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41 42**ABSTRACT**

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44After the initial development of the first TOUGH-based geomechanics model 15 years ago 45based on linking TOUGH2 multiphase flow simulator to the FLAC3D geomechanics 46simulator, at least 15 additional TOUGH-based geomechanics models have appeared in the 47literature. This development has been fueled by a growing demand and interest for modeling 48coupled multiphase flow and geomechanical processes related to a number of geoengineering 49applications, such as in geologic CO₂ sequestration, enhanced geothermal systems, 50unconventional hydrocarbon production, and most recently, related to reservoir stimulation 51and injection-induced seismicity. This paper provides a brief overview of these TOUGH-52based geomechanics models, focusing on some of the most frequently applied to a diverse set 53of problems associated with geomechanics and its couplings to hydraulic, thermal and 54chemical processes.

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57**Keywords: TOUGH, modeling, fluid flow, geomechanics, THMC** 58

591 INTRODUCTION

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61A growing demand and interest for modeling coupled multiphase flow and geomechanical 62processes has resulted in the development of a growing number of models that adds 63geomechanics to the existing multiphase flow capabilities of the TOUGH family codes. This 64development started with the development of the TOUGH-FLAC simulator to meet the need 65for analyzing the effect of geomechanics on multiphase fluid flow behavior and transport 66properties around nuclear waste emplacement tunnels at the previously proposed U.S. high-67level nuclear repository site at Yucca Mountain, Nevada (Rutqvist et al., 2002; Rutqvist and 68Tsang, 2012). The TOUGH-FLAC simulator was developed as a pragmatic approach, linking 69the two existing codes, TOUGH2 and FLAC3D (Rutqvist et al., 2002). The TOUGH-FLAC 70simulator has since been adapted and applied for a wide range of geoscientific research and 71geoengineering applications, such as geologic CO₂ sequestration, enhanced geothermal 72systems, and gas production from hydrate bearing sediments (Rutqvist (2011) and references 73therein).

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75Following the first development of the TOUGH-FLAC simulator, a number TOUGH-based 76geomechanical models have been and are being developed. In fact, at least 15 additional 77TOUGH-based geomechanics models of various sophistications have appeared in the 78literature. This include simulators such as TOUGH+ROCMECH (Kim and Moridis, 2013), 79TOUGH-RDCA (Pan et al., 2014a), TOUGH-CSM (Winterfeld and Wu, 2015), TOUGH-80RBSN (Kim et al., 2015a), and many more linking TOUGH-family codes, such as TOUH2, 81TOUGH-MP, TOUGH+, TOUGHREACT, and ITOUGH to various geomechanics models. 82For example, TOUGHREACT has been linked to geomechanics models for the analysis of 83coupled thermal, hydraulic, mechanical and chemical (THMC) processes (e.g., Taron et al., 842009; Zheng et al., 2014; Kim et al., 2015b). In recent years, additional interest and demand 85have been fueled by the need stimulate reservoirs through fracturing (e.g., for enhanced 86geothermal systems or tight gas and shale gas formations), understand the risk of leakage 87(e.g., at carbon storage sites), and to address the issue of induced seismicity.

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89This paper provides a brief overview of the current TOUGH-based geomechanics models, 90including capabilities, applications and potential future developments. Table 1 lists and briefly 91describes 20 TOUGH-based geomechanics models that have appeared in the literature. In 92general these TOUGH-based geomechanics models differ in the assumptions about the 93mechanical behavior of porous and fractured geologic media, the numerical method used to 94perform the stress-strain calculation, the discretization scheme and how state variables and 95parameters calculated for potentially different meshes are mapped to each other, and the way 96to couple fluid flow and geomechanics. Although the TOUGH-based geomechanics models 97are developed for modeling coupled thermal-hydraulic-mechanical (THM) processes or, in 98some cases, even THMC processes, the couplings of fluid flow and geomechanics, i.e., HM 99couplings, are central to most applications and are known to be challenging to solve 100numerically depending on the specific application. Therefore, an overview of numerical 101schemes related to HM couplings schemes is devoted to the entire next section. This is 102followed by descriptions of TOUGH-FLAC, TOUGH-ROCMECH, TOUGH-RDCA, 103TOUGH-CSM, and TOUGH-RBSN, which are complementary TOUGH-based 104geomechanical models that have been most frequently applied to a diverse range of problems. 105Thereafter, other TOUGH-based geomechanics models listed in Table 1 are briefly reviewed

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106before concluding the paper with some final thoughts on the current state of TOUGH-based 107geomechanics models expected future developments.

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1092 HM COUPLING SCHEMES

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111Figure 1 shows a schematic of the couplings between hydraulic and mechanical processes in a 112deformable porous media such as soil and rock (Rutqvist and Stephansson, 2003). The arrows 113indicate the couplings, which can be divided into two categories: direct (solid line arrows) and 114indirect (dashed line arrows). Direct couplings are associated with pore-volume changes and 115their instantaneous and direct effect on fluid mass balance and effective stress, whereas 116indirect couplings are occurring indirectly through changes in mechanical and hydraulic 117properties.

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119Depending on the type of problem being solved and the porous medium properties, the 120importance of different HM couplings varies. In relatively permeable fractured hard rock, the 121indirect coupling in the form of permeability changes with stress might be most important. In 122relatively impermeable, soft and porous clay, on the other hand, direct pore-volume coupling 123may be most important. For example, when a porous deformable medium is suddenly loaded 124mechanically, the pores will be compressed and thereby squeezing the pore fluid to a higher 125pore pressure that will impact the fluid mass balance. This increase in pore-fluid pressure will 126in turn have an instantaneous effect on effective stress and volumetric strain. These are 127instantaneous two-way couplings between hydraulic and mechanical processes that can be 128challenging to resolve numerically.

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130A number of numerical schemes have been employed for solving coupled fluid flow and 131geomechanics problems (Minkoff et al., 2003; Kim, 2010). These include so-called fully 132coupled (monolithic) and sequentially coupled solution methods. In monolithic solutions, all 133the equations for fluid flow and mechanics including coupling terms are assembled into a 134large matrix system and solved simultaneously. Most of the coupled fluid flow and 135geomechanics finite element codes developed in rock and soil mechanics since the 1980s have 136employed fully coupled numerical schemes (e.g., Noorishad et al., 1982). The fully coupled 137method usually provides unconditional and convergent numerical solutions for 138mathematically well-posed problems (Noorishad et al., 1982; Rutqvist and Stephansson, 1392003; Kim, 2010).

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141When linking two different codes for fluid flow and geomechanics, it is generally not possible 142to use the monolithic solution scheme. Consequently, in most TOUGH-based geomechanics 143models to date, including TOUGH-FLAC, the equations for fluid flow and geomechanics are 144solved sequentially. Sequential coupling methods might be prone to numerical instability and 145inaccuracy when solving problems involving strong direct pore-volume coupling. Analysis of 146sequential methods associated with pore-elasticity with appropriate stability properties has 147been the subject many studies (Settari and Mourits, 1998; Mainguy and Longueare, 2002; 148Kim et al., 2009). However, as shown by Kim (2010), by choosing an appropriate coupling 149scheme with so-called stress fixed iterations in the sequential scheme, the sequential solution 150becomes unconditionally stable. In a stress fixed sequential solution, flow is solved first, 151fixing the total stress field, and then geomechanics is solved from the variables obtained at the 153calculating an appropriate porosity correction term while keeping the pore-compressibility 154non-zero and active in the reservoir simulator (Kim et al., 2011). Though the efficiency of the 155sequential, iterative schemes has been questioned (Prevost, 2013), a recent study showed that 156fixed stress split is a robust and efficient scheme for iteratively coupling poro-elastic systems 157even for highly nonlinear problems (Mikelíc et al., 2014).

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159For practical reasons, the sequential coupling method is used in all TOUGH-based 160geomechanics models except in some one-way coupled approaches and in TOUGH-CSM in 161which a monolithic solution is employed (Winterfeld and Wu, 2015). For strong pore-volume 162coupling, the various TOUGH-based geomechanics models, including TOUGH-FLAC, 163TOUGH+ROCMECH and TOUGH-CSM, have been verified against analytical solutions 164involving poro-elasticity such as solutions involving one-dimensional consolidation 165(Terzaghi) and the 2D Mandel-Cryer effects. These verifications have shown good agreement 166between numerical results and analytical solutions for both the fully coupled scheme in 167TOUGH-CSM (Winterfield and Wu, 2015) and sequentially coupled schemes in 168TOUGH+FLAC (e.g., Kim et al., 2012) and TOUGH+ROCMECH (e.g., Kim and Moridis, 1692013). This shows that both monolithic and sequential coupling schemes can be used to solve 170problems involving strong pore-volume coupling, though the efficiency of the two schemes 171might be substantially different depending on the specific problem being solved.

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173In the development of coupled HM numerical models, a lot of effort is usually dedicated to 174verification of algorithms related to pore-volume coupling, partly because poro-elastic 175analytical solutions for such problems exist. However, in much of the multiphase flow

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176applications encountered, direct two-way pore-volume couplings may not be important, or can 177be ignored by choosing an appropriate pore-compressibility in the flow simulator. More 178common is that indirect couplings by property changes dominate. Moreover, in many cases 179one-way coupling is sufficient, for example hydraulic-to-mechanical coupling considering 180how fluid pressure gives rise to mechanical deformation and failure. In other applications, 181such as fluid-driven hydraulic fracturing propagation, very strong pore-volume coupling 182appears, especially when new fracture volume is created at the crack tip, which is very 183challenging numerically, regardless of the applied HM coupling scheme.

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1863 TOUGH-FLAC

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188The TOUGH-FLAC simulator was originally developed in the late 1990s as part of the Yucca 189Mountain nuclear waste disposal project (Rutqvist et al., 2002; Rutqvist and Tsang, 2003a). At 190that time TOUGH2 (Pruess et al., 2012) was the main code used for the analysis of 191unsaturated zone flow and transport of the Yucca Mountain site, but there was a need to 192analyze how flow and transport was affected by geomechanical processes (Rutqvist and 193Tsang, 2003b). The idea was then to link TOUGH2 to a geomechanics code; the FLAC3D 194code (Itasca, 2012) was selected, because it had the required geomechanics capabilities, was a 195continuum code compatible with the TOUGH2 continuum approach, and was already 196qualified and applied in the Yucca Mountain Project (Rutqvist and Tsang, 2012).

197While FLAC3D (Itasca, 2012) is a commercial code and the source code is not distributed, it 198contains a script programming capability called FISH, which makes it possible to reach and 199modify internal variables and thereby enabled the linking with the TOUGH2 code. FLAC3D 200also has the capability of implementing user defined constitutive models through C++ 201programing added in a dynamic link library file (Rutqvist, 2011). Thus, despite not having 202access to the source code, FLAC3D provides sufficient flexibility for research applications 203and specialized developments to a wide range of applications. In addition, FLAC3D contains 204a large number of constitutive models, including elasto-plastic and visco-elastic (creep) 205models for solids as well as the possibility of including some discontinuities as interfaces 206between solid elements.

207As described in the previous section, TOUGH-FLAC uses sequential coupling between 208TOUGH2 and FLAC3D, whereby fluid flow variables, such as pore pressure, temperature, 209and saturation calculated by TOUGH2, are transferred to a compatible numerical grid for 210FLAC3D, which then calculates effective stresses and associated deformations, returning 211updated values for porosity, permeability, and capillary strength parameter to the flow 212simulator (Rutqvist et al., 2002; Rutqvist, 2011). As described in a 2011 status paper on 213TOUGH-FLAC (Rutqvist. 2011), TOUGH-FLAC was expanded to applications, including 214 geomechanical aspects of CO_2 sequestration and fault activation, geomechanical effects in gas 215production from hydrate bearing sediments, and geothermal energy production. Since 2011, 216TOUGH-FLAC applications have been further broadened along with an increasing number of 217users, including continued modeling of geomechanical aspects of CO₂ sequestration (Cappa 218 and Rutqvist, 2012; Mazzoldi et al., 2012; Rinaldi and Rutqvist, 2013; Jeanne et al., 2014a; 219Konstantinovskaya et al., 2014; Rinaldi et al., 2014a, b, 2015a; Figueiredo et al., 2015), 220nuclear waste disposal (Rutqvist et al., 2013; 2014), enhanced geothermal systems (Jeanne et 221al., 2014b-d, 2015a, b; Rutqvist et al., 2015a; Rinaldi et al., 2015b), underground gas storage 222and compressed air energy storage (Rutqvist et al., 2012a; Kim et al., 2013; Walsh et al.,

2232015), and gas production from hydrate bearing formations (Kim et al., 2012; Rutqvist et al., 2242012a).

225In the recent few years significant advancements of TOUGH-FLAC have been made, 226 extending the simulations to more complex geomechanical processes, especially related to 227modeling injection-induced fault activation and induced seismicity (Rutqvist et al., 2014a; 228Rinaldi et al., 2015a), advanced constitutive models for expansive clay in nuclear waste 229isolation (Rutqvist et al., 2014b; Vilarrasa et al., 2015), and modeling of salt geomechanical 230processes coupled with temperature and multiphase flow (Blanco-Martín et al., 2015a; 2016). 231Fault activation and induced seismicity have been modeled in 3D using strain-softening (slip-232weakening) fault friction models that enable modeling of sudden seismic slip (Rinaldi et al., 2332015a). This includes recent 3D modeling of injection-induced fault activations associated 234 with both underground CO₂ injection and during stimulation of shale-gas reservoirs (Rutqvist 235et al., 2015b; Rinaldi et al., 2015a). In some cases this has involved fully dynamic 236calculations of the fault activation and resulting ground surface motion (Rutqvist et al., 2372014a). Implementation of more advanced fault frictional laws is underway; Urpi et al. (2016) 238present a first step in the implementation of a rate-and-state fault friction law into the 239TOUGH-FLAC framework.

240The recent extension of the TOUGH-FLAC simulator for modeling THM processes 241associated with nuclear waste disposal in salt has been accomplished through collaboration 242between LBNL and Clausthal Technical University, Germany (Blanco-Martín et al., 2015b). 243This includes the development, implementation and application of an advanced constitutive 244model from Clausthal Technical University (the Lux/Wolters constitutive model) for THM 245induced damage, healing and sealing of salt host rocks and compaction of crushed salt 246(Blanco-Martín et al., 2016). Moreover, this involves modeling of large strain along with the 247compaction of the crushed salt backfill from a porosity of about 30% to less than 1% (Blanco-248Martín et al., 2015a, b). Clausthal Technical University uses a different coupling scheme in 249which FLAC3D is the main code driving the simulation forward, and denotes this simulator 250FLAC-TOUGH rather than TOUGH-FLAC (Lux et al., 2014; Blanco-Martín et al., 2015b).

251Related to THM in clay, the implementation of the Barcelona Basic Model for mechanical 252behavior of unsaturated soils (Rutqvist et al., 2014b), and the Barcelona Expansive Model 253(Vilarrasa et al., 2015) for mechanical behavior of expansive soils are important additions for 254rigorous modeling of bentonite based backfill material. Moreover, the consideration of two 255structural levels, i.e., macro- and micro-structures in the expansive model, provides a link 256between mechanics and chemistry for more mechanistic modeling of THMC behavior. Two 257recent papers by Zheng et al. (2014; 2015) describe different types of chemical-mechanical 258coupling behavior in bentonite, i.e., effects of chemistry on the mechanical evolution of the 259bentonite material. In this case TOUGHREACT is linked to FLAC3D to model CM 260couplings, such as salinity effects on swelling pressure. Such chemical-mechanical coupling 261effects might be especially important when considering higher temperature disposal systems 262(Zheng et al., 2015).

263Most recently, the TOUGH-FLAC approach has been extended and applied in inverse 264modeling, by linking FLAC3D to the ITOUGH simulation–optimization code (Finsterle, 2652015) using the general structure of the TOUGH-FLAC simulator (Blanco-Martín et al., 2662015c). The resulting simulator, ITOUGH-FLAC, provides an inverse modeling framework 267for the estimation of flow parameters, considering the system response accounting for 268geomechanical processes. Moreover, using iTOUGH2-PEST (Finsterle and Zhang, 2011) and

269TOUGH-FLAC, both flow and mechanical parameters can be estimated, including sensitivity 270analysis, uncertainty propagation and data-worth analysis. Currently, iTOUGH2-PEST with 271TOUGH-FLAC has been applied for material parameter estimation by analyzing field data at 272the In Salah CO₂ storage project. Algeria (Rinaldi et al., 2015c), and at a multi-year in situ 273heating experiment at Asse mine in Germany (Blanco-Martín et al., 2016).

274FLAC3D is a well-established code with a large user base (Itasca, 2012). It makes available 275many geomechanical constitutive models and has the flexibility to extend and implement new 276constitutive models, which is one of the most appealing features for selecting FLAC3D as the 277geomechanics code to be linked to TOUGH. One drawback with the current TOUGH-FLAC 278simulator is that it runs exclusively under Windows (because FLAC3D only runs under 279Windows), which prohibits the use ultra-large computer clusters. However, there are plans to 280port FLAC3D to Linux and to develop an MPI version in the near future (personal 281communication with Itasca, April 2016).

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2834 TOUGH-ROCMECH

285TOUGH-ROCMECH is developed as an alternative to TOUGH-FLAC, in which the source 286code of the geomechanics part is available and therefore enabling a more efficient linking 287between multiphase flow and geomechanics, and the possibility of porting the simulator for 288computer clusters and massive parallel processing (Kim and Moridis, 2013). ROCMECH is 289an LBNL in-house developed finite element code that was tailored first for linking with 290TOUGH+ (Kim and Moridis, 2013) and later with TOUGHREACT (Kim et al., 2015b) and 291iTOUGH2 (Finsterle, 2015). Similar to TOUGH-FLAC, TOUGH-ROCMECH employs

292sequential coupling schemes, including the fixed stress split algorithms, which have been 293implemented and verified by Kim and Moridis (2013).

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295The current basic ROCMECH version has the capability of modeling mechanical failure 296within solid elements through elasto-plastic Drucker-Prager or Mohr-Coulomb models. This 297has recently been extended to consider failure on multiple shear planes representing fracture 298sets of different orientation and applied for the analysis of shear stimulation related to an 299enhanced geothermal project at the Newberry Volcano, Oregon (Smith et al., 2015). A new 300multiporosity approach for poro-elasticity was also developed and implemented by Kim et al. 301(2012). This version of TOUGHREACT-ROCMECH has also been applied for modeling 302THMC processes for flow along fractures, considering mechanical and chemical 303(precipitation) effects on porosity and permeability (Kim et al., 2015b). These are processes 304important for the long-term sustainability of enhanced geothermal systems and for sealing of 305fractures associated with geologic containment of CO_2 and nuclear waste disposal.

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307In a version of TOUGH+ROCMECH, capabilities for modeling 3D fracture propagation 308along a vertical pre-defined plane have been implemented. This model was applied for the 309analysis of hydraulic fracture propagation associated with stimulation of shale-gas reservoirs 310(Kim and Moridis, 2013; 2015). The approach is similar to that of Ji et al. (2009), in which the 311fracture propagates along the boundary of the model domain through a nodal-splitting 312algorithm. The permeability of fractured elements are increased with fracturing opening 313according to the cubic relation between flow and fracture aperture (Rutqvist and Stephansson, 3142003). Using such an approach in the case of modeling hydraulic fracturing in tight shale, the 315TOUGH+RealGasH2O with ROCMECH has been applied (Kim and Moridis, 2013; 2015). 316The vertical fracturing is modeled by adding traction boundary conditions at locations where 317nodes have been split. Moreover, once a fracture has been created adjacent to the solid 318element, the initial single continuum element in TOUGH is changed to multiple continuum 319for considering the local leak-off from the fracture to the surrounding porous rock.

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321In ROCMECH, fracturing conditions for node-splitting are based on tensile strength rather 322than toughness. A fracturing criterion considering the effects of both effective stress normal to 323the fracture and shear stress enables a mix-mode fracturing criterion. Using this model, Kim 324and Moridis (2015) were able to model multiphase flow driven hydraulic fracturing and found 325significant effects of complex two-phase flow processes, including vertical gravity 326segregation that are processes important for estimating the fracture volume and leak-off to the 327surrounding rock.

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329Ongoing developments of TOUGH-based geomechanics models linked to ROCMECH 330includes MPI versions of both TOUGH+ROCMECH and TOUGHREACT-ROCMECH, 331which will enable simulations of much larger problems using massive parallel processing on 332large scale computer clusters.

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3345 TOUGH-RDCA335

336Pan et al. (2014a) coupled TOUGH2 to RDCA (rock discontinuous cellular automaton), a 337code capable of simulating nonlinear and discontinuous deformation behavior, such as plastic 338yielding and the initiation, propagation and coalescence of cracks induced by changes of fluid 339pressure and temperature.

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341RDCA uses a special displacement function to represent internal discontinuities (Pan et al., 3422014b). A level-set method tracks the fracturing path, and a partition of unity method is used 343to improve the integral precision of fracture surface and fracture tip calculations. The 344mechanical state is evaluated by a cellular automaton updating rule. In this approach, the 345discontinuity of a crack is incorporated independently of the mesh, such that the crack can be 346arbitrarily located within an element, i.e., the method does not require any re-meshing for 347crack growth. As a result, a fixed mesh can be used in RDCA and this greatly simplifies the 348modeling procedure and its sequential integration with TOUGH2. If a fracture propagates 349through a certain element, the permeability of this element is increased according to the cubic 350law with the additional permeability of the fracture superimposed on the initial permeability 351representing the rock matrix.

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353In TOUGH-RDCA, the fracturing condition can be evaluated either by linear elastic fracture 354mechanics using fracture toughness or by a modified Mohr-Coulomb criterion. The 355toughness-based criterion includes mixed Mode I (extension) and Mode II (shear) fracture 356propagation, whereas the Mohr–Coulomb criterion is modified with a tension cut-off, 357enabling modeling of both shear and tensile failure.

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359TOUGH-RDCA has been verified against analytical solutions and against TOUGH-FLAC for 360poro-elastic behavior and injection-induced ground surface uplift (Pan et al., 2013). A number 361of simulation applications have been presented related to fluid driven fracture propagation and 362CO₂ leakage through fractures. This includes multiple fracture propagation with intersections 363to pre-existing fractures (Pan et al., 2014c). The code is currently limited to modeling fracture 364propagation in 2D, whereas a 3D RDCA code is under development.

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366**6 TOUGH-CSM**

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368TOUGH-CSM is being developed at the Colorado School of Mines (CSM), with the ultimate 369goal of an efficient code tailored for massive parallel processing simulations (Winterfeld and 370Wu, 2012; 2015). The geomechanics part is accomplished by adding a mean stress equation 371for thermo-poroelastic multi-porosity media to the standard set of governing multiphase flow 372equations of TOUGH2-MP. In this formulation, the mean total stress is included as an 373additional primary variable, and the coupled thermal–hydrological–mechanical system is 374solved fully implicitly, obtaining volumetric strain and associated changes in porosity and 375permeability. Geochemical reactions based on the TOUGHREACT code have also been 376included in this formulation (Zhang et al., 2012; Winterfeld and Wu, 2012).

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378A few applications of TOUGH-CSM related CO_2 sequestration in deep sedimentary 379formations and geothermal systems have been published (Hu et al., 2013; Winterfeld and Wu, 3802014). In the case of CO_2 sequestration, the effect of fracturing through the caprock overlying 381a reservoir was studied in Huang et al. (2015). Since only the mean stress was solved in the

382fully coupled simulation, some other relationships and assumptions were used to estimate the 383horizontal stress needed for evaluating the possibility of vertical fracturing through the 384caprock. The application example related to geothermal, using a version of the code denoted 385TOUGH-EGS, included simulation of ground subsidence at the Geyser geothermal field with 386comparison to the previous results obtained with TOUGH-FLAC (Hu et al., 2015).

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388As concluded in Hu et al. (2015), calculations limited to mean total stress as opposed to the 389full stress tensor is a simplification that may be a shortcoming since it cannot analyze 390phenomena dependent on shear stress, such as rock failure. However, currently a new 391algorithm is being developed and tested in which the stress tensor, including all normal and 392shear stress components, are solved in a sequential manner (Winterfeld and Wu, 2015). This 393approach of calculating the stress components was verified against analytical solutions 394showing the potential of TOUGH-CSM for realistic and efficient modeling coupled 395geomechanical processes using massive parallel processing.

3967 TOUGH-RBSN

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398TOUGH-RBSN is being developed at LBNL with the main goal of modeling mass transport 399through permeable media under dynamically changing hydrologic and mechanical conditions 400in 3D heterogeneous geological media (Asahina et al., 2014; Kim et al., 2015a). A strong 401motivator is the potential of modeling discrete fracture propagation through heterogeneous 402geological media in 3D (Kim et al., 2015a). The simulation tool combines TOUGH2 with the 403rigid-body-spring network (RBSN) model, which enables a discrete (lattice) representation of 404elasticity, individual fractures and fracture networks in rock. 406One advantage of linking TOUGH2 and RBSN resides in their common utilization of a set of 407nodal points and properties of the corresponding Voronoi tessellation (e.g., natural neighbor 408and volume rendering definitions). Shared use of the Voronoi tessellation facilitates every 409stage of the analyses, including model construction and results interpretation. In such a 410system, the discrete fractures are directly mapped onto unstructured Voronoi grids via an 411automated geometric scheme (Asahina et al., 2011). A fracture is represented by the controlled 412breakage of the springs (1D lattice elements) linking adjacent Voronoi cells along the fracture 413trajectory. Fractures can propagate along Voronoi cell boundaries as THM-induced stresses 414evolve and exceed prescribed material strength values. The fracturing process is represented 415by the damage/breakage of the springs. A Mohr-Coulomb criterion with tension cut-off is used 416to judge when a lattice element undergoes a fracturing event.

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418The RBSN code has been extensively used and validated for fracturing in concrete materials, 419including heterogeneities such as large grain inclusions, whereas the linked TOUGH-RBSN 420code has been verified against analytical solutions and other numerical tools for various 421features, including poro-elasticity, swelling, and fracture deformation (Asahina et al., 2014; 422Kim et al., 2015a). Applications include validation against experimental results on desiccation 423cracking in a fine-grained sediment (mining waste), and most recently modeling of fracture 424propagation through a heterogeneous laboratory sample that includes pre-existing weaknesses 425(Kim et al., 2015a).

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427Currently a new dynamic simulation framework for RBNS is being developed. In the new 428methodology, nodal kinematic information (displacements, velocities, and accelerations) is 429calculated through the explicit time integration scheme, by which the code implementation 430with parallelization can be easily realized. The parallelization will be a requirement for being 431able to solve large-scale problems in 3D with this approach.

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4338 OTHER TOUGH-BASED GEOMECHANICS MODELS

435In addition to TOUGH-FLAC, TOUGH-ROCMECH, TOUGH-CSM, TOUGH-RDCA, and 436TOUGH-RBSN, a number of other TOUGH-based geomechanics models have been 437developed as listed in Table 1, though most of them have not been extensively applied.

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439Some of the earlier work includes Gosavi and Swenson (2005) who linked TOUGH2 to the 440finite element code GeoCrack3D, and later applied it to geothermal energy applications. 441Hurwitz et al. (2007) linked TOUGH2 to the USGS coupled hydro-mechanical finite element 442code Biot2, named the simulator TOUGH2-Biot, and applied it to study hydro-thermal fluid 443flow and deformation in large calderas. Recently another simulator named TOUGH2Biot was 444presented (Lei et al., 2015) involving TOUGH2 linked to an in-house finite element code and 445verified against previous TOUGH-FLAC simulations of the Geysers geothermal system and 446applied to simulate CO₂ injection of a site in China.

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448Taron et al. (2009) at Penn State University linked TOUGHREACT to FLAC3D, a TOUGH-449based geomechanics model that has been applied for modeling THMC processes associated 450with geothermal systems (Taron et al., 2009; Taron and Elseworth, 2009; Izada and Elsworth, 4512015). For example, Taron and Elseworth (2009) used THMC modeling to study the evolution 452of permeability associated with mechanical, thermal, and chemical (precipitation and 453dissolution) effects. In Izada and Elsworth (2014; 2015), the FLAC domain was populated 454with an implicit fracture network for the analysis of injection-induced micro-seismicity during 455hydraulic stimulation.

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457Other efforts includes Rohmer and Seyedi (2010) who linked TOUGH2 to the French open 458source finite element mechanics code Code_Aster and simulated deep underground CO₂ 459injection. Loschetter et al. (2012) used the TOUGH2-Code_Aster combination to model 460enhanced coalbed methane production. Aoyagi et al. (2013) linked TOUGH2 to FrontISRM, 461an open source finite element code in Japan, based on TOUGH-FLAC links, and 462demonstrated it by modeling a generic CO₂ injection simulation.

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464Some of the most recent efforts include Lee at al. (2015) who linked TOUGH2 to UDEC, 465which is a distinct element code, enabling modeling the geomechanical behavior of fracture 466networks in 2D. Miah et al. (2015) presented on-going work on linking TOUGH2 with 467PyLith, which is a USGS-developed finite-element code primarily used for large-scale 468geomechanical crustal deformation and earthquake simulation (static, quasi-static and 469dynamic modes). PyLith has advanced fault frictional models that will be applied and 470benchmarked against TOUGH-FLAC implementations of rate-and-state frictional models.

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472Finally, simpler TOUGH-based geomechanics approaches have been developed for 473specialized applications, including Walsh et al. (2012) who added the effects of an external, 474vertical stress change to the porosity updates. This approach was recently applied to model 475effects of glaciation in the safety assessment of a hypothetical nuclear waste repository 476(Calder et al., 2015). Another example is TOUGH2-Seed, a coupled fluid flow and 477mechanical statistical model for the study of injection-induced seismicity (Nespolia et al., 4782015). With TOUGH2-Seed, the authors were able to model several mechanisms influencing 479each other during and after the injection phase.

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4819 CONCLUDING REMARKS

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483After the first development of the TOUGH-FLAC simulator 15 years ago, at least 15 484additional TOUGH-based geomechanics models have appeared in the literature (Table 1).

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486Seven of those involve linking TOUGH2 to an in-house developed or open source finite 487element code, using sequential coupling techniques as in TOUGH-FLAC, but with access to 488the source code for the geomechanics part. One of the main motivations related to those 489developments is the access to the source code and the potential of more efficient coupling as 490well as the possibility of running the codes together on computer clusters. Among the codes 491linking TOUGH to an in-house or open source finite element code, TOUGH-ROCMECH is 492the one that has been applied most extensively to date. Most of these finite element codes are 493limited to linear poro-elasticity, although ROCMECH includes some elasto-plasticity with 494Drucker-Prager and Mohr-Coulomb constitutive models. To extend such geomechanics codes 495to more sophisticated constitutive models that are currently available in FLAC3D will require 496a substantial effort, but is feasible. TOUGH-CSM includes an unorthodox mechanical 497approach that with the current addition for calculation of the full stress tensor can be an 498efficient and useful approach for modeling large systems. TOUGH-based geomechanics 499models based on codes with access to the source code, such as TOUGH-ROCMECH and 500TOUGH-CSM, is expected to have increased user basis as more advanced constitutive 501geomechanics models and processes can be added along with their applications on large 502computer clusters.

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504TOUGH-FLAC still remains by far the most applied TOUGH-based geomechanics model. It 505is the combination of the TOUGH2 library of fluid equations-of-states (EOS) and the 506FLAC3D library of geomechanical constitutive models that make it possible to extend 507TOUGH-FLAC to new areas of research and geo-engineering applications within a relatively 508short time. The fact that FLAC3D only runs under Windows has been viewed as a bottleneck 509since it cannot be ported to large computer clusters to reduce the computation time. However, 510the computation time is only one part of the effort. Extension into a new research area or other 511types of geological media usually involves development and implementation of new 512constitutive models, to build the mesh and populate the model with material properties, 513boundary conditions, to run the models, to interpret the results and to publish it in scientific 514journals. FLAC3D has the user interface and flexible meshing and post-processing 515capabilities that can be used to construct models for both FLAC3D and TOUGH in an 516efficient way. A Linux and MPI version of FLAC3D is planned to be developed in the next 517few years (personal communication with Itasca, April, 2016). This could be very beneficial 518for being able to run large scale problems, though there are issues on how to deal with the 519sequential coupling of codes on large-scale computer clusters.

520

521Currently there is a need for effective model simulations of fracturing and fracture 522propagation in heterogeneous geological media. The ability to model discrete fracture 523propagation in 2D has been demonstrated for TOUGH-RDCA; the fractures can propagate 524through the mesh without the need for remeshing. A 3D version of RDCA is under 525development, but this will require substantial effort and 3D fracture propagation through a 3D 526heterogeneous rock mass will be challenging. Discrete fracture propagation has also been 527demonstrated for TOUGH-ROCMECH, in 3D, but limited to a pre-defined path, such as 528vertical fracture along the boundary of the model domain. Other approaches, such as 529TOUGH-UDEC and TOUGH-PyLith, could be useful additions for modeling complex 530hydraulic stimulations and induced seismicity. TOUGH-RBSN has the potential for modeling 531 complex fracturing processes in 3D in heterogeneous geological media, though more 532 developments are required before it can be applied for large-scale systems. The dependency 533of mesh orientation and size that are typically associated with hydraulic fracturing modeling 534 will also have to be investigated when applying these TOUGH-based hydraulic fracturing 535models.

536

537Finally, TOUGH-based geomechanics models enabling modeling of coupled THMC (through 538TOUGHREACT) as well as multi-physics joint inversion (trough ITOUGH), are areas of 539active research in which significant developments and applications are expected to take place 540in the coming years. TOUGH-based geomechanics models such as TOUGH-FLAC, TOUGH-

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541ROCMECH, TOUGH-CSM, TOUGH-RDCA, TOUGH-RBSN, are fully compatible to be 542extended for linking geomechanics to TOUGHREACT and ITOUGH. These TOUGH-based 543geomechanics models are complementary in terms of capabilities and application areas and 544the choice of model for a specific application will always be up to the user based on 545experience with different models, their capability and availability.

546

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859Figure 1. Hydromechanical couplings in geological media; (i) and (ii) are direct couplings 860through pore volume interactions, while (iii) and (iv) are indirect couplings through changes 861in material properties (Rutqvist and Stephansson, 2003).