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Coupled Vadose Zone and Atmospheric Surface-Layer Transport of
CO₂ from Geologic Carbon Sequestration Sites

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1 ABSTRACT

2 Geologic carbon dioxide (CO₂) sequestration is being considered as a way to offset
3 fossil-fuel-related CO₂ emissions to reduce the rate of increase of atmospheric CO₂
4 concentrations. The accumulation of vast quantities of injected carbon dioxide (CO₂) in
5 geologic sequestration sites may entail health and environmental risks from potential
6 leakage and seepage of CO₂ into the near-surface environment. We are developing and
7 applying a coupled subsurface and atmospheric surface-layer modeling capability built
8 within the framework of the integral finite difference reservoir simulator TOUGH2. The
9 overall purpose of modeling studies is to predict CO₂ concentration distributions under a
10 variety of seepage scenarios and geologic, hydrologic, and atmospheric conditions.
11 These concentration distributions will provide the basis for determining above-ground
12 and near-surface instrumentation needs for carbon sequestration monitoring and
13 verification, as well as for assessing health, safety, and environmental risks. A key
14 feature of CO₂ is its large density ($\rho = 1.8 \text{ kg m}^{-3}$) relative to air ($\rho = 1.2 \text{ kg m}^{-3}$), a
15 property that may allow small leaks to cause concentrations in air above the occupational
16 exposure limit of 4% in low-lying and enclosed areas such as valleys and basements
17 where dilution rates are low. The approach we take to coupled modeling involves
18 development of T2CA, a TOUGH2 module for modeling the multicomponent transport
19 of water, brine, CO₂, gas tracer, and air in the subsurface. For the atmospheric surface-
20 layer advection and dispersion, we use a logarithmic vertical velocity profile to specify
21 constant time-averaged ambient winds, and atmospheric dispersion approaches to model
22 mixing due to eddies and turbulence. Initial simulations with the coupled model suggest
23 that atmospheric dispersion quickly dilutes diffuse CO₂ seepage fluxes to negligible

1 concentrations, and that rainfall infiltration causes CO₂ to return to the subsurface as a
2 dissolved component in infiltrating rainwater.

3

4 **1. INTRODUCTION**

5 Geologic carbon dioxide (CO₂) sequestration is being considered as a way of reducing
6 the rate of increase of atmospheric CO₂ concentrations due to combustion of fossil fuels
7 for energy production (Reichle et al., 1999). Once injected into deep geologic formations
8 such as depleted oil and gas reservoirs, deep coal seams, and brine formations saturated
9 with ground water, CO₂ will tend to rise upward by buoyant flow even under supercritical
10 conditions unless trapped by low-permeability structures, by dissolution into ground-
11 water, or by mineralogic reactions (Bachu et al., 1994). Despite numerous secondary
12 trapping processes, there is a risk that CO₂ will leak from the target storage formation and
13 migrate upwards to where it can seep out of the ground (Oldenburg and Unger, 2003).
14 During leakage and seepage, a fraction of the leaking CO₂ may dissolve in groundwater
15 aquifers or in surface waters, thus impacting these natural resources. From the point of
16 view of human and environmental risk associated with exposure to CO₂ from leaking
17 geologic carbon sequestration sites, it is advection and dispersion above the ground
18 surface in the biosphere that is most significant since this is where the key receptors are
19 located. Yet the advection and dispersion processes occurring in the atmospheric surface
20 layer (also referred to simply as the surface layer, and defined approximately as the
21 bottom one-tenth of the atmospheric boundary layer), will be coupled to subsurface
22 processes since (1) the subsurface is the source of the seeping CO₂, (2) ambient air can

1 flow into and out of the subsurface in response to atmospheric pressure changes, and (3)
2 CO₂ is a dense gas that will tend to migrate downwards and hug the ground relative to
3 ambient air. Therefore, simulation models for atmospheric dispersion of CO₂ that neglect
4 processes involving the subsurface and the vadose zone in particular may not be
5 appropriate except in certain limited situations.

6 A schematic of potential CO₂ leakage and seepage from a geologic sequestration site is
7 shown in Figure 1 along with associated processes and features. Specifically, Figure 1
8 shows a geologic CO₂ sequestration site with a permeable fault through which CO₂ is
9 unexpectedly leaking upward by buoyancy and pressure-driven flow. The leaking CO₂
10 plume spreads as it decompresses with rise in the subsurface and eventually flows out
11 from the water table into the vadose zone where it displaces and mixes with existing soil
12 gas. In the vadose zone, leaking CO₂ may spread out and upwards until it seeps out of
13 the ground. Above the ground surface in the surface layer, wind and possibly density-
14 driven flow effects will control the flow and dispersion of CO₂. A schematic of an eddy-
15 flux tower and CO₂ monitoring vault are shown to suggest potentially important near-
16 surface monitoring strategies for CO₂ seepage detection and CO₂ sequestration
17 verification.

18 Motivated by the need to predict CO₂ concentrations in the event that a geologic
19 sequestration site would leak leading to significant upward migration through the
20 saturated and vadose zones and eventual CO₂ seepage at the ground surface, we have
21 developed a coupled subsurface–surface-layer simulation capability called T2CA
22 (TOUGH2 CO₂ and Air). T2CA can be used for risk assessment and for designing
23 instrumentation and strategies for geologic carbon sequestration monitoring and

1 verification. This new simulation capability can be used to answer questions about what
2 the expected concentrations will be in the surface layer and shallow subsurface resulting
3 from assumed leakage fluxes. This information can then be used to (1) assess the
4 potential exposure to CO₂ for humans and other environmental receptors, and (2) develop
5 specifications and designs of monitoring equipment and strategies for sequestration
6 verification (e.g., Oldenburg and Lewicki, 2003).

7

8 In the case of catastrophic failures involving large seepage fluxes, for example due to a
9 well blowout, the health risks are obvious and the event could have potentially lethal
10 effects, thus subordinating the sequestration verification issue in favor of safety
11 assurance. However, we expect the challenging issues to be health, safety, and
12 environmental risk assessment, as well as monitoring and verification, associated with
13 diffuse or very slow seepage phenomena that are hard to detect. For this reason, our
14 simulation capability is designed for cases of diffuse seepage as opposed to catastrophic
15 failures. The time scale of interest is from 1 month to 10 years, making averaging of
16 winds and other environmental variables defensible. The purpose of this paper is to
17 present our approach to modeling subsurface and surface-layer CO₂ migration and
18 dispersion of leakage and seepage from geological carbon sequestration sites, and to
19 show some initial results. This modeling effort is the subject of ongoing testing and
20 verification.

21

1 2. BACKGROUND

2 Carbon dioxide is a dense gas ($\rho = 1.8 \text{ kg m}^{-3}$) relative to air ($\rho = 1.2 \text{ kg m}^{-3}$) as shown in
3 Figure 2, where we have plotted gas density and viscosity for mixtures of CO₂ and air
4 calculated from the NIST14 Database (NIST, 1992; Magee et al., 1994). Although CO₂
5 is ubiquitous and essential to life as part of the natural carbon cycle, it is hazardous at
6 high concentrations. The current ambient CO₂ concentration in the atmosphere is
7 approximately 375 ppmv (0.0375 %); concentrations of 4% can cause immediate danger
8 to humans (NIOSH, 1981). As such, CO₂ can be considered a dense hazardous gas, a
9 class of substances that has received considerable attention over the years for leak and
10 spill risk assessment of industrial gases (e.g., Britter and Griffiths, 1982; Hanna and
11 Steinberg, 2001). For example, liquefied propane gas (LPG), liquefied natural gas
12 (LNG), and many others are dense hazardous gases upon release to the atmosphere.
13 Motivated by the need to assess risks associated with the mass production and transport
14 of dense gases, a great deal of experimental, analytical, and modeling work has been
15 focused on the problem of dense gas dispersion in the surface layer. This work is
16 summarized in the review article by Britter (1989).

17 The result of many field experiments of dense gas dispersion processes has been the
18 development of correlations involving the most important parameters controlling
19 atmospheric dispersion such as wind speed, density of released gas, and release flux
20 (Britter and McQuaid, 1988). These correlations were developed based on simple scale
21 and dimensional analysis. One of these correlations relates the seepage flux and average
22 wind speed at an elevation of 10 m to delineate regimes of density-dependent and passive
23 dispersion. In Figure 3, we have plotted this correlation with values appropriate for CO₂-

1 air mixtures for four different length scales (L) of the source area along with the typical
2 amount of CO₂ emitted and taken up by plants, soil, and roots known as the net
3 ecosystem exchange (NEE) (e.g., Baldocchi and Wilson, 2001). The length scale L is a
4 characteristic length scale that describes the size, e.g., diameter, of the seepage source
5 region. As shown in Figure 3, seepage fluxes have to be quite high (note logarithmic
6 scale) for windy situations for the resulting dispersive mixing process to be density-
7 dependent. Note that wind conditions are averages over a period of 10 minutes.

8 In prior work (Oldenburg and Unger, 2003), we have simulated subsurface migration of
9 leaking CO₂ through the unsaturated zone with rainwater infiltration for various leakage
10 rates specified at the water table. Typical seepage fluxes were on the order of 10^{-5} – 10^{-6}
11 kg m⁻² s⁻¹. As shown in Figure 3, seepage fluxes of this magnitude lead to passive (i.e.,
12 not density-dependent) dispersion for all but the calmest wind conditions. Therefore, we
13 have developed an approach for the case of diffuse emissions that models passive mixing
14 and does not consider dense-gas dispersion effects nor catastrophic CO₂ emission events.
15 For these diffuse gas seepage scenarios, we are considering 10 m to 1 km length scales,
16 and time scales from 1 month to 10 years.

17

18 **3. COUPLED MODELING APPROACH**

19 **3.1 Introduction**

20 In order to simulate the coupled subsurface–surface-layer advection and dispersion of
21 CO₂, we have developed T2CA, an extension of the EOS7R module of TOUGH2
22 (Oldenburg and Pruess, 1995; Pruess et al., 1999). TOUGH2 is an integral finite
23 difference reservoir simulator developed for handling multicomponent and multiphase

1 porous media flow systems such as geothermal and hydrocarbon reservoirs, and
2 multiphase flow systems such as the vadose zone or saturated systems that contain
3 contaminant plumes with non-aqueous phase liquids (NAPLs) (Pruess et al., 1999).
4 T2CA handles five components (H_2O , brine, CO_2 , a gas tracer, air) and heat. Real gas
5 mixture properties are calculated so the full range of high-pressure sequestration-site
6 conditions to low-pressure ambient surface-layer conditions can be modeled. We have
7 added atmospheric surface-layer dispersion capabilities to T2CA to create a fully coupled
8 subsurface–surface-layer simulator. The advantages of adding atmospheric dispersion
9 process-modeling capabilities to the reservoir simulation code as opposed to coupling an
10 existing atmospheric dispersion code to the reservoir code are (1) consistent multiphase
11 and multicomponent treatment in the subsurface and surface layer for convenient mass-
12 conservative transport, (2) full coupling of multiphase and multicomponent flow and
13 transport between the subsurface and surface-layer regions, (3) synchronous time-
14 stepping in the two regions, (4) lack of need to license or purchase externally developed
15 software, and (5) expediency for us due to our long experience with TOUGH2. For other
16 surface-layer modeling objectives, such as modeling dispersion over non-flat terrain,
17 density-dependent flow, or high Reynolds number flows, coupling of existing Navier-
18 Stokes codes to TOUGH2 would likely be the most expedient approach.

19 The purpose of this section is to present the methods implemented in T2CA. Because
20 subsurface transport in T2CA is unchanged from the standard approach used in
21 TOUGH2, we focus our discussion on the methods we apply in the surface layer to model
22 atmospheric dispersion. These methods are derived from the atmospheric dispersion
23 modeling literature and transferred into the TOUGH2 reservoir simulation framework in

1 an expedient way. A simple verification problem is presented to show that the methods
2 are implemented correctly. While the discussion below focuses on CO₂ transport, all of
3 the gas-phase components are treated identically.

4 **3.2 Transport of Dilute CO₂ as a Passive Gas**

5 Transport of CO₂ as a passive gas implies that it advects and disperses in the atmosphere
6 without influencing the flow field. In order for this assumption to hold, CO₂ must be at
7 sufficiently low concentrations that it does not significantly affect the density or viscosity
8 of the ambient atmosphere. Under this assumption, we discuss below the underpinnings
9 of the use of an ambient wind profile as well as advection and dispersion processes in the
10 lower layers of the atmosphere as developed in the atmospheric transport literature (e.g.,
11 Slade, 1968; Pasquill, 1974; Stull, 1988; Arya, 1999).

12 **3.3 Logarithmic Velocity Profile**

13 The ambient time-averaged wind profile near the ground surface has been shown
14 theoretically to follow a logarithmic profile. An excellent review of the assumptions and
15 calculations involved in the logarithmic profile, as well as experimentally derived
16 parameters obtained from calibration to field data is provided in Slade (1968, p. 73). The
17 logarithmic wind profile is valid over approximately the lower one-tenth of the
18 atmospheric boundary layer, or approximately a few tens of meters above the ground
19 surface. The logarithmic wind profile as shown on Figure 4 is given as:

20

21

$$u(z) = \frac{u_*}{k} \ln\left(\frac{z}{z_0}\right) \quad (1)$$

22

1 where $u(z)$ is the ambient wind velocity as a function of height, u^* is the friction velocity
 2 (a parameter that governs the shape of the wind profile near the ground surface for
 3 various surface types), k is von Karman's constant ($k = 0.4$), z is the elevation, and z_0 is a
 4 roughness height such that $u(z) = 0$ for $z \leq z_0$ and is also a function of various surface
 5 types (Slade, 1968). The logarithmic wind profile is strictly applicable only to neutral
 6 stability conditions, although equations that account for its variation with atmospheric
 7 stability can be formulated (e.g., Golder, 1972).

8 **3.4 Advective-Dispersive Transport**

9 *Gradient Transport Theory*

10 The mean turbulent transport of CO₂ as a passive gas in the surface layer can be
 11 described by the advective-dispersive transport equation with variable eddy diffusivities
 12 (K_x , K_y , K_z) (Arya, 1999, p. 137). For the three-dimensional (x , y , z) transport of a
 13 component (such as CO₂) at concentration c , this equation is

$$14 \frac{\partial c}{\partial t} + u \frac{\partial c}{\partial x} + v \frac{\partial c}{\partial y} + w \frac{\partial c}{\partial z} - \frac{\partial}{\partial x} \left(K_x \frac{\partial c}{\partial x} \right) - \frac{\partial}{\partial y} \left(K_y \frac{\partial c}{\partial y} \right) - \frac{\partial}{\partial z} \left(K_z \frac{\partial c}{\partial z} \right) = 0 \quad (2)$$

16 For convenience in surface-layer transport modeling, the coordinate system can be
 17 arranged so that x is aligned in the downwind direction, making $v = w = 0$ where u is the
 18 ambient wind.

19 *Gaussian Plume Model*

20 For the special case of constant eddy diffusivities and the assumption of a uniform wind
 21 velocity (u) with no shear (i.e., no velocity gradient), and assuming that advection

1 dominates diffusion in the x -direction, solutions to Eq. 2 are given by the well-known
 2 Gaussian plume dispersion model, with eddy diffusivities D_{xx} , D_{yy} , and D_{zz} given by

$$3 \quad D_{xx} = \frac{\sigma_x^2}{2t}, \quad D_{yy} = \frac{\sigma_y^2}{2t}, \quad D_{zz} = \frac{\sigma_z^2}{2t} \quad (3)$$

4 where σ_x , σ_y , σ_z are the standard deviations of concentration distributions at an
 5 observation or receptor point, and t is the travel time to the point (e.g., Arya, 1999, p.
 6 132).

7 The fundamental challenge in Gaussian plume modeling is the estimation of the eddy
 8 diffusivities. The empirically derived Pasquill-Gifford (P-G) dispersion curves provide a
 9 practical means of determining atmospheric dispersion, and are discussed in detail in
 10 Slade (1968) and Arya (1999). Essentially, eddies that are smaller than the plume size
 11 are assumed to result in dispersion of passive constituents that can be mathematically
 12 represented as a diffusion process. The Pasquill-Gifford dispersion curves were
 13 developed from experiments conducted over a wide variety of terrain (e.g., project Prairie
 14 Grass and British diffusion experiments (Pasquill, 1961; Gifford, 1961)) and atmospheric
 15 conditions (ranging from class A-extremely unstable, class B-moderately unstable, class
 16 C-slightly unstable, class D-neutral, class E-slightly stable, to class F-moderately stable).
 17 The Pasquill-Gifford curves provide values of σ_y and σ_z as a function of a downwind
 18 observation or receptor location under a specific atmospheric condition (classes A–F)
 19 from which constant values of D_{yy} and D_{zz} can be derived from Eq. 3. The Pasquill-
 20 Gifford dispersivities are valid for dispersion over distances less than approximately 1 km
 21 downwind from near-surface sources over moderately rough and flat terrain (Slade, 1999,
 22 p. 203).

1 Despite the agreement with field data and widespread acceptance for large-scale
2 modeling, the Gaussian plume model assumes uniform velocity, which is not valid in the
3 surface layer near the ground surface, an area of particular interest for CO₂ leakage and
4 seepage studies. Before presenting the preferred approach that we have used in this
5 study, we present a verification problem that makes use of the simple analytical solutions
6 of the Gaussian plume model to confirm our implementation of eddy diffusivities and
7 velocity specification in T2CA.

8 *Verification*

9 The simple Gaussian plume model is useful for verifying the surface-layer dispersion
10 capabilities we have developed in T2CA. For a 3-D system with uniform wind speed (u)
11 of 1 m s^{-1} , $D_{xx} = D_{yy} = D_{zz} = 5 \text{ m}^2 \text{ s}^{-1}$, and a point source strength of 0.314 kg s^{-1} , we
12 solved the Gaussian plume analytical solutions given in equations 6.38 and 6.42 of Arya
13 (1999) and compared them to the T2CA solution of the same problem. Note that we take
14 advantage of symmetry in the problem and carry out the T2CA simulation in the upper
15 half of one side of the 3-D domain, and use a corresponding source strength that is 1/4
16 that used in the analytical solution. We show in Figure 5 T2CA results for the 3-D CO₂
17 concentration plume as it is advected by a uniform wind in the x -direction ($u = 1 \text{ m s}^{-1}$)
18 from a $1 \text{ m} \times 1 \text{ m}$ source with strength $Q = 0.0785 \text{ kg s}^{-1}$ in a finely discretized region near
19 the origin ($x, y, z < 10 \text{ m}$) and disperses equally in the y - and z -directions. Note that the
20 CO₂ concentration shown in Figure 5 is in units of $\text{kg CO}_2 \text{ m}^{-3}$ of gas to match the units
21 of the analytical solutions. Furthermore, the analytical solution assumes isotropic
22 dispersion, whereas in T2CA we assume that advection dominates over dispersion in the
23 x -direction. To make up for this difference, we used a grid with 10 m gridblocks ($\Delta x =$

1 10 m) throughout most of the domain ($x, y, z > 10$ m) to make numerical dispersion in
 2 T2CA approximately match the D_{yy} and D_{zz} of the analytical solution, where numerical
 3 dispersion in the upstream-weighted and implicit T2CA is approximately $\Delta x/2 \times u = 5$ m
 4 $\times 1 \text{ m s}^{-1} = 5 \text{ m}^2 \text{ s}^{-1}$.

5 We show in Figure 6 contours of CO₂ concentration for the y - z plane extracted from the
 6 3-D domains of both the analytical and T2CA results. As shown, the agreement is very
 7 good. At $x = 100$ m, we have extracted the profile in the y -direction and plotted CO₂
 8 concentration against y for the analytical and numerical T2CA results as shown in Figure
 9 7. As shown, the agreement is very good, and the calculated standard deviations match
 10 closely (Figure 7). Using Eq. 3 with $D_{yy} = D_{zz} = 5 \text{ m}^2 \text{ s}^{-1}$, the theoretical standard
 11 deviation at $x = 100$ m would be 31.6 m, in good agreement with calculated results. The
 12 10% puff-radius approximation (Arya, 1999, p. 132) matches the theoretical result to
 13 within 1% ($\sigma_{rp} = 67.4 \text{ m}/2.15 = 31.3 \text{ m}$). These results serve to verify the atmospheric
 14 dispersion framework built into T2CA.

15 *Variable-K Theory*

16 Although attractive for its simplicity and widely used, the Gaussian plume model is not
 17 valid for situations with wind shear (i.e., a non-zero gradient of u with height), as
 18 appropriate for winds near the ground surface that will affect CO₂ seepage (Arya, 1999,
 19 p. 197-199). Instead, theory and data point to the need for variable eddy diffusivities (K_x ,
 20 K_y , K_z), an approach called variable-K theory. The variable-K theory is recommended for
 21 cases with wind shear and non-homogeneous turbulence such as will be found in the
 22 surface layer (Arya, 1999, p. 143). For our surface-layer applications involving CO₂

1 seepage, we have used variable K-theory and the assumption that K_z increases linearly
2 with height as

$$3 \quad K_z = k u_* z \quad (4)$$

4 (Arya, 1999, p. 143). This model assumes neutral stability in the surface layer, allows for
5 a variable wind speed with height, and models the larger dispersion that occurs as the
6 plume moves upward. There is no analogous formulation of K_y valid for short travel
7 distances (< 10 km) in variable-K theory (Arya, 1999, p. 151). Because of this
8 shortcoming of variable-K theory, and the urgent need to understand potential leakage
9 and seepage CO_2 concentrations, we adopt here a 2-D configuration for our test problem
10 that models only vertical dispersion and downwind advection by wind with a logarithmic
11 velocity profile. Because CO_2 dispersion will occur only in the vertical direction, this
12 represents a conservative model in that actual CO_2 concentrations downwind will be
13 lower for emissions from any realistic areal source for which lateral dispersion occurs.
14 The neglect of lateral dispersion is not an inherent limitation of T2CA, which is in fact
15 three-dimensional, and can include lateral dispersion assuming a reasonable
16 parameterization is available.

17 **3.5 Summary**

18 We have combined the logarithmic velocity profile and variable-K theory into a
19 preliminary and expedient approach for modeling multicomponent (CO_2 , gas tracer, and
20 air) transport in a 2-D surface layer that is directly coupled with a porous medium
21 subsurface region. In this approach, we calculate eddy diffusivities from the variable-K
22 diffusivity of Eq. 4 to produce an effective atmospheric dispersivity at every gridblock in
23 the surface layer, a convenient approach in the discretized framework of T2CA.

1 Although it is normally negligible, the molecular diffusion coefficient is added to the
 2 eddy diffusivity with the largest term controlling the dispersion process. The single
 3 effective dispersivity is then used in the advective-dispersive transport equation for each
 4 chemical component to model surface-layer transport. The methods implemented in
 5 T2CA for surface-layer dispersion are the subject of ongoing verification and testing.

6 **4. IMPLEMENTATION IN TOUGH2**

7 **4.1 Specification of the Logarithmic Wind Profile**

8 The simulation of atmospheric advection and dispersion by the above methods requires
 9 the specification of a logarithmic wind profile within the TOUGH2 framework that will
 10 prevail throughout the simulation. This step involves generating a grid with sufficient
 11 layers (i.e., parallel to the ground surface) to discretize the wind profile to the desired
 12 accuracy. Next, a static gas-phase pressure profile in the z -direction is used along with a
 13 constant pressure difference between the upstream and downstream boundaries of the
 14 surface layer

$$15 \quad \Delta P = P_2 - P_1, \quad P_1 > P_2 \quad (5)$$

17 where P_1 and P_2 are the upstream and downstream pressures, respectively, within a layer.

18 TOUGH2 computes the phase velocity using Darcy's equation

$$19 \quad u = -\frac{k_D}{\phi \mu} \nabla(P - \rho g z) \quad (6)$$

22 where k_D is the intrinsic (Darcy) permeability, ϕ is the porosity, μ is the gas viscosity, ρ is
 23 the mass density of the gas phase, g is the gravitational acceleration and z is height.

24 Setting the porosity of the surface-layer materials to unity, the velocity of the atmospheric

1 air will be proportional to the permeability of the layer and pressure difference, ΔP , for
2 horizontal layers. Given that ΔP is a constant for all layers, the individual permeability
3 variations of the layers will combine to produce the logarithmic wind profile. Note that
4 the thickness of each layer must be constant to ensure a constant air velocity within the
5 layer across the length of the domain. Note further that the permeability is a pseudo-
6 permeability with no physical significance; its purpose is simply to create the desired
7 velocity profile. Note further that the velocity in the surface layer does not change during
8 the simulations because the dispersion process is passive. In essence, we have specified a
9 velocity field for the surface layer that persists throughout the T2CA simulation. In the
10 example presented below, the permeability for the top atmospheric layer with the highest
11 (reference) velocity is set to $1 \times 10^{-2} \text{ m}^2$ to minimize ΔP in Eq. 5 and the potential for
12 artificial forced flow of atmospheric air from the upstream boundary into the subsurface.
13 In addition, this value also permits smooth convergence of the Newton iteration.

14 **4.2 Calculating Atmospheric Dispersion**

15 Within the TOUGH2 framework, transport of CO_2 as a passive gas will follow the
16 advective-dispersive transport equations used to calculate the multicomponent transport
17 of species in the gas phase. Ambient atmospheric dispersion of CO_2 is implemented by
18 using a spatially dependent effective molecular diffusivity in the surface-layer region.
19 With this approach, the diagonal of the tensor representing diffusion of CO_2 is modified
20 to be the sum of the eddy diffusivity and molecular diffusion.

21 Numerical dispersion in the implicit and upstream-weighted TOUGH2 framework is on
22 the order of one-half the grid spacing multiplied by the velocity. Because of the

1 alignment of the grid with the unidirectional wind, numerical dispersion occurs only in
2 the flow direction (i.e., x -direction) in the surface layer. In the quasi-steady cases we are
3 considering, advection dominates transport in the flow direction. In the vertical direction,
4 the velocity is zero ($w = 0$), thus vertical eddy diffusion is untainted by numerical
5 dispersion. If CO₂ front tracking in the surface layer ever arises as a focus of interest,
6 special weighting schemes can be implemented to diminish numerical dispersion in the
7 flow direction (e.g., Oldenburg and Pruess, 2000).

8 **4.3 Restriction to Passive Dispersive Transport**

9 In general, CO₂ dispersion can occur both as a dense or as a passive gas, depending on
10 CO₂ concentration. Although our approach is applicable only to passive gas transport in
11 the surface layer, note in Eq. 6 that the body force term remains. Therefore, if significant
12 density effects ever arise in the surface layer, velocity will be affected and will deviate
13 from the logarithmic velocity profile that should remain unaltered throughout the
14 simulation. If the velocity profile in the surface layer changes, it is an indication that the
15 atmospheric dispersion process is not strictly passive, and the user should proceed
16 carefully to assess whether other methods should be applied to model dense gas
17 dispersion. Full density dependence is assumed in the subsurface (porous medium)
18 regions where CO₂ concentrations can be quite large and density-driven flow
19 correspondingly important.

20 **4.4 Summary**

21 Implementing the coupled subsurface–surface-layer CO₂ flow and transport model in
22 TOUGH2 involves the assumption of an average logarithmic wind velocity profile and
23 the use of an effective dispersivity formed by summing the eddy diffusion and molecular

1 diffusion coefficients. Our approach is novel in that it implicitly couples the surface
2 layer to the subsurface region. This coupling is important because CO₂ seepage may
3 return to the subsurface through gas-phase advection, diffusion, or dissolution in
4 infiltrating water. While our multicomponent transport methods for the subsurface are
5 firmly established and accepted, we present our surface-layer transport and dispersion
6 approach as a preliminary and expedient multicomponent method useful for estimating
7 surface-layer CO₂ concentrations resulting from CO₂ leakage.

8 **5. PRELIMINARY RESULTS**

9 We present in this section preliminary results to demonstrate the capabilities of T2CA.
10 The properties of an idealized two-dimensional unsaturated zone and atmospheric surface
11 layer are shown in Figure 8 with properties given in Table 1. The domain consists of 100
12 x 1 x 55 gridblocks in the x -, y -, and z -directions. The subsurface consists of 35 layers of
13 gridblocks of dimension $\Delta z = 1.0$ m. The atmospheric surface layer consists of 20 layers
14 of gridblocks of dimension $\Delta z = 0.5$ m. The horizontal discretization is $\Delta x = 10$ m and Δy
15 = 1.0 m and is uniform throughout the domain. The bottom boundary is held at constant
16 pressure, while the top boundary is closed. The side boundaries in the subsurface are
17 closed, while the side boundaries in the surface layer are held at constant pressure to
18 generate the logarithmic velocity profile.

19 In the model system, CO₂ is being injected at the water table to model the arrival of
20 leaking CO₂ from a deep geologic sequestration site. The CO₂ migrates upwards through
21 the unsaturated zone and seeps out of the subsurface into the surface layer. We inject
22 pure water at a constant rate of 10 cm yr⁻¹ at the ground surface to model rainfall

1 infiltration. This rainfall infiltration is capable of transporting dissolved CO₂ from the
2 surface layer back into the subsurface as will be shown below. The subsurface part of
3 this system is a Cartesian version of the radial system we have studied earlier (Oldenburg
4 and Unger, 2003). We use the same leakage rate of 0.1% yr⁻¹ of an assumed 4 x 10⁹ kg
5 CO₂ sequestration site giving rise to a leakage rate of 4 x 10⁶ kg yr⁻¹. If we assume this
6 leakage occurs over 10⁴ m², the seepage flux is approximately 1.3 x 10⁻⁵ kg m⁻² s⁻¹. Here
7 we assume a 2-D system with no lateral dispersion ($D_{yy} = K_y = 0$), and we assume a
8 closed top boundary, both of which cause CO₂ concentrations to be larger than in a 3-D
9 system with a thicker surface layer. The neglect of lateral dispersion and 10-m surface-
10 layer height are consequences of the choice of test problem and not inherent limitations
11 of T2CA, which is in fact three-dimensional with no limits on domain height.

12 The surface-layer part of the system has porosity equal to unity and a logarithmic velocity
13 profile for neutral stability conditions that we specify by using variable permeabilities in
14 the layers above the ground surface as described in Section 4.1. We define a reference
15 velocity at an elevation of 10 m above the ground to be 1 m s⁻¹ and 5 m s⁻¹ to test two
16 different wind conditions. The simulation is run for six months allowing time for the
17 CO₂ to migrate upward through the unsaturated zone, and seep out of the ground where it
18 is advected and dispersed by wind in the atmospheric surface layer. The simulation is
19 isothermal at 15 °C.

20 Results of CO₂ mass fraction in the gas phase are shown in Figures 9a and 9b for wind
21 velocities of 1 m s⁻¹ and 5 m s⁻¹. As shown in the figures, concentrations of CO₂ are quite
22 high in the unsaturated zone because the CO₂ sweeps through the pores and displaces
23 existing soil gas with little chance for attenuation (Oldenburg and Unger, 2003). A sharp

1 gradient in concentration is maintained at the ground surface because of the large amount
2 of dilution afforded by the wind which advects air into the seeping CO₂ and carries it
3 downwind. Note that we have assumed zero background CO₂ concentration in the
4 system to examine the CO₂ added by the leakage and seepage processes. As shown in
5 Figures 9a, b, the CO₂ concentrations rise strongly in the subsurface, but the CO₂
6 concentrations in the surface layer due to this seepage flux and wind condition are
7 practically negligible. Indeed, Figure 9a shows that the concentrations increase by
8 approximately 0.0001 by mass fraction (~66 ppmv) just above the source area and far
9 less several meters above and downwind from it. Such concentration increases would be
10 easily detectable relative to a background CO₂ concentration of 375 ppmv ($\sim 5.7 \times 10^{-4}$
11 mass fraction), but would not be a health hazard (NIOSH, 1981). Dispersion is higher in
12 the 5 m s⁻¹ case than in the 1 m s⁻¹ case because K_z increases with friction velocity, and
13 because of the wind dilution effect. The concentrations in the surface layer are
14 essentially steady by $t = 6$ mos., whereas the concentrations in the subsurface associated
15 with the downward infiltration of rainwater containing dissolved CO₂ are still evolving.

16 Note further in Figures 9a and b the apparent subsurface dispersion of CO₂ to the right
17 (downwind) of the main subsurface plume. This CO₂ is re-entering the subsurface as a
18 dissolved component in infiltrating rainwater. The infiltration source is in the first row of
19 subsurface gridblocks, which obtain CO₂ from the surface-layer plume by gas-phase
20 diffusion. Although infiltration in the model is pure water, natural infiltrating rainwater
21 does have significant capacity to dissolve additional CO₂ relative to its CO₂ content when
22 in equilibrium with ambient atmosphere. Specifically, water in equilibrium with air with
23 375 ppmv CO₂ would contain approximately 0.6 mg CO₂ L⁻¹, whereas the solubility of

1 CO₂ in water at ground-surface conditions is approximately 1500 mg L⁻¹. Thus rain
2 water can dissolve additional CO₂ from high-concentration leakage or seepage plumes
3 and transport CO₂ downward as a dissolved component. The process of downward reflux
4 of CO₂ by water infiltration points out the need for coupled modeling approaches that
5 include interactions between the surface layer and subsurface that may be significant in
6 some situations.

7 Figures 9c and d show liquid saturation and mass fraction CO₂ in the liquid phase,
8 respectively. These results point out the multiphase and multicomponent aspects of the
9 model inherent to the TOUGH2 framework. Note the downward infiltration that occurs,
10 and the attenuating effect of CO₂ solubility in water infiltrating into the vadose zone.

11 Figure 10 shows the CO₂ gas-phase mass fractions at a receptor located at the ground
12 surface at $x = 645$ m (~100 m downstream from the source) for three different reference
13 wind speeds where a CO₂ mass fraction of 10^{-4} is approximately 66 ppmv CO₂. Once
14 again, these results demonstrate that dispersion increases with wind speed, resulting in
15 lower receptor concentrations of CO₂. Furthermore, this is a conservative estimate in that
16 actual areal sources with lateral dispersion would result in even lower CO₂ concentrations
17 for the same seepage flux. Although the results presented here are two-dimensional,
18 T2CA is a fully three-dimensional model although wind is required to be unidirectional
19 in the x -direction.

20

1 6. CONCLUSIONS

2 We have developed a simulation capability for coupled vadose zone and atmospheric
3 surface-layer advection and dispersion of CO₂ that may potentially seep from the ground
4 after leaking from geologic carbon sequestration sites. The purpose of such simulations
5 is to provide input to health, safety, and environmental risk assessments, as well as to
6 make specifications for instrumentation needs, and to design monitoring strategies that
7 can be used to verify carbon sequestration and ensure minimal health and environmental
8 risk. The approach we have taken for the dense gas CO₂ is to focus on the difficult-to-
9 detect cases of diffuse gas seepage where fluxes are small and surface-layer
10 concentrations are low. In these scenarios, dispersion in the atmospheric surface layer is
11 passive, and the steady logarithmic velocity profile can be used to approximate time-
12 averaged winds under conditions of neutral stability. Variable-K theory is used to
13 estimate atmospheric dispersion in T2CA.

14

15 Preliminary application of the method to a two-dimensional CO₂ leakage and seepage
16 scenario shows that while high concentrations of CO₂ can develop in the subsurface,
17 dispersion strongly attenuates the seepage plume in the surface layer. Our preliminary
18 simulation shows that while such seepage would be readily detectable by conventional
19 instrumentation which can detect in the ppmv range, the additional CO₂ would not
20 constitute a significant health or environmental hazard for the conditions studied. As
21 testimony to the need for coupled models, we observed that infiltration is capable of
22 bringing CO₂ back into the subsurface through dissolution into rainwater infiltrating into
23 the subsurface.

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Table 1. Properties of the 2-D model system.

Property	Value
<i>Subsurface</i>	
Permeability ($k_x = k_z$)	$1 \times 10^{-12} \text{ m}^2$
Porosity (ϕ)	0.2
Infiltration rate (i)	10 cm yr^{-1}
Residual water sat. (S_{lr})	0.1
Residual gas sat. (S_{gr})	0.01
van Genuchten (1980) α	$1 \times 10^{-4} \text{ Pa}^{-1}$
van Genuchten (1980) m	0.2
<i>Surface Layer</i>	
Friction velocity (u_*) for $u = 1 \text{ m s}^{-1}$	0.0869 m s^{-1}
Friction velocity (u_*) for $u = 3 \text{ m s}^{-1}$	0.261 m s^{-1}
Friction velocity (u_*) for $u = 5 \text{ m s}^{-1}$	0.434 m s^{-1}
Roughness length (z_0)	0.10 m
Reference velocity at $z = 10 \text{ m}$	1, 3, or 5 m s^{-1}

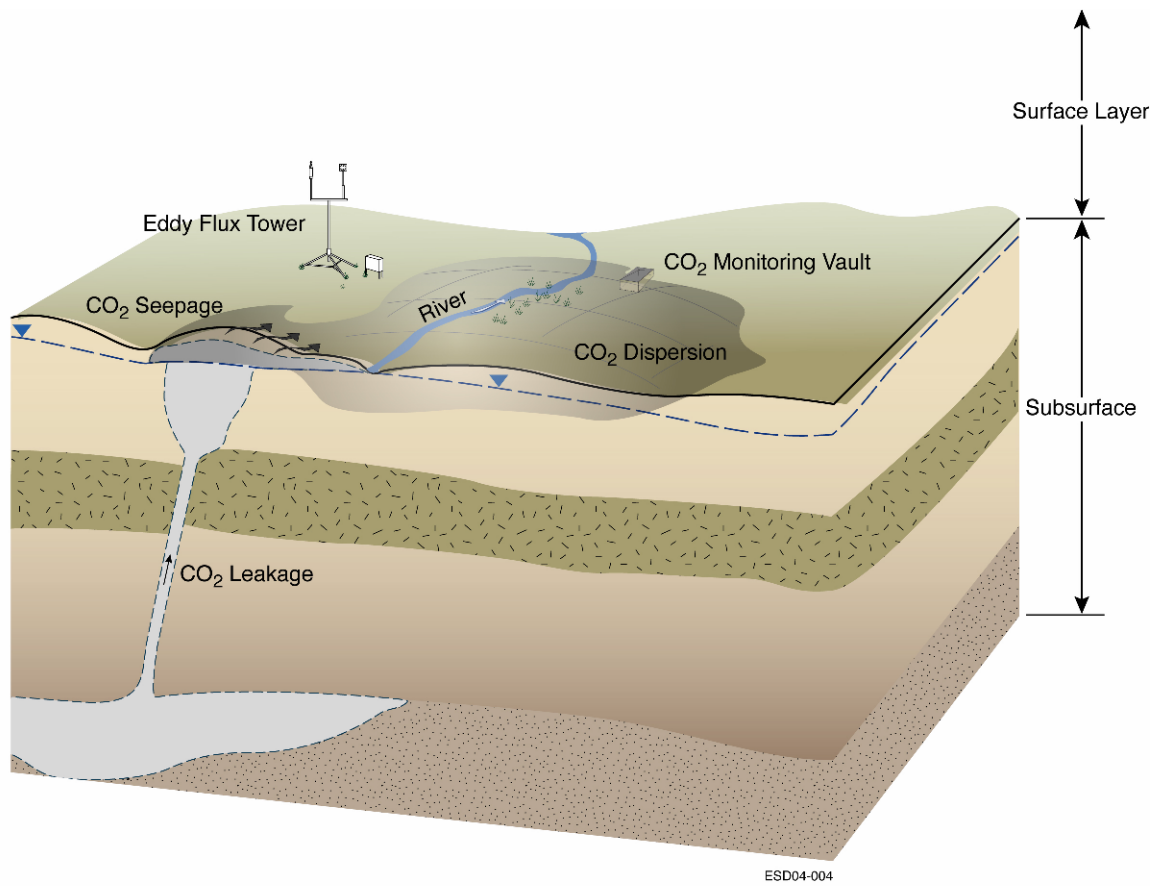


Figure 1. Sketch of unexpected leakage and seepage of CO₂ from a geologic carbon sequestration site showing the subsurface and (atmospheric) surface-layer regions, and eddy-flux tower and monitoring vault (not to scale).

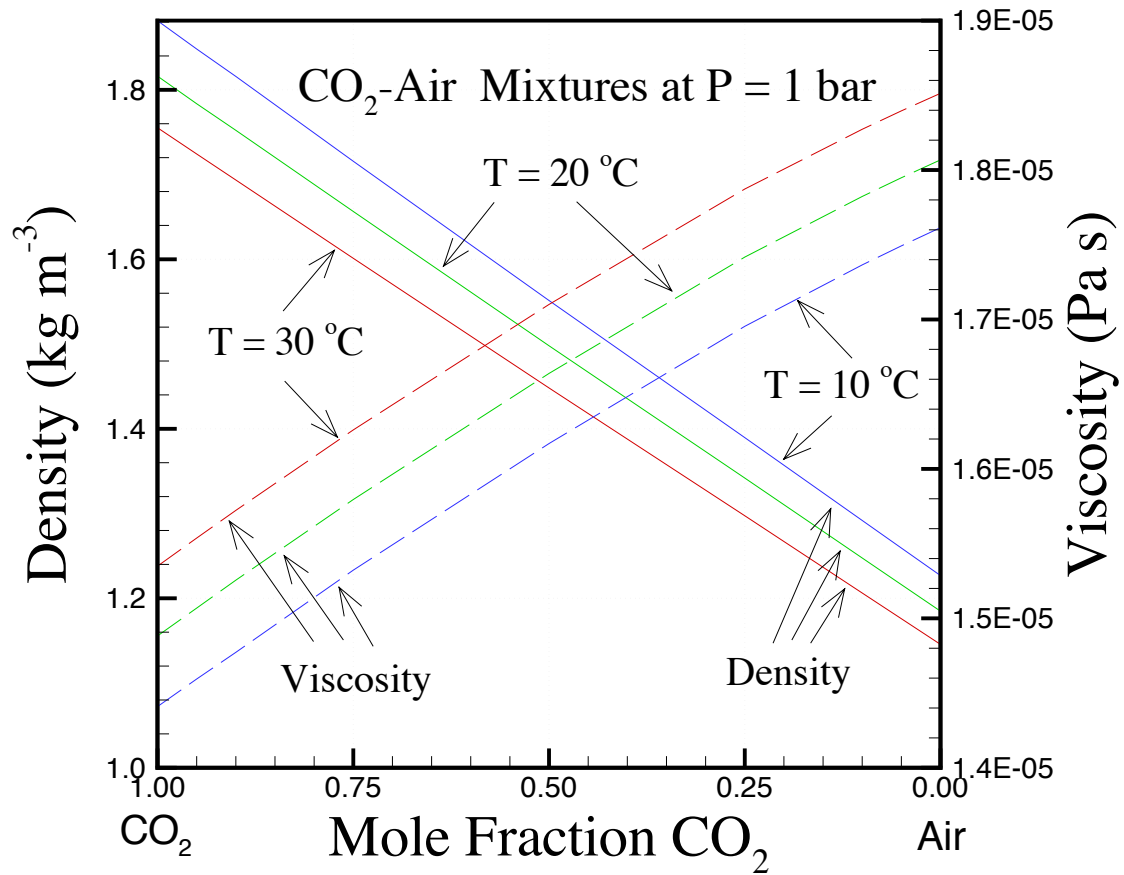


Figure 2. Mixture density and viscosity at 1 bar in the system CO₂-air showing higher density and lower viscosity of gaseous CO₂ relative to air.

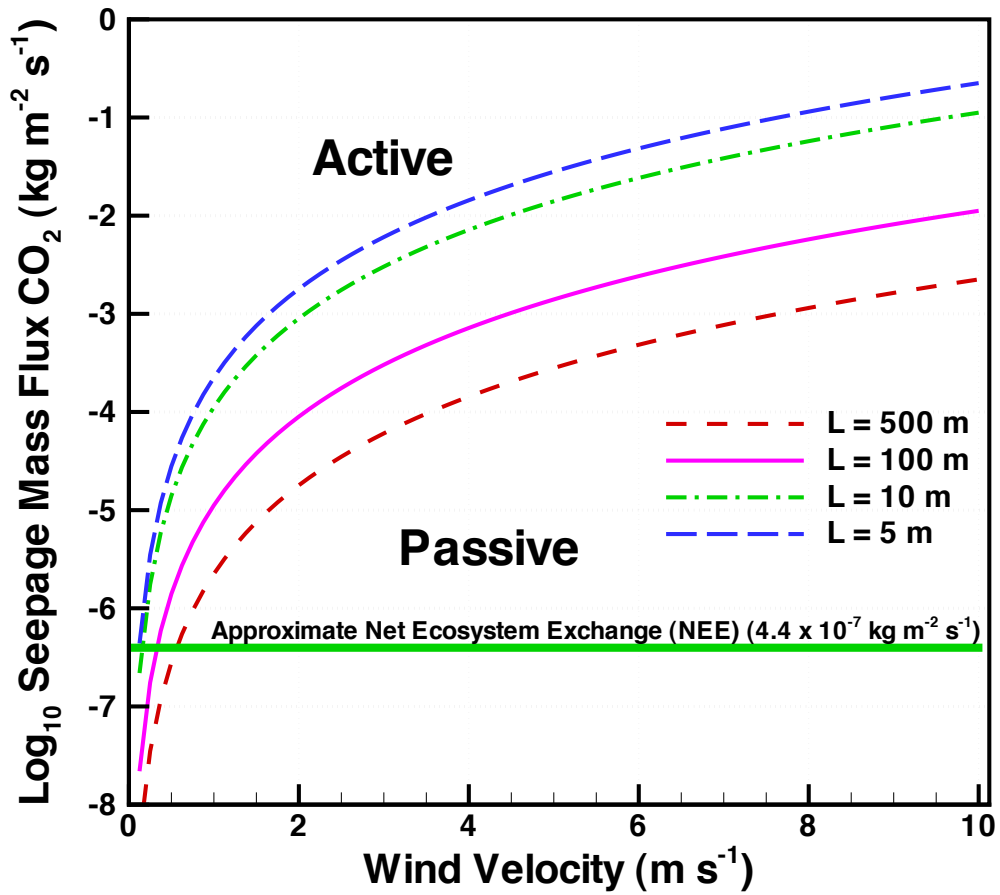


Figure 3. Correlation for density-dependent and passive dispersion in the surface layer as a function of seepage flux and wind velocity for four different characteristic source area length scales (L) (see Britter and McQuaid, 1988).

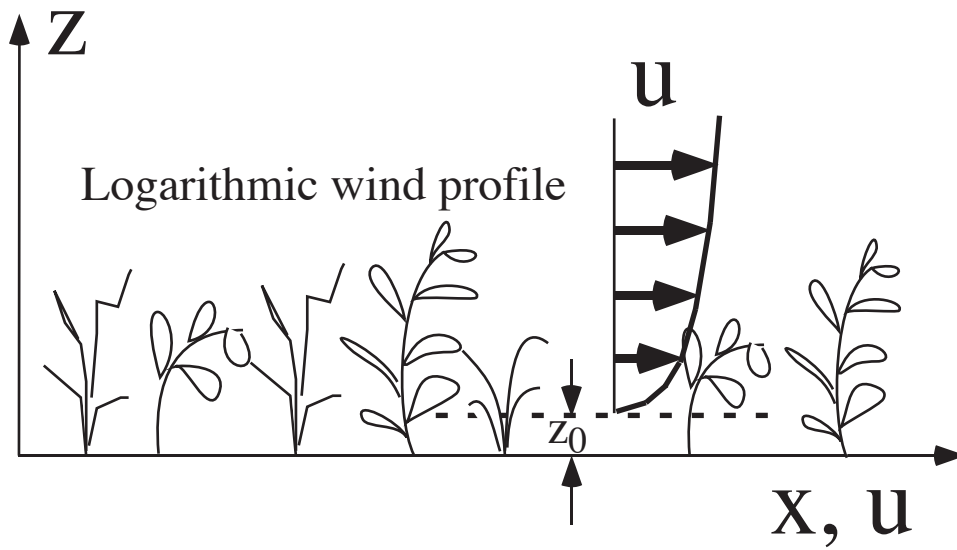


Figure 4. Schematic of the logarithmic velocity profile used to approximate time-averaged winds in the surface layer.

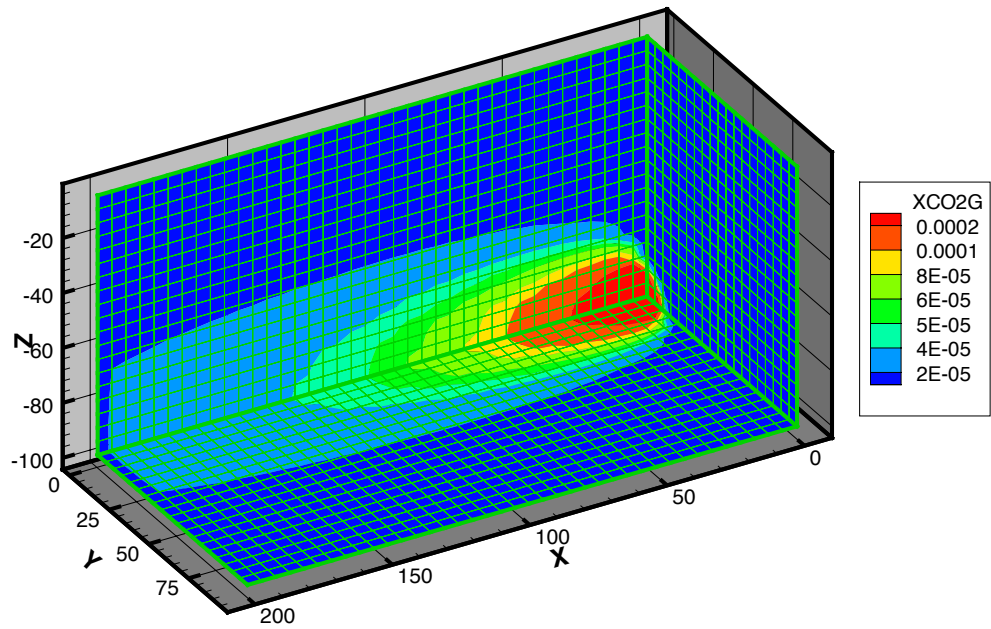


Figure 5. T2CA results of CO₂ concentration (kg CO₂ m⁻³ gas) for the 3-D Gaussian plume verification problem.

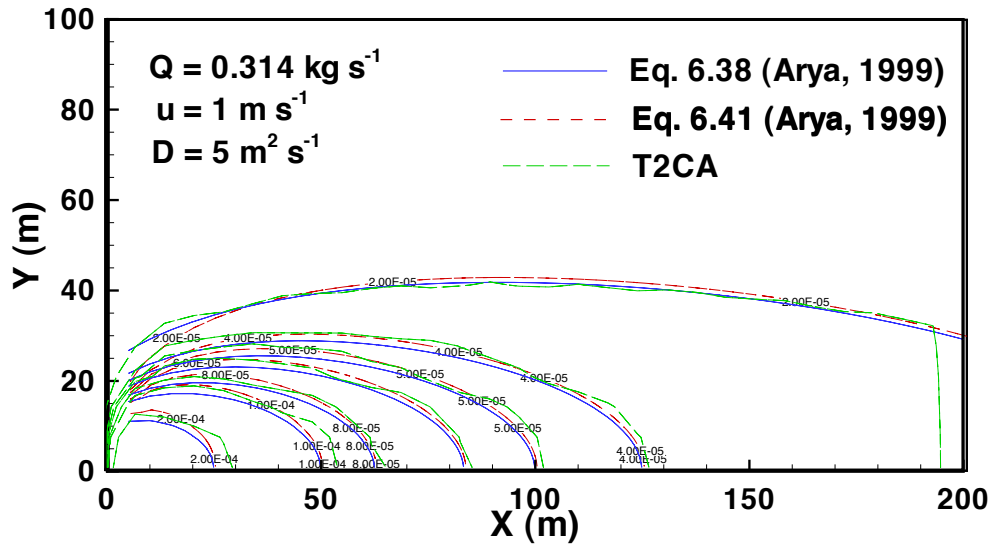


Figure 6. Comparison of T2CA results against analytical solutions for the 3-D Gaussian plume verification problem for the x - y plane.

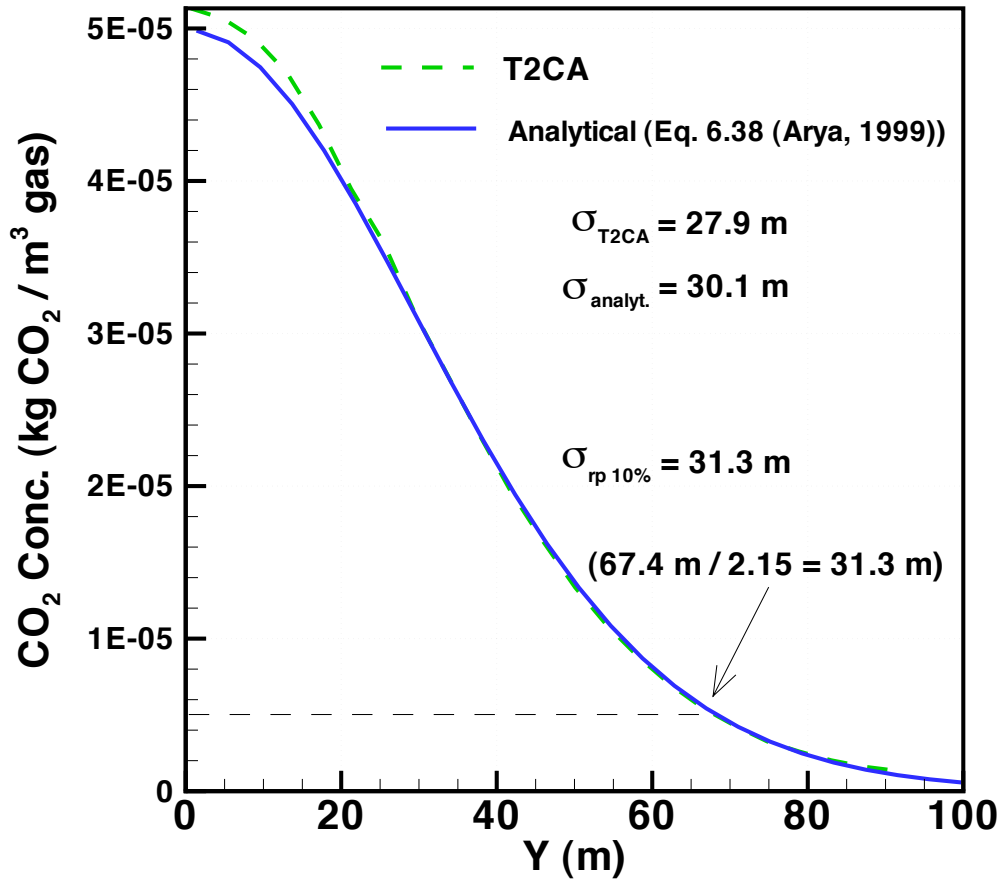


Figure 7. Comparison between T2CA results and analytical solution of the CO₂ concentration profile in the *y*-direction, with calculated standard deviations.

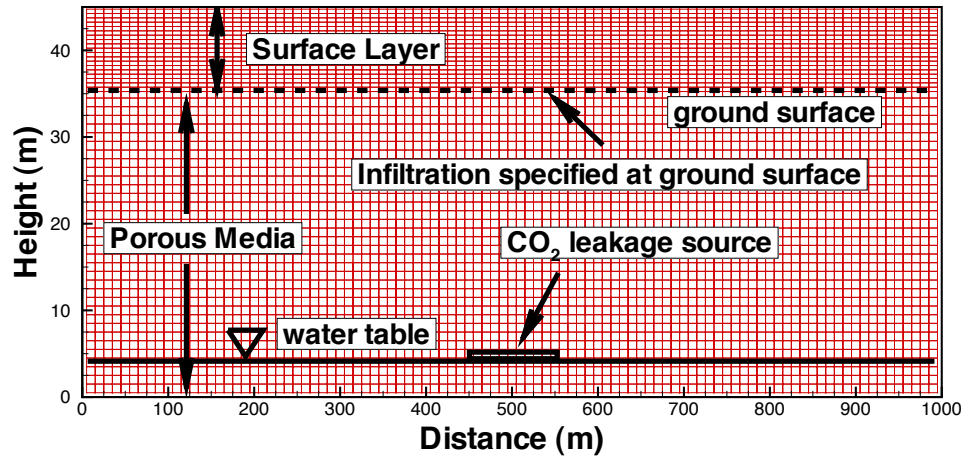


Figure 8. Mesh used in the 2-D coupled vadose zone and surface-layer model system.

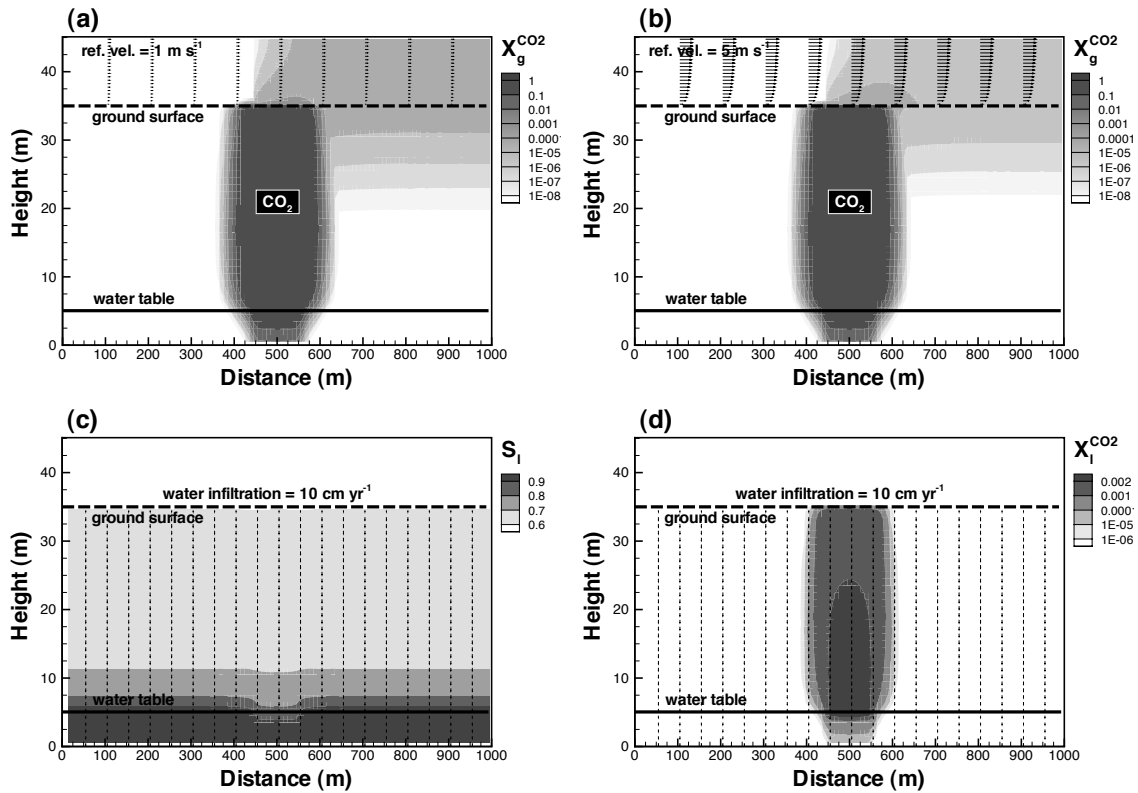


Figure 9. Gas phase mass fraction of CO_2 and gas velocity in the coupled subsurface-surface-layer model domain six months after CO_2 seepage begins for reference velocity of (a) $u = 1 \text{ m s}^{-1}$, and (b) $u = 5 \text{ m s}^{-1}$. Liquid saturation (c) and mass fraction of CO_2 in the liquid (d) with water velocity for infiltration of 10 cm yr^{-1} (largest water velocity vector $\sim 2 \times 10^{-8} \text{ m s}^{-1}$).

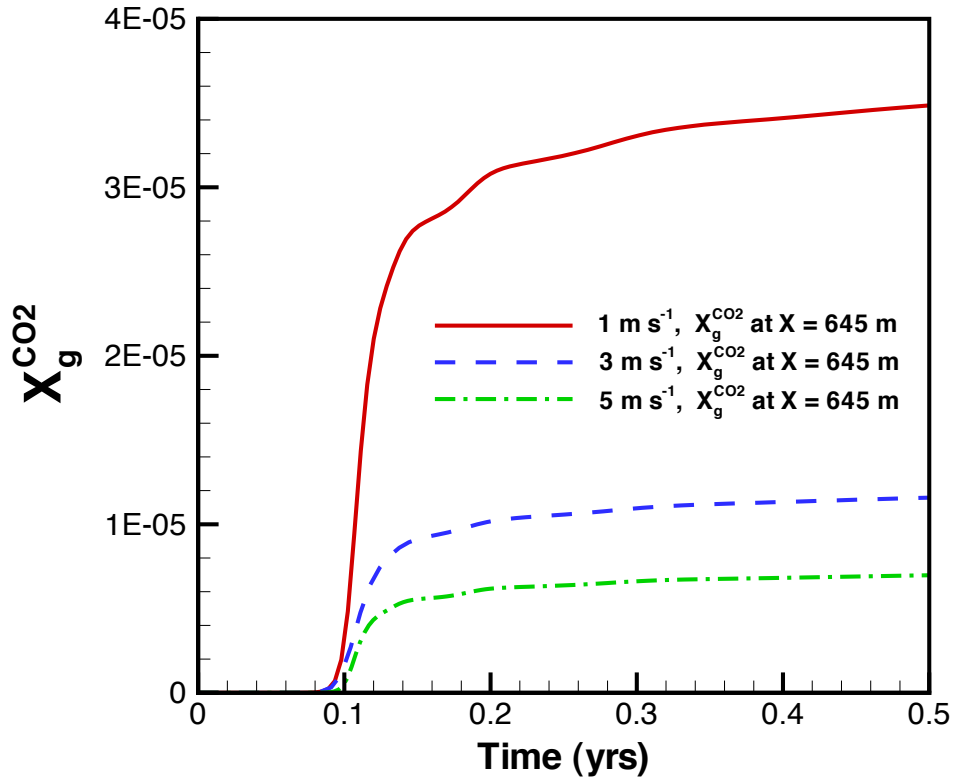


Figure 10. Mass fraction of CO₂ in the gas phase at a receptor located on the ground approximately 100 m downstream from the source ($x = 645$ m) for three reference wind velocities.