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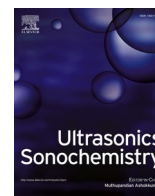
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## Characterization of the acoustic cavitation in ionic liquids in a horn-type ultrasound reactor

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### ABSTRACT

Most ultrasound-based processes root in empirical approaches. Because nearly all advances have been conducted in aqueous systems, there exists a paucity of information on sonoprocessing in other solvents, particularly ionic liquids (ILs). In this work, we modelled an ultrasonic horn-type sonoreactor and investigated the effects of ultrasound power, sonotrode immersion depth, and solvent's thermodynamic properties on acoustic cavitation in nine imidazolium-based and three pyrrolidinium-based ILs. The model accounts for bubbles, acoustic impedance mismatch at interfaces, and treats the ILs as incompressible, Newtonian, and saturated with argon. Following a statistical analysis of the simulation results, we determined that viscosity and ultrasound input power are the most significant variables affecting the intensity of the acoustic pressure field ( $P$ ), the volume of cavitation zones ( $V$ ), and the magnitude of the maximum acoustic streaming surface velocity ( $u$ ).  $V$  and  $u$  increase with the increase of ultrasound input power and the decrease in viscosity, whereas the magnitude of negative  $P$  decreases as ultrasound power and viscosity increase. Probe immersion depth positively correlates with  $V$ , but its impact on  $P$  and  $u$  is insignificant. 1-alkyl-3-methylimidazolium-based ILs yielded the largest  $V$  and the fastest acoustic jets – 0.77 cm<sup>3</sup> and 24.4 m s<sup>-1</sup> for 1-ethyl-3-methylimidazolium chloride at 60 W. 1-methyl-3-(3-sulfo-propyl)-imidazolium-based ILs generated the smallest  $V$  and lowest  $u$  – 0.17 cm<sup>3</sup> and 1.7 m s<sup>-1</sup> for 1-methyl-3-(3-sulfo-propyl)-imidazolium *p*-toluene sulfonate at 20 W. Sonochemiluminescence experiments validated the model.

### 1. Introduction

Sonoprocessing finds numerous industrial applications, including chemical synthesis [1], surface modification [2], reaction acceleration [3], extraction [4], cleaning, and food processing [5]. Ultrasound (US) is a mechanical wave consisting of a cyclic succession of expansion and compression phases, during which liquid molecules are pulled apart and pushed together [5]. When the maximum change in pressure between compression and expansion phases, which is the pressure amplitude of the acoustic wave, exceeds the tensile strength of the liquid medium in the rarefaction regions, cavitation bubbles form. At high acoustic intensity, bubbles grow drastically and collapse during a compression phase when the radius of the bubble is tens to hundreds of times the equilibrium radius. This transient cavitation forms hot spots (5000 K and 500 bar) and liquid micro-jets, which elicit chemical and physical effects

on the sonicated system [6,7]. Among the advantages of sonoprocessing we find the generation of reactive species and the enhancement of mass transfer, particularly in multiphase systems [8]. One of the key factors that determine the outcomes of sonoprocessing is the nature of the solvent. Water has been the preferred solvent for most sonoprocessing applications, due to its abundance, low cost, and ability to generate reactive oxidizing species. However, some organic and inorganic compounds are insoluble or partially soluble in water. Moreover, some reactions either cannot take place or are extremely slow in presence of water. For example, the esterification of carboxylic acids with alcohols yields water as a by-product, which shifts the equilibrium towards the reactants thereby limiting the formation of the desired ester [9]. For these reasons, most organic and organometallic reactions require non-aqueous solvents, which are generally volatile, flammable, toxic, and their regeneration is energy intensive.

To obviate the undesirable properties of aqueous solvents for certain

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Nomenclatures			
$b$	Damping factor	$P_{\text{vap}}$	Vapour pressure
$c$	Speed of sound	$R_{\text{eq}}$	Equilibrium radius of bubble
$C$	Constant	$R_0$	Incipient radius of a monodispersed bubble
CI	Confidence interval	$R_p$	Probe radius
$C_p$	Isobaric specific heat capacity	RMS	&Root mean square deviation
$d$	Probe immersion depth	SCL	Sonochemiluminescence
$D$	Thermal diffusivity of gas	$t$	Time
$f$	Ultrasonic frequency	$u$	Maximum acoustic streaming surface velocity
$F$	Volumetric force	US	Ultrasound
H	height	$V$	Active region volume
$i$	Imaginary unit	$Z$	Acoustic impedance
ID	Internal diameter	<i>Greek letters</i>	
IL	Ionic liquid	$\alpha$	Acoustic attenuation from the intrinsic properties of the liquid
$k_m$	Complex wave number	$\beta$	Bubbles volume fraction
$N$	Bubble number density	$\gamma$	Specific heat ratio (adiabatic index)
$P$	Acoustic Pressure	$\mu$	Dynamic viscosity
$P_A$	Pressure amplitude	$\rho$	Density
$P_c$	Pressure threshold required for cavitation	$\sigma$	Surface tension
$P_{\text{max}}$	Maximum acoustic pressure (positive)	$\phi$	Complex adimensional parameter
$P_{\text{min}}$	Minimum acoustic pressure (negative)	$\chi$	Complex function
$P_0$	Static pressure (or undisturbed pressure in the bubble position)	$\omega$	Acoustic wave angular frequency
$P_{\text{US}}$	Ultrasound input power	$\omega_0$	Bubbles resonant frequency

applications, the scientific community shifted its attention towards ionic liquids (ILs). ILs are salts that are liquid at room temperature and that possess convenient intrinsic properties that make them attractive solvents for a plethora of chemical reactions. ILs are non-flammable, have high thermal stability, and do not emit volatile organic compounds. The combination of specific ions tunes the acidity [10], hydro- and lipophilicity [11], melting point [12], viscosity [13], surface tension and density [14], making ILs attractive 'designer solvents' in the chemical field. Another advantage of ILs is their undetectable vapour pressure [15].

Because liquids and gases have different speeds of sound and compressibilities, there is an acoustic impedance ( $Z$ ) mismatch at the bubbles' interface.  $Z$  is a measure of the resistance that a material exerts on the acoustic flow [16]. Acoustic cavitation relies on the violent collapse of bubbles. If bubbles do not implode, they scatter, reflect, or refract sound waves, leading to less intense sonochemical events. The number density and size of cavitation bubbles increases with the US input power. The attenuation of sound waves propagation is therefore an undesirable effect of cavitation at high acoustic intensity. As power increases, more bubbles collide and coalesce at the tip of the US probe, thereby forming a continuous layer of bubbles that adhere to its surface [17]. These bubbles are incapable of growing enough to implode because they undergo continuous cycles of coalescence and fragmentation, the latter imparted by the acoustic streaming jet forming below the sonotrode that pushes bubbles downwards. Furthermore, coalescence perturbs bubbles sphericity. Fattahi et al., [17] demonstrated that bubbles that remain spherical over several acoustic cycles and then collapse, lead to more intense sonochemical activity and larger active zones. Spherical bubbles are symmetric in shape, which means that the pressure inside the bubble is distributed evenly in all directions. They also have the minimum surface area for a given volume, so they require less energy to maintain their shape than other shapes, and they have a higher internal pressure for a given size, making them more prone to collapse. Additionally, spherical bubbles vibrate at the same frequency as the sound waves. This resonance amplifies the pressure fluctuations in the bubble, leading to rapid growth and collapse of the bubble. These factors make spherical bubbles more stable and easier to collapse than irregularly shaped

bubbles.

The enthalpy of vaporization ( $\Delta H_{\text{vap}}$ ) of ILs is four to seven times higher than that of water and common organic solvents – e.g.  $\Delta H_{\text{vap}}$  is 175.8 kJ mol<sup>-1</sup> for 1-ethyl-3-methylimidazolium acetate, 40.6 kJ mol<sup>-1</sup> for water, and 29.1 kJ mol<sup>-1</sup> for acetone [18]. As a consequence of their low volatility, ILs generate a lower number of cavitation bubbles than water. This results in less numerous non-spherical bubble clusters, which translates into a lower attenuation of the acoustic energy and, in theory, larger active zones. Numerous variables affect the size of the active regions, including the solvent's thermodynamic properties. The application of US to intensify chemical reactions, given the significant diversity in properties amongst ILs, requires a deep understanding of the numerous factors influencing cavitation.

The state of the art surrounding the characterization of acoustic cavitation in ILs is rather limited compared to that of aqueous working media. We queried the Web Of Science Core Collection database with the keywords ((ionic liquid AND cavitation) OR (ionic liquid AND ultrasound)). The search yielded only 121 articles, published from 1993 to 2022. These articles were most published in: multidisciplinary chemistry (34), physical chemistry (21), chemical engineering (16), and acoustics (13). Ultrasonics Sonochemistry published 11 %, followed by the Journal of Chemical Physics (2.5 %) and Separation and Purification Technology (2.5 %). VOSviewer generated a bibliographic map based on the text in the titles, abstracts, and keywords of the 121 publications (binary counting, minimum number of term occurrence: 3). The dimension of a node is directly proportional to the occurrence of the term in the dataset, while the proximity of circles indicates how related the terms are. VosViewer identified 6 clusters (Fig. 1fig:map\_us).

The green cluster groups publications concerning the application of US to ILs for synthetic purposes [20], while the yellow cluster those studying the cavitation bubble temperature [21,22] and sonoluminescence [15,23] under various conditions. The turquoise cluster gathers articles that make use of electrochemical or spectroscopic techniques for the investigation of cavitation activity [24]. The magenta and red clusters comprise US-assisted extractions and biomass pre-treatments [25,26]. Finally, the blue cluster groups studies focusing on bubble dynamics in ionic aqueous solution [27]. In some instances, the



m s<sup>-1</sup>,  $t$  is time in s, and  $\nabla^2$  is the spatial Laplacian operator:

$$\nabla^2 = \frac{\delta^2 P}{\delta x^2} + \frac{\delta^2 P}{\delta y^2} + \frac{\delta^2 P}{\delta z^2} \quad (2)$$

To model the ultrasonic field, we considered the liquid medium was incompressible (Paragraph 2.4). Moreover, to apply Eq. (1) we assumed that shear stresses are absent or negligible, the sound waves propagating through the medium are linear, and pressure has a harmonic time dependence so that  $P(r, t) = P(r) \cdot e^{i\omega t}$  [32], where  $\omega$  is the acoustic wave angular frequency in rad s<sup>-1</sup>.  $\omega$  is the magnitude of the pseudovector quantity angular velocity, which in other words corresponds to the rate of the phase change of a sinusoidal wave and it is equal to  $2\pi f$ , where  $f$  is the ultrasonic frequency in Hz. Accordingly, Eq. (1) becomes the Helmholtz equation (Eq. (3)), which describes the propagation of acoustic waves in liquid media [33].

$$\frac{\nabla^2 P}{\rho} + \frac{\omega^2}{\rho c^2} P = 0 \quad (3)$$

However, when ultrasound is applied to a liquid at a specific power and frequency, transient cavitation occurs. In this instance, bubbles form and accumulate the formation of bubbles and their consequent accumulation at the tip of the US probe is appreciable. In fact, bubbles scatter sound waves thereby attenuating their propagation [34,35]. A bubbly liquid is considered a continuous (fictitious homogeneous) medium if velocity and pressure variations change over distances larger than the inter bubble distance. The density of the medium then depends on the liquid, while compressibility on the gas content. If the frequency of ultrasound is below the lowest resonance frequency of bubbles, the distribution of gas in bubbles of specific size is negligible and only the total gas content per unit volume is significant [36].

Wijngaarden developed a series of equations that describe the one-dimensional turbulent flow that takes place in liquids containing bubbles [37,38]. Based on Wijngaarden's equations and the continuity equation, Commander and Prosperetti formulated a rigorous model for the propagation of pressure waves in liquids containing bubbles. Their model takes into account the damping effect of bubbles, which arises from viscous, thermal, and acoustic forces. The model assumes a negligible contribution of bubbles resonance and an incompressible fluid (constant density and null divergence of flow velocity). They validated their model by processing the experimental data sets of other existing works, with bubble radii ranging from 5  $\mu\text{m}$ –3000  $\mu\text{m}$ , frequencies in the range of 20 Hz to 10 MHz, and small gas volume fractions ( $10^{-5}$  to  $10^{-2}$ ). The model is accurate for gas volume fractions up to 2 % [39]. The Commander and Prosperetti's modified Helmholtz equation is:

$$\nabla^2 P + k_m^2 P = 0 \quad (4)$$

where  $k_m^2$  is the complex wave number. For a monodisperse bubble distribution,  $k_m^2$  is expressed as [40]:

$$k_m^2 = \frac{\omega^2}{c^2} \left( 1 + \frac{4\pi c^2 N R_0}{\omega_0^2 - \omega^2 + 2ib\omega} \right) \quad (5)$$

where  $\omega_0$  is the bubbles resonant frequency  $b$  is the damping factor,  $R_0$  is the incipient radius of a monodispersed bubble,  $N$  is the bubble number density, and  $i$  is imaginary unit.  $\omega_0$  is determined from:

$$\omega_0 = \sqrt{\frac{P_0}{\rho R_{eq}^2} \left( \text{Re}\phi - \frac{2\sigma}{P_0 R_{eq}} \right)} \quad (6)$$

where  $P_0$  is the undisturbed pressure in the bubble position (liquid static pressure), which corresponds to  $P_{atm} + (2\sigma/R_{eq})$  where  $\sigma$  is the surface tension of the liquid.  $R_{eq}$  is the bubbles equilibrium radius considering direct contact coalescence and rectified diffusion, and  $\phi$  is a complex adimensional parameter, a function of the specific heat ratio (or adiabatic index) of the gas inside bubbles ( $\gamma$ ), and  $\chi$ .

$$\phi = \frac{3\gamma}{1 - 3i\chi(\gamma - 1) \left[ \sqrt{\frac{i}{\chi}} \cdot \coth \left( \sqrt{\frac{i}{\chi}} \right) - 1 \right]} \quad (7)$$

$\chi$  is expressed as:

$$\chi = \frac{D}{\omega R_{eq}^2} \quad (8)$$

where  $D$  is the thermal diffusivity of the gas. The damping factor  $b$  in Eq. (5) corresponds to:

$$b = \frac{2\mu}{\rho R_{eq}^2} + \frac{P_0}{2\rho\omega R_{eq}^2} \text{Im}\phi + \frac{\omega^2 R_{eq}}{2c} \quad (9)$$

where  $\mu$  is the dynamic viscosity of the fluid. The bubble number density  $N$  depends on  $\beta$ , the volume of the gas fraction within the bubbles in the reactor with respect to the total volume:

$$N = \frac{3\beta}{4\pi R_0^3} \quad (10)$$

## 2.2. Active regions

The pressure threshold required for cavitation ( $P_c$ ) depends on the nature and temperature of the sonicated liquid, and on its gas content (Eq. (11)):

$$P_c = P_0 - P_{\text{vap}} + \frac{\frac{2}{3\sqrt{3}} \sqrt[3]{\left(\frac{2\sigma}{R_{eq}}\right)^2}}{\sqrt{P_0 - P_{\text{vap}} + \frac{2\sigma}{R_{eq}}}} \quad (11)$$

where  $P_{\text{vap}}$  is the vapour pressure of the sonicated liquid. To calculate and compare the cavitation zones that form inside the reactor, the acoustic pressure is set to  $P_c$ .

The identification and quantification of cavitation zones allows the comparison of various sonotrode geometries and positions with respect to the reactor. The cavitation zone generated by a conical tip is 1.56 times larger than that generated by a plane tip. However, a plane tip generates a faster acoustic streaming than conical tip [41], which results in better mass transfer. For this reason, and because they are the most commercially available, our simulation adopted a plane tip. Cavitation zones are quantified by using the acoustic pressure derived from Eq. (3) and Eq. (4) to display the attenuation elicited by cavitation bubbles.

## 2.3. Acoustic streaming

Sound waves elicit pressure fluctuations that induce fluid flow, which is referred to as acoustic streaming. US in the range 20 kHz to 20 MHz with power above 0.0004 W [42] in the form of a concentrated beam (horn-type probe) generates a turbulent acoustic stream within the sonicated system. The streaming velocity ( $u$ ) is calculated from the Navier-Stokes equations (Eq. (12) [43,44,45,46].

$$\rho \left( \frac{\delta \vec{u}}{\delta t} + \vec{u} \cdot \nabla \vec{u} \right) = -\nabla \vec{P} + \mu \nabla^2 \vec{u} + \vec{F} \quad (12)$$

Acoustic streaming originates from Bjerkén forces acting on bubbles in an acoustic field. The intensity of these forces depends on the gradient of the acoustic pressure amplitude. Assuming that (i) the volume of the bubbles is constant, (ii) the amplitude below the sonotrode is above 1.8 atm (to achieve transient cavitation) [31,41], and (iii) the pressure wave emitted is a standing wave [16], the volumetric force ( $F$ ) acting on the sonicated system is [41]:

$$F = -\beta \cdot \nabla |P| \quad (13)$$

We incorporated Eq. (13) into Eq. (12) to determine the flow pattern of the acoustic streaming generated upon the application of US. The

pressure gradient calculated through Eq. 4 determines the direction of  $F$ .

When examining velocity, it is important to differentiate between point velocity and surface velocity. Point velocity is the velocity of a fluid at a specific point in the simulation domain. Surface velocity, on the other hand, is the velocity of the fluid along a surface in the simulation domain. While most articles in the literature report the point acoustic streaming velocity, we chose to analyze the surface acoustic streaming velocity for the following reasons:

- Acoustic streaming is heavily influenced by boundary effects, especially when the fluid is contained or near surfaces. Surface velocity directly captures the effects at these boundaries, whereas point velocities may ignore them, especially if the chosen point is away from such boundaries.
- Surface velocities provide an averaged value over the entire surface area, which can help in reducing noise or discrepancies that may be more apparent when considering a single point.
- When comparing results across different setups or experiments, analyzing surface velocities gives a more consistent parameter for comparison. Point velocities may vary significantly based on the precise location of the point, making comparisons less reliable.

#### 2.4. Assumptions of the model

Eq. (3), Eq. (4), and Eq. (12) assume:

- The liquid is incompressible and Newtonian. Because ILs consist of ions, they establish strong Coulombian ionic interactions, which makes them 90 % less compressible than organic solvents. The isothermal compressibility of imidazolium and pyridinium-based ILs is similar to water and molten salts across a wide range of temperature and pressure (298 K–343 K, up to 207 MPa) [47]: the longer the alkyl chain and the higher the temperature, the more compressible the IL. On the contrary, the higher the pressure, the less compressible the ILs become. The bulk modulus of a liquid, which is a measure of its resistance to a change in volume under pressure, is a quantitative indicator of the incompressibility of a liquid. The higher the bulk modulus, the less compressible the liquid. ILs have higher bulk modulus than water and other organic solvents. For example, at atmospheric pressure and room temperature the bulk moduli of 1-ethyl-3-methylimidazolium ethyl sulfate and water are 3.0 GPa [48] and 2.1 GPa [49], respectively.
- The bubble to liquid volume ratio is low so that the cavitation bubbles do not affect the overall behaviour of the fluid.
- The thermodynamic properties of the sonicated fluid are independent from temperature and bubble volume fraction.
- The concentration of bubbles is homogeneous throughout the medium and  $\beta$  ranges between  $10^{-4}$  and  $10^{-1}$ . For  $\beta > 10^{-1}$ , bubbles scatter most of the incident acoustic waves. Hence, considering fractions larger than  $10^{-1}$  does not contribute any meaningful physical significance to the model. The bubble density, hence  $\beta$ , linearly depends on the pressure amplitude, so that  $\beta = C \cdot P$ , where  $C$  is a constant [50,51]. Jamshidi et al., [40] investigated the ultrasonic wave propagation in a sonochemical reactor considering the effect elicited by the inhomogeneous bubble clusters and assumed that  $\beta = 2 \times 10^{-9} \cdot P$ . They validated the model in water and observed a high level of concurrence between the experimental outcomes and their model assuming this  $C$  value. For this investigation, we selected the same constant.
- Ionic liquids are assumed to be saturated with argon gas. Despite the fact that ILs absorb more other gases like  $\text{CO}_2$  [52], monoatomic gases have a higher adiabatic index ( $\gamma = 1.67$  for He, Ne, and Ar,  $\gamma = 2.5$  for Xe vs.  $\gamma = 1.30$  for  $\text{CO}_2$ ), which results in higher temperature during the compression of a bubble that collapses adiabatically [36]. Although less soluble than Kr and Xe, produces more intense

sonochemical events, regardless of bubble type [53]. solubility rates are high enough to create gaseous inclusions and induce acoustic cavitation upon the application of sufficient tensile strength [31]. The saturation of 1-ethyl-3-methylimidazolium acetate with argon originates monodispersed bubbles with a radius  $R_0$  of  $5 \mu\text{m}$  [31]. The equilibrium radius ( $R_{\text{eq}}$ ) considering coalescence is about 50 times  $R_0$  [54]. For this simulation we set  $R_{\text{eq}}$  equal to  $250 \mu\text{m}$ .

- The horn releases the acoustic radiation as Gaussian beams: the displacement amplitude across the face of the transducer plane varies so that it is the greatest in the middle and decreases as the radial distance from the center of the probe increases. In other words, the decrease in amplitude follows a Gaussian mathematical function.

### 3. Simulation

COMSOL Multiphysics 5.5 solved the equations in Paragraph 2 to determine the acoustic pressure distribution with and without bubble attenuation, and the acoustic streaming surface velocity profile. The equations were solved in a 2D axisymmetric configuration to reduce computation time.

The simulation consists of three steps (or studies), each dependent on the previous one:

- The COMSOL Acoustic Module - Pressure Acoustic modelled a continuous wave excitation and solved Eq. (3) in the *Frequency Domain* considering the attenuation of the acoustic pressure arising from the intrinsic properties of the liquid medium ( $\alpha$ ). The study yields the effect of power and pressure amplitude on the acoustic field while neglecting the presence of cavitation bubbles in the medium and it provides an initial estimate for study 2.

$$\alpha = \frac{8\mu\pi^2 f^2}{3\rho c^3} \quad (14)$$

- We included the attenuation due to bubbles by setting the Stabilized Convection-Diffusion Equation equal to Eq. (4) and by defining Eq. (5) to Eq. (10) within the parameters list. We calculated  $\beta$  by using the total acoustic pressure estimated in Study 1. Finally, we determined  $N$  and  $k_m^2$  (Eq. (10) and Eq. (5) and solved Eq. (4) until steady state.

- The COMSOL turbulent flow  $k-\epsilon$  interface simulated the acoustic streaming turbulent jet. It solved the Navier-Stokes equations through a stationary study considering the acoustic pressure gradient derived from Study 2.

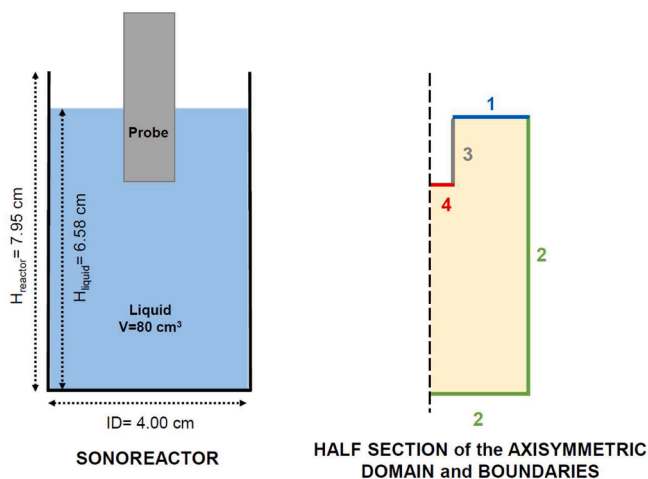
#### 3.1. Geometry and boundary conditions

The sonochemical reactor selected for this study is a 100 mL borosilicate beaker ( $H = 8 \text{ cm}$ ,  $ID = 4 \text{ cm}$ , thickness =  $4.5 \text{ cm}$ ). The ultrasound probe is positioned vertically at the top of the beaker. The sonotrode is made of a titanium alloy, Ti-6Al-4 V, and has a diameter of  $1.30 \text{ cm}$ . The ultrasonic processor selected for the study operates at  $20 \text{ kHz}$ . The simulation domain corresponds to the volume of the sonicated liquid. We maintained the sonicated volume constant at  $80 \text{ mL}$  and the dimensions of the domain varies with the immersion of the probe. For example, with the probe immersed  $2.00 \text{ cm}$ , the dimensions of the domain are  $H = 6.58 \text{ cm}$  and  $ID = 4.00 \text{ cm}$  (Fig. 2fig:reactor).

##### 3.1.1. Boundary conditions for acoustic pressure profile and active regions - studies 1 and 2

Jamshidi et al., [40] and Fang et al., [41] set the liquid-glass and liquid-probe boundaries as hard ( $\frac{\partial P}{\partial x} = 0$  for  $x = 0$ ) and the liquid-air boundary as soft ( $P = 0$  vanishes). However, ultrasound reflects at interfaces with a  $Z$  mismatch. For a given material,  $Z$  corresponds to the product of its density and speed of sound. In this study, we applied the following boundary conditions (Fig. 2fig:reactor):

- At the boundary liquid-air,  $Z = 1.2 \text{ kg/m}^3 \times 343 \text{ m/s}$ .



**Fig. 2.** Sonochemical reactor and half section of the axisymmetric computational domain with boundaries. The domain and the boundaries are an example assuming a liquid volume of 80 mL and for a 1.30 cm diameter probe immersed 2.00 cm.

- At the boundary liquid-glass,  $Z = 2230 \text{ kg/m}^3 \times 5640 \text{ m/s}$  (for Pyrex).<sup>1</sup>
- At the boundary liquid-probe,  $Z = 4470 \text{ kg/m}^3 \times 4987 \text{ m/s}$  (for a Ti-6Al-4 V probe).
- At the tip of the probe, the pressure amplitude ( $P_A$ ) was set to:

$$P_A = \sqrt{\frac{P_{US} 2c\rho}{\pi R_p^2}} \quad (15)$$

where  $P_{US}$  is the ultrasonic power delivered to the system calculated upon calorimetric calibration [55], and  $R_p^2$  is the radius of the sonotrode.

### 3.1.2. Boundary conditions for acoustic streaming - study 3

For the simulation of acoustic streaming, we applied the the following boundary conditions (Fig. 2fig:reactor):

- The liquid-air boundary was set as a pressure outlet with pressure set to 0.
- No-slip boundary condition at the liquid-glass interface.
- Slip boundary condition at the liquid-probe interface.

4. At the tip of the probe, Eq. (15) was set as the pressure inlet with inflow velocity directions ( $x$  and  $z$ ) set to 1.3 and 0.03, respectively. The distance between the piezoelectric and the US emitting tip, which is 5 cm for the probe adopted for this investigation, dictated the inflow velocity direction. The turbulence length scale, which represents the size of the energy-containing eddies in the turbulent flow and depends on the turbulent kinetic energy and turbulent dissipation rate, was set to 0.07  $R_p$ . Trujillo and Knoerzer, determined this correlation and we adopted it for our simulation as it was a suitable fit [56].

### 3.2. Mesh

Upon mesh sensitivity study, we opted for a 2D computational mesh consisting of triangles and quads (Table 1tab:mesh). We set the

<sup>1</sup> Considering the thinness of conventional beakers, it would be more fitting to adopt the acoustic impedance of air at the interface between the liquid and glass. However, this study primarily aimed to identify ionic liquids that maximize the active region volume for a separate ongoing project within our research group. In this project, we utilize an unconventional reactor with walls approximately five times thicker than traditional beakers. Consequently, we have chosen to define the acoustic impedance of the borosilicate glass at the reactor walls.

**Table 1**

Meshing specifics for the three probe immersion depths.

Probe immersion	Triangles	Quads	Mesh area
cm			cm <sup>2</sup>
0.5	5274	755	12.52
1	5189	760	12.29
2	5067	770	11.86

maximum dimension of each mesh element to be less than 1/8 of the ultrasound wavelength ( $\lambda_{1/8, H_2O} = 0.92 \text{ cm}$  and  $\lambda_{1/8, IL} = 0.80 \text{ cm}$  to 1.15 cm [33]). We chose a fluid dynamics *normal mesh* for the domain (maximum size 0.09 cm, minimum size 0.004 cm, curvature factor 0.3, growth rate 1.15), and a fluid dynamics *finer mesh* (maximum size 0.056 cm, minimum size  $8 \times 10^{-4} \text{ cm}$ , curvature factor 0.25, growth rate 1.10) along boundaries 2, 3 and 4 (Fig. 2fig:reactor).

The solution of Eq. (3) requires approximating the solution using a set of discrete points. For study 1 and study 2, we applied a quadratic Lagrange discretization as it provides a more detailed approximation of the solution, hence higher accuracy. For study 3, we applied a P2 + P1 fluid discretization (second order elements for velocity and first order elements for pressure) to solve the Reynolds-averaged Navier-Stokes equations as it captures the behaviour of fluid flow more accurately than other numerical methods [57].

## 4. Ionic liquids and design of experiments

For this study, we selected twelve imidazolium- and pyrrolidinium-based ILs (Table 2tab:ILs) based on an acidity criterion that is of interest for a few ongoing investigations in our research group.

### 4.1. Prediction the thermodynamic properties of of ILs

Some of the thermodynamic properties of the ILs under investigation – specifically the isobaric specific heat capacity ( $C_p$ ), speed of sound ( $c$ ), density ( $\rho$ ), surface tension ( $\sigma$ ), and dynamic viscosity ( $\mu$ ) – have been determined experimentally and are available in the literature. Nevertheless, we predicted the thermodynamic properties for all the ILs with Conductor like Screening Model for Real Solvents (COSMO-RS) [18,58,59,60], group contribution method (GCM) [61,62], or via machine learning (ML) algorithms [63,64]. We compared the predicted values with the experimental ones and determined the root mean square deviation (RMSD) to identify flaws and further refined the prediction algorithms.

**Table 2**

The twelve ILs chosen for this study and their molar mass.

IL	Cation	Anion	Molar mass
[Etmim][Ac]	1-Ethyl-3-methylimidazolium	Acetate	170.2
[Etmim][Cl]	1-Ethyl-3-methylimidazolium	Chloride	146.6
[Etmim][MeSO <sub>4</sub> ]	1-Ethyl-3-methylimidazolium	Methyl sulfate	222.3
[Bmim][Ac]	1-Butyl-3-methylimidazolium	Acetate	198.3
[Bmim][Cl]	1-Butyl-3-methylimidazolium	Chloride	174.7
[Bmim][MeSO <sub>4</sub> ]	1-Butyl-3-methylimidazolium	Methyl sulfate	250.3
[Pyr][Ac]	Pyrrolidinium	Acetate	131.2
[Pyr][Cl]	Pyrrolidinium	Chloride	107.6
[Pyr][H <sub>2</sub> SO <sub>4</sub> ]	Pyrrolidinium	Hydrogen sulfate	169.2
[SPMim][Cl]	1-Methyl-3-(3-sulfopropyl)-imidazolium	Chloride	242.7
[SPMim][H <sub>2</sub> SO <sub>4</sub> ]	1-Methyl-3-(3-sulfopropyl)-imidazolium	Hydrogen sulfate	304.3
[SPMim][PTS]	1-Methyl-3-(3-sulfopropyl)-imidazolium	<i>p</i> -Toluene sulfonate	378.5

COSMO-RS predicted  $C_p$  (1 % ≤ RMSD ≤ 23 %),  $\mu$  (RMSD ≫ 10 %), and  $\rho$  (0.4 % ≤ RMSD ≤ 2.4 %). A ML algorithms determined  $\sigma$  (RMSD ≤ 2 %) and  $c$  (RMSD ≤ 1 %). The GCM developed by Sattari et al., [65] predicted  $C_p$  (3 % ≤ RMSD ≤ 38 %). The GCMs by Lazzús et al., [66] and Gharagheizi et al., [61] predicted  $\mu$  (RMSD ≤ 1 %). The elevated RMSD for  $C_p$  and  $\mu$  only concerned protic ILs (e.g. [Pyr][Ac]). High deviations stem from factors such as the proton transfer from acid to base, the pH of the acid/base, the proton affinity, and the presence of neutral molecules and ions in the mixture.

For the simulations, we adopted the experimental thermodynamic properties whenever available, and the predicted ones with the lowest deviations for those unavailable in literature (Table 3tab:ILsparam).

## 5. Design of experiments and statistical analysis

The dependant variables of this study are:

- the ultrasound power,  $P_{US}$ , three levels – 20 W (250 W/L), 40 W (500 W/L), 60 W(750 W/L)
- the probe immersion,  $d$ , three levels – 0.5 cm, 1 cm, 2 cm
- and the thermodynamic properties of the twelve ILs (Table 3tab:ILsparam)

The response variables are the minimum and maximum acoustic pressure generated ( $P_{min}$  and  $P_{max}$ ), the volume of the acoustically active regions ( $V$ ), and the magnitude of the maximum acoustic streaming surface velocity ( $u$ ).

We opted for a full factorial design, for a total of 108 simulations. We conducted a statistical analysis to establish patterns and relationships within the data. To identify the key dependant variables that affect our response variables, we ran a preliminary predictor screening analysis with bootstrap forest partitioning (BFP). BFP algorithms randomly select subset of data and create multiple decision trees (100 trees in this instance) with aleatory features, and then take the average of all the tree's predictions. BFP reduces the chance of overfitting and improves the accuracy of the final prediction. According to the results of the predictor screenings, we then eliminated the non-significant dependant variables to find the model that predicted the response variables with an accuracy within a 95 % confidence interval (CI).

For the sake of clarity, in the Actual vs Predicted plots in the 'Results and discussion' paragraph, the term *actual* refers to the simulated data points that were used to develop the prediction equation.

**Table 3**  
Thermodynamic properties of water and ILs.

	$C_p^*$	$c$	$\rho$	$\sigma$	$\mu$	$T_{ref}$
	J kg <sup>-1</sup> K <sup>-1</sup>	m s <sup>-1</sup>	kg m <sup>-3</sup>	mN m <sup>-1</sup>	mPa s <sup>-1</sup>	K
Water**	4184 <sup>E</sup>	1498 <sup>E</sup>	1000.0 <sup>E</sup>	71.99 <sup>E</sup>	1.00 <sup>E</sup>	298.15
[Etmim][Ac]	1897 <sup>E</sup>	1721 <sup>M</sup>	1101.4 <sup>E</sup>	38.17 <sup>E</sup>	93.0 <sup>E</sup>	298.15
[Etmim][Cl]	1955 <sup>C</sup>	1854 <sup>M</sup>	1123.9 <sup>E</sup>	49.23 <sup>M</sup>	65.0 <sup>E</sup>	353.15
[Etmim][MeSO <sub>4</sub> ]	1568 <sup>C</sup>	1770 <sup>M</sup>	1284.2 <sup>E</sup>	52.66 <sup>M</sup>	78.8 <sup>E</sup>	298.15
[Bmim][Ac]	1854 <sup>C</sup>	1650 <sup>M</sup>	1062.2 <sup>E</sup>	35.31 <sup>E</sup>	293.0 <sup>E</sup>	298.15
[Bmim][Cl]	1963 <sup>C</sup>	1802 <sup>M</sup>	1055.7 <sup>E</sup>	46.38 <sup>E</sup>	123.0 <sup>E</sup>	343.15
[Bmim][MeSO <sub>4</sub> ]	1613 <sup>C</sup>	1676 <sup>M</sup>	1212.2 <sup>E</sup>	42.44 <sup>M</sup>	213.9 <sup>E</sup>	298.15
[Pyr][Ac]	1896 <sup>C</sup>	1607 <sup>M</sup>	1121.3 <sup>E</sup>	33.50 <sup>M</sup>	90.4 <sup>C</sup>	298.15
[Pyr][Cl]	1912 <sup>C</sup>	1761 <sup>M</sup>	1178.6 <sup>C</sup>	56.08 <sup>M</sup>	1379.6 <sup>G</sup>	298.15
[Pyr][H <sub>2</sub> SO <sub>4</sub> ]	1529 <sup>C</sup>	1545 <sup>G</sup>	1424.1 <sup>E</sup>	50.51 <sup>M</sup>	321.8 <sup>C</sup>	298.15
[SPMim][Cl]	1527 <sup>C</sup>	1752 <sup>M</sup>	1287.5 <sup>C</sup>	38.42 <sup>M</sup>	3921.0 <sup>G</sup>	298.15
[SPMim][H <sub>2</sub> SO <sub>4</sub> ]	1392 <sup>C</sup>	1647 <sup>M</sup>	1395.3 <sup>C</sup>	40.73 <sup>M</sup>	1304.5 <sup>C</sup>	298.15
[SPMim][PTS]	1451 <sup>C</sup>	1519 <sup>M</sup>	1269.5 <sup>C</sup>	46.03 <sup>M</sup>	7113.1 <sup>C</sup>	298.15

\*Isobaric, \*\*Distilled, <sup>E</sup>Experimental [67], <sup>C</sup>COSMO-RS [18,58,59,60], <sup>G</sup>GCM, <sup>M</sup>ML[63,64].

## 6. Experimental validation of the model

To visualize the sonochemically active regions and acoustic streaming and validate the model, we conducted sonochemiluminescence (SCL) experiments in a dark room [17]. A 20 kHz and 500 W nominal power US processor from Sonics & Materials Inc. with a 13 mm replaceable tip Ti-6Al-4 V probe (115 μm displacement amplitude) sonicated 80 mL of liquid in a 4 cm ID x 7.5 cm H glass reactor.

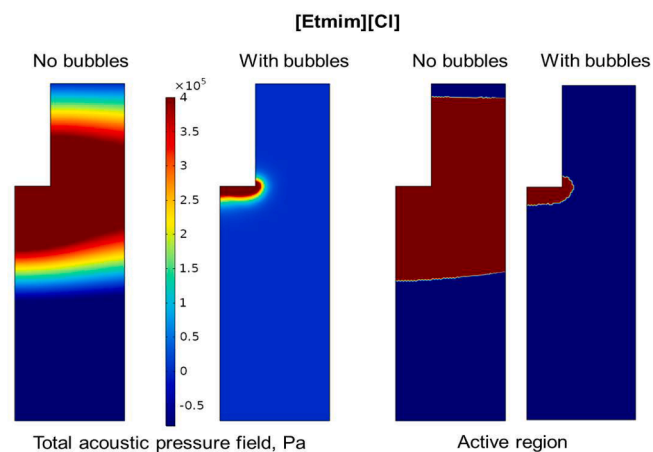
We conducted experiments in water (at 298 K) and in [Bmim][Cl] (at 343 K). SCL in water required the addition of 0.15 g/L of 5-amino-2,3-dihydro-1,4-ftalazindione (Luminol, 97 %, Sigma Aldrich) and 4 g/L of sodium hydroxide (, 98 %, Sigma Aldrich). SCL in [Bmim][Cl] utilized 50 g of IL and 30 mL of a 0.20 g/L luminol and 4 g/L of solution. Luminol reacts with the hydroxyl radicals generated through water sonolysis and oxidizes to 3-aminophthalate in its excited state (3-APA\*). 3-APA\* then relaxes to 3-APA by emitting visible sonochemiluminescent blue light at a wavelength of 425 nm.

A Fujifilm X-T1 exposure-controlled digital camera and a lens with 56 mm focal length acquired SCL images with a shutter speed of 2 s and a F1.2 diaphragm aperture (sensitivity ISO1600). We processed the images and measured the intensity of blue light emission signals with respect to the position in the sonoreactor. MATLAB (The Mathworks Inc., USA) subtracted the blank obtained in silent conditions (no background light) from the acquired SCL picture, and concealed parasite pixels with a blue filter. The software retained pixels with a light intensity above a 25/255 threshold. The lower threshold of 25 is the intensity of the blue light of the pixels in silent conditions, which corresponds to the background noise signal in the camera's blue channel. The upper threshold of 255 is the saturation of the 8-bits SCL images.

## 7. Results and discussion

### 7.1. Acoustic attenuation

Cavitation bubbles accumulate at the tip of the sonotrode and locally absorb and scatter sound waves, thereby reducing the cavitation intensity [34,35]. Neglecting the presence of bubbles results in higher acoustic pressure and larger active region volumes, as there is no attenuation of the acoustic wave travelling throughout the reactor (Fig. 3fig:bubbles). The absolute difference between  $V$  calculated neglecting acoustic attenuation and  $V$  computed by considering the presence of bubbles ranges between 161 % and 197 %. These results



**Fig. 3.** Profiles of acoustic pressure field and active volume regions for [Etmim][Cl] at 60 W and  $d = 2$  cm. Comparison between simulations with (profiles on the right) and without (profiles on the left) acoustic attenuation elicited by cavitation bubbles. For [Etmim][Cl], the volumes of the active regions differ by 193 %.



demonstrate the significant impact that cavitation bubbles elicit on acoustic fields and active region sizes, highlighting the importance of accounting for their presence in models.

## 7.2. Acoustic pressure - $P_{max}$ and $P_{min}$

Positive pressure and negative pressure during acoustic cavitation refer to the pressure increase and decrease, respectively, in the liquid as the sound wave propagates. Cavitation bubbles grow under positive pressure, while they collapse and release energy in the form of shock waves, heat, and light under negative pressure.  $P_{max}$  and  $P_{min}$  are the maximum and minimum acoustic pressure in the reactor, respectively.

The regression analysis of the simulation data (Fig. 4fig:APmaxreg) yielded the following equation for  $P_{max}$ :

$$P_{max} = 49.1 \cdot 10^4 + 11.5 \cdot 10^3 \cdot P_{US} \cdot \rho + 736.3 \cdot \sigma \quad (16)$$

$P_{max}$  localizes under the sonotrode tip and it increases with the increase of  $P_{US}$ ,  $\rho$ , and  $\sigma$  (Eq. (16)).  $C_p$ ,  $c$ ,  $d$ , and  $\mu$  do not have a significant effect on the magnitude of  $P_{max}$  within the reactor as they account for less than 0.5 % of the variance (Table 4tab:APmaxreg).

The behaviour of  $P_{min}$  is more complex and difficult to describe than that of  $P_{max}$ . Hence, we divided the dataset in two groups based on their  $\mu$ . For ILs with  $\mu \geq 1$  Pa s (high viscosity, HV), the regression (Fig. 5fig:APminHVreg) yielded the following equation:

$$P_{min,HV} = -38.8 \cdot 10^3 + 80.2 \cdot 10^3 \cdot \exp\left(\frac{-\mu \cdot \rho \cdot \sqrt{C_p}}{19.2 \cdot 10^4}\right) - 18.7 \cdot 10^3 \cdot \sqrt{\frac{P_{US} \cdot \sigma}{c}} \quad (17)$$

$P_{min}$  decreases (becomes more negative) as  $\mu$ ,  $\rho$ ,  $C_p$ , and  $c$  increase, and as  $P_{US}$  and  $\sigma$  decrease (Eq. (17)).  $d$  explains less than 0.5 % of the variance and is insignificant (Table 5tab:APminHVreg).

For ILs with  $\mu < 1$  Pa s (low viscosity, LV), the regression (Fig. 6fig:APminLVreg) provided the following equation:

$$P_{min,LV} = \frac{-4.15 \cdot 10^{-4} \cdot d \cdot (P_{US})^{0.53}}{-0.49 + d} \quad (18)$$

$P_{min,LV}$  decreases as  $d$  and  $P_{US}$  decrease, and as  $\rho$  increases.  $\mu$ ,  $\sigma$ ,  $c$ , and  $C_p$  account for less than 2 % of the variance each and their contribution to the prediction of  $P_{min,LV}$  is statistically insignificant ( $p$ -value  $> 0.05$ ) (Table 6tab:APminLVreg).

The magnitude of acoustic pressure is directly proportional to the speed of sound in a given medium.  $c$  determines how quickly the sound waves travel through the medium. As  $c$  increases, the particles in the

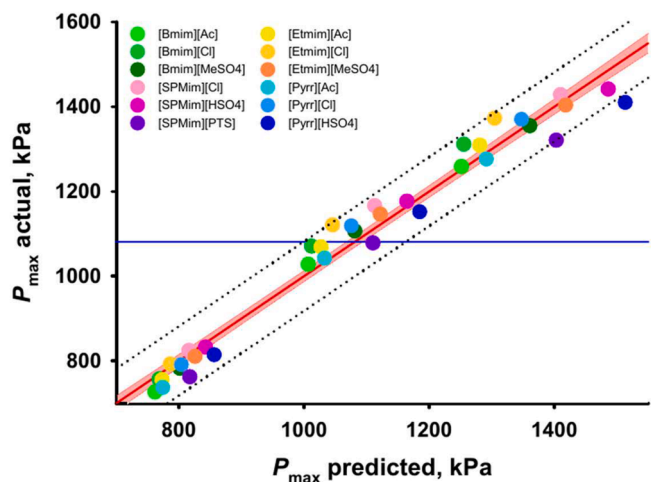


Fig. 4. Actual by Predicted plot of  $P_{max}$ , ■ Regression, ■ 95 % CI of prediction, RMSE = 40647.8,  $R^2 = 0.972$ ,  $p$ -value  $< 0.0001$ , ■ Mean of response (1080 kPa), ● ● ● Prediction interval.

Table 4

$P_{max}$  predictor screening. Statistic significance in descending order. \*Portion of the variance explained by the predictor.

Predictor	Portion*
$P_{US}$	95.5 %
$\rho$	3.0 %
$\sigma$	0.7 %
$C_p$	0.3 %
$c$	0.2 %
$d$	0.2 %
$\mu$	0.1 %

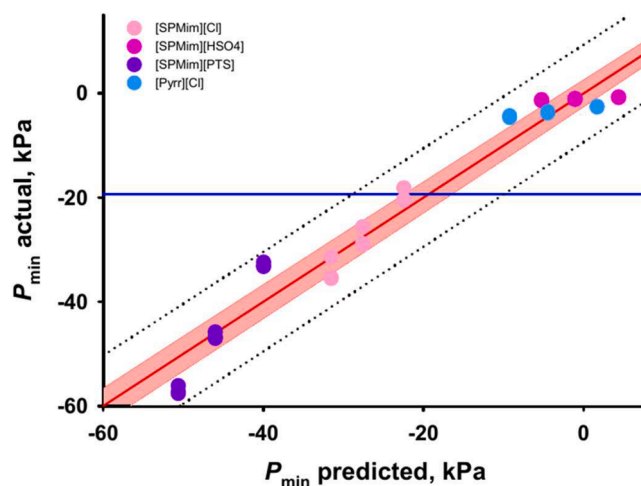


Fig. 5. Actual by Predicted plot of  $P_{min}$  for ILs with  $\mu \geq 1$  Pa s. ■ Regression, ■ 95 % CI of prediction, RMSE = 4294,  $R^2 = 0.955$ ,  $p$ -value  $< 0.0001$ , ■ Mean of response (-19.34 kPa), ● ● ● Prediction interval.

Table 5

Predictor screening analysis of  $P_{min}$  for ILs with  $\mu \geq 1$  Pa s. Statistic significance in descending order. \*Portion of the variance explained by the predictor.

Predictor	Portion*
$\mu$	24.5 %
$\sigma$	24.2 %
$\rho$	19.0 %
$C_p$	18.5 %
$P_{US}$	7.7 %
$c$	5.8 %
$d$	0.3 %

medium vibrate more rapidly in response to the acoustic wave. More frequent vibrations increase the magnitude of acoustic pressure. Similarly, as the input  $P_{US}$  increases, so does the amount of energy transferred to the liquid: the magnitude of the generated sound waves - hence acoustic pressure - increases.

Despite having insignificant effects on  $P_{max}$ ,  $\mu$  substantially affects  $P_{min}$ . The higher the  $\mu$  of a liquid, the larger the negative pressure required to break the cohesive forces keeping the liquid molecules together [68]. When the negative pressure exceeds the tensile strength of the liquid, the distance between molecules surpasses the critical molecular distance necessary to hold the liquid intact and cavitation bubbles form. High viscosity ILs, namely [SPMim]-based ILs, require lower  $P_{min}$  to cavitate. For example, [SPMim][PTS] ( $\mu = 7113.1$  mPa s<sup>-1</sup>) requires -56 kPa—58 kPa to cavitate at 60 W. On the contrary, [Etmim][MeSO<sub>4</sub>] ( $\mu = 78.8$  mPa s<sup>-1</sup>) needs  $8.21 \times 10^{-8}$  Pa—0.46 Pa to cavitate under the same conditions. Moreover, denser liquids have

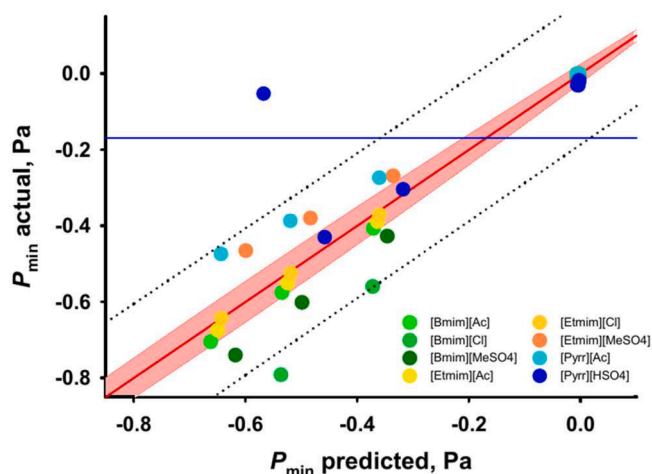


Fig. 6. Actual by Predicted plot of  $P_{\min}$  for ILs with  $\mu < 1$  Pa s. ■ Regression, ■ 95 % CI of prediction, RMSE = 0.1057,  $R^2 = 0.877$ , p-value < 0.0001, ■ Mean of response (-0.1813 Pa), ● ● ● Prediction interval.

Table 6

Predictor screening analysis of  $P_{\min}$  for ILs with  $\mu < 1$  Pa s. Statistic significance in descending order. \*Portion of the variance explained by the predictor.

Predictor	Portion*
$d$	86.0 %
$P_{US}$	3.9 %
$\rho$	3.9 %
$\mu$	1.9 %
$\sigma$	1.7 %
$c$	1.2 %
$C_p$	1.1 %

higher  $Z$  and require higher energy inputs to cavitate. This translates into cavitation bubbles requiring larger negative acoustic pressure to collapse in high density ILs.

The specific heat capacity indirectly affects the magnitude of acoustic pressure. When  $C_p$  increases, it becomes harder to compress the medium through which the sound waves are travelling:  $c$  increases and so does the amplitude of the sound waves, resulting in a higher magnitude of acoustic pressure.

The surface tension represents the strength of the cohesion forces that oppose the pressure variation during the compression and expansion phases of an acoustic cycle. When  $\sigma$  decreases, the attractive forces between the molecules at the surface decrease, which means that external forces easily displace the liquid. If  $\sigma$  is high, cavitation bubbles require more energy to expand and contract, and hence the amplitude of the sound wave will be lower. Conversely, if  $\sigma$  is low, the bubbles require less energy to expand and contract, resulting in a higher amplitude of the sound wave and therefore a higher  $P_{\max}$ . Nevertheless,  $\sigma$  appeared to have insignificant effects (p-value > 0.05) on  $P_{\min}$  at  $\mu < 1$  Pa s.  $d$  does not have a significant effect on the magnitude of neither  $P_{\max}$  nor  $P_{\min,HV}$ , but it accounts for a large portion of the variance when  $\mu < 1$  Pa s.

### 7.3. Active region volume $V$

The non-linear regression analysis of the simulated data (Fig. 7fig: ARVreg) yielded the following equation for the volumes of the active regions: Fig. 8.

$$V = 0.12 + 0.11 \cdot \exp\left(\frac{-\mu}{3845.19}\right) \cdot (P_{US})^{0.41} \cdot \left(\frac{C_p}{c}\right)^{-0.27} \cdot (d)^{0.13} \quad (19)$$

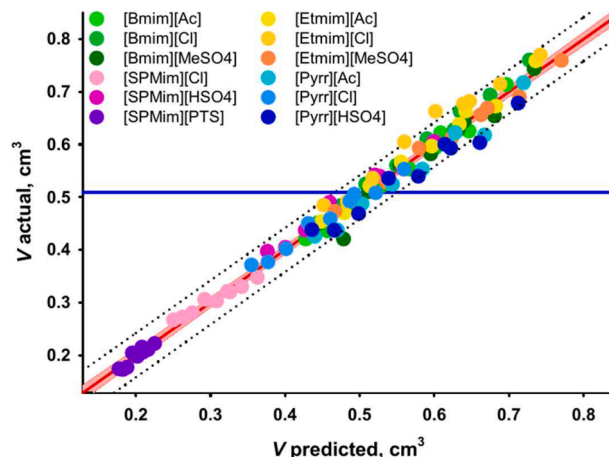


Fig. 7. Actual by Predicted plot of  $V$ . ■ Regression, ■ 95 % CI of prediction, RMSE = 0.0204,  $R^2 = 0.982$ , p-value < 0.0001, ■ Mean of response (0.50  $\text{cm}^3$ ), ● ● ● Prediction interval.

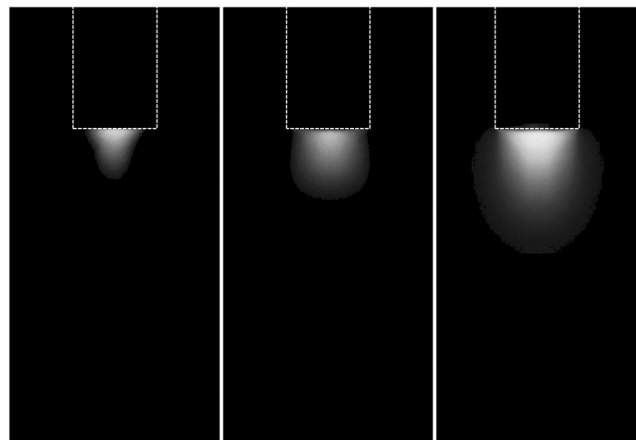
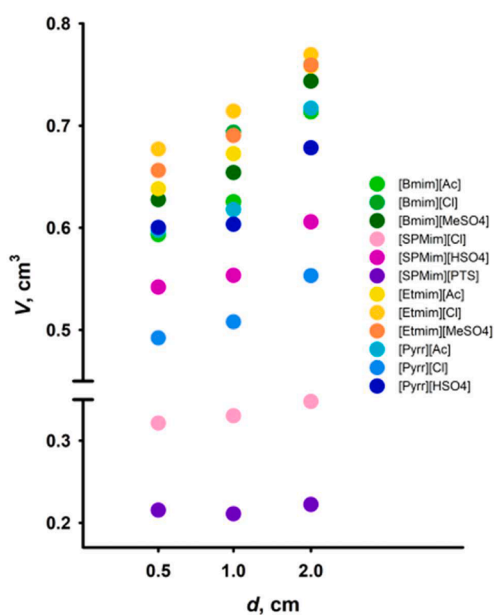
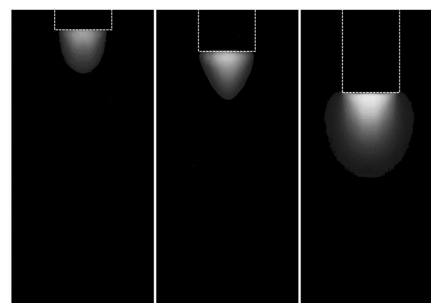


Fig. 8. SCL images in [Bmim][Cl] at 20 W (left), 40 W (center), and 60 W (right), with the probe immersed 2 cm. The dashed line represents the probe.  $V$  and  $u$  increase as  $P_{US}$  increases.

$V$  increases as  $P_{US}$ ,  $d$ , and  $C_p/c$  increase, and as  $\mu$  decreases (Eq. (19)). The intensity of US increases with the increase of input  $P_{US}$ . When the number of acoustic pressure cycles increases, cavitation bubbles become larger and more numerous, which then collapse more frequently and intensely, leading to larger  $V$  (Fig. 4fig:SCL\_IL).

In water, the immersion depth of a 0.3 cm diameter probe does not affect the size of the cavitation region when exposed to  $P_{US}$  from 20 W to 60 W [69]. Instead, Fattahi et al., demonstrated that a 1.9 cm diameter probe at moderate power of 70 W (424 W/L power density) originates active zones below the probe and around its neck, resulting in larger  $V$  and higher cavitation yields [17]. Despite having the same probe, their sonicated volumes were 62 % and 106 % larger than in our study. In ILs, the active regions formed only under the sonotrode tip and  $V$  increased with  $d$  for all the ILs (Fig. 9afig:ARVsPI and Fig. 9bfig:SCL\_IL2). When the immersion depth increases, the hydrostatic pressure of the liquid surrounding the probe increases, causing  $P_c$  to increase as well. This, in turn, implies that the same intensity of ultrasound will subject a larger volume of liquid to cavitation. Moreover, the faster the sound waves travel through the medium (high  $c$ ), the quicker and with greater magnitude the temperature and pressure change throughout the medium. This results in more rapid cavitation at lower pressures and in regions where cavitation might not otherwise occur, hence larger  $V$ .

On the contrary, changes in  $\mu$  affect bubbles' size and distribution,

(a)  $V$  vs  $d$  at 60 W.(b) Images of SCL in [Bmim][Cl] at 60 W with the probe immersed 0.5 cm (left), 1 cm (center), and 2 cm (right).  $V$  and  $u$  increase as  $d$  increases.Fig. 9. There is a positive correlation between  $V$  and  $d$ , with a more pronounced enlargement when  $d$  increases from 1 cm to 2 cm.

hence wave attenuation [70]. The pressure fluctuations in viscous liquids are more gradual, leading to less shock waves and energy release during acoustic cavitation, resulting in smaller  $V$  (Fig. 10fig:ILvsH2O). The higher the  $c$  and the lower the  $\mu$  of the ionic liquid, the larger the  $V$ . At 60 W and  $d = 2$  cm,  $V$  was the largest for [Etmim][Cl] ( $0.77 \text{ cm}^3$ ) and the smallest for [SPMim][PTS] ( $0.22 \text{ cm}^3$ ) (Fig. 11fig:ARVbubbleplot).

For comparison, water is 65x and 7113x less viscous than [Etmim][Cl] and [SPMim][PTS], respectively. At 60 W and  $d = 2$  cm, the  $V$  of water is 160 % and 800 % larger than that of [Etmim][Cl] and [SPMim][PTS], respectively.

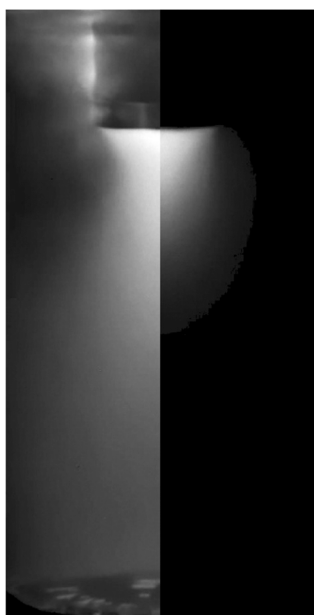


Fig. 10. Comparison between SCL images in water (left side) and [Bmim][Cl] (right side) at 60 W and  $d = 2$  cm.  $V_{\text{H}_2\text{O}}$  is 163 % larger than  $V_{[\text{Bmim}][\text{Cl}]}$ . The brighter areas at the bottom of the reactor in the SCL images in water are a result of light reflection caused by engraving on the bottom of the reactor. In water, active regions form around the neck of the probe.

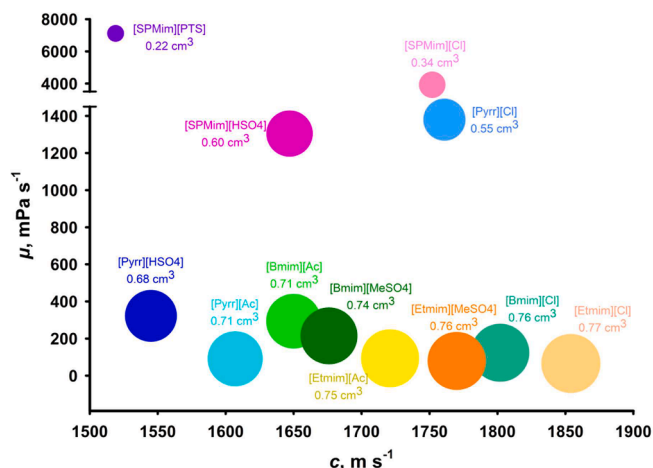


Fig. 11. Bubble plot representing the relationship between ILS'  $\mu$  and  $c$ , with the bubble size representing  $V$  at 60 W and  $d = 2$  cm. As  $c$  increases, the volume of cavitation active regions also increases, particularly for fluids with lower  $\mu$ .

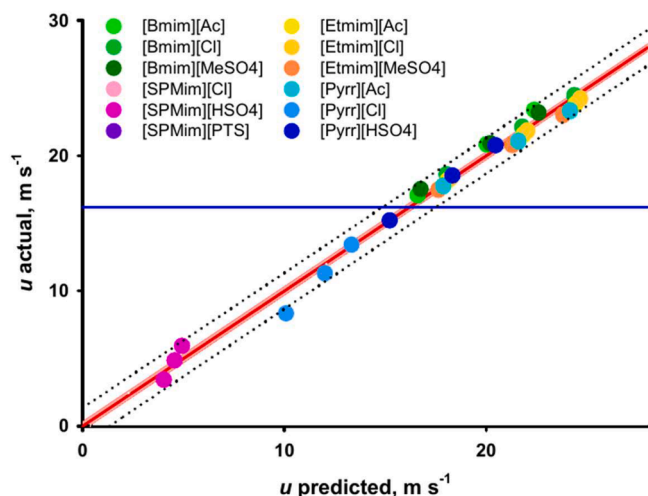
Similarly to what described in the previous section, the collapse of a bubble in a low- $\sigma$  liquid produces a more violent collapse due to the lower cohesive forces holding the liquid molecules together at the surface. Contrary to what expected,  $\rho$  positively correlates with  $V$ . When  $\rho$  increases, the pressure required to cause cavitation also increases. This is because cavitation occurs when the local pressure in the liquid falls below the vapour pressure of the liquid, which is related to its density. Therefore, a denser liquid requires a higher pressure to achieve the same level of cavitation.  $\sigma$  and  $\rho$  did not have a significant effect on the volume of the active regions within the reactor and each accounted for less than 1.5 % of the variance (Table 7tab:ARVreg).

#### 7.4. Maximum acoustic streaming surface velocity $u$

The regression analysis (Fig. 12fig:ASVreg) yielded the following equation for the maximum acoustic streaming surface velocities:

**Table 7**  
Predictor screening analysis of  $V$ . Statistic significance in descending order. \*Portion of the variance explained by the predictor.

Predictor	Portion*
$\mu$	58.7 %
$P_{US}$	23.6 %
$C_p$	8.2 %
$c$	3.8 %
$d$	3.3 %
$\sigma$	1.3 %
$\rho$	1.1 %



**Fig. 12.** Actual by Predicted plot of  $u$ . ■ Regression, ■ 95 % CI of prediction, RMSE = 0.6478,  $R^2 = 0.992$ ,  $p$ -value < 0.0001, ■ Mean of response (16.25  $m s^{-1}$ ), ●●● Prediction interval.

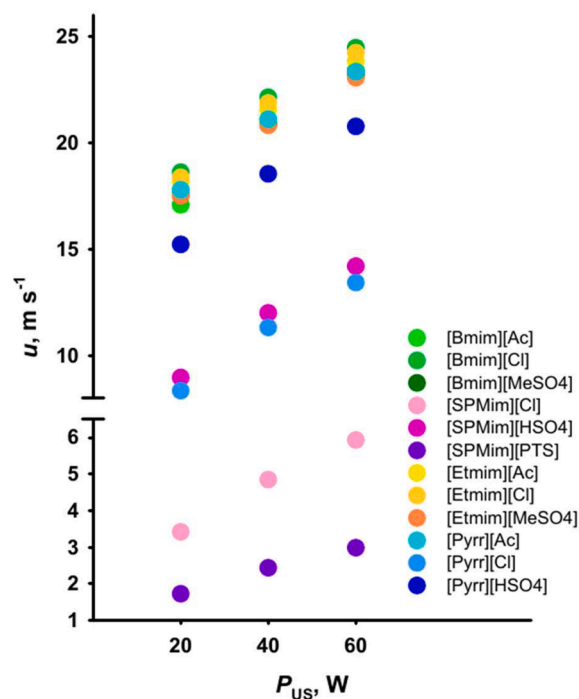
$$u = 1.7 + 6.3 \cdot \exp\left(-\frac{\mu \cdot \rho^{-0.06}}{0.2 \cdot 10^4}\right) \cdot \left(\frac{P_{US}}{c}\right)^{0.3} \cdot \left(\frac{c}{\rho}\right)^{0.4} \cdot \left(\frac{C_p}{\rho}\right)^{-0.07} \quad (20)$$

$u$  increases as  $P_{US}$ ,  $c$ , and  $C_p$  increase, and as  $\mu$  and  $\rho$  decrease (Eq. (20)). As  $P_{US}$  increases, so does the gradient of the acoustic pressure amplitude (primary acoustic radiation force), which results in more intense Bjerknes forces, hence higher  $u$ . Acoustic waves also interact with the acoustic streaming flow (secondary acoustic radiation force), which contributes to the increase in  $u$  with increasing  $P_{US}$  (Fig. 13).

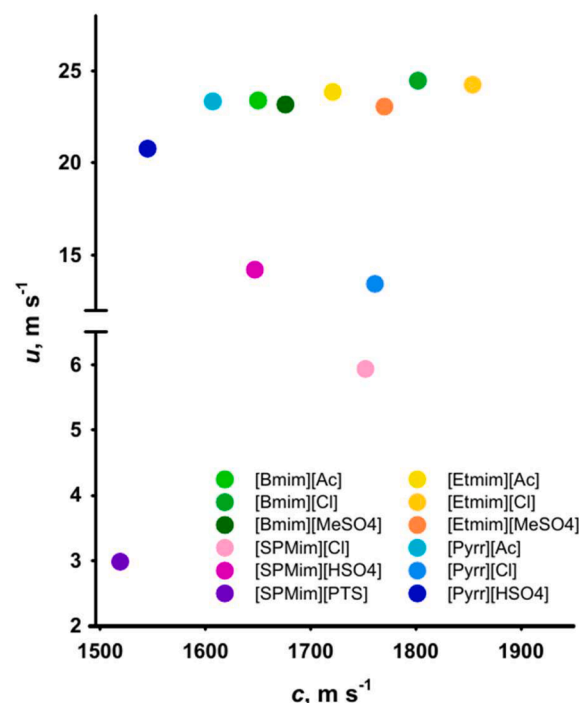
When  $c$  increases, the wavelength of the acoustic wave also increases, which leads to a larger acoustic radiation force and a stronger acoustic streaming flow. As mentioned before,  $C_p$  affects the amplitude of sound waves. When  $C_p$  increases, the medium through which sound waves travel becomes less compressible, which results in an increase of the amplitude of waves and higher  $c$ . [Etmim][Cl] and [Bmim][Cl] have the highest  $c$  and generated the fastest acoustic jets with maximum surface velocities of about 24  $m s^{-1}$  (Fig. 14fig:ASVvsc). Similarly, because the acoustic pressure amplitude and gradient are both proportional to the density of the fluid, the primary acoustic radiation force is also proportional to the density of the fluid. Therefore, a higher  $\rho$  of the liquid medium leads to a stronger acoustic radiation force and a higher  $u$ .

On the contrary,  $u$  decreases as  $\mu$  increases (Fig. 15fig:ASV\_20W). Like for  $V$ , the more gradual pressure fluctuations in viscous liquids lead to less intense shock waves formation and energy release during bubbles collapse, resulting in smaller jets with lower  $u$ . In fact, [SPMim]-based ILs, which all have viscosity above 1300  $mPa s^{-1}$ , yielded the lowest maximum streaming velocity, ranging from 1.7  $m s^{-1}$  to 14.2  $m s^{-1}$ .

$\sigma$  and  $d$  did not have a significant effect on the magnitude of  $u$  within the reactor and they account for less than 0.2 % of the total variance



**Fig. 13.**  $u$  vs  $P_{US}$  at  $d = 2$  cm.



**Fig. 14.**  $u$  vs  $c$  at 60 W and  $d = 2$  cm.

(Table 8).

## 8. Conclusions

Conducting experiments to study acoustic cavitation in liquid media other than water can be costly, particularly when a significant number of variables are involved in the experimental design. In such cases, numerical modelling has emerged as a particularly useful approach, as it enables the investigation of a vast array of parameters at a fraction of the

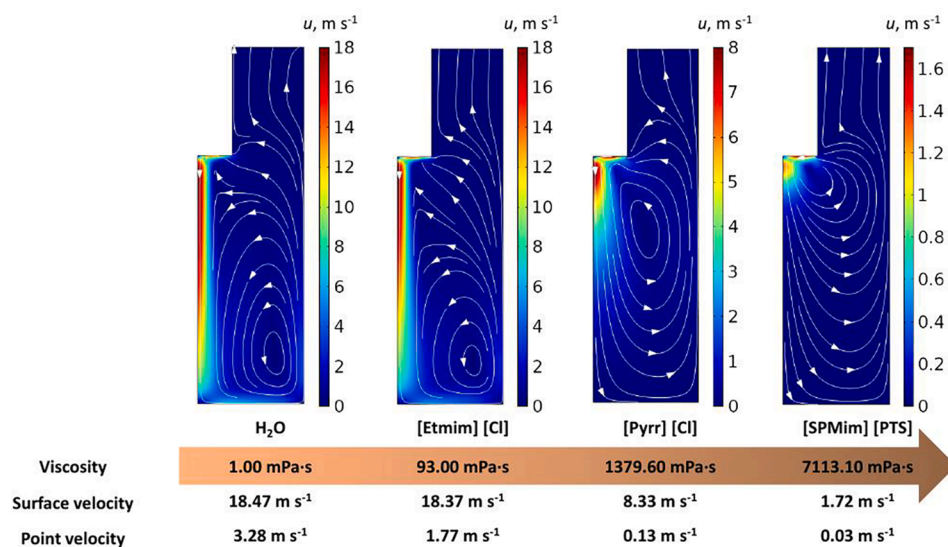


Fig. 15.  $u$  of water, [Etmim][Cl], [Pyrr][Cl], and [SPMim][PTS] at 20 W and  $d = 2$  cm.  $u$  decreases with the increase of  $\mu$ .

Table 8

Predictor screening analysis of  $u$ . Statistic significance in descending order. \*Portion of the variance explained by the predictor.

Predictor	Portion*
$P_{us}$	56.25 %
$\mu$	26.4 %
$c$	8.2 %
$C_p$	6.0 %
$\rho$	2.7 %
$\sigma$	<0.1 %
$d$	<0.1 %

cost. In this study, we characterized the acoustic cavitation in twelve ILs in a horn-type ultrasound reactor. We developed a model that takes into account the presence of numerous cavitation bubbles in the sonicated medium. The model incorporates the acoustic impedance mismatch at the geometrical boundaries of the simulation domain, and treats the ILs as incompressible, Newtonian, and saturated with argon. The experimental design studied the effect of ultrasound input power, probe immersion depth, and five ILs' thermodynamic properties on the acoustic pressure field, the volume of the active regions, and on the velocity of the acoustic streaming jet. The present study is the first to consider a large number of ionic liquids with such a diverse range of thermodynamic properties. A predictor screening analysis determined the portion of the variance explained by each independent variable. The non-linear regression of the simulation data provided five equations correlating acoustic pressure, active region volume, and streaming velocity to the variables contributing the most to the variance of the dataset. Viscosity is the most significant thermodynamic property on all the response variables except the maximum acoustic pressure. The US input power is significant on all variables but the minimum acoustic pressure. Specifically, the volume of the active regions and the magnitude of the acoustic streaming field increase with the increase of ultrasound power and the decrease of viscosity, whereas the magnitude of the minimum acoustic pressure increases with ultrasound power and viscosity. Probe immersion depth positively correlates with the active region volume and negative acoustic pressure at low viscosity, but its impact on the maximum acoustic streaming surface velocity and maximum acoustic pressure is insignificant ( $p$ -value  $> 0.05$ ). 1-ethyl-3-methylimidazolium- and 1-butyl-3-methylimidazolium-based ILs yielded the largest active region volumes and the fastest acoustic jets. At 60 W and  $d = 2$  cm, [Etmim][Cl] generates  $V = 0.77$  cm<sup>3</sup> and  $u = 24.2$  m s<sup>-1</sup>, while [Bmim]

[Cl] produces  $V = 0.76$  cm<sup>3</sup> and  $u = 24.4$  m s<sup>-1</sup>. 1-methyl-3-(3-sulfo-propyl)-imidazolium-based ILs generated the smallest active region volumes and lowest maximum acoustic streaming surface velocities – 0.17 cm<sup>3</sup> and 1.72 m s<sup>-1</sup> for [SPMim][PTS] at 20 W. Sonochemiluminescence experiments validated the results obtained through numerical simulation. This study advances the understanding of acoustic cavitation behaviour in ionic liquids and provides valuable insights for optimizing ultrasound-assisted processes in these solvents, whose application have become more and more frequent due to their tunable properties. Future research will address some limitations of this study, such as the fact that the hygroscopicity of some of the ILs was neglected and the thermodynamic properties of the ionic liquid were considered independent of temperature, which is equivalent to simulating the first stages of a sonication process. Because the ultrasound probe vibrates, there is a vertical displacement occurring at the liquid-probe boundary. Future investigations should consider the ultrasound tip as a moving wall rather than a fixed wall. Additionally, this study focused on argon gas to saturate the liquid, leaving room for investigation of other gases.

#### CRedit authorship contribution statement

**Dalma Schieppati:** Conceptualization, Data curation, Formal analysis, Investigation, Writing – original draft. **Mood Mohan:** Data curation, Software. **Bruno Blais:** Investigation, Validation, Writing – review & editing. **Kobra Fattahi:** Investigation, Software. **Gregory S. Patience:** Supervision, Software, Data curation, Writing – review & editing. **Blake A. Simmons:** Supervision, Validation, Writing – review & editing. **Seema Singh:** Software, Validation, Writing – review & editing. **Daria C. Boffito:** Supervision, Resources, Conceptualization, Validation, Writing – review & editing.

#### Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

#### Data availability

Data will be made available on request.

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