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Reply

## Reply to the Comment by M. Pitkin

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The comment by M. Pitkin [1] on our *EPL* article “Measurements of Newton’s gravitational constant and the length of day” claims to provide evidence that a constant  $G$  measurement model with an additional Gaussian noise term is “hugely favoured” over models employing sinusoidal terms when using a Bayesian model selection procedure. Unfortunately, we were unable to replicate his claims with our own independent analysis testing the hypotheses of the following three scenarios for the  $G$  measurements:

- 1) Constant value:  $G = a_0$ .
- 2) Constant plus a sinusoidal term with period of approximately 6 years:  $G = a_0 + a_1 \cos\left(\frac{2\pi t}{P_1}\right) + b_1 \sin\left(\frac{2\pi t}{P_1}\right)$ .
- 3) Constant plus sinusoidal terms with two different periods of approximately 6 years and 1 year:  $G = a_0 + a_1 \cos\left(\frac{2\pi t}{P_1}\right) + b_1 \sin\left(\frac{2\pi t}{P_1}\right) + a_2 \cos\left(\frac{2\pi t}{P_2}\right) + b_2 \sin\left(\frac{2\pi t}{P_2}\right)$ .

We used a non-linear regression analysis with a minimization of the L1 norm to determine the best fit values for the input parameters of each of the above cases (*i.e.* for  $a_i, b_i$  and  $P_i$  values). After fitting to the  $G$  data, we found normalized  $\sigma$  values of 4.0, 2.6 and 2.0 for the weighted residuals of scenarios 1), 2) and 3), respectively, suggesting the two-period model is favored. We also computed histograms for the 19 weighted residuals

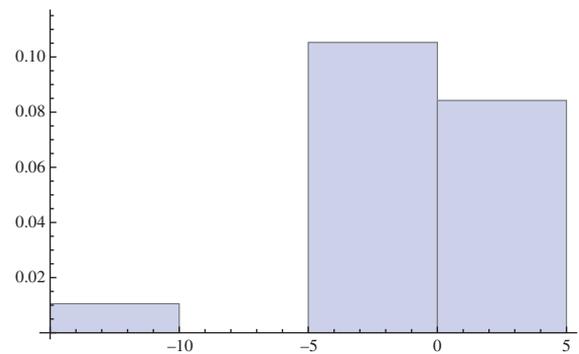


Fig. 1: (Colour on-line) Probability density function of the normalized residuals about a weighted mean  $G$  model (hypothesis 1).

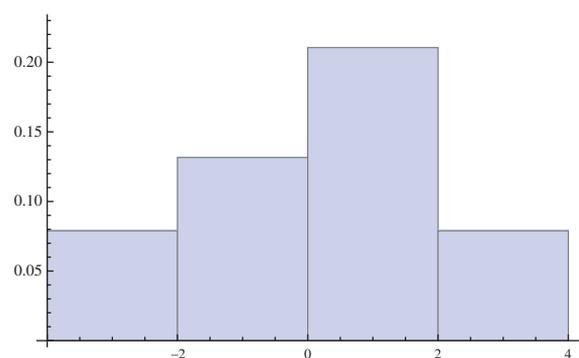


Fig. 2: (Colour on-line) Probability density function of the normalized residuals about a constant plus two-period sinusoid model (hypothesis 3).

<sup>(a)</sup> Retired

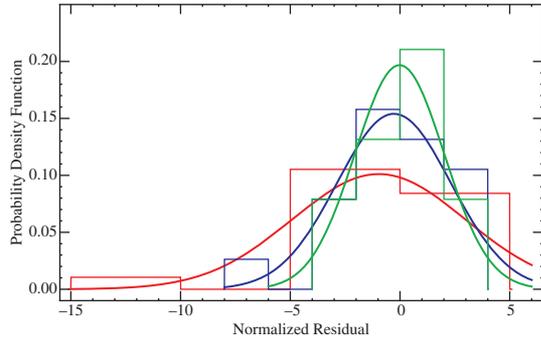


Fig. 3: (Colour on-line) Probability density functions of the normalized residuals for all three hypotheses (red: hypothesis 1), blue: hypothesis 2), green: hypothesis 3)). Overlaid are fitted normal distributions for each hypothesis with clear indication that hypothesis-3) residuals have a tighter Gaussian fit than the others.

and best-fit probability density functions for the three hypotheses. Importantly, the probability density function

of the weighted residuals about a mean value of the  $G$  measurements (hypothesis 1)) follows more of a uniform distribution whereas for the two-period sinusoidal model (hypothesis 3)) the probability density function of the weighted residuals appears to follow a normal distribution, suggesting a possible error in Pitkin's analysis. See figs. 1–3 for our outputs from *Mathematica*. Thus, we stand by our conclusions of potential periodic terms in the reported  $G$  measurements (see our added appendix of [2] in response to [3] for our logic with a two-period sinusoidal model).

#### REFERENCES

- [1] PITKIN M., arXiv:1505.06725 [gr-qc] (2015).
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