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Structural connection with predetermined discrete variable friction forces

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ABSTRACT

This paper presents a simple and practical structural connection able to develop predetermined discrete variable friction forces at target design displacement levels. The innovative connection is termed Modified Friction Device (*Modified FD*). Modified FDs are used to transfer the seismic induced horizontal forces from the floors to the core wall seismic force-resisting system of a building. The schematics of the physical embodiment of the Modified FD are presented. The components and the assembly of the Modified FD are discussed. The mechanics of the Modified FD are explained. Results from static structural analyses of two types of finite element models of the Modified FD are presented. The first model is developed using solid finite elements and it is used to assess the expected kinematics and the expected force-displacement response of the Modified FD. The second model is developed using a truss finite element and it can be used to efficiently simulate the force-displacement response of the Modified FD in numerical earthquake simulations of structural systems. The force-displacement response of the Modified FD computed using a numerical earthquake simulation of an eighteen-story reinforced concrete core wall building model is presented. The seismic response of the building model with Modified FDs is compared with the seismic response of the building model with monolithic connections and the seismic response of the building model with friction devices with constant friction forces. The results presented in this paper show that it is possible to develop a simple and practical structural connection with predetermined discrete variable force-displacement response to limit the seismic induced horizontal forces transferred between the floors of the flexible gravity load resisting system and the core wall piers in high-performance earthquake resilient buildings.

1. Introduction

1.1. Need for earthquake resilience

In February 2011, significant earthquake events occurred in Christchurch, New Zealand. One hundred and eighty-two fatalities and total damage of 18 billion US dollars were reported [1]. After the earthquake events, approximately 1240 buildings were demolished in the central city of Christchurch [2]. For five years, from 29 March 2011 until 18 April 2016, the Canterbury Earthquake Recovery Authority (CERA) led and coordinated the response and recovery efforts. This earthquake event is one out of the 905 large earthquakes reported from 1901 until 2015 [1]. The CRED/OFDA International Disaster Database from Université Catholique de Louvain, Brussels, Belgium [1] provides annual data related to the total deaths, the total damage, and the number of large earthquakes. Tsampras (2016) [3] analyzed the data and provided a plot of their cumulative normalized values as shown in Fig. 1. Fig. 1 also shows the normalized cumulative frequency of appearance of the word "*Resilience*" (defined in the following section) in the English corpus of Google Ngram between 1900 and 2008 [4]. The reported annual total number of large earthquakes was higher between 1980 and 2015 compared to previous years, possibly because of improved data collection. The word *Resilience* appeared more often in the literature during the same period of years compared to past years. The reported annual total damage was higher between 1980 and 2015 compared to past years, although it is possible that damage existed but was not included in the database [1]. Finally, between 1980 and 2015, the reported annual total deaths were significant compared to the past years. One might expect the reported annual total number of deaths and total damage to reduce over time considering the advancement of engineering knowledge and practice. However, the high concentration of population in earthquake-prone regions (e.g., the population in California doubled from 1960 to 2000 and continues to increase [5]) and the growth of infrastructure may explain the observed trend. Considering the above observations, it can be concluded that the data imply an increasing need for earthquake resilience.

1.2. US National earthquake resilience

US National earthquake resilience is one of the priorities of the National Earthquake Hazards Reduction Program (NEHRP) [6,7]. Accord-

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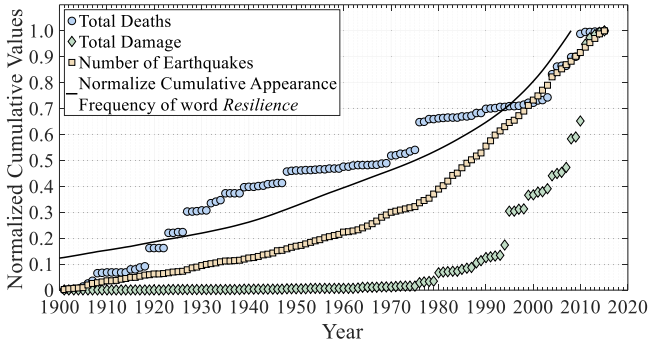

Fig. 1. Normalized cumulative annual total deaths, total damage, number of large earthquakes, and appearance frequency of the word *Resilience*.

ing to the National Research Council of the National Academies [8], "*A disaster-resilient nation is one in which its communities, through mitigation and pre-disaster preparation, develop the adaptive capacity to maintain important community functions and recover quickly when major disasters occur*". McAllister et al. [9] defined community resilience as "*the ability to prepare for anticipated hazards, adapt to changing conditions, and withstand and recover from disruptions*". The same authors stated that "*Even if a community enforces and adopts all current codes and standards, the performance of the built environment is not expected to result in a resilient community. This is because prescriptive and performance requirements in current codes and standards primarily focus on life safety objectives for buildings and transportation, and on reliability for electric and water*".

Designing individual buildings to recover at a functional level promptly after a strong earthquake event is required to contribute to community resilience and, as a result, enhance the national earthquake resilience. Individual buildings can be designed to return to a target functionality state after a given period if resilience-based design methods are used [7]. High-performance building systems can be utilized to mitigate the expected damage in the structural and non-structural components. In 2015, the Building Seismic Safety Council recommended research to advance the state of the art in earthquake-resistant building design [10] and identified issues in the current procedures used for the analysis and design of buildings. FEMA published issues and research needs related to the future development of the NEHRP Provisions and seismic design methods [11]. Key issues are associated with the "*Specific performance objectives and associated design criteria for performance beyond current code*" and provisions associated with "*better-than-code*" structural systems. Examples of "*better-than-code*" structural systems include buildings with components in their seismic load path that inherently can be designed to achieve high seismic performance compared to conventional building systems.

1.3. Uncertainty in seismic response of buildings and potential earthquake damage

The design of conventional earthquake-resistant building systems is associated with uncertainty in the prediction of their seismic response. This uncertainty is a result of the variability in the earthquake ground motions, and the variability in the structural characteristics and their evolution in time, which in turn affects the nonlinear response of the building components [12–14]. More specifically, the variability in the seismic response of structural connections can be high due to the complex interactions resulting from the need to preserve kinematic compatibility between structural components. For example, the framing interaction between the floor diaphragms and the seismic force-resisting systems may lead to damage of the connection [15] that results in uncontrolled transfer of forces. Because of this uncontrolled response, the seismic induced horizontal forces in the floor diaphragms can be large relative to the floor diaphragm strength and may lead to a non-ductile response of the diaphragms [16]. The development of excessive seismic induced inertial forces can also produce inelastic responses and significant damage to the seismic force-resisting system [17,18]. More specifically, the loss of the ability of the connections of diaphragms to transfer forces to the seismic force-resisting system could lead to local collapse of the floor or complete collapse of the building [19–21]. After the 2010–2011 Christchurch earthquakes, excessive damage and collapse of floor diaphragms were attributed to inadequate integrity of the load path, underestimation of seismic-induced horizontal forces, and poorly understood interactions between floor diaphragms and walls, supporting beams, and reinforced concrete moment frames [22–24]. The damage repairs required after the 2010–2011 Christchurch earthquakes highlighted the need for the development of low-damage high-performance earthquake-resilient seismic force-resisting systems [25,26].

1.4. High-performance buildings and the effect of higher modes in the total dynamic response of buildings

Kelly et al. [27,28], inspired by the bridge piers of the 200 ft high South Tangitikei railway bridge, provided a sketch of a "stepping wall" which acts as the seismic force-resisting system of the structure. This stepping wall has energy absorbers to control the response of the structure. Damage is concentrated on the energy absorbers that could be replaced after a strong ground motion. Since then, research has been conducted to develop seismic force-resisting systems with low post-earthquake damage and replaceable structural components. More specifically, researchers have developed post-tensioned moment-resisting frames [29–34], rocking structural wall systems [35–45], and rocking frame systems [46–51]. Summaries of high-performance earthquake-resilient seismic force-resisting systems developed to mitigate the damage of structural and nonstructural components are provided in the following references [52–55]. Alavi and Krawinkler showed that strengthening moment-resisting frames with walls that are able to pivot at their base instead of rocking mechanism can reduce the drift demands in a building [56]. Mar [57], Wada et al. [58], Qu et al. [59], and Janhunen et al. [60] presented examples of buildings that use vertical seismic force-resisting systems with rocking or pivoting base mechanism that prevents the localization of the story drift demand at a particular story in a frame building. "Strongbacks" or "spines" with a pivoting base mechanism have also been used in addition to energy dissipation mechanisms to resist the seismic induced horizontal forces, prevent the localization of the story drift demand at a particular story in a frame building [61–65], and limit the floor accelerations [66,67]. Fig. 2 shows sketches of example planar wall buildings with (a) flexural inelastic base mechanism, (b) rocking base mechanism, and (c) pivoting base mechanism. The sketch of the system with the pivoting base mechanism is based on the system proposed by Wada et al. [58].

The nonlinear response of the vertical elements of the seismic force-resisting system can act as a "cut–off" mechanism that may limit the floor accelerations and, as a result, limit the seismic induced horizontal inertial forces [68,69]. Even when the ductile nonlinear response of the seismic force-resisting system occurs, high floor accelerations may be observed, due to the uncontrolled forces transferred between the floors and the vertical elements of the seismic force-resisting system and the amplified response of second and higher modes [70]. Studies of buildings with seismic force-resisting systems that develop a flexural inelastic base mechanism (e.g., flexural-dominated reinforced concrete structural walls), a rocking base mechanism (e.g., rocking structural walls or controlled rocking braced frames), or a pivoting base mechanism show that high floor accelerations due to the contribution of the second-mode and higher-mode response in the total dynamic response (termed higher-mode effects) can be expected [46,52,71–74].

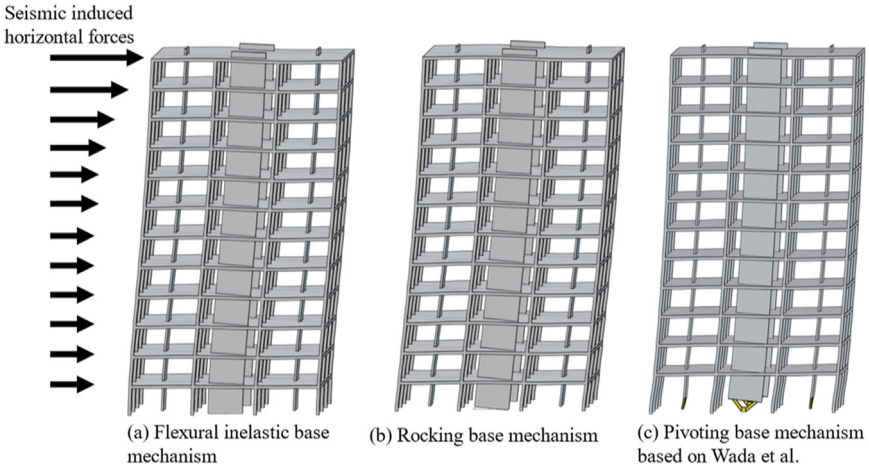

Fig. 2. Example planar wall buildings with (a) flexural inelastic base mechanism, (b) rocking base mechanism, and (c) pivoting base mechanism. The sketch of the system with the pivoting base mechanism is based on the system proposed by Wada et al..

1.5. Methods to limit the higher-mode effects

Christopoulos and Zhong provided a review of the current state-of-the-art and state of research pertaining to the understanding, estimation, and mitigation of higher-mode effects on the seismic response of tall and slender RC structures [52]. To limit the higher-mode effects in high-rise structural wall buildings with flexural inelastic base mechanism, Panagiotou et al. [75] developed the dual-plastic hinge design concept which introduces a second plastic hinge along the height of the structural wall. To control the higher-mode effects in rocking frames, Wiebe et al. [73,74] proposed the use of multiple rocking mechanisms above the rocking base mechanism.

Practical force-limiting connections have been developed with goal to limit the seismic induced horizontal forces transferred from the floors to the vertical elements of planar seismic force-resisting systems in earthquake-resistant buildings and limit the higher-mode effects [3,76–84]. A force-limiting connection consists of a friction device or a buckling-restrained brace and low-damping rubber bearings. The force-limiting connections are designed to accommodate the seismic induced three-dimensional kinematic requirements between floors and planar seismic force-resisting systems. The low-damping rubber bearings provide out-of-plane stability to the planar walls of the seismic force-resisting system and post-elastic stiffness to the force-limiting connections. The post-elastic stiffness in the force-limiting connections limits the seismic induced displacement of the floors relative to the planar seismic force-resisting system. Fig. 3 shows a force-limiting connection that consists of a friction device and low-damping rubber bearings installed in an example building with rocking walls [79,80]. The seismic response of buildings with force-limiting connections between gravity load resisting systems and reinforced concrete planar walls [3,76–79,81], planar rocking walls [79,80,82–84], and self-centering concentrically braced steel frames [3,84] has been studied. The use of force-limiting connections in these buildings (1) limits the seismic induced force and acceleration responses, (2) reduces the variability in the force and acceleration responses due to the ground motion variability, and (3) mitigates the effects of higher-mode responses on the dynamic response of buildings [77]. Similar observations have been made for the seismic response of buildings with dissipative floor connectors between the gravity load resisting system and steel concentrically braced frames [85]. The dissipative floor connectors consist of rubber bearings and a friction device [86].

1.6. Friction-based force-limiting connections in core wall buildings

Friction devices can be designed to be axially stiff, compact, and easy to manufacture and assemble. The design of friction devices is not limited by strain requirements similar to the strain requirements used in the design of metallic yielding devices. However, the friction force generated by a friction device depends on the materials used in the frictional interface, the sliding velocity, the cumulative sliding, the dwell time, and the manufacturing tolerances of the components of the friction device [79]. If properly designed, friction devices can remain undamaged during earthquakes, and they can be reused. Friction devices have been used in various structural applications. Clark et al. (1973) presented test results for a static load control friction device intended to limit the effect of differential settlement that occurs at foundations [89]. Researchers also used friction devices for energy dissipation in various types of earthquake-resistant structures, such as bridge structures [90], precast concrete structures [37,91–94,94–104], wall pier coupling beams [105,106], steel braced frames [107–116], steel moment resisting frames [117–123], self-centering moment resisting frames [33,124–128], and rocking timber shear walls [129–131]. Friction dampers [132–138], negative stiffness friction dampers [139,140], and self-centering braces with friction-based energy dissipation [141–145] have been developed and tested, as well.

The reinforced concrete core wall system is a widely used seismic force-resisting system for tall buildings because of its high lateral stiffness and its capacity for dissipating energy [146–151]. In addition to reinforced concrete, core walls can also be formed using cross-laminated timber structural walls [152] or concrete filled composite plate structural walls [153–155]. In contrast to planar seismic force-resisting systems that are not stable out-of-plane if they are not braced, core walls are stable without lateral bracing. In the core wall system, the wall piers are typically connected by reinforced concrete coupling beams along the height of the structure [156]. The core wall system is designed in a way that the nonlinear inelastic mechanism takes place at the coupling beams and at the base of the walls, with the rest of the structure designed to remain linear elastic [156]. Similar to buildings with planar seismic force-resisting systems, the inelastic response at the core wall base reduces the first mode response. However, the higher-mode effects are not reduced by the inelastic response at the wall base [157] and they may amplify the seismic induced story shear forces and floor accelerations.

Force-limiting connections between the floors of the flexible gravity load resisting system and the stiff core wall could be used to mitigate the higher-mode effects on the dynamic response of tall buildings and contribute to the accelerated post-earthquake recovery of these buildings to a target level of functionality. However, the force-limiting connections developed for buildings with planar walls cannot be used in buildings with core walls. The reason is that the three-dimensional kinematic requirements in force-limiting connections between the floors and the core wall are different from the three-dimensional kinematic require-

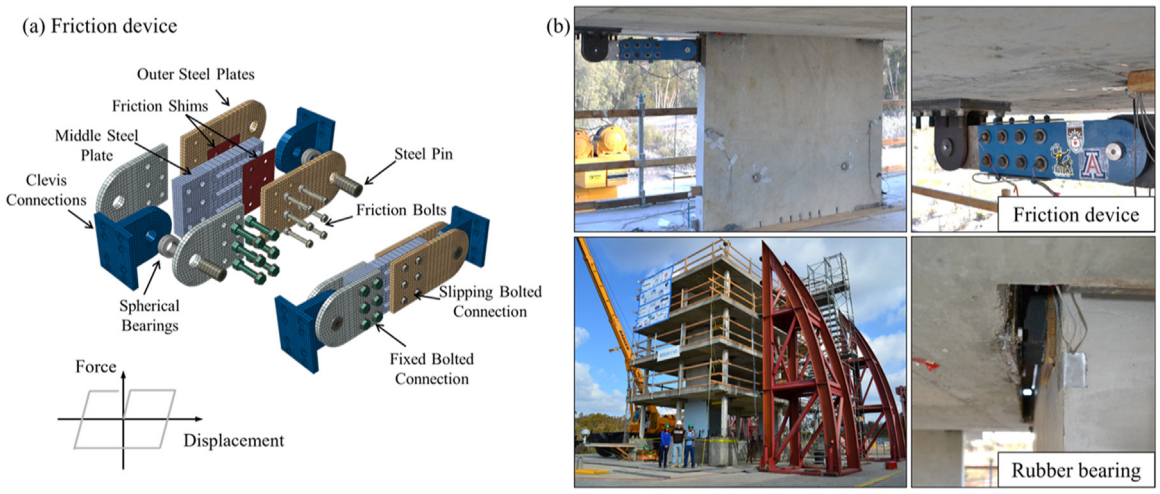

Fig. 3. Force-limiting connections between floors and planar seismic force-resisting systems are able to limit the contribution of higher-mode responses in the total dynamic response of the building and effectively reduce the variability in the seismic response of buildings due to the ground motion variability. (a) Friction device developed for force-limiting connections [79,87]. (b) Example of force-limiting connections in a building with planar rocking walls [79,80,88].

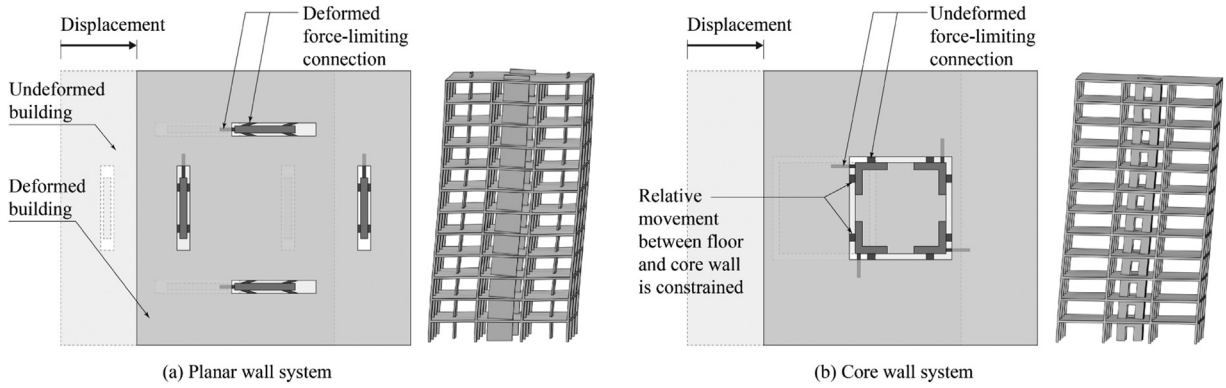

Fig. 4. In contrast with the planar wall system, the relative movement between the floors and the core wall system is constrained by the rubber bearings. The planar wall system is shown in (a) and the core wall system is shown in (b).

ments in force-limiting connections between floors and planar walls. The high stiffness of the rubber bearings under compression would constrain the relative movement between the floors and the core wall, making the force-limiting connection ineffective, as shown schematically in Fig. 4. In the already developed force-limiting connection for planar wall buildings, the functions of rubber bearings are (1) to provide out-of-plane stability to the planar walls and (2) to provide post-elastic stiffness to the force-limiting connection to prevent the potentially excessive connection deformation. Shake-table experimental seismic simulations of a half-scale, four-story reinforced concrete flat-plate structural wall structure with force-limiting connections conducted at the NHERI experimental facility at UC San Diego [158] showed that pounding of the slabs and the planar walls is expected at the maximum-considered-level of earthquake ground motion [80,88]. As a result, rubber bumpers are required to transfer the pounding forces. The rubber bumpers are used in addition to the friction devices and the low-damping rubber bearings. The use of conventional friction devices with constant force transferred between the floors of the flexible gravity load resisting system and the stiff core wall without the use of low-damping rubber bearings and bumpers would result in large displacement of the floor relative to the core wall and potentially uncontrolled pounding forces at the maximum-considered-level of earthquake ground motions.

Considering the above-mentioned limitations related to the use of the already developed force-limiting connections in core wall buildings, there is a need for a structural connection that can develop predetermined forces at target design displacement levels with goal to limit the force and acceleration responses of core wall buildings without inducing excessive displacement demand in the connections.

2. Scope of research

This paper presents a simple and practical structural connection able to develop predetermined discrete variable friction forces at target design displacement levels. As a result, a performance-based discrete variable limiting force-displacement response can be achieved. The innovative connection is termed Modified Friction Device (*Modified FD*). The term Modified FD is used to indicate that a positive effective post-elastic stiffness is achieved through the discrete variable friction force instead of the constant friction force expected in conventional friction devices. In the following sections, the schematics of the physical embodiment of the Modified FD are presented. The components and the assembly of the Modified FD are discussed. The mechanics of the Modified FD are explained. Results from static structural analyses of two types of finite element models of the Modified FD are presented. The first model is developed using solid finite elements and it is termed *Solid Model*. The Solid Model is used to assess the expected kinematics and the expected force-displacement response of the Modified FD. The second model is developed using a truss finite element and it is termed *Truss Model*. The Truss Model can be used to efficiently simulate the force-displacement response of the Modified FD in numerical earthquake simulations of

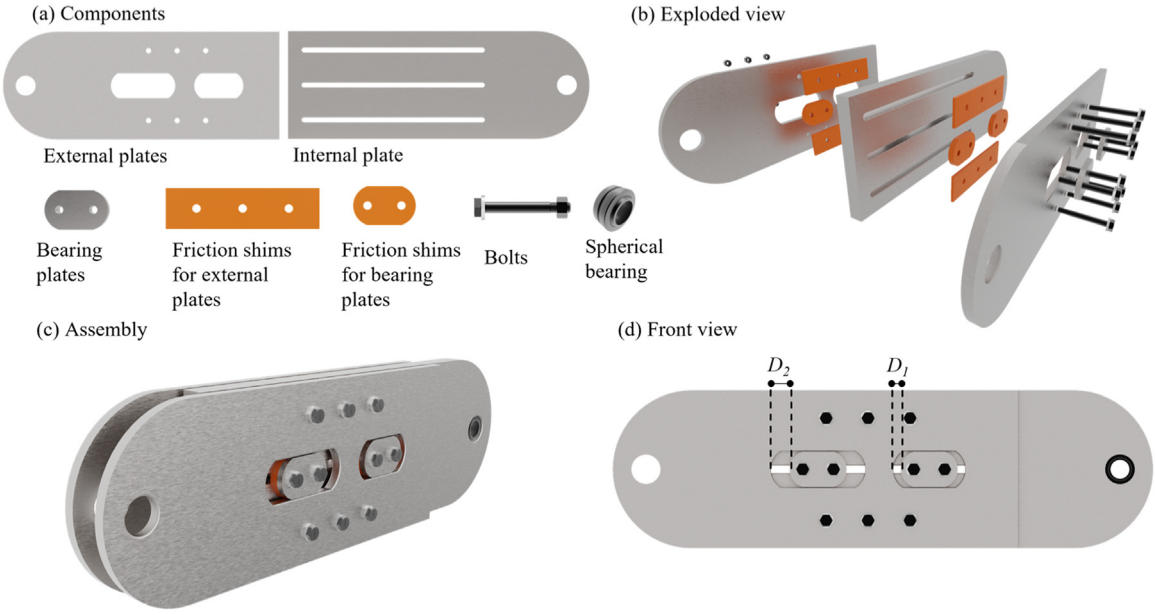

Fig. 5. Schematics of the Modified FD (a) components, (b) exploded view, (c) assembly, and (d) front view with initial gap dimensions D_1 and D_2 between the bearing plates and the slots in the external plates.

structural systems. The force-displacement response of the Modified FD computed using a numerical earthquake simulation of an eighteen-story reinforced concrete core wall building model is presented. The seismic response of the building model with Modified FDs is compared with the seismic response of the building model with monolithic connections and the seismic response of the building model with friction devices with constant friction forces. The results presented in this paper show that it is possible to develop a simple and practical structural connection with predetermined discrete variable force-displacement response to limit the seismic induced horizontal forces transferred between the floors of the flexible gravity load resisting system and the core wall piers in high-performance earthquake resilient buildings.

3. Modified FD

3.1. Components and assembly

Fig. 5 shows a sketch of the components, the exploded view, the assembly, and the front view of the Modified FD. The Modified FD consists of an internal plate, two external plates, four bearing plates, four friction shims between the external plates and the internal plate (termed friction shims for external plates), four friction shims between the bearing plates and the internal plate (termed friction shims for bearing plates), ten structural bolts with flat washers and nuts, and a spherical bearing. The number of bearing plates, friction shims, and bolts can be adjusted to achieve the variations of the predefined discrete variable friction force-displacement response discussed in the following sections. The end clevises used to attach a Modified FD on the floor and the seismic force-resisting system are not shown in Fig. 5. The plates and the clevises are made of structural steel ASTM A572 Grade 50. The friction shims are made of composite material similar to the laminated glass fiber fabric with graphite composite materials [159] used in friction devices developed for force-limiting connections [79].

Pretension load is applied to the bolts to clamp the external plates, the bearing plates, the friction shims, and the internal plate. The bolted components create the assembly of the Modified FD. Friction interfaces are established in the contact surfaces between the internal plate and the friction shims. The bolt load results in normal force on the friction interfaces between the friction shims and the internal plate. The friction shims for the external plates are not expected to move relative to the external plates. The friction shims for the bearing plates are not expected to move relative to the bearing plates. The slots in the internal plate allow the longitudinal motion of the friction shims, the external plates, and the bearing plates relative to the internal plate. The bearing plates and the associated friction shims are positioned within slots in the external plates, and they are not expected to move relative to the internal plate until the bearing plates are in contact with the external plates. The first gap distance between the bearing plates and the slots in the external plates is termed D_1, and the second gap distance between the bearing plates and the slots in the external plates is termed D_2, as shown in Fig. 5(d). The spherical bearings at the end of the Modified FD and the clevis allow the rotational motions and restrain the translational motions within the plane of the plates. As a result, the Modified FD is expected to develop axial load along its longitudinal direction and zero moments at the ends.

3.2. Expected kinematics and force-displacement response

Fig. 6 shows the expected kinematics and the expected force-displacement response of the Modified FD. The term “expected” is used because the kinematics and force-displacement response have not been validated through experimental testing. The following parameters define the expected kinematics and the expected force-displacement response: the first gap between the bearing plates and the slot in each external plate is termed D_1; the second gap between the bearing plates and the slot in each external plate is termed D_2; the friction force generated by the frictional interface between the internal plate and the friction shims for the external plates is termed F_1; the friction force generated by the frictional interface between the internal plate and the friction shims for the bearing plates in the slots associated with D_1 is termed F_2; the friction force generated by the frictional interface between the internal plate and the friction shims for the bearing plates in the slots associated with D_2 is termed F_3; and the elastic stiffnesses are termed K_1, K_2, and K_3. K_1 simulates the flexibility of the components of the Modified FD that are designed to have a linear elastic force-displacement response, and the shear flexibility of the friction shims associated with external plates. The linear elastic components include the clevis plates, the external plates, the internal plate, and the pins. K_2 and K_3 simulate

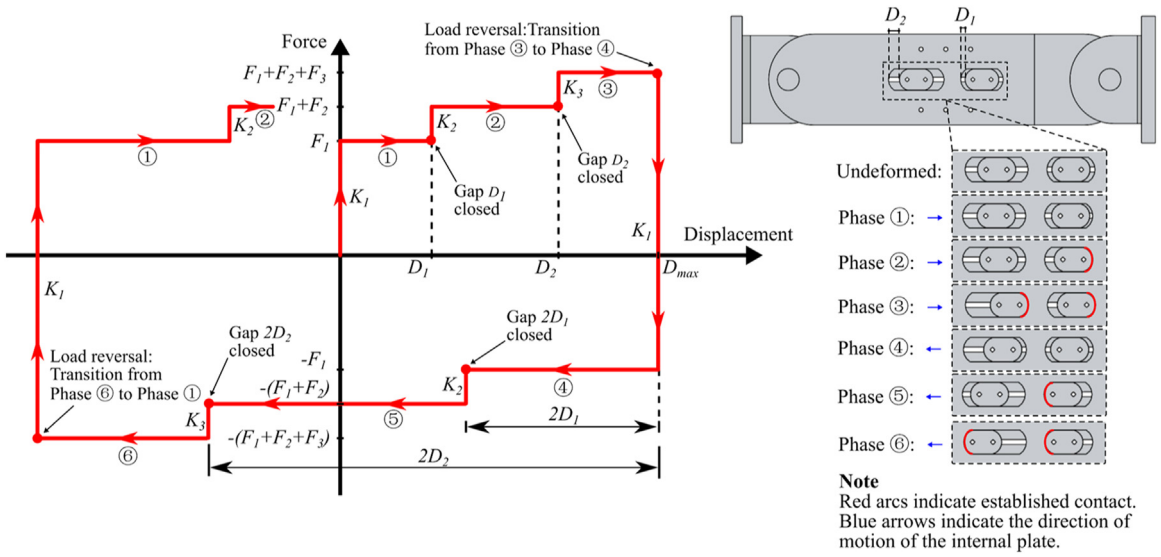

Fig. 6. Expected kinematics and expected force-displacement response in the Modified FD.

the flexibility of the components of the Modified FD that are designed to have a linear elastic force-displacement response, the shear flexibility of the friction shims associated with external plates, and the shear flexibility of the friction shims associated with D_1 and D_2, respectively. Six phases define the expected kinematics of the Modified FD that result in the expected force-displacement response. The expected kinematics and the expected force-displacement response described below assume that the translational motion of the external plates is restrained (i.e., pinned condition at the ends of the external plates) and that a displacement along the longitudinal direction of the Modified FD is applied at the end of the internal plates. Positive displacement results in axial tension in the Modified FD and negative displacement results in axial compression in the Modified FD. The following section presents the six phases. The discussion of the kinematics in the six phases ignores the elastic deformations F_1/K_1, F_2/K_2, and F_3/K_3 assuming K_1=K_2=$K_3 \cong \infty$. The rigid body kinematics of the Modified FD components are considered.

Phase 1 – Sliding along the positive direction of motion with friction force F_1: The increase of the imposed displacement in the Modified FD results in increasing force with stiffness K_1. When the force in the Modified FD becomes equal to F_1, the friction shims for the external plates and the external plates start moving relative to the internal plate. The sliding at the frictional interface between the internal plate and the friction shims for the external plates results in F_1. F_1 can be estimated using Coulomb theory, $F_1 = n_s N_1 \mu_{s1}$, where $n_s = 2$ is the number of friction interfaces; N_1 is the total load from the six bolts acting normal to the friction interfaces between the friction shims for the external plates and the internal plate; μ_{s1} is the coefficient of friction in the friction interfaces between the friction shims for the external plates and the internal plate.

Phase 2 – Sliding along the positive direction of motion with friction force F_1+F_2: Assuming $K_1 \cong \infty$, once the value of displacement reaches D_1, the external plates contact the bearing plates located in the slots associated with D_1. As the displacement in the Modified FD increases, the force in the Modified FD increases with stiffness K_2. When the force in the Modified FD becomes equal to F_1+F_2, the bearing plates and the friction shims in the slots associated with D_1 start moving relative to the internal plate. The sliding at the frictional interface between the internal plate and the friction shims in the slots associated with D_1 results in F_2. F_2 can be estimated using Coulomb theory, $F_2 = n_s N_2 \mu_{s2}$, where N_2 is the total load from the two bolts acting normal to the friction interfaces between the friction shims in the slots associated with D_1 and the internal plate; μ_{s2} is the coefficient of friction in the friction interfaces between the friction shims in the slots associated with D_1 and the internal plate. The total force in the Modified FD during this phase is F_1+F_2.

Phase 3 – Sliding along the positive direction of motion with friction force F_1+F_2+F_3: Assuming K_1=$K_2 \cong \infty$, once the value of the displacement reaches D_2, the external plates contact the bearing plates located in the slots associated with D_2. As the displacement in the Modified FD increases, the force in the Modified FD increases with stiffness K_3. When the force in the Modified FD becomes equal to F_1+F_2+F_3, the bearing plates and the friction shims in the slots associated with D_2 start moving relative to the internal plate. The sliding at the frictional interface between the internal plate and the friction shims in the slots associated with D_2 results in F_3. F_3 can be estimated using Coulomb theory, $F_3 = n_s N_3 \mu_{s3}$, where N_3 is the total load from the two bolts acting normal to the friction interfaces between the friction shims in the slots associated with D_2 and the internal plate; μ_{s3} is the coefficient of friction in the friction interfaces between the friction shims in the slots associated with D_2 and the internal plate. The total force in the Modified FD during this phase is F_1+F_2+F_3. The motion continues until the Modified FD reaches the maximum imposed displacement D_{max}.

Phase 4 – Sliding along the negative direction of motion with friction force -F_1: The reversal of the imposed displacement reduces the force in the Modified FD with elastic stiffness K_1. When the force in the Modified FD becomes equal to -F_1, the internal plate starts moving relative to the external plates along the negative direction. The friction shims for the bearing plates are not expected to move relative to the internal plate during this phase. The internal plate moves relative to the friction shims for the external plates and the external plates, resulting in a force with magnitude equal to F_1.

Phase 5 – Sliding along the negative direction of motion with friction force –(F_1+F_2): Assuming $K_1 \cong \infty$, once the value of displacement reaches D_{max} - $2D_1$, the external plates contact the bearing plates located in the slots associated with D_1. As the displacement in the Modified FD decreases, the force in the Modified FD decreases with stiffness K_2. When the force in the Modified FD becomes equal to –(F_1+F_2), the internal plate starts moving relative to the bearing plates and the friction shims in the slots associated with D_1. The sliding at the frictional interface between the internal

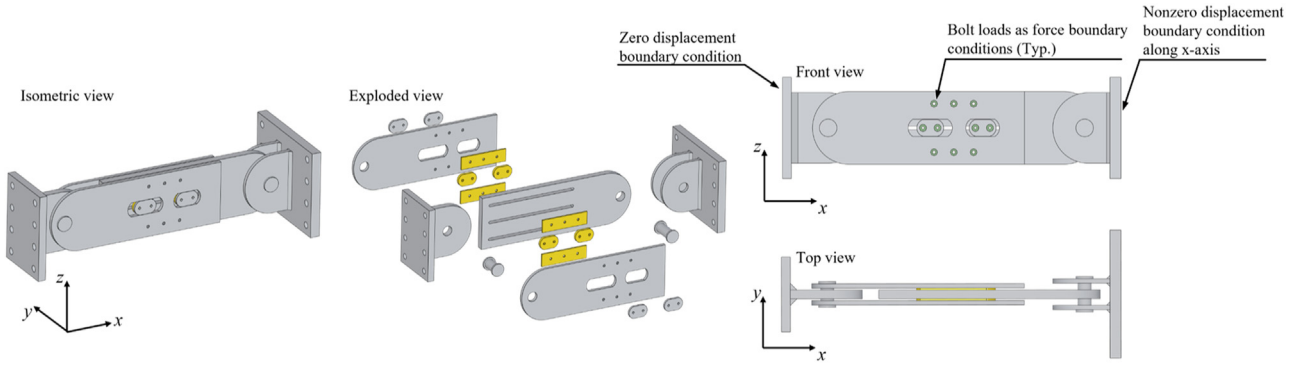

Fig. 7. Finite element model developed to assess the expected kinematics and the expected force-displacement response of the Modified FD.

plate and the friction shims in the slots associated with D_1 results in a force with magnitude equal to F_2. The total force in the Modified FD during this phase is $-(F_1+F_2)$.

Phase 6 – Sliding along the negative direction of motion with friction force $-(F_1+F_2+F_3)$: Assuming $K_1 = K_2 \cong \infty$, once the value of displacement reaches D_{max} - $2D_2$, the external plates contact the bearing plates located in the slots associated with D_2. As the displacement in the Modified FD decreases, the force in the Modified FD decreases with stiffness K_3. When the force in the Modified FD becomes equal to $-(F_1+F_2+F_3)$, the internal plate starts moving relative to the bearing plates and the friction shims in the slots associated with D_2. The sliding at the frictional interface between the internal plate and the friction shims in the slots associated with D_2 results in a force with magnitude equal to F_3. The total force in the Modified FD during this phase is $-(F_1+F_2+F_3)$.

4. Numerical simulations of the modified FD

Experimental characterization of the kinematics and the force-displacement response of the Modified FD is required. However, finite element analyses can be used for rapid digital prototyping of the Modified FD. For this reason, the Solid Model and the Truss Model defined in Section 2 are developed. The Solid Model is used to assess the expected kinematics and the expected force-displacement response of the Modified FD. The Truss Model is used to efficiently simulate the force-displacement response of the Modified FD in numerical earthquake simulations of structural systems. This section presents the results from the static structural analyses of the Solid Model and the Truss Model.

4.1. Description of the solid model

Fig. 7 shows the undeformed geometry of the Solid Model developed in ANSYS Mechanical finite element software [160] and its exploded view, front view, and top view. The Solid Model explicitly simulates the internal plate, the external plates, the bearing plates, the friction shims, the clevises, and the pins using 24,962 eight-node solid finite elements. In this model, the overall lengths (i.e., their longest dimensions along the x-direction) of the external plates are 122.56 cm, their thicknesses (i.e., their dimensions along the y-direction) are 2.54 cm and their heights (i.e., their dimensions along the z-direction) are 41.91 cm; the overall length of the internal plate is 127.64 cm, its thickness is 5.08 cm and its height is 41.91 cm; the overall lengths of the bearing plates are 15.56 cm, their thicknesses are 1.52 cm and their heights are 9.68 cm; the dimensions of the friction shims for the external plates are 38.1 cm × 1.02 cm × 10.16 cm ($x \times y \times z$); the overall lengths of the friction plates associated with the bearing plates are 15.56 cm, their thicknesses are 2.03 cm and their heights are 9.68 cm; the diameters of both pins are 7.8 cm. The bolts are assumed to be ASTM A325 structural bolts with a diameter of 19.05 mm. The minimum pretension of each bolt is 124.55 kN. ASTM A572 Grade 50 is considered for the steel plates. The Solid Model does not explicitly simulate the bolts and the associated washers and nuts used to apply the normal force on the friction interfaces. The preload of the bolts is simulated as a constant force boundary condition distributed to the nodes on the surface of the elements in the external plates and the bearing plates. The surfaces that the simulated bolt load is applied are highlighted with green color in the front view shown in Fig. 7 and they represent the common surface areas between the washers and the external plates and the common surface areas between the washers and the bearing plates. Zero displacement boundary condition is enforced at all the degrees of freedom of the nodes located on the surface of the single clevis located closer to the origin of the global x-axis. In a building application, the single clevis would have been attached to a core wall pier. As a result, the enforced boundary condition is a simplification. The simplified boundary condition is acceptable considering that the objective of the analysis of the Solid Model is to assess the expected kinematics and the expected force-displacement response of the Modified FD. For the same reason, simplified nonzero displacement boundary condition is enforced at the degrees of freedom along the global x-axis of the nodes on the surface of the double clevis further away from the origin of the global x-axis.

The Solid Model explicitly simulates the contact interfaces between the modeled components of the Modified FD using pair-based contact definition with 44,805 surface-to-surface contact elements. A contact pair is defined between each curved surface of a bearing plate and the adjacent curved surface in the slot of the external plate. These contact pairs are assumed to be frictionless. A contact pair is defined between each surface of the friction shims and the adjacent surface of the internal plate. The stress normal to the surfaces is related to the shear stress that defines the limit for the initiation of sliding using the Coulomb friction model with a constant friction coefficient equal to 0.4. The assumed friction coefficient is justified based on past experimental observations [79] of a friction device with friction interfaces established between steel and laminated glass fiber fabric with graphite composite friction shims [159]. The friction shims are assumed to be bonded on the bearing plates and the external plates. This assumption is justified considering that the bearing action of the bolts on the friction shims enforces the kinematic compatibility between the friction shims and the bearing plates and between the friction shims and the external plates. Past research has shown that it is possible to accomplish this kinematic compatibility without damaging the friction shims due to the expected bearing stresses acting on the friction shims [79]. A contact pair is defined between each surface of the pins and the surface of the internal plate where bearing is expected to occur. Similarly, a contact pair is defined between each surface of the pins and the surface of the external plates where bearing is expected to occur. A constant friction coefficient equal to 0.3 is assumed for the steel pin to steel plates contact interfaces. The components of the Modified FD are designed to remain linear elastic. All materials are simulated using a linear elastic consti-

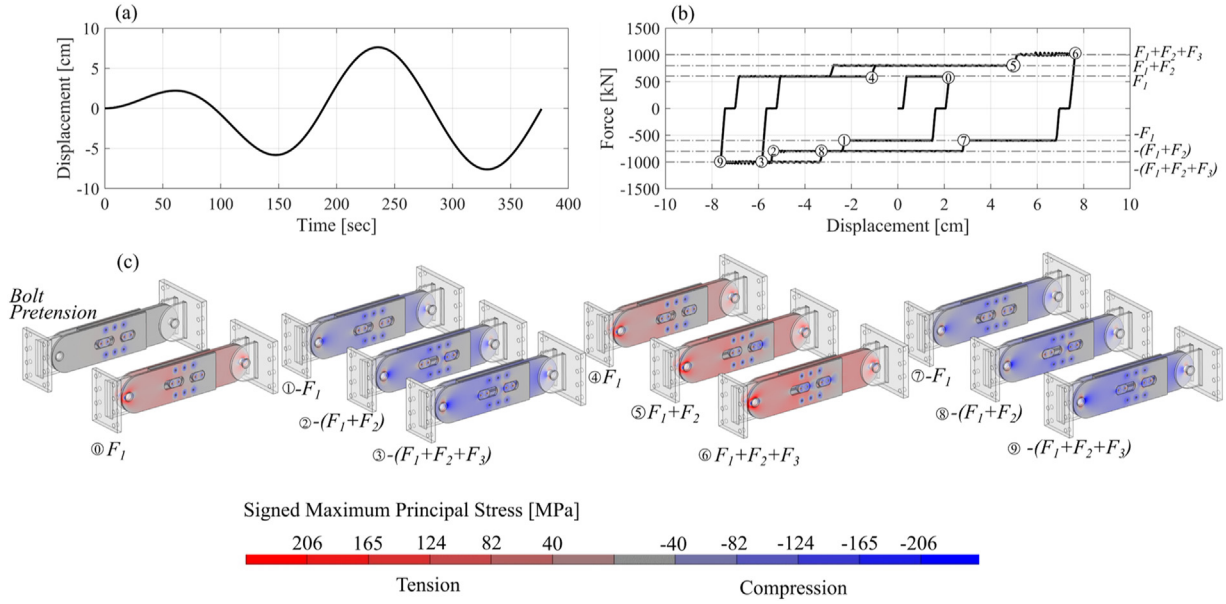

Fig. 8. Static structural analysis of the Solid Model shows that it is possible to develop predetermined friction forces at target design displacements with the proposed Modified FD.

tutive stress-strain relationship. The structural steel is assumed to have a modulus of elasticity equal to 200 GPa and a Poisson's ratio equal to 0.3. The composite friction material is assumed to have a modulus of elasticity equal to 6.9 GPa and a Poisson's ratio equal to 0.4.

The example parameters considered for the design of the Modified FD used to develop the Solid Model are $D_1 = 2$ cm, $D_2 = 5$ cm, $F_1 = 600$ kN, $F_2 = 200$ kN, and $F_3 = 200$ kN. The calculation of F_1, F_2, and F_3 follows Coulomb theory, for example, $F_1 = n_s N_1 \mu_{s1}$, where $n_s = 2$ is the number of friction interfaces; N_1 is the total load from the six bolts acting normal to the friction interfaces, $N_1 = 6 \times 124.55$ kN $= 747.30$ kN, given the minimum pretension of each bolt is 124.55 kN; $\mu_{s1} = 0.4$ is the assumed coefficient of friction at the friction interface. Standard oversize holes were considered for all the pin holes. As a result, the difference between the nominal diameter of the holes and the nominal diameter of the pins is equal to $\Delta_{dn} = 0.16$ cm $= 1/16$ inches. A static structural analysis of the Modified FD is performed and the stiffness matrix is updated at each converged step of analysis to account for the updated geometry. The following section shows the results from the static structural analysis of the Solid Model.

4.2. Solid model analysis results

Static structural analysis of the Solid Model is performed. The analysis is executed in two steps. Results from the analysis are shown in Fig. 8. The force boundary conditions that simulate the bolt pretension loads are applied in the first step of analysis. In the second step of analysis, the sinusoidal displacement shown in Fig. 8(a) is applied along the global x-axis at the degrees of freedom with the nonzero displacement boundary condition shown in Fig. 7. Fig. 8(b) shows the relationship of the applied displacement and the total reaction force along the global x-axis multiplied by −1. Positive force in the plot indicates tension in the Solid Model. The force-displacement relationship also shows the pinching displacement at zero force due to the difference between the nominal diameter of the holes and the nominal diameter of the pins. Fig. 8(c) shows the maximum principal stresses in the Solid Model at the first step of analysis and the ten sub-steps of the second step of analysis. In the first step, stresses develop in the Solid Model only due to the simulated bolt pretension. In the second step, the stress distribution at each sub-step is used to discuss the kinematics associated with the computed force-displacement response of the Solid Model. Sub-steps 0, 1, 4, and 7 are associated with force magnitude F_1 since contact has not been established between the bearing plates and the external plates. The gap distance D_1 has closed in sub-steps 2, 5, and 8. Two out of the four bearing plates are in contact with the two external plates. The increased magnitude of the maximum principal compressive stresses in the contact areas between two bearing plates and the two external plates is indicated with dark blue color as shown in Fig. 8(c). Sub-steps 2, 5, and 8 are associated with a force magnitude equal to $F_1 + F_2$. The gap distance D_2 has closed in sub-steps 3, 6, and 9. All bearing plates are in contact with the two external plates and high magnitude maximum principal compressive stresses are observed in the contact areas between the bearing plates and the external plates. Sub-steps 3, 6, and 9 are associated with a force magnitude equal to $F_1 + F_2 + F_3$. The simulated kinematics and the computed force-displacement relationship verify that it is possible to develop predetermined discrete variable friction forces at target design displacements with the proposed Modified FD.

4.3. Description of the truss model

The Truss Model simulates the force-displacement response of the Modified FD in OpenSees [161] using a corotational truss element. Fig. 9(a) shows the schematic representation of the Truss Model. A reference unit area is assigned to the truss element, termed A_{truss}. The length of the truss element is equal to the total approximate length of the Modified FD, termed L_{truss}. A uniaxial material termed *Aggregate Material* is assigned to the truss element. The term "Aggregate" is used for the uniaxial material to indicate that its stress-strain relationship is simulated by combining the stress-strain relationships of seven primary uniaxial materials. The stress of the Aggregate Material is equal to the internal force in the truss element normalized by A_{truss}. The strain of the Aggregate Material is equal to the axial deformation of the truss element divided by L_{truss}. The use of a normalized force-displacement response as the stress-strain relationship of a uniaxial material assigned to a truss element is a common modeling approach in OpenSees [78,161]. Fig. 9(b) shows the schematic representation of the combination of the seven primary uniaxial materials used to develop the Aggregate Material. The primary uniaxial materials in Fig. 9(b) are represented as springs and their normalized force-displacement behavior is defined in the following paragraphs.

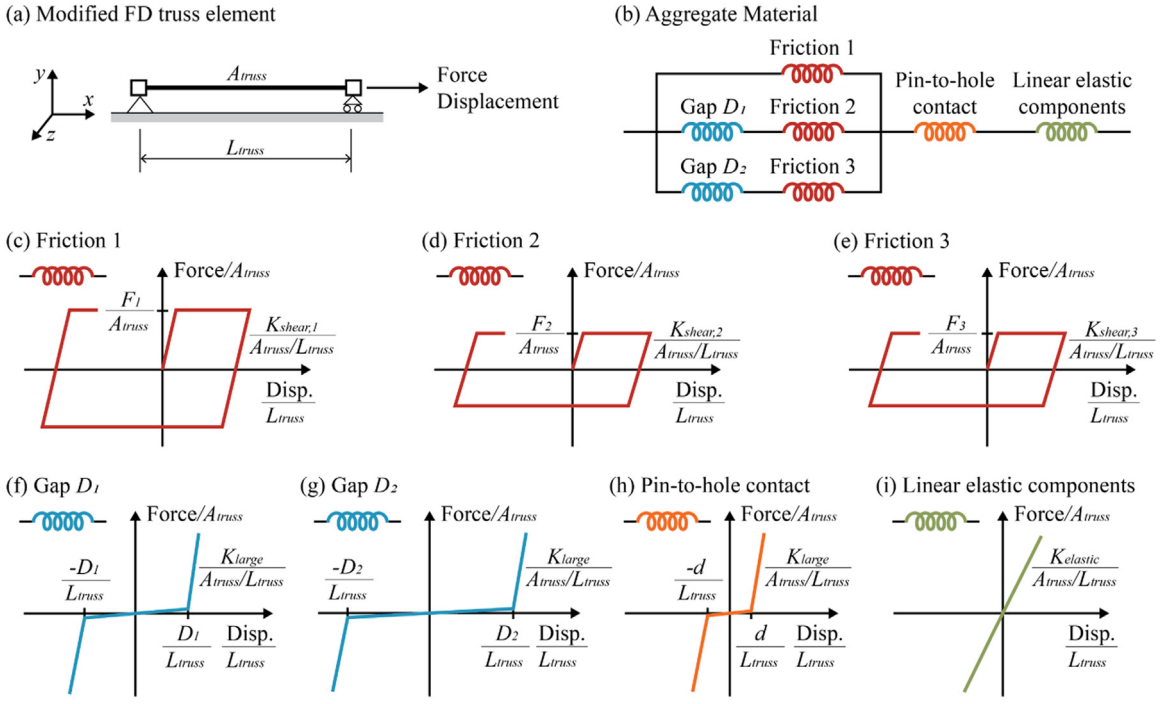

Fig. 9. Schematic representation of the Modified FD Truss Model and the associated material definitions.

The primary uniaxial materials termed *Friction 1, Friction 2*, and *Friction 3* simulate the normalized force-displacement behavior of the frictional interfaces that result in F_1, F_2, and F_3. The normalized force-displacement relationships of Friction 1, Friction 2, and Friction 3 are shown in Fig. 9(c), Fig. 9(d), and Fig. 9(e), respectively. Friction 1, Friction 2, and Friction 3 are modeled using the *Steel01* uniaxial material in OpenSees. Their normalized elastic stiffness simulates the elastic shear stiffness of the friction shims $K_{shear,i} = n_{fpi} \times G \times A_{fpi} / t_{fpi}$ normalized by (A_{truss} / L_{truss}). The subscript $i = 1$, 2, and 3 indicates the number associated with Friction 1, Friction 2, and Friction 3, respectively. n_{fpi} is the number of friction shims associated with the development of the friction forces F_i. G is the expected shear modulus of the material of the friction shims assuming that the same material is used for all the friction shims. A_{fpi} is the surface area of the associated friction shim. t_{fpi} is the thickness of the associated friction shim. Fig. 10 shows the schematic representation of the geometric terms A_{fpi} and t_{fpi} for $i = 1$, 2, and 3. The transition from the elastic to the post-elastic normalized force-displacement response simulates the slip between the friction shims and the internal plate associated with the friction force F_i for $i = 1$, 2, and 3 normalized by A_{truss}.

The primary uniaxial materials, termed *Gap* D_1 and *Gap* D_2, simulate the contact behavior between the bearing plates and the external plates. They are modeled using the *ElasticMultiLinear* uniaxial material in OpenSees. The normalized force-displacement relationships of Gap D_1 and Gap D_2 are shown in Fig. 9(f) and Fig. 9(g), respectively. The pinching displacement behavior at an approximately zero normalized force is simulated with a small, normalized stiffness relative to the normalized elastic stiffness of the Modified FD. The small, normalized stiffness is assigned to the normalized force-displacement region between the normalized gap lengths $-D_j/L_{truss}$ and D_j/L_{truss} where $j = 1$ or 2 indicates the gap distance D_1 or D_2, respectively. A large, normalized stiffness relative to the normalized elastic stiffness of the Modified FD is used to simulate the normalized contact stiffness between the bearing plates and the external plates.

The primary uniaxial material, termed *Pin-to-hole contact*, simulates the contact behavior between the pins and associated holes in the clevises, the external plates, and the internal plates. Fig. 9(h) shows the normalized force-displacement relationship of the *ElasticMultiLinear* uniaxial material used to simulate this contact behavior. The pinching displacement behavior at an approximately zero normalized force is simulated with a small, normalized stiffness relative to the normalized elastic stiffness of the Modified FD. The small, normalized stiffness is assigned to the normalized force-displacement region between the normalized gap lengths $-d/L_{truss} = -(4 \times \Delta_{dn})/L_{truss}$ and $d/L_{truss} = (4 \times \Delta_{dn})/L_{truss}$. A large, normalized stiffness relative to the normalized elastic stiffness of the Modified FD is used to simulate the contact stiffness between the pins, the clevises, and the plates.

The primary uniaxial material, termed *Linear Elastic Components*, simulates the flexibility of the components of the Modified FD that are designed to have a linear elastic force-displacement response. Fig. 9(i) shows the normalized force-displacement relationship of the *Elastic* uniaxial material used in OpenSees. The flexibility of the elastic components is estimated as a combination of the elastic components in series as follows:

$$1/K_{elastic} = 1/K_{CP1} + 1/K_{Pin1} + 1/K_{EPs} + 1/K_{IP} + 1/K_{Pin2} + 1/K_{CP2}$$

where $K_{CP1} = E_{steel} \times A_{CP1}/L_{CP1}$ is the estimate of the axial stiffness of the single clevis plate; $K_{\mathrm{Pin1}} = 2 \times G_{steel} \times A_{\mathrm{Pin1}}/t_{\mathrm{Pin1}}$ is the estimate of the shear stiffness of the pin connecting the external plates with the single clevis plate; $K_{EPs} = 2 \times E_{steel} \times A_{EP}/L_{EP}$ is the estimate of the axial stiffness of the two external plates; $K_{IP} = E_{steel} \times A_{IP}/L_{IP}$ is the estimate of the axial stiffness of the internal plate; $K_{\mathrm{Pin2}} = 2 \times G_{steel} \times A_{Pin2}/t_{Pin2}$ is the estimate of the shear stiffness of the pin connecting the double clevis plate with the internal plate; $K_{CP2} = 2 \times E_{steel} \times A_{\mathrm{CP2}}/L_{\mathrm{CP2}}$ is the estimate of the axial stiffness of the double clevis plate. For all the terms above, A, L, and t relate to the size of components of the Modified FD and the clevis plates. Fig. 10 shows the schematic representations of the geometric terms used to compute the estimate of the stiffness of each elastic component that was considered in the computation of the flexibility of the linear elastic components. E_{steel} and G_{steel} are the modulus of elasticity and the shear modulus of steel, respectively. The parameters for the example Modified FD model analyzed in Section 4.1 are the following: for the structural steel, E_{steel} = 200 GPa and G_{steel} = 77 GPa; for the single clevis plate, B_{CP1} = 40.64 cm,

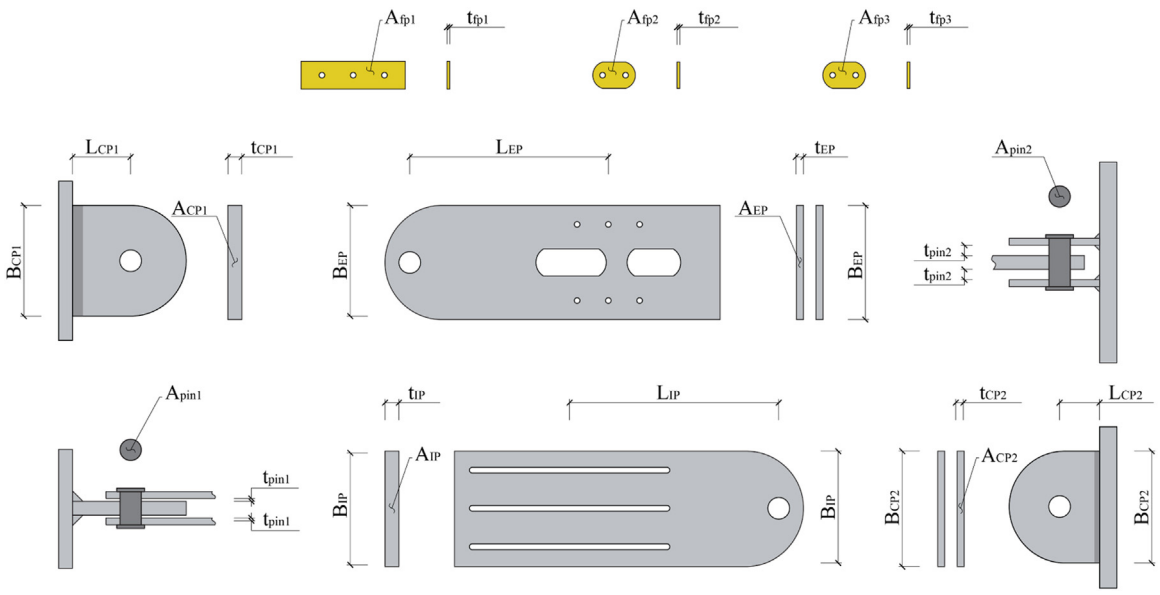

Fig. 10. Schematic representation of the geometric terms used to estimate the stiffness of the components of the Modified FD simulated with the Truss Model.

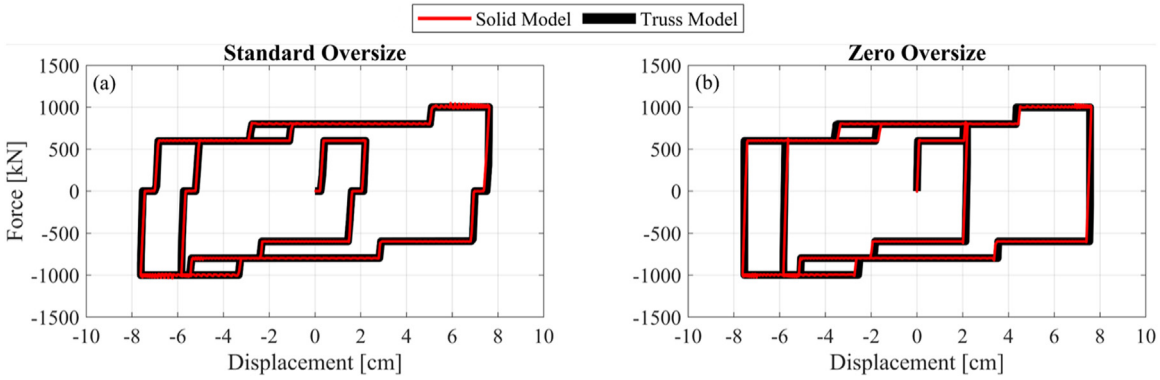

Fig. 11. Comparison of the force-displacement response computed using the Solid Model and the Truss Model assuming standard oversized pin holes and zero oversized pin holes.

t_{CP1} = 5.08 cm, $A_{CP1} = B_{CP1} \times t_{CP1}$ = 206.45 cm^2 and L_{CP1} = 17.46 cm; for the pin connecting the external plates with the single clevis plate, A_{Pin1} = 47.78 cm^2 and t_{Pin1} = 1.27 cm; for the external plates, B_{EP} = 41.91 cm, t_{EP} = 2.54 cm, $A_{EP} = B_{EP} \times t_{EP}$ = 106.45 cm^2 and L_{EP} = 72.64 cm; for the internal plate, B_{IP} = 41.91 cm, t_{IP} = 5.08 cm, $A_{IP} = B_{IP} \times t_{IP}$ = 212.9 cm^2 and L_{IP} = 72.64 cm; for the pin connecting the double clevis plate with the internal plate, A_{Pin2} = 47.78 cm^2 and t_{Pin2} = 3.81 cm; for the double clevis plate, B_{CP2} = 40.64 cm, t_{CP2} = 2.54 cm, $A_{CP2} = B_{CP2} \times t_{CP2}$ = 103.23 cm^2 and L_{CP2} = 14.61 cm.

4.4. Truss model analysis results

Static structural analyses of the Truss Model are performed to compare the computed force-displacement response with the force-displacement response computed from the static structural analyses of the Solid Model. The axial degree of freedom at one node of the Truss Model is fixed. The displacement history shown in Fig. 8(a) is applied at the second axial degree of freedom of the Truss Model. The Truss Model assumes the design parameters considered in Section 4.1: D_1 = 2 cm; D_2 = 5 cm; F_1 = 600 kN; $F_2 = F_3$ = 200 kN. Fig. 11 shows results from two analysis cases. The first analysis case assumes standard oversized pin holes with a 0.16 cm = 1/16 inches difference between the diameter of the pin holes and the diameter of the pins. This analysis case is termed *Standard Oversize*. The second analysis case assumes a 0.00 cm difference between the diameter of the pin holes and the diameter of the pins. This analysis case is termed *Zero Oversize*. The Zero Oversize analysis case represents an ideal design case with machining requirements subjected to low tolerance. Low tolerance machining of the components of the Modified FD can be accomplished by using Computer Numerical Control (CNC) subtracting manufacturing methods. Fig. 11(a) and Fig. 11(b) compare the force-displacement response of the Truss Model and the force-displacement response of the Solid Model for the Standard Oversize analysis case and the Zero Oversize analysis case, respectively. The comparison of the results shows that the Truss Model approximates reasonably well the force-displacement response computed using the Solid Model. As a result, the Truss Model can be used to simulate the expected force-displacement response of the Modified FD in numerical earthquake simulations of core wall building models.

Five additional static structural analyses of the Truss Model are conducted to show the effect of the variation of the design parameters D_1, D_2, F_1, F_2, and F_3 in the expected force-displacement response of the Modified FD. Table 1 lists the design parameters considered in the six analysis cases discussed in this section.

The Baseline Model assumes the design parameters discussed in the Zero Oversize analysis case. DP1 assumes that the bearing plate in the slot associated with D_1 is replaced by a bearing plate that is 3.12 cm shorter compared to the bearing plate assumed in Baseline Model. DP2 assumes that the bearing plate in the slot associated with D_2 is replaced

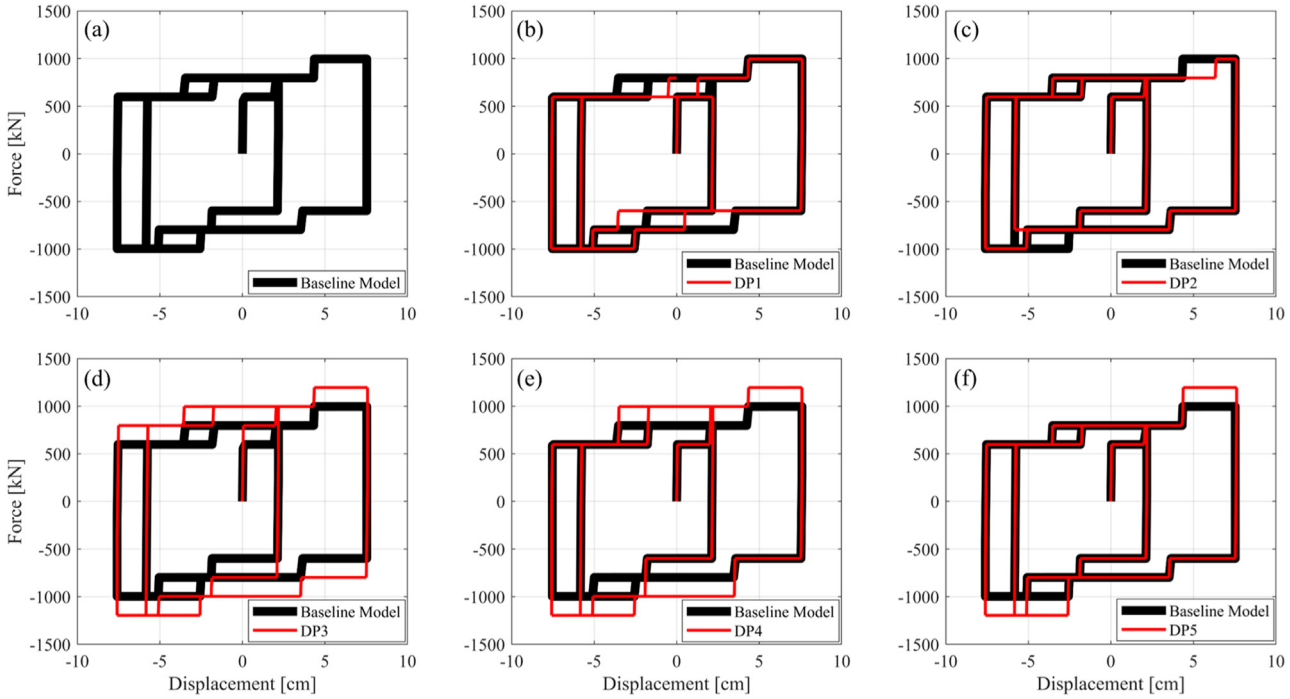

Fig. 12. The force-displacement responses from six analysis cases of the Truss Model show that the expected performance of the Modified FD is possible to be controlled by selecting the design parameters that lead to predefined discrete variable forces at target displacement levels.

Table 1
Design parameters considered in six variations of the Truss Model.

Case of Design Parameters [-]	D_1 [cm]	D_2 [cm]	F_1 [kN]	F_2 [kN]	F_3 [kN]
Baseline Model	2.00	5.00	600	200	200
DP1	3.56	5.00	600	200	200
DP2	2.00	6.35	600	200	200
DP3	2.00	5.00	800	200	200
DP4	2.00	5.00	600	400	200
DP5	2.00	5.00	600	200	400

by a bearing plate that is 2.70 cm shorter compared to the bearing plate assumed in Baseline Model. DP1 and DP2 can be accomplished by replacing the associated bearing plates without revising the design of the remaining components of the Modified FD. DP3 assumes that F_1 is changed from 600 kN to 800 kN, which represents a case when the number of bolts contributing to F_1 is increased from six to eight. DP4 assumes that F_2 is changed from 200 kN to 400 kN, which represents a case when the number of bolts contributing to F_2 is increased from two to four. DP5 assumes that F_3 is changed from 200 kN to 400 kN, which represents a case when the number of bolts contributing to F_3 is increased from two to four. Static structural analyses are conducted using the displacement history shown in Fig. 8(a). Fig. 12(a) shows the force-displacement response computed from the analysis of the Baseline Model. Fig. 12(b) through (f) compare the force-displacement response of the baseline model with the force-displacement responses computed from the analysis of DP1, DP2, DP3, DP4, and DP5. The results demonstrate that the expected performance of the Modified FD is possible to be controlled by selecting the design parameters that lead to predefined forces at target displacement levels.

5. Seismic demands in modified FDs from numerical earthquake simulation of core wall building

In this section, the expected force and displacement seismic demands in the Modified FD are computed using results from a numerical earthquake simulation of a model of a reinforced concrete core wall building with Modified FDs. The computed displacement demands can be used as applied displacement histories in future testing for the experimental characterization of the kinematics and the force-displacement response of the Modified FD. The Modified FD between each floor and core wall pier is simulated using a Truss Model. The seismic response of the building model with Modified FDs is compared with the seismic response of the building model with monolithic connections and the seismic response of the building model with friction devices with constant friction forces. It is shown that it is possible to develop discrete variable limiting forces transferred between the floors of the flexible gravity load resisting system and the core wall piers within design target displacement levels. The detailed assessment of the seismic response of core wall buildings with Modified FD is outside the scope of this paper.

5.1. Numerical model of example building

An eighteen-story reinforced concrete core wall building is adopted from a reference report by Tauberg et al. (2018) [149]. The seismic force-resisting system of the building is a core wall with four L-shaped wall piers connected by coupling beams along the height of the structure, as shown in Fig. 13. The typical story height is 3.0 m (i.e., 10 ft), the length of the wall is 2.7 m (i.e., 9 ft), and the aspect ratio of the coupling beam is 3.0 with a length of 2.3 m (i.e., 7.5 ft) and a height of 0.8 m (i.e., 30 in). The slab is 0.2 m (i.e., 8 in) thick with a 1.8 m (i.e., 6 ft) cantilever slab overhang. Twelve gravity columns are located along the edge of the slab with a 9.1 m (i.e., 30 ft) distance. The structure was designed for Seismic Design Category (SDC) D_{max} as defined in FEMA P695.

A three-dimensional numerical model of this eighteen-story core wall building with added Modified FDs between the floors and the core wall piers was developed in OpenSees. Fig. 14 shows the schematic representation of the eighteen-story core wall building with the Modified FDs, the numerical model of the eighteen-story core wall building, and a typical simulated floor in the numerical model of the eighteen-story core wall building. The four piers of the core wall in each story of

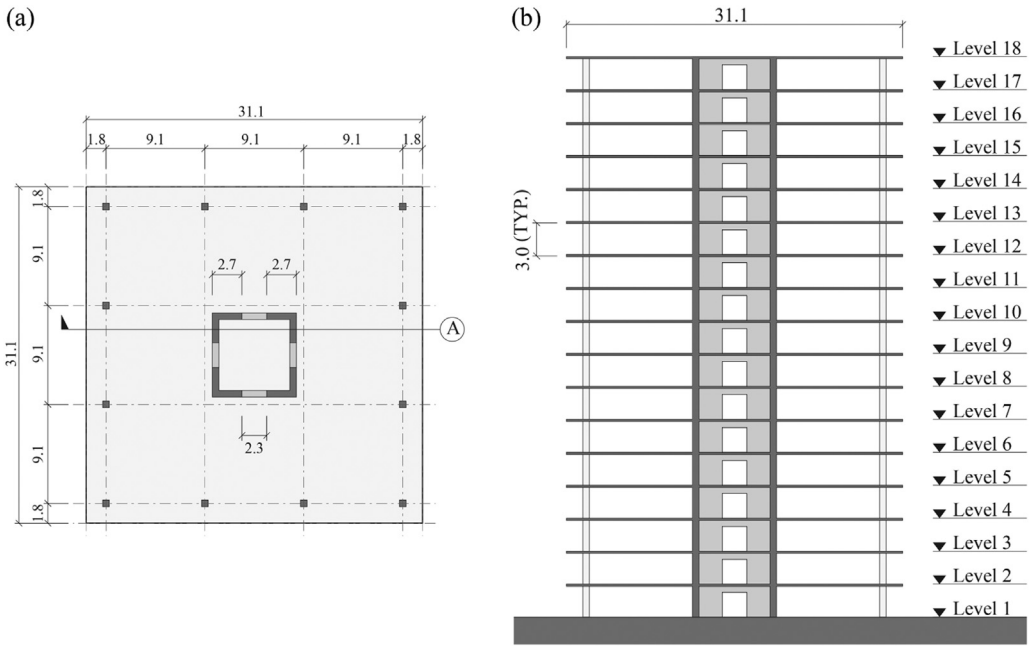

Fig. 13. (a) Typical floor plan and (b) section A of the eighteen-story building (all dimensions are in meters).

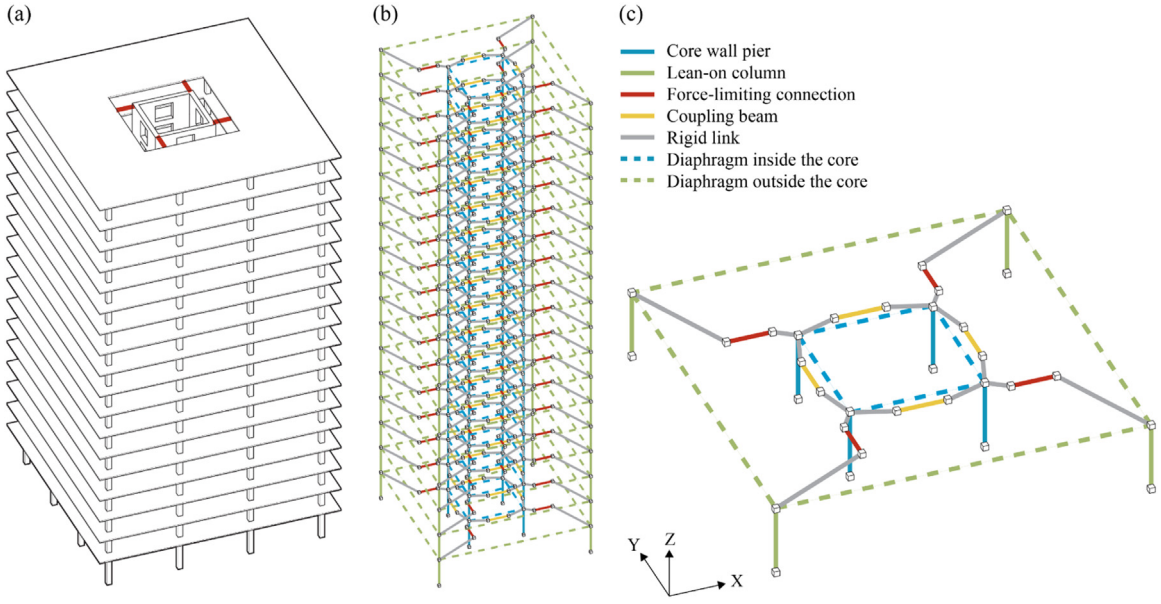

Fig. 14. Schematic representation of (a) the eighteen-story core wall building with the Modified FDs, (b) the numerical model of the eighteen-story core wall building and (c) a typical floor simulated in the numerical model of the building.

the building model are simulated using force-based nonlinear elements with fiber sections. The inelastic response of the coupling beams that are connecting the wall piers is simulated using lumped plasticity zero-length elements. The gravity columns are simulated using four linear elastic beam-column elements with section properties that aggregate the cracked section properties of the gravity columns. Rigid in-plane behavior is assumed for the diaphragms. The Truss Model is used to simulate the Modified FD. The Modified FD design parameters used in the model are $D_1 = 2.0$ cm, $D_2 = 5.0$ cm, and $F_2 = F_3 = 200$ kN. The values of F_1 on the 18th floor, 17th floor, 16th floor, 15th floor, and 1st – 14th floor are 1262 kN, 1082 kN, 902 kN, 722 kN, and 614 kN, respectively. The values of F_1 at each floor were computed using a force-based method proposed by Tsampras and Sause (2022) [81]. This method is modified from the ASCE/SEI 7–16 [162] alternative seismic design force method for floor diaphragms. Numerical earthquake simulations [81] demonstrated that using this method in designing reinforced concrete planar wall buildings with force-limiting connections would result in reasonable connection deformation demands and relatively uniform distribution connection deformation demands over the height of the building.

The building model was subjected to a ground motion recorded at Shin-Osaka station during the 1995 earthquake in Kobe, Japan, scaled to the design level of the expected earthquake ground motion. The two horizontal components of the scaled ground acceleration, SHI000 (H1) and SHI090 (H2), are shown in Fig. 15(a) and Fig. 15(b), respectively. Fig. 15(c) shows the response spectra of the scaled ground motion and the design spectrum with a 5% damping ratio. The natural periods of the first, second, and third translational modes of the building model properties are also plotted in Fig. 15(c). H1 and H2 are applied at

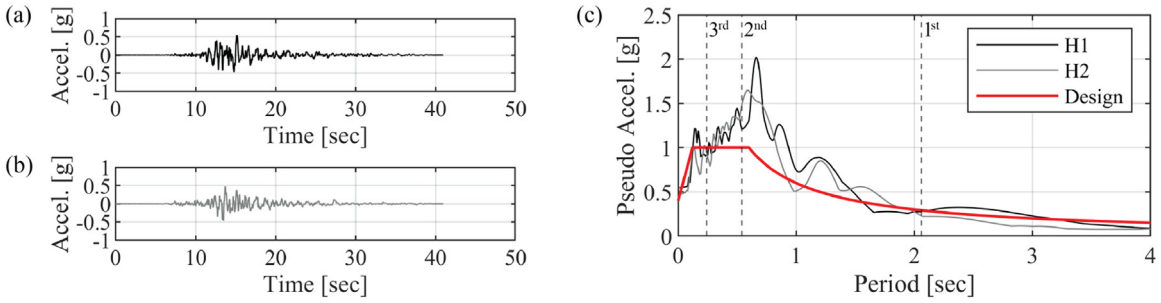

Fig. 15. Scaled ground acceleration of the two horizontal components (a) SHI000 (H1) and (b) SHI090 (H2), and (c) pseudo acceleration response spectra of scaled ground motions and design spectrum with a 5% damping ratio. The dashed lines are associated with the natural periods of the first, second, and third translational modes of the building model.

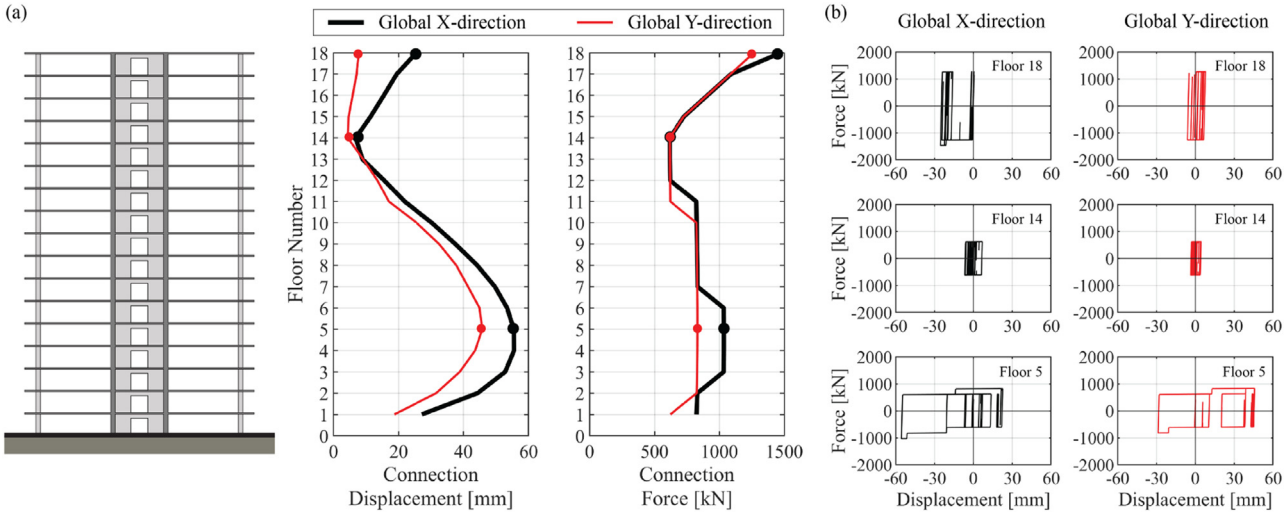

Fig. 16. Peak force and peak displacement responses in the Modified FD along the global X- and Y-directions, and (b) the force-displacement response of the Modified FD at floor levels 5, 14, and 18.

the base of the building model along the global X- and Y- directions, respectively.

5.2. *Seismic response of the modified FD in the example building model*

Fig. 16 shows the force and displacement seismic responses of the Modified FD computed using analysis results from the numerical earthquake simulation. Fig. 16(a) shows the peak (i.e., absolute maximum) response of the Modified FD connection displacement and connection forces over the height of the building model. The peak responses are computed at each floor level. The black lines are associated with the peak responses in the global X-direction, and the red lines are associated with the peak responses in the global Y-direction. The peak connection forces show the activation of different force levels at different floors to limit the displacement demand. For example, due to the contribution of the second and higher translational mode responses in the total dynamic response of the building, the peak connection deformation is the largest near floor levels from 3 to 6, and larger connection forces are activated at the corresponding floor levels to limit the large displacement demand. Fig. 16(b) shows the force-displacement responses of the Modified FD at floor levels 5, 14, and 18, representing the largest response, the smallest response, and the response at the roof, respectively. On the 5th floor, the connection force reached $F_1+F_2+F_3$ and F_1+F_2 in the global X- and Y-directions, respectively. On the 14th floor, where the deformation is the smallest, only the connection force F_1 was activated in both the global X- and Y-directions. On the 18th floor, the connection force reached F_1+F_2 and F_1 in the global X- and Y-directions, respectively. The numerical earthquake simulation results show that it is possible to limit the forces transferred from the floors to the core wall piers in a controlled manner through the expected predetermined discrete variable force-displacement response of the Modified FD simulated using the Truss Model.

The seismic responses of the eighteen-story reinforced concrete core wall building model with three types of connections are compared. The first type of connection assumes conventional monolithic connections between the floors and the core wall system; the second type of connection assumes the use of friction devices with constant friction forces, termed FD; the third type of connection assumes the use of Modified FDs. The monolithic connections are simulated using a linear-elastic force-displacement response with high elastic stiffness to approximate a rigid behavior. The FDs are simulated using elastic-perfectly plastic force-displacement response (i.e., zero post-elastic stiffness). The elastic stiffness of the FDs is equal to the elastic stiffness of the Modified FDs. The post-elastic force of the FDs is equal to F_1 discussed in Section 5.1. Fig. 17 shows the peak floor total acceleration, the peak connection displacement, and the peak connection force in global X- and Y-directions over the height of the building model. The use of FDs or Modified FDs reduces the peak floor total acceleration and the peak connection force compared to the use of monolithic connections. In addition to the reduction of acceleration and force responses, the use of Modified FDs effectively reduces the peak connection displacement compared to the use of FDs. The peak connection displacement of the monolithic connections is close to zero due to the high connection stiffness.

The numerical earthquake simulation results showed that the use of the Modified FDs can limit the seismic induced horizontal forces transferred from the floors to the core wall of the example building model

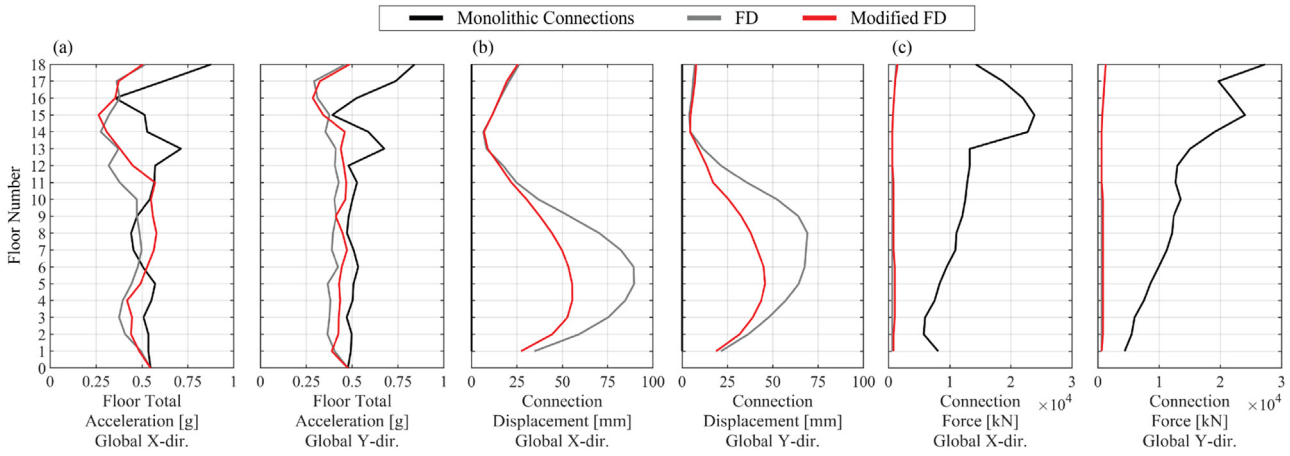

Fig. 17. Peak floor total acceleration, peak connection displacement, and peak connection force in global X- and Y-directions.

without inducing excessive connection displacement demand. Further research is required to determine the effect of the characteristics of earthquake strong ground motions in the seismic response of multistory reinforced concrete core wall buildings with Modified FDs and to determine the values of the design parameters of the Modified FD that result in target seismic performance of core wall buildings.

6. Conclusions

A simple and practical structural connection that develops predetermined discrete variable friction forces at target design displacement levels was presented. The innovative connection was termed Modified Friction Device (Modified FD). Modified FDs are used to transfer the seismic induced horizontal forces from the floors to the core wall seismic force-resisting system of a building. The schematics of the physical embodiment of the Modified FD were presented. The components and the assembly of the Modified FD were discussed. The mechanics of the Modified FD were explained. Results from numerical simulations of a solid finite element model of the Modified FD validated the expected kinematics and the expected force-displacement response of the Modified FD. A truss finite element model was developed in OpenSees. It was shown that the truss model simulates efficiently and reasonably well the expected force-displacement response of the Modified FD. Numerical earthquake simulations of an eighteen-story reinforced concrete core wall building model with three types of connections (i.e., conventional monolithic connections, friction devices with constant friction forces, and the Modified FD) were conducted using OpenSees. The numerical earthquake simulation results showed that the use of the Modified FDs can limit the seismic induced horizontal forces transferred from the floors to the core wall of the example building model without inducing excessive connection displacement demand.

Further research is required to determine the effect of the characteristics of earthquake strong ground motions in the seismic response of multistory reinforced concrete core wall buildings with Modified FDs and to determine the values of the design parameters of the Modified FD that result in target seismic performance of core wall buildings. Experimental characterization of the kinematics and the force-displacement response of the Modified FD is required.

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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