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1. Introduction

The geological storage of carbon dioxide (CO₂), which involves injecting large quantities of carbon dioxide underground, is likely to be an important tool for preventing greenhouse gases from entering the atmosphere [Baines and Worden, 2004; Schrag, 2007]. Past experience with the use of CO₂ for secondary oil recovery suggests that the migration of carbon dioxide within the Earth can be complicated, and can differ from the movement of injected water or the flow of hydrocarbons [Hoversten et al., 2003; Arts et al., 2004; White et al., 2004]. Due to the complexity of the movement of carbon dioxide within the Earth, and the desire to keep this greenhouse gas from migrating towards the surface and eventually reaching the atmosphere, there is a need to monitor the fate of the injected CO₂.

In many important settings, satellite-based geodetic techniques can fulfill the twin goals of long-term, cost-effective monitoring [Massonnet and Feigl, 1998; Burgmann et al., 2000]. Satellite-based surveillance can be less expensive, more frequent, and less invasive than other geophysical monitoring techniques such as seismic or electromagnetic methods. Interferometric Synthetic Aperture Radar (InSAR) can provide high spatial resolution (a few meters or tens of meters) and almost monthly measurements of surface deformation. Roughly speaking, InSAR utilizes the phase change of radar reflections off the Earth’s surface to measure minute changes in the position of the reflection points. Given the presence of radar reflectors of suitable quality, InSAR can be used to detect surface motion with an accuracy of a few millimeters. To date, InSAR has contributed significantly to the intermediate and long-term monitoring of ground motion associated with numerous phenomena, such as groundwater variations, geothermal production, earthquake-related strain, tunneling and mining, and oil and gas production [Massonnet and Feigl, 1998; Burgmann et al., 2000].

2. In Salah CO₂ Storage Project

We utilize InSAR observations gathered over a site of active CO₂ storage to image ground motion induced by the injected fluid volume. The injected carbon dioxide is associated with the In Salah CO₂ storage project located in Algeria [Vasco et al., 2008; Ringrose et al., 2009], one of only two existing large-scale sequestration efforts, the other being the Sleipner field under the North Sea [Arts et al., 2004]. In addition, there are projects in which carbon dioxide is injected into partially depleted oil reservoirs as a means of sequestration as well as enhancing oil recovery, as in the Weyburn project in Canada [White et al., 2004]. The In Salah project, which has been operational since 2004, gathers excess carbon dioxide that is present in natural gas extracted from three adjacent gas fields. The carbon dioxide is compressed, dehydrated, and transported to three horizontal wells, where it is injected into a 1800 to 1900 m deep saline formation, down-dip of the gas fields. The target formation for the storage of the CO₂ is twenty meters of Carboniferous sandstone with approximately 15% porosity and an estimated permeability of 10 mD [Ringrose et al., 2009]. The sandstone formation is part of a northwest trending anticline that defines the natural gas fields. The reservoir is overlain by more than a kilometer of interbedded shales which act as a barrier to flow. From 2004 to 2008 over 3 million tons of CO₂ have been injected into the formation.

3. Satellite-Based Monitoring

Following the initiation of injection at In Salah, Tele-Rilevamento Europa (TRE) and Lawrence Berkeley
National Laboratory acquired, processed, and analyzed satellite radar images from the European Space Agency’s (ESA) Envisat archive \[VASCO et al., 2008\] to evaluate InSAR’s potential for monitoring the fate of the injected CO$_2$. Two satellite paths, Track 65 and Track 294, repeatedly passed over the In Salah site, providing an irregular time sequence of 41 radar reflection images from July 12, 2003 through March 19, 2007 \[VASCO et al., 2008\]. The data associated with each satellite pass consist of a Frame, a dense grid of 20 m by 20 m pixels, covering an area of 100 km by 100 km. In our analysis we examine the backscattered radar signal and identify permanent scatterers \[Ferretti et al., 2001\]. These are objects at the Earth’s surface, a subset of the pixels within the Frame, some 300,000 in all, which return stable reflections for a given time sequence of radar images (Figure 1).

[6] Once the permanent scatterers are identified we construct corrections for atmospheric and orbital effects. Then we estimate changes in the distance between a reference point in space and the scatterers located on the Earth’s surface \[Ferretti et al., 2001\], the range change. The individual radar images are spaced roughly one to three months apart in time and provide a time series of the range changes associated with the CO$_2$ injection \[VASCO et al., 2008\]. For example, Figure 1 is an image of the range velocities of the 300,000 identified permanent scatterers. The velocities are computed by estimating the slope of a line fit to the range change time series of each permanent scatterer. There are observable decreases in range, of the order of 5 mm/year, associated with the three injection wells, corresponding to uplift. Note the variations in the pattern of range change over the labeled injectors in Figure 1.

**Figure 1.** InSAR range velocity measurements, in mm/year, indicating the changes in distance between points on the surface of the Earth and a reference point in space. The three CO$_2$ injection wells (KB-501, KB-502, and KB-503) are labeled in this figure and their trajectories are indicated by the solid lines. The open circles denote the surface locations of the three wellheads. The cross, which signifies the origin of the local coordinate system, is located at longitude 2.137° East and latitude 29.114° North.

**Figure 2.** In Salah layered elastic model. (a) Compressional and shear velocity model for the In Salah region, derived from well logs. The upper and lower boundaries of the reservoir interval are indicated by the two horizontal lines. (b) The range velocity at the surface due to the opening of a tensile crack at a depth of 1.8 km. The range velocity for a source within a homogeneous half-space (Uniform Moduli) is indicated by the filled squares while the crosses represent the range velocity for the layered model shown in Figure 2a (Layered Moduli).
For example, the range decrease over well KB-501 is elongated in a north-northwesterly direction, suggesting preferential flow. Above injection well KB-502 there are two lobes of range decrease, a pattern characteristic of the opening of a tensile feature such as a fault or fracture [Davis, 1983]. In addition to the range decreases over the injectors, there are range increases associated with subsidence due to gas production and subsidence associated with the erosion or the drying of various stream beds in the region.

4. Estimation of Reservoir Volume Change and Fault/Fracture Aperture Change

[7] Given the estimates of deformation provided by the InSAR data (Figure 1), our aim is to relate the ground motion to flow-related processes at depth. This is an example of an inverse problem in which observations made at the surface of the Earth are used to infer processes or properties at depth [Vasco et al., 2000]. We restrict our attention to an analysis of the two-lobed pattern of surface deformation above injector KB-502 (Figure 1). Injection started in April 2005 at a rate of over 280,000 cubic meters of CO\textsubscript{2} per day. Shortly afterward, the ground above the well began to rise at a rate of about 5 mm/year. As noted above, the two-lobed pattern of deformation evident in the range velocity estimates (Figure 1), is suggestive of the opening of a tensile feature at depth [Davis, 1983]. The existence of such a fault/fracture is supported by data from a seismic reflection survey and by logging information from well KB502 [Ringrose et al., 2009]. The fault/fracture is thought to be vertical or dip at a very high angle and to lie between the two lobes of range decrease, trending to the northwest. The exact vertical extent of the fault/fracture is not well constrained but it does intersect the reservoir interval. Because the reservoir is bounded above and below by lower permeability formations and contains natural gas, we expect that the twenty meters of Carboniferous sandstone comprising the reservoir will provide a stable conduit for the migration of the injected CO\textsubscript{2}. Due to these considerations we construct a model containing two components: the opening (aperture change) of an extended tensile feature representing a fault or a fracture, and volume change within the 20 m thick reservoir interval.

4.1. Assessing the Importance of an Accurate Elastic Earth Model

[8] Using logs from several wells in the area we are able to construct a 20-layer model of compressional and shear velocity for the region (Figure 2a). A numerical code is used to compute the displacement fields in this layered model [Wang et al., 2006]. The reservoir, which lies at a depth of around 1.8 km, is situated in a low velocity zone (Figure 2a). This fact turned out to have a significant impact on the calculated surface deformation associated with a given tensile source.

[9] An example calculation shows that the opening of a vertical tensile crack in a low velocity zone produces range velocity variations significantly different from those associated with a homogeneous half-space (Figure 2b). In the example shown in Figure 2, which is for illustrative purposes only, the fracture lies at the reservoir depth of 1.8 km, is 4 km long, and 100 m in vertical extent and opens by 5 cm. In Figure 2b we plot the range velocity along a line transverse to the plane of the tensile crack. Range velocities were computed for the tensile source in two different elastic models: a uniform half-space and the layered model (Figure 2a). While both models display the characteristic two-lobed pattern of a tensile fracture, the range change for the uniform elastic model (Uniform moduli) is very different.
from that of a 20 layer elastic model (Layered moduli). The height and spacing of the lobes varies notably for the two models and the uniform model has a significant peak that is not present in the layered model. As an aside, we note that the bi-lobed pattern in Figure 2b is asymmetric because range change is a projection of the displacement vector onto a vector that points from the observation point to the location of the satellite [Burgmann et al., 2000]. The fact that the variation of elastic properties with depth can influence the surface deformation for a given source model has been noted by others [Chinnery and Jovanovich, 1972; Savage, 1987; Hearn and Burgmann, 2005]. However, the dramatic change when a tensile source lies within a low velocity zone (Figure 2b) surprised us and does not appear to be cited in the literature.

4.2. Inverting the Observed Range Velocities

[10] Having settled upon the major constituents of our source model and the elastic structure of the overburden, we now solve the inverse problem. That is, we use the range change observations to obtain estimates of the reservoir volume change and the opening of the fault/fracture. The reservoir layer geometry is fixed by the position of its boundaries, determined by 3D seismic data [Ringrose et al., 2009]. The overall characteristics of the planar fault/fracture are determined from the range change observations themselves. We find that a vertical fault/fracture model provides a good fit to the range changes. The final geometry of the fault/fracture model is indicated in Figure 3. In Figure 3a we plot the northwest trending surface trace of the vertical fault/fracture. The planar fault model is centered at a depth of 1.8 km.

[11] Both the reservoir layer and the fault/fracture plane are sub-divided into 8 by 8 grids of cells which can undergo fractional volume change or aperture change, respectively. Aperture change is opening of the fracture due to the injected fluid volume, while the fractional volume change is the volumetric expansion of the porous sandstone comprising the reservoir interval. We extend the fault plane above and below the reservoir center line by 80 m in order to model any possible vertical propagation of this feature. An iterative least squares solver is used to find the reservoir layer volume expansions and the fault/fracture plane aperture changes which best fit the range change observations [Vasco et al., 2000].

[12] The resulting fault/fracture plane aperture changes and reservoir fractional volume changes are shown in Figure 3. The fractional volume changes in Figure 3a indicate that flow within the reservoir layer was confined to the region immediately surrounding the injection well. The aperture changes on the fault/fracture plane are shown in Figure 3b, suggest that the fluid has migrated several kilometers to the northwest, 40 m above and below the reservoir. Thus, the fault/fracture zone appears to be acting as a high conductivity pathway for the injected fluid. Note that the fractional volume and aperture changes relate fundamentally to pressure changes and do not necessarily indicate the exact location of the CO$_2$. The aperture change may be indicative of the cumulative opening of a number of sub-parallel fractures. As indicated in Figure 4, using the two-component model shown in Figure 3, and the numerical code of Wang et al. [2006], we are able to fit the overall features of the range velocity data including the two-lobed pattern.

5. Conclusions

[13] This study illustrates that satellite-based observations can be used to monitor the fate of carbon dioxide injected...
deep within the Earth. An injected mass of 3 million tons of CO\(_2\) gives rise to surface deformation of a few millimeters per year. Detailed images of this surface deformation, provided by InSAR data, suggest preferential flow away from the injection wells and the opening of a tensile feature at depth. The tensile feature coincides with a seismically imaged fault intersecting the reservoir. Though the results are preliminary, our work clearly indicates that, when an accurate elastic Earth model is used, it is possible to fit the observations with volume and aperture changes that are essentially at the reservoir level, a depth of 1.8 km. That is, we do not require fluid flow to a depth significantly above the reservoir in order to fit the InSAR data.

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References


