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svt: Singular Value Thresholding in MATLAB

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Abstract

Many statistical learning methods such as matrix completion, matrix regression, and multiple response regression estimate a matrix of parameters. The nuclear norm regularization is frequently employed to achieve shrinkage and low rank solutions. To minimize a nuclear norm regularized loss function, a vital and most time-consuming step is singular value thresholding, which seeks the singular values of a large matrix exceeding a threshold and their associated singular vectors. Currently MATLAB lacks a function for singular value thresholding. Its built-in svds function computes the top r singular values/vectors by Lanczos iterative method but is only efficient for sparse matrix input, while aforementioned statistical learning algorithms perform singular value thresholding on dense but structured matrices. To address this issue, we provide a MATLAB wrapper function svt that implements singular value thresholding. It encompasses both top singular value decomposition and thresholding, handles both large sparse matrices and structured matrices, and reduces the computation cost in matrix learning algorithms.

Keywords

matrix completion; matrix regression; singular value thresholding (SVT); singular value decomposition (SVD); sparse; structured matrix; MATLAB

1. Introduction

Many modern statistical learning problems concern estimating a matrix-valued parameter. Examples include matrix completion, regression with matrix covariates, and multivariate response regression. Matrix completion (Candès and Recht 2009; Mazumder, Hastie, and Tibshirani 2010) aims to recover a large matrix of which only a small fraction of entries are observed. The problem has sparked intensive research in recent years and is enjoying a broad range of applications such as personalized recommendation system (ACM SIGKDD and Netflix 2007) and imputation of massive genomics data (Chi, Zhou, Chen, Del Vecchio, and Lange 2013). In matrix regression (Zhou and Li 2014), the predictors are two

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dimensional arrays such as images or measurements on a regular grid. Thus it requires a regression coefficient array of same size to completely capture the effects of matrix predictors. Another example is regression with multiple responses (Yuan, Ekici, Lu, and Monteiro 2007; Zhang, Zhou, Zhou, and Sun 2017), which involves a matrix of regression coefficients instead of a regression coefficient vector.

In these matrix estimation problems, the nuclear norm regularization is often employed to achieve a low rank solution and shrinkage simultaneously. This leads to a general optimization problem

$$\text{minimize } \ell(\mathbf{B}) + \lambda \|\mathbf{B}\|_*, \quad (1)$$

where ℓ is a relevant loss function, $\mathbf{B} \in \mathbb{R}^{m \times n}$ is a matrix parameter, $\|\mathbf{B}\|_* = \sum_i \sigma_i(\mathbf{B}) = \|\sigma(\mathbf{B})\|_1$ (sum of singular values of \mathbf{B}) is the nuclear norm of \mathbf{B} , and λ is a positive tuning parameter that balances the trade-off between model fit and model parsimony. The nuclear norm plays the same role in low-rank matrix approximation that the ℓ_1 norm plays in sparse regression. Generic optimization methods such as accelerated proximal gradient algorithm, majorization-minorization (MM) algorithm, and alternating direction method of multipliers (ADMM) have been invoked to solve optimization problem (1). See, e.g., Mazumder et al. (2010); Boyd, Parikh, Chu, Peleato, and Eckstein (2011); Parikh and Boyd (2013); Chi et al. (2013); Lange, Chi, and Zhou (2014) for matrix completion algorithms and Zhou and Li (2014); Zhang et al. (2017) for the accelerated proximal gradient method for solving nuclear norm penalized regression. All these algorithms involve repeated singular value thresholding, which is the proximal mapping associated with the nuclear norm regularization term

$$\mathbf{A} \mapsto \arg \min \frac{1}{2} \|\mathbf{X} - \mathbf{A}\|_F^2 + \lambda \|\mathbf{X}\|_*. \quad (2)$$

Let the singular value decomposition of \mathbf{A} be $\mathbf{U} \text{diag}(\sigma_i) \mathbf{V}^\top = \sum_i \sigma_i \mathbf{u}_i \mathbf{v}_i^\top$. The solution of (2) is given by $\sum_i (\sigma_i - \lambda)_+ \mathbf{u}_i \mathbf{v}_i^\top$ (Cai, Candès, and Shen 2010). Some common features characterize the singular value thresholding operator in applications. First the involved matrices are often large. For matrix completion problems, m, n can be at order of $10^3 \sim 10^6$. Second only the singular values that exceed λ and their associated singular vectors are needed. Third the involved matrix is often structured. In this article, we say a matrix is *structured* if matrix-vector multiplication is fast. For example, in matrix completion problems, \mathbf{A} is of the form “sparse + low rank”. That is $\mathbf{A} = \mathbf{M} + \mathbf{L}\mathbf{R}^\top$, where \mathbf{M} is sparse and $\mathbf{L} \in \mathbb{R}^{m \times r}$ and $\mathbf{R} \in \mathbb{R}^{n \times r}$ are low rank $r \ll \min\{m, n\}$. Although \mathbf{A} is not sparse itself, matrix-vector multiplications $\mathbf{A}\mathbf{v}$ and $\mathbf{w}^\top \mathbf{A}$ cost $\mathcal{O}(m+n)$ flops instead of $\mathcal{O}(mn)$. Storing the sparse matrix \mathbf{M} and \mathbf{L} and \mathbf{R} also takes much less memory than the full matrix \mathbf{A} . All these characteristics favor the iterative algorithms for singular value decomposition such as the Lanczos bidiagonalization method (Golub and Van Loan 1996).

Most algorithms for aforementioned applications are developed in MATLAB (The MathWorks Inc. 2013), which however lacks a convenient singular value thresholding functionality. The most direct approach for SVT is applying full SVD through `svd` and then soft-threshold the singular values. This approach is in practice used in many matrix learning problems according to the distributed code, e.g., Kalofolias, Bresson, Bronstein, and Vandergheynst (2014); Chi et al. (2013); Parikh and Boyd (2013); Yang, Wang, Zhang, and Zhao (2013); Zhou, Liu, Wan, and Yu (2014); Zhou and Li (2014); Zhang et al. (2017); Otazo, Candès, and Sodickson (2015); Goldstein, Studer, and Baraniuk (2015), to name a few. However, the built-in function `svd` is for full SVD of a dense matrix, and hence is very time-consuming and computationally expensive for large-scale problems. Another built-in function `svds` wraps the `eigs` function to calculate top singular triplets using iterative algorithms. However the current implementation of `svds` is efficient only for sparse matrix input, while the matrix estimation algorithm involves singular value thresholding of dense but structured matrices. Another layer of difficulty is that the number of singular values exceeding a threshold is often unknown. Therefore singular value thresholding involves successively computing more and more top singular values and vectors until hitting below the threshold.

To address these issues, we develop a MATLAB wrapper function `svt` for the SVT computation. It is compatible with MATLAB's `svds` function in terms of computing a fixed number of top singular values and vectors of sparse matrices. However it is able to take functional handle input, offering the flexibility to exploit matrix structure. More importantly, it automatically performs singular value thresholding with a user-supplied threshold and can be easily used as a plug-in subroutine in many matrix learning algorithms.

We discuss implementation details in Section 2 and describe syntax and example usage in Section 3. Section 4 evaluates numerical performance of the `svt` function in various situations. We conclude with a discussion in Section 5.

2. Algorithm and implementation

Our implementation hinges upon a well-known relationship between the singular value decomposition of a matrix $A \in \mathbb{R}^{m \times n}$, $m \geq n$, and the eigenvalue decomposition of the symmetric augmented matrix $\begin{pmatrix} \mathbf{0} & A^T \\ A & \mathbf{0} \end{pmatrix}$ (Golub and Van Loan 1996, Section 8.6). Let the singular value decomposition of A be $U\Sigma V^T$, where $U \in \mathbb{R}^{m \times n}$, $\Sigma \in \mathbb{R}^{n \times n}$ and $V \in \mathbb{R}^{n \times n}$. Then

$$\begin{pmatrix} \mathbf{0} & A^T \\ A & \mathbf{0} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} V & V \\ U & -U \end{pmatrix} \cdot \begin{pmatrix} \Sigma & \mathbf{0} \\ \mathbf{0} & -\Sigma \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} V & V \\ U & -U \end{pmatrix}^T. \quad (3)$$

Therefore the SVD of A can be computed via the eigen-decomposition of the augmented matrix. Our wrapper function utilizes MATLAB's built-in `eigs` function for computing the top eigenvalues and eigenvectors of large, sparse or structured matrices.

In absence of a threshold, `svt` is similar to `svds` and calculates the top singular values and vectors. Since we allow function handle input, users can always take advantage of special structure in matrices by writing a user defined function for calculating matrix-vector multiplication. This is one merit of `svt` compared with MATLAB's `svds`.

With a user input threshold, `svt` does singular value thresholding in a sequential manner. It first computes the top k (default is 6) singular values and vectors. Two methods have been implemented to gradually build up the requested subspace. Let U_r , V_r and σ_r , $i = 1, \dots, r$, be the singular values and vectors accrued so far. In the deflation method (Algorithm 1), we obtain next batch of *incr* (default is 5) singular values and vectors by working on the deflated matrix $A - U_r \text{diag}(\sigma_1, \dots, \sigma_r) V_r^T$. In the succession method (Algorithm 2), originally hinted in Cai et al. (2010), we work on A directly and retrieve top k , $k + \text{incr}$, $k + 2 \cdot \text{incr}$, ... singular values and vectors of the original matrix A successively. Both algorithms terminate as soon as a singular value below the threshold is identified. Efficiency of these two algorithms are compared in Section 4.5.

Algorithm 1: Singular value thresholding based on deflation method.

```

1 Initialization:  $mat = [0, A^T; A, 0]$ ,  $iter = \min(m, n)$ ;
2 while  $iter > 0$  do
3    $[eigvec, eigval] \leftarrow \text{eigs}(mat, k)$ ;
4    $i \leftarrow i_{\{eigval \leq \lambda\}}$ ;
5   if  $i \neq na$  then
6      $w \leftarrow [w, eigvec_{(:,1:i-1)}]$ ;
7      $e \leftarrow [e, eigval_{(1:i-1)}]$ ;
8     break
9   else
10     $w \leftarrow [w, eigvec]$ ;
11     $e \leftarrow [e, eigval]$ ;
12  end
13   $iter \leftarrow iter - k$ ;
14   $k \leftarrow \min(incr, iter)$ ;
15   $mat \leftarrow mat - w \cdot e \cdot w^T$ ;
16 end
17  $S \leftarrow e$ ;
18  $w \leftarrow \sqrt{2} \cdot w$ ;
19  $U \leftarrow w_{(n+1:end,:)}$ ;
20  $V \leftarrow w_{(1:n,:)}$ ;
21 return  $[U, S, V]$ 

```

Algorithm 2: Singular value thresholding based on succession method.

```

1 Initialize  $mat = [0, A^T; A, 0]$ ,  $iter = \min(m, n)$ ;
2 while  $iter > 0$  do
3    $[eigvec, eigval] \leftarrow eigs(mat, k)$ ;
4    $i \leftarrow i_{\{eigval \leq \lambda\}}$ ;
5   if  $i \neq na$  then
6      $w \leftarrow eigvec(:, i-1)$ ;
7      $e \leftarrow eigval(1, i-1)$ ;
8     break
9   else
10     $w \leftarrow eigvec$ ;
11     $e \leftarrow eigval$ ;
12  end
13   $iter \leftarrow iter - k$ ;
14   $k \leftarrow \min(k + incre, iter)$ ;
15 end
16  $S \leftarrow e$ ;
17  $w \leftarrow \sqrt{2} \cdot w$ ;
18  $U \leftarrow w_{(n+1:end,:)}$ ;
19  $V \leftarrow w_{(1:n,:)}$ ;
20 return  $[U, S, V]$ 

```

3. The MATLAB function aspect

We demonstrate various usages of `svt` in this section. A complete demonstration script with output is available on the software web page <http://hua-zhou.github.io/svt/>.

To find the top k singular values and vectors of a matrix A , the usage is the same as MATLAB's built-in function `svds`. A can be either full or sparse. By default, it computes the top 6 singular values and vectors

```
[U, S, V] = svt(A)
```

To request top 15 singular values and vectors, we use

```
[U, S, V] = svt(A, 'k', 15)
```

Users can also supply a function handle, instead of the matrix itself, that computes matrix-vector multiplication. This allows `svt` to utilize a special structure other than sparsity. For example, suppose A is a 1000-by-1000 “sparse plus low rank” matrix $M + LR^T$, where M is sparse and $L, R \in \mathbb{R}^{1000 \times 5}$ are two skinny and tall matrices. To compute the top 15 singular values and vectors, we first define a function that computes Av or $w^T A$ for arbitrary vectors v, w of compatible dimensions

```

function Av = Afun(v, trans)
  if trans
    Av = (v' * M)' + R * (v' * L)';
  else
    Av = M * v + L * (R' * v);
  end

```

```

    end
end

```

and then call

```
[U, S, V] = svt(Afun, 'k', 15, 'm', 1000, 'n', 1000)
```

Note the function `Afun` needs to have access to the variables `M`, `L` and `R` and is best declared as a sub-function in the main computation routine. The dimensions of matrix are required when using a functional handle. 'm' is the number of rows and 'n' is the number of columns.

Great convenience of `svt` comes from singular value thresholding. That is to compute the singular values that exceed a threshold λ and associated singular vectors. The code

```
[U, S, V] = svt(A, 'lambda', 0.1)
```

computes the singular values and vectors of a matrix `A` that exceed 0.1. `A` can be either full or sparse. For a non-sparse, structured matrix, we can use the same function handle for singular value thresholding

```
[U, S, V] = svt(Afun, 'lambda', 0.1, 'm', 1000, 'n', 1000)
```

Again the dimensionality of the matrix must be specified by setting 'm' and 'n'. By default, `svt` uses the deflation method for locating all singular values and vectors above the threshold. Users can change to the succession method by

```
[U, S, V] = svt(A, 'lambda', 0.1, 'method', 'succession')
```

or

```
[U, S, V] = svt(Afun, 'lambda', 0.1, 'm', 1000, 'n', 1000, 'method', ...
'succession')
```

For singular value thresholding, users can specify the number of top singular values to try in the first iteration and then increment the size in subsequent iterations by the 'k' and 'incre' options respectively. The command

```
[U, S, V] = svt(A, 'lambda', 0.1, 'k', 15, 'incre', 3)
```

computes the top 15 singular values and vectors in the first iteration and then adds 3 more in each subsequent iteration until hitting the singular values below threshold 0.1. This option is

useful when users have a rough idea how many singular values are above the threshold and can save considerable computation time. The default values are $k = 6$ and $incr = 5$.

4. Numerical experiments

In this section, we evaluate the numerical performance of svt in different scenarios and compare it with the MATLAB built-in functions svd and svds. We conduct these experiments on a desktop with an Intel Quad Core CPU @ 3.20 GHz and 12 GB of RAM. Computing environment is Linux MATLAB R2013a 64-bit version. For testing purpose, we use 5 square sparse matrices and 4 rectangular sparse matrices of varying sizes downloaded from the University of Florida sparse matrix collection (Davis and Hu 2011). For each numerical task, 10 replicate runs are performed and the average run time and standard error are reported, unless stated otherwise. Sparsity of a matrix A is defined as the proportion of zero entries, $1 - \text{nnz}(A)/\text{numel}(A)$.

4.1. Top k singular values and vectors of sparse matrices

Table 1 reports the run times of svt, svds and svd for computing the top 6 singular values and associated vectors of sparse matrices. In this case, svt internally calls svds thus their run times should be indistinguishable. The huge gain of svt/svds in large sparse matrices simply demonstrates the advantage of the iterative method over the full decomposition method implemented in svd.

4.2. Top k singular values and vectors of “sparse + low rank” matrices

This example tests the capability of svt to take functional handle input. We generate structured matrices by adding a low rank perturbation to a sparse matrix. Let $M \in \mathbb{R}^{n \times n}$ be a sparse test matrix. We form a “sparse + low rank” matrix $A = M + LR^T$, where $L, R \in \mathbb{R}^{n \times 10}$ have independent standard normal distributed entries. Table 2 shows the average run times of svt with function handle input and svds with input A itself to compute the top 6 singular values and vectors based on 10 simulation replicates. It clearly shows the advantage of exploiting the special matrix structure over applying the iterative algorithm to the full matrix directly. The speed-up is up to 100 fold for large matrices.

4.3. Singular value thresholding of sparse matrices

In this example we compare the singular value thresholding capability of svt with the strategy of full singular value decomposition by svd followed by thresholding on sparse test matrices. The threshold value is pre-determined such that the top 50 singular values are above threshold. By default, svt starts with $k = 6$ singular values and then add more than 5 in each subsequent iteration. Results are presented in Table 3. For matrices of size less than 1000, svt is less efficient due to the overhead of repeated calling iterative algorithms until hitting the threshold. For large matrices, svt shows 100 ~ 1000 fold speed-ups.

4.4. Singular value thresholding of “sparse + low rank” matrices

This example investigates singular value thresholding of structured matrices. “Sparse + low rank” matrices are generated by the same mechanism as in Section 4.2. Results in Table 4

show roughly the same pattern as in Table 3. Speed-up of svt is most eminent for large matrices. To evaluate the effectiveness of exploiting structure in singular value thresholding, we also call svt with input \mathbf{A} directly, which apparently compromises efficiency.

4.5. Deflation versus succession method for singular value thresholding

Table 5 compares the efficiency of the deflation and succession strategies for singular value thresholding of sparse test matrices. The threshold value is pre-determined such that the top 50 singular values are above the threshold. Both methods start with $k = 6$ singular values and then add 5 more in each subsequent iteration. The deflation method is in general faster than the succession method.

A similar comparison is done on “sparse + low rank” structured matrices, which are generated in the same way as in Section 4.2. The threshold is again set at the 50th singular value of each matrix. The average run time and standard error are reported in Table 6. We found non-convergence of the underlying **ARPACK** routine when applying the deflation method to the rdb800l and mhd4800 matrices. The non-convergence is caused by clustered eigenvalues. It is well known that **ARPACK** works best for finding eigenvalues with large separation between unwanted ones, and non-convergence is typical when dealing with ill conditioned matrices (Lehoucq and Sorensen 1996). When this happens, we restart with the succession method and continue from the current subspace.

4.6. Large-scale singular value thresholding

The purpose of this section is to demonstrate the performance of svt on large rectangular matrices. For the first two test matrices (bibd_20_10 and bibd_22_8), “sparse + low rank” matrices are generated by the same mechanism as in Section 4.2. For the other two matrices (sotrmG2_1000 and tp-6), singular value thresholding is performed on the original sparse matrices. The threshold is set at the 5th, 20th, and 50th singular value of each matrix respectively. Table 7 displays the run time of svt from one replicate. The full singular value decomposition svd takes excessively long time for these 4 problems so its results are not reported.

4.7. Application to matrix completion problem

To demonstrate the effectiveness of svt as a plug-in computational routine in practice, we conduct a numerical experiment on the spectral regularization algorithm for matrix completion (Mazumder et al. 2010), which minimizes

$$\frac{1}{2} \sum_{(i,j) \in \Omega} (x_{ij} - y_{ij})^2 + \lambda \|\mathbf{X}\|_* \quad (4)$$

at a grid of tuning parameter values λ . Here Ω indexes the observed entries y_{ij} and $\mathbf{X} = (x_{ij})$ is the completed matrix. Algorithm 3 lists the computational algorithm, which involves repeated singular value thresholding (lines 4–6). See Chi et al. (2013) for a derivation from the majorization-minimization (MM) point of view. Although $\mathbf{A}^{(l)}$ is a dense matrix, it can be written as

$$\begin{aligned} \mathbf{A}^{(t)} &= P_{\Omega}(\mathbf{Y}) + P_{\Omega^{\perp}}(\mathbf{X}^{(t)}) \\ &= [P_{\Omega}(\mathbf{Y}) - P_{\Omega}(\mathbf{X}^{(t)})] + \mathbf{X}^{(t)}, \end{aligned}$$

where $\mathbf{X}^{(t)}$ is a low rank matrix at large values of λ (only few singular values survive after thresholding), and $P_{\Omega}(\cdot)$ is a binary projection operator onto the observed entries. Fortunately, in many applications, large values of λ are the regime of interest, which encourages low rank solutions. That means most of the time $\mathbf{A}^{(t)}$ is of the special form “sparse + low rank” that enables extremely fast matrix-vector multiplication.

Algorithm 3: MM algorithm for minimizing the penalized loss (4).

```

1 Initialize  $\mathbf{X}^{(0)}$ ;
2 repeat
3    $\mathbf{A}^{(t)} \leftarrow P_{\Omega}(\mathbf{Y}) + P_{\Omega^{\perp}}(\mathbf{X}^{(t)})$ ;
4   SVD  $\mathbf{U} \text{diag}(\mathbf{a}^{(t)}) \mathbf{V}^{\top} \leftarrow \mathbf{A}^{(t)}$ ;
5    $\mathbf{x}^{(t+1)} \leftarrow (\mathbf{a}^{(t)} - \lambda)_+$ ;
6    $\mathbf{X}^{(t+1)} \leftarrow \mathbf{U} \text{diag}(\mathbf{x}^{(t+1)}) \mathbf{V}^{\top}$ ;
7 until objective value converges;
```

In the numerical experiment, we generate a rank-5 matrix by multiplying two matrices $\mathbf{M} = \mathbf{L}\mathbf{R}^{\top}$, where $\mathbf{L}, \mathbf{R} \in \mathbb{R}^{n \times 5}$ have independent standard normal distributed entries. Then, we add independent standard Gaussian noise to corrupt the original parameter matrix \mathbf{M} , that is $\mathbf{Y} = \mathbf{M} + \boldsymbol{\epsilon}$. 5% entries of \mathbf{Y} are randomly chosen to be observed. The dimension n of our synthetic data ranges from 500 to 5000. For each n , we minimize (4) at a grid of 20 points. The grid is set up in a linear manner as in Mazumder et al. (2010).

```

lambdas = linspace(maxlambda * 0.9, maxlambda / 5, 20)
```

Here maxlambda is the largest singular value of the input matrix \mathbf{Y} with missing entries set at 0. Warm start strategy is used. That is the solution at a previous λ is used as the start point for the next λ . Path following is terminated whenever all 20 grid points are exhausted or the rank of the solution exceeds 10 (twice the true rank). Three methods for singular value thresholding are tested: svt using functional handle input, svt using matrix input $\mathbf{A}^{(t)}$, and full singular value thresholding by svd followed by thresholding. Table 8 shows the run time in minutes for obtaining the whole solution path. Speed-up of svt increases with matrix size and utilizing the “sparse + low rank” structure via functional handle boosts the performance.

5. Discussion

We develop a MATLAB wrapper function svt for singular value thresholding. When a fixed number of top singular values and vectors are requested, svt expands the capability of MATLAB’s built-in function svds by allowing function handle input. This enables application of the iterative method to dense but structured large matrices. More conveniently, svt provides a simple interface for singular value thresholding, the key step in many matrix learning algorithms. Our numerical examples have demonstrated efficiency of svt in various

situations. The `svt` package is continuously developed and maintained at GitHub <http://hua-zhou.github.io/svt/>.

We describe a few future directions here. Our wrapper function utilizes the well-known relationship between SVD and eigen-decomposition of the augmented matrix (3) and builds on the MATLAB's `eigs` function, which in turn calls the **ARPACK** subroutines (Lehoucq, Sorensen, and Yang 1997) for solving large scale eigenproblems. An alternative is to use the **PROPACK** library (Larsen 1998), an efficient package for singular value decomposition of sparse or structured matrices. This involves distributing extra source code or compiled programs but may further improve efficiency. Both **ARPACK** and **PROPACK** implement Krylov subspace method and compute a fixed number of top eigenvalues or singular values. Thus singular value thresholding has to be done in a sequential manner. The recent **FEAST** package (Plizzi and Kestyn 2012) is an innovative method for solving standard or generalized eigenvalue problems, and is able to compute all the eigenvalues and eigenvectors within a given search interval, which is particularly attractive for the singular value thresholding task. However users must provide an initial value for the number of eigenvalues in the search interval. If the initial guess is too small, the program will exit. In real applications of singular value thresholding, such an estimate may be hard to obtain. Further investigation of the feasibility of using **FEAST** for singular value thresholding is underway.

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Table 1:

Top 6 singular values and vectors of sparse matrices by svt, svds and svd. Reported are the average run time (in seconds) and standard error (in parentheses) based on 10 runs.

Matrix	Size	Sparsity	svt	svds	svd
bfbw398	398	0.9816	0.0396 (0.0003)	0.0393 (0.0004)	0.0450 (0.0001)
rdb800l	800	0.9928	0.0944 (0.0008)	0.0941 (0.0009)	0.2184 (0.0007)
to1s1090	1090	0.9970	0.0549 (0.0007)	0.0592 (0.0005)	0.4377 (0.0006)
mhd4800b	4800	0.9988	0.0579 (0.0029)	0.0536 (0.0026)	249.1995 (0.0143)
cryg10000	10000	0.9995	0.1550 (0.0019)	0.1580 (0.0017)	1773.6812 (0.2014)

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Table 2:

Top 6 singular values and vectors of “sparse + low rank” matrices by svt and svds. Structured matrices are formed by adding a random rank-10 matrix to the original sparse test matrix. Reported are the average run time (in seconds) and standard error (in parentheses) based on 10 simulation replicates.

Matrix	Size	Sparsity	svt (fh input)	svds
bfbw398	398	0.9816	0.0176 (0.0011)	0.0408 (0.0009)
rdb800l	800	0.9928	0.0240 (0.0005)	0.2115 (0.0014)
tols1090	1090	0.9970	0.0780 (0.0009)	0.9396 (0.0079)
mhd4800b	4800	0.9988	0.0471 (0.0001)	5.6700 (0.0166)
cryg10000	10000	0.9995	0.1909 (0.0022)	44.2213 (0.4373)

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Table 3:

Singular value thresholding of sparse matrices by svt and svd. Reported are the average run time (in seconds) and standard error (in parentheses) based on 10 runs. The threshold value is pre-determined to catch the top 50 singular values.

Matrix	Size	Sparsity	svt	svd
bfbw398	398	0.9816	0.3633 (0.0012)	0.0456 (0.0001)
rdb800l	800	0.9928	0.7716 (0.0047)	0.2237 (0.0005)
tols1090	1090	0.9970	0.4295 (0.0012)	0.4451 (0.0011)
mhd4800b	4800	0.9988	1.3733 (0.0075)	249.4558 (0.0423)
cryg10000	10000	0.9995	3.1157 (0.0152)	1773.0692 (0.3403)

Table 4:

Singular value thresholding of “sparse + low rank” matrices. Reported are the average run time (in seconds) and standard error (in parentheses) based on 10 simulation replicates. Structured matrices are formed by adding a random rank-10 matrix to the original sparse test matrix. The threshold value is pre-determined to catch the top 50 singular values.

Matrix	Size	Sparsity	svt (fh input)	svt (matrix input)	svd
bfbw398	398	0.9816	1.3540 (0.1486)	1.4209 (0.1744)	0.0502 (0.0002)
rdb800l	800	0.9928	2.4144 (0.0089)	2.8655 (0.0194)	0.2569 (0.0005)
tols1090	1090	0.9970	0.5100 (0.0023)	1.3044 (0.0051)	0.4455 (0.0005)
mhd4800b	4800	0.9988	5.6852 (0.1462)	89.9854 (3.3959)	48.9117 (0.0122)
cryg10000	10000	0.9995	3.5793 (0.0145)	104.0540 (0.2411)	443.3518 (0.1034)

Table 5:

Comparison of deflation and succession methods for singular value thresholding of sparse matrices. Reported are the average run time (in seconds) and standard error (in parentheses) based on 10 runs. The threshold is pre-determined to catch the top 50 singular values.

Matrix	Size	Sparsity	Deflation	Succession
bfwb398	398	0.9816	0.3626 (0.0012)	0.4055 (0.0026)
rdb800l	800	0.9928	0.7636 (0.0048)	0.8670 (0.0019)
tols1090	1090	0.9970	0.4250 (0.0016)	0.5167 (0.0013)
mhd4800b	4800	0.9988	1.3761 (0.0110)	2.3382 (0.0227)
cryg10000	10000	0.9995	3.1782 (0.0173)	5.8789 (0.0648)

Table 6:

Comparison of deflation and succession methods for singular value thresholding of “sparse + low rank” matrices. Reported are the average run time (in seconds) and standard error (in parentheses) based on 10 simulation replicates. The threshold is pre-determined to catch the top 50 singular values.

Matrix	Size	Sparsity	Deflation	Succession
bfbw398	398	0.9816	1.2936 (0.0588)	2.0956 (0.0059)
rdb800l	800	0.9928	2.3758 (0.0187)	1.3863 (0.0118)
tol51090	1090	0.9970	0.5084 (0.0022)	0.6088 (0.0011)
mhd4800b	4800	0.9988	5.6008 (0.1598)	4.4027 (0.0396)
cryg10000	10000	0.9995	3.5636 (0.0129)	6.3697 (0.0621)

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Table 7:

Singular value thresholding of large rectangular matrices. Reported are the run time (in minutes) of svt from one replicate. The threshold value is pre-determined to catch the top 5, 20, and 50 singular values respectively.

Matrix	Size	Sparsity	5th	20th	50th
bibd_20_10	(190, 184756)	0.7632	0.0350	0.6152	11.2083
bibd_22_8	(231, 319770)	0.8788	0.0372	2.6438	4.1058
stormG2_1000	(528185, 1377306)	0.9999	0.2518	1.0394	12.6890
tp-6	(142752, 1014301)	0.9999	1.6373	20.2409	41.3021

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Table 8:

Run time of matrix completion problem using different singular value thresholding methods. Reported are the run time (in minutes) for the whole solution path. Path following is terminated whenever 20 grid points are exhausted or the rank of solution goes beyond 10 (twice the true rank).

Size	Sparsity	Rank	Grid points	svt (fh input)	svt (matrix input)	svd
500	0.95	5	15	0.8541	0.7335	0.5466
1000	0.95	5	19	2.9359	4.0803	4.2763
2000	0.95	5	20	10.3611	35.7058	40.1562
3000	0.95	5	20	20.6781	69.3164	138.8011
4000	0.95	5	20	52.2150	175.2524	335.2373
5000	0.95	5	20	71.8051	246.3738	630.2729