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Corrigendum

Corrigendum to “Rotational kinematics and torques for triaxial bodies” [Icarus 223 (2013) 615–618]

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Eq. (24), add G to numerator above denominator $C\omega_{\text{rot}}$;

Line 15, “B-axis” should read “A-axis”;

Eq. (26), after the $\cos\theta$, replace the + sign by a – sign;

Eqs. (27) and (28), replace term $(A + 3B - 4C)$ by $(3A + B - 4C)$ on the right hand side.

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