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Publication Date

1969-10-01

UCRL-19332 Preprint

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Generalized Criteria of Characteristics Nonlinearity of Phase-Sensitive Detection Systems:

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Recent investigations [1,2] have shown that in the instrumentation of experimental research the total nonlinearity of characteristics of phasesensitive detection systems is of prime importance. The idealized phasesensitive detection system to be considered is shown in Fig. 1. The system input consists of an input signal va(t) superimposed on a broad-band Gaussian noise $v_s^*(t)$. After time-invariant linear narrow-band filtering the sum $v_s(t) + v_n(t)$ is applied to the balanced phase-sensitive detector. Detector inputs are subtracted in a differential circuit. The dc output of varying amplitude represents the output signal Vo. In most cases of practical interest, the total nonlinearity of system characteristics is determined by the essential nonlinearity of characteristics of the phasesensitive detector used, and is described by generalized equations $N_B = 1 - (\Delta_1) / \{ x \mu_1 F_1 [1/2; 2; - (\mu^2 + x^2)/2] (\pi/2 - \psi) \}$ and $N_e = 1 - (\Delta_1)/(\Delta_2)$.

The term $x = V_s/V_0$ is the detector input signal-to-noise ratio; $\mu = V_c/V_0$ is the system reference wave-to-noise ratio; ${
m V_S}$ is the amplitude of the detector input sine signal; $V_{
m c}$ is the amplitude of the system reference wave; Vo is the root-mean square value of the detector input narrow-band noise; ψ is the phase angle between the detector input signal and the system reference wave; $_1F_1$ denotes the confluent hypergeometric function [3,4]; Δ_1 and Δ_2 signify the difference of hypergeometric functions $_1F_1$ [-1/2; 1; - (μ^2+x^2 + $2x \mu \cos \psi$)/2] - $_{1}F_{1}$ [-1/2;1; $(\mu^{2} + x^{2} - 2\mu x \cos \psi)$ /2] and $_{1}F_{1}$ [-1/2;1; $-(\mu + x)^2/2$] - $_1F_1$ [-1/2;1; - $(\mu - x)^2/2$], respectively. Essential nonlinearity results from the inherent behaviour of the detector used in the system when signal is being detected in the presence of noise. Based on previous work [2] and comments made by A. R. Johnson [5], careful investigations show that the necessary and sufficient condition for nonlinearity minimum NBMIN is given by a transcendental generalized criterion in the $w[f(x_B)] \{ [x_B^2/2 + (\mu x_B \cos \psi)/2] \cdot s[v(x_B)] \}$

 $- [x_B^2/2 - (\mu x_B \cos \psi)/2] m[t(x)] - \Delta_{1B} + \Delta_{1B}(x_B/2)^2 K[f(x_B)] = 0,$

where functions $w[f(x_B)]$, $s[v(x_B)]$, $m[t(x_B)]$, and $K[f(x_B)]$ are given by

$$w[f(x_B)] = {}_{1}F_{1} [1/2;2; -(\mu^2 + x_B^2)/2],$$

$$s[v(x_B)] = {}_{1}F_{1} [1/2;2; -(\mu^2 + x_B^2 + 2 \mu x_B \cos \psi)/2],$$

$$m[t(x_B)] = {}_{1}F_{1} [1/2;2; -(\mu^2 + x_B^2 - 2 \mu x_B \cos \psi)/2],$$
(4)

$$s[v(x_R)] = {}_{1}F_{1}[1/2;2; -(\mu^2 + x_R^2 + 2 \mu x_R \cos \psi)/2],$$
 (3)

$$m[t(x_p)] = {}_{1}F_{1}[1/2;2; -(\mu^2 + x_p^2 - 2 \mu x_p \cos \psi)/2],$$
 (4)

$$K[f(x_B)] = {}_{1}F_{1}[3/2;3; -(\mu^2 + x_B^2)/2].$$
 (5)

Terms Δ_{1R} and Δ_{2R} signify the previously defined difference of hypergeometric functions, only x should be changed into x_{p} .

Work done under auspices of the U.S. Atomic Energy Commission.

By means of computer-aided analysis, using numerical solutions of Eq. (1) and high-density discrete-value calculations, the minimum nonlinearity expressed N_BMIN = $f^*(\mathbf{x}_B)_{\mu,\psi}$ is calculated and plotted in Fig. 2. From curves it can be seen that N_BMIN is a monotonically decreasing function of \mathbf{x}_B having a fast rate of decrease of almost a half order of magnitude for $\mathbf{x}_B \leq 10$. N_BMIN varies less than 16% for $\mathbf{x}_B \geq 10$ and $\psi \leq \pi/6$. For $\mathbf{x}_B \geq 10$ and $\psi \geq \pi/6$, N_BMIN has approximately a constant value with variation of \mathbf{x}_B . Furthermore, there are N_BMIN accumulation points at $\mathbf{x}_B = 2.37295$ for $\mu \leq 0.1$ and for any value of ψ . The N_BMIN accumulation points are maximum values of N_BMIN for a given value of ψ .

Similarly, a generalized criterion for the maximum nonlinearity $^{N}_{\hspace{0.5cm}\text{CMAX}}$

is given by

$$\begin{aligned} & \left\{ \phi[g(x_C)] - z[h(x_C)] \right\} \left\{ [x_C/2 - (\mu \cos \psi)/2] \ m[t(x_C)] \right. \\ & - \left[x_C/2 + (\mu \cos \psi)/2 \right] \ s[v(x_C)] \right\} \\ & + \Delta_{1C} \left\{ \left[(x_C + \mu)/2 \right] \rho[g(x_C)] - \left[(x_C - \mu)/2 \right] \ell[h(x_C)] \right\} = 0, \quad (6) \end{aligned}$$

where functions $m[(x_C)]$ and $s[v(x_C)]$ are given by relations (2) and (3), respectively. Other functions are defined by

$$\phi[g(x_c)] = {}_{1}F_{1}[-1/2;1; -(\mu + x_c)^{2}/2], \qquad (7)$$

$$z[h(x_c)] = {}_{1}F_{1}[-1/2;1; -(\mu - x_c)^{2}/2],$$
 (8)

$$\rho[g(x_c)] = {}_{1}F_{1}[1/2;2; -(\mu + x_c)^{2}/2], \qquad (9)$$

$$l[h(x_C)] = {}_{1}F_{1}[1/2;2; -(\mu - x_C)^{2}/2].$$
 (10)

Terms Δ_{1C} signifies the previously defined difference of hypergeometric functions, only x should be changed into \mathbf{x}_C . The maximum nonlinearity expressed as $N_{CMAX} = \varphi^*(\mathbf{x}_C)_{\mu,\psi}$ is calculated by use of a high-density discrete-value approach and plotted in Fig. 3. From the curves in Fig. 3-we see that N_{CMAX} is a monotonically increasing function of \mathbf{x}_C , having a fast rate of increase depending upon ψ . N_{CMAX} accumulation points are again at $\mathbf{x}_C = 2.37295$ for $\mu \leq 0.1$ and for any value of ψ . Generally N_{CMAX} accumulation points are minimum values of N_{CMAX} for a given value of ψ .

Furthermore, applying the same method as in previous considerations, it is also of interest to calculate over a wide dynamic range of operating conditions the normalized form of characteristics of the phase-sensitive system as a function of ψ , for various values of μ and calculated values of x_B and x_C , considering above criteria. According to [2], normalized forms of the detector characteristics as a function of ψ , with μ , x_B , and x_C as parameters, are given by

$$(V_o/\eta_d V_\sigma)_B = (\pi/2)^{1/2} \Delta_{1B}$$
 (11)

and

$$(v_o/\eta_d v_\sigma)_c = (\pi/2)^{1/2} \Delta_{1c}$$
 (12)

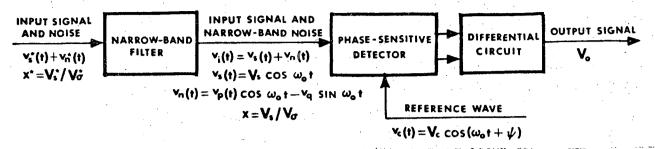
where \boldsymbol{V}_{o} and $\boldsymbol{\eta}_{d}$ are the system output signal and detector efficiency.

Calculations show that the numerical values of \mathbf{x}_B and \mathbf{x}_C are very close over a wide range of μ and ψ , although \mathbf{x}_B gives the condition for minimum nonlinearity, and \mathbf{x}_C for maximum nonlinearity. Consequently, both functions (11) and (12) can be represented by one curve for a set of values of μ , ψ , and \mathbf{x}_B or \mathbf{x}_C . Calculations show that the normalized output signal is almost independent of the phase angle for a ratio $\psi \leq 0.2$. For a $\psi \geq 0.2$ ratio, the normalized output signal considerably decreases its value, achieving $V_O/\eta_d V_O = 0$ for $\psi = \pi/2$.

FOOTNOTE AND REFERENCES

The author wishes to express appreciation to E. Schroeder for writing the computer program.

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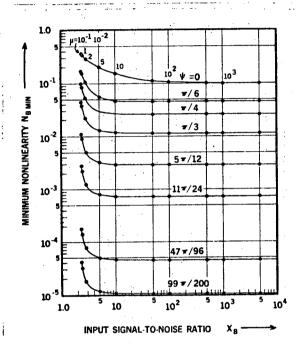


Fig. 1. Idealized phase-sensitive detection system.

Fig. 2. Minimum nonlinearity N_{BMIN} as a function of the optimum value of the input signal-to-noise ratio x_B, with the phase angle \(\psi\$ and the reference wave-to-input noise ratio as parameters.

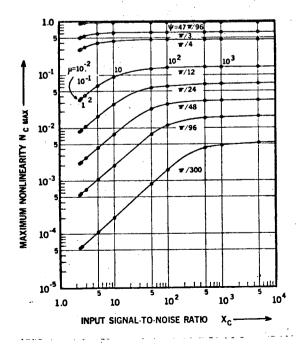


Fig. 3. Maximum nonlinearity N_{CMAX} as a function of the nonoptimum value of the input signal-to-noise ratio x_C, with the phase angle ψ and the reference wave-to-input noise ratio as parameters.

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