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Proceedings of the Annual Meeting of the Cognitive Science Society

Title

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Journal

Proceedings of the Annual Meeting of the Cognitive Science Society, 41(0)

Authors

Loula, Joo

Silver, Tom

Allen, Kelsey

et al.

Publication Date

2019

Peer reviewed

Discovering a symbolic planning language from continuous experience

Joo Loula

MIT, Cambridge, Massachusetts, United States

Tom Silver

MIT, Cambridge, Massachusetts, United States

Kelsey Allen

Massachusetts Institute of Technology, Cambridge, Massachusetts, United States

Josh Tenenbaum

MIT, Cambridge, Massachusetts, United States

Abstract

Humans make plans with remarkable flexibility by leveraging symbolic representations. How are these representations learned? We present a model that starts out with a language of low-level physical constraints and, by observing expert demonstrations, builds up a library of high-level concepts that afford planning and action understanding. We demonstrate its versatility through experiments inspired by developmental psychology literature.