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Direct Image-Based Attenuation Correction using Conditional Generative Adversarial Network for SPECT Myocardial Perfusion Imaging

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Abstract

Attenuation correction (AC) is important for an accurate interpretation and quantitative analysis of SPECT myocardial perfusion imaging. Dedicated cardiac SPECT systems have invaluable efficacy in the evaluation and risk stratification of patients with known or suspected cardiovascular disease. However, most dedicated cardiac SPECT systems are standalone, not combined with a transmission imaging capability such as computed tomography (CT) for generating attenuation maps for AC. To address this problem, we propose to apply a conditional generative adversarial network (cGAN) for generating attenuation-corrected SPECT images (*SPECT*_{GAN}) directly from non-corrected SPECT images (*SPECT*_{NC}) in image domain as a one-step process without requiring additional intermediate step. The proposed network was trained and tested for 100 cardiac SPECT/CT data from a GE Discovery NM 570c SPECT/CT, collected retrospectively at Yale New Haven Hospital.The generated images were evaluated quantitatively through the normalized root mean square error (NRMSE), peak signal to noise ratio (PSNR), and structural similarity index (SSIM) and statistically through joint histogram and error maps. In comparison to the reference CT-based correction (*SPECT*_{CTAC}), NRMSEs were 0.2258±0.0777 and 0.1410±0.0768 (37.5% reduction of errors); PSNRs 31.7712±2.9965 and 36.3823±3.7424 (14.5%)

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improvement in signal to noise ratio); SSIMs 0.9877 ± 0.0075 and 0.9949 ± 0.0043 (0.7% improvement in structural similarity) for *SPECT_{NC}* and *SPECT_{GAN}*, respectively. This work demonstrates that the conditional adversarial training can achieve accurate CT-less attenuation correction for SPECT MPI, that is quantitatively comparable to CTAC. Standalone dedicated cardiac SPECT scanners can benefit from the proposed GAN to reduce attenuation artifacts efficiently.

Keywords

SPECT; myocardial perfusion imaging (MPI); attenuation correction; deep learning; generative adversarial network

1. INTRODUCTION

Single-photon emission computed tomography (SPECT) is a well-validated noninvasive imaging technique which enables studying the function of underlying organs or tissues after the injection of radioactive tracers. SPECT gamma camera by capturing the emitted gamma-ray photons of the injected radioactive tracer can clearly reflect the distribution of the tracer throughout patient's whole-body. SPECT imaging has a wide spectrum of clinical applications. One of the most common SPECT clinical applications is myocardial perfusion imaging (MPI) for clinical diagnosis and risk stratification of cardiovascular disease.¹

Photon attenuation from photoelectric absorption and Compton scattering are the major factors in reducing quantitative accuracy and quality of SPECT images. Diaphragm is the primary reason for attenuation artifacts in MPIs which results in perfusion defects in inferior wall. Breast attenuation in women can also produces artifacts along the anterior wall of left ventricle (LV). Several studies have demonstrated that attenuation correction can improve both the sensitivity and specificity for detection of coronary artery disease (CAD) and generate a relative uniform tracer distribution for patients with a low likelihood of CAD.^{2–4} Moreover, attenuation corrected images can help physicians to have a more accurate diagnosis which in result can reduce the unnecessary invasive angiography procedures. ^{5,6}Therefore, correcting the tissue-dependent attenuation is essential for accurate quantitative analysis. Without accurate attenuation correction, severe artifacts may occur, which may prevent accurate clinical interpretation.

Integrated SPEC/CT systems were first introduced by Lang and Hasagawa et al.⁷ The system by performing additional anatomical imaging on patients can fuse physiologic and anatomic images in a registered format which facilitates visualization of anatomic localization of tracer distribution in the body. Furthermore, integrated SPECT/CT systems facilitated attenuation correction using a CT for generating attenuation maps (μ -map), that is more efficient and practical than using radionuclide transmission sources only for attenuation correction. However, these integrated systems are still more expensive than standalone SPECT systems, that currently occupy the majority of cardiac SPECT market share,⁸ and increase the patient's radiation dose due to performing an extra CT scan only for AC in SPECT. Besides, respiratory and cardiac motion may cause incorrect attenuation correction artifacts due to a mismatch between SPECT and CT data. Therefore, it is

important to be able to correct attenuation in standalone SPECT scanners with no extra transmission source or CT available and saving unnecessary extra CT radiation dose in integrated systems.

To address the problem of μ -maps estimation from only SPECT emission data, different algorithms were proposed which can be categorized into two categories: (1) segmentation-based algorithm, and (2) model-based algorithm. In segmentation-based algorithm, estimating μ -map without transmission imaging like a CT can be achieved by utilizing photopeak and scatter data information. In this approach, μ -maps are estimated by assigning predefined attenuation coefficient to different manually segmented regions in SPECT images.^{9–11} The main assumption here is that tissues have uniform attenuation coefficient which is not a correct assumption and cannot be extended to all the patients. Moreover, manual segmentation of different regions makes the segmentation-based approaches operator-dependent, time consuming, and not suitable for clinical workflow. The Model based algorithms also estimate the attenuation coefficients directly from SPECT emission data.^{12–14} Model-based approaches do not incorporate the scattered photon in their models, and this causes an inaccurate estimation. In addition, these methods suffer from computational time and can only be applied to slices of the images and not the whole 3D structure.

In recent years, deep learning has demonstrated tremendous success in different computer vision tasks. Duo to deep learning success and its proven potential in computer vision, there has been an increased interest recently in investigating how deep learning algorithms can be applied to medical images and provide insightful information to physicians in their diagnosis and treatment procedure. Attenuation correction is also among one of the problems which have been studied using deep learning for both SPECT and PET data.^{15–18} Convolutional Neural Networks (CNNs) can be used to generate synthetic CT images from magnetic resonance imaging (MRI) in order to correct attenuation for PET in PET/MRI.^{18,19} However, these methods still require anatomical images and our focus in this study is to develop an end-to-end approach for AC with no transmission source available.

In this study, we developed a 3D conditional generative adversarial network (cGAN) to correct the attenuation in SPECT MPI images directly from non-corrected SPECT images. We demonstrated the feasibility of attenuation correction using a cGAN to correct attenuation in image domain using only non-corrected SPECT images without using CT data or generating pseudo-CT data as an intermediate step. The proposed approach is an end-to-end process that can model non-linear mapping directly from non-corrected to attenuation-corrected images, whereas conventional methods rely on CT values that needs to be generated first and then be used for attenuation correction.

2. MATERIALS AND METHODS

2.1 Data Acquisition

In an IRB-approved study, 100 patients were scanned on GE Discovery NM/CT 570c SPECT/CT scanner (GE D570c) at Yale New Haven Hospital for stress-only myocardial perfusion SPECT studies using ⁹⁹*n*/Tc-tetrofosmin. The datasets consist of 42 female

subjects and 58 male subjects. Other characteristics of subjects are not available duo to data anonymization. CT data was acquired for each subject with the parameters of 120 kVp, 50 mA, and rotation time of 0.4 second. Corresponding attenuation corrected images for each non-corrected image were generated by rigid alignment of CT and $SPECT_{NC}$ using Attenuation Correction Quality Control package (GE ACQC). Both $SPECT_{NC}$ and $SPECT_{CTAC}$ were reconstructed using one-step-late algorithm with Green prior. $SPECT_{CTAC}$ images were reconstructed with 60 iterations and post-filtered by a Butterworth filter with a cutoff of 0.37 cm-1 and an order of 7; and $SPECT_{NC}$ images were reconstructed with 30 iterations and post-filtered by a Butterworth filter with a cutoff of 0.4 cm-1 and an order of 10. All reconstruction parameters are clinically used at Yale New Haven Hospital.

The *SPECT_{CTAC}* was used as a ground truth to compare the proposed deep learning method to the standard CT-based correction approach. The original size of reconstructed images was $70 \times 70 \times 50$ with an isotropical voxel size of 4 mm. As a preprocessing step, the size of reconstructed images was changed to $64 \times 64 \times 32$ to enable upsampling and downsampling by removing edges from the images. Voxel values were normalized to a scale of 0 to 1 by the maximum value of volumetric images.

2.2 Network Architecture and Training

Generative adversarial network (GAN) is a generative model which was first introduced by Ian Goodfellow in 2014.²⁰The framework includes two neural network models, a generator (G) and a discriminator (D) which compete with each other in a zero-sum game manner. Adversarial way of training led to more stable models compared to non-adversarial training and was formulated as a new way of deep convolutional learning method in 2015.²¹ GANs can generate synthetic plausible images with data distribution of a given dataset from the latent space. The objective function of the original GAN can be expressed as follows.

$$argmin_Gmax_D(L_{GAN}(G, D) = E_x \sim P_{data}[\log D(x)] + E_z \sim P_{noise}(z)[\log(1 - D(G(z)))]$$
(1)

Where P_{data} is the real data distribution, z is a random input drawn from a specific probability distribution (such as Gaussian) $z \sim P_{noise}(z)$.

Conditional generative adversarial networks can be used for an image-to-image translation task by conditioning a model on source images and learning a map between the source and target images which in our case are non-corrected and attenuation corrected images, respectively.²²

Given the non-attenuation corrected SPECT image $x \sim P_{NC}(x)$, and the corresponding CTbased attenuation corrected image $y \sim P_{CTAC}(y)$, the objective function of a conditional GAN can be formulated as below.

$$\begin{aligned} \arg \min_{G} \max_{D} (L_{cGAN}(G, D) + \lambda L(G)) &= E_{x} \sim P_{NC}(x), y \sim P_{CTAC}(y) [\log D(x, y)] + \\ E_{x} \sim P_{NC}(x) [\log(1 - D(x, G(x)))] + \\ \lambda E_{x} \sim P_{NC}(x), y \sim P_{CTAC}(y) [y - G(x)] \end{aligned}$$

$$(2)$$

The last term is an additional estimation of error loss which we added to the main objective function in order to make sure that the generated images are similar to the real attenuation corrected images. In this case the generator uses both the discriminator's feedback and the generator's loss information to deceive the discriminator while trying to generate real looking images. λ is a hyper parameter for tuning the weight between the original objective function and the added error loss.

The conditional GAN network architecture in this work was inspired by the Pix2Pix network.²² We used the Pix2Pix GAN framework as a baseline and modified the architecture explained above for our application. The discriminator in this model is a deep convolutional neural network which performs the conditional-image classification task. The generator task is to generate real-looking images of the target domain given the source images as its input and via adversarial training. The schematic conditional GAN architecture is shown in Fig. 1.

Below we explain the generator and discriminator architecture used in the proposed cGAN in more details.

2.2.1 Generator—The modified generator's architecture has an encoder-decoder structure with symmetrical skip connections between different stages adopted from the original U-Net model.²³ In the U-Net, the input progressively downsample through the encoder's layers and the process is reversed through the layers of the decoder. A U-Net can extract important features at different resolutions through its encode-decoder structure. The U-Net model was first introduced for segmentation task and later was modified for image synthetic task. The original U-Net has a 2D architecture, while in this work 3D architecture was used. The 3D generator model takes 3D volume ($64 \times 64 \times 32$) as its input and uses 3D operations throughout the architecture.

Residual blocks were embedded between the last layer of the encoder and first layer of the decoder to keep the important characteristics of the original input images. Each residual block is a neural network which consists of two convolution layers along with a normalization and rectified linear unit (ReLU) activation function. Combining U-Net architecture with residual blocks can facilitate smoother flow of information between the input and output of the network. Skip connections can help regain some of the lost gradient information by combining hierarchical features. Moreover, it can also provide a better model's convergence and performance in image translation applications.²²

The proposed generator's architecture consists of 4 contracting (encoder) paths and 4 expansive paths (decoder) with symmetrical skip connections. We used convolution operator (Conv) with kernel size of 3, instance normalization (IN), and leaky ReLU (LReLU) as an

2.2.2. Discriminator—The discriminator in this model is a deep convolutional neural network which performs a conditional-image classification task. The discriminator takes either a real AC SPECT image or a synthesized one (generated by the generator) as input and determine whether the input to its network is real or fake.

we used ReLU instead of LReLU in the decoder part (Fig. 2).

The discriminator in our model consists of 6 convolutional layers with kernel size 3 and with strides 2. The first convolution layer produces 16 feature maps, and then this number is doubled at each following convolution step. All convolutional layers are followed by normalization and Leaky ReLU activation function with slope of 0.2. A filter size of 1 is applied to the last convolutional layer to determine whether the input was real or fake (Fig. 3).

2.2.3. Training with CGAN—Following the same standard adversarial training approach in the original GAN,²⁰ the generator and discriminator were trained in an alternative manner. The discriminator was trained first and then the generator using the Adam optimization with an initial learning rate of 0.0002. The initial learning rate changed to 0 after the first 100 epochs. 200 epochs were used for the entire training and setting the estimation error weight (λ) to 0.005 results in better evaluation performance. 5-fold cross-validation method was used for training and testing the proposed approach.

2.2.4 Training with WGAN—Although GAN has been successful in many generative tasks, training a GAN model is challenging because stable training requires finding and maintaining an equilibrium between the capabilities of the generator and discriminator. The Wasserstein GAN^{24} was proposed to enable more stable and less sensitive training to the architecture of a model. Mathematically, Wasserstein (Earth Mover (EM)) distance which measure the similarity between two probability distributions is continuous and differentiable almost everywhere and this feature makes it to be a much more sensible cost function than other commonly used cost functions such as cross-entropy used in training a network.

The problem with using cross-entropy loss function is that the discriminator learns very quickly to distinguish between fake and real images and after a while provides no reliable gradient information that can help a generator to improve the quality of generated images (vanishing gradient problem). One of the reasons that a discriminator in a GAN learns to separate real and fake samples perfectly is that both real and generated datasets rest in low dimensional manifolds due to restrictions on image characteristics that the model is trained on. When a low dimensional manifold (image hyperplanes) is embedded in high dimensional space (image dimension), the image hyper-planes hardly overlap and allows the discriminator to easily separate the real and fake images. WGAN replaces the discriminator model with a critic model which instead of binary classification, scores the realness of a given data. The critic function does not have the saturation problem and converges to a linear function that provides clean gradients everywhere. Therefore, a new Wasserstein-based training model has the capacity to improve the stability of the optimization process.

2.3 Evaluation metrics

To evaluate the reliability of the proposed method on correcting the attenuation, we calculated normalized mean square error (NRMSE), peak signal to noise ratio (PSNR), and structural similarity index (SSIM) for non-corrected SPECT (*SPECT_{NC}*) and cGAN-corrected SPECT (*SPECT_{GAN}*), compared to the reference CT-based attenuation corrected images (*SPECT_{CTAC}*). Lower NRMSE and higher SSIM and PSNR indicate better similarity. The evaluation measurements are defined as below.

$$NRMSE = \sqrt{\frac{\sum_{i \in V} \left(I(i) - I_{ref}(i) \right)^2}{\sum_{i \in V} \left(I_{ref}(i) \right)^2}}$$
(3)

$$PSNR = 10 \log_{10} \left(\frac{N \cdot \max_{i \in V} \left(I(i), I_{ref}(i) \right)}{\Sigma_{i \in V} \left(I(i) - I_{ref}(i) \right)^2} \right)$$
(4)

$$SSIM = \frac{(2\mu\mu_{ref} + c_1)(2 + \sigma_{ref} + c_2)}{(\mu^2 + \mu_{ref}^2 + c_1)(\sigma^2 + \sigma_{ref}^2 + c_2)}$$
(5)

where *V* is image volume. *I* is either *SPECT_{NC}* or *SPECT_{DL}*, and *I_{ref}* is *SPECT_{CTAC}*. μ and σ denote the mean and variance of the image *I*. c_1 and c_2 are variables for stabilizing the division with a weak denominator.

For statistical analysis, joint histograms were used to show the statistical distribution of voxel-by-voxel correlation with the reference for $SPECT_{NC}$ and $SPECT_{DL}$, respectively.

3. RESULTS

The results of the quantitative measures using 5-fold cross-validation can be found in Tab. 1. The numerical results in Tab. 1 demonstrate that the proposed DL approach improves the similarity of $SPECT_{DL}$ to the reference $SPECT_{CTAC}$ by 37.5% for NRMSE and 14.5% for PSNR, compared to that of $SPECT_{NC}$ to the reference. The joint histograms in Fig. 4 demonstrate how the proposed approach can improve the similarity of $SPECT_{NC}$ to the reference $SPECT_{CTAC}$ which is consistent with the results in Tab. 1, by reducing the bandwidth of the scattered correlation of $SPECT_{NC}$ with the reference.

For qualitative analysis, $SPECT_{CGAN}$ and $SPECT_{NC}$ images were visually compared to the reference $SPECT_{CTAC}$ images using CGAN training. Fig. 5 shows a sample image with the minimum NRMSE value (0.06116) in the transverse, coronal, and sagittal view. This case has the highest value for both PSNR (42.7727) and SSIM (0.99921). Places where the attenuation was improved using the cGAN based approach have been marked by arrows.

The conditional GAN performance depends heavily on the tuning of the parameters to slow down the rate at which discriminator learns relative to the generator's model. Using Wasserstein loss can make the training process more stable and less sensitive to the choice of hyperparameter configurations. For the results in Tab. 1, we need to tune the parameters in a

way to have a balanced model which as a result provides a better performance. As can be seen in Tab. 1 conditional GAN using Wasserstein loss has better quantitative results compared to the unbalanced cGAN. The results of the Wasserstein cGAN is also slightly better than the cGAN itself and there is no need to balance learning capability between the generator and the discriminator. Parameters such as loss weight, learning rate, and momentum parameters in the chosen optimizer can affect the relative rate of learning and need to be tuned. Therefore, the model trained with Wasserstein loss is more stable and has a slightly better quantitative results compared to the other models trained with other loss functions. However, what we found is that with enough hyperparameter optimization to find a balance between the generator and the discriminator, cGAN and WGAN provide comparable results.

4. CONCLUSION AND FUTURE DIRECTIONS

SPECT MPI is susceptible to attenuation artifacts; and thus an efficient AC technique is desired for improving diagnostic accuracy. Specifically, the technique will benefit patients scanned in stand-alone dedicated cardiac SPECT systems. In this work, we proposed a direct DL-based AC technique using a cGAN in SPECT MPI. The preliminary results demonstrate the feasibility of producing accurate attenuation corrected images directly from non-corrected data in an end-to-end manner using adversarial training. We further extended the proposed model to Wasserstein cGAN and compared the results of WGAN with cGAN from the stability point of view. The proposed approach has the potential to promote the clinical feasibility of offering a practical means of attenuation correction for dedicated myocardial SPECT systems which requires a practical way of attenuation correction without generating attenuation maps as an intermediate step. Future work will include testing our algorithms using a larger number of clinical datasets for robust training with diverse cases annotated by expert human readers as well as extending the proposed cGAN model to a cycleGAN model. ²⁵

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Figure 1. Schematic conditional GAN architecture



Figure 2. Top: generator's architecture. Bottom: residual block's architecture.



Figure 3. Discriminator's architecture

Torkaman et al.



Figure 4.

Joint histogram: (a) $SPECT_{NC}$ versus $SPECT_{CTAC}$ slope (dashed line) = 0.9054, (b) $SPECT_{GAN}$ versus $SPECT_{CTAC}$, slope = 0.9825. To visualize small counts in the joint histograms, the counts were log-scaled (i.e., log(counts)).

Page 14



Figure 5.

case 14 with the minimum NEMSE (0.06116). Column 1: CT-based AC. Column 2: Deep Learning AC. Column 3: Non-corrected data. Column 4: Error map between DL results and CT-based AC. Column 5: Error map between non-corrected data and CT-based AC.

Table 1.

Voxel-wise analysis. The NRMSE, PSNR, SSIM of $SPECT_{NC}$ and $SPECT_{CGAN}$, compared to the reference $SPET_{CTAC}$ (mean \pm SD).

	NRMSE	PSNR	SSIM
SPECT _{NC}	0.2258 ± 0.0777	31.7712 ± 2.9965	0.9877 ± 0.0075
SPECT _{CGAN}	0.1410 ± 0.0768	36.3823 ± 3.7424	0.9949 ± 0.0043
SPECT _{UnbalCGAN}	0.1468 ± 0.0873	$36.1304 \pm 3.8735.$	0.9947 ± 0.0050
SPECT _{WGAN}	0.1355 ± 0.0571	36.4537 ± 3.4182	0.9949 ± 0.0042