

Centrifuge Testing of Model Levees atop Peaty Soil: Experimental Data

Anne Lemnitzer,^{a)} A.M.EERI, Riccardo Cappa,^{a)} S.M. EERI, Samuel Yniesta^{c)}, S.M. EERI, and Scott Brandenburg,^{c)} A.M.EERI,

Four large scale centrifuge tests were performed at the NEES@UCDavis equipment site to study the cyclic behavior of levee structures resting atop soft organic peat. The model configurations using a non-liquefiable levee focused on the seismic deformation potential of peat during primary consolidation and secondary compression. The tests performed with a sandy levee studied the liquefaction potential of saturated loose sand fill overlying soft peat as well as the levee-peat interaction under different loading conditions. The models were subjected to scaled ground motions representative of the Sacramento – San Joaquin Delta where unengineered levee fills rest atop soft compressible peat soils. System instrumentation consisted of linear potentiometers, pore pressure sensors and accelerometers. Slow data recorded at 1Hz document the settlements during spin up, application of ground motions, and spin down. Fast data sampled at 4167 Hz measured the dynamic response of the system, the excess pore pressure increase and immediate settlements. The project is archived at the NEES data repository under nees.org/warehouse/project/1161.

INTRODUCTION

This research aims to better understand the contribution of peat soil to the seismic response of levees using centrifuge models. Non-liquefiable clay levees were tested to study the post-cyclic volumetric strain behavior of the peat, and to study the deformation modes of the comparatively stiffer levee using concepts from soil-structure interaction theories. Levees composed of loose liquefiable sand were also tested to mimic a condition that characterizes some levees in the Sacramento / San Joaquin Delta, and to study the influence of the peat on the liquefaction behavior of the sand. This research will be applicable in the Delta, and in

^{a)} University of California Irvine, 4149 Engineering Gateway, Irvine, CA, 92831, USA, alemnitz@uci.edu

^{b)} University of California Los Angeles, 405 Hilgard Ave, Los Angeles, 90095, USA

28 other regions worldwide where levees rest atop peat in seismic regions (e.g., Hokkaido,
29 Japan; Sasaki,1994), and will provide valuable experimental data to support engineering
30 evaluation procedures for predicting levee deformations.

31 This paper presents experimental data from a centrifuge testing program conducted at the
32 NEES@UCDavis equipment site from January 2013 – March 2014. Eleven preliminary small
33 scale tests on the 1-m radius Schaevitz centrifuge helped establish the most suitable model
34 construction techniques, which was complicated by (1) the very high compressibility of the
35 peat material and associated geometry changes during spin-up, and (2) the need to maintain a
36 water channel on one side of the liquefiable levee. Two investigations were then performed
37 on the 9m-radius centrifuge at 57g, implementing lessons learned from small scale testing
38 and preliminary analytical studies. Table 1 reports a summary of all centrifuge experiments
39 performed as part of this project. A comprehensive set of detailed reports and drawings
40 (Cappa et al. 2014 a,b) along with test data for all experiments listed in Table 1 are available
41 at the NEES project warehouse under project #1161: <http://nees.org/warehouse/project/1161>.
42 This manuscript will focus on the presentation of the two large scale investigations
43 performed on the 9-m radius centrifuge and describes the model setup and construction,
44 model materials, instrumentation, data acquisition and data processing/storage as well as
45 sample data obtained from both large scale investigations. Hereafter, and in consistency with
46 the NEES data repository, investigation 1 will be labeled RCK01 and investigation 2 is
47 named RCK02 accordingly following the NEES@UCDavis convention of identifying each
48 investigation by the lead investigator's initials. The primary difference between the two
49 investigations is the peat layer thickness and its impact on the seismic response of the levee-
50 peat system.

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57 **Table 1.** Summary of centrifuge experiments performed as part of this study.

Investigation	Experiment	Centrifuge Radius	Brief Description*	DOI
Small Scale Investigations	1	1m	Peat slurry under surcharge.	10.4231/D32V2C96M
	2	1m	Peat passed through #4 sieve, under surcharge.	10.4231/D3TD9N80K
	3	1m	Peat processed through blender, under surcharge.	10.4231/D3PN8XF79
	4	1m	Peat passed through #4 sieve, no surcharge.	10.4231/D3JW86N3J
	5	1m	Peat passed through #4 sieve, no surcharge.	10.4231/D3F47GT8M
	6	1m	Sandy levee on peat shaken by SGM.	10.4231/D39C6S14W
	7	1m	Sandy levee shaken by SGM.	10.4231/D35M62704
	8	1m	Consolidation of peat under a sand layer.	10.4231/D31V5BD6C
	9	1m	Sandy levee on peat shaken by SGM.	10.4231/D3X63B55H
	10	1m	Sat. sandy levee constructed on arm by water pluviation.	10.4231/D3Z31NP21
	11	1m	Clay levee on peat shaken by SGM sequence.	10.4231/D3G73748K
RCK01	12	9m	Clay levee on peat shaken by SGM sequence.	10.4231/D34M91B6S
	13	9m	Saturated sandy levee on peat shaken by MGM.	10.4231/D30V89J2N
RCK02	14	9m	Clay levee on peat shaken by SGM sequence.	10.4231/D3W37KW7Z
	15	9m	Saturated sandy levee on peat , MGM & aftershocks.	10.4231/D3RB6W337

* SGM = Strong Ground Motion, MGM = Moderate Ground Motion

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EXPERIMENTAL CONFIGURATION FOR RCK01 AND RCK02

61 The general test setup of the levee systems is depicted in Figure 1. Each configuration
 62 consisted of a drainage layer of coarse sand with thickness D at the bottom of the model,
 63 followed by a peat layer with varying thicknesses (H) and a model levee consisting of (a)
 64 modeling clay or (b) saturated sand, with geometries as indicated in Figure 1. The levee
 65 system was constructed inside a rigid wall container with dimensions of 175.8 cm in length,
 66 90.9 cm in width and 53.7 cm in height (Figure 2a). The rigid container has transparent side
 67 walls to enable the acquisition of videos during testing, which was important for this project
 68 and outweighed the undesired boundary conditions imposed at the rigid soil/container
 69 contact. Figure 2b shows the placement of the container on the centrifuge arm with its
 70 respective global coordinate system.

71 Each of the two large scale investigations (RCK01 and RCK02) consisted of two
 72 Experiments: (1) a levee composed of non-liquefiable modeling clay rests on soft peat and
 73 several ground motions and sinusoidal sweeps are applied in flight to observe the seismic
 74 performance of the peat and the levee-peat interaction (Experiments 12 & 14 in Table 1); (2)
 75 the clayey levee is removed and substituted with a saturated sandy levee, and subsequently
 76 subjected to the target ground motion to investigate the system behavior (interaction &
 77 liquefaction) (Experiments 13 & 15 in Table 1). Model configurations for these four

78 experiments are shown in Figures 3 through 6. The high compressibility of the peat resulted
79 in significant settlement of the levee during spin-up, and Figs. 3 through 6 depict the models
80 in their configurations during testing, with dashed-lines indicating the pre-spin-up model
81 geometry.

82 The prototype system consists of a 5 m tall levee resting atop top of a 9.5 m and 6 m thick
83 layer of soft peat for RCK01 and RCK02, respectively. The models were spun to a
84 centrifugal acceleration of 57g, therefore the model scale dimensions were a 9 cm tall levee
85 resting atop 16.5 cm and 10.5 cm of peat for RCK01 and RCK02, respectively. The peat
86 thickness during RCK01 was selected to match conditions at a site on Sherman Island where
87 a previous field testing program was conducted on a non-liquefiable model levee using the
88 UCLA eccentric shaker (Reinert et al. 2014). Figure 7 shows photographs of the clayey levee
89 resting atop the peat for RCK01 and RCK02 before the container was installed on the
90 centrifuge arm.

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MATERIAL CHARACTERIZATION

93 The five soil materials utilized in the test setup include peat, modeling clay for the
94 nonliquefiable levees, loose Nevada sand for the liquefiable levees, coarse dense sand
95 beneath the peat, and loam placed atop the liquefiable levee for erosion protection.
96 Additionally, viscous fluid was used to scale the prototype permeability of the liquefiable
97 sandy levee.

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Peat

100 Bulk samples of peat were recovered from depths of 2-3 m at the field test site on Sherman
101 Island in the Sacramento-San Joaquin Delta documented by Reinert et al. (2014). The
102 samples were stored in plastic-lined metal barrels filled with water at UC Davis. Prior to
103 placement in the model container, the material was hand processed to remove coarse particles
104 and long fibers that are unsuitable for use in relatively small centrifuge models. Careful
105 handling was important to avoid the loss of fluid in the fibers due to squeezing and to obtain
106 a homogeneous and soft soil matrix. The peat was maintained submerged during model
107 construction. Important material characteristics of the processed peat were determined via
108 laboratory studies (Cappa et al., 2015). Additional in-situ test results of the peat from
109 geophysical testing, hand augering and cone penetration testing (CPT) are available in
110 Reinert et al. (2014).

111 The peat had a specific gravity G_s of 1.79 and an average organic content, OC, of 64%.
 112 Across an overburden pressure range of 5-150 kPa, the virgin compression index C_c and the
 113 recompression index C_r were determined to be 3.9 and 0.4, respectively. Two sets of bender
 114 elements recorded shear wave velocities at accelerations of 1, 5, 10, 20, 40, and 57g during
 115 spin-up, thereby enabling characterization of the shear wave velocity as a function of
 116 confining pressure. Figure 8 presents a sample measurement of shear wave velocities during
 117 RCK02 at 57g. The bender elements exhibited capacitive coupling with the conductive peat
 118 soil, and the desired elastic wave signal is superposed on an undesired portion of the signal
 119 corresponding to capacitive decay. The travel time corresponding to first arrival of the shear
 120 wave can nevertheless be measured from the two receivers, enabling calculation of the shear
 121 wave velocity. Equation 1 is a general form for characterizing shear wave velocity as a
 122 function of vertical effective stress, σ_v' .

$$123 \quad V_s = V_{s1} \cdot \left(\frac{\sigma_v'}{P_A} \right)^n \quad (1)$$

124 By plotting shear wave velocities measured across a range of centrifugal accelerations, the
 125 parameters V_{s1} and n can be determined via least squares regression, as shown in Figure 9. In
 126 the peat, V_{s1} and n were found to be 33 m/s and 0.31, respectively.

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128 P-wave velocity was measured by gently striking the top of the modeling clay levee and
 129 measuring the downward-propagating compressive wave using vertical accelerometers. The
 130 p-wave velocity of the peat was found to be approximately 419 m/s in RCK01 and
 131 approximately 172 m/s in RCK02. Both measurements indicate that the peat was unsaturated.
 132 This is consistent with field conditions, in which the peat holds a significant amount of
 133 entrapped gasses due to its past and ongoing decomposition.

134 A miniature CPT test was performed in-flight during RCK02, measuring tip resistance over a
 135 depth range of 27 cm (Figure 10). The CPT apparatus was placed in the free field region
 136 during Experiment 14 and was pushed through the mid-point of the upstream levee slope
 137 during Experiment 15. The free-field peat exhibited a very low tip resistance that increased
 138 slightly with depth, reaching a maximum near 0.24 MPa at the bottom of the peat layer. The
 139 relatively low tip resistance is due to low consolidation stresses in the free field. By contrast,
 140 the resistance in the peat beneath the sandy levee was significantly higher, increasing from
 141 about 0.5 MPa at the top of the peat to 1.0 MPa at the bottom of the peat. Consolidation

142 stresses from the overlying levee clearly increased the peat strength. Tip resistance increased
143 dramatically below the peat as the CPT probe pushed into the dense coarse sand.

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145 ***Liquefiable Sandy Levee (Nevada Sand)***

146 The liquefiable levee fill (Experiments 13 and 15, Table 1) consisted of saturated Nevada
147 sand with a mean grain size D_{50} of 0.14 mm, a specific gravity G_s of 2.66, a maximum and
148 minimum void ratio $e_{max/min}$ of 0.78 and 0.51 respectively, a coefficient of uniformity C_u of 2,
149 and a hydraulic conductivity k of approximately 10^{-3} cm/s in non-viscous water (Dashti
150 2009). The fines content passing # 200 sieve was removed from the sand. Shear wave
151 velocity measurements of the material obtained during the second investigation (RCK02)
152 suggested shear wave velocity parameters V_{sl} and n of 151 m/s and 0.23, respectively. To
153 obtain well saturated sand capable of simulating undrained shearing behavior during
154 liquefaction, traditional vacuum saturation techniques normally used in centrifuge modeling
155 were not suitable for our application because the gasses in the peat would expand under
156 vacuum, thereby resulting in model disturbance. A device was therefore developed to pre-
157 saturate the sand and the saturated sand was subsequently water pluviated into the model
158 without air contact. The device consists of an acrylic vacuum chamber with a hose attached at
159 the bottom, and details can be found in Yniesta et al. (2015). The relative density, D_R , of the
160 sand placed by this method was 27 – 58%, with an average density of 42% and a standard
161 deviation of 8.3%. This density range matches well with D_R values of 30 -50% observed in
162 non-engineered hydraulic fill in the field. Water pluviation has the benefit of matching the
163 manner in which many liquefiable sand deposits are placed. Fabric is known to exert a
164 significant influence on liquefaction potential of sand (Abdun et al., 2013).

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166 ***Coarse Dense Sand (Monterey Sand)***

167 A coarse sand layer consisting of #0/30 Monterey Sand was placed at the bottom of the
168 container to represent the natural geologic strata typical for the Delta, and to provide drainage
169 at the bottom of the peat layer during consolidation. The granular material was dry pluviated
170 to a relative density of 90%, thereby preventing liquefaction during shaking. A chimney drain
171 constructed of the same coarse sand material was placed along the south wall of the container
172 (Figure 1). Dashti (2009) determined this particular material to have a grain size $D_{50} = 0.40$
173 mm, a coefficient of uniformity $C_u = 1.3$, a specific gravity G_s of 2.64, and a
174 maximum/minimum void ratio $e_{max/min}$ of 0.843 and 0.510, respectively. The hydraulic

175 conductivity (k) is approximately 10^{-2} cm/s. Shear wave velocity parameters $V_{s,l}$ and n were
176 195 m/s and 0.26, respectively.

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178 ***Modeling Clay***

179 Impermeable, oil based modeling clay with a unit weight γ of 18 kN/m^3 was formed into a
180 clayey levee by pouring molten clay into a mold. The clay levee was moderately deformable,
181 allowing for small differential settlements in flight. Shear wave velocity of the modelling
182 clay measured at 1g was about 400 m/s, and this is anticipated to be the same as the shear
183 wave velocity in-flight since the modelling clay does not consolidate during spin-up.

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185 ***Loam Layer atop the Sandy Levee Fill***

186 To provide erosion protection, and to better visualize the crack and deformation patterns of
187 the sandy levee during testing, the liquefiable levee fill was covered with a dry-pluviated,
188 1.5cm thick mixture of 75% Yolo loam and 25% Monterey sand (by mass). This particular
189 loam is frequently found in the Sacramento region and was excavated from an open area at
190 the centrifuge facility.

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192 ***Viscous Pore Fluid***

193 The liquefiable sandy levees were saturated with a viscous pore fluid to provide undrained
194 loading conditions during shaking. The viscosity of the methylcellulose/water mixtures was
195 14 cSt and 18 cSt (1 centistokes = $1 \text{ mm}^2/\text{s}$) for RCK01 and RCK02, respectively.
196 Measurements were taken at 20°C prior to testing. Water expelled during consolidation of the
197 peat mixed with the viscous fluid, resulting in a post-test viscosity of about 4 cSt in the free
198 fluid in the channel. However, we believe that the fluid inside the levee fill was not prone to
199 this mixing, and therefore the viscosity remained high.

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201 **MODEL CONSTRUCTION AND LOAD APPLICATION**

202 The coarse dense sand stratum at the bottom of the model was dry pluviated in two lifts to
203 accommodate placement of sensors after the first lift. The sand was water saturated by
204 pouring water on a sponge resting on the sand surface.

205 Peat slurry was then poured from buckets onto the sand and smoothed with trowels at
206 elevations where sensors would be placed. The amount of peat slurry required to achieve the
207 target peat thickness after consolidation in-flight was based on observations from the

208 Shaevitz centrifuge test program (Cappa et al. 2015), laboratory consolidation studies
209 (Shafiee et al. 2013), and settlement predictions using Settle 3D (Rocscience 2014). The peat
210 slurry was too weak to support the clay levee, so a layer of Nevada sand ($\gamma_{dry} = 17 \text{ kN/m}^3$)
211 was placed on top of the peat to pre-consolidate the material over the course of three days.
212 The thickness of the Nevada sand was 3.5 cm for RCK01 and 9 cm for RCK02. Following
213 the pre-consolidation at 1g, the Nevada sand layer along with the expelled water was
214 removed and the clayey levee was placed on a thin geotextile atop the peat. Based on
215 anticipated settlement of the peat beneath the levee, peat was removed from the free-field to
216 achieve an approximately horizontal peat surface after consolidation at 57g (Cappa et al.
217 2014 a&b). Final construction steps included the installation of lights, attachment of racks for
218 sensor instrumentation, placement of all external sensors and CPT, installation of video
219 cameras and connection of all instrumentation to the data acquisition system.

220 Centrifuge spin-up proceeded incrementally to avoid undrained bearing failure of the peat.
221 Pore pressures in the peat beneath the levee were monitored to guide the spin-up rate. This
222 procedure is similar to staged construction techniques commonly utilized to construct
223 embankments on soft foundations (e.g., Ladd 1991), except that the gravity load is staged
224 rather than the fill height. The clayey levee was tested for two consecutive days in RCK01
225 (as described in Table 2), dedicated to consolidating the peat for several hours at various g-
226 levels (day 1) and applying a series of ground motions with different peak base accelerations
227 at 57-g (day 2). During investigation RCK02 the clayey levee test required only one day
228 because the peat thickness was less and consolidation therefore required less time.

229 During spin-up, the levees settled significantly and became submerged in water expelled
230 from the peat. We originally intended to pump the expelled water out of the models to bring
231 the water table near the surface of the peat. However, the pumping system failed during
232 RCK01, and we elected to test RCK02 with the free water in place to facilitate comparison
233 with RCK01. Furthermore, during spin-down the peat swelled back to near its initial position,
234 re-absorbing the expelled water. If this water were pumped out, the peat could have become
235 desiccated during spin-down and we wished to maintain saturation of the peat for the sandy
236 levee experiments.

237 Upon test completion, the clayey levee was removed and replaced with a sandy levee. A 10
238 cm wide drainage blanket consisting of coarse sand wrapped with filter paper was placed
239 beneath the downstream toe of the levee to prevent piping erosion and maintain the phreatic
240 surface within the levee prism. The container was filled with viscous fluid and the sandy

241 levee was pluviated into the model. Vertical sheet metal barriers constrained the pluviated
242 sand within the desired footprint area, and the levee was then manually re-shaped to the
243 desired geometry. The sandy levee was constructed with a 3:1 slope on the dry side to reduce
244 the amount of erosion due to seepage during flight and to represent typical levee conditions
245 in the field. The upstream slope was constructed with a 2:1 angle. After water pluviation, the
246 fluid was slowly siphoned from the dry-side of the levee.

247 During spinning, viscous water that seeped through the levee was collected in a U-shaped
248 ditch installed in the downstream peat, and collected fluid was pumped back to the channel to
249 maintain a steady-state seepage condition. Furthermore, a spillway was installed in the levee
250 to regulate the elevation of the channel relative to the levee crest and prevent over-topping
251 during spin up as the levee settled. For RCK01, the spillway was formed of a stiff metal U-
252 channel that settled less than the levee during consolidation, resulting in erosion of the sand
253 from beneath the channel. As a result, the water table was hydrostatic. A more flexible
254 spillway was implemented in RCK02, enabling a channel to be maintained on one side of the
255 levee.

256

257 ***Loading***

258 Table 2 summarizes the base excitations applied to the models for both investigations. The
259 organization of data into trials and repetition follows NEES requirements. Applied ground
260 motions include: (1) scaled versions of ground motions recorded during the 1989 Loma
261 Prieta Earthquake at the USCS/Lick Lab, Ch. 1 – 90°, and the 1995 Kobe Earthquake
262 recorded at a depth of 83 m at the Port Island downhole array, (2) low-amplitude step waves
263 imposed primarily to verify sensor function, and (3) sine sweeps intended to characterize the
264 dynamic response of the model. The magnitudes of the Loma Prieta and Kobe earthquakes
265 are in the range that contributes the most to seismic hazard in the Delta (DRMS 2009).
266 Scaled versions of these motions with amplitudes ranging from 0.006g to 0.52g in prototype
267 scale were imposed on the base of the model container.

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276 **Table 2.** Base Excitation Summary.

Investigation	Experiment	Trial	Repetition	Date	Time Stamp	Description	Peak base acceleration, PBA (g) in prototype scale
RCK01	12	1	1	11/4/2013	12:01:51	Slow data file for first spin	-
	12	1	2	11/4/2013	15:36:41	Slow data file for first spin	-
	12	1	3	11/4/2013	9:26:00	Rpm record	-
	12	2	1	11/4/2013	15:50:46	Step wave 1	0.006
	12	3	1	11/5/2013	10:18:50	Slow data file for second spin	-
	12	4	1	11/5/2013	13:25:45	Step wave 2	0.006
	12	5	1	11/5/2013	14:03:14	Sine sweep 1	0.021
	12	6	1	11/5/2013	14:31:51	Small Loma Prieta	0.036
	12	7	1	11/5/2013	14:45:16	Small Kobe	0.034
	12	8	1	11/5/2013	14:57:21	Medium Loma Prieta	0.174
	12	9	1	11/5/2013	15:13:14	Medium Kobe	0.194
	12	10	1	11/5/2013	15:39:51	Large Kobe	0.491
	12	11	1	11/5/2013	16:29:07	Large Loma Prieta	0.476
	12	12	1	11/5/2013	17:13:39	Sine sweep 2	0.021
		13	1	1	11/21/2013	10:31:08	Slow data file for second spin
13		2	1	11/21/2013	14:43:30	Step wave 3	0.005
13		3	1	11/21/2013	14:50:49	Moderate Kobe	0.375
RCK02	14	1	1	2/27/2014	7:53:12	Slow data file for first spin	-
	14	2	1	2/27/2014	12:50:38	Step wave 1	0.006
	14	3	1	2/27/2014	13:01:20	Sine sweep 1	0.018
	14	4	1	2/27/2014	13:45:13	Large Kobe	0.526
	14	5	1	2/27/2014	16:27:04	Large Loma Prieta	0.439
	14	6	1	2/27/2014	17:23:09	Sine sweep 2	0.020
	14	7	1	2/27/2014	17:37:01	Step wave 2	0.007
	14	8	1	2/27/2014	17:45:34	Medium Kobe	0.270
	14	9	1	2/27/2014	17:54:24	Small Kobe	0.131
	15	1	1	3/12/2014	12:00:21	Slow data file for second spin	-
	15	2	1	3/12/2014	17:04:41	Step wave 3	0.006
	15	3	1	3/12/2014	17:17:15	Moderate Kobe	0.336
	15	4	1	3/12/2014	17:33:41	Small Kobe	0.101
	15	5	1	3/12/2014	17:43:42	Very small Kobe	0.057

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INSTRUMENTATION

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Sensors used to characterize model response include accelerometers [PCB Piezotronics,

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models 352B68, 352C68, 352M54, 355M69, 353B18 & 353B31; range: 50g, 100g and

281 500g], pore pressure transducers [Keller, model 2Mi-100-81840 range: 0 - 689.5kPa], linear
282 potentiometers (L) [BEI Duncan, models: 606R6KL.12 & 604R4KL.15, stroke: 10cm and
283 15cm], and bender elements [Piezo Systems Inc., 2 layer transducer with PSI-5A4E
284 piezoceramic (nickel electrodes) and brass center reinforcement]. The general
285 instrumentation layout for each experiment is shown in Figures 3-6. Accelerometers and
286 bender elements were coated with a waterproofing layer prior to being placed into the model.
287 Linear potentiometers were attached to a rack mounted to the top of the container. Vertical
288 linear potentiometer rods rested on small footing plates to prevent penetration into the soft
289 soil. Horizontal linear potentiometer rods were attached to a metal frame cantilevered from
290 the soil. These horizontal linear potentiometers provide accurate low frequency response for
291 measuring permanent ground deformations, but the metal frame alters the high frequency
292 response. The high frequency response is typically obtained from an accelerometer embedded
293 in the soil near the anchor frame. Some of the accelerometers were fastened to a right-angle
294 connector to maintain a 90° angle between sensors, which sometimes tend to shift during
295 model construction and/or testing on the centrifuge. The position of each sensor was
296 measured during installation and again during excavation following testing. Tables
297 containing sensor positions, orientations, serial numbers, calibrations and measurements are
298 available at the NEES project warehouse. Some of the sensors ceased to function properly
299 during experimental activities, and a list of such sensors is available in the NEEShub
300 repository. Loss of sensor functionality is a natural part of experimental testing, and only a
301 small fraction of the sensors failed to function properly.

302 A total of eight cameras supported the surveillance of the specimen behavior during flight.
303 Two high speed cameras captured the behavior of the levee from the east and west side of the
304 container during the application of the ground motions. The models were also documented by
305 photographs taken during construction and testing, and a time-lapse video of the model
306 construction sequence was constructed from automated photos recorded at set time intervals.
307 All videos, photos, and construction time lapses are available on the NEEShub repository.

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310 **DATA PROCESSING AND ARCHIVING**

311 Experimental data are categorized as "Unprocessed Data", "Converted Data", and "Corrected
312 Data" in accordance with NEES standards. Experimental data is further categorized as "slow
313 data" sampled at 1 Hz during spin-up, spin-down and between ground motion applications,

314 and "fast data" sampled at 4167 Hz during the application of ground motions. Slow data
315 helped observe the low frequency response of the model and time dependent consolidation
316 settlement of the peat, while fast data captured the dynamic response of the model during
317 base excitation. For each experiment, Trial 1 contains the slow data while Trials 2 and higher
318 contain fast data.

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320 ***Unprocessed Data***

321 Unprocessed data are in engineering units in binary format. Prior to testing, a calibration file
322 is uploaded to the data acquisition system, and the recorded voltage signals are then
323 automatically converted to engineering units. All recordings are in model scale. A LabView
324 virtual instrument (vi) file is required to view the binary data files, and we do not anticipate
325 users will download and utilize this data. It is archived for completeness, and compliance
326 with NEES standards.

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328 ***Converted Data***

329 The Unprocessed Data are then converted from binary to ASCII format and saved as text
330 files in the "Converted Data" folder in the NEES repository. Generally, zero voltage does not
331 correspond to a value of zero for the engineering quantity being measured. For example, the
332 rod of the vertical linear potentiometers measuring settlement of the levee were initially
333 retracted as far into the housing as possible to facilitate the maximum possible useful range
334 for these sensors during consolidation. A fully retracted linear potentiometer returns a non-
335 zero voltage. Therefore the reference condition corresponding to zero settlement does not
336 correspond to zero voltage. In accordance with NEES standards, offsets are not applied to
337 Converted Data. For this reason, we anticipate that users will not utilize the Converted Data
338 as the primary data source, and it is archived for completeness and compliance with NEES
339 standards.

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343 ***Corrected Data***

344 Corrected Data are the data files that we anticipate will be most useful to users of the curated
345 dataset. The following operations are applied to the Converted Data to obtain Corrected Data:

346 (i) Offsets were applied such that zero corresponds to a desired reference condition.
347 Specifically, the mean value was subtracted from all acceleration records, and the
348 initial value prior to spin-up was subtracted from all displacement and load cell
349 records. Offsets to pore pressure transducers were set such that zero corresponds
350 to atmospheric pressure. During testing, some of the linear potentiometer rods fell
351 off the bearing pads, resulting in an abrupt offset in the settlement record. These
352 offsets were removed from the corrected linear potentiometer data.

353 (ii) The data were sorted such that they are grouped by sensor type in ascending
354 numerical order (e.g., A1, A2, A3, ..., L1, L2, L3, ...). The unprocessed and
355 converted data files are ordered in accordance with the data acquisition channel
356 used to collect the data, but this order is inconvenient for interpreting the data.

357 (iii) The data files were truncated to remove excess data collected before and after shaking
358 to reduce file size. Typically, 15 seconds of data are collected for each fast data
359 file, but only approximately 1 second corresponds to the shaking event. Enough
360 pre- and post-event data are left in the signals to facilitate proper interpretation of
361 the dynamic processes. However, the data files are too short to monitor pore
362 pressure dissipation following long shaking events, and the slow data should be
363 used for this purpose.

364 (iv) Sign conventions were assigned to the data quantities to maintain consistency with the
365 global coordinate system. Furthermore, centrifuge scaling factors are applied to
366 the data to produce prototype units. The centrifugal acceleration was 57g for all
367 experiments, and appropriate scale factors followed Kutter (1992).

368
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370

SAMPLE DATA

371 This section presents sample data to illustrate interesting features of the test and demonstrate
372 data quality. More complete presentation of the experimental data to support conclusions
373 from the experimental study is reserved for future publications.

374 Figure 11 shows slow data quantities including centrifuge g-level, pore pressure, and
375 settlement for Experiment 15 for a duration of time that encompasses spin-up, application of
376 a step wave and three ground motions, and spin-down. The model was spun up in increments

377 until the target acceleration of 57-g was reached, with each increment approximately
378 doubling the g-level. The incremental spin-up permitted pore pressures in the peat to
379 decrease, and undrained shear strength to increase, so that the peat could support the load
380 imposed by the levee. This process took approximately 3 hours. After reaching the target g-
381 level, the model was permitted to consolidate for about one hour. As pore pressures
382 decreased, settlement continued to increase due to primary consolidation and secondary
383 compression in the peat, and the levee showed signs of distress as a result of this settlement.
384 The ground motions were imposed before the levee accumulated too much distress, and P6
385 was still decreasing slightly at this time. The total consolidation settlement measured at the
386 levee crest prior to the application of the first ground motion was 55 mm (LP 14), while 35
387 mm of settlement occurred in the free-field.

388 The moderate Kobe motion had a peak base acceleration of 0.38g, and the levee fill liquefied
389 and slumped, resulting in a breach with water from the channel pouring over the levee and
390 eroding it away until the water elevation equalized on both sides of the levee (Figure 12).
391 Settlements at the levee crest measured 13 mm to 16 mm in model scale, which translates to
392 0.71 m – 0.91 m in prototype. Videos capturing the liquefaction process and sandy levee
393 failure are available on the NEES project warehouse.

394

395 The excess pore pressure within the levee fill recorded by P9 abruptly rises during
396 application of the Kobe motion and quickly dissipates due to the high permeability of the
397 sand, whereas the excess pore pressure in the peat beneath the levee decreases slowly after
398 the ground motion. Pore pressure in the free-field on the landward-side of the levee abruptly
399 increases and remains elevated. This is due to the water in the channel being released,
400 thereby permanently elevating the groundwater table on the landward free-field side of the
401 levee.

402 Two more ground motions with smaller amplitude were applied after the moderate Kobe
403 motion to observe the threshold for liquefaction triggering in the levee fill and to simulate
404 aftershocks. These motions induced a measurable pore pressure and settlement response.

405 Fast data recorded during the moderate Kobe motion are shown in Figure 13, including
406 acceleration, pore pressure, and settlement, all in prototype units. The peak base acceleration
407 was 0.38g and the peak acceleration of the levee crest was 0.28g, indicating that the soil
408 profile de-amplified the input motion. The pore pressure in the center of the sandy levee
409 increased by approximately 30 kPa, which is equal to the initial vertical effective stress at the

410 levee center, indicating the levee fill liquefied. Pore pressures in the sand remained elevated
411 for the duration of shaking, then dissipated quickly after shaking ceased. Excess pore
412 pressure in the peat beneath the levee exhibited a dynamic response during shaking and a net
413 reduction from the beginning to the end of shaking. This pore pressure response is caused by
414 a combination of shearing and changes in total stress as the levee breached and water flowed
415 over the top. Settlement records exhibit significant high frequency noise, but a dynamic
416 response is evident superposed on the noise, and the permanent component is clear. The levee
417 crest settled 0.7 m at the position of LP 14, which is near the center of the levee. The breach
418 occurred where settlement was highest, between the center of the levee and the container
419 wall.

420

421

SUMMARY AND CONCLUSIONS

422 This data paper describes the research objectives, test setup, instrumentation and data
423 organization of a series of centrifuge tests performed at the NEES@UC Davis equipment site
424 performed between January 2013 - March 2014. Eleven small scale centrifuge experiments
425 and four large scale centrifuge experiments studied the seismic behavior of levee-peat
426 systems. Test data achieved in the NEES project warehouse are assigned digital object
427 identifiers, and we recommend using the corrected data.

428 Potential uses of the data presented herein includes:

429 (i) Study the post-cyclic volume change potential of peat, which is a previously unidentified
430 mechanism that has been recently studied in the laboratory (Shafiee et al. 2015). Laboratory
431 results indicate the potential for a secondary compression clock reset due to cyclic shearing
432 of the peat with shear strains higher than 1%. This would contribute to an increase in the rate
433 of settlement of the levee fill following strong shaking. Centrifuge test data will provide
434 useful benchmarks to validate the laboratory outcomes given the wide range of shear strain
435 levels achieved during cyclic loading.

436 (ii) Evaluate the dynamic response of the clayey levee using concepts derived from soil-
437 structure interaction. The clay levee is stiff in comparison with the underlying peat, thereby
438 mimicking a stiff structure resting atop soil. The levee was observed to translate and rock on
439 top of a softer underlying layer, thereby altering the stress and strain distribution in the levee
440 fill and in the underlying peat. Vibration modes were presented by Cappa et al 2015 using
441 transfer functions for translation and rocking.

442 (iii) Study the influence of the peat and levee geometry on liquefaction potential of the levee
443 fill. Traditional liquefaction triggering procedures assume one-dimensional wave propagation
444 by assuming that the cyclic stress ratio is related to peak horizontal acceleration. However,
445 the peat permits the levee to rock, thereby resulting in principal stress directions that differ
446 from one-dimensional wave propagation. The influence of these stress rotations is currently
447 not well understood.

448 (iv) Validation of numerical simulations. The development of a nonlinear constitutive model
449 for peat is currently underway. The model focuses on matching the creep behavior of peat,
450 and its damping behavior. This includes the increase of secondary compression rate due to
451 cyclic loading. The model extends the one-dimensional hardening law described in Yniesta et
452 al. (2015), to three-dimensional loading conditions.

453

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460 facility team along with the undergrad and graduate students that assisted in laboratory and
461 model testing

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525

LIST OF FIGURES

Figure 1: Experiment setup for clay levee (a) and liquefiable sandy levee (b). Dimensions in model scale.

Figure 2: (a) Rigid Container with transparent walls and (b) cardinal coordinates of the centrifuge arm.

Figure 3: Experiment 12 configuration during testing. Dimensions in model scale cm.

Figure 4: Experiment 13 configuration during testing. Dimensions in model scale cm.

Figure 5: Experiment 14 configuration during testing. Dimensions in model scale cm.

Figure 6: Experiment 15 configuration during testing. Dimensions in model scale cm.

Figure 7. Test setup with clay levee resting atop peat prior to installation of the model container on the centrifuge for (a) RCK01 and (b) RCK02.

Figure 8: Sample shear wave velocity (V_s) measurements in the peat layer at 57g during RCK02.

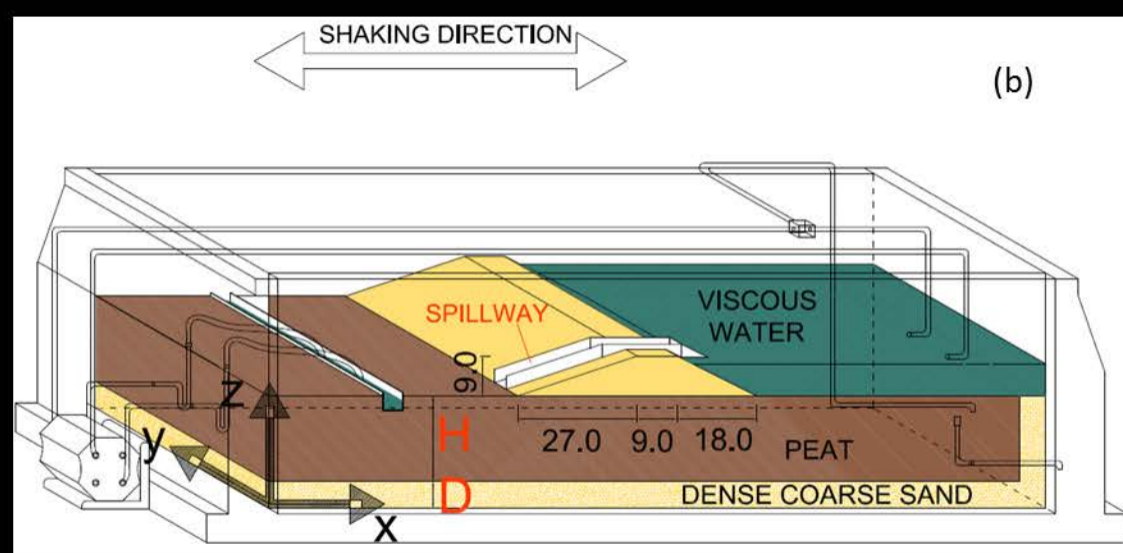
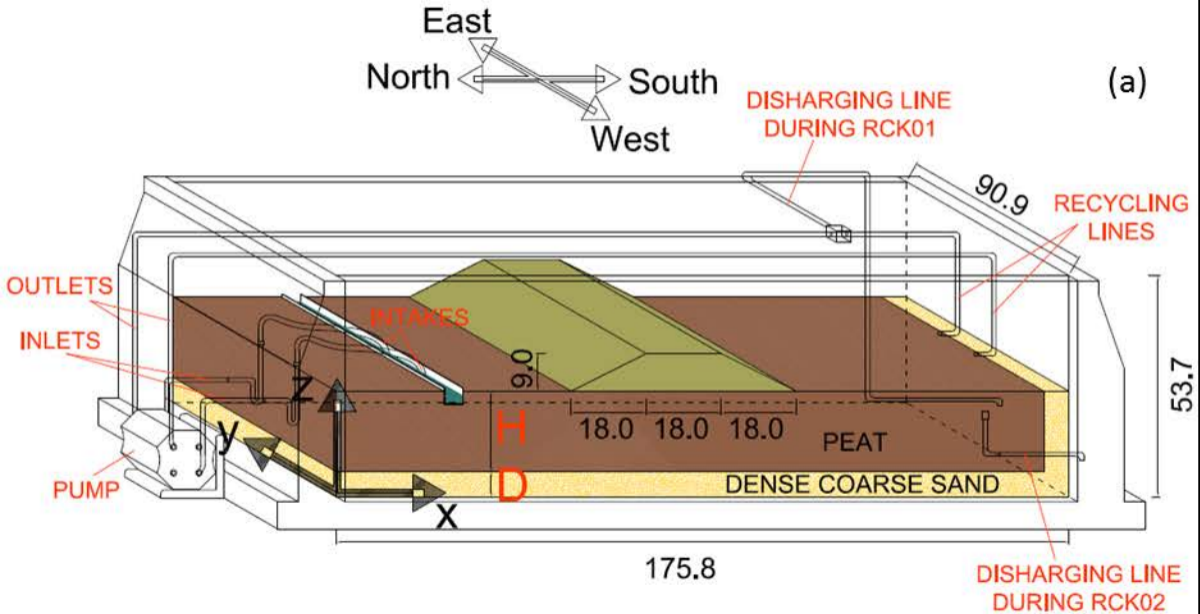
Figure 9. Parabolic data fitting to estimate V_{s1} and n for the various materials during RCK02.

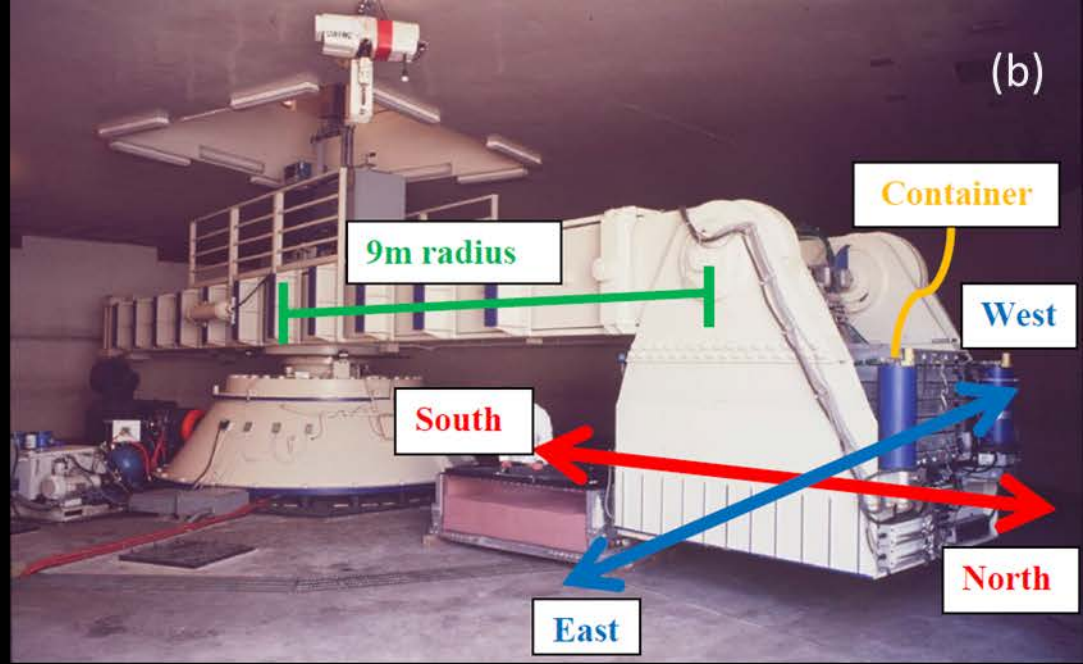
Figure 10. CPT data in the free field [EXP 14] and on the wet side of the sandy levee [EXP 15] during RCK02.

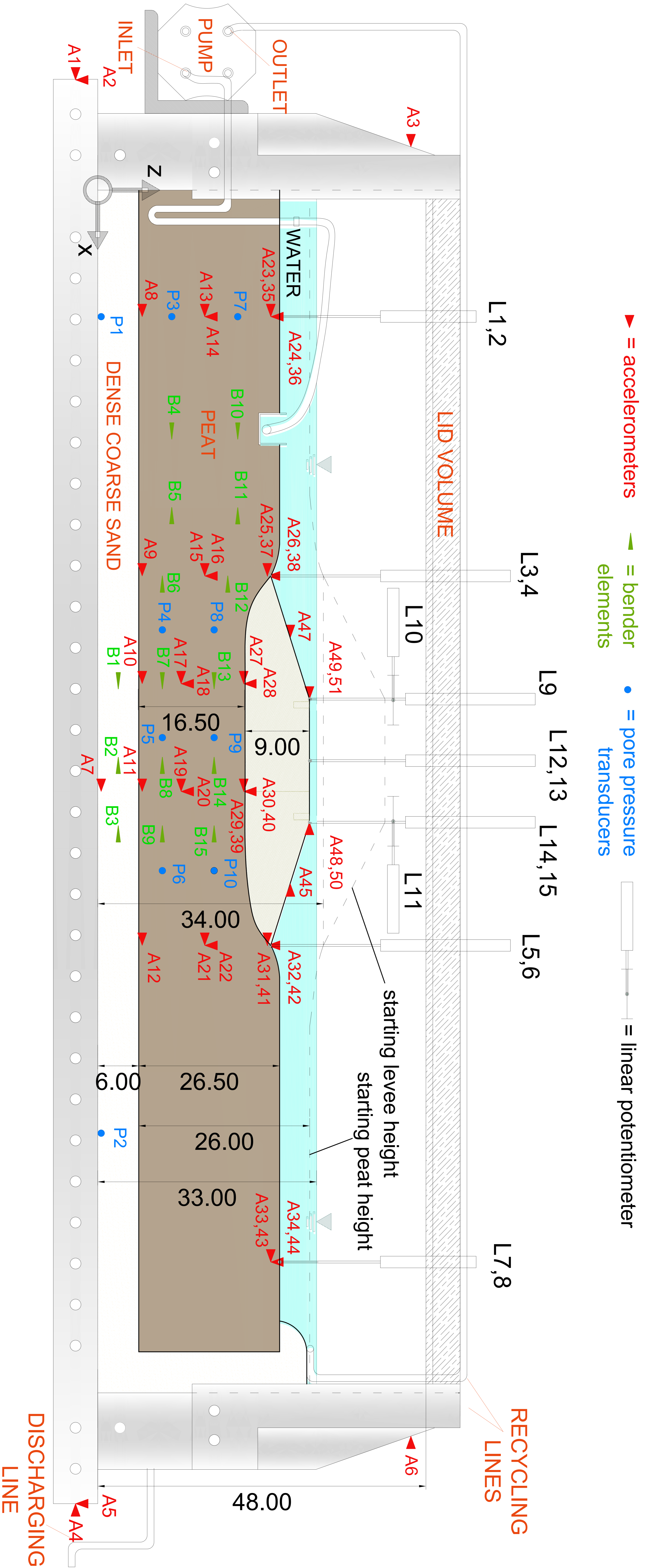
Figure 11: Slow data for Experiment 15 including (a) centrifugal acceleration, (b) pore pressure, and (c) settlement.

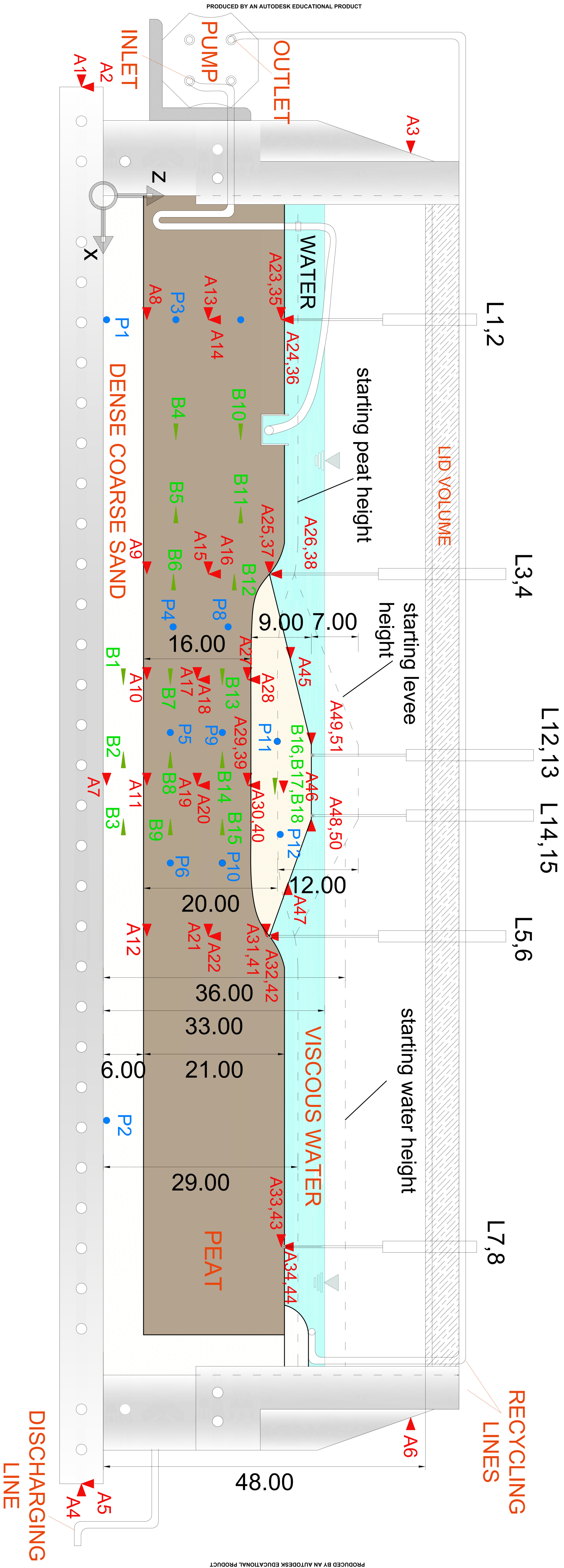
Figure 12: Sandy levee (a) before, and (b) after, application of the moderate Kobe motion.

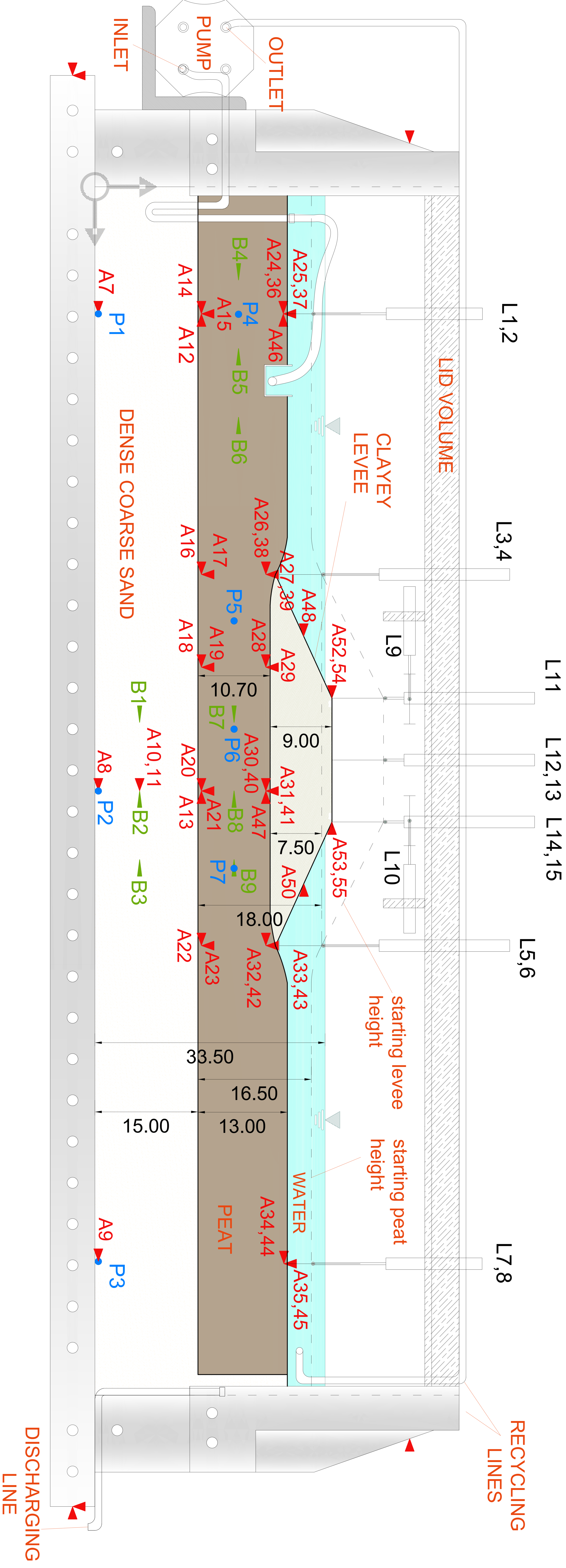
Figure 13 a-c: Prototype acceleration, pore pressure development and settlement time histories during the: Kobe Motion RCK02; Fast data for Exp 15

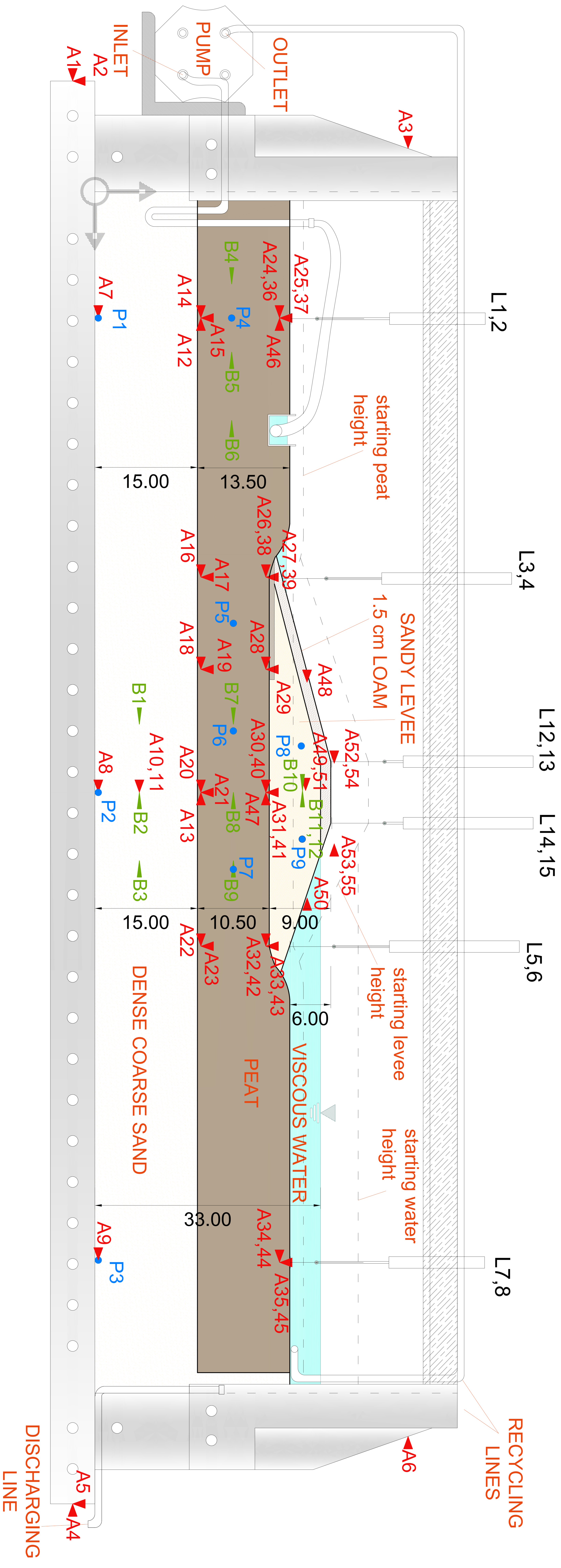


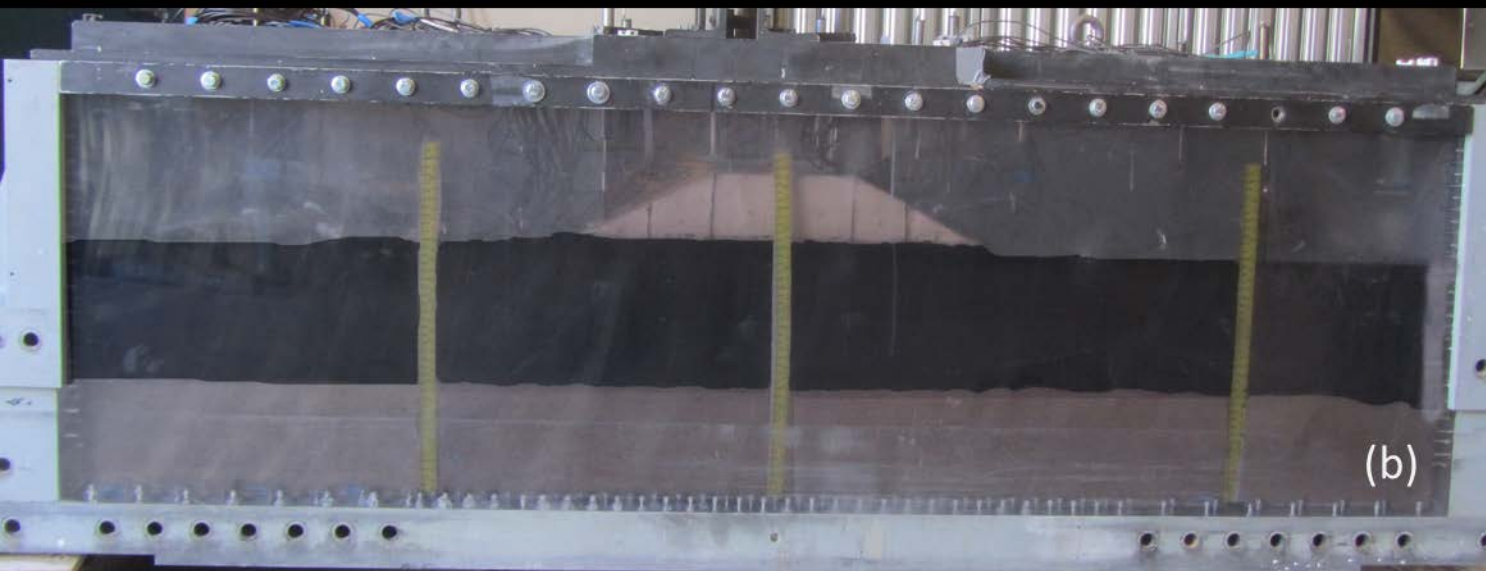


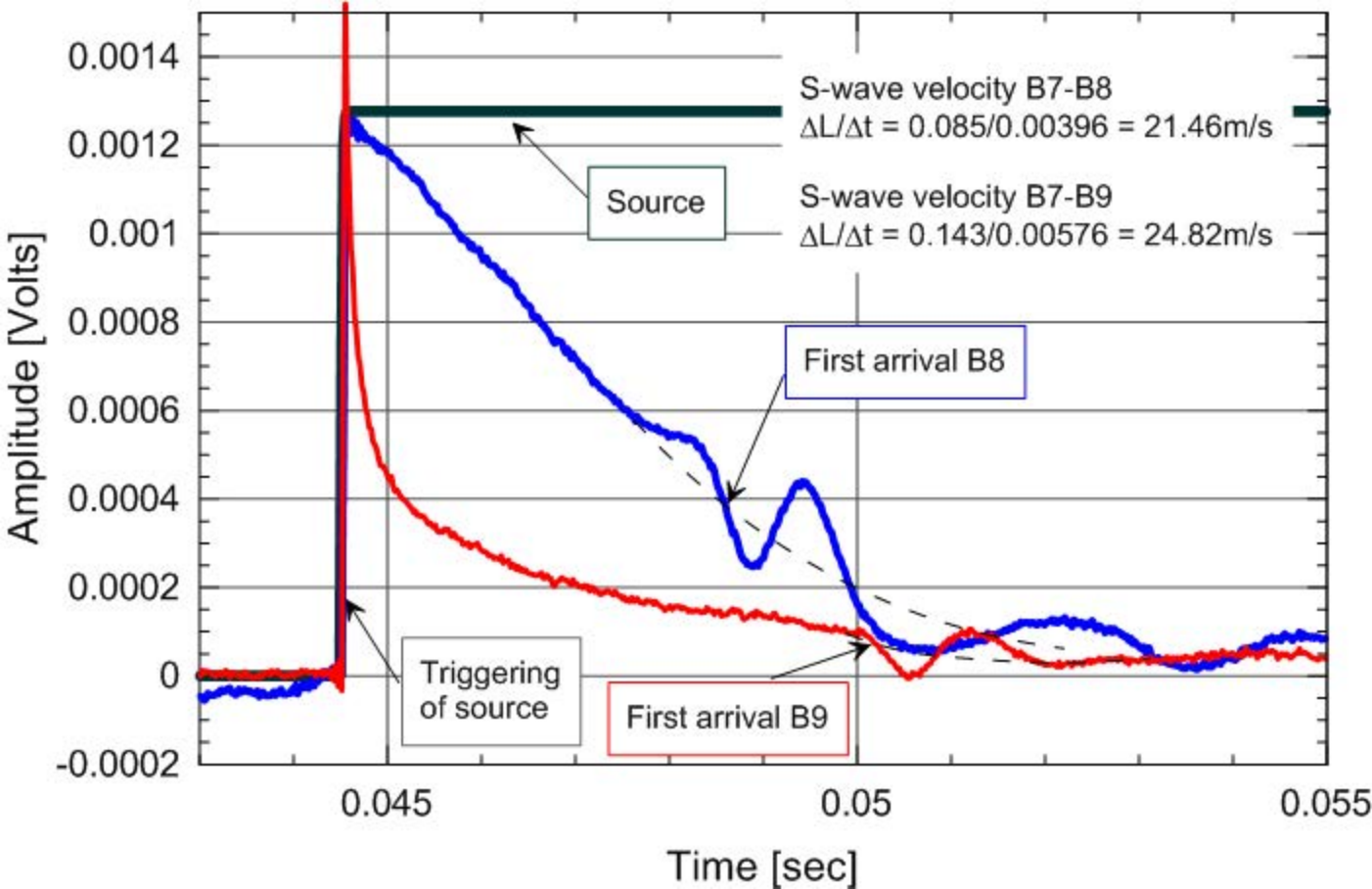












Fit Results

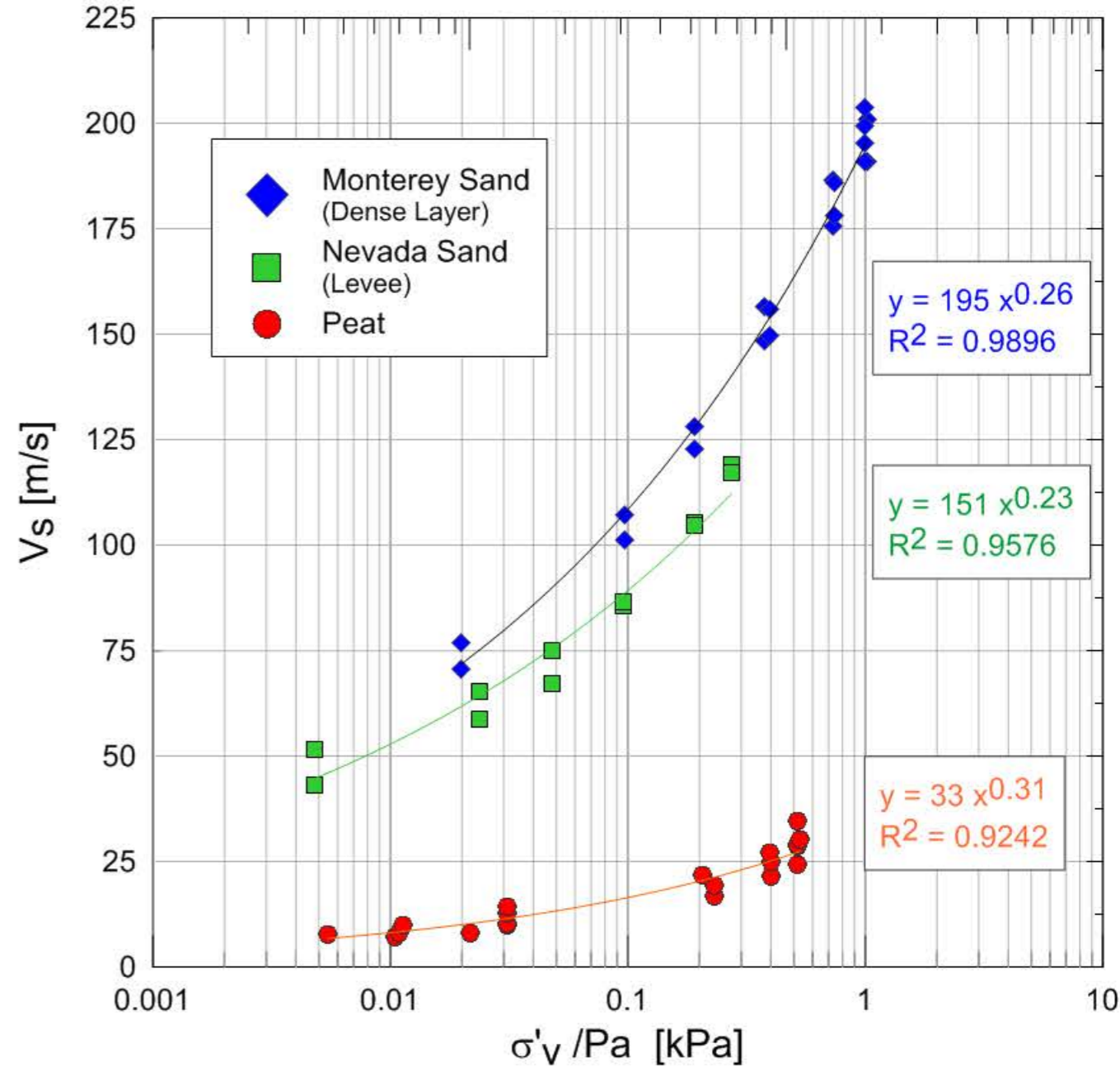
FIT FOR PEAT

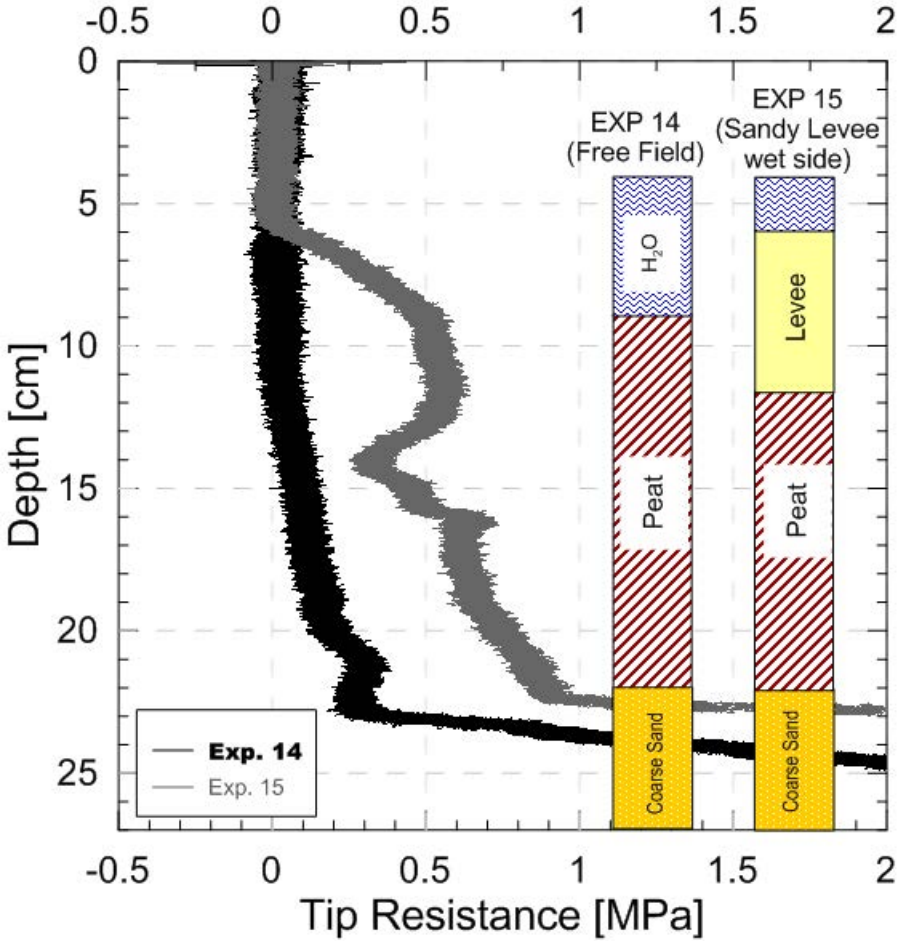
Equation $\ln(Y) = 0.3055639671 \ln(X) + 3.505815996$
 Alternate $Y = \text{pow}(X, 0.3055639671) * 33.30861245$
 Number of data points used = 20
 Average $\ln(X) = -2.35205$
 Average $\ln(Y) = 2.78711$
 Residual sum of squares = 0.399583
 Regression sum of squares = 4.86958
 Coef of determination, R-squared = 0.924166
 Residual mean square, sigma-hat-sq'd = 0.022199

Fit Results

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Time [sec] - model scale

