, 1.0000, 3, 1.0035E+00, 2.212952E+04, 2.220693E+04, 3.50E-03, 2.40E-03, 3.63E-06, 2.4621E+06, 2.4621E+06, 1.0000, 4, 1.0003E+00, 2.220034E+04, 2.220693E+04, 2.97E-04, 6.80E-04, 2.70E-07, 2.4621E+06, 2.4621E+06, 1.0000, 5, 1.0000E+00, 2.220674E+04, 2.220693E+04, 2.97E-04, 6.40E-04, 2.07E-07, 2.4621E+06, 2.4621E+06, 1.0000, 6, 9.9998E-01, 2.220674E+04, 2.220693E+04, 1.60E-05, 6.19E-05, 1.91E-09, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 1.0000, 7, 1.0000E+00, 2.220699E+04, 2.220693E+04, 2.92E-06, 1.90E-05, 1.72E-10, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.4621E+06, 2.462
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                                                                                                                                                          Boundary 4
j, 0x, 0y, 7x,
axy, -532.000000,
axy, -679.000000,
                                                                                                                                                                                                     7y
193.000000, -515.559448,
439.000000, -766.481873,
Boundary Point Table
                                                                                                                                                                                             7x ,
                                                                                                                                                                                                                                                                88.396652
303.306000
Boundary 1

j. 0x , 0y , 7x , 7y

axy, 11.000000, -998.000000,

axy, -1.000000, -1273.000000,

axy, -180.000000, -1270.000000,
                                                                                                                                                          axy, -679.000000, 149.00000, -677.513467, axy, -718.000000, -140.000000, -707.533203, axy, -551.000000, -96.000000, -534.641113, -384.000000, -52.000000, -343.671356,
                                                                        9.401873, -994.352722
-1.869430, -1263.323975
-180.841125, -1257.679932
-359.575073, -1245.164795
-488.256683, -1240.443481
-617.665894, -1248.051392
-596.748108, -955.978455
-612.597778, -673.140381
-676.158875, -411.656769
-707.533703, -153.444016
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                                                                                                                                                                                                                                                               -95.451965
                                                                                                                                                                                                                                                               -64.068535
             -358.000000, -1266.000000,
-501.000000, -1265.000000,
-644.000000, -1263.000000,
                                                                                                                                                          Boundary 5
j, 0x, 0y, 7x,
axy, -383.00000,
axy, -384.00000,
axy, -323.000000,
axy, -261.000000,
axy, -321.000000,
axy, -381.000000,
                                                                                                                                                                                                     7y
145.000000, -338.656769,
-52.000000, -343.671356,
5.000000, -270.298584,
axy,
             -638.000000, -942.000000,
-632.000000, -621.000000,
-675.000060, -381.000000,
                                                                                                                                                                                                                                                                  59.116077
axy,
                                                                                                                                                                                                                                                               -64.068535
                                                                                                                                                                                                                                                              -29.423809
                                          -140.000000, -707.533203, -153.444916
149.000000, -677.513489, 78.632324
439.000000, -766.481873, 303.306000
             -718.000000,
                                                                                                                                                                                                        62.000000, -191.640198,
                                                                                                                                                                                                                                                                 13.235323
axy,
                                                                                                                                                                                                     202.000000, -261.714020, 343.000000, -313.386993,
             -699.000000,
                                                                                                                                                                                                                                                                  95 379990
             -679.000000.
                                                                                                                                                                                                                                                                174 519348
                                           605.000000, -840.126404, 771.000000, -848.293274,
             -699.000000,
axy,
                                                                       -848.293274,
-655.477478,
                                                                                                                                                          Boundary 6

j, 0x, 0y, 7x, 7y

axy, -501.000000, -1265.000000, -488.256683, -1240.443481

axy, -358.000000, -1266.000000, -359.575073, -1245.164795

axy, -277.000000, -978.000000, -262.703949, -721.730042

axy, -451.000000, -977.00000, -488.256683, -1240.443481

-488.256683, -1240.443481

-980.409363

axy, -241.000000, -977.00000, -488.562103, -983.750305
             -718.000000,
                                                                                                       833.703247
axy,
                                           1018.000000.
                                                                                                       1132,310669
             -646.000000
             -574.000000,
                                           1266.000000,
                                                                         -531.602844,
                                                                                                        1332.687378
axv.
                                         1266.000000,
1266.000000,
                                                                         -234.961182, 1307.384766
48.752579, 1250.923950
             -322.000000,
                                                                                                       1307.384766
 axy,
axy.
              -70.000000.
                                                                           285.146027,
523.943420,
               201.000000,
                                           1269.000000,
                                                                                                        1199.844849
axv.
                                                                                                                                                           axy, -644.000000, -977.000000, -48.562103, -983.750305
axy, -644.000000, -1263.000000, -617.665894, -1248.051392
               473.000000,
axy,
                                           1273.000000,
                                                                                                        1158.991821
                                                                            610.355286,
               627.000000,
781 000000,
                                           1272.000000.
                                                                                                       1153.031128
axy,
                                           1271.000000,
                                                                            712.000000,
                                                                                                        1204.276611
axv.
                                                                                                                                                          Boundary 7

j, 0x, 0y, 7x, 7y

axy, -455.000000, -656.000000,

axy, -277.000000, -690.00000000,
                                            895.000000,
519.000000,
              647.000000,
513.000000,
429.000000,
axy,
                                                                          559.709473,
                                                                                                        944.903198
                                                                          508.993103.
                                                                                                        602.339722
                                            420.000000,
                                                                          448.640564.
                                                                                                        491.249725
                                                                                                                                                                                                                                  -433.615295, -715.851990
axv.
                                                                                                        373.357269
               345.000000,
                                            322.000000,
                                                                          383.456665,
                                                                                                                                                                                                                                  -262.703949,
 axy,
                                                                                                                                                           axy, -296.000000,
axy, -314.000000,
              277.000000,
                                         103.000000,
-116.000000,
                                                                         299.373657,
230.555084.
                                                                                                                                                                                                    -666.000000, -276.094086, -704.523926
-642.000000, -286.594849, -687.949036
                                                                                                       127.141075
 axy,
                                                                                                       -90.248100
              209.000000
axy,
                                                                                                                                                                                                                                  -451.417267,
               116.000000,
                                           -420.000000,
                                                                          133.624588,
                                                                                                      -415.297424
                                                                                                                                                           axy, -473.000000,
                                                                                                                                                                                                     -632.000000,
axy,
                23.000000,
                                         -723.000000.
                                                                          28.572025.
                                                                                                   -722.534119
                                                                                                                                                           axy,
                                                                                                                                                                     -632.000000.
                                                                                                                                                                                                     -621,000000.
                                                                                                                                                                                                                                 -612.597778.
                                                                                                                                                                                                                                                               -673.140381
Boundary 2

j, 0x, 0y, 7x

axy, -532.000000,

axy, -384.000000,

axy, -383.000000,

-381.000000.
                                                                                                                                                          Boundary 8
j, 0x, 0y, 7x, 7y
axy, -638,000000, -942,000000,
axy, -644,000000, -1263,000000,
-977,000000, -977,000000,
                                           7y
193.000000,
                                                                                                                                                                                                                                 -596.748108, -955.978455
                                                                      -515.559448.
                                                                                                        88.396652
                                            -52.000000, -343.671356,
                                                                                                                                                                                                                                  -617.665894, -1248.051392
                                                                                                      -64.068535
                                            145.000000, -338.656769,
                                                                                                         59.116077
                                                                                                                                                            axy, -461.000000, -977.000000,
                                                                                                                                                                                                                                 -448.562103, -983.750305
-262.703949, -721.730042
                                                                                                                                                                                                                                                               -983.750305
axy, -381.000000,
                                                                                                                                                           axy, -277.000000,
                                            343.000000
                                                                       -313.386993.
                                                                                                        174.519348
                                                                                                                                                                                                    -690,000000.
axy, -530.000000,
                                            391.000000,
                                                                                                        193.599030
                                                                                                                                                           axy, -455.000000,
                                                                                                                                                                       -455.000000, -656.000000,
-632.000000, -621.000000,
                                                                        -544.720215,
                                                                      -766.481873,
             -679.000000,
                                            439.000000,
                                                                                                        303.306000
                                                                                                                                                            axy,
                                                                                                                                                                                                                                  -612.597778.
                                                                                                                                                                                                                                                               -673.140381
axy,
                                                                                                                                                          Boundary 9
j, 0x, 0y, 7x, 7y
axy, 282.00000, 611.00000,
519.00000, 62000000,
Boundary 3
j, 0x, 0y, 7x
axy, -321.000000,
axy, -261.000000,
axy, -235.000000,
                                           7y
202.000000, -261.714020,
                                                                                                        95.379990
                                                                                                                                                                                                                                   386,776764.
                                                                                                                                                                                                                                                                 666.290039
                                           62.000000, -191.640198,
119.000000, -154.124207,
176.000000, -115.175537,
                                                                                                       13.235323
                                                                                                                                                                                                                                    508.993103,
                                                                                                                                                                                                                                                                 602.339722
                                                                                                         46.477711
                                                                                                                                                                          300.000000,
                                                                                                                                                                                                      653.000000,
                                                                                                                                                                                                                                    400.889313,
                                                                                                                                                                                                                                                                 711.463745
                                                                                                                                                           axy,
axy, -209.000000.
                                                                                                                                                                                                     788.000000,
                                                                                                                                                                                                                                                               854.503601
815.220642
                                                                                                                                                           axy,
                                                                                                                                                                                                                                  260.919250.
                                                                                                        72.916588
                                                                                                                                                                           88.000000.
                                            259.000000, -231.296783, 343.000000, -313.386993,
                                                                                                        133.506653
                                                                                                                                                                            70.000000,
                                                                                                                                                                                                      746.000000,
                                                                                                                                                                                                                                   252.056168,
axy, -295.000000,
                                                                                                                                                           axv.
                                                                                                                                                                                                     704.000000,
                                                                                                                                                                                                                                  247.620010,
            -381.000000.
                                                                                                        174.519348
                                                                                                                                                                            52.000000.
                                                                                                                                                                                                                                                               783.745972
                                                                                                                                                           axy,
```

Boundary 10 j, 0x , 0y , 7x , 7y axy, 198.000000, 513.000000, 339.197510, 556.423035 axy, 52.000000, 704.000000, 247.620010, 783.745972 axy, 74.000000, 536.000000, 283.163422, 575.037903 axy, 96.000000, 368.000000, 263.224644, 352.246674 axy, 220.000000, 345.000000, 312.964081, 369.805237 axy, 345.000000, 322.000000, 383.4566655, 373.357269	Boundary 20 j, 0x, 0y, 7x, 7y axy, -328.000000, 1138.000000, -222.164230, 1203.621704 axy, -81.00000, 1010.000000, 91.568008, 1051.850464 axy, -76.000000, 1138.000000, 77.085602, 1151.731689 axy, -70.000000, 1266.000000, 48.752579, 1250.923950 axy, -322.000000, 1266.000000, -234.961182, 1307.384766 axy, -574.000000, 1266.000000, -531.602844, 1332.687378
Poundary 11 j, 0x, 0y, 7x, 7y axy, 282.000000, 611.000000, 386.776764, 666.290039 axy, 52.000000, 704.000000, 247.620010, 783.745972 axy, 198.000000, 513.000000, 339.197510, 556.423035 axy, 345.000000, 322.000000, 383.456665, 373.357269 axy, 429.000000, 420.000000, 448.640564, 491.249725 axy, 513.000000, 519.000000, 508.993103, 602.339722	Boundary 21 j, 0x, 0y, 7x, 7y axy, -481.00000, 884.00000, -372.888977, 1064.368774 axy, -359.00000, 832.00000, -157.334549, 976.008301 axy, -467.000000, 1049.00000, -385.897858, 1151.967529 axy, -574.00000, 1266.00000, -531.602844, 1332.687378 axy, -588.000000, 1101.000000, -536.120972, 1194.441772 axy, -602.000000, 937.000000, -586.901367, 1090.889038
Boundary 12 j, 0x, 0y, 7x, 7y axy, 300.000000, 653.00000, 400.889313, 711.463745 axy, 513.00000, 519.00000, 508.993103, 602.339722 axy, 469.00000, 758.000000, 518.927246, 821.334167 axy, 426.000000, 998.000000, 508.232666, 996.978210 axy, 257.000000, 893.000000, 366.541321, 925.174377 axy, 88.000000, 788.000000, 260.919250, 854.503601	Boundary 22 j, 0x, 0y, 7x, 7y axy, -660.000000, 854.00000, -741.174744, 975.344482 axy, -602.000000, 937.000000, -586.901367, 1090.889038 axy, -588.000000, 1101.0000000, -536.120972, 1194.441772 axy, -574.000000, 1266.000000, -531.602844, 132.3687378 axy, -646.000000, 1018.000000, -655.477478, 1132.310669 axy, -718.000000, 771.000000, -848.293274, 833.703247
Boundary 13 j, 0x, 0y, 7x, 7y axy, -320,000000, 739,000000, -80,585312, 849,250244 axy, -359,000000, 832,000000, -157,334549, 976,008301 axy, -539,000000, 801,000000, -502,493042, 909,123901 axy, -718,000000, 771,000000, -848,293274, 833,703247 axy, -499,000000, 709,000000, -441,125549, 760,250427 axy, -280,000000, 647,000000, -52,794598, 710,502075	Boundary 23 j, 0x, 0y, 7x, 7y axy, -114.000000, 675.000000, 69.687378, 770.182617 axy, 52.000000, 704.000000, 247.620010, 783.745972 axy, -15.000000, 857.000000, 157.994598, 922.495483 axy, -81.000000, 1010.000000, 91.568008, 1051.850464 axy, -181.000000, 828.000000, 5.738637, 910.465332 axy, -280.000000, 647.000000, -52.794598, 710.502075
Boundary 14 j, 0x, 0y, 7x, 7y axy, -480,000000, 543,000000, -429,957733, 483,144104 axy, -679,000000, 439,000000, -766,481873, 303,306000 axy, -530,000000, 391,000000, -544,720215, 193,599030 axy, -381,000000, 343,000000, -313,386993, 174,519348 axy, -331,000000, 495,000000, -159,253159, 425,625275 axy, -280,000000, 647,000000, -52,794598, 710,502075	Boundary 24 j, 0x, 0y, 7x, 7y axy, -320,000000, 739,00000, -80,585312, 849,250244 axy, -280,00000, 647,00000, -52,794598, 710,502075 axy, -181,00000, 828,000000, 5.738637, 910,465332 axy, -81,000000, 1010,000000, 91,568008, 1051,850464 axy, -220,000000, 921,000000, -46,983383, 992,348511 axy, -359,000000, 832,000000, -157,334549, 976,008301
Boundary 15 j, 0x, 0y, 7x, 7y axy, -539,000000, 801,000000, -502,493042, 909,123901 axy, -359,000000, 832,000000, -157,334549, 976,008301 axy, -481,000000, 884,000000, -372,888977, 1064,368774 axy, -602,000000, 937,000000, -586,901367, 1090,889038 axy, -600,000000, 854,000000, -741,174744, 975,344482 axy, -718,000000, 771,000000, -848,293274, 833,703247	Boundary 25 j, 0x, 0y, 7x, 7y axy, -15.000000, 857.000000, 157.994598, 922.495483 axy, 52.000000, 704.000000, 247.620010, 783.745972 axy, 70.000000, 746.000000, 252.056168, 815.220642 axy, 88.000000, 788.000000, 260.919250, 854.503601 axy, 3.000000, 899.000000, 176.763718, 960.436401 axy, -81.000000, 1010.000000, 91.568008, 1051.850464
Boundary 16 j, 0x, 0y, 7x, 7y axy, -480.000000, 543.000000, -429.957733, 483.144104 axy, -280.000000, 647.000000, -52.794598, 710.502075 axy, -499.00000, 709.000000, -441.125549, 760.250427 axy, -718.000000, 771.000000, -848.293274, 833.703247 axy, -699.000000, 605.000000, -840.126404, 571.255676 axy, -679.000000, 439.000000, -766.481873, 303.306000	Boundary 26 j, 0x, 0y, 7x, 7y axy, 0.000000, 30.000000, 77.599876, 29.133595 axy, 209.00000, 116.000000, 230.555084, -90.248100 axy, 152.000000, 126.000000, 204.171356, 130.163223 axy, 96.000000, 368.000000, 256.272644, 352.246674 axy, -57.000000, 272.000000, 93.024643, 183.847168 axy, -209.000000, 176.000000, -115.175537, 72.916588
Boundary 17 j, 0x, 0y, 7x, 7y axy, 469.00000, 758.00000, 518.927246, 821.334167 axy, 513.000000, 519.00000, 508.993103, 602.339722 axy, 647.00000, 895.000000, 559.709473, 944.903198 axy, 781.00000, 1271.000000, 712.000000, 1204.276611 axy, 603.000000, 1134.000000, 579.183655, 1092.731567 axy, 426.600000, 998.000000, 508.232666, 996.978210	Boundary 27 j, 0x, 0y, 7x, 7y axy, 152.000000, 126.000000, 204.171356, 130.163223 axy, 209.000000, -116.000000, 230.555084, -90.248100 axy, 277.000000, 103.000000, 299.373657, 127.141075 axy, 345.000000, 322.000000, 383.456665, 373.357269 axy, 220.000000, 345.000000, 312.964081, 369.805237 axy, 96.000000, 368.000000, 256.272644, 352.246674
Boundary 18 j, 0x, 0y, 7x, 7y axy, 603.000000, 1134.000000, 579.183655, 1092.731567 axy, 781.00000, 1271.000000, 712.000000, 1204.276611 axy, 627.000000, 1272.000000, 610.355286, 1153.031128 axy, 473.000000, 1273.000000, 523.943420, 1158.991821 axy, 449.000000, 1135.000000, 525.108154, 1081.180664 axy, 426.000000, 998.000000, 508.232666, 996.978210	Boundary 28 j, 0x , 0y , 7x , 7y axy, 0.000000, 30.000000, -77.599876, 29.133595 axy, -209.00000, 176.000000, -115.175537, 72.916588 axy, -235.000000, 119.000000, -154.124207, 46.477711 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -26.000000, -27.000000, 47.242126, -21.279043 axy, 209.000000, -116.000000, 230.555084, -90.248100
Boundary 19 j, 0x, 0y, 7x, 7y axy, -220.00000, 921.00000, -46.983383, 992.348511 axy, -81.00000, 1010.00000, 91.568008, 1051.850464 axy, -328.00000, 1138.00000, -222.164230, 1203.621704 axy, -574.00000, 1266.00000, -531.602844, 1332.687378 axy, -467.00000, 1049.00000, -385.897858, 1151.967529 axy, -359.000000, 832.000000, -157.334549, 976.008301	Boundary 29 j, 0x, 0y, 7x, 7y axy, 3.000000, 899.000000, 176.763718, 960.436401 axy, 88.000000, 788.000000, 260.919250, 854.503601 axy, 257.000000, 893.000000, 366.541321, 925.174377 axy, 426.000000, 998.000000, 508.232666, 996.978210 axy, 172.000000, 1004.000000, 291.733368, 1013.391602 axy, -81.000000, 1010.0000000, 91.568008, 1051.850464

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Boundary 30	Boundary 38
i 0 7 0 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	j, 0x, 0y, 7x, 7y axy, 11.000000, -998.000000, 9.401873, -994.352722
j, 0x, 0y, 7x, 7y axy, 178.000000, 1132.000000, 280.885834, 1103.372192	J, UK, UY, 7X, 79
axy, 178.000000, 1132.000000, 280.885834, 1103.372192	axy, 11.000000, -998.000000, 9.401873, -994.352722 axy, 23.000000, -723.000000, 28.572025, -722.534119 axy, -127.000000, -707.000000, -112.786957, -716.313477 axy, -277.000000, -690.000000, -262.703949, -721.730042 axy, -139.000000, -982.000000, -139.897232, -981.271362
axy, 426.000000, 998.000000, 508.232666, 996.978210	axy, 23.000000, -723.000000, 28.572025, -722.534119
axy, 449.000000, 1135.000000, 525.108154, 1081.180664	axv127.000000707.000000112.786957716.313477
axy, 473.000000, 1273.000000, 523.943420, 1158.991821	avy -277 000000 -600 000000 -262 703049 -721 730042
axy, 473.000000, 1273.000000, 523.943420, 1158.991821 axy, 201.000000, 1269.000000, 285.146027, 1199.844849	axy, -2/7.000000, -090.000000, -202.703949, -721.730042
axy, 201.000000, 1269.000000, 285.146027, 1199.844849	axy, -139.000000, -982.000000, -139.897232, -981.271362
axy, -70.000000, 1266.000000, 48.752579, 1250.923950	axy, -1.000000, -1273.000000, -1.869430, -1263.323975
Boundary 31 j, 0x, 0y, 7x, 7y axy, 172.000000, 1004.000000, 291.733368, 1013.391602	Boundary 39
i Ox Ov 7x 7v	i 0 0 7 7 7 7 7 7 7 7 7 7 7
777 777	J. 180 000000 1070 000000 100 041105 1057 670000
axy, 172.000000, 1004.000000, 291.733368, 1013.391602	j, 0x, 0y, 7x, 7y axy, -180,000000, -1270,000000, -180,841125, -1257,679932
axy, 426.000000, 998.000000, 508.232666, 996.978210	axy, -1.000000, -12/3.000000, -1.869430, -1263.3239/3
axy, 178.000000, 1132.000000, 280.885834, 1103.372192	axy, -139.000000, -982.000000, -139.897232, -981.271362
axy, -70.000000, 1266.000000, 48.752579, 1250.923950	axy, -277.000000, -690.000000, -262.703949, -721.730042
axy, -76.000000, 1138.000000, 77.085602, 1151.731689	axy, -318.000000, -978.000000, -326.271240, -980.409363
axy, -70.00000, 1130.000000, 77.000002, 1131.731089	axy, -516.00000, -576.000000, -520.271240, -560.405505
axy, -81.000000, 1010.000000, 91.568008, 1051.850464	axy, -358.000000, -1266.000000, -359.575073, -1245.164795
	`
Boundary 32	Boundary 40 j, 0x, 0y, 7x, 7y axy, 13.000000, -170.000000, 62.996777, -165.425293 axy, 209.000000, -116.000000, 230.555084, -90.248100
i. 0x 0v 7x 7v	i Ox Ov 7x 7v
271 -508 000000 -337 000000 -485 084375 -361 028407	axy, 13.000000, -170.000000, 62.996777, -165.425293
boundary 32 j, 0x, 0y, 7x, 7y axy, -508.000000, -337.000000, -485.984375, -361.928497 axy, -384.00000, -52.000000, -343.671356, -64.068535 axy, -551.000000, -96.000000, -534.641113, -95.451965	axy, 13.000000, -170.000000, 02.750777, -103.423233
axy, -384.000000, -32.000000, -343.071330, -04.008333	axy, 209.00000, -116.00000, 230.555084, -90.248100
axy, -551.000000, -96.000000, -534.641113, -95.451965 axy, -718.000000, -140.000000, -707.533203, -153.444916	axy, -26.000000, -27.000000, 47.242126, -21.279043
axy, -718.000000, -140.000000, -707.533203, -153.444916	axy, -261.000000, 62.000000, -191.640198, 13.235323
axy, -675.000000, -381.000000, -676.158875, -411.656769	axy -222 000000 -81 000000 -158 464844 -95 406982
axy, -632.000000, -621.000000, -612.597778, -673.140381	axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -182.000000, -223.000000, -114.463287, -231.444458
axy, -032.000000, -021.000000, -012.337776, -073.140361	axy, -182.000000, -223.000000, -114.463287, -231.444438
Boundary 33	Boundary 41
j, 0x, 0y, 7x, 7y	j, 0x, 0y, 7x, 7y
axy, -407.000000, -422.000000, -372.053497, -453.895966	244 -146 000000 -683 000000 -128 763474 -603 600820
axy, -632.000000, -621.000000, -612.597778, -673.140381	axy, -314.000000, -642.00000, -286.594849, -687.949036 axy, -296.00000, -666.000000, -276.094086, -704.523926 axy, -277.000000, -690.000000, -262.703949, -721.730042 axy, -127.000000, -707.000000, -112.786957, -716.313477 axy, 23.000000, -723.000000, 28.572025, -722.534119
	any, -514.00000, -042.000000, -200.55407, -081.545000
axy, -473.000000, -632.000000, -451.417267, -697.147583	axy, -296.000000, -666.000000, -276.094086, -704.523926
axy, -314.000000, -642.000000, -286.594849, -687.949036	axy,277.000000, -690.000000, -262.703949, -721.730042
axy, -248.000000, -433.000000, -188.299805, -461.952118	axy, -127.000000, -707.000000, -112.786957, -716.313477
axy, -182.000000, -223.000000, -114.463287, -231.444458	axv. 23.000000723.000000. 28.572025722.534119
,	
Davidani, 24	Paris day: 42
boundary 34	Boundary 42
j, 0x, 0y, 7x, 7y	j, Ox, Oy, 7x, 7y
j, 0x, 0y, 7x, 7y axy, -508.000000, -337.000000, -485.984375, -361.928497	Boundary 42 j, 0x, 0y, 7x, 7y axy, -283.000000, -138.000000, -219.250107, -142.166077
Boundary 34 j. 0x, 0y, 7x, 7y axy, -508.000000, -337.000000, -485.984375, -361.928497 axy, -632.000000, -621.000000, -612.597778, -673.140381	axy, -283.000000, -138.000000, -219.25010/, -142.1660/7
axy, -632.000000, -621.000000, -612.597778, -673.140381	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 256.272644, 352.246674	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -233.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -114.463287, -231.444458
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 256.272644, 352.246674 axy, -92.000000, 507.000000, 76.751442, 507.713623	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -248.000000, -233.000000, -188.299805, -461.952118
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 256.272644, 352.246674 axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, -280.000000, 647.000000, -52.794598, 710.502075	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -248.000000, -233.000000, -188.299805, -461.952118
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 256.272644, 352.246674 axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, -280.000000, 647.000000, -52.794598, 710.502075	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -248.000000, -233.000000, -188.299805, -461.952118
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, -256.272644, 352.246674 axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, -280.000000, 647.000000, -52.794598, 710.502075 axy, -331.000000, 495.000000, -159.253159, 425.6525275	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -248.000000, -233.000000, -188.299805, -461.952118
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 256.272644, 352.246674 axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, -280.000000, 647.000000, -52.794598, 710.502075	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -114.463287, -231.4444458 axy, -248.000000, -433.000000, -188.299805, -461.952118 axy, -314.000000, -642.000000, -286.5984849, -687.949036
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j. 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 256.272644, 352.246674 axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, -280.000000, 647.000000, -52.794598, 710.502075 axy, -331.000000, 495.000000, -159.253159, 425.625275 axy, -381.000000, 343.000000, -313.386993, 174.519348	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -233.000000, -114.463287, -231.444458 axy, -221.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -233.000000, -114.463287, -231.444458 axy, -314.000000, -433.000000, -188.299805, -461.952118 axy, -314.000000, -642.000000, -286.594849, -687.949036 axy, -146.000000, -683.000000, -128.763474, -693.699829 axy, 23.000000, -723.000000, 288.572025, -722.534119
axy, -632.000000, -621.000000, -512.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -52.000000, -219.250107, -142.166077 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 256.272644, 352.246674 axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, -280.000000, 647.000000, -52.794598, 710.502075 axy, -381.000000, 343.000000, -159.253159, 425.625275 axy, -381.000000, 343.000000, -313.386993, 174.519348 Boundary 36	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -158.464844, -95.406982 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -248.000000, -433.000000, -114.63287, -231.444458 axy, -314.000000, -433.000000, -128.763474, -693.699829 axy, 23.000000, -723.000000, -128.763474, -693.699829 axy, 23.000000, -723.000000, 28.572025, -722.534119 Boundary 44
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axy, -632.000000, -621.000000, -512.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -52.000000, -219.250107, -142.166077 axy, -384.00000, -52.000000, -343.671356, -64.068535 Boundary 35	axy, -283.000000, -138.000000, -219.250107, -142.166077 axy, -182.000000, -23.000000, -114.463287, -231.444458 axy, -261.000000, 62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -114.463287, -231.444458 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -248.00000, -433.00000, -188.299805, -461.952118 axy, -314.000000, -642.000000, -128.6594849, -687.949036 axy, -146.000000, -630.00000, -128.763474, -693.699829 axy, 23.000000, -723.000000, -128.763474, -693.699829 axy, -131.000000, -723.000000, -114.463287, -231.444458 axy, -146.000000, -642.000000, -118.763474, -693.699829 axy, -13.000000, -723.000000, -114.463287, -231.444458 axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -80.000000, -723.000000, -114.463287, -231.444458 axy, -80.000000, -723.000000, -114.463287, -231.444458 axy, -80.000000, -473.000000, -114.463287, -231.444458 axy, -80.000000, -473.000000, -114.463287, -231.444458 axy, -80.000000, -170.000000, -114.463287, -231.444458 axy, -80.0000000, -170.000000, -114.463287, -231.444458 axy, -80.000000, -170.000000, -285.55084, -90.248100
axy, -632.000000, -621.000000, -512.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -52.000000, -219.250107, -142.166077 axy, -384.00000, -52.000000, -343.671356, -64.068535 Boundary 35 j. 0x, 0y, 7x, 7y axy, -143.000000, 365.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 76.751442, 507.713623 axy, -92.000000, 647.000000, -52.794598, 710.502075 axy, -331.000000, 343.000000, -159.253159, 425.625275 axy, -381.000000, 343.000000, -313.386993, 174.519348 Boundary 36 j. 0x, 0y, 7x, 7y axy, -143.000000, 343.000000, -313.386993, 174.519348 Boundary 36 j. 0x, 0y, 7x, 7y axy, -143.000000, 259.000000, -231.296783, 133.506653 axy, -299.000000, 259.000000, -215.5175537, 72.916588 axy, -299.000000, 272.000000, -155.175537, 72.916588 axy, -92.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, 96.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, 96.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, 96.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 267.751442, 507.713623 axy, 96.000000, 368.000000, 266.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 267.00000, 276.751442, 507.713623 axy, 96.000000, 507.000000, 276.751442, 577.073623 axy, 96.000000, 507.000000, 276.751442, 577.073623 axy, 96.000000, 507.000000, 276.773623 axy, 52.000000, 507.000000, 276.773623 axy, 52.000000, 507.000000, 276.773624, 575.037903 axy, 52.000000, 704.000000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.6000000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.6000000, 277.600000, 277.6000000, 277.6000000, 277.6000000, 277.6000000, 277.600000000000000, 277.600	axy, -283.000000, -138.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -1158.464844, -95.406982 axy, -261.000000, -62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -184.463287, -231.444458 axy, -314.000000, -642.000000, -188.299805, -461.952118 axy, -314.000000, -642.000000, -128.763474, -693.699829 axy, 23.000000, -723.000000, -128.763474, -693.699829 axy, 13.000000, -723.000000, -148.492336, -484.705750 axy, 13.000000, -723.000000, -188.299605, -461.952118 Boundary 44 j, 0x, 0y, 7x, 7y axy, 13.000000, -723.000000, -144.463287, -231.444458 axy, -80.00000, -223.000000, -144.463287, -231.444458 axy, -80.00000, -723.000000, -148.492336, -484.705750 axy, 23.000000, -723.000000, -138.572025, -722.534119 axy, 116.000000, -473.000000, -28.572025, -722.534119 axy, 116.000000, -420.000000, 133.624588, -415.297424 axy, 209.000000, -116.000000, 230.555084, -90.248100 Non-Boundary Point Table j, 0x, 0y, 7x, 7y
axy, -632.000000, -621.000000, -612.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -138.000000, -114.463287, -231.444458 axy, -283.000000, -52.000000, -343.671356, -64.068535 Boundary 35 j, 0x, 0y, 7x, 7y axy, -143.000000, 355.000000, -4.429573, 295.824005 axy, -96.000000, 507.000000, 76.751442, 507.713623 axy, -92.000000, 368.000000, -52.794598, 710.502075 axy, -331.000000, 495.000000, -159.253159, 425.625275 axy, -331.000000, 343.000000, -313.386993, 174.519348 Boundary 36 j, 0x, 0y, 7x, 7y axy, -143.000000, 343.000000, -313.386993, 174.519348 Boundary 36 j, 0x, 0y, 7x, 7y axy, -143.000000, 343.000000, -313.386993, 174.519348 Boundary 36 j, 0x, 0y, 7x, 7y axy, -143.000000, 343.000000, -159.253159, 425.625275 axy, -381.000000, 343.000000, -159.253159, 425.625275 axy, -77.000000, 343.000000, -159.253159, 3295.824005 axy, -295.000000, 369.000000, -313.386993, 174.519348 axy, -295.000000, 368.000000, -313.386993, 174.519348 axy, -295.000000, 272.000000, 93.024643, 183.847168 axy, 96.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j, 0x, 0y, 7x, 7y axy, -92.000000, 368.000000, 76.751442, 507.713623 axy, 96.000000, 368.000000, 265.272644, 352.246674 axy, 74.000000, 507.000000, 76.751442, 507.713623 axy, 74.000000, 368.000000, 247.620010, 783.745972 axy, 52.000000, 675.000000, 69.687378, 770.182617	axy, -283.000000, -138.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -1158.464844, -95.406982 axy, -261.000000, -62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -184.463287, -231.444458 axy, -314.000000, -642.000000, -188.299805, -461.952118 axy, -314.000000, -642.000000, -128.763474, -693.699829 axy, 23.000000, -723.000000, -128.763474, -693.699829 axy, 13.000000, -723.000000, -148.492336, -484.705750 axy, 13.000000, -723.000000, -188.299605, -461.952118 Boundary 44 j, 0x, 0y, 7x, 7y axy, 13.000000, -723.000000, -144.463287, -231.444458 axy, -80.00000, -223.000000, -144.463287, -231.444458 axy, -80.00000, -723.000000, -148.492336, -484.705750 axy, 23.000000, -723.000000, -138.572025, -722.534119 axy, 116.000000, -473.000000, -28.572025, -722.534119 axy, 116.000000, -420.000000, 133.624588, -415.297424 axy, 209.000000, -116.000000, 230.555084, -90.248100 Non-Boundary Point Table j, 0x, 0y, 7x, 7y
axy, -632.000000, -621.000000, -512.597778, -673.140381 axy, -407.000000, -422.000000, -372.053497, -453.895966 axy, -182.000000, -223.000000, -114.463287, -231.444458 axy, -283.000000, -52.000000, -219.250107, -142.166077 axy, -384.00000, -52.000000, -343.671356, -64.068535 Boundary 35 j. 0x, 0y, 7x, 7y axy, -143.000000, 365.000000, -4.429573, 295.824005 axy, 96.000000, 368.000000, 76.751442, 507.713623 axy, -92.000000, 647.000000, -52.794598, 710.502075 axy, -331.000000, 343.000000, -159.253159, 425.625275 axy, -381.000000, 343.000000, -313.386993, 174.519348 Boundary 36 j. 0x, 0y, 7x, 7y axy, -143.000000, 343.000000, -313.386993, 174.519348 Boundary 36 j. 0x, 0y, 7x, 7y axy, -143.000000, 259.000000, -231.296783, 133.506653 axy, -299.000000, 259.000000, -215.5175537, 72.916588 axy, -299.000000, 272.000000, -155.175537, 72.916588 axy, -92.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, 96.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, 96.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 76.751442, 507.713623 axy, 96.000000, 368.000000, 256.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 267.751442, 507.713623 axy, 96.000000, 368.000000, 266.272644, 352.246674 Boundary 37 j. 0x, 0y, 7x, 7y axy, -92.000000, 507.000000, 267.00000, 276.751442, 507.713623 axy, 96.000000, 507.000000, 276.751442, 577.073623 axy, 96.000000, 507.000000, 276.751442, 577.073623 axy, 96.000000, 507.000000, 276.773623 axy, 52.000000, 507.000000, 276.773623 axy, 52.000000, 507.000000, 276.773624, 575.037903 axy, 52.000000, 704.000000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.6000000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.600000, 277.6000000, 277.600000, 277.6000000, 277.6000000, 277.6000000, 277.6000000, 277.600000000000000, 277.600	axy, -283.000000, -138.000000, -114.463287, -231.444458 axy, -222.000000, -81.000000, -1158.464844, -95.406982 axy, -261.000000, -62.000000, -191.640198, 13.235323 axy, -323.000000, 5.000000, -270.298584, -29.423809 axy, -384.000000, -52.000000, -343.671356, -64.068535 Boundary 43 j, 0x, 0y, 7x, 7y axy, -80.000000, -473.000000, -48.492336, -484.705750 axy, -182.000000, -223.000000, -184.463287, -231.444458 axy, -314.000000, -642.000000, -188.299805, -461.952118 axy, -314.000000, -642.000000, -128.763474, -693.699829 axy, 23.000000, -723.000000, -128.763474, -693.699829 axy, 13.000000, -723.000000, -148.492336, -484.705750 axy, 13.000000, -723.000000, -188.299605, -461.952118 Boundary 44 j, 0x, 0y, 7x, 7y axy, 13.000000, -723.000000, -144.463287, -231.444458 axy, -80.00000, -223.000000, -144.463287, -231.444458 axy, -80.00000, -723.000000, -148.492336, -484.705750 axy, 23.000000, -723.000000, -138.572025, -722.534119 axy, 116.000000, -473.000000, -28.572025, -722.534119 axy, 116.000000, -420.000000, 133.624588, -415.297424 axy, 209.000000, -116.000000, 230.555084, -90.248100 Non-Boundary Point Table j, 0x, 0y, 7x, 7y

C.3.5 File RLInt.sum.0007

After seven iterations, the map had fully converged to single precision accuracy, about five significant figures. This file shows for each region the current area, target area, the current region magnification M_k , and the current relative error M_k-1 . If fully converged, the magnification for each region should be 1.

DEMP input file in CLOSE3 format vt_500k2_hex_pop80.cl3

```
it0, it, ci, magRMS, DMHsum, nDrop, nleft
7, 0, 1.000E+00, 1.897E-05, 1.721E-10, 1, 43
Region k, areak, area0k, Magk, Mrelerk
1, -2.46214E+06, -9.99000E+02, 4.05744E-04, 0.00E+00
2, 4.35024E+04, 4.35026E+04, 1.0000E+00, 4.89E-06
3, 1.04040E+04, 1.04035E+04, 9.99953E-01, -4.66E-05
4, 6.98692E+04, 6.98688E+04, 9.99994E-01, -5.60E-06
5, 6.7499E+04, 1.77853E+04, 1.0000E+00, 2.07E-05
5, 6.49116E+04, 6.49121E+04, 1.00001E+00, 7.51E-06
7, 5.71297E+03, 5.71287E+03, 9.99982E-01, -1.77E-05
8, 8.98984E+04, 8.98975E+04, 9.99998E-01, -1.00E-05
9, 1.31391E+04, 1.31389E+04, 9.99998E-01, -1.09E-05
10, 2.35993E+04, 2.52946E+04, 9.99994E-01, -6.08E-06
11, 3.52948E+04, 3.52946E+04, 9.99994E-01, -6.08E-06
12, 5.22065E+04, 5.22069E+04, 1.00001E+00, 6.20E-06
13, 1.08314E+05, 1.08316E+05, 1.00002E+00, 1.98E-05
15, 8.01361E+04, 8.01353E+04, 8.01353E+04, 8.0135E+04, 8.0135E+04, 8.0135E+04, 8.0135E+04, 9.99991E-01, -8.52E-06
16, 2.14703E+05, 1.53025E+05, 9.99991E-01, -8.52E-06
17, 2.11369E+04, 2.11370E+04, 1.00001E+00, 1.22E-05
20, 5.82621E+04, 5.82625E+04, 1.00001E+00, 1.22E-05
21, 3.74038E+04, 3.74030E+04, 9.99997E-01, -2.05E-06
22, 2.22070E+04, 2.22069E+04, 1.00001E+00, 6.79E-06
23, 4.0054E+04, 5.40053E+04, 9.99997E-01, -2.05E-06
24, 1.53027E+05, 1.53025E+05, 9.99991E-01, -8.52E-06
25, 5.82621E+04, 5.82625E+04, 1.00001E+00, 6.79E-06
26, 5.82621E+04, 5.82625E+04, 1.00001E+00, 6.79E-06
27, 3.6390E+04, 2.14703E+05, 9.99991E-01, -8.52E-06
38, 8.9885E+04, 8.01353E+04, 9.99990E-01, -9.95E-06
39, 9.86272E+04, 9.86277E+04, 1.00001E+00, 1.35E-05
20, 5.82621E+04, 5.82625E+04, 1.00001E+00, 6.79E-06
31, 3.74038E+04, 3.74030E+04, 9.99997E-01, -2.10E-05
32, 1.2420E+05, 1.99999E-01, -3.00E-05
33, 1.8818E+04, 8.45097E+04, 1.00001E+00, 1.35E-05
34, 9.55756E+04, 9.600E+04, 9.99997E-01, -2.06E-06
35, 1.0549E+04, 9.99997E-01, -2.06E-06
36, 9.75777E+04, 7.1673E+04, 9.99996E-01, -3.06E-06
37, 8.45081E+04, 8.45097E+04, 1.00001E+00, 1.35E-05
38, 9.86277E+04, 9.99997E-01, -2.06E-06
39, 9.86277E+04, 9.99996E-01, -4.06E-06
39, 9.86277E+04, 9.99996E-01, -4.06E-
```

C.3.6 Output Files Not Included in this Appendix

The parameter option idisk = 1 specified map output after every iteration. The files RLInt.out.NNNN and RLInt.plot.NNNN contain that information. Any of the files RLInt.out.NNNN can be copied to the file RLInt.dat and used as input to the program RLInt. When that is done, the mapping starts at the map that exists after iteration NNNN. These files also contain the translation vector that was used to map from the previous iteration to the iteration NNNN.

The RLInt.plot.NNNN files are useful for plotting the region maps after iteration step NNNN. They are comma delimited and contain the closure points that are needed to complete the region boundaries.

The files RLInt.sum.NNNN were requested by specifying isum = 1 and idisk = 1. They contain information about all 44 regions after iteration NNNN. One such file, RLInt.sum.0007, is included in the previous section. The file RLInt.sum includes the same information for all iterations. Written after the mapping is complete, it shows the history of each region as the run proceeds. The file sizes shown below are for the 44-region Vermont pop80 map that was used here as an example. Other maps would produce files of different sizes.

Size (bytes)	File Name	Size (bytes)	<u>File Name</u>
39282	RLInt.out.0000	39600	RLInt.plot.0005
39282	RLInt.out.0001	39600	RLInt.plot.0006
39282	RLInt.out.0002	39600	RLInt.plot.0007
39282	RLInt.out.0003	3040	RLInt.sum.0000
39282	RLInt.out.0004	3040	RLInt.sum.0001
39282	RLInt.out.0005	3040	RLInt.sum.0002
39282	RLInt.out.0006	3040	RLInt.sum.0003
39282	RLInt.out.0007	3040	RLInt.sum.0004
39600	RLInt.plot.0000	3040	RLInt.sum.0005
39600	RLInt.plot.0001	3040	RLInt.sum.0006
39600	RLInt.plot.0002	3040	RLInt.sum.0007 *
39600	RLInt.plot.0003	28884	RLInt.sum
39600	RLInt.plot.0004		

^{*} This file is shown in Section C.3.5.

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