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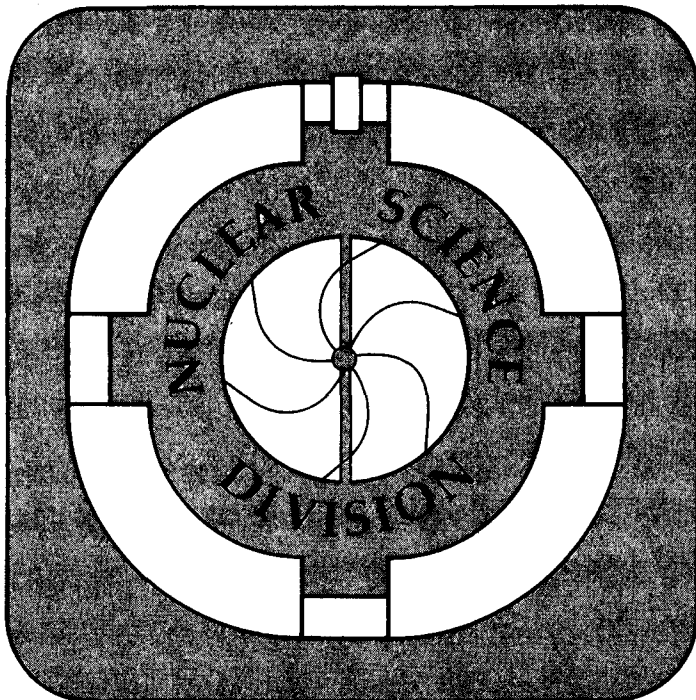
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STABILITY OF A KAPCHINSKIY-VLADIMIRSKIY BEAM
IN A CONTINUOUS-SOLENOID TRANSPORT SYSTEM

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The oscillation modes of a Kapchinskij-Vladimirskij beam¹⁾ have been analyzed by Gluckstern²⁾ for the case of a continuous (constant) focussing system. His results permit one to examine the stability of such a beam subject to small (infinitesimal) perturbations of various forms (including perturbations that are not azimuthally symmetrical). We have made preliminary calculations to this end for several cases characterized by different values of the indices m, j , including $m > 0$ (Gluckstern's notation²⁾), with results presented in attached tabulations. Work sheets and related graphs are also attached.

*Work supported by the U.S. Department of Energy. Calculations performed at the behest of Dr. Lloyd Smith (LBL).

1) I.M. Kapchinskij and V.V. Vladimirskij, Proc. Internat. Conf. High Energy Accelerators, CERN (Geneva, Switzerland; 1959); p. 274.

2) R.L. Gluckstern, Pros. Proton Linear Accelerator Conference, Fermi National Accelerator Laboratory (Batavia, Illinois; 1970), p. 811.
For a perturbation expressed by

$$G(r, \theta) = r^m \begin{Bmatrix} \cos m\theta \\ \sin m\theta \end{Bmatrix} {}_2F_1(-j, m+j, m+1; r^2) \quad [\text{See Eqn. (18), p. 814}],$$

the controlling equation is

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = -i\lambda \int_0^\infty (\cos s)^m {}_2F_1(-j, m+j, m+1; \cos^2 \theta) e^{i\lambda s} ds$$

[Eqn. (19), p. 814], where $v^2 = v_0^2 - \omega_p^2$, ${}_2F_1$ is the hypergeometric function, and $\delta_{j,0}$ is the Kronecker delta. Evaluation of the integral, for any specified

Footnote 2) continued.

pair of indices, leads to a result of the form

$$\frac{v^2}{\omega_p^2} = \text{Fcn}(\lambda^2).$$

A plot of $\text{Fcn}(\lambda^2)$ vs. λ^2 (for positive values of λ^2) serves to indicate whether a full set of positive roots λ^2 exists for every positive value of v^2/ω_p^2 (unconditional stability) or, otherwise, reveals the lower bound to v^2/ω_p^2 values for which a full set of positive roots λ^2 will occur (condition for stability).

K-V BEAM IN CONTINUOUS SOLENOID
 Stability (for all Intensities), or Stability Condition

m \ j	0	1	2	3	4
0	—	r^2 : STABLE	r^4 : $\frac{v}{v_0} > \frac{1}{\sqrt{17}} \approx 0.2425356$	r^6 : $\frac{v}{v_0} > 0.3858759$	r^8 : $\frac{v}{v_0} > 0.3985085$
1	$r \cos \theta$: STABLE	$r^3 \cos \theta$: STABLE	$r^5 \cos \theta$: STABLE	$r^7 \cos \theta$: $\frac{v}{v_0} > 0.2873514$	
2	$r^2 \cos 2\theta$: STABLE	$r^4 \cos 2\theta$: STABLE	$r^6 \cos 2\theta$: $\frac{v}{v_0} > \frac{1}{\sqrt{33}} \approx 0.1740777$	$r^8 \cos 2\theta$: $\frac{v}{v_0} > 0.2581845$	
3	$r^3 \cos 3\theta$: STABLE	$r^5 \cos 3\theta$: STABLE	$r^7 \cos 3\theta$: $\frac{v}{v_0} > 0.2183735$		
4	$r^4 \cos 4\theta$: STABLE	$r^6 \cos 4\theta$: STABLE	$r^8 \cos 4\theta$: $\frac{v}{v_0} > \sqrt{\frac{5}{261}} \approx 0.1384091$		
5	$r^5 \cos 5\theta$: STABLE	$r^7 \cos 5\theta$: STABLE			

m	j	MODE: $r^{m+j} \cos m\theta$		
0	0	---	OMIT	
0	1	r^2	$v^2/\omega_p^2 = \frac{2}{\lambda^2-4}$	STABLE
0	2	r^4	$v^2/\omega_p^2 = -\frac{1}{\lambda^2-4} + \frac{3}{\lambda^2-16}$	Stable only for $v^2/\omega_p^2 > \frac{1}{16}$, or $v^2/\omega_p^2 > \frac{1}{17} = 0.2425356$
0	3	r^6	$v^2/\omega_p^2 = \frac{1}{4} \left[\frac{1}{\lambda^2-4} - \frac{8}{\lambda^2-16} + \frac{15}{\lambda^2-36} \right]$	Stable only for $v^2/\omega_p^2 > 0.17495034$ or $v^2/\omega_p^2 > 0.3858759$
0	4	r^8	$v^2/\omega_p^2 = \frac{1}{16} \left[-\frac{3}{\lambda^2-4} + \frac{10}{\lambda^2-16} - \frac{45}{\lambda^2-36} + \frac{70}{\lambda^2-64} \right]$	Stable only for $v^2/\omega_p^2 > 0.18879054$ or $v^2/\omega_p^2 > 0.3185085$
1	0	$r \cos \theta$	$v^2/\omega_p^2 = \frac{1}{\lambda^2-1}$	STABLE
1	1	$r^3 \cos \theta$	$v^2/\omega_p^2 = \frac{1}{4} \left[-\frac{1}{\lambda^2-1} + \frac{9}{\lambda^2-9} \right]$	STABLE
1	2	$r^5 \cos \theta$	$v^2/\omega_p^2 = \frac{1}{8} \left[-\frac{9}{\lambda^2-9} + \frac{25}{\lambda^2-25} \right]$	STABLE
1	3	$r^7 \cos \theta$	$v^2/\omega_p^2 = \frac{1}{64} \left[-\frac{1}{\lambda^2-1} + \frac{9}{\lambda^2-9} - \frac{125}{\lambda^2-25} + \frac{245}{\lambda^2-49} \right]$	Stable only for $v^2/\omega_p^2 > 0.0900023693$ or $v^2/\omega_p^2 > 0.2873514$
2	0	$r^2 \cos 2\theta$	$v^2/\omega_p^2 = \frac{1}{\lambda^2-4}$	STABLE
2	1	$r^4 \cos 2\theta$	$v^2/\omega_p^2 = \frac{2}{\lambda^2-16}$	STABLE
2	2	$r^6 \cos 2\theta$	$v^2/\omega_p^2 = \frac{1}{16} \left[-\frac{5}{\lambda^2-4} - \frac{8}{\lambda^2-16} + \frac{45}{\lambda^2-36} \right]$	Stable only for $v^2/\omega_p^2 > \frac{1}{32}$, or $v^2/\omega_p^2 > \frac{1}{33} = 0.1740711$
2	3	$r^8 \cos 2\theta$	$v^2/\omega_p^2 = \frac{1}{8} \left[\frac{1}{\lambda^2-4} - \frac{4}{\lambda^2-16} - \frac{9}{\lambda^2-36} + \frac{28}{\lambda^2-64} \right]$	Stable only for $v^2/\omega_p^2 > 0.0714200435$ or $v^2/\omega_p^2 > 0.2581814$
3	0	$r^3 \cos 3\theta$	$v^2/\omega_p^2 = \frac{1}{4} \left[\frac{1}{\lambda^2-1} + \frac{3}{\lambda^2-9} \right]$	STABLE
3	1	$r^5 \cos 3\theta$	$v^2/\omega_p^2 = \frac{1}{16} \left[-\frac{2}{\lambda^2-1} + \frac{9}{\lambda^2-9} + \frac{25}{\lambda^2-25} \right]$	STABLE
3	2	$r^7 \cos 3\theta$	$v^2/\omega_p^2 = \frac{1}{64} \left[\frac{1}{\lambda^2-1} - \frac{45}{\lambda^2-9} + \frac{25}{\lambda^2-25} + \frac{147}{\lambda^2-49} \right]$	Stable only for $v^2/\omega_p^2 > 0.050074896$ or $v^2/\omega_p^2 > 0.2183735$
4	0	$r^4 \cos 4\theta$	$v^2/\omega_p^2 = \frac{1}{2} \left[\frac{1}{\lambda^2-4} + \frac{1}{\lambda^2-16} \right]$	STABLE
4	1	$r^6 \cos 4\theta$	$v^2/\omega_p^2 = \frac{1}{8} \left[-\frac{1}{\lambda^2-4} + \frac{8}{\lambda^2-16} + \frac{9}{\lambda^2-36} \right]$	STABLE
4	2	$r^8 \cos 4\theta$	$v^2/\omega_p^2 = \frac{1}{8} \left[-\frac{1}{\lambda^2-4} - \frac{6}{\lambda^2-16} + \frac{9}{\lambda^2-36} + \frac{14}{\lambda^2-64} \right]$	Stable only for $v^2/\omega_p^2 > \frac{5}{256}$ or $v^2/\omega_p^2 > \frac{1}{261} = 0.1384071$
5	0	$r^5 \cos 5\theta$	$v^2/\omega_p^2 = \frac{1}{16} \left[\frac{2}{\lambda^2-1} + \frac{9}{\lambda^2-9} + \frac{5}{\lambda^2-25} \right]$	STABLE
5	1	$r^7 \cos 5\theta$	$v^2/\omega_p^2 = \frac{1}{64} \left[-\frac{5}{\lambda^2-1} + \frac{9}{\lambda^2-9} + \frac{75}{\lambda^2-25} + \frac{49}{\lambda^2-49} \right]$	STABLE

Work sheets, where $F(\cos^2 x)$ denotes

$${}_2F_1(a, b, c; \cos^2 x) \\ = {}_2F_1(-j, m+j, m+1; \cos^2 x)$$

in terms of the hypergeometric function.

Here, then,

$$F(z) = 1 + \frac{ab}{c} \frac{z}{1!} + \frac{ab}{c} \frac{(a+1)(b+1)}{(c+1)} \frac{z^2}{2!} + \dots$$

$$\cos^2 x = \frac{1}{2} [1 + \cos 2x]$$

$$\cos^4 x = \frac{1}{8} [3 + 4 \cos 2x + \cos 4x]$$

$$\cos^6 x = \frac{1}{32} [10 + 15 \cos 2x + 6 \cos 4x + \cos 6x]$$

$$\cos^8 x = \frac{1}{128} [35 + 56 \cos 2x + 28 \cos 4x + 8 \cos 6x + \cos 8x]$$

$$\cos^3 x = \frac{1}{4} [3 \cos x + \cos 3x]$$

$$\cos^5 x = \frac{1}{16} [10 \cos x + 5 \cos 3x + \cos 5x]$$

$$\cos^7 x = \frac{1}{64} [35 \cos x + 21 \cos 3x + 7 \cos 5x + \cos 7x]$$

We take $\int_0^{\infty} e^{i\lambda x} dx = \frac{i}{\lambda}$ & $\int_0^{\infty} e^{i\lambda x} \cos kx dx = \frac{i\lambda}{\lambda^2 - k^2}$

For the hypergeometric function $F(z) = {}_2F_1(a, b, c; z) = {}_2F_1(-j, m+j, m+1; z)$:

$F(0) = 1$, $\left. \frac{d}{dz} F \right|_{z=0} = \frac{ab}{c} = -\frac{j(m+j)}{m+1}$, and it should satisfy identically the second-order ordinary differential equation

$$z(1-z) \frac{d^2 F(z)}{dz^2} + (m+1)(1-z) \frac{dF(z)}{dz} + j(j+m)F = 0.$$

$$m = 0$$

$$j = 0$$

$$a = -j = \underline{0}$$

$$b = m + j = \underline{0}$$

$$c = m + j = \underline{0}$$

$$F(j) = 1$$

$$\cos^m \cdot F(\cos^2 \alpha) = 1$$

OMIT

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{d^j}{dx^j} = \text{Infinite}$$

$$m = 0$$

$$j = 1$$

$$a = -j = -1$$

$$b = m + j = 1$$

$$c = m + 1 = 1$$

$$F(s) = 1 - 2s$$

$$\begin{aligned} \cos^2 \alpha \cdot F(\cos^2 \alpha) &= 1 - \cos^2 \alpha \\ &= \frac{1}{2} - \frac{1}{2} \cos 2\alpha \\ &= \frac{1}{2} [1 - \cos 2\alpha] \end{aligned}$$

$$\begin{aligned} -\frac{2s^2}{\omega_f^2} &= -2\lambda \int_0^{\infty} \frac{1}{2} [1 - \cos 2\alpha] e^{i\lambda t} dt \\ &= -\frac{2\lambda}{2} \left[\frac{t}{\lambda} - \frac{t \lambda}{\lambda^2 - 4} \right] = \frac{1}{2} \left[1 - \frac{\lambda^2}{\lambda^2 - 4} \right] = -\frac{2}{\lambda^2 - 4} \end{aligned}$$

$$\frac{\lambda^2}{\omega_f^2} = -\frac{2}{\lambda^2 - 4}$$

ONE POSITIVE ROOT FOR λ^2

FOR ANY POSITIVE λ^2 / ω_f^2 . HENCE STABLE.

$$\delta_{j,c} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{\lambda^2}{\omega_f^2} = -1 \frac{\lambda^2}{\omega_f^2}$$

$$m = 0$$

$$j = 2$$

$$a = -j = -2$$

$$b = m + j = 2$$

$$c = m + j = 1$$

$$F(s) = 1 - 4s + 3s^2$$

$$\begin{aligned} \cos^m s \cdot F(\cos^2 s) &= 1 - 4 \cos^2 s + 3 \cos^4 s \\ &= \frac{1}{8} - \frac{1}{2} \cos 2s + \frac{3}{8} \cos 4s \\ &= \frac{1}{8} [1 - 4 \cos 2s + 3 \cos 4s] \end{aligned}$$

$$\begin{aligned} 2 \frac{v^2}{\omega_p^2} &= -i\lambda \int_0^\infty \frac{1}{8} [1 - 4 \cos 2u + 3 \cos 4u] e^{i\lambda u} du \\ &= -\frac{i\lambda}{8} \left[\frac{1}{\lambda} - 4 \frac{i\lambda}{\lambda^2 - 4} + 3 \frac{i\lambda}{\lambda^2 - 16} \right] = \frac{1}{8} \left[1 - 4 \frac{\lambda^2}{\lambda^2 - 4} + 3 \frac{\lambda^2}{\lambda^2 - 16} \right] = -\frac{2}{\lambda^2 - 4} + \frac{6}{\lambda^2 - 16} \\ \frac{v^2}{\omega_p^2} &= -\frac{1}{\lambda^2 - 4} + \frac{3}{\lambda^2 - 16} \end{aligned}$$

FOR STABILITY, REQUIRE $\frac{v^2}{\omega_p^2} > \frac{1}{16}$, or $\frac{v}{v_0} > \frac{1}{\sqrt{16}} \approx 0.25$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = 9 + 2 \frac{v^2}{\omega_p^2}$$

$$m = 0 \qquad j = 3 \qquad a = -j = \underline{-3} \qquad b = m+j = \underline{3} \qquad r = m+1 = \underline{1}$$

$$F(s) = 1 - 9s^2 + 18s^3 - 10s^3$$

$$\begin{aligned} \cos t \cdot F(\cos^2 t) &= 1 - 9 \cos^2 t + 18 \cos^4 t - 10 \cos^6 t \\ &= \frac{1}{16} - \frac{3}{16} \cos 2t + \frac{3}{8} \cos 4t - \frac{5}{16} \cos 6t \\ &= \frac{1}{16} [2 - 3 \cos 2t + 6 \cos 4t - 5 \cos 6t] \end{aligned}$$

$$\begin{aligned} -3 \frac{d^2}{dt^2} &= -s \int_{-\infty}^{\infty} \int \frac{1}{16} [2 - 3 \cos 2t + 6 \cos 4t - 5 \cos 6t] e^{i\lambda t} dt \\ &= -\frac{d^2}{dt^2} \left[2 \frac{1}{\lambda} - 3 \frac{1}{\lambda^2-4} + 6 \frac{1}{\lambda^2-16} - 5 \frac{1}{\lambda^2-36} \right] = \frac{1}{16} \left[2 - 3 \frac{\lambda^2}{\lambda^2-4} + 6 \frac{\lambda^2}{\lambda^2-16} - 5 \frac{\lambda^2}{\lambda^2-36} \right] \\ &= \frac{d^2}{dt^2} = \frac{1}{16} \left[\frac{1}{\lambda^2-4} - \frac{5}{\lambda^2-16} + \frac{15}{\lambda^2-36} \right] \end{aligned}$$

3 stable roots for positive λ^2 only
for $\omega_p^2 > 0.17495534$, or $2/\omega_p > 0.3858759$

$$d_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \omega_p^2 = -3 \frac{d^2}{dt^2}$$

$$m = 0 \qquad j = 4 \qquad a = -j = -4 \qquad b = m+j = 4 \qquad c = m+j = 4$$

$$F(z) = 1 - 16z + 60z^2 - 80z^3 + 35z^4$$

$$\cos^m \lambda \cdot F(\cos^2 \lambda) = 1 - 16 \cos^4 \lambda + 60 \cos^4 \lambda - 80 \cos^6 \lambda + 35 \cos^8 \lambda$$

$$= \frac{9}{128} - \frac{3}{16} \cos 2\lambda + \frac{5}{32} \cos 4\lambda - \frac{5}{16} \cos 6\lambda + \frac{35}{128} \cos 8\lambda$$

$$= \frac{1}{128} [9 - 24 \cos 2\lambda + 20 \cos 4\lambda - 40 \cos 6\lambda + 35 \cos 8\lambda]$$

$$4 \frac{v^2}{\omega_p^2} = -i\lambda \int_{-\infty}^{\infty} \frac{1}{128} [9 - 24 \cos 2\lambda + 20 \cos 4\lambda - 40 \cos 6\lambda + 35 \cos 8\lambda] e^{i\lambda s} ds$$

$$= -\frac{i\lambda}{128} \left[9 \frac{i\lambda}{\lambda^2-4} + 20 \frac{i\lambda}{\lambda^2-16} - 40 \frac{i\lambda}{\lambda^2-36} + 35 \frac{i\lambda}{\lambda^2-64} \right] = \frac{1}{128} \left[9 - 24 \frac{\lambda^2}{\lambda^2-4} + 20 \frac{\lambda^2}{\lambda^2-16} - 40 \frac{\lambda^2}{\lambda^2-36} + 35 \frac{\lambda^2}{\lambda^2-64} \right]$$

$$= \frac{1}{16} \left[-\frac{3}{\lambda^2-4} + \frac{10}{\lambda^2-16} - \frac{45}{\lambda^2-36} + \frac{70}{\lambda^2-64} \right] \quad \text{not}$$

Four stable roots for positive λ^2 only

For $v^2/\omega_p^2 > 0.188790594$, $\lambda^2/\omega_p^2 > 0.3985085$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = +i\lambda \frac{v^2}{\omega_p^2}$$

$$m = 1$$

$$j = 0$$

$$a = -j = 0$$

$$b = m + j = 1$$

$$c = m + 1 = 2$$

$$F(s) = 1$$

$$\cos^{-1} F(s) = \cos^{-1} 1$$

$$1 + \frac{s^2}{\omega_f^2} = -s \int_0^{\infty} \cos u e^{-su} du$$

$$= -s \left[\frac{s^2}{s^2 - 1} \right] = \frac{s^2}{s^2 - 1} = 1 + \frac{1}{s^2 - 1}$$

$$\frac{s^2}{\omega_f^2} = \frac{1}{s^2 - 1}$$

ONE POSITIVE ROOT FOR s^2 .
FOR ANY POSITIVE ω_f^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{s^2}{\omega_f^2} = 1 + \frac{s^2}{\omega_f^2}$$

$$m = 1$$

$$j = 1$$

$$a = -j = -1$$

$$b = m + j = 2$$

$$c = m + j = 2$$

$$F(s) = 1 - s$$

$$\cos^m s \cdot F(\cos^2 s) = \cos s - \cos^3 s = +\frac{1}{4} \cos s - \frac{1}{4} \cos 3s = \frac{1}{4} [\cos s - \cos 3s]$$

$$-\frac{v^2}{\omega_p^2} = -i\lambda \int_0^{\infty} \frac{1}{4} [\cos t - \cos 3t] e^{i\lambda t} dt$$

$$= -\frac{i\lambda}{4} \left[\frac{1}{\lambda^2 - 1} - \frac{i\lambda}{\lambda^2 - 9} \right] = \frac{1}{4} \left[\frac{1}{\lambda^2 - 1} - \frac{9}{\lambda^2 - 9} \right]$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{4} \left[-\frac{1}{\lambda^2 - 1} + \frac{9}{\lambda^2 - 9} \right]$$

TWO POSITIVE ROOTS FOR λ^2
FOR ANY POSITIVE v^2/ω_p^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = 2 - \frac{v^2}{\omega_p^2}$$

$$a = -j = \underline{-2} \quad b = m+j = \underline{3} \quad c = m+1 = \underline{2}$$

$$j = 2$$

$$m = 1$$

$$F(s) = 1 - 3s + 2s^2$$

$$\cos^2 \lambda \cdot F(\cos^2 \lambda) = \cos^2 \lambda - 3 \cos^4 \lambda + 2 \cos^6 \lambda = \frac{1}{8} [-\cos 3\lambda + \cos 5\lambda]$$

$$\begin{aligned} \frac{v^2}{\omega_f^2} &= -i\lambda \int_0^{\infty} \frac{1}{s} [-\cos 3\lambda + \cos 5\lambda] e^{-s\lambda} ds \\ &= -\frac{i\lambda}{s} \left[-\frac{e^{-s\lambda}}{\lambda^2-9} + \frac{e^{-s\lambda}}{\lambda^2-25} \right] = \frac{1}{8} \left[-\frac{\lambda^2}{\lambda^2-9} + \frac{\lambda^2}{\lambda^2-25} \right] = \frac{1}{8} \left[-\frac{9}{\lambda^2-9} + \frac{25}{\lambda^2-25} \right] \end{aligned}$$

$$\frac{v^2}{\omega_f^2} = \frac{1}{8} \left[-\frac{9}{\lambda^2-9} + \frac{25}{\lambda^2-25} \right]$$

TWO POSITIVE ROOTS FOR λ^2 FOR ANY POSITIVE v^2/ω_f^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)! \omega_f^2} \frac{v^2}{\omega_f^2} = \frac{v^2}{\omega_f^2}$$

$$m = 1 \qquad j = 3 \qquad a = -j = -3 \qquad b = m+j = 4 \qquad c = m+j = 4$$

$$F(s) = 1 - 6s + 10s^2 - 5s^3$$

$$\cos^m \cdot F(\cos^2 s) = \cos s - 6 \cos^3 s + 10 \cos^5 s - 5 \cos^7 s = \frac{1}{64} [\cos s - \cos 3s + 5 \cos 5s - 5 \cos 7s]$$

$$-\frac{v^2}{\omega_f} = -i\lambda \int_0^{\infty} \frac{1}{64} [\cos s - \cos 3s + 5 \cos 5s - 5 \cos 7s] e^{i\lambda s} ds$$

$$= -\frac{i\lambda}{64} \left[\frac{i\lambda}{\lambda^2-1} - \frac{i\lambda}{\lambda^2-9} + 5 \frac{i\lambda}{\lambda^2-25} - 5 \frac{i\lambda}{\lambda^2-49} \right]$$

$$= \frac{1}{64} \left[\frac{\lambda^2}{\lambda^2-1} - \frac{\lambda^2}{\lambda^2-9} + 5 \frac{\lambda^2}{\lambda^2-25} - 5 \frac{\lambda^2}{\lambda^2-49} \right] = \frac{1}{64} \left[\frac{1}{\lambda^2-1} - \frac{9}{\lambda^2-9} + \frac{125}{\lambda^2-25} - \frac{245}{\lambda^2-49} \right]$$

$$\frac{v^2}{\omega_f} = \frac{1}{64} \left[-\frac{1}{\lambda^2-1} + \frac{9}{\lambda^2-9} - \frac{125}{\lambda^2-25} + \frac{245}{\lambda^2-49} \right]$$

Four stable roots for positive λ^2 only
 For $v^3/\omega_f^2 > 0.0900023693$, or $v/\omega_0 > 0.2873514$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_f^2} = -\frac{v^2}{\omega_f^2}$$

$$m = 2$$

$$j = 0$$

$$a = -j = 0$$

$$b = m + j = 2$$

$$c = m + j = 3$$

$$F(s) = 1$$

$$\cos^m \cdot F(\cos^2 s) = \cos^2 s = \frac{1}{2} [1 + \cos 2s]$$

$$1 + 2 \frac{s^2}{\omega_p^2} = -i\lambda \int_0^{\infty} \frac{1}{2} [1 + \cos 2s] e^{i\lambda s} ds$$

$$= -\frac{i\lambda}{2} \left[\frac{s}{\lambda} + \frac{s^2}{\lambda^2 - 4} \right] = \frac{1}{2} \left[1 + \frac{\lambda^2}{\lambda^2 - 4} \right] = 1 + \frac{2}{\lambda^2 - 4}$$

$$\frac{s^2}{\omega_p^2} = \frac{1}{\lambda^2 - 4}$$

ONE POSITIVE ROOT FOR λ^2

FOR ANY POSITIVE s^2/ω_p^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{s^2}{\omega_p^2} = 1 + 2 \frac{s^2}{\omega_p^2}$$

$m = 2$	$j = 1$	$a = -j = \underline{-1}$
		$b = m + j = \underline{3}$
		$c = m + j = \underline{3}$

$$F(s) = 1 - s$$

$$\cos^2 s \cdot F(\cos^2 s) = \cos^2 s - \cos^4 s = \frac{1}{8} [1 - \cos 4s]$$

$$-\frac{s^2}{\omega_p^2} = -i\lambda \int_0^{\infty} \frac{1}{s} [1 - \cos 4s] e^{i\lambda s} ds$$

$$= -\frac{i\lambda}{8} \left[\frac{s}{\lambda} - \frac{s\lambda}{\lambda^2 - 16} \right] = \frac{1}{8} \left[1 - \frac{\lambda^2}{\lambda^2 - 16} \right] = -\frac{2}{\lambda^2 - 16}$$

$$\frac{s^2}{\omega_p^2} = \frac{2}{\lambda^2 - 16}$$

ONE POSITIVE ROOT FOR λ^2
FOR ANY POSITIVE s^2/ω_p^2 . HENCE STABLE

$$\delta_{j_0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{s^2}{\omega_p^2} = \frac{s^2}{\omega_p^2}$$

$$m = 2 \qquad j = 2 \qquad a = -j = \underline{-2} \qquad b = m+j = \underline{4} \qquad c = m-j = \underline{3}$$

$$F(s) = 1 - \frac{8}{3}s + \frac{5}{3}s^2$$

$$\cos a \cdot F(\cos^2 a) = \cos^2 a - \frac{8}{3} \cos^4 a + \frac{5}{3} \cos^6 a = \frac{1}{48} - \frac{5}{96} \cos 2a - \frac{1}{48} \cos 4a + \frac{5}{96} \cos 6a$$

$$= \frac{1}{96} [2 - 5 \cos 2a - 2 \cos 4a + 5 \cos 6a]$$

$$\frac{2}{3} \frac{v^2}{\omega_p^2} = -i\lambda \int_{96}^{\infty} [2 - 5 \cos 2a - 2 \cos 4a + 5 \cos 6a] e^{i\lambda a} da$$

$$= -\frac{i\lambda}{96} \left[\frac{2i}{\lambda} - 5 \frac{i\lambda}{\lambda^2-4} - 2 \frac{i\lambda}{\lambda^2-16} + 5 \frac{i\lambda}{\lambda^2-36} \right] = \frac{1}{96} \left[2 - 5 \frac{\lambda^2}{\lambda^2-4} - 2 \frac{\lambda^2}{\lambda^2-16} + 5 \frac{\lambda^2}{\lambda^2-36} \right]$$

$$= \frac{1}{96} \left[-\frac{20}{\lambda^2-4} - \frac{32}{\lambda^2-16} + \frac{180}{\lambda^2-36} \right] = \frac{1}{24} \left[-\frac{5}{\lambda^2-4} - \frac{8}{\lambda^2-16} + \frac{45}{\lambda^2-36} \right]$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{16} \left[-\frac{5}{\lambda^2-4} - \frac{8}{\lambda^2-16} + \frac{45}{\lambda^2-36} \right]$$

FOR STABILITY REQUIRE $\frac{v^2}{\omega_p^2} > \frac{1}{32}$ or $v/v_0 > \frac{1}{\sqrt{33}} \approx 0.174077$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = \frac{2}{3} \frac{v^2}{\omega_p^2}$$

$$m = 2$$

$$j = 3$$

$$a = -j = \underline{-3}$$

$$b = m + j = \underline{5}$$

$$c = m + 1 = \underline{3}$$

$$F(z) = 1 - 5z + \frac{15}{2}z^2 - \frac{7}{2}z^3$$

$$\begin{aligned} \cos^m z \cdot F(\cos^2 z) &= \cos^2 z - 5 \cos^4 z + \frac{15}{2} \cos^6 z - \frac{7}{2} \cos^8 z \\ &= \frac{3}{256} - \frac{1}{64} \cos 2z + \frac{1}{64} \cos 4z + \frac{1}{64} \cos 6z - \frac{7}{256} \cos 8z \\ &= \frac{1}{256} [3 - 4 \cos 2z + 4 \cos 4z + 4 \cos 6z - 7 \cos 8z] \end{aligned}$$

$$\begin{aligned} -\frac{1}{2} \frac{v^2}{\omega_p^2} &= -i\lambda \int_0^\infty \frac{1}{256} [3 - 4 \cos 2z + 4 \cos 4z + 4 \cos 6z - 7 \cos 8z] e^{i\lambda z} dz \\ &= -\frac{i\lambda}{256} \left[3 \frac{i\lambda}{\lambda} - 4 \frac{i\lambda}{\lambda^2 - 4} + 4 \frac{i\lambda}{\lambda^2 - 16} + 4 \frac{i\lambda}{\lambda^2 - 36} - 7 \frac{i\lambda}{\lambda^2 - 64} \right] \\ &= \frac{1}{256} \left[3 - 4 \frac{\lambda^2}{\lambda^2 - 4} + 4 \frac{\lambda^2}{\lambda^2 - 16} + 4 \frac{\lambda^2}{\lambda^2 - 36} - 7 \frac{\lambda^2}{\lambda^2 - 64} \right] \\ &= \frac{1}{256} \left[-\frac{16}{\lambda^2 - 4} + \frac{64}{\lambda^2 - 16} + \frac{144}{\lambda^2 - 36} - \frac{448}{\lambda^2 - 64} \right] = \frac{1}{16} \left[-\frac{1}{\lambda^2 - 4} + \frac{4}{\lambda^2 - 16} + \frac{9}{\lambda^2 - 36} - \frac{28}{\lambda^2 - 64} \right] \end{aligned}$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{8} \left[\frac{1}{\lambda^2 - 4} - \frac{4}{\lambda^2 - 16} - \frac{9}{\lambda^2 - 36} + \frac{28}{\lambda^2 - 64} \right]$$

4 Stable roots for positive λ^2 only

For $\frac{v^2}{\omega_p^2} > 0.0714200435$, or $\frac{v}{v_0} > 0.2581845$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = \frac{1}{2} \frac{v^2}{\omega_p^2}$$

$$m = 3$$

$$j = 0$$

$$a = -j = 0$$

$$b = m + j = 3$$

$$c = m + j = 4$$

$$F(z) = 1$$

$$\begin{aligned} \cos^m \cdot F(\cos^2 z) &= \cos^3 z \\ &= \frac{1}{4} [3 \cos z + \cos 3z] \end{aligned}$$

$$\begin{aligned} 1 + 3 \frac{v^2}{\omega_p^2} &= -i\lambda \int_0^{\infty} \frac{1}{4} [3 \cos z + \cos 3z] e^{i\lambda z} dz \\ &= -\frac{i\lambda}{4} \left[3 \frac{i\lambda}{\lambda^2 - 1} + \frac{i\lambda}{\lambda^2 - 9} \right] = \frac{1}{4} \left[3 \frac{\lambda^2}{\lambda^2 - 1} + \frac{\lambda^2}{\lambda^2 - 9} \right] \\ &= 1 + \frac{3}{4} \left[\frac{1}{\lambda^2 - 1} + \frac{9}{\lambda^2 - 9} \right] \end{aligned}$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{4} \left[\frac{1}{\lambda^2 - 1} + \frac{3}{\lambda^2 - 9} \right]$$

TWO POSITIVE ROOTS FOR λ^2

FOR ANY POSITIVE v^2/ω_p^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = 1 + 3 \frac{v^2}{\omega_p^2}$$

$$m = 3$$

$$j = 1$$

$$a = -j = -1$$

$$b = m + j = 4$$

$$c = m + j = 4$$

$$F(s) = 1 - z$$

$$\cos^m \alpha \cdot F(\cos^2 \alpha) = \cos^3 \alpha - \cos^5 \alpha$$

$$= \frac{1}{16} [2 \cos \alpha - \cos 3\alpha - \cos 5\alpha]$$

$$-\frac{v^2}{\omega_p^2} = -i\lambda \int_0^{\infty} \frac{1}{16} [2 \cos \alpha - \cos 3\alpha - \cos 5\alpha] e^{i\lambda \alpha} d\alpha$$

$$= -\frac{i\lambda}{16} \left[2 \frac{i\lambda}{\lambda^2 - 1} - \frac{i\lambda}{\lambda^2 - 9} - \frac{i\lambda}{\lambda^2 - 25} \right]$$

$$= \frac{1}{16} \left[2 \frac{\lambda^2}{\lambda^2 - 1} - \frac{\lambda^2}{\lambda^2 - 9} - \frac{\lambda^2}{\lambda^2 - 25} \right] = \frac{1}{16} \left[\frac{2}{\lambda^2 - 1} - \frac{9}{\lambda^2 - 9} - \frac{25}{\lambda^2 - 25} \right]$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{16} \left[-\frac{2}{\lambda^2 - 1} + \frac{9}{\lambda^2 - 9} + \frac{25}{\lambda^2 - 25} \right] \quad \text{Plot } \dots$$

3 POSITIVE ROOTS FOR λ^2
FOR ANY POSITIVE v^2/ω_p^2 . HENCE STABLE

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = -\frac{v^2}{\omega_p^2}$$

$$m = 3$$

$$j = 2$$

$$a = -j = -2$$

$$b = m+j = 5$$

$$c = m+j = 4$$

$$F(s) = 1 - \frac{5}{2}s + \frac{3}{2}s^2$$

$$\cos^n \cdot F(\cos^2 \lambda) = \cos^3 \lambda - \frac{5}{2} \cos^5 \lambda + \frac{3}{2} \cos^7 \lambda$$

$$= \frac{1}{128} [\cos \lambda - 5 \cos 3\lambda + \cos 5\lambda + 3 \cos 7\lambda]$$

$$\frac{1}{2} \frac{v^2}{\omega_p^2} = -i\lambda \int_0^{\infty} \frac{1}{128} [\cos \lambda - 5 \cos 3\lambda + \cos 5\lambda + 3 \cos 7\lambda] e^{i\lambda t} dt$$

$$= -\frac{i\lambda}{128} \left[\frac{i\lambda}{\lambda^2-1} - 5 \frac{i\lambda}{\lambda^2-9} + \frac{i\lambda}{\lambda^2-25} + 3 \frac{i\lambda}{\lambda^2-49} \right] = \frac{1}{128} \left[\frac{\lambda^2}{\lambda^2-1} - 5 \frac{\lambda^2}{\lambda^2-9} + \frac{\lambda^2}{\lambda^2-25} + 3 \frac{\lambda^2}{\lambda^2-49} \right]$$

$$= \frac{1}{128} \left[\frac{1}{\lambda^2-1} - \frac{45}{\lambda^2-9} + \frac{25}{\lambda^2-25} + \frac{147}{\lambda^2-49} \right]$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{64} \left[\frac{1}{\lambda^2-1} - \frac{45}{\lambda^2-9} + \frac{25}{\lambda^2-25} + \frac{147}{\lambda^2-49} \right]$$

4 stable roots for positive λ^2 only

for $v^2/\omega_p^2 > 0.0500748996$, or $v/v_0 > 0.2183735$

$$\delta_{j_0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = \frac{1}{2} \frac{v^2}{\omega_p^2}$$

$$m = A$$

$$j = 0$$

$$a = -j = \underline{0}$$

$$b = m + j = \underline{4}$$

$$c = m + 1 = \underline{5}$$

$$F(s) = 1$$

$$\omega_p^m F(\omega_p^2 s) = \cos^4 s = \frac{1}{8} [3 + 4 \cos 2s + \cos 4s]$$

$$1 + 4 \frac{s^2}{\omega_p^2} = -17 \int_0^{\infty} \frac{1}{8} [3 + 4 \cos 2s + \cos 4s] e^{i\lambda s} ds$$

$$= -\frac{i\lambda}{8} \left[3 \frac{2}{\lambda} + 4 \frac{i\lambda}{\lambda^2 - 4} + \frac{i\lambda}{\lambda^2 - 16} \right] = \frac{1}{8} \left[3 + 4 \frac{\lambda^2}{\lambda^2 - 4} + \frac{\lambda^2}{\lambda^2 - 16} \right]$$

$$= 1 + 2 \left[\frac{1}{\lambda^2 - 4} + \frac{1}{\lambda^2 - 16} \right]$$

$$\frac{s^2}{\omega_p^2} = \frac{1}{2} \left[\frac{1}{\lambda^2 - 4} + \frac{1}{\lambda^2 - 16} \right]$$

TWO POSITIVE ROOTS FOR λ^2
FOR ANY POSITIVE s^2/ω_p^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{s^2}{\omega_p^2} = 1 + 4 \frac{s^2}{\omega_p^2}$$

$$m = 4$$

$$j = 2$$

$$a = -j = \underline{-2}$$

$$b = m + j = \underline{6}$$

$$c = m + 1 = \underline{5}$$

$$F(z) = 1 - \frac{12}{5}z + \frac{7}{5}z^2$$

$$\cos^m \lambda \cdot F(\cos^2 \lambda) = \cos^4 \lambda - \frac{12}{5} \cos^6 \lambda + \frac{7}{5} \cos^8 \lambda = \frac{1}{640} [5 - 8 \cos 2\lambda - 12 \cos 4\lambda + 8 \cos 6\lambda + 7 \cos 8\lambda]$$

$$\frac{2}{5} \frac{v^2}{\omega_p^2} = -i\lambda \int_0^\infty \frac{1}{640} [5 - 8 \cos 2\lambda - 12 \cos 4\lambda + 8 \cos 6\lambda + 7 \cos 8\lambda] e^{i\lambda u} du$$

$$= -\frac{i\lambda}{640} \left[5 \frac{i}{\lambda} - 8 \frac{i\lambda}{\lambda^2 - 4} - 12 \frac{i\lambda}{\lambda^2 - 16} + 8 \frac{i\lambda}{\lambda^2 - 36} + 7 \frac{i\lambda}{\lambda^2 - 64} \right]$$

$$= \frac{1}{640} \left[5 - 8 \frac{\lambda^2}{\lambda^2 - 4} - 12 \frac{\lambda^2}{\lambda^2 - 16} + 8 \frac{\lambda^2}{\lambda^2 - 36} + 7 \frac{\lambda^2}{\lambda^2 - 64} \right] = \frac{1}{640} \left[-\frac{32}{\lambda^2 - 4} - \frac{192}{\lambda^2 - 16} + \frac{288}{\lambda^2 - 36} + \frac{448}{\lambda^2 - 64} \right]$$

$$= \frac{1}{20} \left[-\frac{1}{\lambda^2 - 4} - \frac{6}{\lambda^2 - 16} + \frac{9}{\lambda^2 - 36} + \frac{14}{\lambda^2 - 64} \right]$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{8} \left[-\frac{1}{\lambda^2 - 4} - \frac{6}{\lambda^2 - 16} + \frac{9}{\lambda^2 - 36} + \frac{14}{\lambda^2 - 64} \right] \quad \text{Plot.}$$

4 Stable roots for positive λ^2 only

$$\text{for } v^2/\omega_p^2 > \frac{5}{256}, \quad \text{or } v/v_0 > \sqrt{\frac{5}{256}} = 0.1384091$$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = \frac{2}{5} \frac{v^2}{\omega_p^2}$$

$$m = 4$$

$$j = 1$$

$$a = -j = -1$$

$$b = m + j = 5$$

$$c = m + 1 = 5$$

$$F(s) = 1 - 2$$

$$\cos^2 \cdot F(\cos^2 s) = \cos^4 s - \cos^6 s = \frac{1}{32} [2 + \cos 2s - 2 \cos 4s - \cos 6s]$$

$$- \frac{2^2}{\omega_T} = -i\lambda \int_0^{\infty} \frac{1}{32} [2 + \cos 2s - 2 \cos 4s - \cos 6s] e^{s\lambda} ds$$

$$= - \frac{i\lambda}{32} \left[2 \frac{1}{\lambda} + \frac{i\lambda}{\lambda^2 - 4} - 2 \frac{i\lambda}{\lambda^2 - 16} - \frac{12}{\lambda^2 - 36} \right]$$

$$= \frac{1}{32} \left[2 + \frac{\lambda^2}{\lambda^2 - 4} - 2 \frac{\lambda^2}{\lambda^2 - 16} - \frac{\lambda^2}{\lambda^2 - 36} \right] = \frac{1}{32} \left[\frac{4}{\lambda^2 - 4} - \frac{32}{\lambda^2 - 16} - \frac{36}{\lambda^2 - 36} \right]$$

$$= \frac{1}{8} \left[\frac{1}{\lambda^2 - 4} - \frac{8}{\lambda^2 - 16} - \frac{9}{\lambda^2 - 36} \right]$$

$$\frac{1^2}{\omega_T^2} = \frac{1}{8} \left[-\frac{1}{\lambda^2 - 4} + \frac{8}{\lambda^2 - 16} + \frac{9}{\lambda^2 - 36} \right]$$

THESE POSITIVE ROOTS ARE

THE ONLY POSITIVE ROOTS FROM STABILITY

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{2^2}{\omega_T^2} = - \frac{2^2}{\omega_T^2}$$

$$m = 5 \quad j = 0$$

$$a = -j = 0 \quad b = m + j = 5$$

$$c = m + 1 = 6$$

$$F(\lambda) = 1.$$

$$\cos^m \lambda \cdot F(\cos^2 \lambda) = \cos^5 \lambda = \frac{1}{16} [10 \cos^4 + 5 \cos^2 + 1]$$

$$1 + 5 \frac{v^2}{\omega_p^2} = -i\lambda \int_0^\infty \frac{1}{16} [10 \cos^4 + 5 \cos^2 + 1] e^{i\lambda x} dx$$

$$= -\frac{i\lambda}{16} \left[10 \frac{e^{i\lambda}}{\lambda^2 - 9} + 5 \frac{e^{i\lambda}}{\lambda^2 - 25} \right] = \frac{1}{16} \left[10 \frac{\lambda^2}{\lambda^2 - 9} + 5 \frac{\lambda^2}{\lambda^2 - 25} \right] = 1 + \frac{1}{16} \left[\frac{10}{\lambda^2 - 9} + \frac{45}{\lambda^2 - 25} \right]$$

$$= 1 + \frac{5}{16} \left[\frac{2}{\lambda^2 - 9} + \frac{5}{\lambda^2 - 25} \right]$$

$$\frac{v^2}{\omega_p^2} = \frac{1}{16} \left[\frac{2}{\lambda^2 - 9} + \frac{9}{\lambda^2 - 9} + \frac{5}{\lambda^2 - 25} \right]$$

THREE POSITIVE ROOTS FOR λ^2
FOR ANY POSITIVE v^2/ω_p^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{v^2}{\omega_p^2} = 1 + 5 \frac{v^2}{\omega_p^2}$$

$$m = 5$$

$$j = 1$$

$$a = -j = -1$$

$$b = m + j = 6$$

$$c = m + 1 = 6$$

$$F(s) = 1 - z$$

$$\cos^m \lambda \cdot F(\cos^2 \lambda) = \cos^5 \lambda - \cos^7 \lambda = \frac{1}{64} [5 \cos \lambda - \cos 3\lambda - 3 \cos 5\lambda - \cos 7\lambda]$$

$$\begin{aligned}
 -\frac{z^2}{\omega_p^2} &= -i\lambda \int_0^{\infty} \frac{1}{64} [5 \cos \lambda - \cos 3\lambda - 3 \cos 5\lambda - \cos 7\lambda] e^{i\lambda t} dt \\
 &= -\frac{i\lambda}{64} \left[5 \frac{i\lambda}{\lambda^2 - 1} - \frac{i\lambda}{\lambda^2 - 9} - 3 \frac{i\lambda}{\lambda^2 - 25} - \frac{i\lambda}{\lambda^2 - 49} \right] = \frac{1}{64} \left[5 \frac{\lambda^2}{\lambda^2 - 1} - \frac{\lambda^2}{\lambda^2 - 9} - 3 \frac{\lambda^2}{\lambda^2 - 25} - \frac{\lambda^2}{\lambda^2 - 49} \right] \\
 &= \frac{1}{64} \left[\frac{5}{\lambda^2 - 1} - \frac{9}{\lambda^2 - 9} - \frac{75}{\lambda^2 - 25} - \frac{49}{\lambda^2 - 49} \right]
 \end{aligned}$$

$$\frac{z^2}{\omega_p^2} = \frac{1}{64} \left[-\frac{5}{\lambda^2 - 1} + \frac{9}{\lambda^2 - 9} + \frac{75}{\lambda^2 - 25} + \frac{49}{\lambda^2 - 49} \right]$$

4 POSITIVE ROOTS FOR λ^2

FOR ANY POSITIVE ω_p^2 / ω_p^2 . HENCE STABLE.

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{z^j}{\omega_p^2} = -\frac{z^2}{\omega_p^2}$$

$$m =$$

$$j =$$

$$a = -j =$$

$$b = m + j =$$

$$c = m + j =$$

$$F(s) =$$

$$\cos^m \cdot F(\cos^2 s) =$$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{s^2}{\omega_p^2} =$$

$$m =$$

$$j =$$

$$a = -j =$$

$$b = m + j =$$

$$c = m + j =$$

$$F(j) =$$

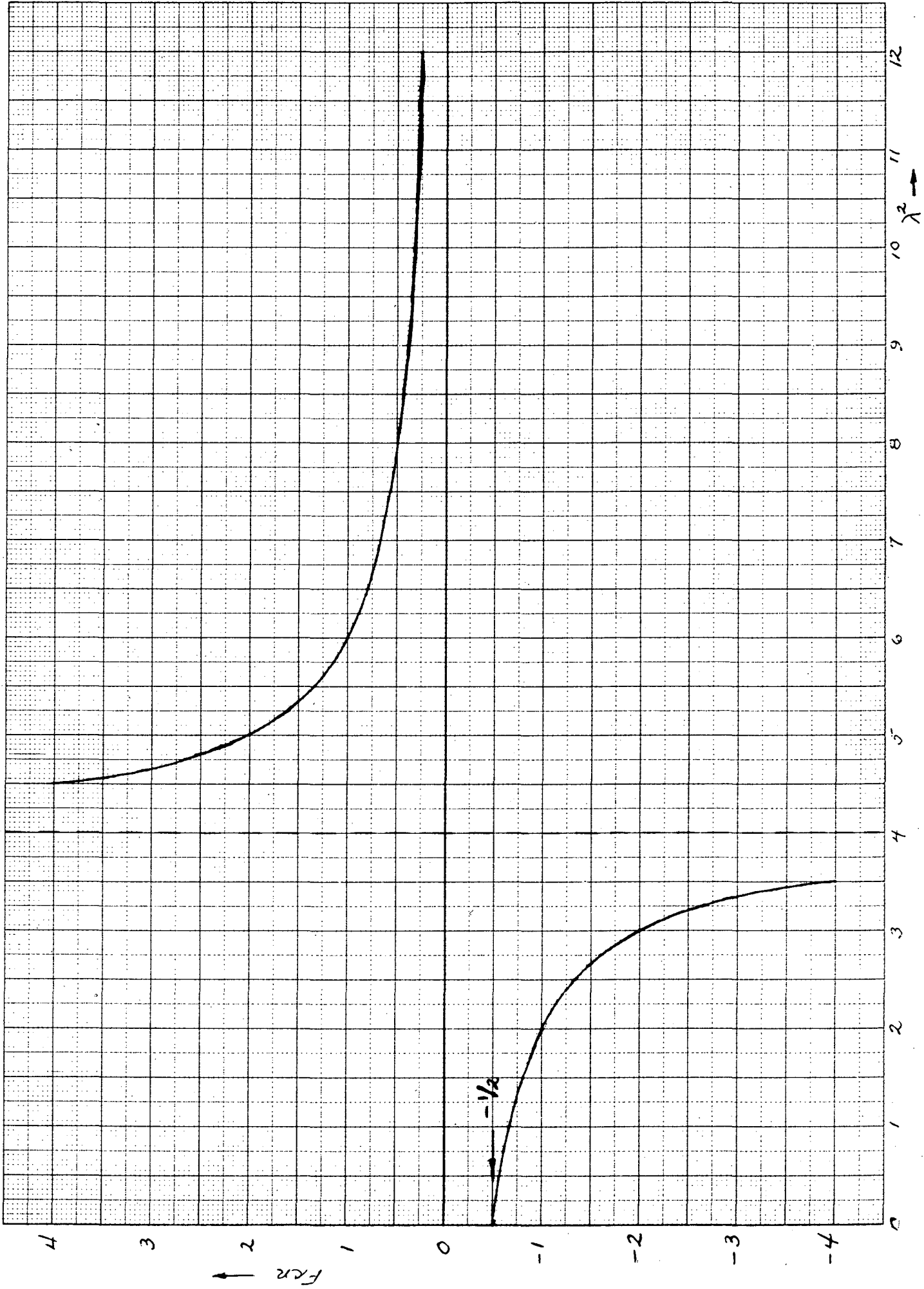
$$\cos^m \cdot F(\cos^2) =$$

$$\delta_{j,0} + \frac{(-1)^j m! j!}{(m+j-1)!} \frac{2^j}{\omega^2} =$$

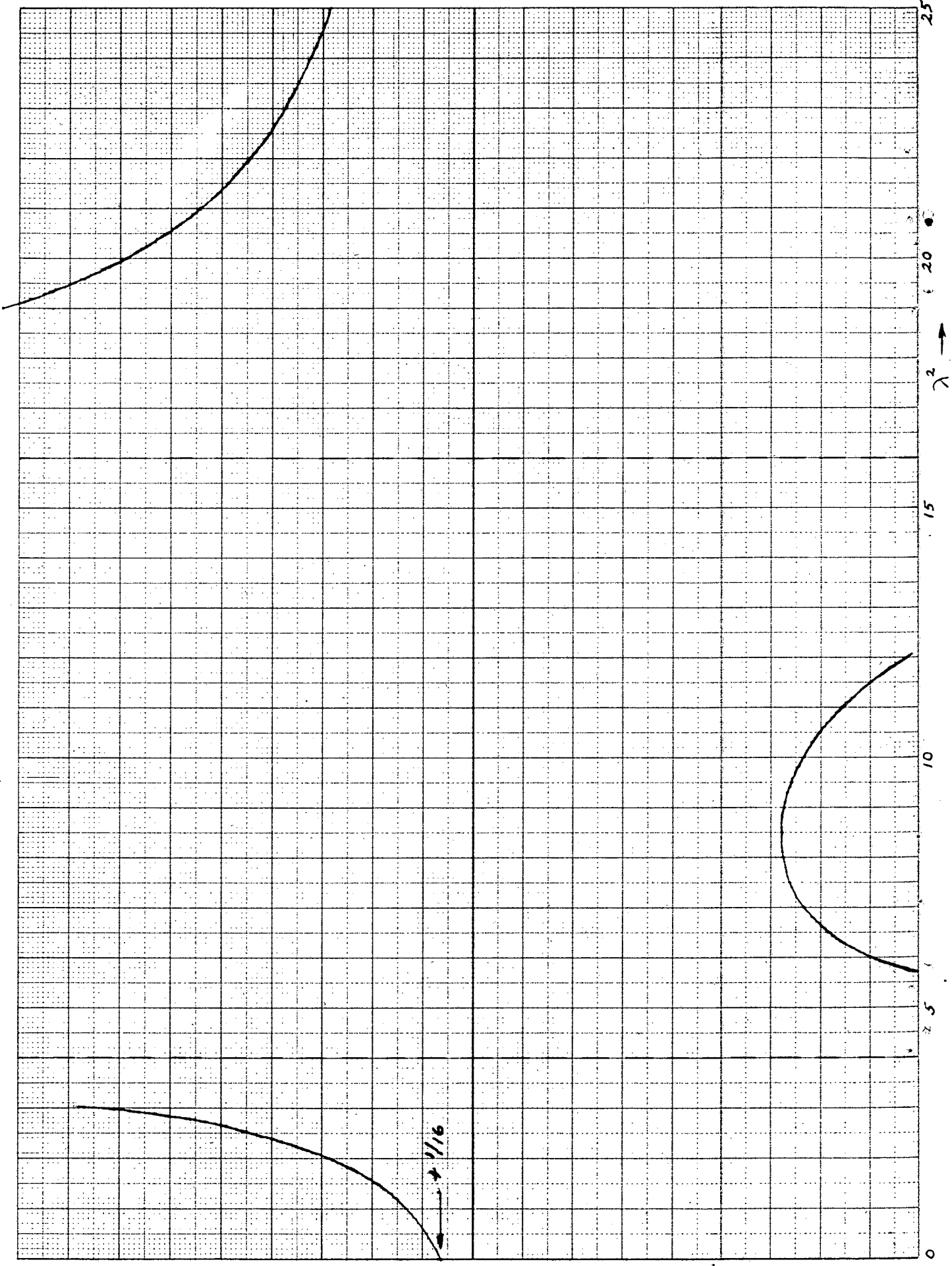
STABLE

$$F_{cn} = \frac{2}{\lambda^2 - 4}$$

$$m=0, j=1$$

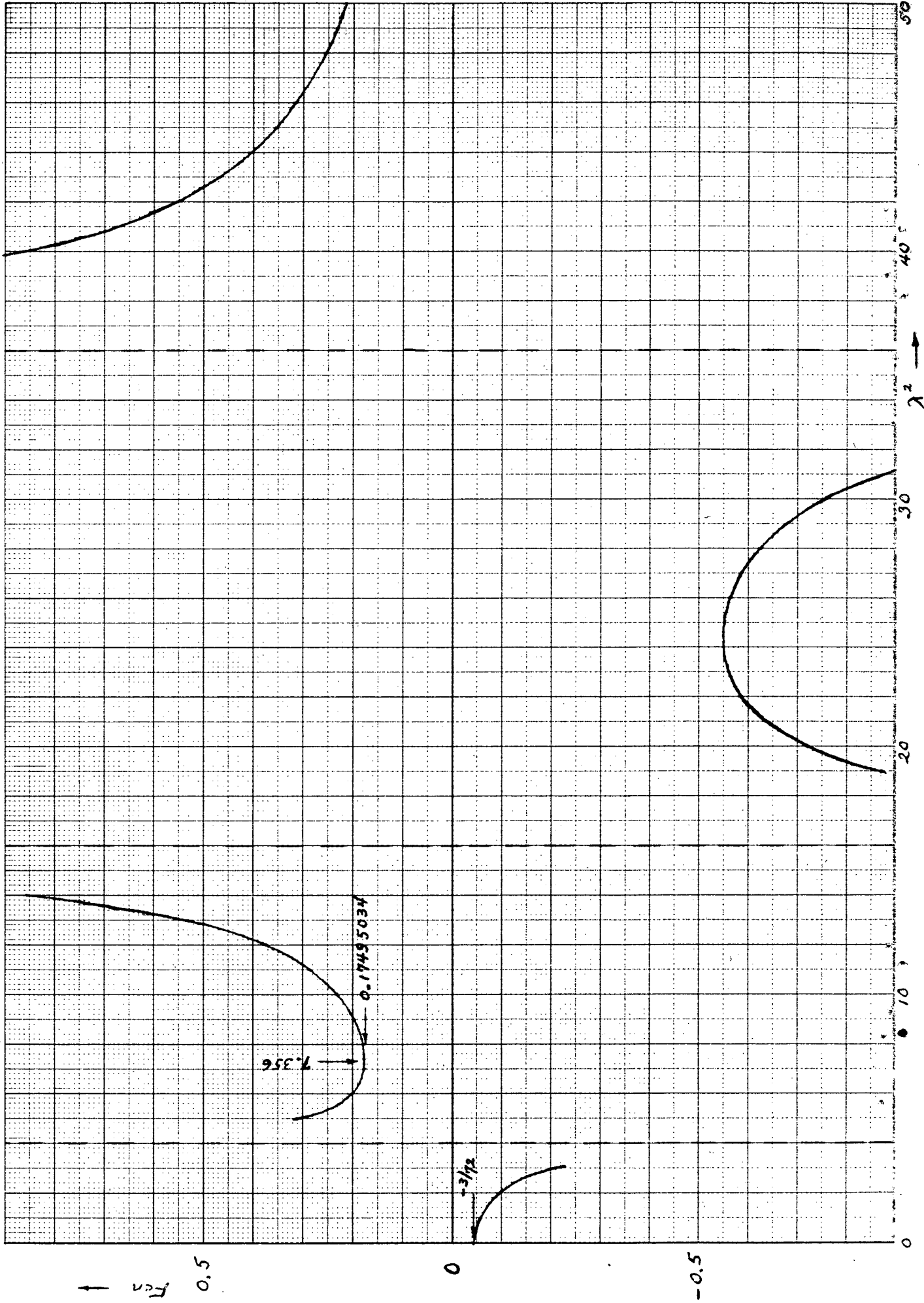


$$m = 0 \quad j = 2 \quad F_{cn} = -\frac{1}{\lambda^2 - 4} + \frac{3}{\lambda^2 - 16}$$

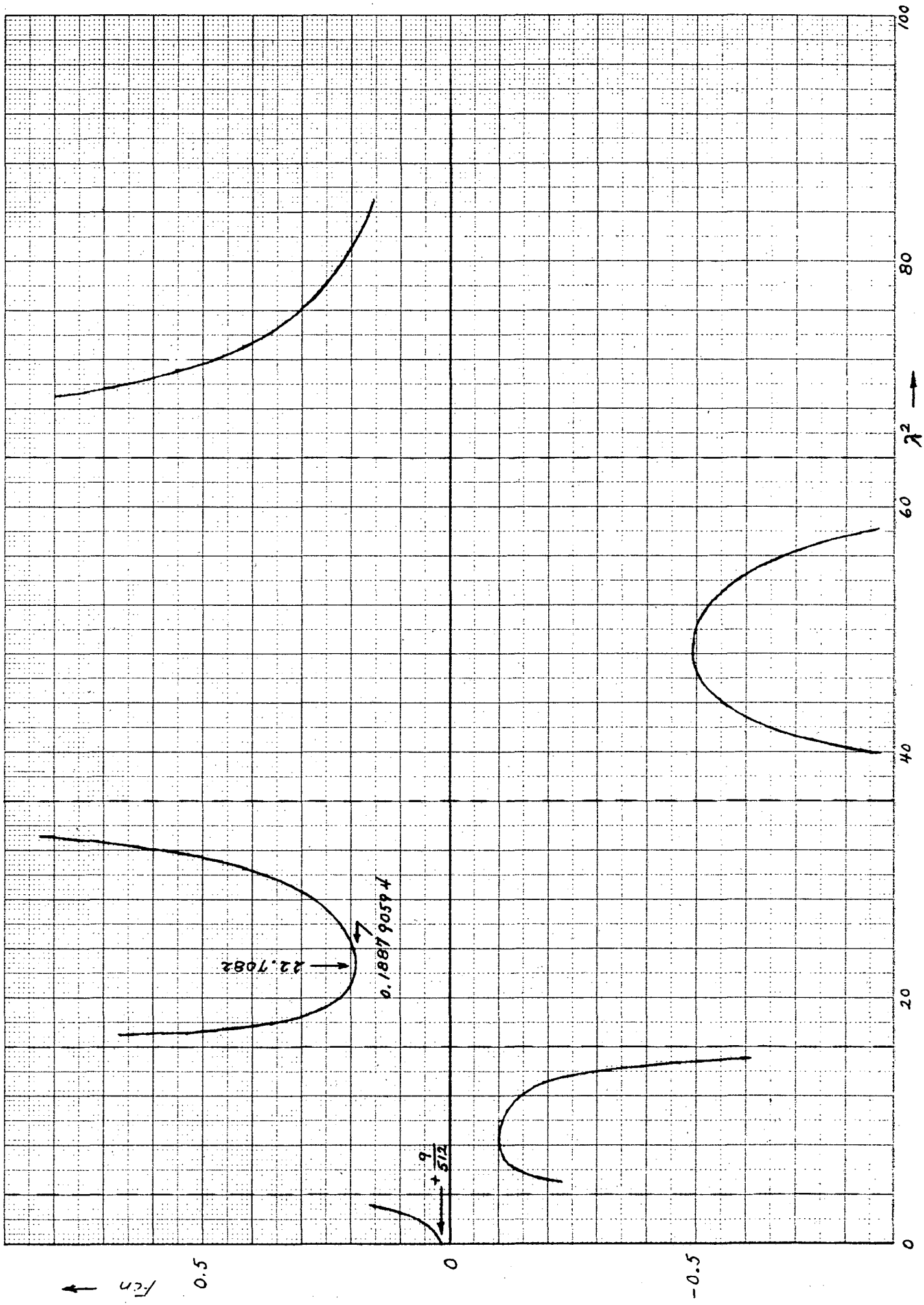


$$F_{cn} = \frac{1}{4} \left[\frac{1}{\lambda^2 - 4} - \frac{8}{\lambda^2 - 16} + \frac{15}{\lambda^2 - 36} \right]$$

$$m = 0 \quad j = 3$$



$$m = 0 \quad j = 4 \quad F_{0j} = \frac{1}{16} \left[-\frac{3}{\lambda^2 - 4} + \frac{10}{\lambda^2 - 16} - \frac{45}{\lambda^2 - 36} + \frac{70}{\lambda^2 - 64} \right]$$

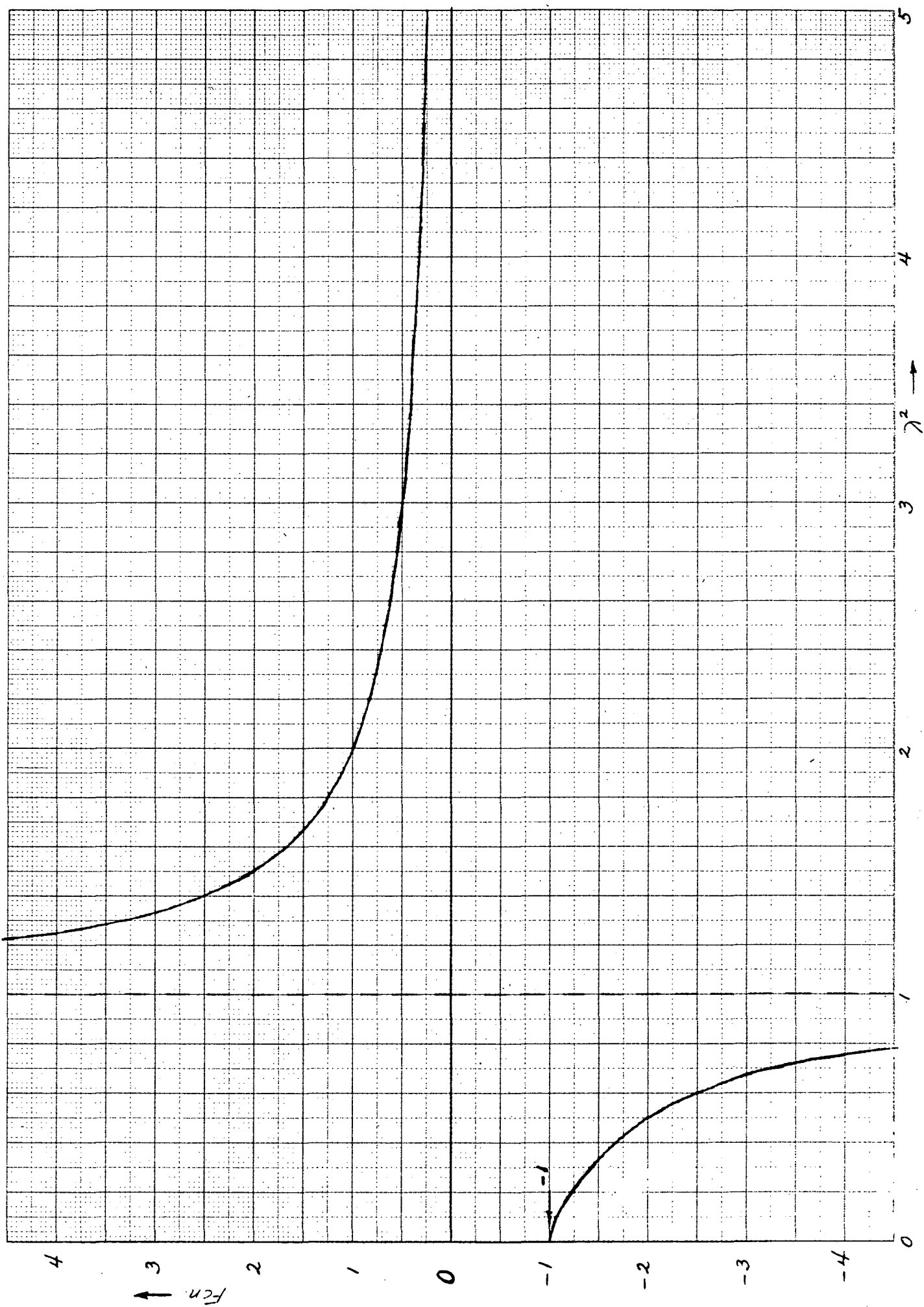


SCALE 10 X 10 PER CENTIMETER AS SHOWN

STABLE

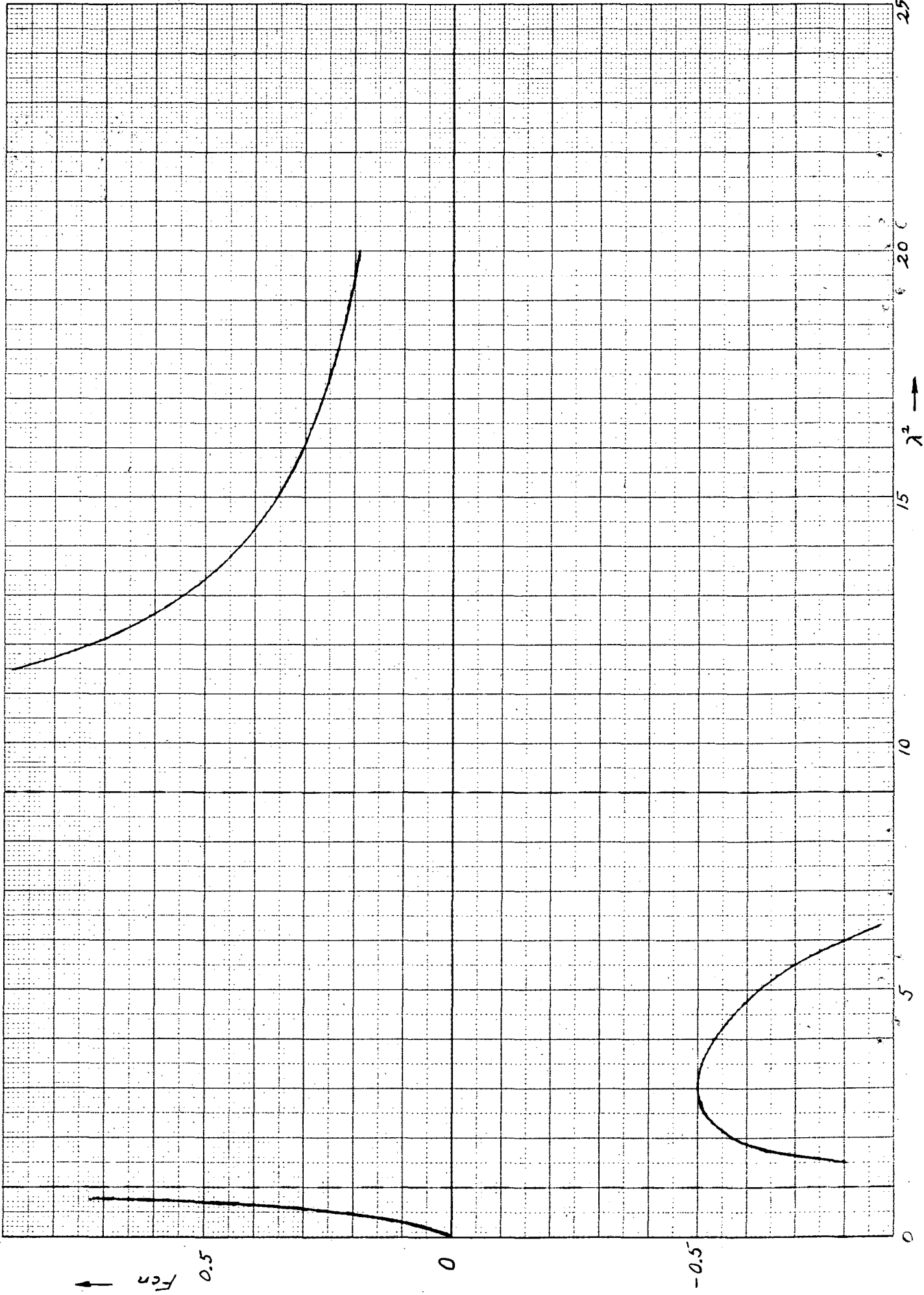
$$f_{cn} = \frac{1}{\lambda^2 - 1}$$

$m = 1 \quad j = 0$



$$m = 1 \quad j = 1 \quad F_{cn} = \frac{1}{4} \left[-\frac{1}{\lambda^2 - 1} + \frac{9}{\lambda^2 - 9} \right]$$

STABLE



F_{cn} ↑

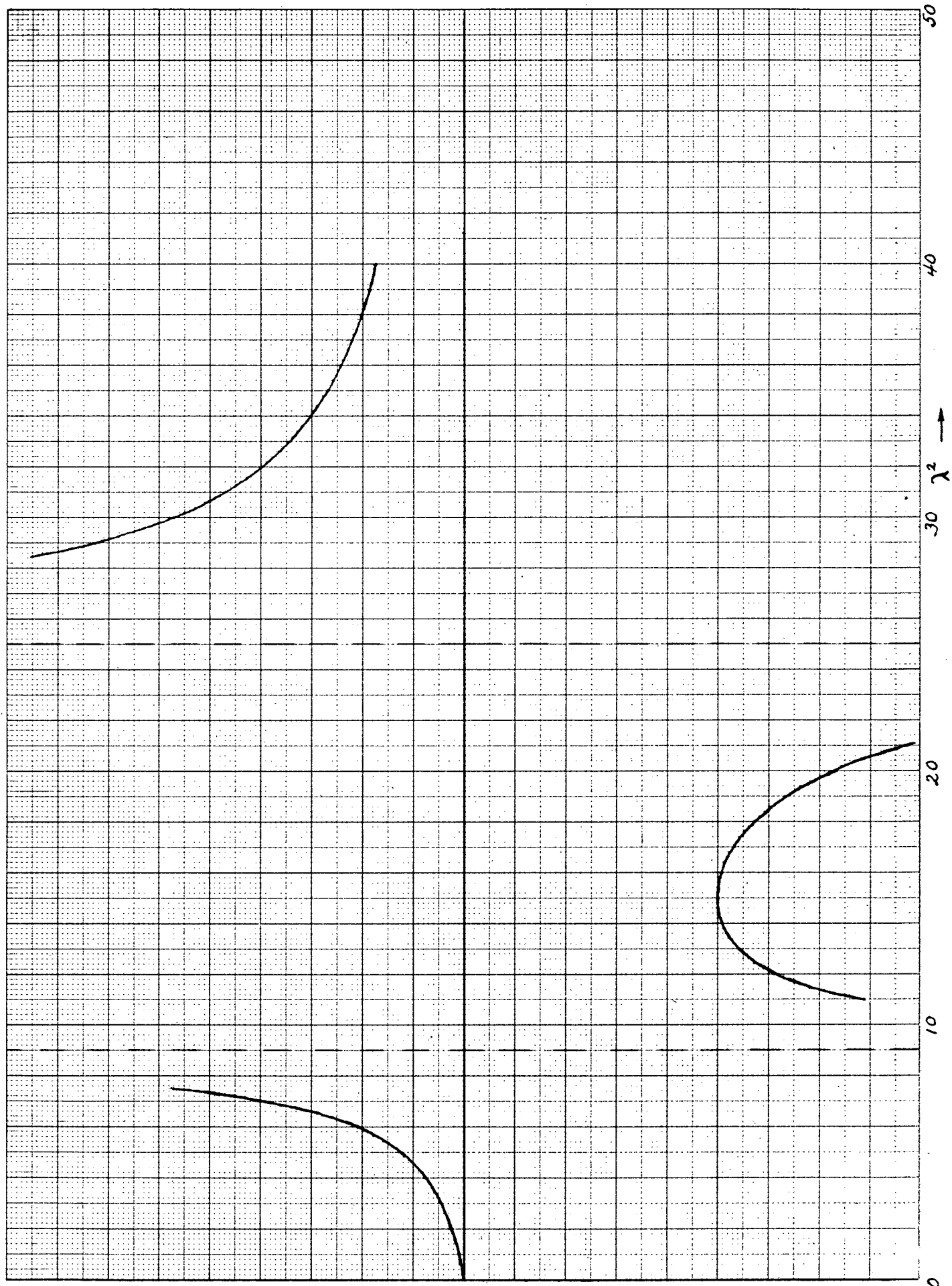
λ^2 →

STABLE AS ROOTS OF

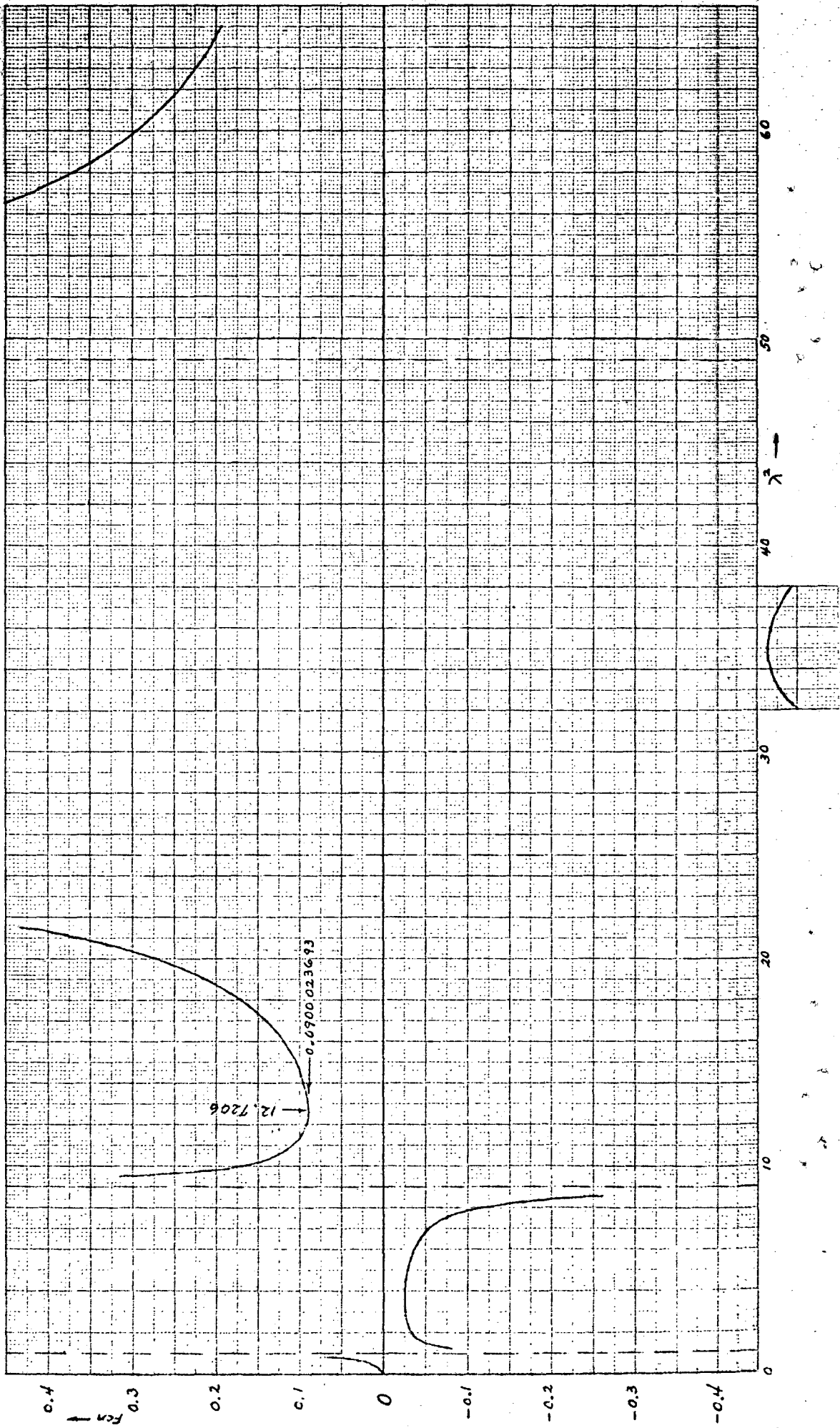
STABLE

$$F_{cn} = \frac{1}{8} \left[-\frac{9}{\lambda^2 - 9} + \frac{25}{\lambda^2 - 25} \right]$$

$$m = 1 \quad j = 2$$

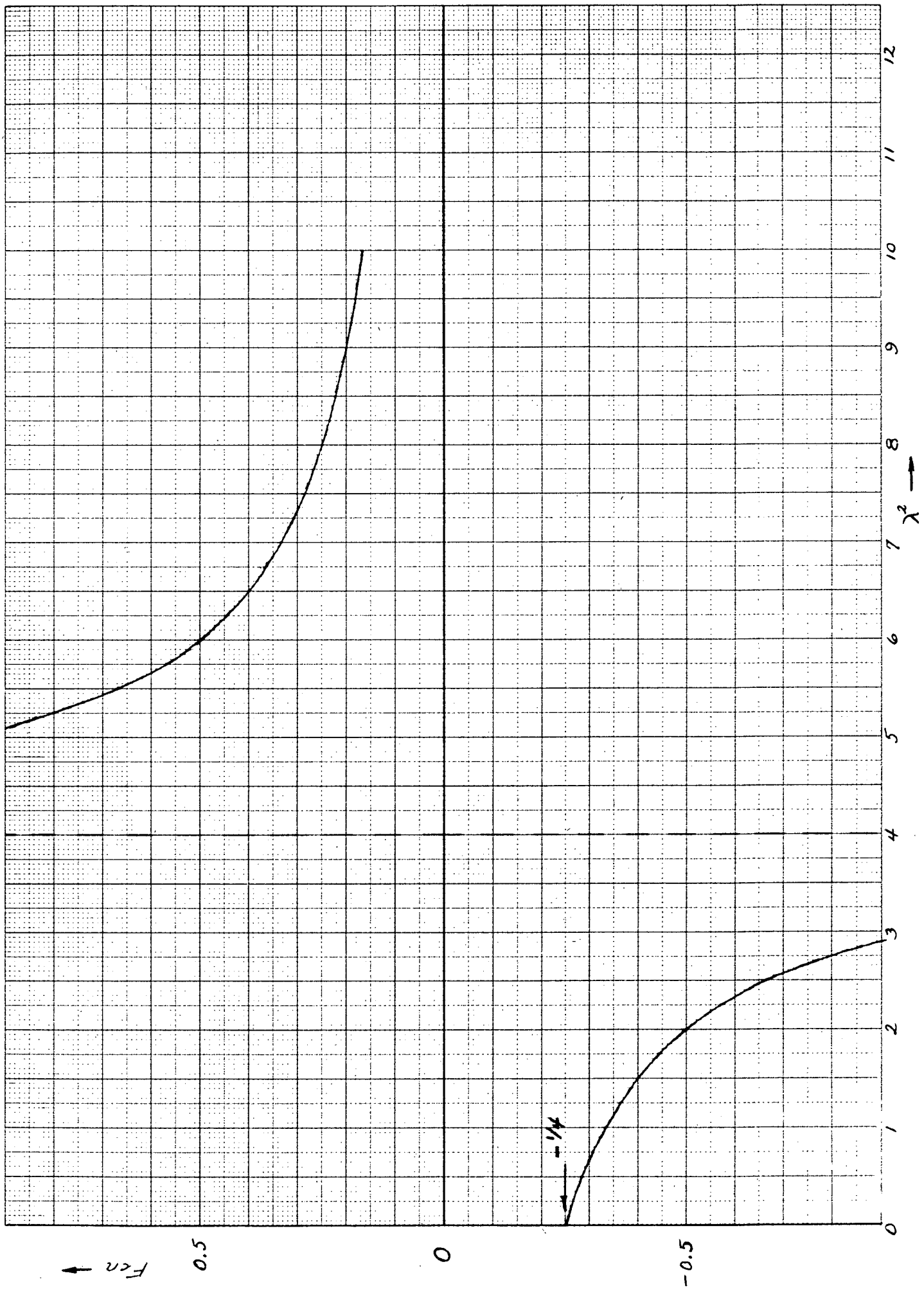


$$m=1 \quad j=3 \quad f_{cn} = \frac{1}{64} \left[-\frac{1}{\lambda^2-1} + \frac{9}{\lambda^2-9} - \frac{12.5}{\lambda^2-25} + \frac{2.45}{\lambda^2-49} \right]$$



$m = 2$ $j = 0$ $f_{cn} = \frac{1}{\lambda^2 - 4}$

STABLE

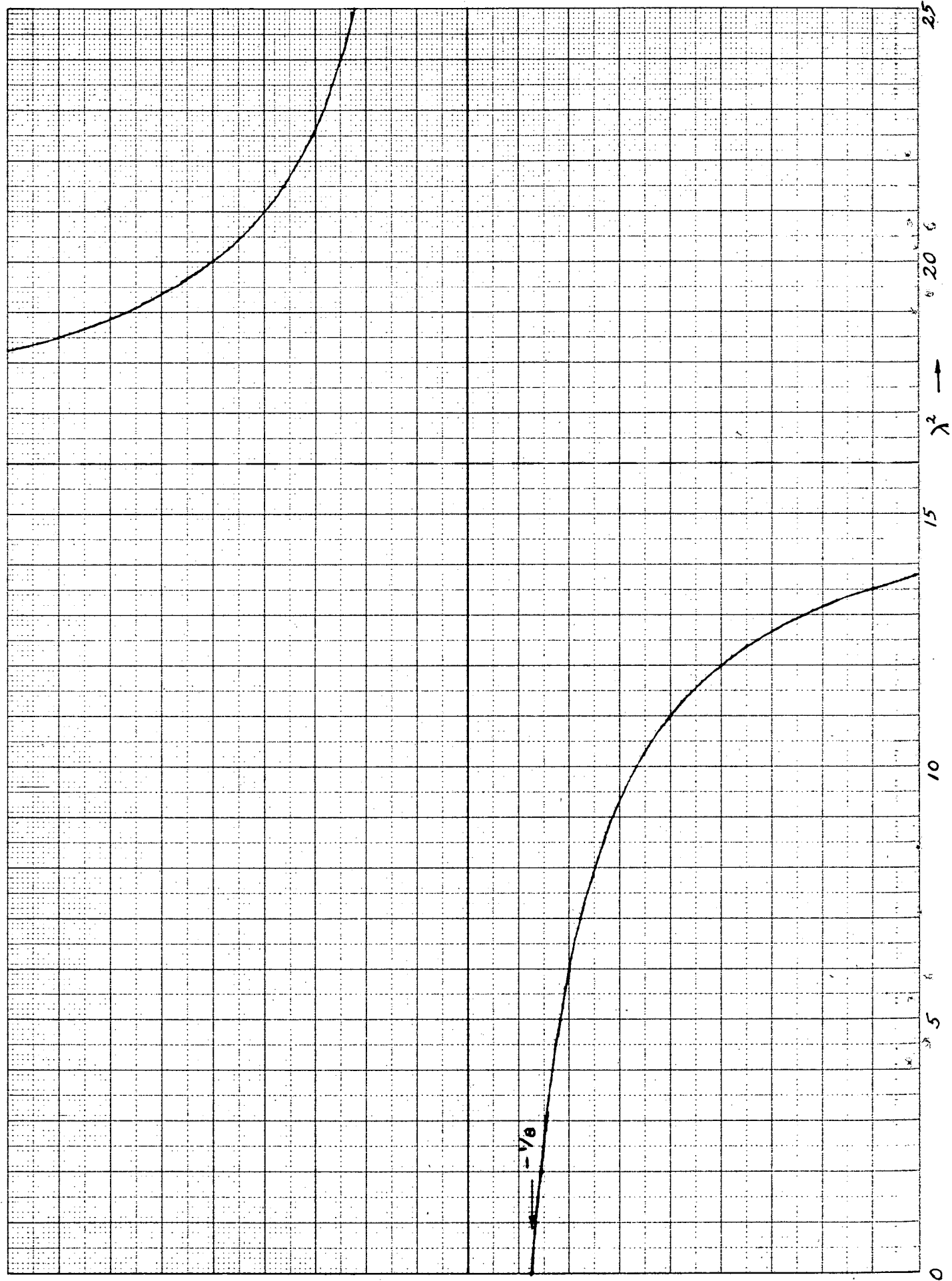


$$F_{cr} = \frac{2}{\lambda^2 - 16}$$

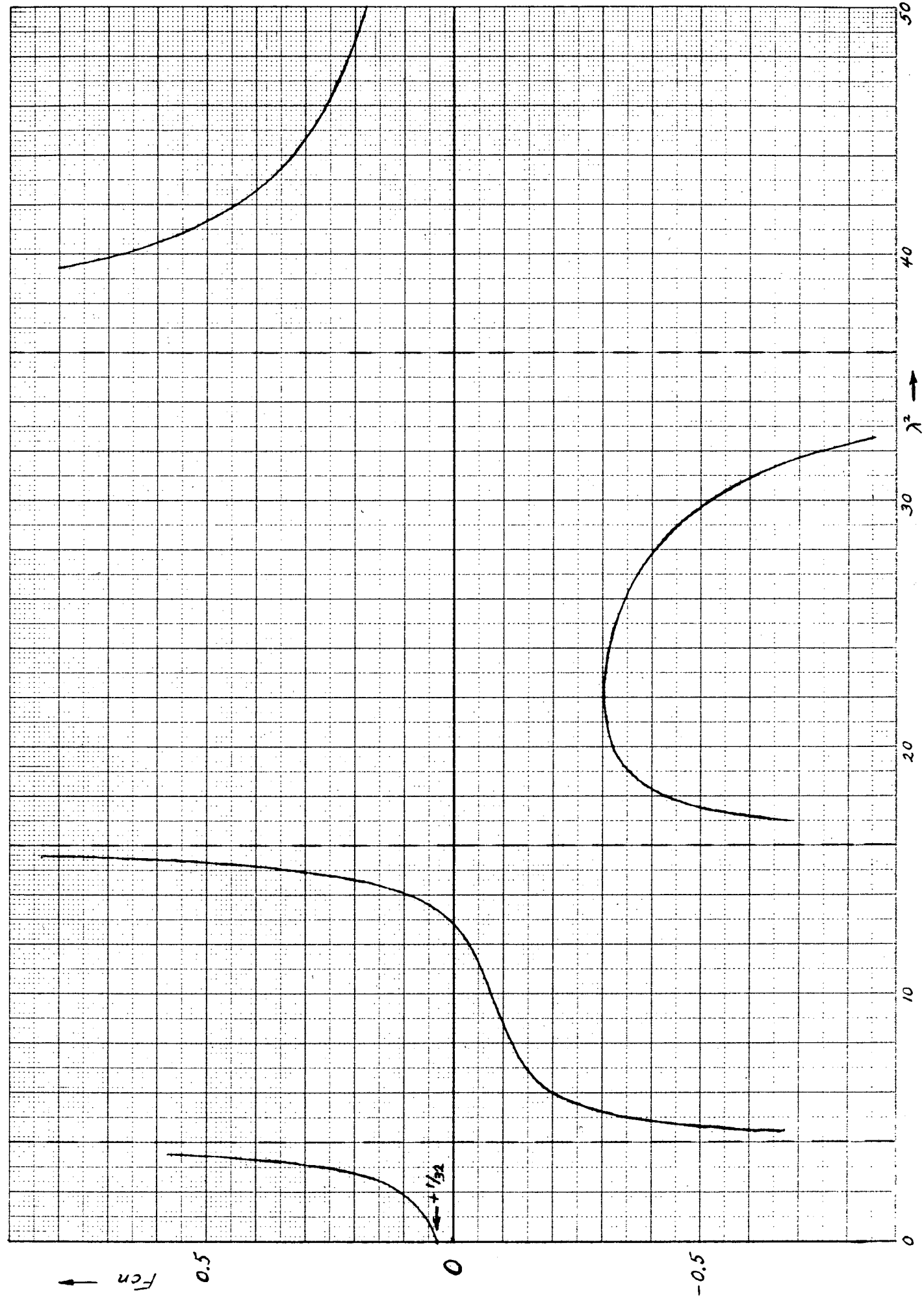
$$j = 1$$

$$m = 2$$

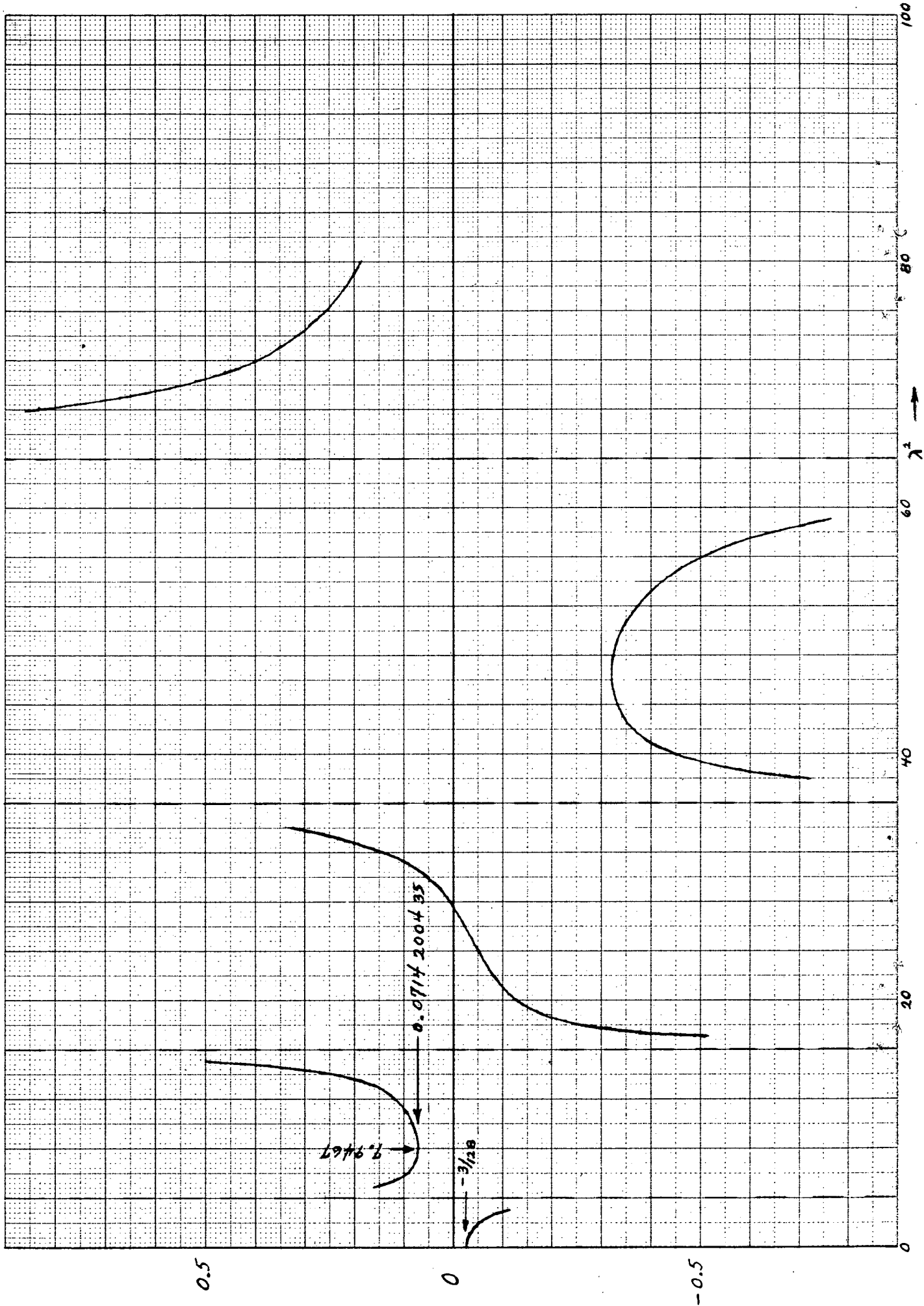
STABLE



$$m = 2 \quad j = 2 \quad Fcn = \frac{1}{16} \left[-\frac{5}{\lambda^2 - 4} - \frac{8}{\lambda^2 - 16} + \frac{45}{\lambda^2 - 36} \right]$$

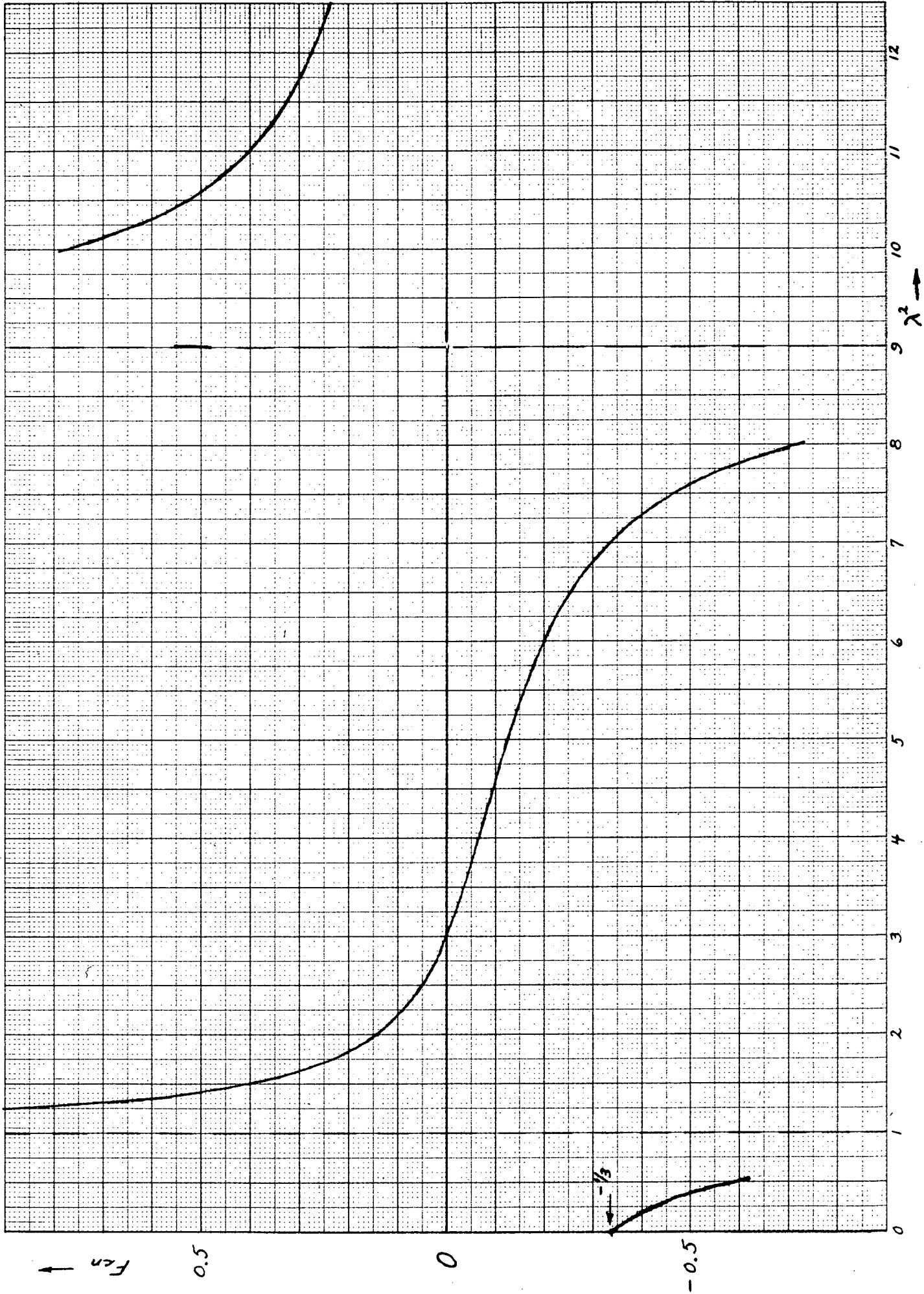


$$m = 2 \quad j = 3 \quad f_{cn} = \frac{1}{8} \left[\frac{1}{\lambda^2 - 4} - \frac{4}{\lambda^2 - 16} - \frac{9}{\lambda^2 - 36} + \frac{28}{\lambda^2 - 64} \right]$$



STABLE

$$m = 3 \quad j = 0 \quad F_{cn} = \frac{1}{4} \left[\frac{1}{\lambda^2 - 1} + \frac{3}{\lambda^2 - 9} \right]$$

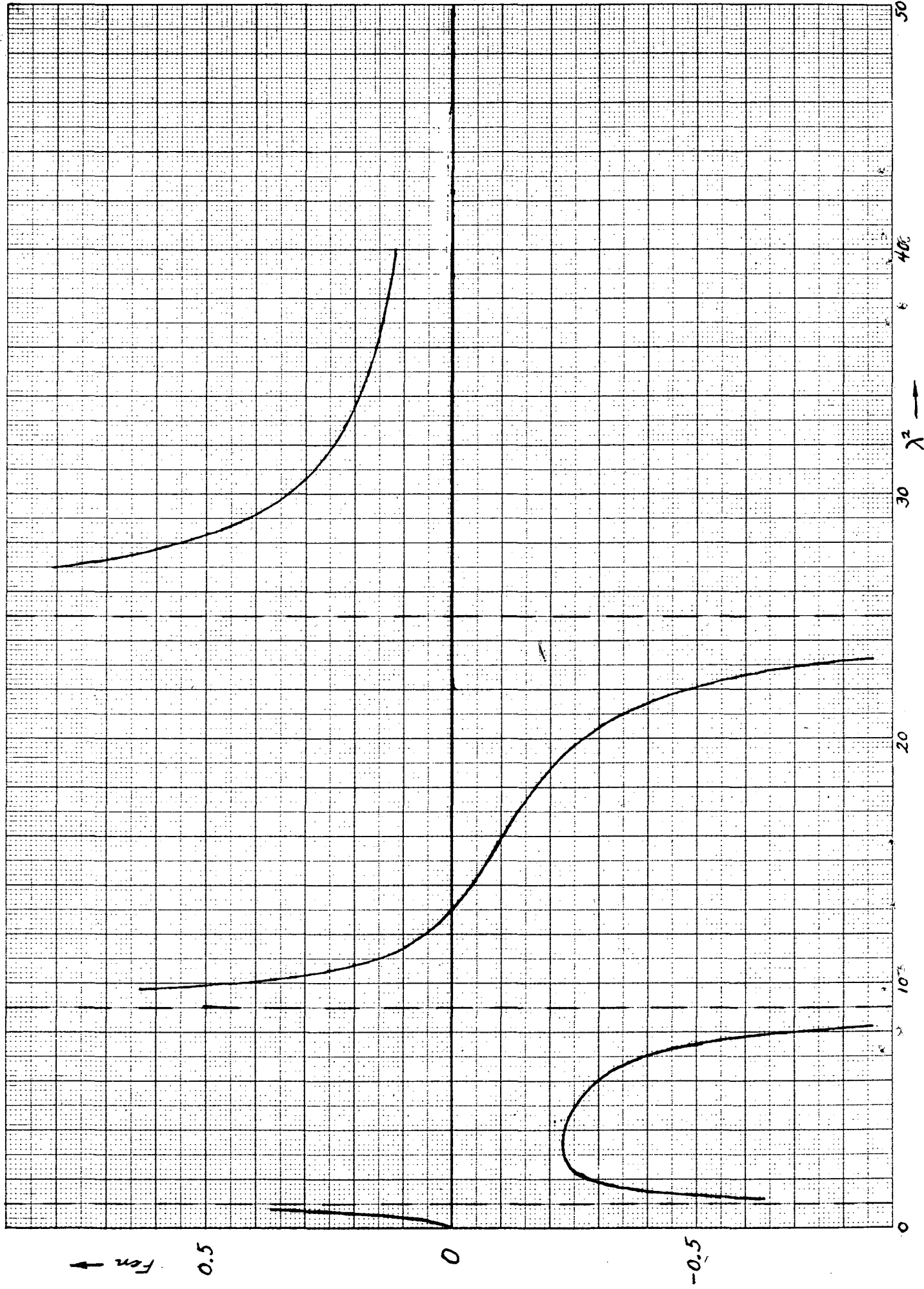


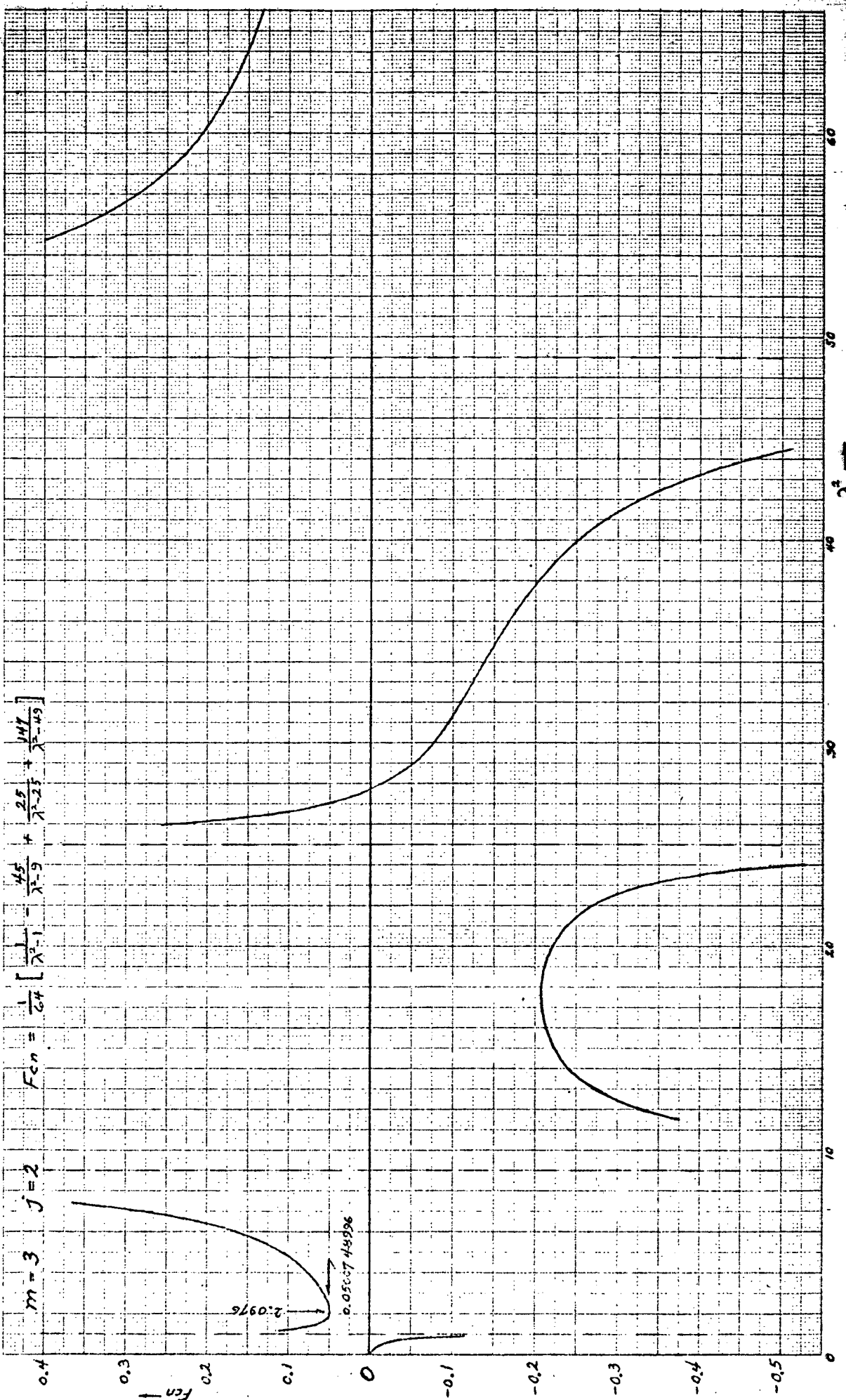
STABLE

$$F_{cn} = \frac{1}{16} \left[-\frac{2}{\lambda^2 - 1} + \frac{9}{\lambda^2 - 9} + \frac{25}{\lambda^2 - 25} \right]$$

$$j = 1$$

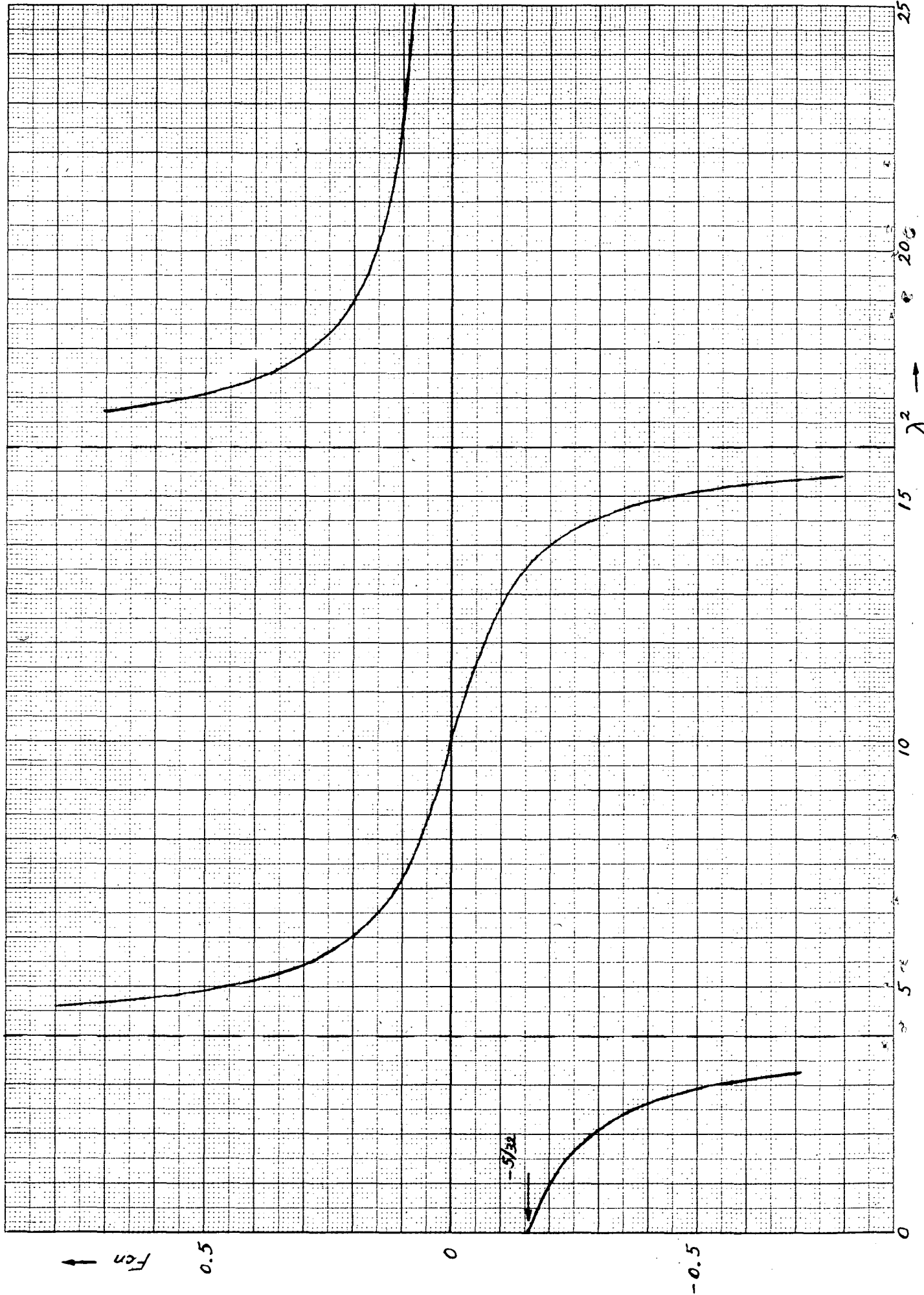
$$m = 3$$





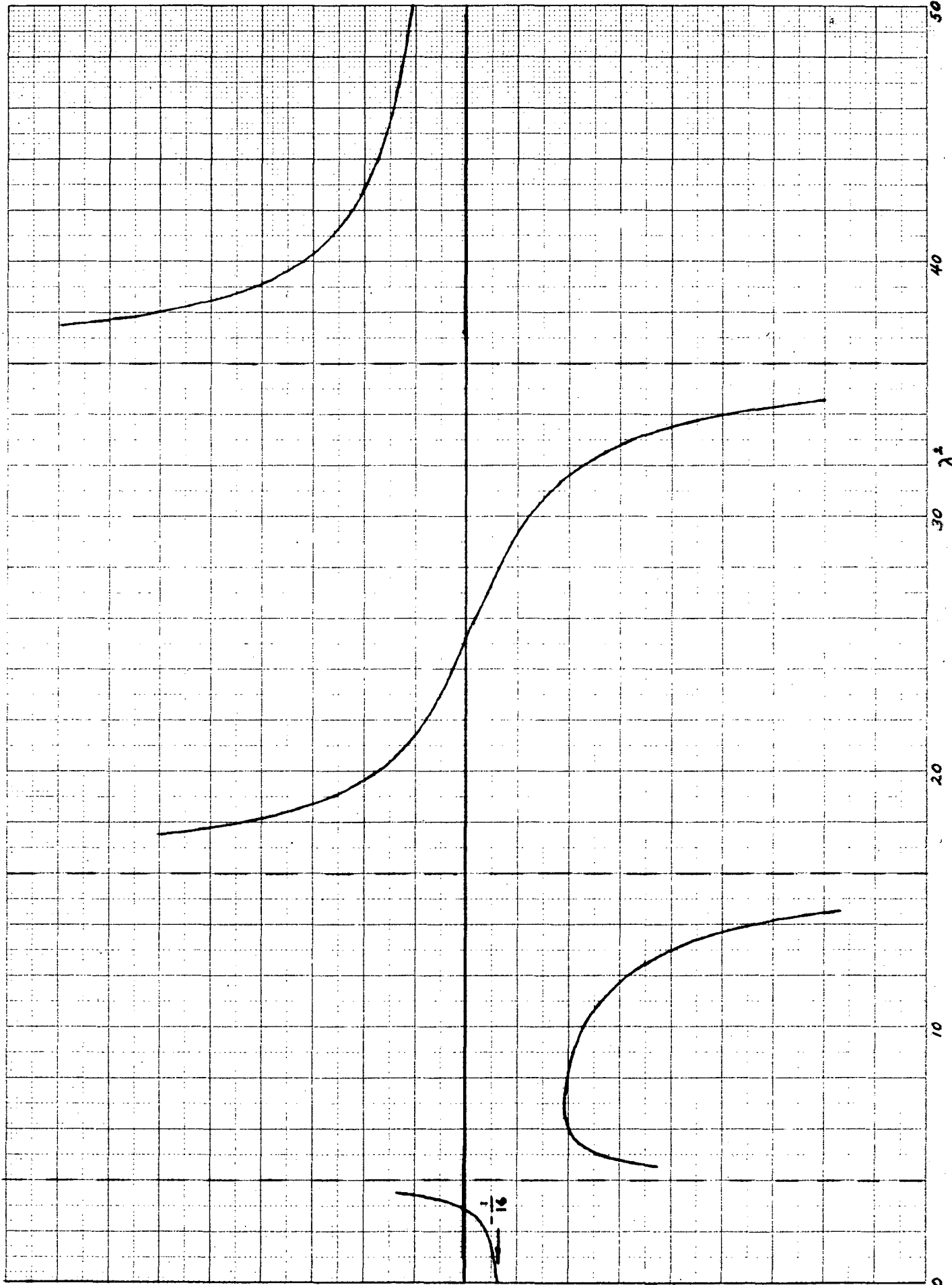
$$m = 4 \quad j = 0 \quad F_{cn} = \frac{1}{2} \left[\frac{1}{\lambda^2 - 4} + \frac{1}{\lambda^2 - 16} \right]$$

STABLE



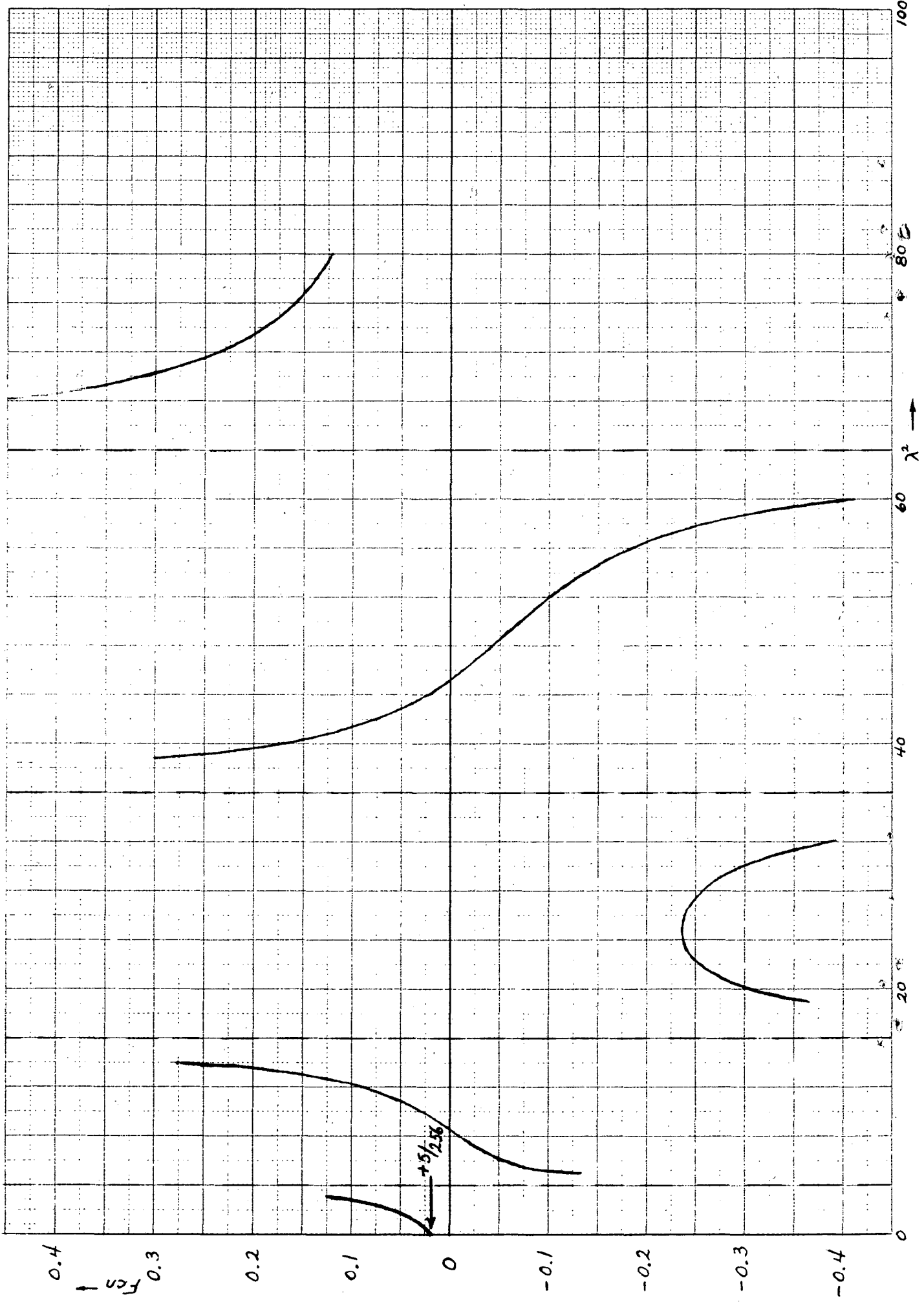
$$m = 4 \quad j = 1 \quad F_{cn} = \frac{1}{8} \left[-\frac{1}{\lambda^2 - 4} + \frac{8}{\lambda^2 - 16} + \frac{9}{\lambda^2 - 36} \right]$$

STABLE



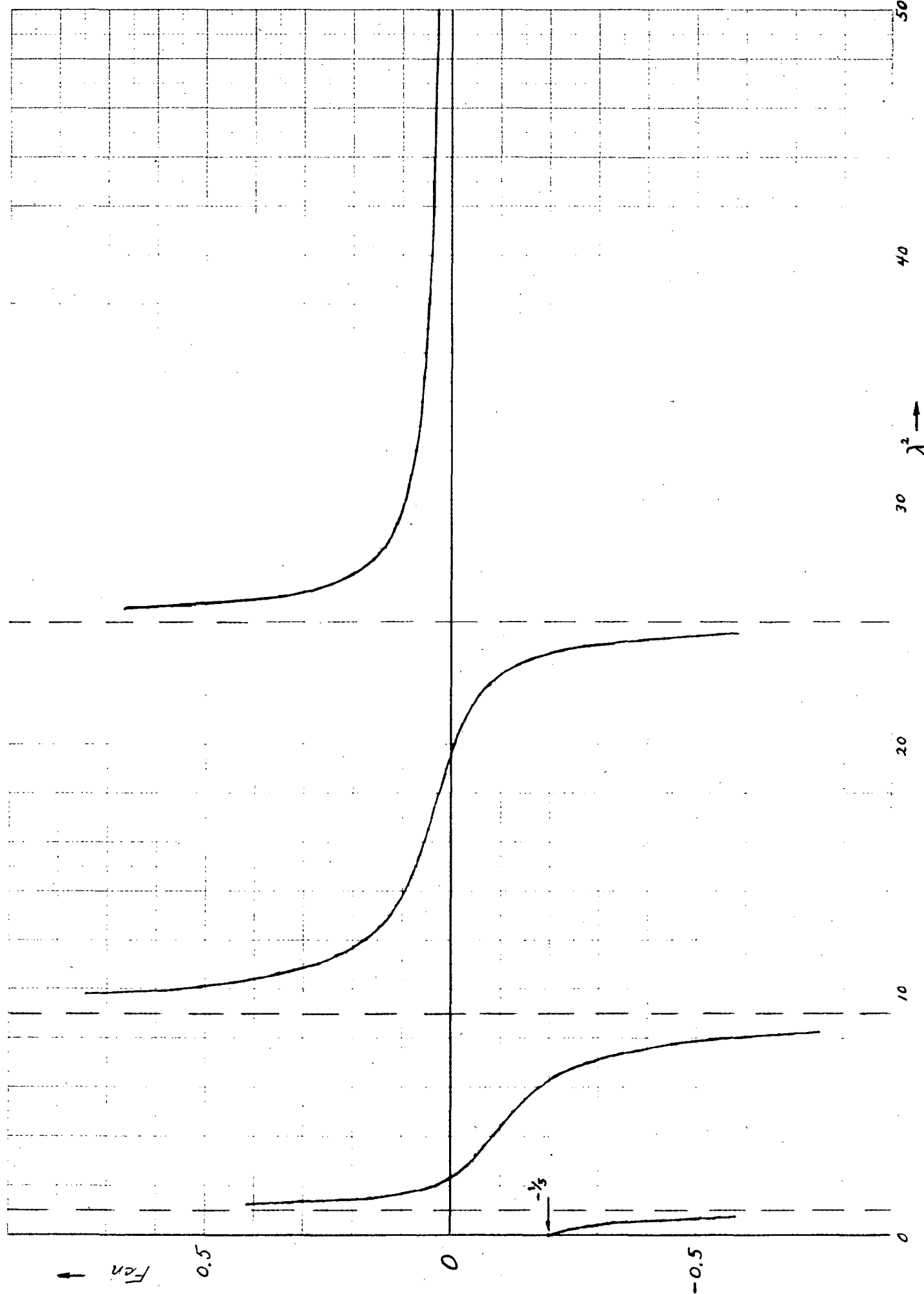
$m = 4 \quad j = 2$

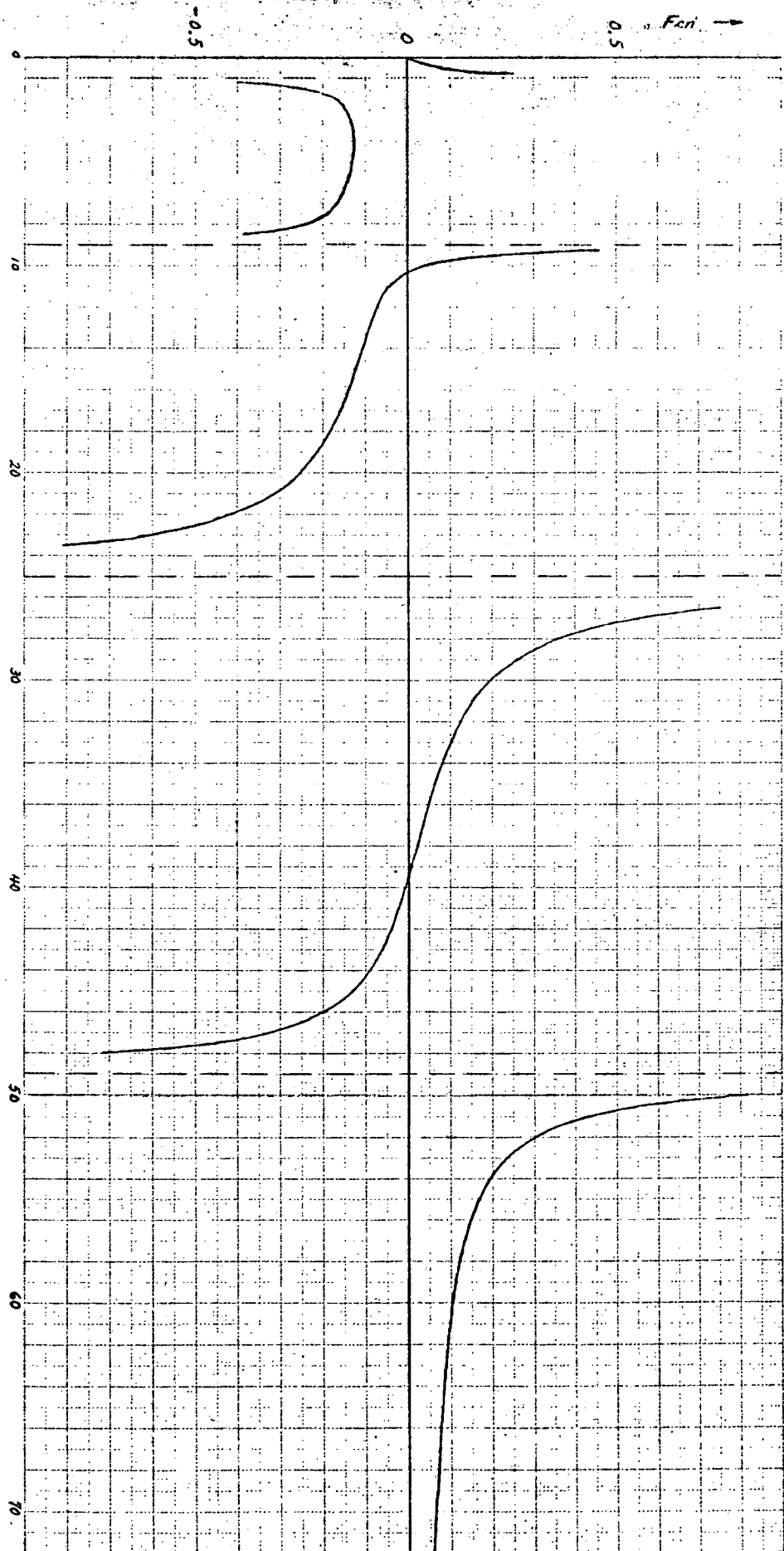
$$F_{cn} = \frac{1}{8} \left[-\frac{1}{\lambda^2 - 4} - \frac{6}{\lambda^2 - 16} + \frac{9}{\lambda^2 - 36} + \frac{14}{\lambda^2 - 64} \right]$$



$m = 5 \quad j = 0$
 $F_{en} = \frac{1}{16} \left[\frac{2}{\lambda^2 - 1} + \frac{9}{\lambda^2 - 9} + \frac{5}{\lambda^2 - 25} \right]$

STABLE





$m = 5 \quad j = 1$

$$F(x) = \frac{1}{64} \left[-\frac{5}{x-1} + \frac{9}{x-9} + \frac{15}{x-25} + \frac{49}{x^2-49} \right]$$

STABLE

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