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2-LOCAL TRIPLE DERIVATIONS ON VON NEUMANN ALGEBRAS

KARIMBERGEN KUDAYBERGENOV, TIMUR OIKHBERG, ANTONIO M. PERALTA AND BERNARD RUSSO

ABSTRACT. We prove that every (not necessarily linear nor continuous) 2-local triple derivation on a von Neumann algebra M is a triple derivation, equivalently, the set $\text{Der}_t(M)$, of all triple derivations on M, is algebraically 2-reflexive in the set $\mathcal{M}(M) = M^M$ of all mappings from M into M.

1. Introduction

Let X and Y be Banach spaces. According to the terminology employed in the literature (see, for example, [4]), a subset \mathcal{D} of the Banach space B(X, Y), of all bounded linear operators from X into Y, is called *algebraically reflexive* in B(X, Y) when it satisfies the property:

(1.1)
$$T \in B(X,Y)$$
 with $T(x) \in \mathcal{D}(x), \forall x \in X \Rightarrow T \in \mathcal{D}.$

Algebraic reflexivity of \mathcal{D} in the space L(X, Y), of all linear mappings from X into Y, a stronger version of the above property not requiring continuity of T, is defined by:

(1.2)
$$T \in L(X,Y)$$
 with $T(x) \in \mathcal{D}(x), \forall x \in X \Rightarrow T \in \mathcal{D}.$

In 1990, Kadison proved that (1.1) holds if \mathcal{D} is the set Der(M, X) of all (associative) derivations on a von Neumann algebra M into a dual M-bimodule X [18]. Johnson extended Kadison's result by establishing that the set $\mathcal{D} = \text{Der}(A, X)$, of all (associative) derivations from a C*-algebra A into a Banach A-bimodule X satisfies (1.2) [17].

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Algebraic reflexivity of the set of local triple derivations on a C*-algebra and on a JB*-triple have been studied in [24], [9], [12] and [14]. More precisely, Mackey proves in [24] that the set $\mathcal{D} = \text{Der}_t(M)$, of all triple derivations on a JBW*-triple M satisfies (1.1). The result has been supplemented in [12], where Burgos, Fernández-Polo and the third author of this note prove that for each JB*-triple E, the set $\mathcal{D} = \text{Der}_t(E)$ of all triple derivations on E satisfies (1.2).

Hereafter, algebraic reflexivity will refer to the stronger version (1.2) which does not assume the continuity of T.

In [6], Brešar and Šemrl proved that the set of all (algebra) automorphisms of B(H) is algebraically reflexive whenever H is a separable, infinitedimensional Hilbert space. Given a Banach space X, a linear mapping $T: X \to X$ satisfying the hypothesis at (1.2) for $\mathcal{D} = \operatorname{Aut}(X)$, the set of automorphisms on X, is called a *local automorphism*. Larson and Sourour showed in [22] that for every infinite dimensional Banach space X, every surjective local automorphism T on the Banach algebra B(X), of all bounded linear operators on X, is an automorphism.

Motivated by the results of Semrl in [31], references witness a growing interest in a subtle version of algebraic reflexivity called *algebraic 2-reflexivity* (cf. [1], [2], [10], [11], [21], [23], [25], [26] and [29]). A subset \mathcal{D} of the set $\mathcal{M}(X,Y) = Y^X$, of all mappings from X into Y, is called *algebraically 2reflexive* when the following property holds: for each mapping T in $\mathcal{M}(X,Y)$ such that for each $a, b \in X$, there exists $S = S_{a,b} \in \mathcal{D}$ (depending on a and b), with $T(a) = S_{a,b}(a)$ and $T(b) = S_{a,b}(b)$, then T lies in \mathcal{D} . A mapping $T: X \to$ Y satisfying the property that for each $a, b \in X$, there exists $S = S_{a,b} \in \mathcal{D}$ (depending on a and b), with $T(a) = S_{a,b}(a)$ and $T(b) = S_{a,b}(b)$ will be called a 2-local \mathcal{D} -mapping. If we assume that every mapping $S \in \mathcal{D}$ is r-homogeneous (that is, $S(ta) = t^r S(a)$ for every $t \in \mathbb{R}$ or \mathbb{C}) with 0 < r, then every 2-local \mathcal{D} -mapping $T: X \to Y$ is r-homogeneous. Indeed, for each $a \in X, t \in \mathbb{C}$ take $S_{a,ta} \in \mathcal{D}$ satisfying $T(ta) = S_{a,ta}(ta) = t^r S_{a,ta}(a) = t^r T(a)$.

Semrl establishes in [31] that for every infinite-dimensional separable Hilbert space H, the sets $\operatorname{Aut}(B(H))$ and $\operatorname{Der}(B(H))$, of all (algebra) automorphisms and associative derivations on B(H), respectively, are algebraically 2-reflexive in $\mathcal{M}(B(H)) = \mathcal{M}(B(H), B(H))$. Ayupov and the first author of this note proved in [1] that the same statement remains true for general Hilbert spaces (see [20] for the finite dimensional case). Actually, the set $\operatorname{Hom}(A)$, of all homomorphisms on a general C^{*}-algebra A, is algebraically 2-reflexive in the Banach algebra B(A), of all bounded linear operators on A, and the set *-Hom(A), of all *-homomorphisms on A, is algebraically 2-reflexive in the space L(A), of all linear operators on A (cf. [27]).

In recent contributions, Burgos, Fernández-Polo and the third author of this note prove that the set *-Hom(M) (respectively, Hom_t(M)), of all *-homomorphisms (respectively, triple homomorphisms) on a von Neumann algebra (respectively, on a JBW*-triple) M, is an algebraically 2-reflexive subset of $\mathcal{M}(M)$ (cf. [10], [11], respectively), while Ayupov and the first author of this note establish that the set Der(M) of all derivations on M is algebraically 2-reflexive in $\mathcal{M}(M)$ (see [2]).

In this paper, we consider the set $\text{Der}_t(A)$ of all triple derivations on a C^{*}-algebra A. We recall that every C^{*}-algebra A can be equipped with a ternary product of the form

$$\{a, b, c\} = \frac{1}{2} (ab^*c + cb^*a).$$

When A is equipped with this product it becomes a JB^{*}-triple in the sense of [19]. A linear mapping $\delta: A \to A$ is said to be a *triple derivation* when it satisfies the (triple) Leibnitz rule:

$$\delta\{a,b,c\} = \{\delta(a),b,c\} + \{a,\delta(b),c\} + \{a,b,\delta(c)\}.$$

It is known that every triple derivation is automatically continuous (cf. [3]). We refer to [3], [15] and [28] for the basic references on triple derivations. According to the standard notation, 2-local $\text{Der}_t(A)$ -mappings from A into A are called 2-local triple derivations.

The goal of this note is to explore the algebraic 2-reflexivity of $\text{Der}_t(A)$ in $\mathcal{M}(A)$. Our main result proves that every (not necessarily linear nor continuous) 2-local triple derivation on an arbitrary von Neumann algebra M is a triple derivation (hence, linear and continuous) (see Theorem 2.14), equivalently, $\text{Der}_t(M)$ is algebraically 2-reflexive in $\mathcal{M}(M)$.

2. 2-local triple derivations on von Neumann algebras

We start by recalling some generalities on triple derivations. Let A be a C*-algebra. For each $b \in A$, we shall denote by M_b the Jordan multiplication mapping by the element b, that is $M_b(x) = b \circ x = \frac{1}{2}(bx + xb)$. Following standard notation, given elements a, b in A, we denote by L(a, b) the operator on A defined by $L(a,b)(x) = \{a,b,x\} = \frac{1}{2}(ab^*x + xb^*a)$. It is known that the mapping $\delta(a,b): A \to A$, given by

$$\delta(a,b)(x) = L(a,b)(x) - L(b,a)(x),$$

is a triple derivation on A (cf. [3], [15]). A triple derivation which is a finite linear combination of derivations of the form $\delta(a, b)$ is called an *inner triple derivation*.

Let $\delta: A \to A$ be a triple derivation on a unital C*-algebra. By [15, Lemmas 1 and 2], $\delta(\mathbf{1})^* = -\delta(\mathbf{1}), M_{\delta(\mathbf{1})} = \delta(\frac{1}{2}\delta(\mathbf{1}), \mathbf{1})$ is an inner triple derivation on A, and the difference $D = \delta - \delta(\frac{1}{2}\delta(\mathbf{1}), \mathbf{1})$ is a Jordan *-derivation on A, more concretely,

$$D(x \circ y) = D(x) \circ y + x \circ D(y)$$
, and $D(x^*) = D(x)^*$,

for every $x, y \in A$. By [3, Corollary 2.2], δ (and hence D) is a continuous operator. A widely known result, due to B. E. Johnson, states that every bounded Jordan derivation from a C*-algebra A to a Banach A-bimodule is an associative derivation (cf. [16]). Therefore, D is an associative *derivation in the usual sense. When A = M is a von Neumann algebra, we can guarantee that D is an inner derivation, that is, there exists $\tilde{a} \in A$ satisfying $D(x) = [\tilde{a}, x] = \tilde{a}x - x\tilde{a}$, for every $x \in A$ (cf. [30, Theorem 4.1.6]). Further, from the condition $D(x^*) = D(x)^*$, for every $x \in A$, we deduce that $(\tilde{a}^* + \tilde{a})x = x(\tilde{a}^* + \tilde{a})$. Thus, taking $a = \frac{1}{2}(\tilde{a} - \tilde{a}^*)$, it follows that $[a, x] = [\tilde{a}, x]$, for every $x \in M$. We have therefore shown that for every triple derivation δ on a von Neumann algebra M, there exist skew-Hermitian elements $a, b \in M$ satisfying

$$\delta(x) = [a, x] + b \circ x,$$

for every $x \in M$.

Our first lemma is a direct consequence of the above arguments (see [15, Lemmas 1 and 2]).

LEMMA 2.1. Let $T: A \to A$ be a (not necessarily linear nor continuous) 2-local triple derivation on a unital C^{*}-algebra. Then

(a) T(1)* = −T(1);
(b) M_{T(1)} = δ(¹/₂T(1), 1) is an inner triple derivation on A;
(c) T̂ = T − δ(¹/₂T(1), 1) is a 2-local triple derivation on A with T̂(1) = 0.

In what follows, we denote by A_{sa} the Hermitian elements of the C^{*}-algebra A.

LEMMA 2.2. Let $T: A \to A$ be a (not necessarily linear nor continuous) 2local triple derivation on a unital C^* -algebra satisfying $T(\mathbf{1}) = 0$. Then $T(x) = T(x)^*$ for all $x \in A_{sa}$.

Proof. Let $x \in A_{sa}$. By assumptions,

$$T(x)^* = \{\mathbf{1}, T(x), \mathbf{1}\} = \{\mathbf{1}, \delta_{x, \mathbf{1}}(x), \mathbf{1}\} = \delta_{x, \mathbf{1}}\{\mathbf{1}, x, \mathbf{1}\} - 2\{\delta_{x, \mathbf{1}}(\mathbf{1}), x, \mathbf{1}\} \\ = \delta_{x, \mathbf{1}}(x^*) - 2\{T(\mathbf{1}), x, \mathbf{1}\} = \delta_{x, \mathbf{1}}(x) = T(x).$$

The proof is complete.

LEMMA 2.3. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on a von Neumann algebra satisfying $T(\mathbf{1}) = 0$. Then for every $x, y \in M_{sa}$ there exists a skew-Hermitian element $a_{x,y} \in M$ such that

$$T(x) = [a_{x,y}, x], \text{ and } T(y) = [a_{x,y}, y].$$

Proof. For every $x, y \in M_{sa}$ we can find skew-Hermitian elements $a_{x,y}, b_{x,y} \in M$ such that

$$T(x) = [a_{x,y}, x] + b_{x,y} \circ x$$
 and $T(y) = [a_{x,y}, y] + b_{x,y} \circ y$.

$$\square$$

Taking into account that $T(x) = T(x)^*$ (see Lemma 2.2), we obtain

$$\begin{split} [a_{x,y},x] + b_{x,y} \circ x &= T(x) = T(x)^* = [a_{x,y},x]^* + (b_{x,y} \circ x)^* \\ &= [x,a_{x,y}^*] + x \circ b_{x,y}^* = [x,-a_{x,y}] - x \circ b_{x,y} \\ &= [a_{x,y},x] - b_{x,y} \circ x, \end{split}$$

that is, $b_{x,y} \circ x = 0$, and similarly $b_{x,y} \circ y = 0$. Therefore, $T(x) = [a_{x,y}, x]$, $T(y) = [a_{x,y}, y]$, and the proof is complete.

We state now an observation which plays a useful role in our study.

LEMMA 2.4. Let a and b be skew-Hermitian elements in a C^{*}-algebra A. Suppose $x \in A$ is self-adjoint with $[a, x] + 2b \circ x = 0$. Then [a, x] = 0 and $b \circ x = 0$.

Proof. Since 0 = ax - xa + bx + xb, by passing to the adjoint, we obtain ax - xa - (bx + xb) = 0. The conclusion is reached by adding and subtracting these two equalities.

Let M be a von Neumann algebra. If $x \in M_{sa}$, we denote by s(x) the support projection of x, that is, the projection onto $(\ker(x))^{\perp} = \overline{\operatorname{ran}(x)}$. We say that x has full support if $s(x) = \mathbf{1}$ (equivalently, $\ker(x) = \{0\}$).

LEMMA 2.5. Let M be a von Neumann algebra. Suppose $u \in M_+$ has full support, $c \in M$ is self-adjoint, and $\sigma(c^2u) \cap (0, \infty) = \emptyset$. Then c = 0. Consequently, if u and c are as above, and uc + cu = 0 (or $c^2u = -cuc \leq 0$), then c = 0.

Proof. For the first statement of the lemma, suppose $\sigma(c^2 u) \cap (0, \infty) = \emptyset$. Note that

$$\sigma(c^2u) \cup \{0\} = \sigma(c \cdot cu) \cup \{0\} = \sigma(cuc) \cup \{0\}.$$

However, *cuc* is positive, hence $\sigma(cuc) \subset [0, \|cuc\|]$, with $\max_{\lambda \in \sigma(cuc)} = \|cuc\|$. Thus, $cu^{1/2}u^{1/2}c = cuc = 0$, which means that $cu^{1/2} = u^{1/2}c = 0$ and hence $s(c) \leq 1 - s(u^{1/2}) = 1 - s(u) = 0$, which leads to c = 0.

To prove the second part, we have $c^2 u = -cuc \leq 0$, hence in particular, $\sigma(c^2 u) \subset (-\infty, 0]$. The proof is complete.

In [2, Lemma 2.2], Ayupov and the first author of this note prove that for every (not necessarily linear nor continuous) 2-local derivation on a von Neumann algebra $\Delta: M \to M$, and every self-adjoint element $z \in M$, there exists $a \in M$ satisfying

$$\Delta(x) = [a, x],$$

for every $x \in \mathcal{W}^*(z)$, where $\mathcal{W}^*(z) = \{z\}''$ denotes the Abelian von Neumann subalgebra of M generated by the element z, and the unit element and $\{z\}''$ denotes the bicommutant of the set $\{z\}$. We prove next a ternary version of this result.

LEMMA 2.6. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2local triple derivation on a von Neumann algebra. Let $z \in M$ be a self-adjoint element and let $W^*(z) = \{z\}''$ be the Abelian von Neumann subalgebra of M generated by the element z and the unit element. Then there exist skew-Hermitian elements $a_z, b_z \in M$, depending on z, such that

$$T(x) = [a_z, x] + b_z \circ x = a_z x - xa_z + \frac{1}{2}(b_z x + xb_z)$$

for all $x \in W^*(z)$. In particular, T is linear on $W^*(z)$.

Proof. We can assume that $z \neq 0$. Note that the Abelian von Neumann subalgebras generated by **1** and z and by **1** and $\mathbf{1} + \frac{z}{2||z||}$ coincide. So, replacing z with $\mathbf{1} + \frac{z}{2||z||}$ we can assume that z is an invertible positive element.

By definition, there exist skew-Hermitian elements $a_z, b_z \in M$ (depending on z) such that

$$T(z) = [a_z, z] + b_z \circ z.$$

Define a mapping $T_0: M \to M$ given by $T_0(x) = T(x) - ([a_z, x] + b_z \circ x), x \in M$. Clearly, T_0 is a 2-local triple derivation on M. We shall show that $T_0 = 0$ on $\mathcal{W}^*(z)$. Let $x \in \mathcal{W}^*(z)$ be an arbitrary element. By assumptions, there exist skew-Hermitian elements $c_{z,x}, d_{z,x} \in M$ such that

$$T_0(z) = [c_{z,x}, z] + d_{z,x} \circ z$$
, and $T_0(x) = [c_{z,x}, x] + d_{z,x} \circ x$.

Since $0 = T_0(z) = [c_{z,x}, z] + d_{z,x} \circ z$, we get $[c_{z,x}, z] + d_{z,x} \circ z = 0$.

Taking into account that z is a Hermitian element and Lemma 2.4 we get $c_{z,x}z = zc_{z,x}$ and $d_{z,x}z = -zd_{z,x}$.

Since z has full support, and $d_{z,x}^2 z = -d_{z,x}zd_{z,x}$, Lemma 2.5 implies that $d_{z,x} = 0$. Further

$$c_{z,x} \in \{z\}' = \{z\}''' = \mathcal{W}^*(z)'$$

that is, $c_{z,x}$ commutes with any element in $\mathcal{W}^*(z)$. Therefore $T_0(x) = [c_{z,x}, x] + d_{z,x} \circ x = 0$, for all $x \in \mathcal{W}^*(z)$. The proof is complete.

2.1. Complete additivity of 2-local derivations and 2-local triple derivations on von Neumann algebras. Let $\mathcal{P}(M)$ denote the lattice of projections in a von Neumann algebra M. Let X be a Banach space. A mapping $\mu : \mathcal{P}(M) \to X$ is said to be *finitely additive* when

(2.1)
$$\mu\left(\sum_{i=1}^{n} p_i\right) = \sum_{i=1}^{n} \mu(p_i),$$

for every family p_1, \ldots, p_n of mutually orthogonal projections in M.

A mapping $\mu : \mathcal{P}(M) \to X$ is said to be *bounded* when the set

$$\left\{ \left\| \mu(p) \right\| : p \in \mathcal{P}(M) \right\}$$

is bounded. The celebrated Bunce–Wright–Mackey–Gleason theorem ([7], [8]) states that if M has no summand of type I_2 , then every bounded finitely

additive mapping $\mu : \mathcal{P}(M) \to X$ extends to a bounded linear operator from M to X.

According to the terminology employed in [32] and [13], a completely additive mapping $\mu : \mathcal{P}(M) \to \mathbb{C}$ —that is, (2.1) holds for an arbitrary set I; see (2.2) below—is called a *charge*. The Dorofeev–Sherstnev theorem ([32, Theorem 29.5] or [13, Theorem 2]) states that any charge on a von Neumann algebra with no summands of type I_n $(n < \infty)$ is bounded.

We shall use the Dorofeev–Shertsnev theorem in Corollary 2.8 in order to be able to apply the Bunce-Wright-Mackey-Gleason theorem in Proposition 2.9. To this end, we need Proposition 2.7, which is implicitly applied in [2, proof of Lemma 2.3] for 2-local associative derivations. A proof is included here for completeness reasons.

First, we recall some facts about the strong^{*} topology. For each normal positive functional φ in the predual of a von Neumann algebra M, the mapping

$$x \mapsto \|x\|_{\varphi} = \left(\varphi\left(\frac{xx^* + x^*x}{2}\right)\right)^{\frac{1}{2}} \quad (x \in M)$$

defines a prehilbertian seminorm on M. The strong^{*} topology of M is the locally convex topology on M defined by all the seminorms $\|\cdot\|_{\varphi}$, where φ runs over the set of all positive functionals in M_* (cf. [30, Definition 1.8.7]). It is known that the strong^{*} topology of M is compatible with the duality (M, M_*) , that is a functional $\psi: M \to \mathbb{C}$ is strong^{*} continuous if and only if it is weak^{*} continuous (see [30, Corollary 1.8.10]). if and only if it is weak^{*} continuous. We also recall that multiplication in every von Neumann algebra is jointly strong^{*} continuous on bounded sets (see [30, Proposition 1.8.12]).

Suppose X = W is another von Neumann algebra, and let τ denote the norm, the weak^{*} or the strong^{*} topology of W. The mapping μ is said to be τ -completely additive (respectively, countably or sequentially τ -additive) when

(2.2)
$$\mu\left(\sum_{i\in I} p_i\right) = \tau \cdot \sum_{i\in I} \mu(p_i)$$

for every family (respectively, sequence) $\{p_i\}_{i \in I}$ of mutually orthogonal projections in M.

It is known that every family $(p_i)_{i \in I}$ of mutually orthogonal projections in a von Neumann algebra M is summable with respect to the weak* topology of M and $p = \text{weak}^* - \sum_{i \in I} p_i$ is a projection in M (cf. [30, Definition 1.13.4]). Further, for each normal positive functional ϕ in M_* and every finite set $F \subset I$, we have

$$\left\|p-\sum_{i\in F}p_i\right\|_{\phi}^2 = \phi\left(p-\sum_{i\in F}p_i\right),$$

which implies that the family $(p_i)_{i \in I}$ is summable with respect to the strong^{*} topology of M with the same limit, that is, $p = \text{strong}^* - \sum_{i \in I} p_i$.

PROPOSITION 2.7. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on a von Neumann algebra. Then the following statements hold:

- (a) The restriction $T|_{\mathcal{P}(M)}$ is sequentially strong^{*} additive, and consequently sequentially weak^{*} additive;
- (b) $T|_{\mathcal{P}(M)}$ is weak^{*} completely additive, that is,

(2.3)
$$T\left(weak^* - \sum_{i \in I} p_i\right) = weak^* - \sum_{i \in I} T(p_i)$$

for every family $(p_i)_{i \in I}$ of mutually orthogonal projections in M.

Proof. (a) Let $(p_n)_{n\in\mathbb{N}}$ be a sequence of mutually orthogonal projections in M. Let us consider the element $z = \sum_{n\in\mathbb{N}} \frac{1}{n}p_n$. By Lemma 2.6, there exist skew-Hermitian elements $a_z, b_z \in M$ such that $T(x) = [a_z, x] + b_z \circ x$ for all $x \in \mathcal{W}^*(z)$. Since $\sum_{n=1}^{\infty} p_n, p_m \in \mathcal{W}^*(z)$, for all $m \in \mathbb{N}$, and the multiplication in M is jointly strong^{*} continuous, we obtain that

$$T\left(\sum_{n=1}^{\infty} p_n\right) = \left[a_z, \sum_{n=1}^{\infty} p_n\right] + b_z \circ \left(\sum_{n=1}^{\infty} p_n\right)$$
$$= \sum_{n=1}^{\infty} [a_z, p_n] + \sum_{n=1}^{\infty} b_z \circ p_n = \sum_{n=1}^{\infty} T(p_n).$$

that is, $T|_{\mathcal{P}(M)}$ is a countably or sequentially strong^{*} additive mapping.

(b) Let φ be a positive normal functional in M_* , and let $\|\cdot\|_{\varphi}$ denote the prehilbertian seminorm given by $\|z\|_{\varphi}^2 = \frac{1}{2}\varphi(zz^* + z^*z)$ $(z \in M)$. Let $\{p_i\}_{i \in I}$ be an arbitrary family of mutually orthogonal projections in M. For every $n \in \mathbb{N}$, define

$$I_n = \{i \in I : ||T(p_i)||_{\varphi} \ge 1/n\}.$$

We claim, that I_n is a finite set for every natural n. Otherwise, passing to a subset if necessary, we can assume that there exists a natural k such that I_k is infinite and countable. In this case, the series $\sum_{i \in I_k} T(p_i)$ does not converge with respect to the semi-norm $\|\cdot\|_{\varphi}$. On the other hand, since I_k is a countable set, by (a), we have

$$T\left(\sum_{i\in I_k} p_i\right) = \operatorname{strong}^*\operatorname{-} \sum_{i\in I_k} T(p_i),$$

which is impossible. This proves the claim.

We have shown that the set

$$I_0 = \left\{ i \in I : \left\| T(p_i) \right\|_{\varphi} \neq 0 \right\} = \bigcup_{n \in \mathbb{N}} I_n$$

is a countable set, and $||T(p_i)||_{\varphi} = 0$, for every $i \in I \setminus I_0$.

Set $p = \sum_{i \in I \setminus I_0} p_i \in M$. We shall show that $\varphi(T(p)) = 0$. Let q denote the support projection of φ in M (see [30, 1.14.2]). Having in mind that $||T(p_i)||_{\varphi}^2 = 0$, for every $i \in I \setminus I_0$, we deduce that $T(p_i) \perp q$ for every $i \in I \setminus I_0$.

Replacing T with $\widehat{T} = T - \delta(\frac{1}{2}T(\mathbf{1}), \mathbf{1})$ we can assume that $T(\mathbf{1}) = 0$ (cf. Lemma 2.1) and $T(x) = T(x)^*$, for every $x \in M_{sa}$ (cf. Lemma 2.2). By Lemma 2.3, for every $i \in I \setminus I_0$ there exists a skew-Hermitian element $a_i = a_{p,p_i} \in M$ such that

$$T(p) = a_i p - p a_i$$
 and $T(p_i) = a_i p_i - p_i a_i$.

Since $T(p_i) \perp q$ we get $(a_i p_i - p_i a_i)q = q(a_i p_i - p_i a_i) = 0$, for all $i \in I \setminus I_0$. Thus, since $pa_i p_i q = p_i a_i q$,

$$(T(p)p_i)q = (a_ip - pa_i)p_iq = a_ip_iq - pa_ip_iq$$

= $a_ip_iq - p_ia_iq = (a_ip_i - p_ia_i)q = 0$,

and similarly

$$q(p_i T(p)) = 0,$$

for every $i \in I \setminus I_0$. Consequently,

(2.4)
$$(T(p)p)q = T(p)\left(\sum_{i\in I\setminus I_0} p_i\right)q = 0 = q\left(\sum_{i\in I\setminus I_0} p_i\right)T(p) = q\left(pT(p)\right).$$

Therefore,

$$\begin{split} T(p) &= \delta_{p,1}(p) = \delta_{p,1}\{p,p,p\} = 2\{\delta_{p,1}(p),p,p\} + \{p,\delta_{p,1}(p),p\} \\ &= 2\{T(p),p,p\} + \{p,T(p),p\} = pT(p) + T(p)p + pT(p)^*p \\ &= pT(p) + T(p)p + pT(p)p, \end{split}$$

which implies that

$$\varphi(T(p)) = \varphi(pT(p) + T(p)p + pT(p)p)$$

= $\varphi(qpT(p)q) + \varphi(qT(p)pq) + \varphi(qpT(p)pq) = (by (2.4)) = 0.$

Finally, by (a) we have

$$T\left(\sum_{i\in I_0} p_i\right) = \|.\|_{\varphi} \cdot \sum_{i\in I_0} T(p_i).$$

Two more applications of (a) give:

$$\varphi\left(T\left(\sum_{i\in I} p_i\right)\right) = \varphi\left(T\left(p + \sum_{i\in I_0} p_i\right)\right) = \varphi\left(T(p) + T\left(\sum_{i\in I_0} p_i\right)\right)$$
$$= \varphi(T(p)) + \varphi\left(T\left(\sum_{i\in I_0} p_i\right)\right) = \sum_{i\in I_0} \varphi(T(p_i)).$$

By the Cauchy–Schwarz inequality, $0 \leq |\varphi T(p_i)|^2 \leq ||T(p_i)||_{\varphi}^2 = 0$, for every $i \in I \setminus I_0$, and hence $\sum_{i \in I_0} \varphi(T(p_i)) = \sum_{i \in I} \varphi(T(p_i))$. The arbitrariness of φ shows that $T(\operatorname{weak}^* - \sum_{i \in I} p_i) = \operatorname{weak}^* - \sum_{i \in I} T(p_i)$.

Let ϕ be a normal functional in the predual of a von Neumann algebra M. Our previous Proposition 2.7 assures that for every (not necessarily linear nor continuous) 2-local triple derivation $T: M \to M$ the mapping $\phi \circ T|_{\mathcal{P}(M)}: \mathcal{P}(M) \to \mathbb{C}$ is a completely additive mapping or a charge on M. Under the additional hypothesis of M being a continuous von Neumann algebra or, more generally, a von Neumann algebra with no Type I_n $(1 < n < \infty)$ direct summands, the Dorofeev–Sherstnev theorem ([32, Theorem 29.5] or [13, Theorem 2]) imply that $\phi \circ T|_{\mathcal{P}(M)}$ is a bounded charge, that is, the set $\{|\phi \circ T(p)|: p \in \mathcal{P}(M)\}$ is bounded. The uniform boundedness principle gives:

COROLLARY 2.8. Let M be a von Neumann algebra with no Type I_n direct summands $(1 < n < \infty)$ and let $T : M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation. Then the restriction $T|_{\mathcal{P}(M)}$ is a bounded weak^{*} completely additive mapping.

2.2. Additivity of 2-local triple derivations on Hermitian parts of von Neumann algebras. Suppose now that M is a von Neumann algebra with no Type I_n direct summands $(1 < n < \infty)$, and $T: M \to M$ is a (not necessarily linear nor continuous) 2-local triple derivation. By Corollary 2.8 combined with the Bunce-Wright-Mackey-Gleason theorem [7], [8], there exists a bounded linear operator $G: M \to M$ satisfying G(p) = T(p), for every projection $p \in M$.

Let z be a self-adjoint element in M. By Lemma 2.6, there exist skew-Hermitian elements $a_z, b_z \in M$ such that $T(x) = [a_z, x] + b_z \circ x$, for every $x \in \mathcal{W}^*(z)$. Since $G|_{\mathcal{W}^*(z)}, T|_{\mathcal{W}^*(z)} : \mathcal{W}^*(z) \to M$ are bounded linear operators, which coincide on the set of projections of $\mathcal{W}^*(z)$, and since every self-adjoint element in $\mathcal{W}^*(z)$ can be approximated in norm by finite linear combinations of mutually orthogonal projections in $\mathcal{W}^*(z)$, it follows that T(x) = G(x) for every $x \in \mathcal{W}^*(z)$, and hence

$$T(a) = G(a), \text{ for every } a \in M_{sa},$$

in particular, T is additive on M_{sa} .

The above arguments prove the following result.

PROPOSITION 2.9. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on a von Neumann algebra with no Type I_n -factor direct summands $(1 < n < \infty)$. Then the restriction $T|_{M_{sa}}$ is additive.

COROLLARY 2.10. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on a properly infinite von Neumann algebra. Then the restriction $T|_{M_{sa}}$ is additive. Next, we shall show that the conclusion of the above corollary is also true for a finite von Neumann algebra.

First, we show that every 2-local triple derivation on a von Neumann algebra "intertwines" central projections.

LEMMA 2.11. If T is a (not necessarily linear nor continuous) 2-local triple derivation on a von Neumann algebra M, and p is a central projection in M, then $T(Mp) \subset Mp$. In particular, T(px) = pT(x) for every $x \in M$.

Proof. If $x \in Mp$, then $x = pxp = \{x, p, p\}$. Since T coincides with a triple derivation $\delta_{x,p}$ on the set $\{x, p\}$,

$$T(x) = \delta_{x,p}(x) = \delta_{x,p}\{x, p, p\} = \{\delta_{x,p}(x), p, p\} + \{x, \delta_{x,p}(p), p\} + \{x, p, \delta_{x,p}(p)\}$$
lies in Mp .

For the final statement, fix $x \in M$, and consider skew-Hermitian elements $a_{x,xp}, b_{x,xp} \in M$ satisfying

$$T(x) = [a_{x,xp}, x] + b_{x,xp} \circ x, \quad \text{and} \quad T(xp) = [a_{x,xp}, xp] + b_{x,xp} \circ (xp).$$

The assumption p being central implies that pT(x) = T(px).

PROPOSITION 2.12. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on a finite von Neumann algebra. Then the restriction $T|_{M_{sa}}$ is additive.

Proof. Since M is finite there exists a faithful normal semi-finite trace τ on M. We shall consider the following two cases.

Case 1. Suppose τ is a finite trace. Replacing T with $\widehat{T} = T - \delta(\frac{1}{2}T(1), 1)$ we can assume that T(1) = 0 (cf. Lemma 2.1) and $T(x) = T(x)^*$, for every $x \in M_{sa}$ (cf. Lemma 2.2). By Lemma 2.3, for every $x, y \in M_{sa}$ there exists a skew-Hermitian element $a_{x,y} \in M$ such that $T(x) = [a_{x,y}, x]$ and $T(y) = [a_{x,y}, y]$. Then

$$T(x)y + xT(y) = [a_{x,y}, x]y + x[a_{x,y}, y] = [a_{x,y}, xy],$$

that is,

$$[a_{x,y}, xy] = T(x)y + xT(y).$$

Further

$$0 = \tau \left([a_{x,y}, xy] \right) = \tau \left(T(x)y + xT(y) \right),$$

that is, $\tau(T(x)y) = -\tau(xT(y))$, for every $x, y \in M_{sa}$. For arbitrary $u, v, w \in M_{sa}$, set x = u + v, and y = w. The above identity implies

$$\tau (T(u+v)w) = -\tau ((u+v)T(w)) =$$

= $-\tau (uT(w)) - \tau (vT(w)) = \tau (T(u)w) + \tau (T(v)w)$
= $\tau ((T(u) + T(v))w),$

and so

$$\tau\big(\big(T(u+v) - T(u) - T(v)\big)w\big) = 0$$

 \Box

for all $u, v, w \in M_{sa}$. Take w = T(u+v) - T(u) - T(v). Then $\tau(ww^*) = 0$. Since the trace τ is faithful it follows that $ww^* = 0$, and hence w = 0. Therefore, T(u+v) = T(u) + T(v).

Case 2. Suppose now that τ is a semi-finite trace. As in Case 1, we may assume $T(\mathbf{1}) = 0$. Since M is finite there exists a family of mutually orthogonal central projections $\{z_i\}$ in M such that z_i has finite trace for all i and $\bigvee z_i = \mathbf{1}$ (cf. [30, §2.2 or Corollary 2.4.7]). By Lemma 2.11, for each i, T maps z_iM into itself. From Case 1, $T|_{z_iM} : z_iM \to z_iM$ is additive. Furthermore,

$$z_iT(x+y) = T|_{z_iM}(z_ix+z_iy) = T|_{z_iM}(z_ix) + T|_{z_iM}(z_iy) = z_iT(x) + z_iT(y),$$
for every $x, y \in M$ and every i . Therefore,

$$T(x+y) = \left(\sum_{i} z_{i}\right)T(x+y) = \sum_{i} z_{i}T(x+y) = \sum_{i} \left(z_{i}T(x) + z_{i}T(y)\right)$$
$$= \left(\sum_{i} z_{i}\right)T(x) + \left(\sum_{i} z_{i}\right)T(y) = T(x) + T(y),$$

for every $x, y \in M$. The proof is complete.

Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on an arbitrary von Neumann algebra. In this case, there exist orthogonal central projections $z_1, z_2 \in M$ with $z_1 + z_2 = \mathbf{1}$ such that:

- z_1M is a finite von Neumann algebra;
- z_2M is a properly infinite von Neumann algebra,

 $(cf. [30, \S 2.2]).$

By Lemma 2.11, for each $k = 1, 2, z_k T$ maps $z_k M$ into itself. By Corollary 2.10 and Proposition 2.12 both $z_1 T$ and $z_2 T$ are additive on M_{sa} . So $T = z_1 T + z_2 T$ also is additive on M_{sa} .

We have thus proved the following result.

PROPOSITION 2.13. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on an arbitrary von Neumann algebra. Then the restriction $T|_{M_{sa}}$ is additive.

2.3. Main result. We can state now the main result of this paper.

THEOREM 2.14. Let M be an arbitrary von Neumann algebra and let T: $M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation. Then T is a triple derivation (hence linear and continuous). Equivalently, the set $\text{Der}_t(M)$, of all triple derivations on M, is algebraically 2-reflexive in the set $\mathcal{M}(M) = M^M$ of all mappings from M into M.

We need the following two lemmata.

LEMMA 2.15. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on a von Neumann algebra with $T(\mathbf{1}) = 0$. Then there

exists a skew-Hermitian element $a \in M$ such that T(x) = [a, x], for all $x \in M_{sa}$.

Proof. Let $x \in M_{sa}$. By Lemma 2.3, there exists a skew-Hermitian element $a_{x,x^2} \in M$ such that $T(x) = [a_{x,x^2}, x], T(x^2) = [a_{x,x^2}, x^2]$. Thus,

$$T(x^{2}) = [a_{x,x^{2}}, x^{2}] = [a_{x,x^{2}}, x]x + x[a_{x,x^{2}}, x] = T(x)x + xT(x),$$

that is,

(2.5)
$$T(x^2) = T(x)x + xT(x),$$

for every $x \in M_{sa}$.

By Proposition 2.13 and Lemma 2.2, $T|_{M_{sa}}: M_{sa} \to M_{sa}$ is a real linear mapping. Now, we consider the linear extension \hat{T} of $T|_{M_{sa}}$ to M defined by

 $\widehat{T}(x_1 + ix_2) = T(x_1) + iT(x_2), \quad x_1, x_2 \in M_{sa}.$

Taking into account the homogeneity of T, Proposition 2.13 and the identity (2.5) we obtain that \hat{T} is a Jordan derivation on M. By [5, Theorem 1] any Jordan derivation on a semi-prime algebra is a derivation. Since M is von Neumann algebra, \hat{T} is a derivation on M (see also [33] and [16]). Therefore, there exists an element $a \in M$ such that $\hat{T}(x) = [a, x]$ for all $x \in M$. In particular, T(x) = [a, x] for all $x \in M_{sa}$. Since $T(M_{sa}) \subseteq M_{sa}$, we can assume that $a^* = -a$, which completes the proof. \Box

LEMMA 2.16. Let $T: M \to M$ be a (not necessarily linear nor continuous) 2-local triple derivation on a von Neumann algebra. If $T|_{M_{sa}} \equiv 0$, then $T \equiv 0$.

Proof. Let $x \in M$ be an arbitrary element and let $x = x_1 + ix_2$, where $x_1, x_2 \in M_{sa}$. Since T is homogeneous, by passing to the element $(1 + ||x_2||)^{-1}x$ if necessary, we can suppose that $||x_2|| < 1$. In this case, the element $y = \mathbf{1} + x_2$ is positive and invertible. Take skew-Hermitian elements $a_{x,y}, b_{x,y} \in M$ such that

$$T(x) = [a_{x,y}, x] + b_{x,y} \circ x$$
, and $T(y) = [a_{x,y}, y] + b_{x,y} \circ y$.

Since T(y) = 0, we get $[a_{x,y}, y] + b_{x,y} \circ y = 0$. By Lemma 2.4 we obtain that $[a_{x,y}, y] = 0$ and $ib_{x,y} \circ y = 0$. Taking into account that $ib_{x,y}$ is Hermitian, y is positive and invertible, Lemma 2.5 implies that $b_{x,y} = 0$.

We further note that $0 = [a_{x,y}, y] = [a_{x,y}, \mathbf{1} + x_2] = [a_{x,y}, x_2]$, that is, $[a_{x,y}, x_2] = 0$. Now, $T(x) = [a_{x,y}, x] + b_{x,y} \circ x = [a_{x,y}, x_1 + ix_2] = [a_{x,y}, x_1]$, i.e. $T(x) = [a_{x,y}, x_1]$. Therefore,

$$T(x)^* = [a_{x,y}, x_1]^* = [x_1, a_{x,y}^*] = [x_1, -a_{x,y}] = [a_{x,y}, x_1] = T(x)$$

So $T(x)^* = T(x)$. Now, replacing x by ix we obtain, from the homogeneity of T, that $T(x)^* = -T(x)$. Combining the last two identities, we obtain that T(x) = 0, which finishes the proof.

Proof of Theorem 2.14. Let us define $\widehat{T} = T - \delta(\frac{1}{2}T(\mathbf{1}), \mathbf{1})$. Then \widehat{T} is a 2-local triple derivation on M with $\widehat{T}(\mathbf{1}) = 0$ (cf. Lemma 2.1) and $\widehat{T}(x) = \widehat{T}(x)^*$, for every $x \in M_{sa}$ (cf. Lemma 2.2). By Lemma 2.15, there exists an element $a \in M$ such that $\widehat{T}(x) = [a, x]$ for all $x \in M_{sa}$. Consider the 2-local triple derivation $\widehat{T} - [a, \cdot]$. Since $(\widehat{T} - [a, \cdot])|_{M_{sa}} \equiv 0$, Lemma 2.16 implies that $\widehat{T} = [a, \cdot]$, and hence $T = [a, \cdot] + \delta(\frac{1}{2}T(\mathbf{1}), \mathbf{1})$, witnessing the desired statement. \Box

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