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
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The Atacama Cosmology Telescope: Summary of DR4 and DR5 Data Products and Data Access

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ABSTRACT

Two recent large data releases for the Atacama Cosmology Telescope (ACT), called DR4 and DR5, are available for public access. These data include temperature and polarization maps that cover nearly half the sky at arcminute resolution in three frequency bands; lensing maps and component-separated maps covering $\sim 2,100$ deg² of sky; derived power spectra and cosmological likelihoods; a catalog of over 4,000 galaxy clusters; and supporting ancillary products including beam functions and masks. The data and products are described in a suite of ACT papers; here we provide a summary. In order to facilitate ease of access to these data we present a set of Jupyter IPython notebooks developed to introduce users to DR4, DR5, and the tools needed to analyze these data. The data products (excluding simulations) and the set of notebooks are publicly available on the NASA Legacy Archive for Microwave Background Data Analysis (LAMBDA); simulation products are available on the National Energy Research Scientific Computing Center (NERSC).

1. INTRODUCTION

The Atacama Cosmology Telescope (ACT) is a 6 m telescope in the Atacama Desert in northern Chile with arcminute resolution (Fowler et al. 2007; Thornton et al. 2016). It has been mapping the millimeter sky since 2007, with three successive cameras. This paper summarizes the fourth and fifth data releases from ACT, referred to as DR4 and DR5. All the elements of the data releases are described in individual papers as outlined below; this paper gives a summary of the contents of the two data releases and describes a suite of Jupyter IPython notebooks that accompany the data products to facilitate their use.

The majority of the DR4 products use data collected from 2013–16 (hereafter s13–s16, likewise for other data seasons). These data cover $\sim 18,000$ deg², resulting in maps made in seven regions of the sky, in frequency bands centered at 98 and 150 GHz in both temperature and polarization. DR4 also includes data collected from 2008–10 (s08–s10). The maps from s08–s10 and s13–s16 are combined with those from the *Planck* satellite to create high-resolution “coadded” maps over the full footprint. The DR4 data products and pipelines are described in more detail in ACT collaboration publications as follows. The individual s13–s16 maps are described in Aiola et al. (2020) (A20, hereafter), while Choi et al. (2020) (C20, hereafter) provides additional details on their validation. The coadded s08–16 maps with *Planck* are in Naess et al. (2020) (N20, hereafter). Derived CMB lensing maps are presented in Darwish et al. (2020), and component separated CMB and Compton y -parameter maps in Madhavacheril et al. (2020a). The angular power spectra are described in C20, and cosmological likelihoods and parameters in A20. Delensed CMB power spectra are reported in Han et al. (2021), and the birefringence spectra in Namikawa et al. (2020).

DR5 adds ACT data acquired in 2017–18 (s17–s18) in frequency bands centered at 98, 150 and 220 GHz. The DR5 data products released so far consist of the coadded s08–s18 maps described in N20, and the derived galaxy cluster catalog presented in Hilton et al. (2021).

The outline of this paper is as follows. In §2 we describe the ACT instrument and the scope of DR4 and DR5. In §3 we describe the individual data products that are publicly available on the NASA Legacy Archive for Microwave Background Data Analysis¹ (LAMBDA) and at the National Energy Research Scientific Computing Center (NERSC). In §4 we give an introduction to the Jupyter IPython notebooks, which contain examples of working with DR4 and DR5 data as well as explanations of how to perform certain analyses. We summarize in §5. While this paper provides a summary, any work using these data products or notebooks should reference the appropriate science publication(s) (Aiola et al. 2020; Choi et al. 2020; Naess et al. 2020; Darwish et al. 2020; Madhavacheril et al. 2020a; Han et al. 2021; Namikawa et al. 2020; Hilton et al. 2021).

¹ https://lambda.gsfc.nasa.gov/product/act/actpol_prod.table.cfm

2. THE ATACAMA COSMOLOGY TELESCOPE

ACT comprises a 6 m primary and a 2 m secondary in an off-axis, Gregorian telescope design (Fowler et al. 2007). ACT’s elevation of $\sim 5,200$ m and the climate at its site on Cerro Toco in the Atacama Desert in Chile provide for excellent transparency at millimeter wavelengths.

ACT has operated with multiple generations of cameras, each housed in a cryostat with three separate cryogenic optics tubes holding silicon reimaging lenses. The earliest data in these releases are from ACT-MBAC, a set of three polarization insensitive detector arrays that were used for the s08–s10 data and observed at 150, 220, and 277 GHz (Swetz et al. 2008). In 2013 ACT deployed the polarization sensitive ACTPol receiver, which ultimately included three polarized detector arrays, including a dichroic array, and observed at 98 and 150 GHz (Thornton et al. 2016). Most recently, ACT updated to the Advanced ACTPol camera, which was used for the s17–18 data. This camera includes four dichroic detector arrays (three in use at a time), covers close to half the sky, and observes at 30, 40, 98, 150, and 220 GHz (Henderson et al. 2016), with the 30 and 40 GHz detectors included from 2020.

These releases use data from all three epochs, with a primary focus on the s13–s16 data from ACTPol for DR4 and the addition of s17–s18 for DR5. The s13–s16 observations cover seven regions (or “patches”) of the sky in the 98 and 150 GHz frequency bands in both temperature and polarization and are discussed in detail in A20 and summarized in §3.1 in this paper. Data from all three ACT receiver generations, including the additional s17–s18 data, are used in combination with *Planck* to create high-resolution, large-area, and deep “coadded” maps, presented in N20 and summarized in §3.2.1 and §3.8.

3. DATA PRODUCTS

The data products included in this release are outlined in Table 1, and comprise over 5 TB of data in total (4.5 TB are simulations). The data set, without the simulations, are publicly available on LAMBDA while simulations are housed on NERSC. Instructions on how to access NERSC are available on the ACT data products page on LAMBDA. Questions about these products can be directed to the ACT data help desk.²

The majority of the maps are released in the Flexible Image Transport System (FITS, see e.g. Pence, W. D. et al. (2010)) format; the FITS system is widely used in the astronomy community. As described in A20, the Q and U Stokes polarization components of all of the maps are defined using the IAU convention, specified in the FITS file header by the keyword POLCONV=IAU. Earlier pre-DR4 ACT maps were released following the COSMO convention (Gorski et al. 2020).

These maps are all released as CAR, or Plate Carrée, maps with rectangular pixelization and x and y axes aligned with right-ascension and declination, respectively. This is distinct from the HEALPix³ format commonly used for CMB data. The CAR projection is a rectangular projection where each pixel represents a constant interval in right-ascension and declination. This results in pixel areas that depend on latitude, with the largest areas at the equator. Compared to HEALPix, the CAR pixelization has the advantage of simpler and hence faster coordinate calculations; simpler extraction and representation of sub-maps; arbitrary resolution, and a simple and exact pixel window. Because these CAR maps are stored as 2D arrays, they can also be displayed as is, without needing to transform them into another projection, as is the norm with HEALPix. On the other hand, CAR has the disadvantage of increasingly oversampling the maps as one moves away from the equator.⁴ The Jupyter IPython notebooks presented in §4.2 provide tutorials with explanations of how to use these maps.

3.1. DR4 Frequency Maps⁵

With the exception of the simulations, the largest component of DR4 is ~ 300 GB worth of CMB maps from the s13–s16 nighttime data. These maps span close to half the sky at 0.5 arcmin x 0.5 arcmin resolution and include 94 data sets, each of which contains four FITS files as outlined below. These maps, which are the basis for all of the other ACT DR4 data products, are presented in A20. Section 5.1 of that paper explicitly details the format of the products and files available.

² The help desk can be reached at act_data_support@googlegroups.com and more information is available on LAMBDA.

³ <https://healpix.sourceforge.io/> (Gorski et al. 2005)

⁴ It is sometimes thought that CAR maps inherently make assumptions about the sky being flat, and that HEALPix is needed for a curved-sky analysis. This is not the case. The question of flat-sky vs. curved-sky is not connected to the projection used, and instead depends on how one analyzes the data in the map, e.g. whether one uses Fourier or spherical harmonic transforms. `pixel1` (a software package discussed in §4.2.2) fully supports curved-sky operations on CAR maps, though it allows one to use the flat-sky approximation should one want it.

⁵ Maps originally presented in A20.

Summary of DR4 and DR5 Data Products

Category	Dataset	Products	Suggested Uses
DR4 Data Products			
Frequency Maps	Per season/patch/array/frequency	Source-free maps and splits Source maps for above Inverse-variance maps for above Cross-linking maps for above	Precision cosmology (e.g. see notebooks 8 §4.2.8 and 9 §4.2.9)
Derived Maps	Coadd maps of s08–s16 data	Source-free maps Source maps for above Inverse-variance maps for above	Studying arcminute-scales Studying galaxy clusters, point sources, and Galactic emission
	Component separated maps	CMB+kSZ maps tSZ/Compton- y maps	Cross correlations with external data (e.g. see notebook 5 §4.2.5)
	Lensing maps	Lensing- κ maps	
Ancillary Products	Masks	Footprint masks Point source masks Lensing masks Masks for component separated maps	Needed for a range of cosmological analyses
	Window functions	Beams Leakage beams Beams for component separated maps Map-making transfer functions	
Derived Spectra		Multifrequency spectra CMB-only spectra Birefringence spectra Delensed spectra	Plotting binned spectra Comparisons to other data sets
Likelihoods	Multifrequency likelihood	Fortran implementation	Testing theoretical models
	Delensed likelihood	CosmoMC compatible code	Combining with other data sets
	CMB-only likelihood	Fortran and Python implementations	Examining covariance matrices
Cosmological Results	Likelihood products	Best fit parameters Chains of cosmological parameters	Comparing with other data sets
	Delensing likelihood products	Best fit parameters Delensed theory Chains of cosmological parameters Parameter-shift covariance matrix	Plotting parameter distributions (e.g. see notebook 11 §4.2.11)
Simulations	Maps	Signal simulations Lensing kappa simulations	These can be used to validate pipelines and
	2D Power spectra	Square-root covariance matrices Lensed CMB a_{lm} Lensing phi a_{lm}	for error analysis (e.g. see notebook 9 §4.2.9)
DR5 Data Products (Available to Date)			
Cluster Catalog		4,195 SZ clusters	Cluster cosmology, stacking analyses (e.g. see notebook 4 §4.2.4)
Derived Maps	Coadd maps of s08–s18 data	Source-free maps Source maps for above Inverse-variance maps for above	Studying arcminute-scales Studying galaxy clusters, point sources, and Galactic emission (e.g. see notebook 2 §4.2.2)

Table 1. An outline of the data products included in the two data releases, DR4 and DR5. Information relating to the particular products is discussed in §3. The last column gives some suggested applications, with examples discussed in §4.2. The majority of data products are DR4 (using s08–s16 data); the s08–s18 coadd maps and derived cluster catalog belong to DR5.

Subset of ACT DR4 and DR5 Derived Data Products

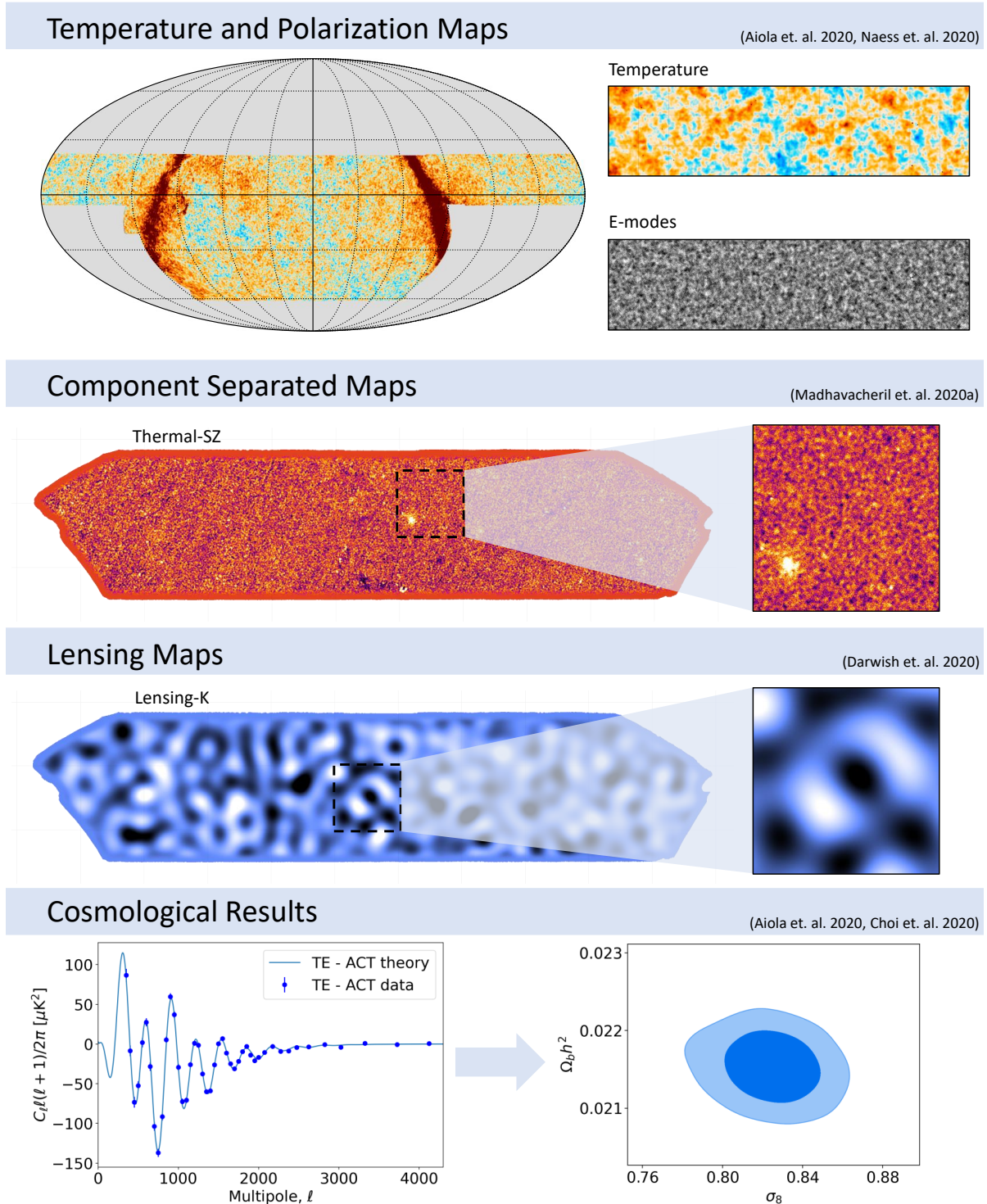


Figure 1. ACT DR4 and DR5 products available to date consist of more than 5 TB of data including temperature and polarization maps, likelihoods, delensed spectra, and simulations. Here we show a sample of the products. Top row: coadded temperature and polarization maps of ACT with *Planck* (N20). The cutouts are centered at -162° (7°) with a dimension of 24° (6°) in right-ascension (declination). Second row: component separated and lensing maps of the D56 region from Madhavacheril et al. (2020a) and Darwish et al. (2020). The cutouts are 5° on each side and centered at 12.5° (0°) and 17.5° (-2.5°) in right-ascension (declination), respectively. The lensing map has been low-pass filtered with a cutoff at $l = 200$ to isolate signal-dominated modes (see Figure B2 of Darwish et al. (2020)). Bottom left: the ACT best-fit *TE* power spectrum (from the ACT likelihood) together with binned data points (C20). Bottom right: 2D parameter distribution generated from the Markov Chain Monte Carlo (MCMC) parameter chains (A20).

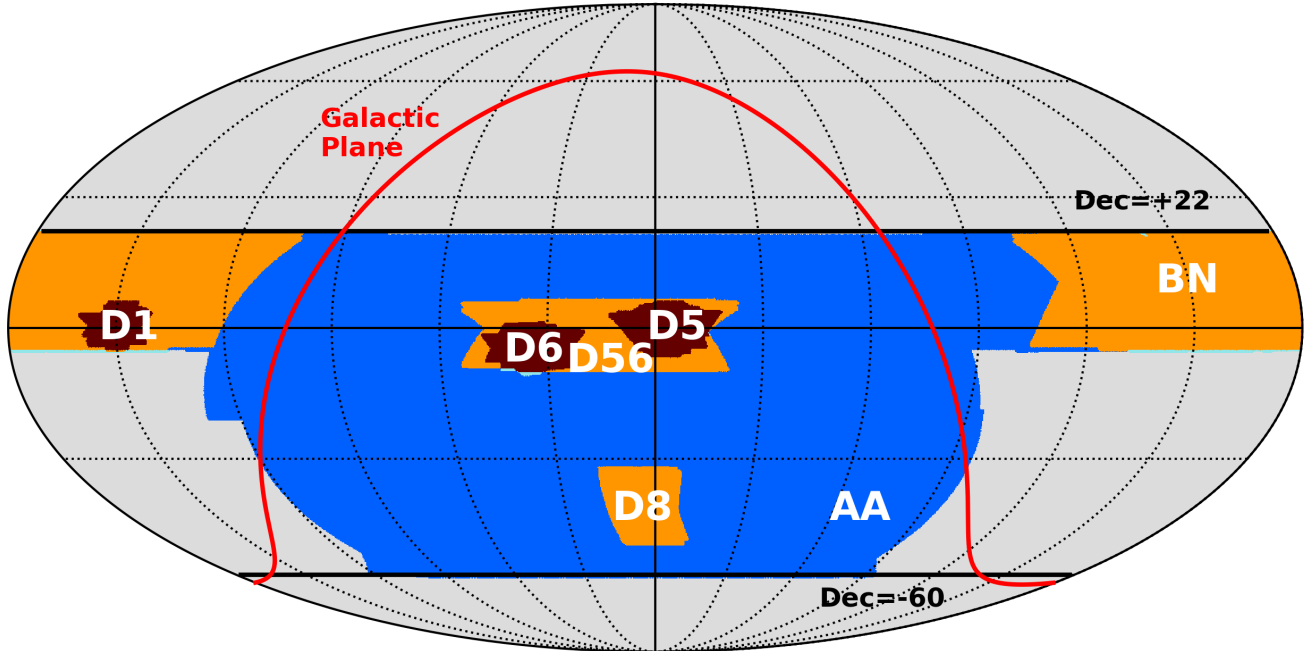


Figure 2. A schematic representation of the observation regions, or patches, in the DR4 frequency maps, as presented in A20. The map is presented in equatorial coordinates, with the D1, D5, and D6 patches in dark red, the D56, D8, and BN patches in orange, and the AA patch in blue. The coadded maps from N20 discussed in §3.2.1 and §3.8 cover the full area between the lines of constant declination, given in degrees. The Galactic plane is overplotted in red for reference. Related figures appear in A20 and C20, in Galactic coordinates.

The maps are grouped according to the observation season, detector array, patch, and frequency channel. For this release there are seven separate patches which range in size from $\sim 100 \text{ deg}^2$ to $\sim 17,000 \text{ deg}^2$, shown in Figure 2. The release also includes data from the 98 and 150 GHz channels (depending on detector array) from three detector arrays, referred to as PA1, PA2 and PA3. Precise sky areas for each patch, the different season/detector array/patch/frequency combinations, and the corresponding map-space white noise levels in $\mu\text{K}_{\text{CMB}}\text{-arcmin}$ are given in A20 and repeated here in Table 2.

The map set includes both separately processed subdivisions – or “splits” – of the data as well as coadded maps. For each detector array/frequency/patch/season the release includes four splits, with the exception of the AA patch (named for AdvACT and shown in Figure 2), for which there are only two splits. These splits are made by dividing the time-ordered data into non-overlapping, day-long blocks. Each split is evenly assigned these blocks in order to ensure the resulting split maps have similar hit count distributions (A20). Each split map therefore has an independent realization of the noise (see C20 and §4.2.9), making them useful for cross correlations. The coadded maps are inverse variance weighted co-additions of the splits, which are not the same as the more complicated multi-array, multi-frequency “coadds” found in N20.

The splits are discussed in greater detail in A20 and C20 Section 6.1. They are also used for the power spectrum analysis presented in C20 and in §3.4, since the noise in each split is independent. Because these maps are well-characterized and include separate splits of the data they are optimal for precision cosmology.

In addition to the CMB maps the release includes a set of other data products that can be used for relevant analyses. In particular, the following data are available:

- Source-free maps: these contain I , Q , and U Stokes components, using the IAU polarization convention, and are in units of μK (differential CMB temperature units, hereafter μK_{CMB}). Some sources are subtracted in the time domain during map-making, while others are subtracted at the map-level (see Section 4.5 of A20 for details on the point source subtraction).

DR4 Frequency Maps: Summary of Patch Sizes and Map White-noise Levels

Map Patch and Area	Season, Detector Array, and Frequency			
	s13	s14	s15	s16
	PA1 ₁₅₀	PA1 ₁₅₀ /PA2 ₁₅₀	PA1 ₁₅₀ /PA2 ₁₅₀ /PA3 _{98/150}	PA2 ₁₅₀ /PA3 _{98/150}
D1 (131 deg ²)	19	—	—	—
D5 (157 deg ²)	16	—	—	—
D6 (135 deg ²)	13	—	—	—
D56 (834 deg ²)	—	32/21	33/22/18/29	—
D8 (248 deg ²)	—	—	42/22/20/29	—
BN (3,157 deg ²)	—	—	77/41/34/49	—
AA (17,044 deg ²)	—	—	—	73/79/120

Table 2. White noise levels in μK_{CMB} -arcmin for the individual season/detector array/frequency/patch maps. Observation patches correspond to those presented in Figure 2. The area on the sky of each patch is also listed. “PA” refers to “polarization array,” or polarization-sensitive detector array. Subscripts indicate frequency band; PA3 is dichroic, with detectors observing the sky at both 98 and 150 GHz. This reproduces Table 2 of A20, with white noise data rounded to two significant figures.

- Source maps: these contain the point-source signal removed from the full maps in units of μK_{CMB} . The sum of the source-free and source maps in a given data set gives the total sky map.
- Inverse-variance (“ivar”) maps: akin to traditional hit count maps, these maps contain an estimate of the inverse-variance *per pixel* of the frequency maps. They are used (for example) to construct masks for the source-free maps as demonstrated in notebook 8 (§4.2.8). However, unlike traditional hit count maps, these include the variance contribution from detector noise as is necessary for data operations in map-space. Although in principle the polarization components at each pixel are correlated, DR4 makes available only the “*II*” element of the inverse-covariance matrix, for two reasons: first, in practice the matrix is diagonal, and second, the “*QQ*” and “*UU*” elements are \sim half that of the “*II*” element (A20). The release provides the “ivar” maps in units of $(\mu\text{K}_{\text{CMB}})^{-2}$.
- Cross-linking maps: cross-linking is the degree to which a pixel is uniformly covered in *scan direction*. A pixel is well cross-linked if the telescope scans across it in multiple different directions (e.g. up/down, left/right, diagonally, etc.). Conversely, a pixel is not cross-linked if the telescope always takes the same path across it. The cross linking maps, like the maps themselves, include three components. The first (*T*) component is the inverse variance map; the second (*Q*) component measures the angle between the scanning direction and north; the third (*U*) records whether a given scan was on the rising or setting side of the sky (A20). For example, the equivalent to the polarization fraction of the cross-linking maps gives the cross-linking fraction, where 0% means uniform coverage in scan direction, and 100% means only one scan direction covers this pixel (C20).

3.2. DR4 Derived Maps

The DR4 frequency maps from §3.1 can be used to form “derived maps.” These products include coadded maps in temperature and polarization from N20, component separated maps from Madhavacheril et al. (2020a), and lensing maps from Darwish et al. (2020). These products are all outlined in Table 1.

3.2.1. DR4 Coadded Maps⁶

While the individual map splits together span a large sky fraction, they do so in small patches and with the noise characteristics of individual seasons and detector arrays. To complement these smaller, noisier maps DR4 includes full ACT-observed sky coadded maps in the 98 and 150 GHz frequency channels, as described in N20. One of these maps is shown in the top panel of Figure 1. These maps combine ACT data from s08–s16 with data from *Planck*, preserving ACT’s high-resolution and sensitivity to small scales while adding *Planck*’s sensitivity to large angular scales. The procedure results in individual temperature and polarization maps covering $\sim 18,000 \text{ deg}^2$ ($f_{\text{sky}} \sim 0.44$) at a resolution of 0.5 arcmin x 0.5 arcmin. Since these maps are deeper, and because quoted sky area is a function of noise level, these coadded maps cover marginally more area than the maps in §3.1. The full-coadded depth is $\leq 20 \mu\text{K}_{\text{CMB}}$ -arcmin over $\sim 2,600 \text{ deg}^2$ (see Figure 14 of N20). See §3.8 for the corresponding improvements in map-depth when s17–s18 data from the AdvACT survey are included in DR5.

DR4 includes coadded maps with and without point sources, as ACT-only and ACT+*Planck*, and in the 98 and 150 GHz channels. In addition to the maps themselves, DR4 includes associated inverse-variance maps, which can be used to characterize the noise in the maps.

The coadded maps are not recommended for precision cosmology as they lack map splits needed to generate noise simulations or run null tests; the DR4 frequency maps in §3.1 are more appropriate. §3.8 describes applications that are well suited for the coadded maps.

3.2.2. DR4 Component Separated Maps⁷

DR4 includes component separated maps of the CMB+kSZ black-body component, and the thermal Sunyaev-Zeldovich Compton- y parameter, presented in Madhavacheril et al. (2020a). These maps combine multi-frequency data from ACT and the *Planck* satellite to construct arcminute resolution, component separated maps that cover a wide area ($\sim 2,100 \text{ deg}^2$). The CMB+kSZ and Compton- y maps are provided for the BN and D56 regions shown in Figure 2. We also show one of these component separated maps in Figure 1.

These maps are constructed from an internal linear combination (ILC) of the ACT maps at 98 and 150 GHz and the *Planck* maps at 30, 44, 70, 100, 143, 217, 353 and 545 GHz. The algorithm (see e.g., Remazeilles et al. 2011) uses the frequency dependence of a signal of interest to create a map that preserves that specific signal while minimizing the overall variance. This minimization is done in the 2D Fourier domain to adapt to the noise properties of a ground-based experiment like ACT. Maps that explicitly null foreground contamination from specific components with assumed frequency dependence are also provided; in particular (a) Compton- y maps that null the contribution of a dust/CIB-like spectral energy distribution (useful for checks of systematic contamination in cross-correlations) and (b) CMB+kSZ maps with tSZ deprojected for use in lensing estimators, among others. See Madhavacheril et al. (2020a) for more discussion of these maps, the procedure used to generate them, and the relevant caveats.

3.2.3. DR4 Lensing Maps⁸

The DR4 s14–s15 data were also used to construct gravitational lensing maps, as described in Darwish et al. (2020). The maps are available for the D56 and BN regions (see Figure 2), in versions with and without *Planck* data. One of the lensing maps is shown in Figure 1. The lensing maps are produced by first coadding the maps at 98 and 150 GHz and over two seasons (s14–s15) to produce input maps for the lensing estimator. The maps are then convolved to a common beam, inpainted around bright sources in order to account for foreground biases, and cleaned to reduce the effect of ground contamination. These maps are then passed through the lensing reconstruction pipeline which uses a minimum variance quadratic estimator. The end result of this process is a set of maps that cover $\sim 2,100 \text{ deg}^2$ on the sky and are signal dominated on large scales. They also overlap with a number of optical surveys which enables them to be used for cross correlations with BOSS CMASS galaxies, for example (see Darwish et al. 2020). DR4 also includes lensing maps with the thermal Sunyaev-Zel’dovich (tSZ) signal removed, following the procedure outlined in Darwish et al. (2020) (building on the method from Madhavacheril & Hill (2018)), which has a minimal effect on the lensing signal-to-noise ratio.

⁶ Maps originally presented in N20.

⁷ Maps presented in Madhavacheril et al. (2020a).

⁸ Maps presented in Darwish et al. (2020).

3.3. DR4 Ancillary Products

The ACT map-based and cosmological data products require several secondary inputs – or ancillary data products – to support specific analyses, including masks and beams. The masks include point source and extended source spatial masks produced by the ACT map-making pipeline (A20), as well as masks of Galactic foregrounds produced by *Planck* (C20, [Planck Collaboration et al. 2020a](#)). The combined spatial masks serve as inputs to the ACT power spectrum pipeline (C20). In addition to the point source masks, DR4 includes a set of masks based on the multifrequency cross-linking and inverse-variance maps (C20), labeled “footprint” masks in [Table 1](#). It also includes the spatial masks used in [Darwish et al. \(2020\)](#) to make lensing maps, and in [Madhavacheril et al. \(2020a\)](#) to make component separated maps.

For many analyses, correct treatment of the ACT maps rely on an accurate understanding of the beam. A20 provides a detailed description of the beam model as well as the beam products included in DR4. There are four main differences between the various beam products:

- Real-space or harmonic space: we include both the real-space azimuthally-averaged beam profiles and the harmonic-space beam transfer functions.
- “Instantaneous” vs “jitter”: the jitter beams include effects of pointing-error variance while the instantaneous beams do not. The jitter beams are recommended for map-domain analyses.
- Corrections: each beam is also provided with and without a Rayleigh-Jeans-to-CMB spectral correction for the ACT bandpasses.
- Season/detector array/frequency(/patch): the release includes beams for each of the maps and the file names indicate which map corresponds to which beam. Note that only the jitter beams contain patch flags, and so these are not needed for the instantaneous beams.

The maps have not been corrected for the smoothing introduced by the beam. Therefore, users must properly account for the beam in their analysis. For map-based analyses, such as comparisons between data sets, users will need to convolve the secondary data set with the ACT beam. Similarly, users can correct for beam effects in harmonic space by dividing out the beam transfer function ([Bond & Efstathiou 1987](#)). In addition to the beams themselves, the beam leakage between temperature and polarization is also characterized. DR4 includes the T - E and T - B harmonic-space beam leakages for both the beam core and the polarized sidelobes, as discussed in A20. The beams for the component separated maps are also provided; the component separated maps themselves (§3.2.2) are already convolved with these beams. Finally, DR4 makes available the harmonic-space mapping transfer function associated with the ground-pickup filter used in C20.

3.4. DR4 Power Spectra

DR4 includes the TT , TE and EE power spectra described in C20. The multi-frequency spectra at 98 and 150 GHz are derived from the DR4 frequency maps. We show one of these spectra in [Figure 1](#). These spectra are combined with intensity spectra from s08–s10 to produce CMB-only TT , TE and EE spectra. More information relevant to these products is found in A20 and C20.

In addition to this full suite of DR4 spectra, the release includes the birefringence spectra from [Namikawa et al. \(2020\)](#), based on s14 and s15 of the ACT polarization data. Lensed and delensed spectra from the D56 region are presented in [Han et al. \(2021\)](#) and §3.7.

3.5. DR4 Likelihoods and Cosmological Parameters

The maps discussed in the previous section are used to produce a number of products for cosmological analyses including two likelihoods. These consist of a multi-frequency likelihood, and a CMB-only likelihood. The CMB-only likelihood, which does not require sampling over foreground parameters and is simplest for use in cosmological parameter estimation, has versions both in Fortran 90 and in Python.⁹ As discussed in A20 and C20, the likelihoods are used to generate Markov Chain Monte Carlo (MCMC) chains to derive constraints on cosmological parameters. A set of these chains has also been included in the release. A 2D parameter distribution plot generated from one of these chains is shown in the bottom row of [Figure 1](#).

⁹ <https://github.com/ACTCollaboration/pyactlike>

3.6. DR4 Simulations

Simulations are key tools in the validation of the ACT data products. They are used throughout the ACT analyses in order to calculate transfer functions and covariance matrices, as well as to perform consistency tests. Due to the quantity of data associated with these simulations (90% of the DR4 disk space), they are not directly available on the public LAMBDA server; instead, they are accessible through NERSC. However, the instructions for access to the simulations, as well as the location at NERSC, are posted on the same LAMBDA webpage as the other data products. The DR4 simulation products (see Table 1) are either maps or the power spectra of various components that comprise those maps, and are shared amongst the DR4 product pipelines. In addition, Madhavacheril et al. (2020a) and Darwish et al. (2020) manipulate simulated maps as inputs to, or tests of, other analyses.

The “base level” simulation product used throughout DR4 are observed-sky simulations. Their goal is to efficiently replicate the raw “telescope-observed” sky, including lensing, foregrounds, and noise, analogous to the DR4 frequency maps in 3.1. They have several layers:

- Lensed, Gaussian realizations of the primary CMB with cosmological parameters set equal to the *Planck* 2018 results (Planck Collaboration et al. 2020b). The release provides the `lensedcmb_alms`, which are the spherical harmonics of the lensed CMB simulations. Since these are given in $a_{\ell m}$ format, they must be projected into map space. The release also provides the `lensing_phi_alms` that generate the lensing potential present in the `lensedcmb_alms`.
- Gaussian realizations of extragalactic foregrounds such as tSZ and radio galaxies.¹⁰
- Gaussian realizations of the map-based noise in each patch, according to the prescription outlined in C20 and discussed in depth in 4.2.9. The release provides “square-root covariance” matrices that facilitate fast sampling of the Gaussian noise field. These matrices are represented in the same basis as the noise covariance, with eigenvalues equal to the square-root of the noise covariance eigenvalues. See e.g. Appendix B of C20 for an explanation.

As the noise is the most technical of these three layers, we provide an example of a “square-root covariance” matrix and associated usage code in one of our notebooks (§4.2.9).¹¹ This base set of “telescope-observed sky” simulations are direct inputs to C20, Madhavacheril et al. (2020a), and Darwish et al. (2020).

The base simulations are also accompanied by 560 simulations of the component separated maps discussed in §3.2.2. These simulations mirror the format of the component separated maps and can be used to generate covariance matrices and characterize the data presented in Madhavacheril et al. (2020a). The foreground-cleaned observed-sky simulations are passed as inputs to 511 simulations of the lensing- κ maps, as discussed in §3.2.3. Darwish et al. (2020) then validates the pipeline by cross-correlating the reconstruction with the input lensing fields and finds good agreement.

3.7. DR4 Delensing Products¹²

Han et al. (2021) use internally reconstructed lensing maps of the D56 region to produce delensed power spectra at 98 and 150 GHz. From this, they obtain constraints on Λ CDM cosmological parameters using the power spectrum of the delensed CMB.

This release includes the lensed and delensed spectra from D56, the delensing likelihood, and the products derived from the likelihood (the theory curves, the best-fit parameters, the MCMC chains, and the parameter-shift covariance matrix). In order to facilitate direct comparison between the lensed and delensed results the release also provides the lensed spectra of just the D56 area computed with this pipeline.

3.8. DR5 Coadded maps¹³

The DR5 maps follow the same format as those in Sec 3.2 for the DR4 coadded maps, but they additionally include preliminary maps from s17 and s18 data, daytime data, and data from the 220 GHz channel, as described in N20.

¹⁰ Though not formally part of DR4, the foreground power spectrum is available from the `actsims` repository as `fg.dat`; see <https://github.com/ACTCollaboration/actsims>.

¹¹ The DR4 matrices match the ones used in C20. However, due to a version update in September 2019, users will find percent level differences when using the most recent version of `pixell`. If users would like to exactly recreate the noise simulations as utilized in C20, they should install a version of `pixell` released prior to September 17th, 2019. This version is available at <https://github.com/simonsobs/pixell/pull/77>

¹² Full data products presented in Han et al. (2021).

¹³ Maps originally presented in N20.

Optimally combining data from the ACT-MBAC, ACTPol, and AdvACT surveys as well as *Planck*, the DR5 coadded maps cover the same total $\sim 18,000 \text{ deg}^2$ sky footprint as DR4 but with a full-coadded depth of $\leq 10 \mu\text{K}_{\text{CMB-arcmin}}$ over $\sim 2,500 \text{ deg}^2$.

These maps are ideal for producing cluster catalogs, such as in §3.9, and are well suited for stacking analyses such as measurements of the tSZ and kSZ effects (Schaan et al. 2020; Amodeo et al. 2020; Calafut et al. 2021; Vavagiakis et al. 2021), cluster lensing (Madhavacheril et al. 2020b), point source and cluster studies, and Galactic science. Due to the preliminary nature of the s17–s18 data, the DR5 coadded maps are not recommended for precision cosmology. This includes $TT/TE/EE$ power spectrum estimates, reconstructed lensing power spectra and cross-correlations, birefringence, primordial bispectra, and component-separated CMB and Compton y -maps. For a discussion of the technical reasons why the s17–s18 data are preliminary, as well as these caveats, see N20 Section 2.2.3 and the publicly-available explanatory supplement.¹⁴ Maps with ACT data observed from s17 onwards, that are appropriate for precision cosmology, are expected in the next ACT data release, DR6.

The DR5 maps are presented with and without point sources, as ACT only and ACT+*Planck*, with the ACT nighttime only or night + day data, and in the 98, 150 and 220 GHz channels. With the exception of the detailed noise maps below, all maps are produced at 0.5 arcmin x 0.5 arcmin resolution. The s08–s18 coadded DR5 maps and the s08–16 DR4 maps are interchangeable in analysis pipelines, including the Jupyter IPython notebook in §4.2.2.

In addition to the maps, the data release includes a range of ancillary data products:

- Inverse-variance maps: similar to those presented in §3.1, that provide estimates for the non-atmospheric inverse-variance per pixel in the maps.
- Detailed noise maps: in addition to per pixel inverse-variance, these maps also present the inverse-variance across 50 multipole bins. Their pixel size is larger than the simple inverse variance maps: 0.5 deg x 0.5 deg vs. 0.5 arcmin x 0.5 arcmin. They are also presented on a per-array basis.
- Bandpasses: provided for each of the 15 detector arrays, these bandpasses are normalized for comparison. The normalization is detailed in Equation 6.1 of N20 and results in bandpasses with units of $\mu\text{K}_{\text{CMB}}/(\text{MJy}/\text{sr})/\text{GHz}$.
- Responses: the map response to individual components such as CMB, tSZ, dust and synchrotron.
- Beams: the harmonic-space beam transfer functions for the maps.

3.9. DR5 Cluster Catalog¹⁵

Hilton et al. (2021) present the DR5 cluster catalog, produced using the DR5 coadded maps. The catalog contains more than 4,000 optically confirmed Sunyaev-Zel’dovich clusters making it significantly larger than ACT’s previous catalog. The catalog covers a sky area of 13,211 deg^2 and overlaps with a number of deep optical surveys including the Dark Energy Survey and the Sloan Digital Sky Survey. This overlap with optical surveys makes it possible to obtain redshifts for the clusters by cross matching the catalogs and estimating redshift values. This process results in mass estimates of clusters that span a redshift range of 0.04 to 1.91 with a median redshift of 0.52, and 221 objects at redshift $z > 1$.

The catalog includes right-ascension and declination coordinates, mass, redshift, signal-to-noise ratios, and optical richness measurements (see Hilton et al. 2021, for a complete list). Example analyses using the cluster catalog are presented in notebook 4 and §4.2.4. The GitHub repository associated with the catalog and the related documentation are both publicly available.¹⁶

4. JUPYTER IPYTHON NOTEBOOKS

We provide a set of Jupyter IPython notebooks to facilitate use of the DR4 and DR5 data products. The notebooks focus on presenting contextual information about the maps, and serve as an introduction to the tools and techniques needed to manipulate them. We give examples of analyses that can be performed and recreate several key plots from the original DR4 and DR5 papers. These notebooks are new products that were developed alongside the data releases in order to make the ACT data accessible and easy to use.

¹⁴ <https://phy-act1.princeton.edu/public/snaess/actpol/dr5/lambda/readme.html>

¹⁵ Catalog presented in Hilton et al. (2021).

¹⁶ Repository: <https://github.com/simonsobs/nemo/>; and documentation: <https://nemo-sz.readthedocs.io/en/latest/>

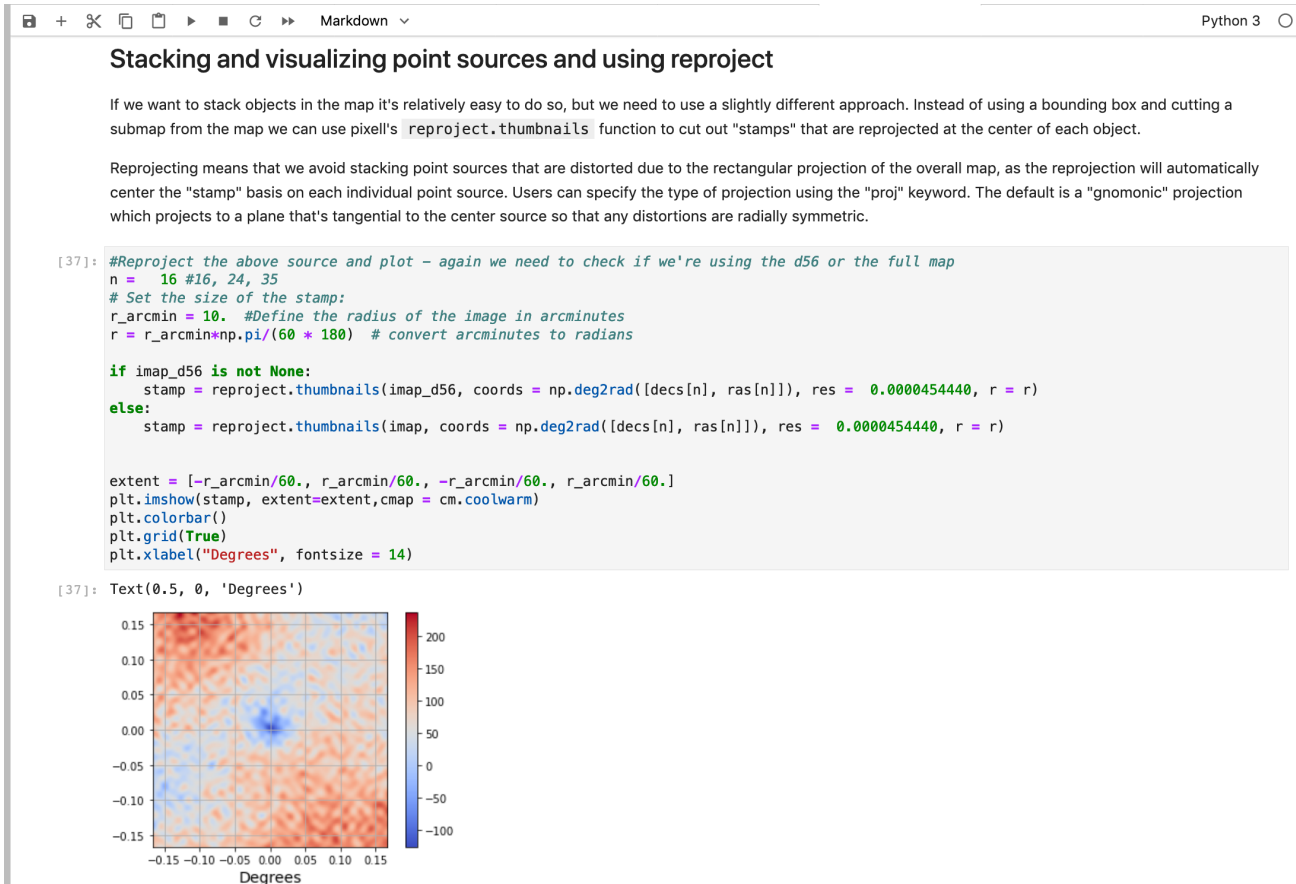


Figure 3. An example from Notebook 4 that demonstrates how to use a cluster catalog to look at compact sources in the maps.

4.1. Notebook Access

The set of notebooks discussed in §4.2 are all available via the ACT GitHub repository,¹⁷ which includes both the notebooks and instructions for set up and use. There are two options for the set up; a completely local installation, and installation using a Docker container.¹⁸ The local installation involves installing the relevant packages, cloning the GitHub repository and then running scripts that download the necessary data products. This includes installing a number of less-common packages. The Docker container installation is more straightforward, and comes with all the necessary software pre-installed. Users download the container and run the included scripts, which then download the necessary data products. Detailed instructions for set up are included with the notebooks on GitHub. In both cases the time-limiting step is downloading the data, so we provide command-line scripts that pull the data for users and can run in the background on their computer. Finally, we have set up a help-desk that anyone can contact with questions pertaining to these notebooks.¹⁹

4.2. Notebook Contents

To complement the ACT DR4 and DR5 data releases, we have assembled 12 notebooks. They include explanatory text that focuses both on the data products and the tools to analyze them. The explanations and accompanying code were designed to be accessible to scientists in the astrophysics community regardless of their familiarity with CMB data; however, familiarity with Python and Jupyter IPython notebooks is recommended. We have also aimed to make these notebooks “laptop friendly” such that any user can run them locally if they desire. At some points, where the computational power needed to run certain analyses is particularly high, we have tried to offer alternative solutions so

¹⁷ https://github.com/ACTCollaboration/DR4_DR5_Notebooks

¹⁸ https://hub.docker.com/r/actcollaboration/dr4_tutorials

¹⁹ The help desk can be reached at act_notebooks@googlegroups.com and more information is available on LAMBDA.

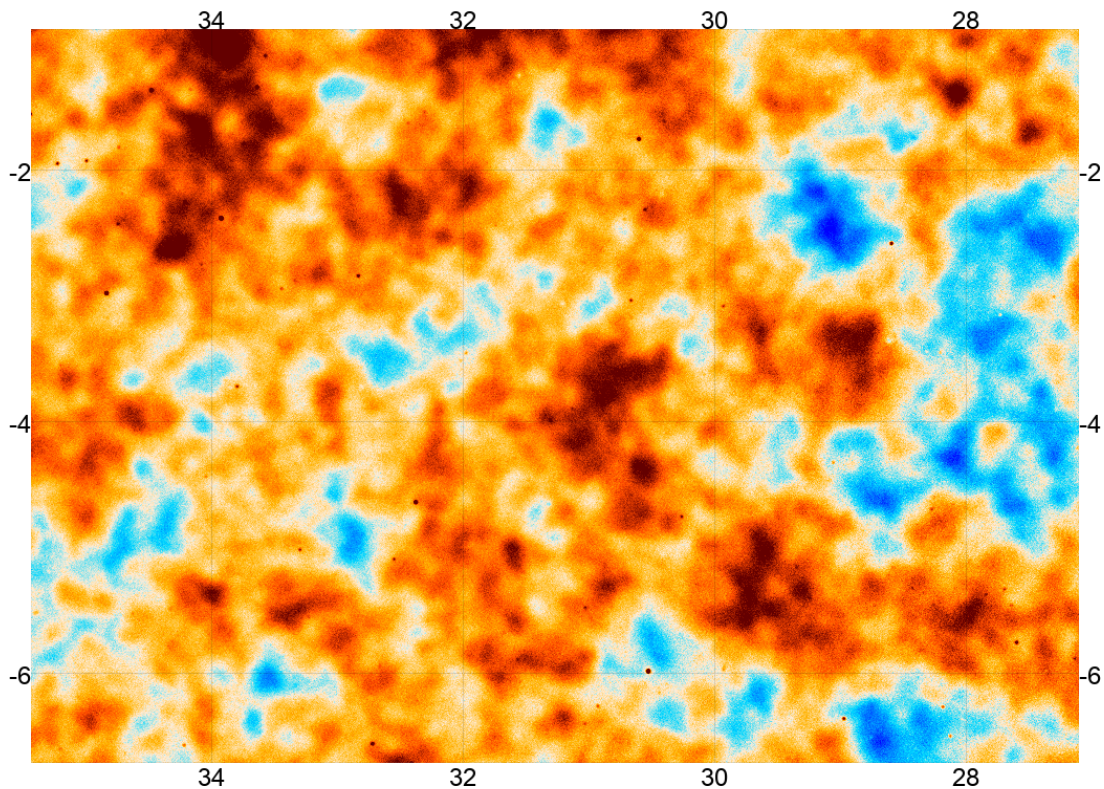


Figure 4. A small section of a full resolution DR5 s08–s18 coadd map (150 GHz, ACT nighttime + *Planck* data, Stokes *I*). The color scale ranges from $-300 \mu\text{K}_{\text{CMB}}$ to $+300 \mu\text{K}_{\text{CMB}}$; the numbers on the x (y) perimeter of the map indicate the right-ascension (declination) in degrees. Individual point sources are visible as small dark red dots at this frequency.

that users can still understand the analysis concepts even if they cannot run the full code locally. In this section we provide brief introductions to each notebook, but we do not discuss the full extent of their capabilities. We encourage users to explore the notebooks for themselves.

4.2.1. *Notebook 1: Overview and Introduction*

This notebook gives an introduction to the two data releases, including an explanation of the CAR map format used in DR4 and DR5. It is important to understand how this format differs from HEALPix when using these maps. While the notebooks do not need to be completed in order, we encourage users to read through this first one in order to get a sense of the scope and use of the notebooks.

4.2.2. *Notebook 2: Guide to Loading and Manipulating the DR4 and DR5 Coadded Maps*²⁰

This notebook introduces both the tools we use to analyze our maps as well the coadded maps presented in N20 and discussed in §3.2.1 and §3.8. Currently, the majority of public CMB data are presented as HEALPix maps, which differ from the format of the ACT maps. Due to this difference we walk through the basics of how to interact with maps in the CAR format. We use the Python library `pixell`,²¹ which is designed for use with CAR maps, and we demonstrate how to load and examine the coadded map.

The coadded maps are reasonably large data files (~ 5 GB) and so, while we encourage users to use the full maps if their laptops permit, we also offer a low memory option. This option involves reading in a low resolution version of the full coadded map as well as a map of a smaller patch of the sky at full resolution. The low resolution version is created by taking the intensity map from the full coadded map, down-sampling pixels by a factor of four, and then saving the output. The smaller area map was created with the same input map, but instead of down-sampling, we cut out the D56 region using the D56 footprint included in the DR4 release and then save that as our output. These two

²⁰ Maps originally presented in N20.

²¹ <https://github.com/simonsobs/pixell>

maps combined represent ~ 150 MB of data, compared to the ~ 5 GB full resolution data, and so are easier to handle, while still allowing users to appreciate the significant depth and resolution of the ACT coadded maps (see Figure 4).

4.2.3. Notebook 3: Converting Between CAR and HEALPix Maps

In many instances it is necessary to convert maps between the CAR and HEALPix format; `pixell` provides functions that do just that. We give an example of how `pixell` can be used to convert a *Planck* map to the same CAR format used for the ACT maps. Similarly, we offer an example of converting the ACT data products to the HEALPix format if users wish to do so.

In order to convert between formats, we calculate the spherical harmonics of the given map and then inverse-transform – or “reproject” – those $a_{\ell m}$ s onto the new geometry. For that reason, the reprojections are bandwidth limited by the initial harmonic transform. The reprojection functions can also be used to rotate between different coordinate frames such as from *Planck*’s Galactic frame to ACT’s equatorial one.

While these conversions are possible there are certain benefits to using the `pixell` framework for the ACT maps. In particular, HEALPix maps do not support analysis using Fourier methods²² and instead must be analysed using spherical harmonics. Furthermore, `pixell` simplifies working with smaller and/or arbitrary patches from the full footprint maps.

4.2.4. Notebook 4: The DR5 Cluster Catalog and Visualizing Map Objects²³

One of the advantages of using `pixell` is that it makes it easier to examine small patches of a map. In this notebook we show how to use the DR5 cluster catalog (Hilton et al. 2021), together with our maps, to manipulate compact sources and their surrounding regions. We first examine the cluster catalog and plot the distribution of the objects in 3D space. We then turn to the maps and extract small patches of the sky around compact sources. We then reproject those cutouts to a plane that is tangential to the sky and centered on the compact source. Switching to this tangential plane, as opposed to the CAR projection used for the full maps, recenters the coordinates such that flat-sky distortions for each cutout are radially-symmetric. This is especially helpful for sources at high declination whose cutouts would otherwise be particularly distorted in the CAR projection. As shown in Figure 3, we extend this analysis by demonstrating how to make stacks of clusters from the reprojected cutouts for use in a variety of analyses.

In order to demonstrate the utility of these cutouts, we show users how to calculate the radially binned profile of the stacked clusters. Users can then fit profiles to the clusters and use these to study a variety of astronomical objects in our maps. We also give an example of how users could apply an Aperture Photometry filter, such as the one shown in Figure 5, to the stack in order to study the brightness and extent of the clusters that we see. We do this by taking the average of a disk centered on a compact source of radius r and subtracting off the mean of a surrounding annulus of radius $\sqrt{2}r$. We repeat this for a range of radii and then plot the result against the radius of the inner circle.

4.2.5. Notebook 5: Introduction to the Lensing Maps²⁴

We read in a single lensing map (Darwish et al. 2020) and give an example of how to cross correlate the lensing- κ signal with a galaxy density map. This example uses CMASS galaxies²⁵ from the Sloan Digital Sky Survey (SDSS) data release 12 (Reid et al. 2015). To create a galaxy density map, $g(\hat{n})$, from this catalog we use

$$g(\hat{n}) = \frac{n(\hat{n}) - \tilde{n}}{\tilde{n}}, \quad (1)$$

where $n(\hat{n})$ represents the number of galaxies in a specific pixel and \tilde{n} gives the average number of galaxies per pixel.

The notebook also explains how to account for masking effects when using the lensing maps. In order to create the lensing maps, a mask, known as the CMB window (W_c), was first applied to the input CMB maps before they were passed into the lensing reconstruction pipeline (Darwish et al. 2020). The released DR4 lensing maps are divided by a factor of W_c^2 , to correct for the loss of power resulting from the original masking. But since we are introducing a new mask applied to the galaxy map (in addition to the original lensing mask) we need to adjust this factor. This means that we must first remove the $1/W_c^2$ factor in the released map by multiplying by $\langle W_c^2 \rangle$. From there we correct for any additional masking that is applied to the maps during the cross correlation as follows:

²² Although the Fourier basis is less accurate than the spherical harmonic basis for signals defined on the sphere, for small patches of the sky they are a good and much faster approximation.

²³ Catalog originally presented in Hilton et al. (2021).

²⁴ Lensing maps originally presented in Darwish et al. (2020).

²⁵ https://data.sdss.org/sas/dr12/boos/lss/galaxy_DR12v5_CMASSLOWZTOT_South.fits.gz

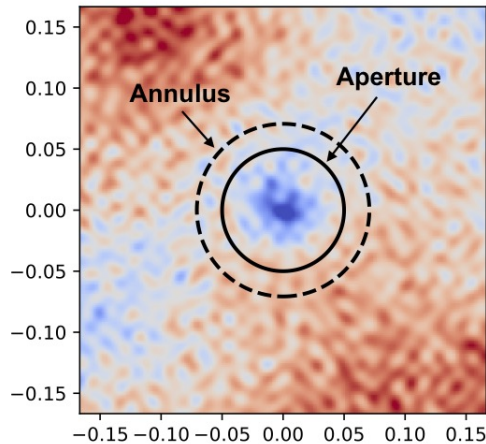


Figure 5. Notebook 4 demonstrates how to apply the filter shown in the image above to stamps of compact sources in the maps. The filtering works by averaging over the disk which is encircled by the solid line, and then subtracting off the average of the equal area annulus, outlined by the dashed line. The result gives an estimate for the intensity of the compact source, where we have averaged out the background fluctuations. The x and y axes give the scale of the stamp in degrees, with the coordinates centered on the source.

Option 1: If the user is only applying a window to the galaxy map, as is done in this notebook, they would use

$$C_L \rightarrow \frac{1}{\langle W_c^2 W_L \rangle} C_L \quad (2)$$

Option 2: If the user would like to apply a mask to both maps, they would instead use

$$C_L \rightarrow \frac{1}{\langle W_c^2 W_L^2 \rangle} C_L \quad (3)$$

The resulting cross-spectrum is shown in Figure 6 where we compare it to the full cross-spectrum from [Darwish et al. \(2020\)](#). The notebook’s quick approach differs from the full result, in part, because we do not apply any cuts to the galaxy catalog nor do we apply any weights to individual galaxies when building the galaxy density map. In addition, we use a much smaller map area than used in [Darwish et al. \(2020\)](#). Despite those limitations the results follow a similar overall form and agree in their orders of magnitude.

4.2.6. Notebook 6: Guide to the Use of the Component Separated Maps²⁶

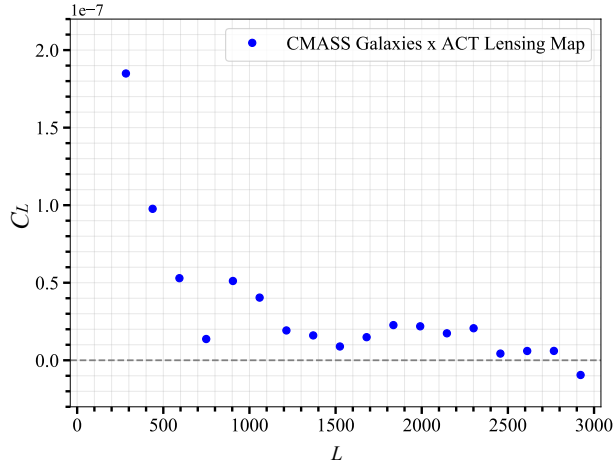
This notebook demonstrates how to examine the Compton- y and CMB+kSZ maps included with the component separated maps ([Madhavacheril et al. 2020a](#)). We also show that it is possible to see galaxy clusters in the Compton- y map by eye and demonstrate how to stack on the locations of these clusters. This stacking is done using the code we first introduced in notebook 4, and the Deep 56 galaxy cluster catalog from ACT DR3 ([Hilton et al. 2018](#)). The same method can be applied to the DR5 catalog.

4.2.7. Notebook 7: Harmonic Analysis with CAR maps

Notebook 7 focuses on how to perform fast harmonic analyses using the CAR maps, walking through both Fourier transforms and spherical harmonic transforms using `pixell`.

In order to generate a simple Fourier-based power spectrum we make use of the *Planck* map, projected to the CAR format from notebook 3, and an ACT map from notebook 2. We apodize the maps to prevent ringing that would occur during the Fourier analysis of the maps due to sharp edges. This process involves smoothly tapering the edges of the maps such that the borders go to zero (an example of an apodized ACT map is shown in Figure 7). Once this

²⁶ Maps originally presented in [Madhavacheril et al. \(2020a\)](#).



Cross correlation using notebook 5

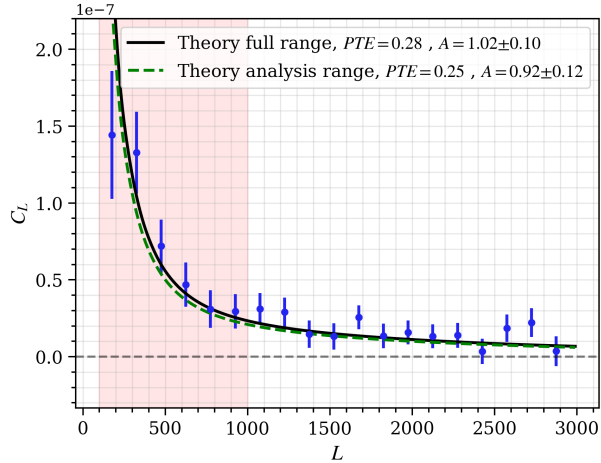


Figure 5 from Darwish et al. (2020)

Figure 6. In notebook 5, we introduce users to the lensing maps and demonstrate how to perform a simple cross correlation between these maps and a galaxy overdensity catalog from CMASS, shown on the left. The right plot is from Darwish et al. (2020), which presents the full cross correlation between CMASS galaxies and the lensing map. The differences are due to some simplifying approximations made in the notebook, as noted in the text.

apodization has been applied we can Fourier transform the ACT and *Planck* maps, and then cross correlate them. Finally, we compare that cross correlation to the ACT autospectrum. This approach is fast and makes it easy to swap in other maps for users who are interested in analyzing their own data products.

While the Fourier transform approach works well with smaller maps (where a flat-sky approximation is appropriate), we also provide an example using spherical harmonics. This approach uses `pixell` functions to generate $a_{\ell m}$ s and `healpy` functions to produce a power spectrum.

Both of these approaches are reasonably straightforward to implement and also run quickly on the average laptop. However, they have a few drawbacks, most noticeably that we fail to properly handle mode-coupling effects from the map mask, as is required for cosmological analyses (Hivon et al. 2002). This method is also improved upon in the following notebook.

4.2.8. Notebook 8: Power Spectrum Example using NaWrapper

In this notebook we continue our study of power spectra, but we pivot to using both the individual ACT map splits from A20 and §3.1, as well as the `NaWrapper`²⁷ code base. This approach offers a few major improvements and much more closely resembles the power spectra analysis that is performed in C20. However, the improvements also make this notebook one of the most computationally intensive. Ordinarily, we would rarely use code like this in a notebook on a laptop; instead we would submit scripts to a computing cluster to make the process significantly more tractable.

With that in mind, the code still offers useful insight into the power spectrum analysis process. We begin by generating the correct mask for the region we are considering, in this case the D56 patch. The total mask consists of an apodized footprint combined with the point source mask. The inverse-variance map is then used to correctly weight the pixels. This mask mixes harmonic modes in the naive power spectrum of the map relative to the true power spectrum of the unmasked full sky. This effect is fully captured in a mode-coupling matrix, which links the modes of the naive power spectrum to the true power spectrum (Hivon et al. 2002). `NaWrapper`, using the `NaMaster` code from Alonso et al. (2019), is designed to efficiently account for this mode-coupling matrix and recover an estimate for the true power spectrum of an unmasked map. Since this step can be relatively time consuming, we provide the matrix on disk so that users can avoid having to run the computation. Using `NaWrapper` allows us to improve our estimate of the cosmological power spectrum relative to the previous notebooks (which used `healpy` and `pixell`), which were unable to properly decouple mixed harmonic modes induced by the mask. Note that we utilize a slightly different code in the C20 pipeline, but the two codes have been shown to produce the same results (see C20).

²⁷ <https://github.com/xzackli/nawrapper>

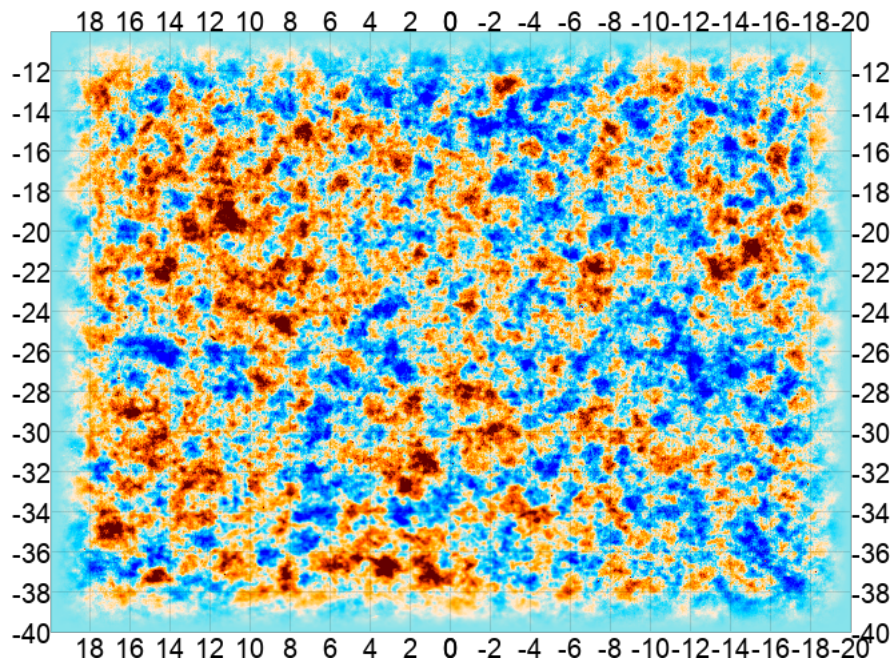


Figure 7. Example of the apodized ACT map from notebook 7 with the x (y) perimeter ticks indicating the right-ascension (declination) in degrees. This example uses a reduced-resolution version of the s08–s16 DR4 coadd map, which we downgrade in order to make the map easier to handle on a laptop. We also offer the full map and the routines needed to do the analysis with the full map for users with access to more computational power.

Another difference between this notebook and notebook 7 is that we use four splits of the data (here D56). This allows us to generate six distinct cross spectra, which we average to estimate the power spectrum. We show two approaches that can be used to generate errors for the power spectra, again providing some of the data products on-disk since the calculations can be difficult to run on the average laptop.

4.2.9. Notebook 9: Generating Simulations

Simulations play a central role in understanding the ACT DR4 and DR5 products, from the power spectra to the component separation pipeline. In particular, feeding large numbers of map-based simulations through those pipelines enables consistency- and null-tests to be run on spectra, the generation of bin-bin covariance matrices, and assessment of biases in the Compton- γ and lensing reconstructions (C20, Madhavacheril et al. 2020a; Darwish et al. 2020). The DR4 release includes a suite of simulation products to complement the data, and in this notebook we walk through an example of how to create simulations of the ACT noise in map space.

The notebook follows Appendix B of C20 to recreate a “square-root covariance matrix,” the on-disk product released for the DR4 noise simulations. As described in C20, the aim is to construct an unbiased noise model of the ACT DR4 maps on a per season, patch, detector array, and frequency basis. Since, in general, the map-domain noise is anisotropic in a given patch (as set by the ACT scan strategy), the 2D Fourier-space power spectrum may contain azimuthally-varying structure. Starting from the ACT maps, we follow C20 to make estimates of the 2D power spectra (including polarization auto- and cross-spectra), which are assumed to capture all off-diagonal elements of the noise covariance matrix. In the notebook we apply post-processing steps to remove bias from these estimates, and emerge with the square-root of the noise covariance matrix. Therefore, when written to disk, the “square-root covariance matrix” enables users to draw fast Gaussian realizations of the underlying anisotropic noise power spectrum.

In Figure 8 we show the Stokes $I-I$ 2D noise power spectrum for the D6 patch, observed by PA1 in s13, as an intermediate step in the C20 noise simulation prescription. The notebook shows corresponding cross spectra for each of the other polarization combinations. The full ACT map-based simulation pipeline, including signal simulations, is publicly available on GitHub.²⁸

²⁸ <https://github.com/ACTCollaboration/actsims>

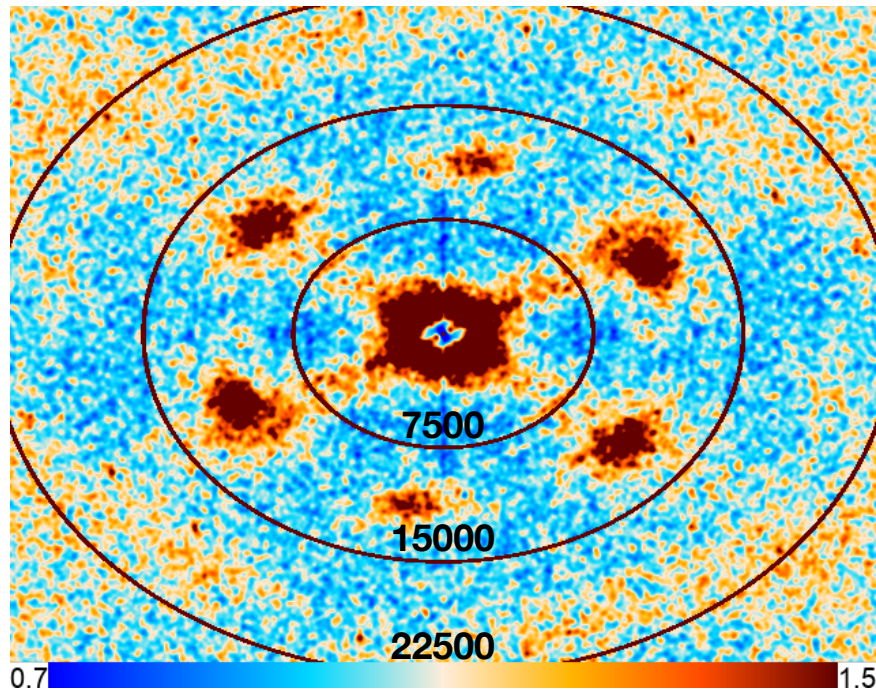


Figure 8. The 2D Fourier-space I - I power spectrum for the s13, D6 patch observed by PA1 at 150 GHz. The concentric circles represent lines of constant ℓ given by the labels. The colorbar is unitless: following the noise prescription in Appendix B of C20, this plot represents the power spectrum after it has been radially flattened and subsequently smoothed by a low-pass filter. Therefore this figure shows the relative anisotropy of the 2D noise power, normalized to the average radial profile. The specific anisotropy pattern is a function of atmospheric noise, the detector array geometry, and the ACT scanning strategy.

4.2.10. Notebook 10: Generating E and B maps from I , Q , and U maps

In many cases the raw I , Q , and U maps provided on-disk contain the information needed to perform a given analysis. For example, when studying point sources, Galactic dust, or doing component separation, users may require the Stokes Q and U maps instead of maps of E and B modes. However, many analyses require E and B modes as inputs instead. Because the E and B maps are not included in this release, we provide an example of how users can generate maps of the E and B modes from the Stokes components using `pixell` functions. The method used is straightforward, but as with many Fourier space operations, decisions such as how users treat bright spots in the maps, or how one apodizes the boundary, can affect the final product.

4.2.11. Notebook 11: ACT Likelihood

The data release includes the likelihood of the CMB power spectrum measured by ACT from the individual DR4 patch maps discussed in A20 and §3.1. The `pyactlike` package used in this notebook is available on GitHub.²⁹ The notebook demonstrates how to plot the best-fitting theoretical power spectra with the TT , TE and EE data, compute the likelihood for a given cosmological model, and plot the residuals of the theoretical model compared to the data. We also show how to load one of the MCMC chains generated using the likelihood from A20, and use it to plot 1D and 2D parameter distributions. The chains allow us to visualize the joint distribution of different model parameters; in the notebook we plot the distribution of H_0 and Ω_m . Another example of the notebook outputs can be found in the bottom row of Figure 1.

²⁹ This code is based on the WMAP and ACT Collaboration’s likelihood software and is available at <https://github.com/ACTCollaboration/pyactlike>

4.2.12. Notebook 12: Delensing and Parameter-shift Covariance Matrix

As discussed in [Han et al. \(2021\)](#) and §3.7, it is possible to use internally reconstructed lensing maps of the D56 region to undo the effect of CMB lensing in the 98 and 150 GHz ACT power spectra. This release includes the delensing likelihood for the D56 region, the best-fit parameters obtained from both lensed and delensed spectra, as well as a parameter-shift covariance matrix. The parameter-shift covariance matrix is used to quantify the shift in the best-fit parameters obtained from lensed and delensed spectra. The notebook demonstrates how to read in the various parameters and the covariance matrix, then uses these products to calculate the parameter-shift χ^2 and probability-to-exceed (PTE) values for the given set of lensed and delensed best-fit parameters.

5. CONCLUSION

The Atacama Cosmology Telescope (ACT) data releases four and five (DR4 and DR5) include maps that span close to half the sky in temperature and polarization at arcminute resolution, along with $\sim 2,100$ deg² of CMB lensing maps, Compton y -maps, and more. DR4 and DR5 also contain data products including beams and masks, signal and noise simulations, power spectra, and likelihoods necessary for a wide range of cosmological analyses. In total, the data releases comprise over 5 TB of data from multiple generations of ACT cameras, which have been documented in a series of papers.

By including Jupyter IPython notebook tutorials with the data products in these releases, the goal is to make it practical to include ACT data in external analyses. The data products support a multitude of applications, from testing Λ CDM-cosmology and its extensions, to extragalactic studies such as measurements of the kSZ effect, active galactic nuclei, and dusty star-forming galaxies, to Galactic science. The releases summarized here include data taken through 2018. As the ACT team validate and release data from 2019-2021 as well as additional data from 2017-18, the depth of the temperature and polarization maps will increase. Indeed, as the community prepares for an anticipated wealth of new cosmological data in the next few years (for example, the Vera C. Rubin Observatory ([Ivezić et al. 2019](#)) or the Euclid mission ([Laureijs et al. 2011](#))), ACT’s unique millimeter maps will contribute to the investigation of, among other things, the dark sector, evolution of structure across scales, and other open questions that lie beyond the scope of traditional CMB science.

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³⁰ <http://www.astropy.org>

2007) package. We used `pixell`³¹ as well as `pyactlike`.³² We also relied on CAMB (Lewis et al. 2000) as well as `getdist` (Lewis 2019). For power spectra examples we used `NaWrapper`³³ which is a wrapper for `NaMaster` (Alonso et al. 2019).³⁴ The packages `numpy` (Oliphant 2006; van der Walt & Colbert 2011; Harris et al. 2020), `pandas` (pandas development team 2020; Wes McKinney 2010) and `scipy` (Virtanen et al. 2020) were also used throughout this work. We acknowledge the use of the Legacy Archive for Microwave Background Data Analysis (LAMBDA), part of the High Energy Astrophysics Science Archive Center (HEASARC). HEASARC/LAMBDA is a service of the Astrophysics Science Division at the NASA Goddard Space Flight Center. We also acknowledge the use of the National Energy Research Scientific Computing Center (NERSC) for hosting the ACT data, and the use of GitHub for hosting our repositories.

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³¹ <https://github.com/simonsobs/pixell>

³² <https://github.com/ACTCollaboration/pyactlike>

³³ <https://github.com/xzackli/nawrapper>

³⁴ <https://github.com/LSSTDESC/NaMaster>

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