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Möbius and Laguerre geometry of Dupin Hypersurfaces

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Abstract

In this paper we show that a Dupin hypersurface with constant Möbius curvatures is Möbius equivalent to either an isoparametric hypersurface in the sphere or a cone over an isoparametric hypersurface in a sphere. We also show that a Dupin hypersurface with constant Laguerre curvatures is Laguerre equivalent to a flat Laguerre isoparametric hypersurface. These results solve the major issues related to the conjectures of Cecil et al on the classification of Dupin hypersurfaces.

2000 Mathematics Subject Classification: 53A30, 53C40;

Key words: Dupin hypersurfaces, Möbius curvatures, Laguerre curvatures, Codazzi tensors, Isoparametric tensors, .

1 Introduction

Let M^n be an immersed hypersurface in Euclidean space \mathbb{R}^{n+1} . A curvature surface of M^n is a smooth connected submanifold S such that for each point $p \in S$, the tangent space T_pS is equal to a principal space of the shape operator \mathcal{A} of M^n at p. The hypersurface M^n is called Dupin hypersurface if, along each curvature surface, the associated principal curvature is constant. The Dupin hypersurface M^n is called proper Dupin if the number r of distinct principal curvatures is constant on M^n . Both Dupin and properness are invariant under the group of Lie sphere transformations, which was verified by Pinkall [35]. The group of Lie sphere transformations is generated by its two subgroups: the group of Möbius transformations and the group of Laguerre transformations. Hence, due to Möbius invariance, the theory of Dupin submanifolds is essentially the same whether it is considered in \mathbb{R}^{n+1} , \mathbb{S}^{n+1} , or \mathbb{H}^{n+1} .

Dupin surfaces were first studied by Dupin [13] in 1822. Since then, Dupin hypersurfaces have been studied extensively (cf. [3, 4, 6, 8, 9, 10, 14, 26, 27, 28, 34, 38, 40]). The classification of Dupin hypersurfaces is far from complete, especially for higher dimensions. An important class of examples are the isoparametric hypersurfaces in \mathbb{R}^{n+1} , \mathbb{H}^{n+1} , and \mathbb{S}^{n+1} . An isoparametric hypersurface is a hypersurface with constant principal curvatures. In \mathbb{R}^{n+1} as well as \mathbb{H}^{n+1} , an isoparametric hypersurface has no more than 2 distinct principal curvatures and is completely classified (cf. [3]). On the other hand, in \mathbb{S}^{n+1} , there are many more examples (cf. [5, 12, 18, 42, 44]). Münzner ([30, 31]) showed that the number r of distinct principal curvatures of an isoparametric hypersurface in \mathbb{S}^{n+1} must be 1, 2, 3, 4 or 6. Cartan [2] classified those with $r \leq 3$.

Thorbergsson [43] showed the restriction that r = 1, 2, 3, 4 or 6 on the number of distinct principal curvatures also holds for compact proper Dupin hypersurfaces embedded in \mathbb{S}^{n+1} . Compact proper Dupin hypersurfaces with $r \leq 3$ are completely classified (cf. [11, 26]). However, it is a different story if the compactness is dropped. In fact, Pinkall [35] discovered the basic constructions of building tubes, cylinders, cones and surfaces of revolution over a Dupin hypersurface. It is important to note that these constructions may yield a compact proper Dupin hypersurface only if the original one is a sphere (cf. [3, 35]). A Dupin hypersurface which is locally equivalent by a Lie sphere transformation to a hypersurface M^n obtained by one of these four basic constructions is said to be reducible, otherwise, the Dupin hypersurface is said to be irreducible. Local classifications have been obtained for irreducible connected proper Dupin hypersurfaces with $r \leq 3$ (cf. [8, 9, 33, 35]).

In all of the above cases when $r \leq 3$, compact (or irreducible) Dupin hypersurfaces are known to be Lie equivalent to isoparametric hypersurfaces (cf. [9, 26, 33]). In addition, Stolz [40] in the cases r = 4 and Grove and Halperin [14] in the cases r = 6 have shown that the multiplicities of the principal curvatures of a compact proper Dupin hypersurface must be the same as that of an isoparametric hypersurface. Hence it was conjectured that, at least for compact cases, proper Dupin hypersurface is always Lie equivalent to an isoparametric hypersurface (see for instance [8, p.184]). However, this conjecture was shown to be false by Pinkall and Thorbergsson [36] for r = 4 and separately by Miyaoka and Ozawa [29] for r = 4 and r = 6. The compact proper Dupin hypersurfaces for counterexamples in [36, 29] have non-constant Lie curvatures. For an oriented hypersurface M^n with $r(\geq 4)$ distinct principal curvatures $\lambda_1, \dots, \lambda_r$, Miyaoka [27] introduced Lie curvatures as the cross-ratios of the principal curvatures

$$\Psi_{ijst} = \frac{(\lambda_i - \lambda_j)(\lambda_t - \lambda_s)}{(\lambda_i - \lambda_s)(\lambda_t - \lambda_j)}$$

and verified that Lie curvatures Ψ_{ijst} are invariant under Lie sphere transformations. Obviously, that the Lie curvatures are constant is a necessary condition for a Dupin hypersurface to be Lie equivalent to an isoparametric hypersurface. Therefore Cecil, Chi and Jensen [8] proposed the following conjecture.

Conjecture 1.1. ([8]) Every compact connected proper Dupin hypersurface with four or six principal curvatures and constant Lie curvatures is Lie equivalent to an isoparametric hypersurface in a sphere.

Analogously, on local classifications of irreducible connected proper Dupin hypersurfaces, Cecil, Chi and Jensen [8] proposed the following conjecture.

Conjecture 1.2. ([8]) If M^n is an irreducible connected proper Dupin hypersurface with four principal curvatures having respective multiplicities m_1, m_2, m_3, m_4 and constant Lie curvature, then $m_1 = m_2, m_3 = m_4$, and M^n is Lie equivalent to an isoparametric hypersurface in a sphere.

In [6], Cecil, Chi and Jensen have verified both Conjecture 1.1 and Conjecture 1.2 for Dupin hypersurfaces with four principal curvatures and multiplicities $m_1 = m_2 \ge 1$, $m_3 = m_4 = 1$. In this paper we will shed different lights on Conjecture 1.1 and Conjecture 1.2. More precisely, we will consider Möbius (Laguerre) curvatures instead of Lie curvatures and show Conjecture 1.1 and Conjecture 1.2 hold in stronger ways where Lie equivalence is replaced by Möbius (Laguerre) equivalence respectively.

For an oriented hypersurface M^n with $r(\geq 3)$ distinct principal curvatures $\lambda_1, \dots, \lambda_r$, the Möbius curvatures are defined by

$$\mathbb{M}_{ijs} = \frac{\lambda_i - \lambda_j}{\lambda_i - \lambda_s}.$$

It is known that the Möbius curvatures \mathbb{M}_{ijs} are invariant under the Möbius transformations but not under Lie sphere transformations in general (cf. [27]). Obviously, Lie curvatures are products of two Möbius curvatures

$$\Psi_{ijst} = \mathbb{M}_{ijs} \mathbb{M}_{tsj}$$

and therefore Möbius curvatures are finer than Lie curvatures. On a seemingly different thread, Hu, Li, and Wang [15, 16, 17] classified the hypersurfaces with vanishing Möbius form and constant Möbius principal curvatures, which are called Möbius isoparametric hypersurfaces, provided that the dimension of the hypersurface or the number of distinct principal curvatures is small. Until Rodrigues and Tenenblat [39] observed that an oriented hypersurface is a Dupin hypersurface with constant Möbius curvatures if and only if it is a Möbius isoparametric hypersurface.

Our first main result is the following classification theorem:

Theorem 1.1. Let M^n be a Dupin hypersurface in \mathbb{R}^{n+1} with $r(\geq 3)$ distinct principal curvatures. If the Möbius curvatures are constant, then locally M^n is Möbius equivalent to one of the following hypersurfaces:

- (1) the image of the stereograph projection of an isoparametric hypersurface in \mathbb{S}^{n+1} ;
- (2) a cone over an isoparametric hypersurface in $\mathbb{S}^k \subset \mathbb{R}^{k+1} \subset \mathbb{R}^{n+1}$.

A Dupin hypersurface with constant Möbius curvatures turns out to be proper (cf. Corollary 2.1). As a consequence of the constraint on the number of distinct principal curvatures for isoparametric hypersurfaces established by Münzner ([30, 31]), we may conclude

Corollary 1.1. Let M^n be a Dupin hypersurface in \mathbb{R}^{n+1} with $r(\geq 3)$ distinct principal curvatures. If the Möbius curvatures are constant, then r = 3, 4, 5, 6, 7.

As argued in [6] based on the analyticity of Dupin hypersurfaces established in [7], we can use Theorem 1.1 to solve some major issues related Conjecture 1.1 and Conjecture 1.2 on the classification of Dupin hypersurfaces.

Corollary 1.2. Let M^n be a compact connected Dupin hypersurface with $r(\geq 3)$ distinct principal curvatures. Then M^n is Möbius equivalent to an isoparametric hypersurface in \mathbb{S}^{n+1} if and only if its Möbius curvatures are all constant.

and

Corollary 1.3. Let M^n be an irreducible connected Dupin hypersurface with $r(\geq 3)$ distinct principal curvatures. Then M^n is Möbius equivalent to an isoparametric hypersurface in \mathbb{S}^{n+1} if and only if its Möbius curvatures are all constant.

For an oriented hypersurface M^n in \mathbb{R}^{n+1} with non-vanishing principal curvatures $\lambda_1, \lambda_2, \cdots, \lambda_r$, let $R_i = \frac{1}{\lambda_i}$ be the curvature radius. Then one can define the Laguerre curvatures of M^n as

$$\Upsilon_{ijs} = \frac{R_i - R_j}{R_i - R_s}.$$

It is clear that Υ_{ijk} are invariant under Laguerre transformations in the light of (5.66) in Section 5. Again, obviously, the Lie curvature is a product of two Laguerre curvatures

$$\Psi_{ijst} = \Upsilon_{ijs} \Upsilon_{tsj}$$

and therefore Laguerre curvatures are finer than Lie curvatures. Analogous to Möbius cases, it turns out, as expected, an oriented hypersurface is a Dupin hypersurface with constant Laguerre curvatures if and only if its Laguerre form vanishes and its Laguerre principal curvatures are all constant (see Proposition 5.1 and also [37]).

Our second main theorem is the following result:

Theorem 1.2. Let M^n be a Dupin hypersurface in \mathbb{R}^{n+1} with $r(\geq 3)$ distinct non-vanishing principal curvatures. Then M^n is Laguerre equivalent to flat Laguerre isoparametric hypersurface in \mathbb{R}^{n+1} if and only if the Laguerre curvatures are all constant.

Flat Laguerre isoparametric hypersurfaces will be reviewed in Section 6.1. We note that a flat Laguerre isoparametric hypersurface is a Dupin hypersurface with any given number kof principal curvatures with any prescribed multiplicities m_1, \dots, m_k and that a flat Laguerre isoparametric hypersurface is reducible and non-compact.

Our approach is to recognize Möbius (Laguerre) second fundamental form $B(\mathbb{B})$ and Blaschke (Laguerre) tensor $A(\mathbb{L})$ are commuting isoparametric tensors. Isoparametric tensors on a Riemannian manifold (M^n, g) are the Codazzi tensors with constant eigenvalues. The name comes from the fact that the second fundamental form of an isoparametric hypersurface in space forms is an isoparametric tensor. We will play with the integrability conditions (2.6) and (5.63) and generalized Cartan identity (A.77) to pin down the specific behaviors of Möbius (Laguerre) second fundamental form $B(\mathbb{B})$ and Blaschke (Laguerre) tensor $A(\mathbb{L})$. In Möbius cases it turns out miraculously we are able to show that either the Möbius second fundamental form and Blaschke tensor are linearly dependent (cf. Definition 4.1) or they behave as in (3.17) and (3.18). Then one may conclude the Dupin hypersurface is Möbius equivalent to an isoparametric hypersurface in the sphere in the former cases following [21, Main Theorem], and to a cone over an isoparametric hypersurface in a sphere in the latter cases in the light of Theorem 3.1. In Laguerre cases the situation is much simpler. We will be able to show that the Laguerre second fundamental form \mathbb{B} in our consideration is in fact parallel. Then Theorem 1.2 follows from the classification result in [23].

We now give a brief outline of the paper. In Sections 2, we will recall some facts about the Möbius geometry of a hypersurface in \mathbb{R}^{n+1} and [21, Main Theorem]. In Section 3, we will give a Möbius characterization of the cone hypersurfaces. In Section 4, we will present the proof of our first main classification Theorem 1.1. In Section 5, we will recall some facts about the Laguerre geometry of a hypersurface in \mathbb{R}^{n+1} . In Section 6, we will first review two families of examples of Dupin hypersurface and then we will present the proof of our second main Theorem 1.2. In Appendix A, we will discuss some properties of isoparametric tensors and applications.

2 Möbius invariants of hypersurfaces in \mathbb{R}^{n+1}

In this section, to set the notations, we will briefly review the Möbius geometry of hypersurfaces in \mathbb{R}^{n+1} via the Minkowski spacetime \mathbb{R}^{n+3}_1 . For details readers are referred to [1, 25, 46]. We observe there is a straightforward way to see that a Dupin hypersurface of constant Möbius curvatures is always proper. We will also recall the characterization of Dupin hypersurfaces of constant Möbius curvatures in terms of Möbius invariants given in [39]. We will also derive the characterization of Dupin hypersurfaces that are Möbius equivalent to isoparametric hypersurfaces based on [21, Main Theorem].

Let \mathbb{R}^{n+3}_1 be the Minkowski spacetime, i.e., \mathbb{R}^{n+3} with the standard spacetime metric

$$\langle x, y \rangle = -x_0 y_0 + x_1 y_1 + \dots + x_{n+2} y_{n+2}$$

for $x = (x_0, x_1, \dots, x_{n+2})$ and $y = (y_0, y_1, \dots, y_{n+2})$. One may identify the conformal round sphere \mathbb{S}^{n+1} as the projective positive light cone

$$C^{n+2}_+ = \{ y = (y_0, y_1) \in R \times \mathbb{R}^{n+2} | \langle y, y \rangle = 0, y_0 > 0 \} \subset \mathbb{R}^{n+3}_1.$$

Let $O^+(n+2,1)$ be the Lorentz group of linear transformations of \mathbb{R}^{n+3}_1 that preserve the time orientation and the spacetime metric, and let $M(\mathbb{S}^{n+1})$ be the group of Möbius transformations of \mathbb{S}^{n+1} . One knows from Liouville Theorem that the group $M(\mathbb{R}^{n+1})$ of Möbius transformations on \mathbb{R}^{n+1} is the same as $M(\mathbb{S}^{n+1})$. It is then useful to mention the natural isomorphism

$$L: \mathcal{O}^+(n+2,1) \to \mathcal{M}(\mathbb{S}^{n+1}) = \mathcal{M}(\mathbb{R}^{n+1}).$$

Let $f: M^n \to \mathbb{R}^{n+1}$ be a hypersurface without umbilical points and $\{e_i\}$ be an orthonormal basis with respect to the induced metric $I = df \cdot df$ with the dual basis $\{\theta_i\}$. Let $II = \sum_{ij} h_{ij} \theta_i \theta_j$ and $H = \sum_i \frac{h_{ii}}{n}$ be the second fundamental form and the mean curvature of f respectively. To study the Möbius geometry of f, as in [25, 46], one considers the Möbius position vector

$$Y = \rho(f)\left(\frac{1+|f|^2}{2}, \frac{1-|f|^2}{2}, f\right) : M^n \to C^{n+2}_+ \subset \mathbb{R}^{n+3}_1$$

and the Möbius metric

$$g = \langle dY, dY \rangle = (\rho(f))^2 df \cdot df$$

where $(\rho(f))^2 = \frac{n}{n-1}(|II|^2 - nH^2)$. One basic fact for this approach is

Lemma 2.1. Suppose that $f: M^n \to \mathbb{R}^{n+1}$ is an immersed hypersurface and

$$Y = \rho(f)\left(\frac{1+|f|^2}{2}, \frac{1-|f|^2}{2}, f\right) : M^n \to C_+^{n+2} \subset \mathbb{R}_1^{n+3}$$

is the Möbius position vector of f. Then, for any $T \in O^+(n+2,1)$, we have

(2.1)
$$TY = \rho(L(T)f)\left(\frac{1+|L(T)f|^2}{2}, \frac{1-|L(T)f|^2}{2}, L(T)f\right) : M^n \to C^{n+2}_+ \subset \mathbb{R}^{n+3}_1$$

and therefore the Möbius metric g stays invariant.

To build a moving frame along Y in \mathbb{R}^{n+3}_1 , as in [25, 46], one starts with the so-called conformal Gauss map

$$\xi = H\left(\frac{1+|f|^2}{2}, \frac{1-|f|^2}{2}, f\right) + (f \cdot e_{n+1}, -f \cdot e_{n+1}, e_{n+1})$$

that represents the mean curvature sphere, where e_{n+1} is the unit normal vector field of f in \mathbb{R}^{n+1} . One can pick up a moving frame $\{Y_1 = Y_*(E_1), \dots, Y_n = Y_*(E_n)\}$ for the tangent space of Y along M^n with its dual $\{\omega_1, \dots, \omega_n\}$. To complete a moving frame, as in [25, 46], one chooses another null normal vector N to Y in \mathbb{R}^{n+3}_1 such that $\langle N, Y \rangle = 1$. Thus $\{Y, N, Y_1, \dots, Y_n, \xi\}$ forms a moving frame in \mathbb{R}^{n+3}_1 along Y and the structure equations are:

$$\begin{split} dY &= \sum_{i} Y_{i}\omega_{i}, \\ dN &= \sum_{ij} A_{ij}\omega_{i}Y_{j} + \sum_{i} C_{i}\omega_{i}\xi, \\ dY_{i} &= -\sum_{j} A_{ij}\omega_{j}Y - \omega_{i}N + \sum_{j} \omega_{ij}Y_{j} + \sum_{j} B_{ij}\omega_{j}\xi, \\ d\xi &= -\sum_{i} C_{i}\omega_{i}Y - \sum_{ij} \omega_{i}B_{ij}Y_{j}, \end{split}$$

where ω_{ij} is the connection form of the Möbius metric g with respect to the dual $\{\omega_1, \dots, \omega_n\}$ and the range of Latin indices are in $1, 2, \dots, n$. The tensors

$$A = \sum_{ij} A_{ij}\omega_i \otimes \omega_j, \quad B = \sum_{ij} B_{ij}\omega_i \otimes \omega_j, \quad C = \sum_i C_i\omega_i$$

are called the Blaschke tensor, the Möbius second fundamental form and the Möbius form of f respectively (cf. [25, 46]). In [46], the integrability conditions for $\{A, B, C\}$ are identified as

(2.3)
$$A_{ij,k} - A_{ik,j} = B_{ik}C_j - B_{ij}C_k,$$

(2.2)

(2.4)
$$C_{i,j} - C_{j,i} = \sum_{k} (B_{ik}A_{kj} - B_{jk}A_{ki}),$$

$$(2.5) B_{ij,k} - B_{ik,j} = \delta_{ij}C_k - \delta_{ik}C_j,$$

$$(2.6) R_{ijkl} = B_{ik}B_{jl} - B_{il}B_{jk} + \delta_{ik}A_{jl} + \delta_{jl}A_{ik} - \delta_{il}A_{jk} - \delta_{jk}A_{il},$$

(2.7)
$$R_{ij} := \sum_{k} R_{ikjk} = -\sum_{k} B_{ik} B_{kj} + (tr\mathbf{A})\delta_{ij} + (n-2)A_{ij},$$

(2.8)
$$\sum_{i} B_{ii} = 0, \quad \sum_{ij} (B_{ij})^2 = \frac{n-1}{n}, \quad tr \mathbf{A} = \frac{1}{2n} (1+n^2 \kappa),$$

where R_{ijkl} denote the curvature tensor of g, $\kappa = \frac{1}{n(n-1)} \sum_{ij} R_{ijij}$ is its normalized scalar curvature. Most importantly, it was shown in [46] that $\{g, B\}$ determines the hypersurface f up to Möbius transformations provided that $n \geq 3$.

We would also like to recall from [25, 46] how $\{A, B, C\}$ can be calculated in terms of the geometry of f in \mathbb{R}^{n+1} :

$$B_{ij} = \rho^{-1}(h_{ij} - H\delta_{ij}),$$

$$C_i = -\rho^{-2}[e_i(H) + \sum_j (h_{ij} - H\delta_{ij})e_j(\log \rho)],$$

$$A_{ij} = -\rho^{-2}[Hess_{ij}(\log \rho) - e_i(\log \rho)e_j(\log \rho) - Hh_{ij}]$$

$$-\frac{1}{2}\rho^{-2}(|\nabla \log \rho|^2 + H^2)\delta_{ij},$$

where Hessian and ∇ are with respect to $I = df \cdot df$. The eigenvalues of B are called the Möbius principal curvatures of f. Let $\{b_1, \dots, b_n\}$ be the Möbius principal curvatures and $\{\lambda_1, \dots, \lambda_n\}$ be the principal curvatures of f, then, from (2.9),

(2.10)
$$b_i = \rho^{-1} (\lambda_i - H).$$

(2.9)

Clearly the number of distinct Möbius principal curvatures is the same as that of principal curvatures of f and

(2.11)
$$\mathbb{M}_{ijk} = \frac{\lambda_i - \lambda_j}{\lambda_i - \lambda_k} = \frac{b_i - b_j}{b_i - b_k},$$

which confirms that the Möbius curvatures are Möbius invariants. It is then rather easily seen from (2.8) that, if Möbius curvatures \mathbb{M}_{ijk} are constant for all $1 \leq i, j, k \leq n$, then all Möbius principal curvatures $\{b_i\}$ are constant.

Proposition 2.1. Let $f: M^n \to \mathbb{R}^{n+1}$ be an immersed hypersurface with $r(\geq 3)$ distinct principal curvatures. Then the Möbius curvatures \mathbb{M}_{ijk} are constant if and only if the Möbius principal curvatures $\{b_1, \dots, b_n\}$ are constant.

Proof. It suffices to prove that the Möbius curvatures \mathbb{M}_{ijk} are constant implies all Möbius principal curvatures b_i are constant. First, for any tangent vector $X \in TM^n$, it is not hard to calculate that

$$\frac{X(b_i) - X(b_j)}{b_i - b_j} = \frac{X(b_i) - X(b_k)}{b_i - b_k} = \frac{X(b_j) - X(b_k)}{b_j - b_k}$$

from \mathbb{M}_{ijk} being constant for all $1 \leq i, j, k \leq n$. Hence there exist μ and d such that

(2.12)
$$X(b_j) = \mu b_j + d \text{ for } j = 1, \cdots, n.$$

It is then immediate that (2.8) implies d = 0 and $b_1 X(b_1) + \cdots + b_n X(b_n) = 0$, which implies $\mu = 0$. Thus all b_1, \cdots, b_n are constant.

As a consequence of Proposition 2.1 and (2.10), one easily derives

Corollary 2.1. A Dupin hypersurface of constant Möbius curvature is always proper.

As another consequence of Proposition 2.1, we can characterize the Dupin hypersurfaces of constant Möbius curvature in terms of Möbius invariants, which were observed by Rodrigues L.A. and Tenenblat K. [39]. In fact, from (2.9), we have

$$C_i = -\rho^{-2}[e_i(H) + \sum_j e_j(\rho B_{ij}) - \rho e_j(B_{ij})] = -\rho^{-2}[e_i(\lambda_i) - \rho e_i(b_i)].$$

Hence one easily derives

Theorem 2.1. ([39]) Let $f: M^n \to \mathbb{R}^{n+1}$ be an immersed hypersurface with $r(\geq 3)$ distinct principal curvatures. Then it is a Dupin hypersurface of constant Möbius curvatures if and only if its Möbius form vanishes and its Möbius principal curvatures are all constant, i.e. it is a Möbius isoparametric hypersurface.

Recall from [15, 16, 20], an immersed hypersurface is said to be a Möbius isoparametric hypersurface if its Möbius form vanishes and its Möbius principal curvatures are all constant. We would like to remind readers that a Möbius isoparametric hypersurface is not necessarily Möbius equivalent to an isoparametric hypersurface.

The following result [21, Main Theorem] enables us to characterize Dupin hypersurfaces that are Möbius equivalent to isoparametric hypersurfaces.

Theorem 2.2. [21, Main Theorem] Let $x : M^n \to \mathbb{S}^{n+1}$ be an immersed hypersurface. Suppose that it satisfies that C = 0 and $A = \lambda B + \mu g$ for some functions λ and μ . Then x is Möbius equivalent to a hypersurface with constant mean curvature and scalar curvature in Euclidean space \mathbb{R}^{n+1} , or sphere \mathbb{S}^{n+1} , or hyperbolic space \mathbb{H}^{n+1} .

Consequently we have

Corollary 2.2. Suppose that $f : M^n \to \mathbb{R}^{n+1}$ is a Dupin hypersurface with $r(\geq 3)$ distinct principal curvatures and constant Möbius curvatures. Then it is Möbius equivalent to an isoparametric hypersurface in the sphere \mathbb{S}^{n+1} if and only if $A = \lambda B + \mu g$ for some numbers λ and μ .

Proof. If $A = \lambda B + \mu g$ for some numbers λ and μ , by the definition of the function ρ , it is immediate that ρ is constant when the mean curvature and the scalar curvature of a hypersurface in a space form are constant. Then one can conclude that the Dupin hypersurface under the assumptions is Möbius equivalent to an isoparametric hypersurface in space forms in the light of the first equation in (2.9). Therefore, with the assumption that f has $r(\geq 3)$ distinct principal curvatures, the proof is complete due to known classifications of isoparametric hypersurafces in \mathbb{R}^{n+1} and \mathbb{H}^{n+1} (cf. [3, Chap. 3]).

On the contrary, If f is an isoparametric hypersurface in the sphere \mathbb{S}^{n+1} , then the mean curvature and the scalar curvature are constant. Hence ρ is constant and $A = \lambda B + \mu g$ for some numbers λ and μ by the equations (2.9).

3 Cones over isoparametric hypersurfaces

Remarkably in [35], Pinkall discovered the cone over a Dupin hypersurface is still a Dupin hypersurface. In fact it is easily seen that the cone over an isoparametric hypersurface in a sphere is always a Dupin hypersurface of constant Möbius curvatures. In this section we will calculate the Möbius invariants, and using Möbius invariants to characterize cones over isoparametric hypersurfaces in spheres. Let us start with the construction of cones over hypersurfaces in spheres.

Definition 3.1. For $1 \le k \le n-1$, let $u: M^k \longrightarrow \mathbb{S}^{k+1} \subset \mathbb{R}^{k+2}$ be an immersed hypersurface in \mathbb{S}^{k+1} . The cone over u in \mathbb{R}^{n+1} is given as

$$f(t, y, p) = (y, tu(p)) : \mathbb{R}^+ \times \mathbb{R}^{n-k-1} \times M^k \longrightarrow \mathbb{R}^{n+1}.$$

It is easily calculated that the first fundamental form of the cone f is $I_f = dt^2 + |dy|^2 + t^2 I_u$ and the second fundamental form of the cone is $II_f = t II_u$, where I_u and II_u are the first and second fundamental forms of the hypersurface u in the sphere \mathbb{S}^{k+1} respectively. The principal curvatures of the cone f are

(3.13)
$$\underbrace{0,\cdots,0}_{n-k}, \frac{1}{t}\lambda_1,\cdots,\frac{1}{t}\lambda_k,$$

where $\{\lambda_1, \dots, \lambda_k\}$ are the principal curvatures of u. Hence

$$\rho^2 = \frac{n}{n-1} (|II_u|^2 - \frac{k^2}{n} H_u^2) \frac{1}{t^2},$$

the Möbius metric of the cone is

(3.14)
$$g = \rho^2 I_f = \rho_0^2 \left(\frac{dt^2 + |dy|^2}{t^2} + I_u\right),$$

and the Möbius position vector of the cone is

$$Y(t,y,p) = \frac{\rho_0}{t} (\frac{1+t^2+|y|^2}{2}, \frac{1-t^2-|y|^2}{2}, y, tu(p)) : \mathbb{R}^+ \times \mathbb{R}^{n-k-1} \times M^k \to C_+^{n+2} \subset \mathbb{R}_1^{n+3},$$

where $\rho_0^2 = \frac{n}{n-1} (|II_u|^2 - \frac{k^2}{n} H_u^2)$. Note that

$$(3.15) \quad i(t,y) = (\frac{1+t^2+|y|^2}{2t}, \frac{1-t^2-|y|^2}{2t}, \frac{y}{t}) : \mathbb{R}^+ \times \mathbb{R}^{n-k-1} = \mathbb{H}^{n-k} \to \mathbb{H}^{n-k} \subset \mathbb{R}^{n-k+1}_1 = \mathbb{H}^{n-k}$$

is nothing but the identity map of \mathbb{H}^{n-k} , since $\mathbb{R}^+ \times \mathbb{R}^{n-k-1} = \mathbb{H}^{n-k}$ is the upper half-space endowed with the standard hyperbolic metric. We may now rewrite the Möbius position vector of the cone f as

(3.16)
$$Y = \rho_0(i(t,y),u) : \mathbb{R}^+ \times \mathbb{R}^{n-k-1} \times M^k \to C^{n+2}_+ \subset \mathbb{R}^{n+3}_1$$

Consequently we have

Lemma 3.1. Let $u: M^k \to \mathbb{S}^{k+1}$ be an immersed hypersurface in $\mathbb{S}^{k+1} \subset \mathbb{R}^{k+2}$ and

$$\frac{1}{\rho_0}Y = (i(t,y),u) : \mathbb{R}^+ \times \mathbb{R}^{n-k-1} \times M^k \to \mathbb{H}^{n-k} \times \mathbb{S}^{k+1} \subset \mathbb{R}^{n+3}_1$$

for smooth positive function ρ_0 . Suppose that Y is the Möbius position vector for an immersed hypersurafce

$$f: \mathbb{R}^+ \times \mathbb{R}^{n-k-1} \times M^k \to \mathbb{R}^{n+1}$$

Then f is a cone over u and $\rho_0^2 = \frac{n}{n-1}(|II_u|^2 - \frac{k^2}{n}H_u^2).$

Lemma 3.1 is useful when we derive the cone structure of a Dupin hypersurface f from the cone structure of its Möbius position vector Y. It is also easily seen that

Lemma 3.2. Let $u: M^k \longrightarrow \mathbb{S}^{k+1}$ be an immersed hypersurface. Then the cone

$$f(t,y,p) = (y,tu(p)): \mathbb{R}^+ \times \mathbb{R}^{n-k-1} \times M^k \longrightarrow \mathbb{R}^{n+1}$$

is a Dupin hypersurface of constant Möbius curvatures if and only if the hypersurface u is an isoparametric hypersurface in \mathbb{S}^{k+1} .

Proof. From (3.13) it is very clear that, if u is isoparametric, then the cone f is a Dupin hypersurface of constant Möbius curvatures. To see the other direction, assume f is Dupin of constant Möbius curvatures. Then, from (3.13) and the fact that all Möbius curvatures are constant, it is straightforward to see that all the ratios $\frac{\lambda_i}{\lambda_j}$ are constant. Now, one knows from the fact that f is Dupin, each principal curvature λ_i is constant along the principal direction e_i that is perpendicular to the homogeneous direction t. Therefore each principal curvature λ_i is in fact constant in all directions. Thus the proof is complete.

For the cone f over an isoparametric hypersurface u in the sphere \mathbb{S}^{k+1} the eigenvalues of the Blaschke tensor and the Möbius second fundamental form are

(3.17)
$$A = diag(\underbrace{\mu, \cdots, \mu}_{n-k}, a_{n-k+1}, \cdots, a_n), B = diag(\underbrace{\lambda, \cdots, \lambda}_{n-k}, b_{n-k+1}, \cdots, b_n), \text{ and } C = 0,$$

where

$$(3.18) a_{\alpha} = -\lambda b_{\alpha} - \mu$$

and

$$\mu = -\frac{1}{2\rho_0^2} (1 + \frac{k^2}{n^2} H_u^2), \quad \lambda = -\frac{1}{\rho_0} \frac{k}{n} H_u, \quad b_\alpha = \frac{1}{\rho_0} (\lambda_{\alpha - n + k} - \frac{k}{n} H_u),$$

for $n-k+1 \leq \alpha \leq n$, following the equations (2.9). From (3.14), we know that the Möbius metric g is a Riemannian product, that is, $(M^n, g) = (\mathbb{H}^{n-k}, \rho_0^2 g_{\mathbb{H}}) \times (M^k, \rho_0^2 I_u)$ locally. Moreover

$$B|_{T\mathbb{H}^{n-k}} = \lambda \rho_0^2 g_{\mathbb{H}}, \ A|_{T\mathbb{H}^{n-k}} = \mu \rho_0^2 g_{\mathbb{H}}, \ A|_{TM^k} = -\lambda B|_{TM^k} - \mu \rho_0^2 I_u, \text{ and } \lambda^2 + 2\mu = -\frac{1}{\rho_0^2} < 0.$$

It is very important to observe that both the Blaschke tensor A and the Möbius second fundamental form B are so-called isoparametric tensors according to Definition A.1. Moreover, and equations (3.17) and (3.18) are sufficient to characterize a cone f over an isoparametric surface u in a sphere. Namely,

Theorem 3.1. Suppose that $f: M^n \to \mathbb{R}^{n+1}$ is a Dupin hypersurface with $r(\geq 3)$ distinct principal curvatures and constant Möbius curvature. And suppose that (3.17) and (3.18) hold for some constants $a_{\alpha}, b_{\alpha}, \lambda, \mu$. Then f is Möbius equivalent to a cone over an isoparametric hypersurface in \mathbb{S}^{k+1} .

Proof. The equations (3.17) and (3.18) implies that the Blaschke tensor A and the Möbius second fundamental form B are not linearly dependent, since $\lambda^2 + 2\mu < 0$. From Theorem 4.1 and its proof in Section 4, we know

(3.19)
$$R_{j\alpha j\alpha} = 0 \text{ and } \omega_{j\alpha} = 0 \text{ for } j = 1, \cdots, n-k \text{ and } \alpha = n-k+1, \cdots, n$$

and therefore

$$\begin{cases} d\omega_j = \sum_m \omega_m \wedge \omega_{mj} = \sum_{m \le n-k} \omega_m \wedge \omega_{mj}, & 1 \le j \le n-k \\ d\omega_\beta = \sum_m \omega_m \wedge \omega_{m\beta} = \sum_{\alpha \ge n-k+1} \omega_\alpha \wedge \omega_{\alpha\beta}, & n-k+1 \le \beta \le n \end{cases}$$

Thus the distributions $\mathbb{D}_1 = Span\{E_1, \cdots, E_{n-k}\}$ and $\mathbb{D}_2 = Span\{E_{n-k+1}, E_{n-k+2}, \cdots, E_n\}$ are integrable. Recall the corresponding Möbius position vector

$$Y = \rho(\frac{1+|f|^2}{2}, \frac{1-|f|^2}{2}, f) : M^n \to C^{n+2}_+ \subset \mathbb{R}^{n+3}_1$$

and set

(3.20)
$$F = \lambda Y + \xi, \quad P = \frac{1}{\sqrt{-K}} [-(\lambda^2 + \mu)Y + N - \lambda\xi],$$
$$T = \frac{-1}{\sqrt{-K}} (\mu Y + N - \lambda\xi), \quad \text{and } K = \lambda^2 + 2\mu.$$

Then $\{F, P, T, Y_1, \dots, Y_n\}$, where $Y_i = Y_*(E_i)$, is a local orthogonal frame along M^n in \mathbb{R}^{n+3}_1 . From the structure equations (2.2) and (3.19), we get the new structure equations

$$\begin{cases}
dF = \sum_{\alpha \ge n-k+1} (\lambda - b_{\alpha})\omega_{\alpha}Y_{\alpha} \\
dP = \sqrt{-K} \sum_{\alpha \ge n-k+1} \omega_{\alpha}Y_{\alpha} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
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dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = ((b_{\alpha} - \lambda)F - \sqrt{-K}P)\omega_{\alpha} + \sum_{\beta \ge n-k+1} \omega_{\alpha\beta}Y_{\beta} \\
dY_{\alpha} = (b_{\alpha} - \lambda)F - \sqrt{-K}P + \sum_{k=1} (b_{\alpha} - \lambda)F - \sum_{\beta \ge n-k+1} (b_{\alpha} - \lambda)$$

From (3.21), we know that the subspace $V = Span\{P, Y_{n-k+1}, \dots, Y_n, F\}$ and the orthogonal complement $V^{\perp} = Span\{T, Y_1, \dots, Y_{n-k}\}$ are parallel along M^n . We can assume that $V = \mathbb{R}^{k+2}$ and $V^{\perp} = \mathbb{R}_1^{n-k+1}$. Let M^{n-k} be an integrable submanifold of the distribution $\mathbb{D}_1 = \{E_1, E_2, \dots, E_{n-k}\}$ and M^k an integrable submanifold of the distribution $\mathbb{D}_2 = \{E_{n-k+1}, \dots, E_n\}$. From (3.21), we know that P is constant along the variables in M^{n-k} and hence

$$P: M^k \to \mathbb{R}^{n+3}_1$$

is an k-dimensional immersed submanifold. Similarly, we know that

$$T: M^{n-k} \to \mathbb{R}^{n+3}_1$$

is an (n - k)-dimensional immersed submanifold. One may calculate that $\langle P, P \rangle = 1$ and conclude that

$$P: M^k \to \mathbb{S}^{k+1} \subset V = \mathbb{R}^{k+2} \subset \mathbb{R}^{n+3}_1$$

since V is a fixed space-like subspace. Similarly, one may calculate $\langle T, T \rangle = -1$ and conclude that, up to a Möbius transformation,

$$T: M^{n-k} \to \mathbb{H}^{n-k} \subset V^{\perp} = \mathbb{R}^{n-k+1}_1 \subset \mathbb{R}^{n+3}_1$$

since V^{\perp} is a fixed Lorentzian subspace in \mathbb{R}^{n+3}_1 . In the light of (4.30), which is a consequence of the integrability condition (2.6), we know that the sectional curvature for the manifold M^{n-k} is, for $i, j = 1, \dots, n-k$,

$$R_{ijij}[g_1] = \frac{1}{-K} R_{ijij}[g] = \frac{1}{-K} (\lambda^2 + 2\mu) = -1,$$

which implies that T is an isometry of \mathbb{H}^{n-k} .

Moreover we have

$$Y = \frac{1}{\sqrt{-K}}(T+P) = \frac{1}{\sqrt{-K}}(T,P) : M^{n-k} \times M^k \to \mathbb{H}^{n-k} \times \mathbb{S}^{k+1} \subset \mathbb{R}^{n+3}_1$$

is the Möbius position vector of the cone over an isoparametric hypersurface P according to Lemma 3.1 and Lemma 3.2. Thus the proof is complete.

4 Proof of Theorem 1.1

In this section we present the proof for Theorem 1.1. By now, according to Corollary 2.2 and Theorem 3.1, to prove Theorem 1.1 it suffices to prove the following:

Theorem 4.1. Let $f: M^n \to \mathbb{R}^{n+1}$ be a Dupin hypersurface with $r(\geq 3)$ distinct principal curvatures and constant Möbius curvatures. Then either

(a) A and B are linearly dependent, that is, $A = \lambda B + \mu g$ for some constants λ and μ , or

(b) the Riemannian manifold (M^n, g) is locally reducible, that is, $(M^n, g) = (M_1, g_1) \times (M_2, g_2)$ locally. Moreover

 $B|_{TM_1} = \lambda g_1, \quad A|_{TM_1} = \mu g_1, \quad and \quad A|_{TM_2} = -\lambda B|_{TM_2} - \mu g_2,$

for some constants λ and μ such that $\lambda^2 + 2\mu < 0$.

4.1 Outline of the proof of Theorem 4.1

The main idea of the proof of Theorem 4.1 is to use two commuting isoparametric tensors (cf. Definition A.1) to capture the geometric structure. We leave the discussions on basics of isoparametric tensors including two commuting isoparametric tensors in Appendix A. We will first show that the Möbius second fundamental form B and the Blaschke tensor A are commuting isoparametric tensors. Then we will show that commuting isoparametric tensors A and B that satisfy the condition (2.6) will be either linearly dependent or cause the hypersurface to be reducible.

Let $f: M^n \to \mathbb{R}^{n+1}$ be a Dupin hypersurface of constant Möbius curvatures. From Theorem 2.1 (cf. [39]) we know that its Möbius form C vanishes and its Möbius principal curvatures $\{b_i\}$ are all constant. Immediately from equations (2.3), (2.4) and (2.5), we know that the Möbius second fundamental form B and the Blaschke tensor A are two commuting Codazzi tensors. Moreover, B is in fact an isoparametric tensor according to Definition A.1.

To make it more clearer about the behaviors of these two tensors, we can choose a local orthonormal basis $\{E_1, \dots, E_n\}$ for TM^n with respect to the Möbius metric g such that

(4.22)
$$(A_{ij}) = diag(a_1, \cdots, a_n),$$
$$(B_{ij}) = diag(b_1, \cdots, b_n) = diag(b_{\overline{1}}, \cdots, b_{\overline{1}}, b_{\overline{2}}, \cdots, b_{\overline{2}}, \cdots, b_{\overline{r}}, \cdots, b_{\overline{r}}).$$

Let $[i] = \{k | b_k = b_i\}$. Then $V_{b_i} = Span\{E_k | k \in [i]\}$ is the eigenspace of *B* corresponding to the eigenvalue b_i . Since *B* is an isoparametric tensor, from (A.74) and (A.75), we know

(4.23)
$$\begin{cases} B_{ij,k} = 0 \text{ when } [i] = [j] \text{ or } [i] = [k], \\ \omega_{ij} = \sum_{k} \frac{B_{ij,k}}{b_i - b_j} \omega_k \text{ when } [i] \neq [j] \end{cases}$$

and

(4.24)
$$R_{ijij} = \sum_{k \notin [i], [j]} \frac{2B_{ij,k}^2}{(b_i - b_k)(b_j - b_k)} \text{ when } [i] \neq [j].$$

One of the important steps in our proof is to show that the Blaschke tensor A is also an isoparametric tensor. That is to show that eigenvalues $\{a_1, \dots, a_n\}$ are all constant according to Definition A.1.

Theorem 4.2. Let $f: M^n \to \mathbb{R}^{n+1}$ be a Möbius isoparametric hypersurface without umbilical points. Then the eigenvalues of the Blaschke tensor $\{a_1, \dots, a_n\}$ are all constant.

Proof. In the light of the classification result in [20], we may assume that the number r of distinct principal curvatures is greater than 2. Since the Blaschke tensor is a Codazzi tensor, we have

$$(a_i - a_j)\omega_{ij} = \sum_k A_{ij,k}\omega_k,$$

which implies, from (4.23),

(4.25)
$$(a_i - a_j) \frac{B_{ij,k}}{b_i - b_j} = A_{ij,k} \text{ when } [i] \neq [j].$$

Hence we know

(4.26)
$$E_i(a_j) = A_{jj,i} = A_{ij,j} = 0$$
 when $[i] \neq [j]$

from $B_{ij,j} = 0$. Now to verify that a_j is a constant, we only need to prove

(4.27)
$$E_i(a_j) = 0, \ i \in [j].$$

For a fixed point $p \in M^n$ and $j \in \{1, \dots, n\}$, it is either $B_{jk,l} = 0$ for all $1 \leq k, l \leq n$ or $B_{jk,l} \neq 0$ for some $1 \leq k, l \leq n$. First assume it is the second case. In fact we may assume

 $B_{jk,l} \neq 0$ in a neighborhood of p for some j, k, l that have to be associated to three distinct Möbius principal curvatures. Therefore, from (4.25), we obtain

$$\frac{a_j - a_k}{b_j - b_k} = \frac{A_{jk,l}}{B_{jk,l}} = \frac{A_{lk,j}}{B_{lk,j}} = \frac{a_l - a_k}{b_l - b_k}$$

which implies

(4.28)
$$a_j = (a_l - a_k) \frac{b_j - b_k}{b_l - b_k} + a_k$$

This easily implies (4.27). Next, suppose it is the first case. If there is a sequence of point $p_i \to p$ in M^n such that the second cases happen on p_i for some $1 \le k, l \le n$, then (4.27) holds at p due to the continuity. Otherwise, there is an open neighborhood $U \subset M^n$ of p such that $B_{jk,l} = 0$ for all $1 \le k, l \le n$ in U. Therefore $R_{jkjk} = 0$ in U from (4.24). Hence, from (2.6), we derive

(4.29)
$$a_j = -b_j b_k - a_k \text{ in } U \text{ when } k \notin [j],$$

which obviously implies (4.27). Thus the proof is complete.

Remark 4.1. From the above proof it is clear that the following statement is true. Suppose that A and B are two commuting Codazzi tensors and that B is an isoparametric tensor of $r(\geq 3)$ distinct eigenvalues. In addition assume $R_{ijij} = -a_i - a_j$ (cf. (5.63)). Then A is also an isoparametric tensor.

From now on in this section we will focus to studying Riemmannian manifolds with two commuting isoparametric tensors T_1 and T_2 that satisfy the condition

(4.30)
$$R_{ijkl} = \frac{1}{2} (T_1 \bigodot T_1)_{ijkl} + (T_2 \bigodot g)_{ijkl}$$

according to (2.6), where \bigcirc denotes the Kulkarni-Nomizu product (cf. Section A.1). We will complete the proof of Theorem 4.1 in Section 4.2 and Section 4.3. For basic properties of isoparametric tensors readers are referred to Section A.1 and Section A.2 in Appendix A.

4.2 Linear relations of commuting isoparametric tensors

Definition 4.1. Let (M^n, g) be a Riemannian manifold. Two symmetric 2-tensors T_1 and T_2 are said to be linearly dependent, if there exist constants $\lambda, \mu, \varepsilon$ such that $\lambda T_1 + \mu T_2 = \varepsilon g$.

Clearly two linearly dependent symmetric 2-tensors are always commuting. It turns out the converse is not true. In fact, two commuting isoparametric tensors on a Riemannian manifold are not necessarily linearly dependent. In this subsection we want to give a sufficient condition

for two commuting isoparametric tensors that satisfy the (4.30) to be linearly dependent. Our approach is to carefully study the linear co-relations of all distinct pairs of eigenvalues of two commuting isoparametric tensors. First of all, given two commuting isoparametric tensors that satisfy (4.30), by Lemma A.3, we may choose the orthonormal basis $\{E_1, \dots, E_n\}$ such that

$$(T_{ij}) = diag(\underbrace{b_{\overline{1}}, \cdots, b_{\overline{1}}}_{(\bar{t}_{ij})}, \underbrace{b_{\overline{2}}, \cdots, b_{\overline{2}}}_{(\bar{t}_{ij})}, \cdots, \underbrace{b_{\bar{r}}, \cdots, b_{\bar{r}}}_{(\bar{t}_{ij})}),$$
$$(\hat{T}_{ij}) = diag(\underbrace{a_{\overline{1}}, \cdots, a_{\overline{1}}, \overline{a_{\overline{1}}}, \cdots, \overline{a_{\overline{1}}}}_{(\bar{t}_{ij})}, \cdots, \underbrace{a_{\bar{r}}, \cdots, a_{\bar{r}}, \overline{a_{\bar{r}}}, \cdots, \overline{a_{\bar{r}}}}_{(\bar{t}_{ij})}),$$

where $a_{\bar{i}}$ and $\bar{a}_{\bar{i}}$ may be same and $b_{\bar{1}} < \cdots < b_{\bar{r}}$. We then define the following two index sets

$$[i] = \{k \in \{1, 2, \cdots, n\} | b_k = b_i\}$$
 and $(i) = \{k \in [i] | a_k = a_i\}$

Let s be the number of the distinct groups of indices in the collection $\{(1), (2), \dots, (n)\}$ and label these distinct groups of indices as $\{(\bar{1}), (\bar{2}), \dots, (\bar{s})\}$. Clearly, we have $(i) \subseteq [i]$ and $s \geq r$. For any $i \in \{1, 2, \dots, n\}$, we consider the pair (a_i, b_i) and observe that

$$(a_i, b_i) = (a_j, b_j)$$
 if and only if $(i) = (j)$.

Hence one may write $(a_i, b_i) = (a_{(i)}, b_{(i)})$ and there are exactly s distinct pairs. Let W denote the set of all of the pairs, that is,

$$W = \{ (a_{(\bar{1})}, b_{(\bar{1})}), (a_{(\bar{2})}, b_{(\bar{2})}), \cdots, (a_{(\bar{s})}, b_{(\bar{s})}) \}.$$

For a number ε (including ∞) and a group (i) fixed, we define the set of pairs

$$S_{(i)}(\varepsilon) := \{(a_k, b_k) \in W | \frac{a_i - a_k}{b_i - b_k} = \varepsilon, \ k \notin (i)\} \bigcup \{(a_{(i)}, b_{(i)})\}$$

From Lemma A.3 and the above definition of $S_{(i)}(\varepsilon)$, it is easy to verify the following properties:

Lemma 4.1. Suppose that T_1 and T_2 are two commuting isoparametric tensors on a Riemannian manifold (M^n, g) and satisfy the relation (4.30). For a fixed index set (i), the following hold:

- (1) $S_{(i)}(\infty)$ can have at most two pairs;
- (2) For two non-empty sets $S_{(i)}(\varepsilon_k), S_{(i)}(\varepsilon_l)$ and $\varepsilon_k \neq \varepsilon_l, S_{(i)}(\varepsilon_k) \cap S_{(i)}(\varepsilon_l) = \{(a_{(i)}, b_{(i)})\};$
- (3) There exist only finitely many constants (including ∞) $\varepsilon_1, \cdots, \varepsilon_l$ such that $S_{(i)}(\varepsilon_1), \cdots, S_{(i)}(\varepsilon_l)$ are non-empty;

(4) If the set
$$S_{(i)}(\varepsilon) = \{(a_{(i)}, b_{(i)}), (a_{(j)}, b_{(j)})\}$$
 for $j \notin (i)$, then

$$(4.31) R_{klkl} = b_i b_j + a_i + a_j = 0 \text{ for all } k \in (i) \text{ and } l \in (j)$$

Proof. These properties are all trivial except (4). It suffices to show that $T_{kl,m} = 0$ for all $m = 1, 2, \dots, n$ when $k \in (i)$ and $l \in (j)$. The nontrivial cases are $k \in (i) \subset [i], l \notin [i]$ and $m \notin [i] \cup [l]$. Hence, from the third equation in (A.81), we would have

$$\frac{a_m - a_k}{b_m - b_k} = \frac{T_{km,l}}{T_{km,l}} = \frac{T_{lk,m}}{T_{lk,m}} = \frac{a_l - a_k}{b_l - b_k}$$

if $T_{kl,m} = T_{km,l}$ were not vanishing. That would imply $(a_m, b_m) \in S_{(i)}(\varepsilon)$ and a contradiction to assumption that $S_{(i)}(\varepsilon)$ has only two pairs. Thus the proof is complete.

Next we want to understand the geometric impacts for the set $S_{(i)}(\varepsilon)$ to contain more than two pairs. Again the key is to establish the generalized Cartan identity that relates the sectional curvatures in the planes generated by the eigenvectors whose eigenvalues lie in the set $S_{(i)}(\varepsilon)$.

Lemma 4.2. Suppose that T_1 and T_2 are two commuting isoparametric tensors on a Riemannian manifold (M^n, g) and satisfy the relation (4.30). And suppose that, for some *i* and ε ,

$$S_{(i)}(\varepsilon) = \{(a_{i_1}, b_{i_1}), (a_{i_2}, b_{i_2}), \cdots, (a_{i_t}, b_{i_t})\}$$

has t number of distinct pairs for $t \geq 3$. Then, for $j \in (i_k)$, $h \in (i_l)$, $i_k \neq i_l$,

(4.32)
$$R_{jhjh} = \sum_{m \in (i_1) \cup (i_2) \cup \dots \cup (i_t), m \notin (i_k) \cup (i_l)} \frac{T_{jh,m}^2}{(b_{i_k} - b_m)(b_{i_l} - b_m)}.$$

Consequently, if $b_{i_1} < b_{i_2} < \cdots < b_{i_t}$, then

(4.33)
$$\begin{aligned} R_{ijij} &= b_{i_m} b_{i_{m+1}} + a_{i_m} + a_{i_{m+1}} \ge 0, \quad i \in (i_m), \ j \in (i_{m+1}), \quad m = 1, 2, \cdots, t-1, \\ R_{ijij} &= b_{i_1} b_{i_t} + a_{i_1} + a_{i_t} \le 0, \quad i \in (i_1), \ j \in (i_t). \end{aligned}$$

More importantly, for each i_k fixed and $j \in (i_k)$, we have the following generalized Cartan identity,

(4.34)
$$\sum_{m \in (i_1) \cup (i_2) \cup \dots \cup (i_t), m \notin (i_k)} \frac{R_{jmjm}}{b_{i_k} - b_m} = 0.$$

Proof. It suffices to prove that

$$T_{jh,m} = 0$$
 when $j, h \in (i_1), (i_2), \cdots, (i_t)$, and $m \notin (i_1), (i_2), \cdots, (i_t)$.

The argument is exactly the same as the proof of (4) in the above lemma. Because $T_{jh,m} \neq 0$ would imply that $(a_m, b_m) \in S_{(i)}(\varepsilon)$, which is a contradiction.

Consequently we observe

Lemma 4.3. Under the same assumptions as in Lemma 4.2,

$$b_{i_1} + \varepsilon < 0, \quad b_{i_t} + \varepsilon > 0.$$

Proof. From Lemma 4.2, we have

$$(4.35) R_{i_1 i_2 i_1 i_2} \ge 0, \quad R_{i_1 i_t i_1 i_t} \le 0.$$

In the light of the assumption (4.30), we arrive at

$$0 \le R_{i_1 i_2 i_1 i_2} - R_{i_1 i_t i_1 i_t} = b_{i_1} (b_{i_2} - b_{i_t}) + a_{i_2} - a_{i_t}$$

= $(b_{i_2} - b_{i_t})(b_{i_1} + \frac{a_{i_2} - a_{i_t}}{b_{i_2} - b_{i_t}}) = (b_{i_2} - b_{i_t})(b_{i_1} + \varepsilon),$

which implies $b_{i_1} + \varepsilon \leq 0$. To prove that $b_{i_1} + \varepsilon < 0$ we do it by contradiction. We assume otherwise $b_{i_1} + \varepsilon = 0$ and hence $b_{i_t} + \varepsilon > b_{i_1} + \varepsilon = 0$. Immediately we have

$$R_{i_1ki_1k} - R_{i_1li_1l} = b_{i_1}(b_k - b_l) + a_k - a_l = (b_k - b_l)(b_{i_1} + \varepsilon) = 0 \text{ for any } k \in (i_k) \text{ and } l \in (i_l).$$

That is

$$R_{i_1ki_1k} = R_{i_1li_1l}$$
 for any $k \in (i_k)$ and $l \in (i_l)$

which forces, from (4.35), $R_{i_1ki_1k} = 0$ for any $k \in (i_2) \cup (i_3) \cdots \cup (i_t)$. On the other hand,

$$R_{i_{t}ki_{t}k} - R_{i_{t}li_{t}l} = b_{i_{t}}(b_{k} - b_{l}) + a_{k} - a_{l} = (b_{k} - b_{l})(b_{i_{t}} + \varepsilon) \quad \text{for any } k \in (i_{k}) \text{ and } l \in (i_{l}),$$

which implies

$$0 = R_{i_t i_1 i_t i_1} < R_{i_t i_2 i_t i_2} < \dots < R_{i_t i_{t-1} i_t i_{t-1}}$$

and hence

$$R_{i_t m i_t m} > 0$$
 for any $m \in (i_2) \cup (i_3) \cdots \cup (i_{t-1})$.

Therefore, in the light of the generalized Cartan identity (4.34) for $i = i_t$,

$$\sum_{\substack{m \in (i_2) \cup (i_3) \cup \dots \cup (i_{t-1})}} \frac{R_{i_t m i_t m}}{b_{i_t} - b_m} = 0$$

and therefore $R_{i_tmi_tm} = 0$ for $m \in (i_1) \cup (i_2) \cup \cdots \cup (i_{t-1})$ and $b_{i_t} + \varepsilon = 0$, which is a contradiction when $t \geq 3$.

To prove $b_{i_t} + \varepsilon > 0$, similarly from Lemma 4.2, we start with

$$R_{i_{t}i_{t-1}i_{t}i_{t-1}} \ge 0$$
 and $R_{i_{1}i_{t}i_{1}i_{t}} \le 0$

and

$$0 \le R_{i_t i_{t-1} i_t i_{t-1}} - R_{i_1 i_t i_1 i_t} = (b_{i_{t-1}} - b_{i_1})(b_{i_t} + \varepsilon),$$

to conclude $b_{i_t} + \varepsilon \ge 0$. Then, with the argument similar as that in the above, we can derive a contradiction if $b_{i_t} + \varepsilon = 0$. Thus the proof is complete.

The following is another technical lemma we will use to discover the structure of the distribution of pairs (a_i, b_i) in the plane and facilitate the proof of Theorem 1.1. It is clear that pairs in each set $S_{(i)}(\varepsilon)$ lie in a line with the slope ε if $S_{(i)}(\varepsilon)$ has more than one pairs. We observe

Lemma 4.4. Under the same assumptions as that in Lemma 4.2, if the set $S_{(i)}(\varepsilon)$ has at least three distinct pairs and the line equation for the set $S_{(i)}(\varepsilon)$ is

$$a=\varepsilon b+d$$

for some constant d, then

$$(4.36)\qquad \qquad \varepsilon^2 - 2d < 0.$$

Proof. As in the above, let $S_{(i)}(\varepsilon) = \{(a_{i_1}, b_{i_1}), (a_{i_2}, b_{i_2}), \cdots, (a_{i_t}, b_{i_t})\}$ and $b_{i_1} < b_{i_2} < \cdots < b_{i_t}$. By the assumption, each pair (a_{i_k}, b_{i_k}) in $S_{(i)}(\varepsilon)$ satisfies the line equation

$$a_{i_k} = \varepsilon b_{i_k} + d.$$

Hence, for $i \in (i_k)$ and $j \in (i_l)$, from the assumption (4.30), we obtain

(4.37)
$$R_{ijij} = b_i b_j + a_i + a_j = (b_{i_k} + \varepsilon)(b_{i_l} + \varepsilon) + 2d - \varepsilon^2.$$

For the simplicity, we will use the notations $\tilde{b}_i = b_i + \varepsilon$ in the following.

We first claim that $2d - \varepsilon \ge 0$. Assume otherwise that $2d - \varepsilon < 0$. From Lemma 4.2, we know that

$$0 \le R_{i_m i_{m+1} i_m i_{m+1}} = \tilde{b}_{i_m} \tilde{b}_{i_{m+1}} + 2d - \varepsilon^2, \quad m = 1, 2, cdots, t - 1,$$

which implies

(4.38)
$$\tilde{b}_{i_m}\tilde{b}_{i_{m+1}} > 0,$$

for all $m \in \{1, 2, \dots, t-1\}$. Under the assumptions, we know from Lemma 4.3 that $\tilde{b}_{i_1} < 0$. Therefore we may conclude that $\tilde{b}_{i_t} < 0$ in the light of (4.38), which is a contradiction to $\tilde{b}_{i_t} > 0$ in Lemma 4.3. So we have $2d - \varepsilon \ge 0$.

Next we want to exclude the cases that $2d - \varepsilon = 0$. Assume again otherwise that $2d - \varepsilon = 0$. From the generalized Cartan identity for $i = i_k$ in Lemma 4.2, we write

$$0 = \sum_{m \in (i), (i_1), (i_2), \cdots, (i_t), m \notin (i_k)} \frac{\tilde{b}_{i_k} \tilde{b}_m}{\tilde{b}_{i_k} - \tilde{b}_m} = \sum_{m \in (i), (i_1), (i_2), \cdots, (i_t), m \notin (i_k)} \frac{1}{\frac{1}{\tilde{b}_{i_m}} - \frac{1}{\tilde{b}_{i_k}}}.$$

This is impossible if one takes $i_k = i_1$ or $i_k = i_t$. Thus $2d - \varepsilon^2 > 0$.

It is obvious that, in order for tensors T_1 and T_2 to be linearly dependent, all the pairs have to be lined in one set $S_{(i)}(\varepsilon)$. Particularly it is necessary that (i) = [i] for each $i = 1, 2, \dots, n$, i.e. r = s. Let us list all the sets $S_{(\bar{1})}(\varepsilon)$ which have more than one pairs

$$S_{(\bar{1})}(\varepsilon_1), S_{(\bar{1})}(\varepsilon_2), \cdots, S_{(\bar{1})}(\varepsilon_t),$$

where $\varepsilon_1 < \varepsilon_2 < \cdots < \varepsilon_t$. Now we are ready to state a theorem for linear dependence of two commuting isoparametric tensors.

Theorem 4.3. Suppose that T_1 and T_2 are two commuting isoparametric tensors on a Riemannian manifold (M^n, g) and satisfy the relation (4.30). And suppose that r = s. If the set $S_{(\bar{1})}(\varepsilon_1)$ has at least three distinct pairs, or $r = s \leq 2$, then there exists constant μ such that

(4.39)
$$T_2 = \varepsilon_1 T_1 + \mu g.$$

Before the proof of Theorem 4.3, we first establish a sequence of lemmas. Let

$$S_{(\bar{1})}(\varepsilon_1) = \{(a_1, b_1), (a_{i_1}, b_{i_1}), \cdots, (a_{i_k}, b_{i_k})\}$$

and $b_1 < b_{i_1} < \cdots < b_{i_k}$ for some $k \ge 2$.

Lemma 4.5. Under the assumptions in Theorem 4.3,

$$(4.40) b_{\bar{1}} + \varepsilon_i < 0$$

for all $i = 1, 2, \dots, t$.

Proof. In the light of Lemma 4.3 one may only need to consider the cases when $S_{(\bar{1})}(\varepsilon_i)$ has exactly two pairs, say, $S_{(\bar{1})}(\varepsilon_i) = \{(a_1, b_1), (a_j, b_j)\}$ for some $i = 2, 3, \dots, t$. Hence, from Lemma 4.2, we know that

$$b_1b_j + a_1 + a_j = 0.$$

On the other hand,

$$b_1^2 + 2a_1 - (b_1b_{i_1} + a_1 + a_{i_1}) = (b_1 - b_{i_1})(b_1 + \frac{a_1 - a_{i_1}}{b_1 - b_{i_1}}) = (b_1 - b_{i_1})(b_1 + \varepsilon_1) > 0.$$

Since $b_1 + \varepsilon_1 < 0$ due to Lemma 4.3. Therefore

$$b_1^2 + 2a_1 > b_1b_{i_1} + a_1 + a_{i_1} = R_{1i_11i_1} \ge 0$$

by Lemma 4.2 again. Thus

$$0 < b_1^2 + 2a_1 - (b_1b_j + a_1 + a_j) = (b_1 - b_j)(b_1 + \varepsilon_i),$$

which implies that $b_1 + \varepsilon_i < 0$. So the proof is complete.

To set some notations, let the line equation for each set $S_{(\bar{1})}(\varepsilon_m)$ is

$$a = \varepsilon_m b + d_m, \quad m = 1, 2, \cdots, t$$

Then we have

(4.41)
$$-b_{\bar{1}} = \frac{d_i - d_j}{\varepsilon_i - \varepsilon_j}$$

for all $i, j = 1, 2, \dots, t$.

Lemma 4.6. Under the assumptions in Theorem 4.3,

$$(4.42) b_i^2 + 2a_i > 0$$

for all $j = 1, 2, \dots n$.

Proof. First, for a given pair (a_j, b_j) , it lies in $S_{(\bar{1})}(\varepsilon_m)$ for some $m = 1, 2, \dots, t$. Then

$$b_j^2 + 2a_j = (b_j + \varepsilon_m)^2 - \varepsilon_m^2 + 2d_m.$$

To prove $b_j^2 + 2a_j > 0$ one may verify that $-\varepsilon_m^2 + 2d_m > 0$. From Lemma 4.4, we know that $-\varepsilon_1^2 + 2d_1 > 0$. Hence we use (4.41) to calculate

$$-\varepsilon_m^2 + 2d_m - (-\varepsilon_1^2 + 2d_1) = (\varepsilon_1 - \varepsilon_m)(2b_1 + \varepsilon_1 + \varepsilon_m),$$

which is positive according to Lemma 4.5. Therefore $-\varepsilon_m^2 + 2d_m > 0$ and the proof is complete.

The following lemma is very useful to understand what are the possible lines that connect all pairs in W. Notice that, if $S_{(\bar{1})}(\varepsilon_1)$ does not contain all the pairs, then the set $S_{(i_l)}(\varepsilon)$ for some $\varepsilon \neq \varepsilon_1$ must contain more than one pairs.

Lemma 4.7. Assume the same assumptions of Theorem 4.3 hold. Then, for any set $S_{(i_l)}(\varepsilon)$, $l = 1, \dots, k$, that contains more than one pairs, if $\varepsilon < \varepsilon_1$, then $b_{i_l} + \varepsilon > 0$ and $b_{i_l} \ge b_j$ for all $(a_j, b_j) \in S_{(i_l)}(\varepsilon)$. Similarly, if $\varepsilon > \varepsilon_1$, then $b_{i_l} + \varepsilon < 0$ and $b_{i_l} \le b_j$ for all $(a_j, b_j) \in S_{(i_l)}(\varepsilon)$.

Proof. Let $d_j = a_j - \varepsilon_1 b_j$ for $j = 1, 2, \dots, n$. Then it is clear that $d_j = d_1$ when $j \in [1] \cup [i_1] \cup \cdots \cup [i_k]$. On the other hand, if $j \notin [1] \cup [i_1] \cdots \cup [i_k]$, then

$$d_1 - d_j = (b_1 - b_j)(-\varepsilon_1 + \frac{a_1 - a_j}{b_1 - b_j}) < 0.$$

Because ε_1 is the smallest slope among all lines passing through (a_1, b_1) . Therefore

(4.43)
$$d_1 = d_j = \min\{d_1, d_2, \cdots, d_n\}, \ j \in [1] \cup [i_1] \cup \cdots \cup [i_k]$$

First, we consider $\varepsilon < \varepsilon_1$. for any $(a_j, b_j) \in S_{(i_l)}(\varepsilon) \setminus \{(a_{i_l}, b_{i_l})\}$, we have

$$d_j - d_{i_l} = (b_j - b_{i_l})(\frac{a_{i_l} - a_j}{b_{i_l} - b_j} - \varepsilon_1) = (b_j - b_{i_l})(\varepsilon - \varepsilon_1)$$

Thus, by (4.43), we see that $b_j \leq b_{i_l}$.

Again, to show $b_{i_l} + \varepsilon > 0$, in the light of Lemma 4.3, one may assume that $S_{(i_l)}(\varepsilon)$ has exactly two pairs, say, $S_{(\bar{i_l})}(\varepsilon) = \{(a_j, b_j), (a_{i_l}, b_{i_l})\}$. From Lemma 4.2, we know

$$R_{ji_l j j i_l} = b_j b_{i_l} + a_j + a_{i_l} = 0.$$

Similar to the proof of Lemma 4.5, we calculate

$$b_{i_l}^2 + 2a_{i_l} = b_{i_l}^2 + 2a_{i_l} - (b_j b_{i_l} + a_j + a_{i_l}) = (b_{i_l} - b_j)(b_{i_l} + \varepsilon)_{i_l}$$

which implies $b_{i_l} + \varepsilon > 0$ due to Lemma 4.6. The above proof works for the case $\varepsilon > \varepsilon_1$. Thus the proof is complete.

We now are ready to present the proof for Theorem 4.3.

Proof of Theorem 4.3. For the case $r = s \leq 2$, obviously $T_2 = \varepsilon_1 T_1 + \mu g$ for some constant μ . Next let $r = s \geq 2$. We assume otherwise that $S_{(\bar{1})}(\varepsilon_1)$ does not contain all the pairs. Recall

$$S_{(\bar{1})}(\varepsilon_1) = \{(a_1, b_1), (a_{i_1}, b_{i_1}), \cdots, (a_{i_k}, b_{i_k})\}$$

and $b_1 < b_{i_1} < \cdots < b_{i_k}$ for some $k \ge 2$. For each $i_l \in \{i_1, \cdots, i_k\}$ fixed, let

$$S_{(i_l)}(\varepsilon_1), S_{(i_l)}(\varepsilon_{j_1}^l), \cdots, S_{(i_l)}(\varepsilon_{j_h}^l)$$

be the full list of the set that contain more than just the pair (a_{i_l}, b_{i_l}) and $\varepsilon_{j_1}^l < \cdots < \varepsilon_{j_h}^l$, where $h \ge 1$ and may depend of l. Our argument is to show there is no way to compare ε_1 with the rest slopes $\varepsilon_{j_m}^l$ when l = k.

It is easy to see that ε_1 has to be large than each slope $\varepsilon_{j_m}^k$. Assume otherwise $\varepsilon_1 < \varepsilon_{j_m}^k$ for some *m*. Then, on one hand, applying Lemma 4.3 to $S_{(\bar{1})}(\varepsilon_1)$, we obtain

$$b_{i_k} + \varepsilon_1 > 0$$

On the other hand, applying Lemma 4.7 to $S_{(i_k)}(\varepsilon_{j_m}^k)$, we obtain

$$b_{i_k} + \varepsilon_1 < b_{i_k} + \varepsilon_{j_m}^k < 0,$$

which is a contradiction.

Next we want to show that it is also impossible to have ε_1 larger than each slope $\varepsilon_{j_m}^k$. But, first, we can easily see that ε_1 can not lie in between two slopes $\varepsilon_{j_m}^l$ for any $l = 1, 2, \dots, k$. Because, if it happened, then we would have from Lemma 4.7 that

$$b_{i_l} + \varepsilon_{j_{m-1}}^l > 0$$
 and $b_{i_l} + \varepsilon_{j_m}^l < 0$,

which is a contradiction. To finish the proof we show inductively for $l = 1, 2, \dots, k$ that it is impossible that

$$\varepsilon_{j_1}^l < \varepsilon_{j_2}^l < \dots < \varepsilon_{j_h}^l < \varepsilon_1.$$

Before we start the induction, we define

$$b_{j_0} = \min\{b_j \mid (a_j, b_j) \notin S_{(\bar{1})}(\varepsilon_1)\}.$$

When l = 1, if ε_1 is larger than every other slope $\varepsilon_{j_m}^1$, then using Lemma 4.7, we know b_{i_1} and b_{j_0} are the largest and the smallest for pairs in the line that connects (a_{j_0}, b_{j_0}) to (a_{i_1}, b_{i_1}) . Therefore, by Lemma 4.2,

$$R_{1i_11i_1} = b_1b_{i_1} + a_1 + a_{i_1} \ge 0, \quad R_{i_1j_0i_1j_0} = b_{i_1}b_{j_0} + a_{i_1} + a_{j_0} \le 0,$$

which implies $0 \le R_{1i_11i_1} - R_{i_1i_0i_1i_0} = (b_1 - b_{j_0})(b_{i_1} + \frac{a_1 - a_{j_0}}{b_1 - b_{j_0}})$ and hence

$$b_{i_1} + \frac{a_1 - a_{j_0}}{b_1 - b_{j_0}} \le 0.$$

On the other hand, from Lemma 4.7, we have

$$0 < b_{i_1} + \varepsilon_{j_m}^1 < b_{i_1} + \frac{a_1 - a_{j_0}}{b_1 - b_{j_0}}$$

which is a contradiction. Here we used the fact that $\varepsilon_1 < \frac{a_1 - a_{j_0}}{b_1 - b_{j_0}}$. So ε_1 can only be smaller than every other slope $\varepsilon_{j_m}^1$ and

(4.44)
$$\varepsilon_1 < \frac{a_{i_1} - a_{j_0}}{b_{i_1} - b_{j_0}} \text{ and } b_{i_1} < b_{j_0}$$

Similarly, from Lemma 4.2,

$$R_{i_1i_2i_1i_2} \ge 0$$
 and $R_{i_2j_0i_2j_0} \le 0$,

which implies $0 \le R_{i_1 i_2 i_1 i_2} - R_{i_2 j_0 i_2 j_0} = (b_{i_1} - b_{j_0})(b_{i_2} + \frac{a_{i_1} - a_{j_0}}{b_{i_1} - b_{j_0}})$ and $a_{i_1} - a_{i_2}$

$$b_{i_2} + \frac{a_{i_1} - a_{j_0}}{b_{i_1} - b_{j_0}} \le 0.$$

If otherwise ε_1 is larger than every slope $\varepsilon_{j_m}^2$, then, from Lemma 4.7,

$$0 < b_{i_2} + \varepsilon_{j_m}^2 < b_{i_2} + \varepsilon_1 < b_{i_2} + \frac{a_{i_1} - a_{j_0}}{b_{i_1} - b_{j_0}},$$

which is a contradiction and implies

(4.45)
$$\varepsilon_1 < \frac{a_{i_2} - a_{j_0}}{b_{i_2} - b_{j_0}} \text{ and } b_{i_2} < b_{j_0}$$

By induction, we can prove ε_1 cannot be larger than every slope $\varepsilon_{j_m}^k$. Thus the proof is finished.

4.3 Reducible cases

In this subsection we want to show that, if the assumptions in Theorem 4.3 for two commuting isoparametric tensors that satisfy (4.30) are not true, then the underlined Riemannain manifold has to be reducible. The first cases are when r < s, that is, when T_2 restricted to some eigensapce V_{b_i} has two distinct eigenvalues. The other cases are when the set $S_{(\bar{1})}(\varepsilon_1)$ has two distinct pairs.

Let us deal with the first cases. In the light of Lemma A.3, we may assume that for some $\bar{k} = \bar{1}, \bar{2}, \cdots, \bar{r}$

(4.46)
$$[\bar{k}] = (k_1) \bigcup (k_2) \text{ and } a_{k_1} < a_{k_2}$$

Lemma 4.8. Suppose that T_1 and T_2 are two commuting isoparametric tensors on a Riemannian manifold (M^n, g) that satisfy the condition (4.30). And suppose that (4.46) holds for some $\bar{k} = \bar{1}, \bar{2}, \dots, \bar{r}$. Then any set $S_{(k_1)}(\varepsilon)$ has at most two pairs.

Proof. We assume otherwise that the $S_{(k_1)}(\varepsilon)$ has at least three distinct pairs for some ε , say,

$$S_{(k_1)}(\varepsilon) = \{(a_{k_1}, b_{k_1}), (a_{j_1}, b_{j_1}), \cdots, (a_{j_t}, b_{j_t})\}$$

for some $t \ge 2$, where $b_{j_1} < b_{j_2} < \cdots < b_{j_t}$. Our argument is again to show that there is no way to compare b_{k_1} with the rest $b_{j_1}, b_{j_2}, \cdots, b_{j_t}$.

First we want to show that b_{k_1} cannot be in between the rest. Assume otherwise that for some $l = 1, 2, \dots, t-1$

$$b_{j_l} < b_{k_1} < b_{j_{l+1}}.$$

From Lemma 4.2, we know that

$$b_{j_l}b_{k_1} + a_{j_l} + a_{k_1} \ge 0$$
 and $b_{j_{l+1}}b_{k_1} + a_{j_{l+1}} + a_{k_1} \ge 0$.

And, from Lemma A.3, we know that $b_{k_1}^2 + a_{k_1} + a_{k_2} = 0$. Hence, on one hand,

$$0 \leq b_{j_{l+1}}b_{k_1} + a_{j_{l+1}} + a_{k_1} - (b_{k_1}^2 + a_{k_1} + a_{k_2})$$

= $(b_{j_{l+1}} - b_{k_1})(b_{k_1} + \frac{a_{j_{l+1}} - a_{k_2}}{b_{j_{l+1}} - b_{k_2}}) = (b_{j_{l+1}} - b_{k_1})(b_{\bar{k}} + \varepsilon + \frac{a_{k_1} - a_{k_2}}{b_{j_{l+1}} - b_{\bar{k}_2}}),$

which implies

$$b_{\bar{k}} + \varepsilon > b_{\bar{k}} + \varepsilon + \frac{a_{k_1} - a_{k_2}}{b_{j_{l+1}} - b_{\bar{k}}} \ge 0.$$

On the other hand,

$$0 \le b_{j_l}b_{k_1} + a_{j_l} + a_{k_1} - (b_{k_1}^2 + a_{k_1} + a_{k_2}) = (b_{j_l} - b_{k_1})(b_{k_1} + \frac{a_{j_l} - a_{k_2}}{b_{j_l} - b_{k_2}}),$$

which implies

$$b_{\bar{k}} + \varepsilon < b_{\bar{k}} + \varepsilon + \frac{a_{k_1} - a_{k_2}}{b_{j_l} - b_{\bar{k}}} \le 0,$$

which is a contradiction.

Next we want to show that b_{k_1} cannot be smaller than all the rest. Assume otherwise

$$b_{k_1} < b_{j_1} < b_{j_2} < \dots < b_{j_t}.$$

From Lemma 4.3, we know that $b_{\bar{k}} + \varepsilon < 0$. But, on the other hand, applying Lemma 4.2, we know that

$$0 \le b_{k_1}b_{j_1} + a_{k_1} + a_{j_1} - (b_{k_1}^2 + a_{k_1} + a_{k_2}) = (b_{j_1} - b_{k_1})(b_{k_1} + \frac{a_{j_1} - a_{k_2}}{b_{j_1} - b_{k_2}}),$$

which implies

$$b_{\bar{k}} + \varepsilon > b_{\bar{k}} + \varepsilon + \frac{a_{k_1} - a_{k_2}}{b_{j_1} - b_{\bar{k}}} \ge 0,$$

which is a contradiction. One may find similarly $b_{\bar{k}}$ cannot be larger than the rest. Thus the proof is complete.

Now we are ready to solve the cases when s > r.

Theorem 4.4. Suppose that T_1 and T_2 are two commuting isoparametric tensors on a Riemannian manifold (M^n, g) that satisfy the condition (4.30). And suppose that there exists an eigenspace $V_{b_{\bar{k}}}$ of T_1 such that $T_2|_{V_{b_{\bar{k}}}}$ has two distinct eigenvalues $a_{k_1} < a_{k_2}$. Then

$$(4.47) b_{\bar{k}}^2 + 2a_{k_1} < 0$$

and the Riemannian manifold (M^n, g) is locally reducible, that is, $(M^n, g) = (M_1, g_1) \times (M_2, g_2)$ locally. Moreover

$$T_1|_{TM_1} = b_{\bar{k}}g_1, \ T_2|_{TM_1} = a_{k_1}g_1 \ and \ T_2|_{TM_2} = -b_{\bar{k}}T_1|_{TM_2} - a_{k_1}g_2.$$

Proof. In the light of Lemma 4.8 we know each set $\hat{S}_{(k_1)}(\varepsilon)$ has at most two pairs, where $[\bar{k}] = (k_1) \cup (k_2)$. Then, from Lemma 4.1, we know

$$R_{ijij} = b_{\bar{k}}b_j + a_{k_1} + a_j = 0$$
 for all $i \in (k_1)$ and $j \notin (k_1)$

Therefore, for $j \notin [\bar{k}]$, we calculate from

$$0 = b_{\bar{k}}b_j + a_{k_1} + a_j - (b_{\bar{k}}^2 + a_{k_1} + a_{k_2}) = (b_j - b_{\bar{k}})(b_{\bar{k}} + \frac{a_j - a_{k_2}}{b_j - b_{\bar{k}}}).$$

that

$$\frac{a_j - a_{k_2}}{b_j - b_{\bar{k}}} = -b_{\bar{k}}.$$

Thus each pair (a_j, b_j) for any $j \notin (k_1)$ falls in $S_{(k_2)}(-b_{\bar{k}})$ and satisfies

$$a_j = -b_{\bar{k}}b_j - a_{k_1}.$$

To finish the proof we only need to verify that both the distribution $V_{a_{k_1}} = span\{E_i | i \in (k_1)\}$ and its orthogonal compliment $V^{\perp} = span\{E_i | i \notin (k_1)\}$ are integrable and parallel. According to [19], that amounts to show that $\omega_{ij} = 0$ for all $i \in (k_1)$ and $j \notin (k_1)$. We first verify that, for $i \in (k_1)$ and $j \in (k_2)$, $\omega_{ij} = 0$. This is because, using (A.83), one only needs to see that $\hat{T}_{ij,l} = 0$ when $l \in [\bar{k}] = (k_1) \cup (k_2)$ from the second equation in (A.81). We then claim $\hat{T}_{ij,m} = 0$ for all $i \in (k_1), j \notin [\bar{k}], m = 1, 2, \cdots, n$. We are proving this claim by repeatedly using the Cartan identity (A.75) and (4.31) in Lemma 4.1

(4.48)
$$0 = R_{ijij} = \sum_{m \notin [\bar{k}], [j]} \frac{2T_{ij,m}^2}{(b_m - b_{\bar{k}})(b_m - b_j)}, \quad when \ i \in (k_1) \subset [\bar{k}], \ j \notin [\bar{k}].$$

First, let $j \in [\overline{k+1}]$ in (4.48), and we note that

$$(b_m - b_{\bar{k}})(b_m - b_j) > 0$$
, when $m \notin [\bar{k}], [\overline{k+1}],$

which forces

(4.49)
$$T_{ij,m} = 0, \text{ when } i \in (k_1), \ j \in [k+1], \ 1 \le m \le n.$$

Then let $j \in [\overline{k+2}]$ in (4.48) and obtain

$$0 = \sum_{m \notin [\bar{k}], [\bar{k+2}]} \frac{2T_{ij,m}^2}{(b_m - b_{\bar{k}})(b_m - b_{\overline{k+2}})} = \sum_{m \notin [\bar{k}], [\bar{k+1}], [\bar{k+2}]} \frac{2T_{ij,m}^2}{(b_m - b_{\bar{k}})(b_m - b_{\overline{k+2}})}$$

due to (4.49), which in turn improves (4.49) into

$$T_{ij,m} = 0$$
, when $i \in (k_1)$, $j \in [\overline{k+1}] \cup [\overline{k+2}]$, $1 \le m \le n$.

Repeatedly extending in both directions we can prove the claim $T_{ij,m} = 0$ for all $i \in (k_1)$, $j \notin [\bar{k}]$ and all $1 \le m \le n$. Therefore, from (A.74), $\omega_{ij} = 0$ for all $i \in (k_1)$ and $j \notin [\bar{k}]$. So the proof is complete. The rest cases are when r = s but $S_{(\bar{1})}(\varepsilon_1)$ has two pairs. Let

(4.50)
$$S_{(\bar{1})}(\varepsilon_1) = \{(a_{\bar{1}}, b_{\bar{1}}), (a_{\bar{k}}, b_{\bar{k}})\}.$$

The patterns of correlations among all the pairs are exactly the same as what they are in the cases of Theorem 4.4, that is, every $S_{(\bar{k})}(\varepsilon)$ has at most two pairs and therefore all pairs except $(a_{\bar{k}}, b_{\bar{k}})$ lie in one line.

Theorem 4.5. Suppose that T_1 and T_2 are two commuting isoparametric tensors on a Riemannian manifold (M^n, g) and satisfy the relation (4.30). And suppose that r = s > 2 and (4.50) holds. Then

$$(4.51) b_{\bar{k}}^2 + 2a_{\bar{k}} < 0$$

and the Riemannian manifold (M^n, g) is locally reducible, that is, $(M^n, g) = (M_1, g_1) \times (M_2, g_2)$ locally. Moreover

$$T_1|_{TM_1} = b_{\bar{k}}g_1, \ T_2|_{TM_1} = a_{\bar{k}}g_1, \ and \ T_2|_{TM_2} = -b_{\bar{k}}T_1|_{TM_2} - a_{\bar{k}}g_2.$$

Proof. We claim that the set $S_{(\bar{k})}(\varepsilon)$ has at most two pairs. One only needs to prove this claim for $\varepsilon \neq \varepsilon_1$. Assume otherwise $S_{(\bar{k})}(\varepsilon)$ has at least three pairs, say,

$$S_{(\bar{k})}(\varepsilon) = \{(a_{\bar{k}}, b_{\bar{k}}), (a_{i_1}, b_{i_1}), \cdots, (a_{i_h}, b_{i_h})\}$$

and $b_{i_1} < b_{i_2} < \cdots < b_{i_h}$, for some $\varepsilon \neq \varepsilon_1$ and $h \ge 2$.

Let $d_j = a_j - \varepsilon_1 b_j$ for $j = 1, 2, \dots, n$. Then it is clear that $d_j = d_1$ when $j \in [\bar{1}] \cup [\bar{k}]$. On the other hand, if $j \notin [\bar{1}] \cup [\bar{k}]$, then

$$d_1 - d_j = (b_1 - b_j)(-\varepsilon_1 + \frac{a_1 - a_j}{b_1 - b_j}) < 0.$$

Because ε_1 is the smallest slope among all lines passing through (a_1, b_1) . Therefore

(4.52)
$$d_1 = \min\{d_1, d_2, \cdots, d_n\}.$$

Now, for any $i \in [\bar{k}]$ and $j \in [i_1] \cup [i_2] \cdots \cup [i_h]$, we have

(4.53)
$$0 < d_j - d_i = (b_j - b_{\bar{k}})(\varepsilon - \varepsilon_1)$$

Let us assume $\varepsilon > \varepsilon_1$ first, which immediately implies $b_{\bar{k}} < b_{i_1} < \cdots < b_{i_h}$ and hence $b_{\bar{k}} + \varepsilon < 0$ from Lemma 4.3. We then calculate

$$0 > b_{\bar{k}} + \varepsilon > b_{\bar{k}} + \varepsilon_1 = b_{\bar{k}} + \frac{a_{\bar{k}} - a_{\bar{1}}}{b_{\bar{k}} - b_{\bar{1}}} = \frac{b_{\bar{k}}^2 + 2a_{\bar{k}}}{b_{\bar{k}} - b_{\bar{1}}}$$

where we used

$$b_{\bar{1}}b_{\bar{k}} + a_{\bar{1}} + a_{\bar{k}} = 0$$

from Lemma 4.1. Therefore $b_{\bar{k}}^2 + 2a_{\bar{k}} < 0$. Meanwhile, applying Lemma 4.2 to $S_{(\bar{k})}(\varepsilon)$, we have,

$$b_{\bar{k}}b_{i_1} + a_{\bar{k}} + a_{i_1} \ge 0.$$

Then

$$0 < b_{\bar{k}}b_{i_1} + a_{\bar{k}} + a_{i_1} - (b_{\bar{k}}^2 + 2a_{\bar{k}}) = (b_{i_1} - b_{\bar{k}})(b_{\bar{k}} + \varepsilon),$$

which implies that $b_{\bar{k}} + \varepsilon > 0$. This is a contradiction and concludes that $\varepsilon < \varepsilon_1$.

From (4.53), when $\varepsilon < \varepsilon_1$, we have $b_{i_1} < b_{i_2} < \cdots < b_{i_h} < b_{\bar{k}}$ and hence $b_{\bar{k}} + \varepsilon > 0$ from Lemma 4.3. Similarly, applying Lemma 4.2 to $S_{(\bar{k})}(\varepsilon)$ again, we have

$$b_{\bar{k}}b_{i_1} + a_{\bar{k}} + a_{i_1} \le 0.$$

Then

$$0 \ge b_{\bar{k}}b_{i_1} + a_{\bar{k}} + a_{i_1} - (b_{\bar{k}}b_{\bar{1}} + a_{\bar{k}} + a_{\bar{1}}) = (b_{i_1} - b_{\bar{1}})(b_{\bar{k}} + \frac{a_{i_1} - a_1}{b_{i_1} - b_1}),$$

which implies that $b_{\bar{k}} + \varepsilon_1 \leq 0$ and therefore $b_{\bar{k}} + \varepsilon < b_{\bar{k}} + \varepsilon_1 \leq 0$. This is a contradiction again and concludes that no $S_{(\bar{k})}(\varepsilon)$ has more than two pairs.

Consequently, as in the proof of Theorem 4.4, we know $S_{(\bar{1})}(-b_{\bar{k}})$ contains all pairs except $(a_{\bar{k}}, b_{\bar{k}})$ and $a_j = -b_{\bar{k}}b_j - a_{\bar{k}}$ for $j \notin [\bar{k}]$. By the minimality of ε_1 , we find that $b_{\bar{k}} + \varepsilon_1 < 0$, which implies

$$0 > b_{\bar{k}} + \varepsilon_1 = b_{\bar{k}} + \frac{a_{\bar{k}} - a_1}{b_{\bar{k}} - b_1} = \frac{b_{\bar{k}}^2 + 2a_{\bar{k}}}{b_{\bar{k}} - b_1}$$

and therefore

$$b_{\bar{k}}^2 + 2a_{\bar{k}} < 0.$$

Finally, by a bootstrapping argument similar to that in the proof of Theorem 4.4, repeatedly using the Cartan identity (A.75) and (4.31) in Lemma 4.1, we can show that

$$T_{ij,m} = 0, \ when \ i \in [k], \ 1 \le j, m \le n,$$

which implies that

(4.54)
$$\omega_{ij} = 0, \quad when \quad i \in [\bar{k}], \quad j \notin [\bar{k}]$$

Thus both the distribution $V_{b_{\bar{k}}}$ and its orthogonal complement are integrable and parallel according to [19]. The proof is completed

5 Laguerre invariants of hypersurfaces in \mathbb{R}^{n+1}

In this section we first recall Laguerre invariants of hypersurfaces in \mathbb{R}^{n+1} . For the details we refer readers to [23, 24]. We then present the characterization of Dupin hypersurfaces with constant Laguerre curvatures in terms of Laguerre invariants.

The group of Laguerre transformations is not as well known as the group of Möbius transformations. It is the other important subgroup of the group of Lie sphere transformations. Let us first introduce the group of Lie sphere transformations (cf. [3]). It starts with the space of all oriented hyperspheres in \mathbb{R}^{n+1} , which are, points, oriented n-spheres, and oriented hyperplanes in \mathbb{R}^{n+1} . One may use the so-called Lie quadric Q_{n+1} to represent the space of all oriented hyperspheres. The Lie quadric is the projectivized light cone C^{n+3} in the Minkowski spacetime \mathbb{R}_2^{n+4} , where the Minkowski spacetime \mathbb{R}_2^{n+4} is the vector space R^{n+4} equipped with the quadratic

$$\langle x, y \rangle = -x_1y_1 + x_2y_2 + \dots + x_{n+3}y_{n+3} - x_{n+4}y_{n+4}$$

and the light cone is given as

$$C^{n+3} = \{ x \in \mathbb{R}^{n+4} | < x, x \ge 0 \}.$$

The group of Lie sphere transformation is the orthogonal group $O(n + 2, 2)/\{\pm 1\}$ of the Minkowski spacetime \mathbb{R}_2^{n+4} . And the group of Laguerre transformations is the isotropy subgroup of $O(n + 2, 2)/\{\pm 1\}$ at $\mathfrak{p} = (1, -1, \vec{0}, 0) \in C^{n+3} \subset \mathbb{R}_2^{n+4}$.

A more geometric way to introduce the group of Lie sphere transformations is to consider the unit tangent bundle $U\mathbb{R}^{n+1}$ over \mathbb{R}^{n+1} , which represents the space of lines on the Lie quadric Q_{n+1} . It is clear that

$$U\mathbb{R}^{n+1} = \mathbb{R}^{n+1} \times \mathbb{S}^n = \{(x,\xi) | x \in \mathbb{R}^{n+1}, \xi \in \mathbb{S}^n\} \subset \mathbb{C}^{n+1}$$

and there is a standard contact structure on $U\mathbb{R}^{n+1}$ defined by the standard contact form

$$\omega = dx \cdot \xi.$$

We then recall that oriented hypershiperes in $U\mathbb{R}^{n+1}$ are the following three types:

- oriented n-sphere $S(p,r) = \{(x,\xi) \in U\mathbb{R}^{n+1} | x p = r\xi\}$ for a point $p \in \mathbb{R}^{n+1}$ and a nonzero real number r
- point sphere $S(p,0) = \{(p,\xi) \ U\mathbb{R}^{n+1} | \xi \in UT_p\mathbb{R}^{n+1}\}$ for a point $p \in \mathbb{R}^{n+1}$, a "sphere" of radius 0,

• oriented hyperplane $P(\xi, \lambda) = \{(x, \xi) \in U\mathbb{R}^{n+1} | x \cdot \xi = \lambda\}$ for a fixed unit vector ξ and a real number λ , a "sphere" of infinite radius.

It turns out that the group of Lie sphere transformations is also the group of diffeomorphisms of $U\mathbb{R}^{n+1}$ that take oriented hyperspheres to oriented hyperspheres and preserve the contact structure ω . Particularly, a Laguerre transformation is a Lie sphere transformation that takes oriented spheres to oriented spheres and takes oriented hyperplanes to oriented hyperplanes.

Let $x : M^n \to \mathbb{R}^{n+1}$ be an oriented hypersurface in \mathbb{R}^{n+1} with non-vanishing principal curvatures. Then the unit normal $\xi : M^n \to \mathbb{S}^n$ is an immersion and x induces a Laguerre surface $f = (x,\xi) : M^n \to U\mathbb{R}^{n+1}$. Let x and \tilde{x} be two oriented hypersurfaces in \mathbb{R}^{n+1} with non-vanishing principal curvatures. We say x and \tilde{x} are Laguerre equivalent, if there is a Laguerre transformation $\phi : U\mathbb{R}^{n+1} \to U\mathbb{R}^{n+1}$ such that $(\tilde{x}, \tilde{\xi}) = \phi \circ (x, \xi)$.

Let $x: M^n \to \mathbb{R}^{n+1}$ be an umbilical free hypersurface with non-vanishing principal curvatures. Let $\{e_1, e_2, \cdots, e_n\}$ be the orthonormal basis for TM^n with respect to $dx \cdot dx$, consisting of unit principal vectors. We write the structure equation of $x: M^n \to \mathbb{R}^{n+1}$ by

$$e_j(e_i(x)) = \sum_k \Gamma_{ij}^k e_k(x) + \lambda_i \delta_{ij}\xi; \quad e_i(\xi) = -\lambda_i e_i(x), \quad 1 \le i, j, k \le n,$$

where $\lambda_i \neq 0$ is the principal curvature corresponding to e_i . Let

$$R_i = \frac{1}{\lambda_i}$$
 and $R = \frac{R_1 + R_2 + \dots + R_n}{n}$

be the curvature radius and mean curvature radius of x. As in [23, 24], we call

(5.55)
$$Y = \rho(x \cdot \xi, -x \cdot \xi, \xi, 1) : M^n \to C^{n+3} \subset \mathbb{R}_2^{n+4}$$

the Laguerre position vector of the hypersurface x, where $\rho = \sqrt{\sum_{i=1}^{n} (R_i - R)^2}$. It is important to realize the following covariant property.

Theorem 5.1. ([24]) Let x and \tilde{x} be two umbilical free oriented hypersurfaces in \mathbb{R}^{n+1} with non-vanishing principal curvatures. Then x and \tilde{x} are Laguerre equivalent if and only if their Laguerre positions Y and \tilde{Y} are the same up to a Laguerre transformation.

Let Y the Laguerre position vector of a hypersurface $x : M \to \mathbb{R}^{n+1}$. We want to build a natural orthogonal moving frame along the surface Y in \mathbb{R}^{n+4}_2 . Analogous to the cases of Möbius geometry,

$$g = \langle dY, dY \rangle$$

is then called the Laguerre metric and the null normal vector

$$N = \frac{1}{n}\Delta Y + \frac{1}{2n^2} < \Delta Y, \Delta Y > Y$$

to the surface Y in \mathbb{R}^{n+4}_2 that is paired with the tautological null normal Y such that

$$\langle Y, N \rangle = -1,$$

where the Laplacian operator Δ is that of the Laguerre metric g. In contrast to the cases of Möbius geometry, we have a constant null normal vector \mathbf{p} and a canonical null normal vector

$$\eta = (\frac{1}{2}(1+|x|^2), \frac{1}{2}(1-|x|^2), x, 0) + R(x \cdot \xi, -x \cdot \xi, \xi, 1)$$

such that

$$<\eta,\mathfrak{p}>=-1 \text{ and } <\eta,Y>=<\eta,N>=<\mathfrak{p},Y>=<\mathfrak{p},N>=0.$$

Therefore, if let $\{E_1, E_2, \dots, E_n\}$ be an orthonormal basis for $g = \langle dY, dY \rangle$ that are tangent to Y with dual basis $\{\omega_1, \omega_2, \dots, \omega_n\}$, then, as given in [23, 24], we have the following orthogonal moving frame along Y in \mathbb{R}^{n+4}_2

$$\{Y, N, E_1, E_2, \cdots, E_n, \eta, \mathfrak{p}\}$$

We next recall from [23, 24] the following structure equations:

(5.56)
$$E_i(N) = \sum_j L_{ij} E_j + C_i \mathfrak{p};$$

(5.57)
$$E_j(E_i) = L_{ij}Y + \delta_{ij}N + \sum_k \Gamma_{ij}^k E_k + B_{ij}\mathfrak{p};$$

(5.58)
$$E_i(\eta) = -C_i Y + \sum_j B_{ij} E_j.$$

Analogous to the cases of Möbius geometry, besides the Laguerre metric $g = \langle dY, dY \rangle$, we have the following Laguerre invariants:

(5.59)
$$\mathbb{B} = \sum_{ij} B_{ij}\omega_i \otimes \omega_j, \quad \mathbb{L} = \sum_{ij} L_{ij}\omega_i \otimes \omega_j, \text{ and } \mathbb{C} = \sum_i C_i\omega_i,$$

where \mathbb{B} is called the Laguerre second fundamental form, \mathbb{L} is called the Laguerre tensor, and \mathbb{C} is called the Laguerre form. In [24], the integrability conditions for $\{\mathbb{L}, \mathbb{B}, \mathbb{C}\}$ are identified as

$$(5.60) L_{ij,k} = L_{ik,j};$$

(5.61)
$$C_{i,j} - C_{j,i} = \sum_{k} (B_{ik} L_{kj} - B_{jk} L_{ki});$$

$$(5.62) B_{ij,k} - B_{ik,j} = C_j \delta_{ik} - C_k \delta_{ij};$$

(5.63)
$$R_{ijkl} = L_{jk}\delta_{il} + L_{il}\delta_{jk} - L_{ik}\delta_{jl} - L_{jl}\delta_{ik};$$

(5.64)
$$\sum_{ij} B_{ij}^2 = 1, \sum_i B_{ii} = 0, \sum_i B_{ij,i} = (n-1)C_j;.$$

where R_{ijkl} is the curvature tensor of g. More importantly, in [24], it was shown that, up to a Laguerre transformation, an umbilical free oriented hypersurfaces in \mathbb{R}^{n+1} with non-vanishing principal curvatures is completely determined by the Laguerre invariants $\{g, \mathbb{B}\}$ when n > 2 and by the Laguerre invariants $\{g, \mathbb{B}, \mathbb{L}\}$ when n = 2.

Finally we recall from [23, 24] how $\{g, \mathbb{B}, \mathbb{C}\}$ can be calculated in terms of the geometry of x in \mathbb{R}^{n+1} :

(5.65)
$$g = \sqrt{\sum_{i} (R_i - R)^2} III, \qquad B_{ij} = \rho^{-1} (R_i - R) \delta_{ij},$$
$$C_i = -\rho^{-2} \{ \tilde{E}_i(R) + \tilde{E}_i(\log \rho) (R_i - R) \},$$

here $\dot{E}_i = R_i e_i$ and $\{e_i\}$ is an orthonormal frame with respect to the metric $dx \cdot dx$, consisting of unit principal vectors.

Definition 5.1. Let $x : M^n \to \mathbb{R}^{n+1}$ be an immersed hypersurface with non-vanishing principal curvatures, and the principal curvature radius $\{R_1 = \frac{1}{\lambda_1}, R_2 = \frac{1}{\lambda_2}, \cdots, R_r = \frac{1}{\lambda_r}\}$. For any three principal curvature radius $\lambda_i, \lambda_j, \lambda_s$, We define the Laguerre curvature of x

$$\Upsilon_{ijs} = \frac{R_i - R_j}{R_i - R_s}.$$

The eigenvalues of \mathbb{B} are called the Laguerre principal curvatures of x. Then, from (5.65), the Laguerre principal curvature $b_i = \rho^{-1}(R_i - R)$. Hence

(5.66)
$$\Upsilon_{ijs} = \frac{R_i - R_j}{R_i - R_s} = \frac{b_i - b_j}{b_i - b_s},$$

which implies that the Laguerre curvatures Υ_{ijs} are Laguerre invariants.

We now are ready to give the characterization of Dupin hypersurfaces with constant Laguerre curvatures in terms of Laguerre invariants.

Proposition 5.1. Let $x : M^n \to \mathbb{R}^{n+1}$ be an oriented hypersurface with $r(\geq 3)$ distinct non-vanishing principal curvatures. Then x is a Dupin hypersurface with constant Laguerre curvatures if and only if its Laguerre form vanishes and all Laguerre principal curvatures are constant.

Proof. First of all it is easily seen that, with a proof that is almost identical to the proof of Proposition 2.1, the Laguerre curvatures Υ_{ijs} are constant if and only if the Laguerre principal curvatures are constant.

Secondly, from (5.65), we have

(5.67)

$$C_{i} = -\rho^{-2} \{ \tilde{E}_{i}(r) + \tilde{E}_{i}(\rho)\rho^{-1}(r_{i} - r) \} = -\rho^{-2} \{ \tilde{E}_{i}(r) + \tilde{E}_{i}(\rho)b_{i} \}$$

$$= -\rho^{-2} \{ \tilde{E}_{i}(r) + \tilde{E}_{i}(\rho b_{i}) - \rho^{-1}\tilde{E}_{i}(b_{i}) \} = -\rho^{-2} \{ \tilde{E}_{i}(r_{i}) - \rho^{-1}\tilde{E}_{i}(b_{i}) \}$$

$$= -\rho^{-2} \{ -\frac{\tilde{E}_{i}(\lambda_{i})}{\lambda_{i}^{2}} - \rho^{-1}\tilde{E}_{i}(b_{i}) \}.$$

Therefore the proof of Proposition 5.1 can easily be completed.

In [41], an immersed hypersurface is said to be a Laguerre isoparametric hypersurface if its Laguerre form vanishes and its Laguerre Principal curvatures are all constant. And Song [41] has classified the Laguerre isoparametric hypersurfaces with two distinct principal curvatures. In these terminology, Theorem 5.1 then says that, a hypersurface in \mathbb{R}^{n+1} is a Dupin surface with constant Laguerre curvatures if and only if it is a Laguerre isoparametric hypersurface. We would like to mention that Proposition 5.1 recently has also been observed in [37].

6 Dupin Hypersurfaces with constant Laguerre curvatures

In this section we will present the proof of Theorem 1.2. We will first study examples of Dupin hypersyrfaces with constant Laguerre curvatures. Then we will proceed similar to the Möbius cases to study the isoparametric tensors. This time the proof will be significantly simpler than that in Möbius cases because of (5.63) in contrast to (2.6).

6.1 Examples

Cyclide of Dupin. For any integer k with $1 \le k \le n-1$, let

$$\mathbb{H}^{n-k} = \{ (v, w) \in \mathbb{R}^{n-k+1} | |v|^2 - w^2 = -1 \text{ and } w > 0 \}$$

be the hyperboloid in the Minkowski space \mathbb{R}_1^{n-k+1} . We then consider the hypersurface

(6.68)
$$x(u,v,w) = \left(\frac{u}{w}(1+w), \frac{v}{w}\right) : \mathbb{S}^k \times \mathbb{H}^{n-k} \to \mathbb{R}^{n+1},$$

where $u: \mathbb{S}^k \to \mathbb{R}^{k+1}$ is the standard embedding of round sphere.

As was verified in [23], the hypersurface given in (6.68) is a Laguerre isoparametric hypersurface with two distinct Laguerre principal curvatures and, in fact, is Lie equivalent to the classical cyclide of Dupin of characteristic (k, n - k).

Flat Laguerre isoparametric hypersurface. For any positive integers m_1, \dots, m_s with $m_1 + \dots + m_s = n$ and any non-zero constants $\kappa_1, \dots, \kappa_s$, we consider the hypersurface

(6.69)
$$x(u_1, u_2, \cdots, u_s) = \left(\varphi, \left((1 + \varphi \kappa_1)u_1, \cdots, (1 + \varphi \kappa_s)u_s\right)\right) : \mathbb{R}^n \to \mathbb{R}^{n+1},$$

where

$$\varphi = \frac{\kappa_1 |u_1|^2 + \dots + \kappa_s |u_s|^2}{\kappa_1^2 |u_1|^2 + \dots + \kappa_s^2 |u_s|^2 + 1}$$

for $(u_1, u_2, \cdots, u_s) \in \mathbb{R}^{m_1} \times \mathbb{R}^{m_2} \times \cdots \mathbb{R}^{m_s} = \mathbb{R}^n$.

Again, as was shown in [23], the hypersurface given in (6.69) is a Laguerre isoparametric hypersurface with s distinct Laguerre principal curvatures and, moreover, its Laguerre metric $g = \langle dY, dY \rangle$ is flat, that is, $R_{ijij}[g] = 0$. Hence we call such hypersurfaces flat Laguerre isoparametric hypersurfaces.

6.2 Proof of Theorem 1.2

The proof of Theorem 1.2 similar to that of Möbius cases uses isoparametric tensors. From the integrability conditions for the Laguerre invariants $\mathbb{L}, \mathbb{B}, \mathbb{C}$ and the Laguerre metric g it is clear that the Laguerre second fundamental form \mathbb{B} is an isoparametric tensor on a Dupin hypersurface with constant Laguerre curvatures in the light of Proposition 5.1. For the definition and basic properties for isoparametric tensors readers are referred to Appendix A. First we want to show that the Laguerre symmetric 2-tensor \mathbb{L} is also an isoparametric tensor on a Dupin hypersurface with constant Laguerre curvatures. From (5.60), it suffices to show that the eigenvalues of \mathbb{L} are all constant, according to Definition A.1.

Lemma 6.1. Let $x : M^n \to \mathbb{R}^{n+1}$ be a Laguerre isoparametric hypersurface. Then the eigenvalues of the Laguerre tensor \mathbb{L} are all constant.

Proof. This lemma in the cases when x has more than 2 distinct principal curvatures follows from Remark 4.1 after the proof of Theorem 4.2. Next we consider r = 2. And

$$(L_{ij}) = diag(\tau_1, \tau_2, \cdots, \tau_n) \text{ and } (B_{ij}) = diag(\underbrace{b_1, \cdots, b_1}_{s}, \underbrace{b_2, \cdots, b_2}_{n-s})$$

Since \mathbb{B} is an isoparametric tensor with two distinct eigenvalues, from Proposition A.1 and Proposition A.2, we know that

$$R_{ijij} = 0, \ 1 \le i \le s, \ s+1 \le j \le n.$$

On the other hand, from (5.63) we know $R_{ijij} = -\tau_i - \tau_j$ and then

$$(L_{ij}) = diag(\tau_1, \tau_2, \cdots, \tau_n) = diag(\underbrace{\tau, \cdots, \tau}_k, \underbrace{-\tau, \cdots, -\tau}_{n-k}).$$

Therefore

$$E_k(\tau) = E_k(\tau_i) = L_{ii,k} = L_{ik,i} = \frac{2\tau}{b_1 - b_2} B_{ik,i} = 0$$

for $i \in \{1, 2, \dots, s\}$ if $k \in \{s + 1, s + 2, \dots, n\}$ and

$$E_k(\tau) = -E_k(\tau_i) = -L_{ii,k} = -L_{ik,i} = \frac{2\tau}{b_2 - b_1} B_{ik,i} = 0$$

for $i \in \{s + 1, s + 2, \dots, n\}$ and $i \neq k$ if $k \in \{1, 2, \dots, s\}$, in the light of (A.74). Thus τ is constant.

Now we know, under the assumptions of Lemma 6.1, \mathbb{B} and \mathbb{L} are commuting isoparametric tensors. We may choose a local orthonormal frame so that

$$(B_{ij}) = diag(b_1, \cdots, b_n)$$

$$(L_{ij}) = diag(\tau_1, \cdots, \tau_n) = diag(\tau_{\tilde{1}}, \cdots, \tau_{\tilde{1}}, \tau_{\tilde{2}}, \cdots, \tau_{\tilde{2}}, \cdots, b_{\tilde{t}}, \cdots, \tau_{\tilde{t}}),$$

where t denotes the number of the distinct eigenvalues of \mathbb{L} . We then define the index set

$$\{i\} = \{k \in \{1, 2, \cdots, n\} | \tau_k = \tau_i\}$$

according to the repeated eigenvalues of Laguerre tensor \mathbb{L} in this section. The main observation that leads to the proof of Theorem 1.2 is the following:

Theorem 6.1. Let $x : M^n \to \mathbb{R}^{n+1}$ be a Laguerre isoparametric hypersurface. Then the Laguerre second fundamental form \mathbb{B} is parallel.

Proof. First, from (5.63) and Cartan identity (A.77), we have

(6.70)
$$\sum_{j \notin \{i\}} \frac{R_{ijij}}{\tau_j - \tau_i} = \sum_{j \notin \{i\}} \frac{-\tau_j - \tau_i}{\tau_j - \tau_i} = \sum_{j \notin \{i\}} \frac{\tau_i^2 - \tau_j^2}{(\tau_j - \tau_i)^2} = 0.$$

Let $\tau_{i_0}^2 = max\{\tau_1^2, \cdots, \tau_n^2\}$. And let $i = i_0$ in equation (6.70), we have

$$\sum_{j \notin (i_0)} \frac{\tau_{i_0}^2 - \tau_j^2}{(\tau_j - \tau_{i_0})^2} = 0,$$

which implies that $\tau_{i_0}^2 - \tau_j^2 = 0$ for $j \in \{1, 2, \cdots, n\}$ and therefore $t \leq 2$.

If t = 2, then

$$(L_{ij}) = diag(\tau_1, \tau_2, \cdots, \tau_n) = diag(\underbrace{\tau, \cdots, \tau}_{s}, \underbrace{-\tau, \cdots, -\tau}_{n-s})$$

for some constant $\tau \neq 0$. Moreover, from Proposition A.1 and Proposition A.2, we know \mathbb{L} is parallel and

(6.71)
$$R_{ijij} = 0, \quad 1 \le i \le s, \quad s+1 \le j \le n.$$

Now we switch the order of $\{E_1, \cdots, E_s\}$ such that

$$(B_{ij})_{1\leq i,j\leq s} = diag(b_1,\cdots,b_s) = diag(b_{\hat{1}},\cdots,b_{\hat{1}},b_{\hat{2}},\cdots,b_{\hat{2}},\cdots,b_{\hat{l}},\cdots,b_{\hat{l}})$$

and $b_1 < b_2 < \cdots < b_l$. Assume that $l \ge 2$. From the Cartan identity (A.77) and (6.71), we have

$$\sum_{1 \le j \le n, b_j \ne b_{\hat{1}}} \frac{R_{1j1j}}{b_j - b_{\tilde{1}}} = \sum_{1 \le j \le s, b_j \ne b_{\tilde{1}}} \frac{-2\tau_{\tilde{1}}}{b_j - b_{\tilde{1}}} = 0,$$

which leads to the contradiction to $\tau \neq 0$. Therefore l = 1 and, in fact, the Laguerre second fundamental form \mathbb{B} has at most two distinct principal curvatures. Thus, from Proposition A.1, \mathbb{B} is parallel.

If otherwise t = 1, then we can assume $L_{ij} = \tau \delta_{ij}$. Let b_1 be the smallest eigenvalues of \mathbb{B} . We then consider the Cartan identity (A.77)

$$\sum_{1 \le j \le n, b_j \ne b_1} \frac{R_{1j1j}}{b_j - b_1} = \sum_{1 \le j \le n, b_j \ne b_1} \frac{-2\tau}{b_j - b_1} = 0$$

and conclude that $\tau = 0$, which implies $R_{ijkl} = 0$ and the Laguerre second fundamental form is parallel using Theorem A.1. So the proof is complete.

Finally Theorem 1.2 follows from Theorem 6.1 and the classification result in [23].

Theorem 6.2. ([23]) Let $x : M^n \to \mathbb{R}^{n+1}$ be an umbilical free hypersurface with nonvanishing principal curvatures. If its Laguerre second fundamental form is parallel, then locally x is Laguerre equivalent to one of the following hypersurfaces,

(1) the Cyclide of Dupin $x: \mathbb{S}^k \times \mathbb{H}^{n-k} \to \mathbb{R}^{n+1}$ given in (6.68)

(2) the flat Laguerre isoparametric hypersurface $x : \mathbb{R}^n \to \mathbb{R}^{n+1}$ given in (6.69).

A Isoparametric tensors

A.1 Definition and properties of isoparametric tensors

A symmetric (0,2) tensor field $T = \sum_{ij} T_{ij}\omega_i \otimes \omega_j$ on a Riemannian manifold (M^n, g) is said to be a Codazzi tensor if it satisfies the Codazzi equation

(A.72)
$$\nabla_X T(Y,Z) = \nabla_Y T(X,Z),$$

for arbitrary vector fields X, Y, Z, where ∇ denotes the Riemannian connection.

Definition A.1. A Codazzi tensor on a Riemannian manifold (M^n, g) is said to be an isoparametric tensor if the eigenvalues are all constant.

Let $T = \sum_{ij} T_{ij}\omega_i \otimes \omega_j$ be an isoparametric tensor on a Riemannian manifold (M^n, g) . We can choose a local orthonormal basis $\{E_1, \dots, E_n\}$ such that

$$(T_{ij}) = diag(b_{\overline{1}}, \cdots, b_{\overline{1}}, b_{\overline{2}}, \cdots, b_{\overline{2}}, \cdots, b_{\overline{r}}, \cdots, b_{\overline{r}}),$$

where $b_{\bar{1}} < \cdots < b_{\bar{r}}$ are constants. Hence

(A.73)
$$(b_i - b_j)\omega_{ij} = \sum_k T_{ij,k}\omega_k,$$

which gives

(A.74)
$$T_{ij,k} = 0, \quad when \quad [i] = [j], \quad or \quad [j] = [k], \quad or \quad [i] = [k],$$
$$\omega_{ij} = \sum_{k} \frac{T_{ij,k}}{b_i - b_j} \omega_k = \sum_{k \notin [i], [j]} \frac{T_{ij,k}}{b_i - b_j} \omega_k, \quad when \quad [i] \neq [j],$$

where $[i] := \{m \in \{1, 2, \cdots, n\} | b_m = b_i\}$. Consequently we have

Proposition A.1. Let (M^n, g) be a Riemannian manifold. If an isoparametric tensor T on (M^n, g) has only two distinct eigenvalues, then T is parallel.

It is well-known that a nontrivial parallel 2-tensor on a Riemannian manifold induces a splitting of Riemannian structure. Namely,

Proposition A.2. ([19, Chap.4]). Let (M^n, g) be a Riemannian manifold. If T is a parallel symmetric (0,2) tensor field on (M^n, g) , then, locally,

$$(M^n,g) = (M_1,g_1) \times (M_2,g_2) \times \cdots \times (M_r,g_r).$$

and there exist r constants $\lambda_1, \cdots, \lambda_r$ such that

$$T = \lambda_1 g_1 \oplus \lambda_2 g_2 \oplus \cdots \oplus \lambda_r g_r.$$

Meanwhile, one may calculate from (A.74), for $[i] \neq [j]$,

$$T_{ij,ij} = \sum_{k \notin [i],[j]} \frac{2T_{ij,k}^2}{b_k - b_i}, \quad T_{ij,ji} = \sum_{k \notin [i],[j]} \frac{2T_{ij,k}^2}{b_k - b_j},$$

and

(A.75)
$$R_{ijij} = \sum_{k \notin [i], [j]} \frac{2T_{ij,k}^2}{(b_k - b_i)(b_k - b_j)},$$

using the Ricci identity. It is important that one immediately sees from (A.75) the following useful fact in this paper.

Lemma A.1. Let $T = \sum_{ij} T_{ij}\omega_i \otimes \omega_j$ be an isoparametric tensor on the Riemannian manifold (M^n, g) . Under the orthonormal basis $\{E_1, \dots, E_n\}$, the coefficients of T have the following form

$$(T_{ij}) = diag(b_{\overline{1}}, \cdots, b_{\overline{1}}, b_{\overline{2}}, \cdots, b_{\overline{2}}, \cdots, b_{\overline{r}}, \cdots, b_{\overline{r}}), \quad b_{\overline{1}} < \cdots < b_{\overline{r}}.$$

Then

(A.76)
$$\begin{aligned} R_{ijij} &\leq 0, \quad when \quad i \in [\bar{1}], \quad j \in [\bar{r}], \\ R_{ijij} &\geq 0, \quad when \quad i \in [\bar{k}], \quad j \in [\bar{k}+1], \quad for \quad \bar{k} = \bar{1}, \cdots, \bar{r-1}, \end{aligned}$$

where $[\overline{i}] = \{m|b_m = b_{\overline{i}}\}.$

As a consequence, for instance, one can obtain the following strong geometric constraints for a Riemannian manifold to have an isoparametric tensor.

Theorem A.1. Let $T = \sum_{ij} T_{ij}\omega_i \otimes \omega_j$ be an isoparametric tensor on a Riemannian manifold (M^n, g) . If (M^n, g) has non-negative sectional curvature (or non-positive sectional curvatures), then T is parallel.

Proof. Let us first present a proof in the cases when (M^n, g) has non-positive sectional curvature. We start with $i \in [\overline{1}]$ and $j \in [\overline{2}]$ in equation (A.75). Notice that

$$(b_k - b_{\bar{1}})(b_k - b_{\bar{2}}) > 0$$
, when $k \notin [\bar{1}] \cup [\bar{2}]$.

From (A.75) we therefore observe that

$$T_{ij,k} = 0, \text{ when } i \in [\bar{1}], j \in [\bar{2}], 1 \le k \le n.$$

We then consider $i \in [\overline{1}]$ and $j \in [\overline{3}]$ in equation (A.75). This time we notice that

$$(b_k - b_{\bar{1}})(b_k - b_{\bar{3}}) > 0$$
, when $k \notin [\bar{1}] \cup [\bar{2}] \cup [\bar{3}]$

and $T_{ij,k} = 0, \ i \in [\overline{1}], \ k \in [\overline{2}]$. From (A.75) again we observe that

$$T_{ij,k} = 0$$
, when $i \in [\bar{1}], j \in [\bar{2}] \cup [\bar{3}], 1 \le k \le n$.

Repeatedly we can prove that $T_{ij,k} = 0$ for $i \in [\bar{1}]$ and $j \in [\bar{2}] \cup [\bar{3}] \cdots \cup [\bar{r}]$. Similarly we can prove $T_{ij,k} = 0$ for all indices, thus T is parallel.

The proof for the cases when (M^n, g) has non-negative curvature uses the same idea but one starts with $i \in [\overline{1}]$ and $j \in [\overline{r}]$ instead.

Next we want to derive the other important fact in this paper, the generalized Cartan identity (cf. [22]) on Riemannian manifolds with an isoparametric tensor T.

(A.77)
$$\sum_{j \notin [i]} \frac{R_{ijij}}{b_j - b_i} = \sum_{j,k \notin [i]} \frac{2T_{ij,k}^2}{(b_k - b_i)(b_k - b_j)(b_i - b_j)} = 0$$

which is easily seen as we note that the matrix, for each i fixed,

$$\left(\frac{2T_{ij,k}^2}{(b_k-b_i)(b_k-b_j)(b_i-b_j)}\right)$$

is antisymmetric for indices j, k.

To show that the generalized Cartan identity is powerful in understanding the curvature structure of Riemannian manifolds with isoparametric tensors, we present a proof of the following interesting result that is believed to be known. Before we state the result we want to recall the Kulkarni-Nomizu product of tensors $T_1 = \sum_{ij} T_{ij} \omega_i \otimes \omega_j$ and $T_2 = \sum_{ij} \hat{T}_{ij} \omega_i \otimes \omega_j$ defined by

$$(T_1 \odot T_2)_{ijkl} = T_{ik}\hat{T}_{jl} + T_{jl}\hat{T}_{ik} - T_{il}\hat{T}_{jk} - T_{jk}\hat{T}_{il}.$$

It its then known that, on a locally conformally flat manifold $(M^n g)$ $(n \ge 3)$,

(A.78)
$$R_{ijkl} = (S \bigodot g)_{ijkl},$$

where $S = \frac{1}{n-2}(Ric - \frac{R}{2(n-1)}g)$ is the so-called Schouten tensor.

Theorem A.2. Let $(M^n, g), (n \ge 3)$ be a locally conformally flat Riemannian manifold. If the eigenvalues of the Schouten tensor S are constant, then either,

(a) (M^n, g) is of constant curvature, or

(b) (M^n, g) is locally reducible, $(M^n, g) = (M_1, g_1) \times (M_2, g_2)$, and there exists constant λ such that

$$\pi_{1*}S = \lambda g_1, \quad \pi_{2*}S = -\lambda g_2.$$

Where $\pi_1: M^n \to M_1, \ \pi_2: M^n \to M_2$ are the standard projections.

Proof. First of all, from the assumption that g is locally conformally flat, we know that the Schouten tensor S is an isoparametric tensor. Hence, under a properly chosen a local orthonormal basis,

$$(S_{ij}) = diag(b_1, b_2, \cdots, b_n) = diag(b_{\overline{1}}, \cdots, b_{\overline{1}}, \cdots, b_{\overline{r}}, \cdots, b_{\overline{r}}),$$

for some constants $b_{\bar{1}} < \cdots < b_{\bar{r}}$. From (A.77) and (A.78), for each *i* fixed, we have

(A.79)
$$0 = \sum_{j \notin [i]} \frac{R_{ijij}}{b_j - b_i} = \sum_{j \notin [i]} \frac{b_j + b_i}{b_j - b_i} = \sum_{j \notin [i]} \frac{b_j^2 - b_i^2}{(b_j - b_i)^2}$$

Now let $b_{i_0}^2 = max\{b_1^2, \dots, b_n^2\}$ and let $i = i_0$ in equation (A.79), we have

$$\sum_{j \notin [i_0]} \frac{b_j^2 - b_{i_0}^2}{(b_j - b_{i_0})^2} = 0,$$

which implies that $b_{i_0}^2 - b_j^2 = 0$ and therefore $r \le 2$. It is clear that (M^n, g) is of constant curvature if r = 1 and the proof is complete in the light of Proposition A.1 and Proposition A.2.

A.2 Commuting isoparametric tensors

Suppose that (M^n, g) is a Riemannian manifold. Then we say that two (0, 2)-tensors are commuting if they are commuting as linear transformations. Given two commuting isoparametric tensors

$$T_1 = \sum_{ij} T_{ij} \omega_i \otimes \omega_j$$
 and $T_2 = \sum_{ij} \hat{T}_{ij} \omega_i \otimes \omega_j$,

we may choose a local orthonormal frame $\{E_1, E_2, \cdots, E_n\}$ so that

(A.80)
$$\begin{cases} (T_{ij}) = diag(b_{\bar{1}}, \cdots, b_{\bar{1}}, b_{\bar{2}}, \cdots, b_{\bar{2}}, \cdots, b_{\bar{r}}, \cdots, b_{\bar{r}}) \\ (\hat{T}_{ij}) = diag(a_1, \cdots, a_n) \end{cases}$$

for constants $b_{\bar{1}} < b_{\bar{2}} < \cdots < b_{\bar{r}}$ and a_1, a_2, \cdots, a_n . Immediately we know

(A.81)
$$T_{ij,k} = 0, \quad when \quad [i] = [j], \quad or \quad [j] = [k],$$
$$\hat{T}_{ij,k} = 0, \quad when \quad a_i = a_j, \quad or \quad a_j = a_k,$$
$$\frac{a_i - a_j}{b_i - b_j} T_{ij,k} = \hat{T}_{ij,k}, \quad when \quad [i] \neq [j].$$

Particularly the third equation in (A.81) and $\hat{T}_{ij,k} = \hat{T}_{ik,j}$ implies

(A.82)
$$\hat{T}_{ij,k} = 0 \text{ for } [j] = [i] \text{ and } k \notin [j],$$

which means more components of the commuting isoparametric tensors are forced to vanish and allows us to focus on the behavior of T_2 restricted to an eigenspace of T_1

$$V_{b_i} = Span\{E_m : m \in [i]\} \text{ or } V_{b_{\bar{k}}} = Span\{E_m : m \in [\bar{k}]\}.$$

We can change the order of the subbasis in the eigenspace $V_{b_{\bar{k}}}$ such that

$$\left(\hat{T}_{ij}\right)|_{i,j\in[\bar{k}]} = diag(\underbrace{a_{k_1},\cdots,a_{k_1}}_{,a_{k_2},\cdots,a_{k_2}}, \underbrace{a_{k_m},\cdots,a_{k_m}}_{,a_{k_m},\cdots,a_{k_m}})$$

for $a_{k_1} < a_{k_2} < \cdots < a_{k_m}$. We then define the index sets

$$(i) := \{l \in [i] | a_l = a_i\} \text{ and } (\bar{k}_i) := \{l \in [\bar{k}] | a_l = a_{k_i}\}.$$

From (A.82), we have the following lemma.

Lemma A.2. Suppose that T_1 and T_2 are two commuting isoparametric tensors as in the above. Then, for some $[\bar{k}]$ fixed, $(i), (j) \in [\bar{k}]$ and $(i) \neq (j)$,

(A.83)
$$(a_i - a_j)\omega_{ij} = \sum_{l \in [\bar{k}]} \hat{T}_{ij,l}\omega_l$$

and

(A.84)
$$R_{ijij} = \sum_{l \in [\bar{k}], l \notin (i), (j)} \frac{2\hat{T}_{ij,l}^2}{(a_i - a_l)(a_j - a_l)}.$$

More importantly we have the generalized Cartan identity for $i \in [\bar{k}]$

(A.85)
$$\sum_{j \in [\bar{k}], j \notin (i)} \frac{R_{ijij}}{a_i - a_j} = \sum_{j, l \in [\bar{k}], j, l \notin (i)} \frac{\hat{T}_{ij,l}^2}{(a_i - a_l)(a_j - a_l)(a_i - a_j)} = 0.$$

One important relation that ties two commuting isoparametric tensors more intimately to the geometry of the underlined manifold and comes naturally from the integrability conditions (2.6) when we are concerned with the Möbius second fundamental form $T_1 = B$ and the Blaschke tensor $T_2 = A$ for a hypersurface in $f: M^n \to \mathbb{R}^{n+1}$ is

(A.86)
$$R_{ijkl} = \frac{1}{2} (T_1 \bigodot T_1)_{ijkl} + (T_2 \bigodot g)_{ijkl}.$$

Lemma A.3. Suppose that T_1 and T_2 are two commuting isoparametric tensors on a Riemannian manifold (M^n, g) and satisfy the relation (A.86). Then $T_2|_{V_{b_{\bar{k}}}}$ has two distinct eigenvalues at most. Moreover

$$b_{\bar{k}}^2 + a_{\bar{k}} + \bar{a}_{\bar{k}} = 0$$

when $T_2|_{V_{b_{\tau}}}$ has two distinct eigenvalues $a_{\bar{k}}$ and $\bar{a}_{\bar{k}}$.

Proof. For $a_{k_1} < a_{k_2} < \cdots < a_{k_m}$ and $i \in (k_1)$ and $j \in (k_2)$, it is easily seen from (A.84) that

$$R_{ijij} = \sum_{l \in [\bar{k}], l \notin (\bar{k}_1), (\bar{k}_2)} \frac{2T_{ij,l}^2}{(a_{k_1} - a_l)(a_{k_2} - a_l)} \ge 0$$

Hence, from (A.86),

(A.87)
$$R_{ijij} = b_{\bar{k}}^2 + a_i + a_j \ge b_{\bar{k}}^2 + a_{k_1} + a_{k_2} \ge 0, \quad i, j \in [\bar{k}] \text{ and } (i) \neq (j).$$

Therefore, from the generalized Cartan identity (A.85) in Lemma A.2, we get

(A.88)
$$R_{ijij} = b_{\bar{k}}^2 + a_{k_1} + a_j = 0, \ i \in (\bar{k_1}) \text{ and } j \in [\bar{k}], j \notin (\bar{k_1}).$$

The key of this proof is to realize that (A.88) allows us to further trim the generalized Cartan identity (A.85) for $i \in (\bar{k_2})$ into

(A.89)
$$\sum_{j \in [\bar{k}], j \notin (\bar{k_1}), j \notin (\bar{k_2}))} \frac{R_{ijij}}{a_{k_2} - a_j} = 0,$$

which in turn implies

$$R_{ijij} = b_{\bar{k}}^2 + a_{k_2} + a_j = 0, \ i \in (\bar{k_2}) \text{ and } j \in [\bar{k}], j \notin (\bar{k_2}).$$

Thus, repeating the above argument, we can get

(A.90)
$$R_{ijij} = b_{\bar{k}}^2 + a_i + a_j = 0 \text{ for all } i, j \in [\bar{k}] \text{ and } (i) \neq (j),$$

which forces $m \leq 2$ and completes the proof.

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