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MICROSCALE RESOLUTION OF INTERFACIAL MASS-TRANSFER RATES IN ELECTRODE PROCESSES

G.M. Whitney* and C.W. Tobias (*Ph.D. Thesis)

June 1987

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Microscale Resolution of Interfacial Mass-Transfer Rates in Electrode Processes

Gina Marie Whitney

(Ph.D. Dissertation)

with

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June 1987

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Microscale Resolution of Interfacial Mass-Transfer Rates in Electrode Processes

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ABSTRACT

Results of four interrelated studies concerning the nature of electrolytic gas evolution are reported.

1. Configurations of axisymmetric bubbles formed on curved surfaces are evaluated. Numerical results are summarized by an equation that relates the maximum stable size of a bubble formed on a curved surface to the equilibrium contact angle, a characteristic length of the system, and the radius of curvature of the solid support.

2. Mass-transfer enhancement by a stream of bubbles rising near a masstransfer surface is resolved spatially and temporally using a micro-mosaic electrode. Bubbles are generated electrolytically, inside or outside of the mass-transfer boundary layer. Enhancement resulting from bubbles rising within the mass-transfer boundary layer is strong and localized, in agreement with trends predicted by a surface-renewal model. Mass transfer resulting from bubbles rising outside the boundary layer receives steady, laminar enhancement, correlating well with predictions based on an approximation involving the bubble stream entraining a cylinder of liquid. 3. The onset of buoyancy-induced convection is investigated for a case in which the density profile develops in a semi-infinite fluid, due to a step change in surface concentration at a rigid, conducting boundary. The limiting current technique at a micro-mosaic electrode is used to effect the concentration change and to monitor the resulting mass transfer. Concentration and density profiles before the onset of convection are obtained numerically. The critical Rayleigh number based on the penetration depth of the concentration profile is approximately 900, and that based on the position and magnitude of the density profile is 1750.

4. Observations of galvanostatic growth and disengagement of hydrogen bubbles at a 127- μ m-diameter micro-electrode embedded in a large, coplanar, horizontal electrode in 1.0-M sulfuric acid are reported. Time scales for the collapse of the contact area and for bubble disengagement are obtained using high-speed cinematography. Observations of hydrogen evolution in free convection along vertical platinum electrodes in 0.5-M sulfuric acid are also reported.

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Chapter 1. Introduction

This dissertation gives account of a series of studies conducted on the nature of electrolytic gas evolution. Each chapter describes a different phase of investigation and is intended to stand alone with its own abstract, nomenclature and bibliography.

The major portion of this dissertation concerns certain fundamental aspects of electrolytic gas evolution, a component of numerous important industrial processes. Chlorine is produced as a gas by the electrolysis of brine at verticallyoriented expanded-mesh electrodes. High-purity hydrogen and oxygen are produced by the electrolysis of water. In the reduction of aluminum from Al_2O_3 dissolved in molten cryolite, the anodic reaction is the oxidation of carbon to gaseous CO_2 at horizontal anodes facing downward. In numerous other electrolytic synthesis processes, and in electroplating, one of the reaction products is a gas.

The total electrical energy consumption by the chlorine and aluminum industries alone accounted in 1985 for 4% of the total U.S. electrical energy use. Yet many fundamental aspects of the complex processes that occur during electrolytic gas evolution are poorly understood. Relevant research issues may be listed as follows:

- (1) nucleation;
- (2) physics of bubble shape and stability;
- (3) bubble growth by diffusion and coalescence; and detachment and rise from electrode
- (4) ohmic effects;
- (5) mass-transfer effects, both macroscopic and microscopic.

The physical phenomena in the area of bubble nucleation in gas evolution are essentially identical to those in nucleate boiling. Cole (1974) has written an excellent review on the subject of boiling nucleation; much of his monograph is also relevant to the subject of electrolytic gas evolution.

The second topic involves the balance of buoyancy and surface-tension forces, which determine the maximum-size bubble that can adhere to a solid support, and has been the subject of numerous investigations over the last one hundred years. In Chapter 2 of this thesis, the classic work on bubble shape and size by Bashforth and Adams (1883), Wark (1933), Fritz (1935), and Padday (1969), among others, is extended to account for the effect of the curvature of the solid support on the maximum stable bubble size. This topic becomes relevant today, simply because gas is rarely evolved on a flat, horizontal surface, and there has been no quantification of the effects of electrode morphology, such as protrusions or indentations, on the maximum equilibrium bubble size. Chapter 2 treats the problem of a bubble adhering to an axisymmetric curved surface, such as a hemispherical protrusion on an electrode.

The third topic includes bubble growth, disengagement, and coalescence, all dynamic processes that may occur simultaneously. In recent years, a number of

Introduction

optical observations of bubble behavior have been recorded. Some of the theoretical work consists of simplified treatments of the complex phenomena, such as Scriven's (1959) classic treatment of the growth of a hemispherical bubble by diffusion from a super-saturated solution or Cheh and Tobias' (1968) work on bubble growth in a non-uniform concentration gradient. This area of study of gas evolution is one of the most complex, comprising fluid mechanics, mass transfer, and surface tension forces, as well as the electrical nature of the problem. Chapter 5 of this thesis is a collection of experimental observations of bubble growth and detachment from planar horizontal and vertical electrodes. The goal of these experiments has been to observe both single- and multiple-bubble behavior from the side (i.e., parallel to the electrode surface), rather than from either the front of the bubble layer, or from beneath, through a transparent electrode. First, examination of individual bubble growth has been performed by growing bubbles at a small electrode encased in another material, so that only one bubble evolution site was available, and an unobstructed view of the bubble base could be obtained. Photographs of hydrogen evolution in sulfuric acid at vertical platinum electrodes were also obtained by evolving the gas on narrow strip electrodes, on which only a few columns of bubbles could be formed, and a profile view of attached bubbles could be obtained.

The subject of ohmic effects due to the presence of bubbles in solution is one area that is well in hand. Sides and Tobias (1982) have shown that the effective conductivity of a dispersion can be treated quantitatively by applying the Bruggeman effective medium theory. The motion of the bubbles has little effect on the ohmic penalty they inflict. The incremental resistance caused by bubbles still

attached to the electrode has also been evaluated by the same authors, and later, by Dukovic and Tobias (1987).

In contrast to ohmic effects, mass-transfer processes at gas-evolving electrodes are not well characterized. Theoretical treatments have been aimed at obtaining a form of the applicable correlation for the mass-transfer coefficient as a function of gas-evolution rate and are based on a simplified view of the events taking place at the electrode surface. Experimental measurements have consisted of quantifying this relationship for different electrode geometries, gases, and electrolytes. Only recently have the first microscopic investigations been conducted (Dees and Tobias, 1987). The major difference between the popular theories of gas-evolution mass transfer is whether mass-transfer enhancement is the result of point disturbances of the boundary layer or of macroscopic flow generated by the ascending gas. The results of an experimental investigation into the mechanism of mass-transfer enhancement by bubble streams at vertical micro-sectioned electrodes are presented in Chapter 3.

Chapter 4 is an experimental investigation into the onset of convection resulting from an unstable density gradient at a horizontal surface. The limitingcurrent technique at a sectioned electrode is used to generate the density gradient and to monitor the mass-transfer rate; a change in the mass-transfer rate from the convection-free base case is used as the criterion for determining when convection has commenced. The micro-mosaic electrode is used to resolve the spatial distribution of the ensuing convection and to determine the size scale at which averaging over the electrode surface degrades the accurate determination of convection onset.

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Chapter 2. The Shape and Stability of Axisymmetric

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Gas Bubbles Attached to a Curved Surface

1. Abstract

The equation of Bashforth and Adams is used to calculate the configurations of axisymmetric bubbles formed on a curved surface, such as on a hemispherical solid. A stability analysis is performed to determine which configurations are stable to a disturbance in shape. Numerical results are summarized by a correlation that relates the maximum size of a bubble formed on a curved surface to the equilibrium contact angle, a characteristic length of the system, and the radius of curvature of the solid support.

2. Introduction

The shape and size of electrolytically-generated gas bubbles is of interest in so far as they affect the ohmic cell resistance and mass transfer to and from gasevolving electrodes. In nucleate boiling, the shape and size of bubbles affects the rate at which heat can be transferred to solution. Also, generation of small bubbles of uniform size is of technological interest, for example in mineral flotation. Equilibrium shapes of attached bubbles and drops have been the subject of numerous studies over the past two hundred years, involving such luminaries as Laplace, Gauss, Poisson, Gibbs, and Rayleigh, to name a few.

In spite of the massive amount of high quality work in this area, virtually no attention has been given to drops and bubbles attached to other than planar horizontal surfaces. Also, much of the past effort was directed to the elucidation of conditions that prevail in the case of large pendant drops as opposed to small emergent gas bubbles on electrode surfaces.

The principles that govern the shape of an interface between two phases have been long established. There is a balance between buoyancy forces, which tend to deform the interface, and surface-tension forces, which act to resist deformation. Young (1804) and Laplace (1805) independently proposed that the pressure difference Δp across an interface is related to the deformation of the interface by

$$\frac{\Delta p}{\gamma} = \frac{1}{R_1} + \frac{1}{R_2} \tag{1}$$

where γ is the surface tension and R_1 and R_2 are the two principal radii of curvature. Eq. (1) has become known as the Laplace equation. Young also proposed that the angle of contact formed between a solid and the surface of a fluid exposed to air is a characteristic value for any combination of solid and fluid. Young's equation relates the contact angle θ to the surface tension of the liquid γ_{lg} , the surface tension of the solid γ_{sg} , and the tension of the interface between the solid and the liquid γ_{sl} :

$$\gamma_{lg}\cos\theta = \gamma_{sg} - \gamma_{sl} \quad . \tag{2}$$

As described by Padday (1969) in his excellent description of the development of this area, Gauss (1830), Poisson (1831), Rayleigh (1902), and Gibbs (1906) have all contributed to the early development of this field, and all work in this area is based on the principles they set forth. Padday (1969) also discusses the concepts of the forces of attraction and repulsion that give rise to the surface tension. For purposes of the present work, we shall accept the surface tension of a fluid as a thermodynamic quantity that equals the free energy associated with the formation of a unit area of interfacial surface.

Bashforth and Adams (1883) tested Eq. (1) by calculating shapes of axisymmetric sessile drops. They substituted an expression for the hydrostatic pressure as a function of position z from the apex of the drop, where the two principal radii of curvature are the same, defined as R_0 . As a consequence, Eq. (1) assumes the form:

$$2 + \frac{\Delta \rho g R_0^2}{\gamma} \frac{z}{R_0} = \frac{1}{R_1/R_0} + \frac{1}{R_2/R_0} , \qquad (3)$$

which is commonly referred to as the equation of Bashforth and Adams. $\Delta \rho$ is the density of the included phase minus the density of the surrounding phase, and is positive for sessile drops and captive bubbles, and negative for pendant drops and emergent bubbles. Normally, $\Delta \rho$ is written as ρ since the density of one phase is

usually much greater than that of the other. R_1 is the radius of curvature in the plane of axial symmetry, given by

$$R_{1} = \frac{\left(1 + \left(\frac{dz}{dx}\right)^{2}\right)^{3/2}}{\frac{d^{2}z}{dx^{2}}}$$
(4)

where x is the radial coordinate. R_2 is the radius of curvature in the plane normal to the plane of symmetry given by

$$R_{2} = \frac{x \left(1 + \left(\frac{dz}{dx}\right)^{2}\right)^{1/2}}{\frac{dz}{dx}} , \qquad (5)$$

The geometry is shown in Figure 1. The dimensionless group

$$\beta \equiv \frac{\Delta \rho g R_0^2}{\gamma} \quad , \tag{6}$$

appearing as a parameter in Eq. (3), is characteristic of the shape of the bubble. In recent literature, this group is called the Bond number.

Bashforth and Adams compared calculated sessile drop shapes to experiment and published extensive tables of accurate values of profile shapes. The tables have been extended by Blaisdell (1940) to cover larger values of β and by Fordham (1948) and Mills (1953) to cover pendant drops ($\beta < 0$). Padday (1969) published these tables together, and later (1972) extended the range of the tables considerably, making them available on microfiche cards.

The determination of the largest equilibrium bubble volume on a flat surface has been addressed by Wark (1933) and by Fritz (1935). The equation of Bashforth and Adams is integrated numerically from the top of the bubble, generating values







for the coordinates of the bubble surface, until the interface meets the horizontal with the specified contact angle. Wark used the tables of Bashforth and Adams to construct graphical relations between bubble volume, radius of contact and contact angle. He found that there are two points in the bubble profile at which one can impose the contact angle condition and questioned the stability of the lower, or reentrant, occurrence. He found that for any contact angle there exists a maximum equilibrium bubble volume. The physical explanation is that, for a volume greater than this maximum, the buoyancy forces are too great to be balanced by the surface tension forces of adhesion. Equivalently, there is too high a pressure gradient in solution to allow the bubble to remain sufficiently close to spherical in shape to meet the specified contact angle. Wark presented graphically the relationship between maximum bubble volume and contact angle, and included curves for both upper and lower occurrences of the contact angle. Kabanow and Frumkin (1933) found that their experimentally measured bubble volumes at departure fell on Wark's curve for the re-entrant contact angles.

Fritz (1935) has shown that a linear relationship exists between the group $\frac{V_{max}^{1/3}}{R_0}\sqrt{-\beta}$ and contact angle for θ less than 120°. Cheh (1967) expressed

Fritz' result by the simple relation

$$V_{max, flat} = \left(\frac{3}{\pi}\right)^3 \left(\frac{\gamma}{\rho g}\right)^{3/2} \theta^3 \quad (\theta \text{ in radians}) \quad . \tag{7}$$

Consider now a bubble attached to a solid support that curves away from the bubble, such as a wire, or a protrusion from a flat surface. If the bubble is to meet the solid support with the same angle of contact through the liquid phase as that for a flat surface, the bubble interface must meet the horizontal at a sharper (smaller) angle. Thus, for a given contact angle, a bubble adhering to a support that curves away from the bubble will be smaller and closer to spherical in shape than one on a flat support.

The question of *stability* of the calculated bubble configurations must be addressed before the results for maximum bubble size can be correlated. Pitts (1974) derived the equations for the stability of axisymmetric pendant drops. He presents calculations of stability for *drop* contact angles of 20 and 50°, which correspond to *bubble* contact angles of 160 and 130°, respectively. (By convention, the contact angle is measured through the liquid phase.) Since we are concerned with bubble contact angles less than 90° (aqueous solutions generally wet metal surfaces), we conduct calculations of stability with respect to a perturbation in bubble shape for small contact angles and for bubbles adhering to curved surfaces.

The motivation for this investigation of bubble sizes on curved surfaces is that, in practice, gas is rarely evolved on flat, horizontal surfaces. The objective of this work then is to quantify the relationship between the maximum stable equilibrium bubble size and the properties of the system, the angle of contact, and the curvature of the surface. The method of calculation of bubble shape and size is described in Section 3. The question of stability of the calculated bubble configurations and the results for bubbles on a flat surface are presented in Section 4. The extension to axisymmetric curved surfaces is presented in Section 5.

3. The Calculation of Bubble Size

Consider first the general problem of the shape of a bubble. The equation of Bashforth and Adams (Eq. (3)) can be integrated numerically from the top of the bubble, where $R_1 = R_2 = R_0$, to give the coordinates describing the bubble interface. Equations (3), (4), and (5) are first transformed to a simple set of ordinary, coupled differential equations with s, the arc length along the interface, as the independent variable, and x and z as dependent variables. Using x^* , z^* , and s^* to designate variables made dimensionless with R_0 , Eq. (3) becomes

$$2 + \frac{\Delta \rho g R_0^2}{\gamma} z^* = \frac{\frac{d^2 z^*}{ds^{*2}}}{\frac{dx^*}{ds^*}} + \frac{\frac{dz^*}{ds^*}}{x^*}$$
(8)

Eq. (8) is rearranged to obtain a set of differential equations for z' ($\equiv dz'/ds'$) and z':

$$\frac{dz'}{ds^*} = \left(2 + \frac{\Delta \rho g R_0^2}{\gamma} z^* - \frac{z'}{x^*}\right) (1 - z'^2)^{1/2} \quad . \tag{9}$$

$$\frac{dz^*}{ds^*} = z' \qquad . \tag{10}$$

 x^* is obtained from integration of the geometric relation

$$\frac{dx^*}{ds^*} = (1 - z'^2)^{1/2} \quad , \tag{11}$$

and the dimensionless volume V^* is given by

$$\frac{dV^*}{ds^*} = \pi \frac{dz^*}{ds^*} x^{*2} .$$
 (12)

Eqs. (9)-(12) are integrated numerically from the top of the bubble ($s^* = 0$), where

$$x^* = z^* = V^* = 0$$
, $\frac{dx^*}{ds^*} = 1$ and $\frac{dz^*}{ds^*} = 0$, using a fourth-order Runge-

Kutta-Gill integration scheme. The end condition is the specification of the contact angle at which the gas-liquid interface must meet the solid support.

$$\frac{dz^*}{ds^*} = \sin\theta \quad . \tag{13}$$

How far a bubble surface can be distorted from spherical is given by the Bond number β (Eq. (6)), which is a measure of the ratio of buoyancy forces, which act to deform the bubble surface from spherical, to the surface tension forces resisting deformation. This group appears as a parameter in the equation that describes the shape of the bubble (Eq. (8)). (It is negative for the emergent bubble and pendant drop problems, and positive for the captive bubble and sessile drop problems.) Because it includes R_0 , the scaling of the dimensionless distance variables in Eq. (8), the Bond number is characteristic of both bubble *shape* and *size*. A small Bond number ($|\beta| < 0.1$) is indicative of a small bubble that is nearly spherical (small R_0 , large γ). A large Bond number ($|\beta| > 0.3$) is characteristic of a large "floppy" bubble. Figure 2 shows calculated bubble shapes for three Bond numbers, -0.1, -0.2, and -0.3, using values characteristic of water at $25 \,^{\circ}$ C ($\gamma = 72.8$ dynes/cm, $\Delta \rho = -0.997$ g/cm³). The calculation of each bubble was terminated when the angle through the liquid phase reached 90°.

The group

$$L_c \equiv \left(\frac{\gamma}{\Delta\rho g}\right)^{1/2} \tag{14}$$

is a characteristic length of the system that could alternatively have been used in the scaling of Eq. (3). Had we used this scaling, we would still obtain a parameter,



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Figure 2. Calculated bubble configurations in water at 25 °C ($\gamma = 72.8$ dynes/cm, $\Delta \rho = -0.997$ g/cm³) for three Bond numbers. The bubbles shown meet the horizontal at an angle of 90 °.

often referred to as the capillary datum, which can be related to the Bond number and represents the pressure across the interface at some reference point. All lengths in the system do scale by L_c , in any case, and we expect the maximum bubble volume to be proportional to L_c to the third power, in agreement with the result of Fritz (1935).

For each chosen value of the Bond number, there are two points at which the end condition can be met. Figure 1 shows a bubble calculation for $\beta = -0.2$ with two 60° contact angles indicated. The stability of the lower occurrence of the contact angle, which has been questioned by Wark (1933), will be discussed in the following section. By varying the Bond number, and repeating the calculation, we obtain a family of solutions (two for each Bond number) for a given contact angle. At some point we reach a Bond number for which the buoyancy forces are too great to allow the bubble interface to meet the contact angle condition. Each time a solution is generated, we obtain a bubble volume, radius of contact, bubble height, and maximum radius. A plot of the family of bubble volumes versus radii of contact for a contact angle of 60° is shown in Figure 3. The lower (solid) curve represents the upper occurrences of the contact angle condition; the upper (dashed) curve represents the lower, or re-entrant, occurrences, for which the stability is in question. The point of maximum volume on the curve is very close to the meeting of the two curves, which represents the maximum value of β for which a solution can be obtained. A similar plot of families of solutions is shown in Figure 4 for contact angles from 30 to 90°. At contact angles greater than 60°, the point of maximum volume for a given contact angle lies on the re-entrant portion of the curve.



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Figure 3. Family of solutions of volumes and radii of contact for a contact angle of 60°. Solid curve corresponds to first meeting of the contact angle condition (uppermost, in Figure 1); dashed curve corresponds to lower, or re-entrant, contact angles.



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Figure 4. Families of solutions of volumes and radii of contact for a contact angles of 30 to 90°. Solid curves represent first meeting of the contact angle condition; dashed curves correspond to re-entrant contact angles.

4. The Stability of Calculated Configurations

The equations for stability of an axisymmetric pendant drop to an axisymmetric disturbance that extends over the profile of the drop have been derived by Pitts (1974) using the calculus of variations. Our treatment here follows that of Pitts directly, with only minor differences, and will be given in outline form only.

The total energy of a bubble adhering to a support that is at height h below the apex of the bubble is written

$$E = \int_{0}^{h} \left[2\pi \gamma x \frac{ds}{dy} - \pi \rho g \left(h - y \right) x^{2} \right] dy + \pi \gamma r_{c}^{2} \cos \theta \quad .$$
 (15)

The first term is the surface energy required for the creation of an area of interface having profile length ds. The second term is the potential energy gained by raising a volume slice to a height h - y above the plane of the support. The last term is the energy required to replace a surface of contact of area πr_c^2 between the solid and liquid with a surface of contact between gas and liquid. The only difference between our equations and those of Pitts is that, for a bubble, this last term is a positive contribution for contact angles θ less than 90°; for a drop this term is energy gained.

The drop volume is given by

$$V = \pi \int_{0}^{h} x^2 dy \qquad (16)$$

The equilibrium profile is obtained by finding the function x(y) that minimizes the energy E for a given volume V.

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Pitts non-dimensionalizes equations (15) and (16) using $L_c = \left(\frac{\gamma}{\rho g}\right)^{1/2}$ as

the scale of distance:

$$\kappa \equiv \frac{h}{L_c} , \quad \lambda \equiv \frac{r_c}{L_c} , \quad \xi \equiv \frac{x}{L_c} , \quad \varsigma \equiv \frac{y}{L_c} , \quad (17)$$

and

$$E_0 \equiv \frac{E \rho g}{\pi \gamma^2}$$
 and $v \equiv \frac{V}{\pi L_c^3}$ (18)

Eqs. (15) and (16) become

$$E_{0} = -v \kappa + \int_{0}^{\kappa} \left[2\xi (1 + \xi'^{-2})^{1/2} + \xi^{2} \varsigma \right] d\varsigma + \lambda^{2} \cos\theta \quad , \tag{19}$$

$$v = \int_0^\kappa \xi^2 d\varsigma \quad , \tag{20}$$

where ' denotes differentiation with respect to ς .

The calculus of variations is used to find the equilibrium profile by searching for the function $\xi(\varsigma)$ that minimizes E_0 for a given v. Thus we seek the vanishing of the first variation of $E_0 - \mu v$, where μ is an arbitrary multiplier. We substitute the functions

$$\xi(\varsigma) = \overline{\xi}(\varsigma) + \epsilon \eta(\varsigma) \quad , \tag{21-a}$$

$$\xi'(\varsigma) = \overline{\xi}'(\varsigma) + \epsilon \eta'(\varsigma) \quad , \tag{21-b}$$

where $\overline{\xi}$ is the equilibrium profile and ϵ is an arbitrary (small) constant, into Eq. (19) and (20) for the energy and volume, and take the derivatives with respect to ϵ . At the minimum in energy for a given volume,

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$$\frac{\partial (E_0 - \mu v)}{\partial \epsilon} = 0 \quad . \tag{22}$$

Taking the first variation gives the Euler-Lagrange equation

$$\varsigma - \mu = \frac{-1}{\varsigma \left(1 + \xi'^{-2}\right)^{1/2}} + \frac{\xi''}{\left(1 + \xi'^{-2}\right)^{3/2}} \quad . \tag{23}$$

Rearranging, and comparing to Eq. (3), we see that

$$\mu = \frac{2}{\sqrt{-\beta}} = \frac{2}{R_0/L_c} \quad , \tag{24}$$

is the sum of curvatures at the origin and is necessarily positive.

We can write Eq. (23) in the equivalent form

$$\xi\xi' \ (\mu - \varsigma) = \frac{d}{d\varsigma} \left[\frac{\xi}{(1 + \xi'^{-2})^{1/2}} \right] \quad , \tag{25}$$

and integrate over the height of the bubble

$$\int_{0}^{\kappa} \xi \xi' \ \mu d \varsigma - \int_{0}^{\kappa} \xi \xi' \ \varsigma d \varsigma = \left[\frac{\xi}{(1 + \xi'^{-2})^{1/2}} \right]_{0}^{\kappa}$$
(26)

Integrating the second term by parts and using the contact angle condition,

$$\xi'(\kappa) = -\cot\theta \quad , \tag{27}$$

and Eq. (20) for volume, gives

$$v = 2\lambda \sin\theta + (\kappa - \mu)\lambda^2 \quad . \tag{28}$$

Next we require that any calculated equilibrium be stable to a perturbation in shape. We solve for the change in energy δE_0 due to an axisymmetric perturbation in shape by substituting Eqs. (21) for the disturbed profile function, $\kappa + \delta \kappa$ for κ , and $\lambda + \delta \lambda$ for λ into Eq. (19) to obtain a form for $E_0 + \delta E_0$. We subtract E_0 to obtain
$$\delta E_{0} = \delta \lambda^{2} \cos\theta + 2\delta \lambda \delta \kappa \left[\lambda(\kappa - \mu) + \csc\theta\right] + (1/2) \ \delta \kappa^{2} \left[\lambda^{2} + 2\csc\theta \cot\theta + 2\lambda(\kappa - \mu)\cot\theta\right] + \epsilon^{2} \int_{\xi_{0}}^{\kappa + \delta \kappa} \left[\eta^{2}(\varsigma - \mu) + \frac{2\eta\eta' \ \xi'}{(1 + \xi'^{-2})^{1/2}} + \frac{\xi\eta' \ 2}{(1 + \xi'^{-2})^{3/2}}\right] d\varsigma$$
(29)

If an equilibrium configuration is stable, then δE_0 will be greater than zero, for all values of $\delta\lambda$ and $\delta\kappa$. The second variational problem then is to find $\eta(\varsigma)$ that minimizes δE_0 , again subject to the constant volume condition, which becomes

$$-\int_{\kappa}^{\kappa+\delta\kappa} \xi^2 d\varsigma = 2\epsilon \int_{\varsigma_0}^{\kappa+\delta\kappa} \eta \xi d\varsigma + \epsilon^2 \int_{\varsigma_0}^{\kappa+\delta\kappa} \eta^2 d\varsigma \quad , \tag{30}$$

where ς_0 is a point near the origin which is later set to 0. Following the same procedure as before, Eq. (30) is multiplied by an arbitrary constant and added to the integral in Eq. (29). The minimum in this integral is found by substituting $\eta = \overline{\eta} + \epsilon_2 \nu$ and taking the derivative with respect to ϵ_2 . We then have the expression for η that minimizes δE_0 . After considerable manipulation, Pitts finds that at the minimum in δE_0 ,

$$\delta E_{0} = 3\delta\lambda^{2}[\lambda(\kappa - \mu) + \sin\theta] \frac{\partial v}{\partial \mu} \left(\frac{\partial N}{\partial \mu}\right)^{-1} , \qquad (31)$$

where

$$N \equiv -3v \cot \theta - \lambda^3 \quad . \tag{32}$$

Defining

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$$R \equiv \lambda(\kappa - \mu) + \sin\theta \quad , \tag{33}$$

the equation for δE_0 at the minimum is

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$$\delta E_{0} = 3\delta\lambda^{2}R \frac{\partial v}{\partial \mu} \left(\frac{\partial N}{\partial \mu}\right)^{-1} , \qquad (34)$$

where v is given by Eq. (28). Eq. (34) is derived considering that $\delta\lambda$ and $\delta\kappa$ do not both vanish. If the radius of contact and the height are both fixed ($\delta\lambda = \delta\kappa = 0$), we obtain an additional equation that must be satisfied for the configuration to be stable. The conjugate point condition can be written

$$M(\kappa) \equiv \frac{1}{2} \left(-\frac{\partial v}{\partial \mu} \cot \theta - \lambda^2 \frac{\partial \lambda}{\partial \mu} \right) = \frac{1}{6} \frac{\partial N}{\partial \mu} \quad . \tag{35}$$

If $\frac{\partial N}{\partial \mu}$ goes through zero, the drop is unstable to the conjugate point condition.

Figure 5 shows R, v, N, and μ as functions of κ for a series of bubble configurations with a contact angle of 80°. Here too, solid curves are for the uppermost occurrences of the contact angle, and dashed curves represent re-entrant contact angles. At the point of changeover on the curves (maximum β), R, $\frac{\partial N}{\partial \kappa}$, and $\frac{\partial \mu}{\partial \kappa}$ all pass through zero, as shown by Pitts is necessarily the case. Along the portion A-B on the solid curves, R and $\frac{\partial N}{\partial \kappa}$ are negative and $\frac{\partial v}{\partial \kappa}$ is positive; hence δE_0 is positive and these bubble configurations are stable according to Eq. (34). From point B to point C, R, $\frac{\partial N}{\partial \kappa}$, and $\frac{\partial v}{\partial \kappa}$ are all positive and these configurations are also stable. At point C, $\frac{\partial v}{\partial \kappa}$ changes sign, so configurations between C and D are unstable. At point D, $\frac{\partial v}{\partial \kappa}$ again changes sign, but so does $\frac{\partial N}{\partial \kappa}$, making configurations between D and E unstable.

The characteristics of the curves are similar for smaller contact angles. As

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Figure 5. Relevant parameters in the determination of the stability of equilibrium bubble configurations for $\theta = 80^{\circ}$. Solid curves represent first meeting of the contact angle condition; dashed curves correspond to re-entrant contact angles.

the contact angle decreases, the point of maximum β (point B) moves closer to the point of maximum volume (point C), and the envelopes decrease in size. An example is shown in figure 6 for a contact angle of 40°.

The calculated configurations are always stable to the conjugate point condition (Eq. (35)). Thus, the equilibrium bubble configuration are all stable up to the point of maximum volume. Re-entrant contact angles are more often than not unstable; however, for purposes of the calculation of the maximum bubble volume on a flat surface (as addressed by Wark (1933)), the bubble of maximum volume for a given contact angle is stable to an axisymmetric disturbance in shape.

The maximum bubble volume is given as a function of contact angle in Figure 7 for $L_c = 0.273$ cm. A least-squares fit of these data gives the correlation

$$\frac{V_{max, flat}}{\pi L_c^3} = 0.285 \ \theta^{2.96} \quad (\theta \text{ in radians}) \quad . \tag{36}$$

which has a maximum error of 3% at $\theta = 9^{\circ}$, and an average error of magnitude 0.7% from 9 to 90°. Our correlation is a minor improvement over that of Fritz (1935) and Cheh (1967), which has an average error of magnitude 4%.

5. The Size of a Bubble on a Curved Support

The calculation of the bubble interface for a bubble on a curved surface is identical to that for a horizontal support. The difference appears in the end point condition, the specified angle of contact measured through the liquid phase. The thermodynamic contact angle is the same as that used previously for a flat surface because Young's equation (Eq. (2)) can be derived independently of the orientation



Figure 6. Relevant parameters in the determination of the stability of equilibrium bubble configurations for $\theta = 40^{\circ}$.



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Figure 7. The maximum stable equilibrium bubble volume as a function of contact angle for parameters characteristic of water at 25 °C ($L_c = 0.273$ cm).

of the surface. If one assumes that this equilibrium angle is maintained, a geometric relation obtains between the thermodynamic contact angle θ , the radius of contact r_c , the radius of curvature of the surface r_w , and the contact angle θ_h measured from the bubble interface to the horizontal. This geometric relation is demonstrated in Figure 8 and is given by

$$r_c = r_w \sin(\theta - \theta_h) \quad . \tag{37}$$

To apply Eq. (37), we return to the families of solutions generated for a given value of θ_h , as described in Section 3. We plot the calculated values of volume as a function of r_c for values of θ_h (which is equal to θ for a flat surface), as in Figure 4. We then choose the radius of curvature of the surface r_w and a contact angle θ . For any value of θ_h , we calculate r_c according to Eq. (37) and generate a new family of solutions. This procedure is demonstrated graphically in Figure 9, which shows two solutions for $r_w = 0.1$ cm and $\theta = 60^{\circ}$ (circles) and $\theta = 90^{\circ}$ (squares). The point of maximum volume for a given θ and r_w falls on a dashed curve, which corresponds to one of the configurations determined to be unstable. It becomes obvious that the maximum stable volume for a given θ and r_w will be found when the curve generated for $V(r_c, \theta, r_w)$ intersects one of the curves for $V(\theta_h, r_c)$ at the point of the maximum volume on the $V(\theta_h, r_c)$ curve. This simplifies the procedure considerably, as now we have only to find the intersection of the curve for $r_{c}(\theta_{h})$ at the maximum volume with the curve for the geometric relationship (Eq. (37)) $r_c(\theta_h)$ for a given θ , r_w . The curve of r_c vs θ_h at the maximum volume is given in Figure 10.

We choose values for r_w and θ and calculate r_c as a function of θ_h from Eq.



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Figure 9. Graphical solution of the problem of a bubble on a curved surface. Curves are for $V(\theta_h, r_c)$. Symbols represent points where Eq. (37) is satisfied for contact angles of 60° (•) and 90° (\blacksquare).



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(37). The point where this curve crosses the curve of $r_c(\theta_h)$ in Figure 10 is found by numerical interpolation. This procedure is demonstrated graphically in Figure 11 for $r_w = 0.1$ cm for five values of θ from 30 to 90°. The corresponding volumes are also numerically interpolated. Figure 12 shows the bubble configurations of maximum volume for $\theta = 60°$ on a flat surface and on a hemispherical surface of curvature $r_w = 0.1$ cm.

The above procedure was repeated for contact angles from 10 to 90° and r_w from 0.01 to 1.0 cm. Figure 13 shows the maximum stable equilibrium bubble volume as a function of contact angle θ and radius of curvature of the surface r_w . The corresponding reduction in volume as a result of the curvature of the surface is shown in Figure 14, which shows the ratio of the maximum volume on a curved surface to that on a flat surface as a function of θ and r_w .

The goal of this work has been to obtain a simple correlation for the volume reduction resulting from the curvature of the surface. From Figure 14, we expect

$$\frac{V_{max,r_w}}{V_{max,flat}} \to 0 \text{ as } r_w \to 0$$

 $\rightarrow 1 \text{ as } r_w \rightarrow \infty$

$$\rightarrow 1 \text{ as } \theta \rightarrow 0$$
 .

Several forms for the correlation were tested, some based on physical arguments, others based on manipulation of the equations and the graphical results, and still others more empirical. The best fit was obtained with the empirical correlation



Figure 11. Graphical solution of the problem of a bubble on a curved surface for $r_w = 0.1$ cm and five values of θ . Points of intersection are points where Eq. (37) is satisfied.



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Figure 12. Largest stable equilibrium bubble configurations with a contact angle of 30° (top row) and 60° (bottom row) on a flat surface (left), on a surface of curvature $r_w = 1.0 \text{ mm}$ (middle) and $r_w = 0.1 \text{ mm}$ (right).



Figure 13. Maximum stable equilibrium bubble volume as a function of contact angle θ and radius of curvature of the surface r_w .



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$$\frac{V_{max, r_{w}}}{V_{max, f \, lat}} = \left(\frac{r_{w}}{r_{w} + L_{c}}\right)^{0.95 \, \theta} \quad (\theta \text{ in radians}) \quad . \tag{38}$$

A nonlinear least-squares fit was used to determine if any significant improvement could be gained by writing the correlation as

$$\frac{V_{max, r_{v}}}{V_{max, f \, lat}} = a \left(\frac{r_{w}}{r_{w} + b L_{c}}\right)^{c \theta}$$
(39)

and solving for the three coefficients by minimizing the sum of squares between the fit and the determined values. The improvement in the fit does not justify using all three coefficients. The average magnitude of the error in the volume reduction using Eq. (38) is 0.02; this value was reduced only to 0.017 by using three coefficients. A demonstration of the fit of Eq. (38) for the volume reduction is shown in Figure 15. The individual points are the calculated values and the solid curves show the fit according to Eq. (38). The fit of maximum bubble volumes using γ and ρ for water at 25 °C is shown in Figure 16.

6. Conclusions

The volume of the largest stable equilibrium bubble that can adhere to a flat horizontal surface is a function of the characteristic length of the system,

$$L_c \equiv \left(\frac{\gamma}{\rho g}\right)^{1/2}$$

and the equilibrium contact angle and is given by

$$\frac{V_{max, flat}}{\pi L_c^3} = 0.285 \ \theta^{2.96} \quad (\theta \text{ in radians})$$



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Figure 15. Reduction in the maximum stable equilibrium bubble volume as a function of contact angle θ and radius of curvature of the surface r_w . Individual points are the calculated values; solid curves show the fit according to Eq. (38).



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Figure 16. The maximum stable equilibrium bubble volume as a function of contact angle θ and radius of curvature of the surface r_w . Individual points are the calculated values; solid curves show the fit according to Eqs. (38) and (36).

The bubble configurations of maximum volume for contact angles greater than 60° have re-entrant contact angles. A stability analysis that accounts for axisymmetric disturbances in bubble shape that extend over the entire surface of the bubble shows that, although re-entrant contact angles usually indicate instability, the profiles with re-entrant contact angles at the point of maximum volume are stable.

The determination of maximum bubble volume has been extended to account for the destabilizing effect of the solid support curving away from the bubble. The situation described applies exactly to a bubble growing on a hemispherical protrusion on the surface, and by extension, to a bubble growing on a wire or screen. The reduction in the maximum stable bubble volume for such a case can be described by the simple function

$$\frac{V_{max, r_{w}}}{V_{max, flal}} = \left(\frac{r_{w}}{r_{w} + L_{c}}\right)^{0.95 \theta} \quad (\theta \text{ in radians})$$

where r_w is the radius of the protrusion.

This result is the first step in accounting for the role of the morphology of the substrate on bubble size, which profoundly affects the dynamics of gas-evolution on electrode surfaces. In practice, gas is often evolved on more complex electrode geometries and on orientations other than horizontal, and further extensions of the classical theory to describe these cases will prove valuable to understanding the factors affecting electrolytic gas evolution, and also nucleate boiling, and mineral flotation.

7. Chapter 2 Nomenclature

a	fitting parameter in Eq. (39)
b	fitting parameter in Eq. (39)
с	fitting parameter in Eq. (39)
E	energy to create bubble, ergs
E ₀	dimensionless energy to create bubble
g .	acceleration of gravity, 980 cm/s 2
h	bubble height, cm
L_c	characteristic length, defined by Eq. (14), cm
М	stability parameter, defined by Eq. (35)
Ν	stability parameter, defined by Eq. (32)
p	pressure, dyne/cm ²
r _c	radius of contact at bubble base, cm
r_w	radius of curvature of support, cm
R	stability parameter, defined by Eq. (33)
R_0	radius of curvature at origin, cm
R_1	radius of curvature of interface, given by Eq. (4)
R_2	radius of curvature of interface, given by Eq. (5)
8	arc length, cm
v	dimensionless volume
$V_{max, flat}$	maximum bubble volume, cm ³
V _{max} , r _v	maximum bubble volume, curved surface, cm 3 .
x	radial coordinate, cm
z	axial coordinate, cm
β	Bond number, given by Eq. (6)
γ	surface tension, dyne/cm
ε	arbitrary small number
\$	dimensionless vertical position

η	first perturbation variable		
θ	angle of contact, degrees		
0 _h	portion of θ above horizontal, degrees		
κ	dimensionless bubble height		
λ	dimensionless radius of contact		
μ.	capillary datum = $\frac{2L_c}{R_0}$		
ν	second perturbation variable		
ξ	dimensionless radial coordinate		
ρ	density, g/cm ³		

Subscripts and superscripts

derivative with respect to s

distance made dimensionless with R_0

8. Chapter 2 References

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Chapter 3. Mass-Transfer Effects of Bubble

Streams Rising Near Vertical Electrodes

1. Abstract

Mass-transfer enhancement by a stream of bubbles rising near a masstransfer surface is resolved spatially and temporally using a micro-mosaic electrode. A stream of gas bubbles is generated electrolytically, either at a segment directly below and in the plane of the monitoring electrodes, or at a wire tip that can be positioned inside or outside of the mass-transfer boundary layer. The mass-transfer enhancement resulting from bubbles rising within the mass-transfer boundary layer is found to be strong and localized, in agreement with trends predicted by a surface-renewal model. Mass transfer resulting from bubbles rising outside the boundary layer is found to receive a steady, laminar enhancement, correlating well with predictions from an idealization of the bubble stream entraining a cylinder of liquid.

2. Introduction

Electrolytic gas evolution has been recognized in the literature since 1951 (Roald and Beck, 1951) as an efficient means of achieving high mass-transfer rates at solid surfaces. The magnitude of this effect can be illustrated by comparing the equivalent diffusion boundary-layer thicknesses for gas evolution and for forced convection. Ibl *et al.* (1971) measured mass-transfer rates during electrolysis by adding Fe⁺³ to the electrolyte as an indicator ion: the Fe⁺³ is reduced at limiting current simultaneously as the hydrogen ion is discharged. For hydrogen evolution at a planar vertical surface at a rate of 1 cm 3 /cm 2 -min , which corresponds to a current density of 130 mA /cm 2 , they determined a diffusion-layer thickness δ of 15 μ m , or a mass-transfer coefficient k of 3.6 \times 10⁻⁴ cm/sec. For comparison, we calculate the average diffusion boundary-layer thickness for developed mass transfer in turbulent channel flow with the correlation of Landau and Tobias (1976)

$$Sh \equiv \frac{d}{\delta} = 0.0113 \ Re^{0.87} \ Sc^{0.35} \qquad 2800 < Re < 12,000 \quad , \qquad (1)$$

where d is the equivalent diameter, $Re \equiv ud / \nu$ and $Sc \equiv \nu/D_i$. For a Sc of 1800, the Re required to obtain the average diffusion boundary-layer thickness of 15 μ m is 6700. In a 1-cm square channel, the equivalent diameter d is 0.5 cm and the required average velocity between parallel plate electrodes is 135 cm/sec. Thus gas evolution indeed provides a very effective stirring mechanism.

The reason gas evolution is so effective a stirring mechanism is that the bubble motion takes place in the near vicinity of the electrode surface, within and just outside the mass-transfer boundary layer. Gas evolution is itself a very complex process, involving bubble nucleation, growth, coalescence, and detachment

Mass-Transfer Effects of Bubble Streams

from the electrode. In addition to these local events, a macroscopic flow is generated by the rise of bubble swarms or curtains. In practice, forced convection is often superimposed to facilitate removal of the gas from the inter-electrode gap, thereby lowering the ohmic penalty for the presence of gas in the electrolyte.

The dominant mechanism for the high mass-transfer enhancement by gas evolution is not obvious. In fact, it may be different under different conditions of gas-evolution rate, and electrode coverage, orientation, or morphology. The traditional approach has been to assume a primary mode of mass transfer, quantify the mass-transfer rate for the chosen mode, and average over the electrode area to obtain a relation between the mass-transfer rate and the gas-evolution rate. An example of this approach would be to assume that the important mechanism of mass transfer is the diffusional mass transfer to the newly-exposed electrode site following each bubble disengagement. Several schools of thought have emerged over the past two decades, each one emphasizing a different mechanism as the main contributor. The example mentioned above is the penetration, or surface-renewal, model. These theories will be briefly reviewed in Section 3. This coverage is by no means exhaustive; the reader is referred to two recently-published reviews (Vogt (1983) and Sides (1986)) for more details on all aspects of electrolytic gas evolution.

Recent advances in integrated-circuit processing have allowed the limitingcurrent technique of measuring mass-transfer coefficients to be applied at electrodes that are sectioned on the microscopic scale. The first study of this type involving gas-evolving electrodes was conducted by Dees and Tobias (1987b). They resolved on a scale of 100 μ m (an order of magnitude smaller than the bubble diameter) the mass-transfer resulting from a single bubble detaching from a horizontal electrode,

and also that resulting from two bubbles coalescing and rising from the electrode. They found that the mass transfer following a coalescence event was significantly more intense than that following a disengagement. A coalescence and simultaneous disengagement increased the mass-transfer rate by an order of magnitude over the free-convection limiting current, while a single-bubble disengagement increased the mass-transfer rate by only a few percent.

The present study is an effort to advance our understanding of local, transient mass-transfer during electrolytic gas evolution, in much the same way as have Dees and Tobias (1987b). The objective of this work is to resolve spatially and temporally the mass transfer resulting from a single stream of gas bubbles evolved at or near a *vertical* micro-mosaic electrode. Our aim is to characterize the nature of the enhancement in an effort to fill in the missing microscopic picture, so that the correlation of mass-transfer enhancement data, and ultimately, the engineering design of gas-evolving electrodes, may be based on the fundamental physicochemical principles. The specific topic addressed in this study is the dependence of the magnitude and spatial distribution of the mass-transfer enhancement at vertical gas-evolving electrodes on bubble size, bubble stream position relative to the masstransfer surface, and rate of gas evolution.

3. Models for Mass-Transfer Enhancement

Three theories of mass transfer at gas-evolving electrodes have been advanced, each one emphasizing a particular mechanism of mass-transfer enhancement. These theories are the penetration model, the hydrodynamic model, and the micro-convection model.

3.1. The Penetration Model

The penetration model, or surface-renewal effect, was first proposed by Higbie (1935) in relation to the absorption of a gas into a liquid, and was adopted by Ibl and coworkers (Ibl and Venczel (1970)) for electrolytic gas evolution. In this description, a volume of fluid in the mass-transfer boundary layer, having been depleted of reactant, is renewed as each bubble detaches from the electrode and allows fresh electrolyte with bulk concentration of reactant to penetrate to the electrode. The transport of reactive species to the nucleation area at the electrode is by diffusion during a waiting period τ_w before a new bubble is nucleated. The reactant-ion limiting current during the waiting time falls with $t^{-1/2}$ following the Cottrell equation (1903),

$$i(t) = \frac{n_i F D_i c_i^{\infty}}{\sqrt{\pi D_i t}}$$
(2)

The average limiting current during the waiting time is

$$i = \frac{1}{\tau_w} \int_0^{\tau_w} i(t) dt = \frac{2n_i F D_i c_i^{\infty}}{\sqrt{\pi D_i \tau_w}} \quad . \tag{3}$$

If one assumes that the bubble growth time is insignificant in comparison to the total life-cycle time, the waiting time τ_w is inversely proportional to the bubble frequency and hence to the volumetric flux of evolved gas. In this case, *i* and the mass-transfer coefficient *k* will depend on *v*, the volumetric rate of gas evolution per unit area, to the 1/2 power. The constant of proportionality is subject to various assumptions involving electrode coverage and the shape of attached bubbles.

Ibl and Venczel (1970) assumed that bubbles adhering to the electrode were hemispherical in shape, covering an area of πR_b^2 . The waiting time was then the ratio of the gas volume per bubble to the product of the gas evolution rate per electrode area and the area per bubble, πR_b^2 .

$$\tau_w = \frac{2\pi R_b^3}{3v \pi R_b^2} = \frac{2R_b}{3v} \quad . \tag{4}$$

To account for the fact that, on the average, a fraction θ of the electrode is blocked by attached bubbles, Ibl and Venczel multiplied τ_w and k by $1 - \theta$. Substituting Eq. (3) into Eq. (4), they obtained

$$i = n_i F c_i^{\infty} \left(\frac{6D_i v (1-\theta)}{\pi R_b} \right)^{0.5}$$
(5)

Experimentally determined values of $\frac{\partial \ln k}{\partial \ln v}$ fall between 0.3 and 0.7. A summary is listed in Table 1.

3.2. The Hydrodynamic Model

The second theory of mass-transfer enhancement at gas-evolving electrodes is the hydrodynamic model, first proposed in relation to nucleate boiling by Zuber (1963). The model was discussed in relation to gas evolution by Janssen and Hoogland (1970, 1973) and described quantitatively by Janssen and Barendrecht (1979). This treatment emphasizes the electrolyte flow caused by the buoyant lift of the rising bubbles in the vicinity of the electrode. The mass-transfer correlation for turbulent natural convection at a plane wall,

Gas	Electrolyte	$\frac{\partial \ln k}{\partial \ln v}$	Investigator
H 。	alkaline	0.43	Green and Robinson (1959)
		0.29	Vondrak and Balei (1970)
		0.36	Janssen and Hoogland (1973)
		0.25	Found and Sedahmed (1973)
		0.65	Rousar et al. (1975)
		0.17-0.30	Janssen (1978)
H ₂	acidic	0.5(0.59)	Roald and Beck (1951)
-		0.525	Venczel (1961)
		0.47	Janssen and Hoogland (1970)
		0.62(Pt)	Janssen and Hoogland (1973)
		0.36(Hg)	Janssen and Hoogland (1973)
•	`	0.45	Kind (1975)
O 2	alkaline	0.87/0.33	Janssen and Hoogland (1973)
-		0.4	Fouad and Sedahmed (1973)
O 2	acidic	0.5	Beck (1969)
-	••	0.4	Janssen and Hoogland (1970)
		0.6	Ibl et al. (1971)
		0.57	Janssen and Hoogland (1973)
		0.66	Kind (1975)
Cl ₂	acidic	0.71	Janssen and Hoogland (1970)

Table 1. Experimentally determined values of $\frac{\partial \ln k}{\partial \ln v}$ (from Vogt (1983))

$$Sh_H \equiv \frac{kH}{D_i} = 0.16 \, (GrSc)^{1/3} \quad ,$$
 (6)

is assumed to be applicable to the case of two-phase flow. The Grashof number Gris defined

$$Gr \equiv \frac{gH^3}{\nu^2} \frac{\rho^{\infty} - \rho^0}{\rho^0} \quad , \tag{7}$$

where ρ^{∞} is the density of the bulk solution, and ρ^0 is the mean density at the electrode surface. The bulk density ρ^∞ is equal to the density of the liquid ρ_L , and

 ρ^0 is a function of the gas volume fraction ϵ : $\rho^0 = \epsilon \rho_G + (1-\epsilon)\rho_L$. For $\rho_L >> \rho_G$, the Grashof number becomes

$$Gr = \frac{gH^3}{\nu^2} \frac{\epsilon}{1-\epsilon} \quad . \tag{8}$$

Zuber (1963) related the volume fraction to the volumetric rate of gas evolution by

$$\frac{\epsilon}{1-\epsilon} = \frac{v}{v_t} \tag{9}$$

where v_t is the terminal velocity of a single bubble and, for a small spherical bubble with a rigid interface, is given by

$$v_{t} = \frac{1}{12} \frac{gd^{2}}{\nu} \frac{\rho_{L} - \rho_{G}}{\rho_{L}} \quad .$$
 (10)

Equation (9) is valid in the "turbulent" regime, in which a net upward flow is induced by the rising bubbles. If the liquid were stationary, Equation (9) would be replaced by

$$v = \epsilon v_t \quad . \tag{11}$$

Similarly, if the net upward flow were zero, so that liquid flowed downward to replace the ascending gas, one would obtain the "laminar" result of Zuber (1963)

$$v = v_t \epsilon (1 - \epsilon) \quad . \tag{12}$$

In any case, gas volume fractions are typically small compared to unity, so that $\epsilon/(1-\epsilon)$ in Equation (8) may be replaced by v/v_i . Substituting this result and Equations (8) and (10) into Equation (6), one obtains

$$Sh \equiv \frac{kd}{D_i} = 0.16 \left(\frac{12\rho_L}{\rho_L - \rho_G}\right)^{1/3} \left(\frac{vd}{D_i}\right)^{1/3}$$

$$= 0.37 \left(ReSc \right)^{1/3} . \tag{13}$$

The mass-transfer rate is proportional to the gas-evolution rate to the 1/3 power. This result may be applicable to gas evolution under certain conditions of current density and electrode coverage. Ibl and coworkers (1971) experimentally determined the slope of the $\ln k$ -versus- $\ln v$ curve to be 0.36 for gas-sparged systems.

3.3. The Micro-Convection Model

The micro-convection model was developed by Vogt (1977) and Stephan and Vogt (1979). Their approach treats the mass transfer caused by the local convection generated by the growth of an attached bubble. The electrode area per bubble available for mass transfer is $1/(n/A) - \pi R_b^2$, where R_b is a function of time. The local, transient mass transfer for laminar flow is averaged over this area and over the time of bubble growth. In the resulting correlation,

$$Sh = 0.93 \ Re^{0.5} Sc^{0.487}$$
(14)

Sh is a factor of approximately three below that calculated from the penetration model.

The important point to be gained from these mass-transfer theories is that single-bubble disturbances of the mass-transfer boundary layer, such as those emphasized in the penetration and the micro-convection models, result in a dependence of the mass-transfer coefficient on the gas-evolution rate to the 1/2power. The mass-transfer enhancement resulting from macro-convection generated by the buoyant lift of bubble swarms depends on the gas-evolution rate to the 1/3power.

4. Experimental

The micro-mosaic electrode used in this study was conceived by Dees and Tobias (1982) in this laboratory and was originally designed in a collaborative effort with the Hewlett-Packard Company. The design was modified for this investigation, and the electrodes were fabricated using integrated-circuit technology at Hewlett-Packard Laboratories, and later at AT&T Bell Laboratories. The electrode is fabricated on a 7.62-cm silicon wafer. The active area, shown in Figure 1, consists of a 5-mm platinum square. The center 1-mm square of the active area comprises a 10 \times 10 array of 98- μ m square, platinum segments on 100- μ m centers; the remaining part of the active area acts as a "buffer" segment to eliminate edge effects in the center region. An enlargement of the center section is shown in Figure 2. The electrode simulates a continuous surface, but contains one hundred electrically-isolated electrode elements.

The micro-mosaic electrode is housed in a Plexiglas cell along with two platinum counter electrodes and a reference-electrode capillary. A printed-circuit board presses onto the electrode edges to bring out the electrical connections. An o-ring seal between the cell body and the wafer ensures leak-free containment of the electrolyte. A data acquisition system developed by Dees (1983) includes currentto-voltage converters for each of the 112 segments, and a Multiplexer channel scanner which can monitor the current to each of the electrode segments at rates from 1.25 to 10.0 KHz. The data are taken by a Hewlett-Packard 9825T desktop computer, stored on floppy disk, and later transferred to a mainframe. Dees and Tobias (1982, 1987a) give a detailed description of the fabrication of the first



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Figure 1. Center 5-mm active area of the micro-mosaic electrode, including both segmented area and surrounding "buffer" section.



XBB 872-1401

Figure 2. Center segmented portion (1-mm square) of the micro-mosaic electrode.

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generation of electrodes and of the data acquisition system. The electrode fabrication steps and materials used in the electrodes built for this study are given in Appendix A.

The working electrode potential is held at a value in the region of limiting current for the reduction of the indicator ion Fe⁺³ to Fe⁺² from 0.0484-M Fe₂(SO₄)₃ in 0.5-M H₂SO₄. A bubble stream can be generated at one of the "satellite" segments in the plane of the micro-mosaic electrode by making the potential at that segment several hundred milivolts more cathodic than the rest of the electrode. The "satellite" segments were used for all of the experiments in which the bubble stream was rising within the mass-transfer boundary layer. An attempt was made in some early experiments to generate bubble streams at the segments in the bottom row of the 10 by 10 array of monitoring electrodes. The back reaction of dissolved hydrogen that was not captured by the bubble was found to overwhelm the indicator-ion reaction in the vicinity of the bubble evolution site. The magnitude of the back reaction of hydrogen was quantified by conducting experiments without addition of the indicator ion. These results are presented in Appendix B.

The experiments in which the bubble stream was generated away from the electrode surface were conducted using a modified cell top, shown in Figure 3. A post extending through the top of the cell (lower right in photo) holds a platinum wire electrode whose position with respect to the micro-mosaic electrode can be adjusted by turning the teflon nut. A Brown and Sharpe dial gauge (lower left) rests on top of the post and allows the measurement of position of the wire electrode with respect to the micro-mosaic to within about 12 μ m. The completely-



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Figure 3. Closeup of assembled cell holding micro-mosaic electrode. Brown and Sharpe dial gauge (lower left) measures position of bubble-generating electrode relative to micro-mosaic electrode.
Mass-Transfer Effects of Bubble Streams

assembled cell is shown in Figure 4, and the supporting electronics and researcher are shown in figure 5.

During the early experiments, in which the bubble stream was generated away from the electrode surface, the current was found to *decrease* as a result of the rising bubbles for bubble streams generated at 750 μ m from the mass-transfer surface. It was determined that the reference-electrode capillary (shown in Figure 3) caused the upward natural convection along the electrode to deflect downward from that point. The reference-electrode capillary was modified so that it did not extend all of the way to the top of the mass-transfer surface. All results presented in this chapter were taken after the cell was modified. Some results from the earlier experiments are presented in Appendix C.

One problem with the type of experiment described here is that the micromosaic electrodes cannot withstand attack by the aggressive solutions in which they are immersed for long times. A photographic examination of several electrodes after use indicates that the less noble metal, which is used to enhance the adhesion of the noble electrode material to the insulator, is oxidized by the electrolyte solution. Eventually the noble electrode material can detach completely from the substrate. The results of the photographic examination are presented in Appendix D. A table showing the electrodes used and their operability before and after use is given in Appendix E.

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XBC 853-2164

Figure 4. Experimental apparatus for vertical gas-evolution experiments.



XBC 853-2162

Figure 5. Experimental apparatus with researcher *in situ* for vertical gas-evolution experiments.

5. Results

The modes of mass-transfer enhancement observed for the case of the bubbles rising *within* the mass-transfer boundary layer and for the case of the bubbles rising *outside* the mass-transfer boundary layer are qualitatively distinct and lend themselves to different analyses. In this section and in the Discussion section, the results and analyses for the two cases are presented separately.

5.1. Bubbles Rising Within the Mass-Transfer Boundary Layer

Bubbles generated at the plane of the micro-mosaic electrode surface at one of "satellite" segments below the 10×10 array of monitoring electrodes are typically 45 to 100 μ m in diameter at the time of detachment. High-speed cinematography reveals that, upon leaving the growth site, a bubble slides along the electrode for a distance corresponding to several bubble diameters, and then separates from the electrode and rises at a constant separation of approximately one bubble radius. Thus the bubbles rise entirely within the free-convection masstransfer boundary layer (approximately 200 μ m in thickness), established by the indicator ion reaction. Figure 6 shows how these high-speed movies were taken. A micro-mosaic electrode was cut, and the center section mounted onto a Plexiglas strip which fits into a viewing cell. Contacts from the bonding pads at the edge of the electrode were connected with conductive silver epoxy to screws in the Plexiglas. One of the connected segments was used to generate a stream of hydrogen bubbles, and the other segments and the buffer section were polarized as they would be in a mass-transfer experiment. Figure 7 is taken from a high-speed movie of H₂



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Figure 6. Strip from micro-mosaic electrode and viewing cell, used for making high-speed motion pictures of bubbles rising along the micro-mosaic electrode.

evolution in this cell. The detached bubbles are 100 μ m in diameter. The smallest bubble, approximately 30 μ m in diameter, is still attached at the growth site. The bubble immediately above it is sliding along the electrode, and the uppermost bubble is rising at a separation of roughly 30 μ m.

Figure 8 is a photograph taken during an experiment that uses the entire micro-mosaic electrode. A stream of $60-\mu m$ -diameter bubbles is generated by an 8.5- μ A current at the lowest of the satellite segments below the array of monitoring electrodes. Figure 9 shows the current response of one of the monitoring segments directly in the path of the bubble stream. Time zero is the start of data acquisition; the transport processes are presumably in a steady, possibly periodic, state before this. The currents to two segments located at the same height, but 100 and 500 μm to the side, respectively, are also shown. One can see that the average masstransfer rate to the segments close to the bubble path is enhanced by a factor of approximately 1.5. The frequency of the oscillations corresponds to the frequency of bubble evolution. The oscillatory behavior may be attributed at least in part to the increased mass-transfer rate immediately after the bubble has passed over the segment, trailing bulk fluid in its wake. The question arises as to whether the periodic decrease in the current is caused in part by the bubble directly over the segment blocking the field, or entirely by the decrease of mass transport. One way to determine this experimentally would be to conduct the same experiment at an applied overpotential well below that required for limiting current. Another would be to capture the transient behavior when the last bubble in a series passes by the electrode. These experiments were not performed. However, it is instructive to compare the current to a segment that is directly in the path of the bubble stream



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Figure 7. Frame from a high-speed movie of bubbles rising along micro-mosaic strip electrode. Frame is 1.4 mm wide and 1.1 mm high.



XBC 853-2187

Figure 8. Photograph taken during a mass-transfer experiment showing $60-\mu m$ diameter bubbles rising along micro-mosaic electrode.



Figure 9. Current to three segments showing effect of $60-\mu m$ diameter H₂ bubbles rising within the mass-transfer boundary layer generated by an 8.5- μ A current. The three segments are 1) directly in the bubble path and 2) 100 and 3) 500 μ m to the side.

to that for a segment in the adjacent column. The segment 100 μ m to the side would presumably experience an enhanced mass-transfer, but suffer no ohmic obstruction from the passing bubbles. The corresponding curve, shown in Figure 9, exhibits almost no oscillatory behavior, but the average value is nearly the same as that for the segment directly in the path. Evidently, the field-obstruction effect does contribute to the periodic behavior.

The spatial variation of the mass-transfer enhancement due to the rising bubble streams can be seen by comparing the curves in Figure 9; one can see that at least two columns receive enhanced mass transfer due to the rising bubbles. The edge column is unaffected by the bubble stream. Figure 10 shows the spatial distribution of mass-transfer rate for the matrix of monitoring electrodes averaged over the 5-second duration of the run. The site of bubble evolution is behind the monitoring electrodes in the figure and the bubbles rise toward the viewer, as indicated by the arrow. Figures 9 and 10 show that the mass-transfer enhancement is fairly localized, affecting an area approximately four columns, or seven bubble diameters, in width. The end columns are unaffected by the rising bubbles; the current to the end columns is approximately $0.25 \ \mu$ A per segment, which corresponds to 2.5 mA /cm² or a mass-transfer coefficient of 2.5 cm/s. This is the value of the background natural-convection current, generated by the redox reaction itself.

An example showing the magnitude of the mass-transfer effect is given in Figure 11, in which the current to one segment from the column closest to the bubble path is plotted as a function of time for several experiments with different bubble evolution rates. As expected, the mass-transfer rate increases with the

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Figure 10. Spatial distribution of mass-transfer rate enhanced by $60-\mu m$ H₂ bubbles generated by an $8.5-\mu A$ current and rising within the mass-transfer boundary layer.



Figure 11. Transient mass-transfer to a segment in the column closest to the bubble stream for bubble evolution rates of 16, 8.5, and 3.5 μ A.

bubble evolution frequency. The spatial distributions of the mass-transfer rate for 3.5- and 16- μ A bubble streams can be seen in Figures 12 and 13. As the bubble evolution rate is increased, the mass-transfer rate to the segments within 200 μ m of the bubble path is increased, but the current to the edge columns remains unaffected at the value of the background natural-convection current. As will be seen in the next section, these results are in good agreement with those provided by the surface-renewal theory of mass-transfer enhancement.

5.2. Bubbles Rising Outside the Mass-Transfer Boundary Layer

For the case of bubbles rising outside the mass-transfer boundary layer, the transient response of the monitoring electrodes is much more steady in time than for the case of bubbles rising very close to the electrode. Figure 14 shows the transient mass transfer to one segment, again closest to the path of the rising bubble stream, as a result of $30-\mu$ A bubble streams rising 200, 300 and 450 μ m away from the electrode. One can see that the magnitude of the mass-transfer enhancement is strongly dependent on bubble-stream position. The oscillations in the mass-transfer rate due to the passing of individual bubbles are virtually absent when the bubble stream is 300 μ m from the electrode or beyond.

Figures 15, 16, 17, and 18 show the time-averaged mass-transfer distributions for this same series of experiments, in which the distance between the bubble evolution site and the electrode is varied from 200 to 750 μ m. The magnitude of the enhanced mass transfer decreases with increasing distance from the electrode. Note, however, that the currents to the edge columns are considerably higher than the background natural-convection current of 0.25 μ A. Even at the greatest

= 3.5 μA l bub



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Figure 12. Spatial distribution of mass-transfer rate enhanced by 50- μ m H₂ bubbles generated by a $3.5-\mu A$ current and rising within the mass-transfer boundary layer.



Figure 13. Spatial distribution of mass-transfer rate enhanced by 75- μ m H₂ bubbles generated by a 16- μ A current and rising within the mass-transfer boundary layer.



Figure 14. Transient mass-transfer to a segment in the column directly behind the bubble stream for a bubble evolution rate of 30 μ A, and bubble stream positions of 200, 300 and 450 μ m.



Figure 15. Spatial distribution of mass-transfer rate enhanced by 100- μ m H₂ bubbles generated by a 30- μ A current at 200 μ m from the electrode surface.





Figure 16. Spatial distribution of mass-transfer rate enhanced by 100- μ m H₂ bubbles generated by a 30- μ A current at 300 μ m from the electrode surface.

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Figure 17. Spatial distribution of mass-transfer rate enhanced by 100- μ m H₂ bubbles generated by a 30- μ A current at 450 μ m from the electrode surface.





Figure 18. Spatial distribution of mass-transfer rate enhanced by 100- μ m H₂ bubbles generated by a 30- μ A current at 750 μ m from the electrode surface.

distance of 750 μ m (Figure 18), at which the current distribution is fairly flat, the average current is considerably higher than the background natural-convection current, even at the the edge of the segmented area. The enhancement from bubble streams rising outside the mass-transfer boundary layer is significant, steady, and less localized than that from bubble streams rising within the mass-transfer boundary layer.

The mass-transfer rate averaged over the 1×1 mm segmented area of the electrode and over the 20-second duration of data acquisition is plotted as a function of bubble evolution rate in Figure 19 and as a function of distance in Figure 20.

6. Analysis and Discussion

6.1. Bubbles Rising Within the Mass-Transfer Boundary Layer

Bubble streams rising within the mass-transfer boundary layer result in fluctuating, localized mass-transfer enhancement to the electrode surface. In light of this, we wish to examine our results in the context of a surface-renewal theory of mass-transfer enhancement. We first present a general derivation for surface renewal at vertical gas-evolving electrodes, and then consider the special case of a single bubble stream originating from one position on the electrode.

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Figure 19. Mass-transfer rate, averaged over the area of the segmented portion of the electrode and over the time of data acquisition, as a function of bubble evolution rate.



Figure 20. Average mass-transfer rate to the segmented portion of the electrode as a function of bubble-stream position.

6.1.1. Surface Renewal at Vertical Gas-Evolving Electrodes

Consider streams of bubbles of radius R_b rising upward along the electrode surface and sweeping a renewal path of width $2R_b$. From the time a bubble crosses a horizontal line at vertical position z, until the next bubble arrives, the current density at z falls according to the Cottrell (1903) equation for transient onedimensional diffusion in a stagnant medium,

$$N = c_i^{\infty} \sqrt{\frac{D_i}{\pi t}}$$
 (15)

The average flux over the surface of the electrode is N averaged over the electrode area and over the time between surface renewals. We will follow the description by Danckwerts (1951) in considering a distribution of surface ages. Let $\phi(t)dt$ be the fraction of surface area that is of a surface age, or time since last being renewed, between t and t + dt. Let s be the mean rate of fractional surface renewal, assumed constant in time, but possibly a function of position. The fraction of surface age between t and t + dt is equal to that with surface age between t - dt and t minus the fraction renewed in time dt.

 $\phi(t)dt = \phi(t - dt)dt - \phi(t - dt)dt \cdot sdt \quad . \tag{16}$

Dividing by dt and taking the limit as $dt \rightarrow 0$ gives

$$\frac{d\phi}{dt} = -s\phi \quad . \tag{17}$$

Integrating Eq. (17) with the condition that $\int_{0}^{\infty} \phi(t) dt = 1$ gives

$$\phi(t) = se^{-st} \quad . \tag{18}$$

The average flux over time is the integral of the transient flux times the fraction of

surface with surface age t.

$$\overline{N} = \int_{0}^{\infty} N(t) \phi(t) dt$$
⁽¹⁹⁾

$$\overline{N} = \int_{0}^{\infty} N(t) s e^{-st} dt = c_i^{\infty} \sqrt{\frac{D_i}{\pi t}} s e^{-st} dt \qquad (20)$$

For the case of gas evolution at a vertical electrode, the mean rate of surface renewal by bubbles rising along the electrode is a function of vertical position z on the electrode. The fraction of surface area at height z that is renewed per unit time is equal to the rate at which bubbles cross a horizontal line of length w at height z, times the probability that any given point on the line is in the renewal path.

$$s(z) = \dot{n}_z \frac{2R_b}{w} \quad , \tag{21}$$

where R_b is the bubble radius and $2R_b$ is the renewal path width. \dot{n}_z is the total bubble evolution rate below height z and, assuming the gas evolution rate v to be uniform, is given by

$$\dot{n}_z = \frac{v}{4/3\pi R_b^3} wz$$
 (22)

Combining Eqs. (21) and (22), we obtain

$$s(z) = \frac{3vz}{2\pi R_b^2} \quad . \tag{23}$$

Integrating Eq. (20) over time gives

$$\overline{N} = \frac{1}{H} \int_{0}^{H} c_i^{\infty} \sqrt{D_i} \int_{0}^{\infty} \frac{1}{\sqrt{\pi t}} s(z) e^{-st} dt dz$$
(24)

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$$= \frac{c_i^{\infty} \sqrt{D_i}}{H} \int_0^H s(z) \left(\int_0^\infty \frac{1}{\sqrt{\pi t}} e^{-st} dt \right) dz$$
(25)

$$=\frac{c_i^{\infty}\sqrt{D_i}}{H}\int_0^H\sqrt{s(z)}dz \quad .$$
(26)

The flux to the electrode must be averaged over electrode height z from 0 to H. If s were independent of z, we would obtain the result of Danckwerts (1951)

$$\overline{N} = c_i^{\infty} \sqrt{D_i s} \quad . \tag{27}$$

Inserting Eq. (23) into (26) and integrating, we finally obtain

$$\bar{N}_A = c_i^{\infty} \sqrt{\frac{2D_i vH}{3\pi R_b^2}}$$
(28)

We would expect the above description to have validity only at low current densities, where flow of the bulk fluid does not become appreciable. Found and Sedahmed (1972) found that the mass-transfer rate increases with increasing electrode height for low current densities (2 to 10 mA /cm²) of hydrogen evolution over the entire range of electrode heights investigated (2.5 to 50 cm), though not as strongly as a square-root dependence. For higher current densities of hydrogen evolution (15 to 40 mA /cm²), the mass-transfer rate *decreases* with increasing electrode height for the shorter electrodes (2.5 to 10 cm). For oxygen evolution, the mass-transfer rate increases with increasing electrode height, in this case for the entire range of electrode heights and current densities investigated (2.5 to 50 cm, and 2 to 60 mA /cm²). Janssen and Hoogland (1970) found the opposite trend to hold for oxygen evolution at vertical electrodes of height 0.3 to 2 cm and at current densities of 10 to 400 mA /cm², the mass-transfer coefficient falling with electrode

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height to the -0.13 power.

The observed decrease of mass-transfer rate with height at short electrodes may be simply due to the increasing diffusion boundary layer thickness with height as given by boundary layer theory. For the higher current densities, the increase in mass transfer with increasing height will undoubtedly be aided by bulk convection, which was not accounted for in the above treatment. We simply note at this point that the surface-renewal theory based on bubbles sweeping a path as they slide along the electrode gives the same value (1/2) of the exponent on the gas-evolution rate v as the other surface-renewal theories.

6.1.2. Surface Renewal with a Single Bubble Stream

The surface-renewal theory applied to the experiments described in Section 3 is simpler than presented above in that we do not have a random distribution of surface ages. The bubble stream rises along the electrode surface on a particular path and sweeps a region of width $2R_b$ with a frequency equal to the bubble evolution frequency, $3\dot{V}/4\pi R_b^3$. Substituting the bubble evolution frequency for $1/\tau$ in the integrated form of Eq. (15), we obtain the average flux \overline{N}_τ to the area being renewed:

$$\overline{N}_{r} = 2c_{i}^{\infty} \sqrt{\frac{3D_{i}\dot{V}}{4\pi^{2}R_{b}^{3}}}$$

$$(29)$$

The area that is periodically renewed is $2R_b H$. The average flux to an area wH is then

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$$\bar{N}_{\tau,A} = \bar{N}_{\tau} \frac{2R_{b} H}{wH} = c_{i}^{\infty} \sqrt{\frac{12D_{i} \dot{V}}{\pi^{2}R_{b} w^{2}}}$$
(30)

The above description does not include a contribution to the average flux from the electrode area lying outside the renewal path. In fact, the rest of the electrode is receiving a flux due to the background natural-convection current density i_{nc} . The overall flux to the electrode, expressed as a current density, includes contributions from the renewal area of width $2R_b$ and the non-renewed area of width $(w - 2R_b)$.

$$i_{avg} = (i_{nc} (w - 2R_b) + n_i F \overline{N}_r 2R_b)/w$$
 (31)

$$i_{avg} = i_{nc} + \left(\frac{n_i F c_i^{\infty}}{\pi} \sqrt{\frac{12D_i RT I}{n_g F p R_b}} - 2R_b i_{nc}\right) \frac{1}{w} \qquad (32)$$

Equation (32) is valid for electrode width w greater than the renewal path $2R_b$. With the micro-mosaic electrode we can conveniently vary w by varying the number of columns of segments over which we average the mass-transfer rate. We can, in effect, vary the electrode width by simply grouping the data from the same experiment in different ways. If we plot the average current density as a function of 1/w, where w is the electrode width over which we average, we should obtain a straight line with a slope of

$$b = \frac{n_i F c_i^{\infty}}{\pi} \sqrt{\frac{12 D_i RT I}{n_g F p R_b}} - 2 R_b i_{nc} \qquad (33)$$

and a y-intercept of i_{nc} . Knowing b, i_{nc} , and I, the current to generate the bubble stream, we can solve Eq. (33) for R_b , the effective bubble radius.

If $w < 2R_b$, Eq. (32) is no longer valid; the average current becomes equal to the renewal current, $n_i F \overline{N}_{\tau}$, where \overline{N}_{τ} is given by Eq. (29). Knowing R_b , we can calculate i_{max} , the renewal current. Thus using the slope and the y-intercept from the part of the curve for small 1/w, we can calculate the limiting value of the curve as 1/w becomes large with respect to $1/(2R_b)$.

Figure 21 is the plot of the average current density versus 1/w for two experiments, in which the bubble evolution rates were 3.5 μ A and 8.5 μ A. The current distribution plots for these two runs appear in Figures 12 and 10, respectively. For small 1/w, the points lie on a straight line. The y-intercept of approximately 2.8 mA /cm² corresponds to the background natural-convection current measured independently. There is a region of transition from approximately 25 to 50 cm⁻¹, beyond which the current density reaches a plateau. The effective bubble radii from Eq. (33) for the two runs were found to be 160 and 170 μ m, factors of 6.4 and 5.7 greater than visual estimates from photographs, such as the one shown in Figure 8 for the 8.5 μ A run. Values of I and R_b were inserted into Eq. (29) to calculate the maximum current density for $1/w > 1/2R_b$. These values were found to agree within several percent with the experimentally measured values of the current to the 100- μ m -wide column of electrodes in the bubble path. These are the values plotted in Figure 21 for 100 cm⁻¹.

Table 2 summarizes the application of the surface-renewal theory to a series of five experiments in which the bubble stream rises within the mass-transfer boundary layer. The effective bubble radius varies from 5.7 to 7.5 times the experimentally-determined bubble radius. This factor is not surprising when one considers the spatial distribution of the mass-transfer rate. Figure 22 shows this distribution averaged along the height of the electrode for one of the runs described above. The visually-observed bubble diameter for this experiment is 60 μ m, while the effective bubble diameter was found to be 340 μ m. From Figure 22, we can see



Figure 21. Enhanced mass-transfer rate versus the inverse of the averaging width w for two experiments. The top curve is for a 60- μ m diameter H₂ bubble stream evolved at a rate of 8.5 μ A within the mass-transfer boundary layer. The second is for a 50- μ m diameter H₂ bubble stream evolved at a rate of 3.5 μ A.





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Ι	R _b	inc	10 ² b	Rb, eff	Eff.	i exp i max	i calc i max	Δ
(µA)	(µm)	(mA /cm ²)	(mA /cm)	(μm)	factor	(mA /cm ²)	(mA /cm ²)	%
3.5	25	2.69	2.73	160	6.4	3.54	3.54	0.0
4.5	22	2.51	4.88	159	7.2	4.06	4.04	0.4
8.5	30	2.91	7.01	172	5.7	5.07	4.95	2.4
9.0	22	2.82	8.67	164	7.5	5.66	5.46	3.5
16.0	38	2.71	8.93	218	5.7	5.46	4.76	12.8

Table 2. Effective bubble radii and renewal currents from Eqs. (33) and (29)

that the path of enhanced mass transfer is appreciably wider than the actual bubble diameter. In the simplified theory described here, we consider the actual distribution shown in Figure 22 to be idealized as having only two possible values, as shown by the dashed curve: the value of the current to the renewal path is i_{max} and that to the rest of the electrode is i_{nc} . The width of the renewal path and the values of i_{max} and i_{nc} were taken from the low 1/w values; these are found to match i_{nc} measured in independent experiments, and also i_{max} for large 1/wvalues. Thus the effectiveness factor of 6 to 7.5 is a physically-meaningful quantity, representing the width of the renewal path for a bubble stream rising within the mass-transfer boundary layer.

6.2. Bubbles Rising Outside the Mass-Transfer Boundary Layer

When the bubble stream is rising outside the mass-transfer boundary layer, the mass-transfer enhancement is a relatively steady process; the effects of individual bubbles are averaged somewhat. This suggests a treatment in terms of an assisting laminar flow enhancement. We first attempt to account for the background natural-convection at the electrode.

6.2.1. Background Natural Convection and Assisting Flows

The redox reaction itself causes a density difference between the fluid at the electrode surface and the bulk fluid, the fluid near the electrode being less dense than that of the bulk. This phenomenon is rather complex, involving the multicomponent diffusion and migration of ionic species in concentration and potential gradients. The subject is treated in considerable detail in Chapter 4. In the cell geometry used in this study, the less dense fluid generated at the electrode causes an upward laminar flow along the electrode surface, which dissipates beyond the upper edge of the active region on the electrode. Under mass-transfer control, in the absence of any bubble generation at the electrode, there is a non-uniform current distribution along the electrode: the local current density is proportional to the distance from the lower edge to the negative one-fourth power. The experimentally measured mass-transfer distribution for laminar, natural-convection flow at the micro-mosaic electrode is shown in Figure 23.

For the case of assisting laminar flows, Churchill (1977) has shown experimentally, and Ruckenstein and Rajagopalan (1980) have demonstrated using scaling arguments that the cube of the effective mass-transfer coefficient is equal to

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Figure 23. Spatial distribution of the background natural-convection masstransfer rate generated by the redox reaction itself. The upward direction is indicated by the arrow in the figure.

the sum of the cubes of the component coefficients.

$$k_{tot}^{\ 3} = k_1^{\ 3} + k_2^{\ 3} \quad . \tag{34}$$

The mass-transfer coefficient is directly proportional to the current density as $i = n_i Fkc_i^{\infty}$, so the measured current densities combine in the same way. The background natural-convection current density to the area of the 10 \times 10 array of monitoring electrodes is measured between gas-evolution runs. This value is subtracted from the total mass-transfer rate measured during the gas-evolution experiments according to Eq. (34). The resulting mass-transfer rate due solely to the influence of the bubble stream is presented as a function of bubble evolution rate in Figure 24, and as a function of bubble stream position in Figure 25.

6.2.2. Comparison to Rising Cylinder

The steady nature of the mass-transfer enhancement when the bubble stream is outside the mass-transfer boundary layer suggests an idealization of the bubble stream as a steadily-rising column of bubbles and entrained fluid. The masstransfer enhancement in such a case results from an increased velocity gradient in the vicinity of the electrode.

6.2.2.1. Velocity Field around a Cylinder Rising Parallel to a Wall

The velocity profile for an infinite cylinder rising parallel to a stationary wall can be derived analytically. In rectangular coordinates, x is the normal distance from the electrode, y is the horizontal distance parallel to the electrode, and z is the vertical distance parallel to the electrode and to the axis of the cylinder. The laminar flow problem involves only the z-component of velocity. For $v_z(x, y)$, the



Figure 24. Mass-transfer enhancement, averaged over the segmented portion of the electrode and over the time of data acquisition, and corrected for the background natural-convection current, as a function of bubble evolution rate.


Figure 25. Average mass-transfer enhancement to the segmented portion of the electrode, corrected for the background natural convection current, as a function of bubble stream position.

Navier-Stokes equation reduces to

$$\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} = 0 \quad . \tag{35}$$

The problem can be solved by transforming to bi-cylindrical coordinates (Moon and Spencer, 1961), shown in Figure 26. In this geometry, Laplace's equation is

$$\nabla^2 v_z = \frac{(\cosh \eta - \cos \psi)^2}{a^2} \left(\frac{\partial^2 v_z}{\partial \psi^2} + \frac{\partial^2 v_z}{\partial \eta^2} \right) + \frac{\partial^2 v_z}{\partial z^2} \quad , \tag{36}$$

where

$$x = \frac{a \sinh \eta}{\cosh \eta - \cos \psi}$$
 and $y = \frac{a \sin \psi}{\cosh \eta - \cos \psi}$ (37-a,b)

and a is a constant of the geometry to be determined later. If $v_z \neq f(z)$, Eq. (36) reduces to

$$\nabla^2 v_z = \frac{\partial^2 v_z}{\partial \psi^2} + \frac{\partial^2 v_z}{\partial \eta^2} = 0 \qquad (38)$$

The boundary conditions are that the velocity vanishes at the electrode and is equal to the velocity of the cylinder v_c at η_c :

$$v_z = 0 \quad \text{at} \quad \eta = 0 \tag{39-a}$$

$$v_z = v_c \quad \text{at} \quad \eta = \eta_c \quad . \tag{39-b}$$

The problem is symmetric at $\psi = 0$ and $\psi = \pi$ so we expect

$$\frac{\partial v_z}{\partial \psi} = 0 \quad \text{at} \quad \psi = 0 \tag{40-a}$$

$$\frac{\partial v_z}{\partial \psi} = 0 \text{ at } \psi = \pi$$
 (40-b)

There is in fact no reason to expect any dependence of the velocity field on ψ , and the solution to Eq. (38) is simply

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Figure 28. $\eta - \psi$ plane (x-y plane) of bi-cylindrical coordinate system for an infinite cylinder rising parallel to a plane wall. Lines of constant η are eccentric circles with radius proportional to $1/\eta$; $\eta = 0$ is the wall.

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$$v_z = A + B \eta \quad . \tag{41}$$

Inserting boundary conditions (40-a,b) we find

$$v_z = v_c \frac{\eta}{\eta_c} \quad . \tag{42}$$

The complexity of the problem arises from transforming the solution back to rectangular coordinates. Solving Eq. (37-a) for $\cos\psi$ and substituting into Eq. (37-b), we find the equation for a circle (constant η) to be

$$y^{2} + (x - a \coth \eta)^{2} = \frac{a^{2}}{\sinh^{2} \eta}$$
 (43)

Solving Eq. (43) for η , we have

$$\eta = \frac{1}{2} \ln \left(\frac{x^2 + y^2 + a^2 + 2ax}{x^2 + y^2 + a^2 - 2ax} \right) \quad . \tag{44}$$

The cylinder is described by the circle at η_c . We need to solve for η_c and the constant a in terms of the radius R_c and the distance L from the center of the cylinder to the wall. By inspection of Eq. (43) we have

$$R_c = \frac{a}{\sinh \eta_c}$$
 and $L = a \coth \eta_c$. (45-a,b)

Combining Eqs. (45) we obtain

$$a = \sqrt{L^2 - R_c^2} \tag{46}$$

$$\eta_c = \cosh^{-1}\left(\frac{L}{R_c}\right) = \ln\left(\frac{1}{R_c}\left(L + \sqrt{L^2 - R_c^2}\right)\right)$$
(47)

The velocity contours from Eq. (42) are shown in Figure 27 for a 100- μ m diameter cylinder rising at a center-to-wall distance of 200 μ m, and in Figure 28 for 750 μ m. Both the velocity gradient and the non-uniformity of the gradient along the electrode surface (y = -500 to 500μ m) decrease as the cylinder is moved from



Figure 27. Lines of constant velocity for a 100- μ m diameter cylinder rising at 200 μ m from the electrode surface.



Figure 28. Velocity contours for a 100- μ m diameter cylinder rising at 750 μ m from the electrode surface.

200 to 750 μ m. The essence of the idealization of the bubble stream as a rising cylinder can be seen in these two figures; the rising cylinder creates a high velocity gradient at the electrode surface. To obtain the same velocity gradient at the surface by forced convection of the bulk fluid, one would have to maintain fairly high flow rates of all the fluid in the cell. The cylinder or bubble stream drags the fluid that is very near the electrode surface upward, producing a high velocity gradient without carrying a large amount of fluid.

6.2.2.2. Mass-Transfer Effect Caused by a Rising Cylinder

We solve next for the mass-transfer rate to the electrode at x = 0 (i.e. $\eta = 0$), and z > 0, by solving for the gradient of velocity at the wall and inserting this into the equation of convective diffusion. The equation of convective diffusion is

$$\frac{\partial c_i}{\partial t} + \mathbf{v} \cdot \nabla c_i = D_i \nabla^2 c_i \quad . \tag{48}$$

The first term is zero at steady state, and the only component of velocity is $v_z(x, y; L, R_c)$. In rectangular coordinates, Eq. (48) becomes

$$v_{z} \frac{\partial c_{i}}{\partial z} = D_{i} \left(\frac{\partial^{2} c_{i}}{\partial x^{2}} + \frac{\partial^{2} c_{i}}{\partial y^{2}} + \frac{\partial^{2} c_{i}}{\partial z^{2}} \right) \quad .$$
(49)

The boundary conditions are

$$c_i(x = 0, \text{ all } y, z > 0) = c_i^0$$
 (50-a)

$$c_i (x = 0, \text{ all } y, z \leq 0) = c_i^{\infty}$$
(50-b)

$$c_i(x \to \infty, \text{ all } y, \text{ all } z) = c_i^{\infty}$$
 (50-c)

Diffusion in the y-direction may be neglected since the driving force for

concentration changes is primarily in the x-direction. We make Eq. (49)

dimensionless with

$$v_z^* \equiv \frac{v_z}{v_c} \quad , \tag{51-a}$$

$$\theta_i \equiv \frac{c_i - c_i}{c_i^{\infty} - c_i^{0}} , \qquad (51-b)$$

and

$$\xi \equiv \frac{x}{a} \quad . \tag{51-c}$$

Substituting Eqs. (51) into Eq. (49), we obtain

$$\left(\frac{v_c a^2}{D_i}\right) v_z^* \frac{\partial \theta_i}{\partial z} = \frac{\partial^2 \theta_i}{\partial \xi^2} + a^2 \frac{\partial^2 \theta_i}{\partial z^2} \quad .$$
(52)

The appropriate scaling of z becomes obvious from Eq. (52):

$$\varsigma \equiv \frac{z}{\frac{v_c a^2}{D_i}}$$
 (53)

Eq. (52) becomes

$$v_z^* \frac{\partial \theta_i}{\partial \varsigma} = \frac{\partial^2 \theta_i}{\partial \xi^2} + \left(\frac{D_i}{v_c a}\right)^2 \frac{\partial^2 \theta_i}{\partial \varsigma^2} \quad . \tag{54}$$

Defining the Peclet number Pe as av_c/D_i we have

$$v_z^* \frac{\partial \theta_i}{\partial \varsigma} = \frac{\partial^2 \theta_i}{\partial \xi^2} + \frac{1}{Pe^2} \frac{\partial^2 \theta_i}{\partial \varsigma^2} \quad . \tag{55}$$

Although the cases we will consider have Re on the order of unity, the Peclet number ($Pe \equiv ReSc$) is high because of the high Schmidt number (~ 2000). Thus we can neglect diffusion in the flow direction and solve

$$v_z^* \frac{\partial \theta_i}{\partial \varsigma} = \frac{\partial^2 \theta_i}{\partial \xi^2}$$
(56)

with boundary conditions

 $\theta_i \left(\xi = 0, \, \varsigma > 0\right) = 0 \tag{57-a}$

$$\theta_i (\xi = 0, \, \varsigma \le 0) = 1$$
 (57-b)

$$\theta_i (\xi \to \infty, \text{ all } \varsigma) = 1$$
 (57-c)

For small ξ we can approximate v_z as $\frac{\partial v_z}{\partial \xi} \Big| \qquad \xi.$

$$v_{z} = \frac{\partial v_{z}}{\partial \xi} \begin{vmatrix} \xi = \frac{\partial v_{z}}{\partial x} \\ \xi = 0 \end{vmatrix} x = 0 \qquad x = 0 \qquad y = 0 \qquad x = 0 \qquad (58)$$

From Eq. (42)

$$\frac{\partial v_s}{\partial \eta} = \frac{v_c}{\eta_c} \quad , \tag{59}$$

and from Eq. (44)

$$\frac{\partial \eta}{\partial x} \bigg|_{x = 0} = \frac{2a}{y^2 + a^2}$$
 (60)

Substituting Eqs. (58)-(60) into (56) and defining $f \equiv y/a$, we obtain

$$\frac{2\xi}{\eta_c \left(f^2 + 1\right)} \frac{\partial \theta_i}{\partial \varsigma} = \frac{\partial^2 \theta_i}{\partial \xi^2} \quad . \tag{61}$$

The similarity variable

$$\lambda \equiv \xi \left(\frac{2}{9\eta_c \left(f^2 + 1 \right) \varsigma} \right)^{1/3} \tag{62}$$

transforms Eq. (61) to

$$\frac{d^2\theta_i}{d\lambda^2} + 3\lambda^2 \frac{d\theta_i}{d\lambda} = 0 \quad . \tag{63}$$

Boundary conditions (57) become

$$\theta_i (\lambda = 0) = 1$$
 (64-a)
 $\theta_i (\lambda = \infty) = 0$. (64-b)

The solution to Eq. (63) with boundary conditions (64) is

$$\theta_i = \frac{1}{\Gamma(4/3)} \int_{\lambda}^{\infty} \exp(-\lambda^3) \, d\,\lambda \qquad (65)$$

The flux to the electrode is found by

$$N_{i} = -D_{i} \frac{\partial c_{i}}{\partial x} \bigg|_{x} = 0 = -D_{i} (c_{i}^{\infty} - c_{i}^{0}) \frac{\partial \theta_{i}}{\partial \lambda} \bigg|_{\lambda} = 0 \qquad (66)$$

$$= \frac{-D_i \left(c_i^{\infty} - c_i^{0}\right)}{\Gamma(4/3)} \left(\frac{2av_c}{9D_i \eta_c}\right)^{1/3} \left(\frac{1}{y^2 + a^2}\right)^{1/3} \left(\frac{1}{z}\right)^{1/3} .$$
(67)

6.2.2:3. Equivalent Velocity of Rising Cylinder

The only quantity in Eq. (67) still to be specified is v_c , the cylinder velocity. There are three possibilities: 1) equate the volumetric flow rate of the cylinder to that of the rising bubbles, 2) equate the drag on the rising cylinder to the drag on the rising bubbles, or 3) allow the cylinder to rise at the terminal velocity of the individual bubbles. The first option allows for no entrainment of the liquid by the rising bubbles, the second for intermediate entrainment, and the third for maximum entrainment. This last possibility can be eliminated by noting that v_c would not depend on bubble evolution rate, but only on bubble size, which is not the case (See Figure 24).

Equating the gas flows for the cylinder and the bubble stream, (Option 1), we find

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$$v_c = \frac{V}{\pi R_b^2} = \frac{IRT}{n_g F p \pi R_b^2} \quad , \tag{68}$$

and the mass-transfer rate due to the rising cylinder is dependent on $I^{1/3}$.

In Option 2, the case of equal drag forces, the drag on the cylinder can be calculated by integrating the tangential force over the area of the cylinder. It is simpler, however, to calculate the drag on the wall (which must be equivalent since the wall is infinite). The drag on the wall is

$$F_D = 2 \int_0^\infty \int_0^l \mu \frac{\partial v_z}{\partial x} \Big|_{x = 0} dz dy$$
(69)

$$\frac{F_D}{l} = 2 \int_0^\infty \mu \left. \frac{\partial v_z}{\partial x} \right|_{x=0} dy \qquad (70)$$

Substituting Eqs. (59) and (60) for $\frac{\partial v_z}{\partial x}\Big|_{x=0}$ into (70) we obtain

$$\frac{F_D}{l} = \frac{4av_c \,\mu}{\eta_c} \int_0^\infty \frac{1}{y^2 + a^2} \, dy \tag{71}$$

$$= \frac{4av_c \mu}{\eta_c} \frac{1}{a} \tan^{-1} \frac{y}{a} \bigg|_{y=0}^{y=\infty}$$
(72)

$$=\frac{4\mu v_c}{\eta_c}\left(\frac{\pi}{2}-0\right) \tag{73}$$

$$\frac{F_D}{l} = \frac{2\mu v_c \pi}{\eta_c}$$
(74)

The drag on a series of bubbles is computed by assuming that the bubbles act independently and rise in Stokes flow. Faxén (1923) solved for the total drag force on a single bubble rising at terminal velocity v_i and distance L from a wall:

$$\frac{F_D}{\text{bubble}} = \frac{6\pi\mu R_b v_t}{f (R_b/L)} \quad , \tag{75}$$

where $f(R_b/L)$ is the correction for the presence of the wall and is given by (Happel and Brenner (1965), p.327)

$$f\left(\frac{R_b}{L}\right) = 1 - \frac{9}{16}\left(\frac{R_b}{L}\right) + \frac{1}{8}\left(\frac{R_b}{L}\right)^3 - \frac{45}{256}\left(\frac{R_b}{L}\right)^4 - \frac{1}{16}\left(\frac{R_b}{L}\right)^5 \quad . \tag{76}$$

The frictional drag force per unit length of a rising column of bubbles is the product of the frictional drag force per bubble (2/3 of the total drag force) and the bubble frequency, divided by the bubble velocity:

$$\frac{F_D}{l} = \frac{F_D}{\text{bubble}} \frac{\dot{V}}{\frac{4}{3}\pi R_b^3 v_l} = \frac{6\mu \dot{V}}{2R_b^2 f (R_b/L)}$$
(77)

Combining Eqs. (77) and (74), we finally obtain

$$v_{c} = \frac{V}{\pi R_{b}^{2}} \frac{9\eta_{c}}{4f(R_{b}/L)} = \frac{IRT}{n_{g}Fp\pi R_{b}^{2}} \frac{9\eta_{c}}{4f(R_{b}/L)}$$
(78)

In the above treatment, we have chosen, somewhat arbitrarily, to exclude the form drag from the bubble force calculation. By this choice we attempt to account for the fact that the bubbles do not act independently: each bubble decreases the form drag on the bubble that follows.

We have also chosen to fix the radius of the cylinder (at the radius of the bubbles), and to vary the cylinder velocity. If we had done the reverse, we would obtain the same result in the maximum entrainment case (Option 3). In the case of equivalent volumetric flowrate (Option 1), we would obtain only a weak dependence on bubble evolution rate. In the case of equivalent drag (Option 2), we would obtain the identical result as that derived above (Eq. (78)).

The average mass-transfer enhancement due to the rising cylinder is evaluated in terms of the average current density by integrating Eq. (67) over the Mass-Transfer Effects of Bubble Streams

electrode area:

$$i_{avg} = \frac{-nFD_{i}\left(c_{i}^{\infty}-c_{i}^{0}\right)}{s_{i}\Gamma(4/3)} \left(\frac{2av_{c}}{9D_{i}\eta_{c}}\right)^{1/3} \times \frac{3}{2} \left(\frac{z_{2}^{(2/3)}-z_{1}^{(2/3)}}{z_{2}-z_{1}}\right) \frac{1}{y_{2}-y_{1}} \int_{y_{1}}^{y_{2}} \left(\frac{1}{y^{2}+a^{2}}\right)^{1/3} dy \quad , \tag{79}$$

with v_c given by Eq. (68) or (78).

The predicted current distribution resulting from a rising cylinder that is equivalent, on the basis of equivalent drag, to a 30- μ A bubble stream at 200 μ m is shown in Figure 29. The current distribution resulting from a stream of the same diameter and rise velocity, but positioned at 750 μ m is shown in Figure 30. Figures 29 and 30 include the background natural-convection mass transfer, added according to Eq. (34), so that they may be compared directly to the experimentally measured current distributions, Figures 15 and 18, respectively. The degree of nonuniformity in the calculated and experimental distributions agrees reasonably well. The agreement between the calculated and experimental average mass-transfer enhancement is excellent. Figure 31 compares, as a function of bubble evolution rate, the experimental and calculated mass-transfer rates for a bubble-stream-to-wall separation of 200 μ m. The calculated results for both equivalent drag (Eq. (78)) and equivalent volummetric flow of gas (Eq. (68)) are shown. The former matches experiment very well; the latter would be expected to present a lower limit to the mass-transfer enhancement. The functionality of the dependence of mass-transfer enhancement on bubble evolution rate is seen to agree with the one-third power dependence predicted by the model. This result implies that the enhancement is due to a laminar flow of gas and liquid. Figure 32 shows the same comparison for a

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Figure 29. Mass-transfer distribution resulting from a 100- μ m diameter cylinder rising at 200 μ m from the electrode surface, at a rate equivalent to a 30- μ A rate of gas evolution. The background natural-convection current is included.



Figure 30. Mass-transfer distribution resulting from a 100- μ m diameter cylinder rising at 750 μ m from the electrode surface, at a rate equivalent to a 30- μ A rate of gas evolution. The background natural-convection current is included.



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separation of 300 μ m and Figure 33 for a separation of 450 μ m. The agreement between experiment and theory decreases with increasing separation. In part this reflects a weakness of the theory, but also, as the total mass-transfer rate approaches the background natural-convection mass-transfer rate, the sensitivity of the determined value of the enhancement to experimental error increases.

In summary, the rising cylinder model describes the effect of an increased laminar flow along the electrode and neglects individual bubble effects. The resulting mass-transfer rate matches the experimentally measured values in both magnitude and distribution. The measured dependence of the mass-transfer enhancement on the bubble-stream-to-electrode separation is stronger than predicted by the cylinder model.

7. Conclusions

The mass-transfer enhancement due to a stream of bubbles rising along a vertical electrode has been characterized by transient and spatial resolution using an indicator ion reaction at a micro-mosaic electrode. Bubbles rising within the masstransfer boundary layer create a strong, localized, periodic enhancement. Spatial resolution of these effects reveals a mechanism consistent with a surface-renewal theory of mass-transfer enhancement. The effective renewal path of the bubbles is typically 5 to 7 bubble diameters wide.

Bubble streams rising outside the mass-transfer boundary layer cause a steady increase in the mass-transfer rate over a large area. The mass-transfer enhancement in this case depends on the bubble evolution rate to the one-third



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Figure 32. Comparison of mass-transfer enhancement as a function of bubble evolution rate 1) measured for a single stream of bubbles and 2) calculated for a steadily-rising cylinder, both centered at 300 μ m from the electrode.



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power, a result of an increased velocity gradient at the electrode surface. The experimental results are consistent with a laminar-flow model that treats the rising column of bubbles and entrained liquid as an equivalent cylinder rising with the same friction drag.

8. Chapter 3 Nomenclature

a	constant of bi-cylindrical geometry, given by Eq. (47), cm
Ь	slope of i vs $1/w$, given by Eq. (33)
c _i	concentration of indicator ion, mol $/\text{cm}^3$
d	bubble diameter or equivalent channel diameter, cm
D _i	diffusivity of indicator ion, cm $^2/s$
f	dimensionless y coordinate
F	Faraday constant, 96,487 C/eq
F _D	drag force, g-cm/s ²
Gr	Grashof number
H	electrode length, cm
i	current density, A/cm 2
i _{avg}	current density, averaged over electrode area, A/cm 2
Ibub	bubble evolution rate, A
inc	natural-convection current density, A/cm^2
i _{max}	current density to renewal path, A/cm 2
k	mass-transfer coefficient, cm/s
1	cylinder length, cm
L	distance between wall and bubble column distance or cylinder, cm
n _i	number of electrons transferred in the indicator reaction
n_g	number of electrons transferred in gas-evolution reaction

n _z	cumulative bubble evolution rate below height z , s ⁻¹
n/A	number of bubbles evolved per unit area, cm $^{-2}$
Ν	flux, mol/cm ² -s
\overline{N}	flux averaged over time, mol/cm ² -s
\overline{N}_{A}	flux averaged over time and area, mol/cm 2 -s
$\overline{N}_{ au}$	flux averaged over waiting time, mol/cm^{2} -s
$\overline{N}_{ au,A}$	flux averaged over waiting time and area, mol/cm 2 -s
p	pressure, atm
Pe	Peclet number, $v_c a / D_i$
R	universal gas constant, 82.055 cm ³ -atm/mol-K
R _b	bubble radius, cm
R _c	cylinder radius, cm
Re	Reynolds number, $v_c a / \nu$
8	fraction of surface renewed per time, s^{-1}
<i>s</i> _i	stoichiometric coefficient of indicator ion in the electrode reaction
Sc	Schmidt number, ν/D_i
Sh	Sherwood number, dimensionless mass flux
t	time, s
T	temperature, K
u	liquid velocity, cm/s
v	gas evolution rate per unit area, cm $^3/$ cm $^2-$ s
v _c	cylinder velocity, cm/s
v_z	fluid velocity, cm/s
vz*	fluid velocity, made dimensionless with v_e
v_t	terminal velocity of rising bubble, cm/s
\dot{V}	volumetric gas evolution rate, cm $^3/s$
w	electrode width, cm
x	horizontal distance from electrode surface, cm
y	horizontal distance along electrode surface, cm
2	vertical distance along electrode surface, cm

δ	diffusion boundary-layer thickness, cm
ε	gas volume fraction
\$	dimensionless z coordinate
η	bi-cylindrical geometry coordinate
θ	fraction of electrode area shadowed by attached bubbles
θ _i	dimensionless concentration of indicator ion
λ	similarity variable defined by Eq. (62)
μ	viscosity, g/cm-s
ν	kinematic viscosity, cm $^{2}/s$
ξ	dimensionless x coordinate
ρ	density, g/cm ³
$ au_w$	waiting time between bubble departure and nucleation, s
$oldsymbol{\psi}$	bi-cylindrical geometry coordinate

Subscripts and superscripts

i	indicator ion
0	at the electrode surface
∞	in the bulk solution

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Chapter 4. The Onset of Buoyancy-Induced

Convection at a Micro-Mosaic Electrode

1. Abstract

The onset of convection is investigated for a case in which the density profile is evolving in time in a semi-infinite fluid, due to a step change in surface concentration at a rigid, conducting boundary. The limiting current technique at a micro-mosaic electrode, which is composed of $100-\mu$ m, square elements, is used to effect the concentration change and to monitor the resulting mass transfer. The equations of transient mass transport by diffusion and migration and the equation of electroneutrality are solved numerically to determine the concentration and density profiles before the onset of convection. The critical Rayleigh number based on the penetration depth of the concentration profile was found to be approximately 900, and the critical Rayleigh number based on the position and magnitude of the density profile was found to be approximately 1750. The micro-mosaic electrode is used to demonstrate the dependence of experimentally-determined onset times on the size of the sensing elements and the sensitivity of the monitoring instruments.

2. Introduction

An adverse density gradient in a horizontal fluid may induce convection if it is of sufficient magnitude and extends over a sufficient distance. The criterion for the onset of convection in such a fluid, confined between two rigid boundaries and containing a linear density profile, has become known as the Bénard-Rayleigh stability problem. Bénard-Rayleigh instability can result from temperature or concentration gradients. We consider here a variation of the Bénard-Rayleigh problem in which the density profile is nonlinear, time-dependent, and does not extend far enough into the fluid to be affected by the presence of the second boundary. This type of situation occurs in nature, as in heat transfer at the surface of a body of water. Several examples of engineering interest include thermal effects in buildings and electronic equipment, mass-transfer effects in chemical processes that involve gas-liquid contacting, and in electrochemical processes, which inherently involve concentration gradients extending into solution from a solid boundary.

Many electroanalytical techniques involve a variation of electrode potential in a stagnant medium. Even though the resulting concentration gradients may be small, significant density gradients may result due to the strong dependence of solution density on species concentrations. That this effect may be important for metal deposition reactions is more readily apparent than for redox reactions, in which there is no net removal of material at the electrode. However, the combined effects of diffusion and migration of ionic species in an electric field can result in significant density gradients in the vicinity of the electrode for redox systems as well. The key objective of this work is to quantify experimentally the criterion for convection onset in electrochemical redox systems, and to relate this criterion to theoretical work on stability for this type of problem.

Several researchers have used electrochemical techniques to effect a density gradient at an electrode and monitor the resulting mass transfer. The earliest investigations (Wagner (1949), Wilke, Eisenberg, and Tobias (1953), and Ibl and Muller (1958)) involved determination of free-convection mass transfer at vertical electrodes. Fenech and Tobias (1960) deposited copper at limiting current from acid copper sulfate solutions onto a horizontal cathode facing upward. Depletion of the copper ion from the solution near the electrode resulted in an unstable density gradient. The buoyancy-affected mass-transfer distribution was measured using a sectioned electrode. The mass-transfer distribution could also be evaluated directly from the patterns in the electrodeposit. Boeffard (1966) extended this work using the ferri-ferrocyanide redox couple to measure the mass-transfer limited current to a nickel cathode in various orientations. Ward and Le Blanc (1984) used the ferric/ferrous couple in chloride solution to effect a density gradient between two closely-spaced electrodes. They repeated the classic Bénard-Rayleigh stability experiment by imposing a current (flux) step and monitoring the potential. At very low current densities, the potential gives a direct measure of the ratio of concentrations of Fe $^{+3}$ to Fe $^{+2}$ at the electrodes, from which they could estimate the difference in solution density between the two electrodes. They found the critical Rayleigh number to be 1350 ± 300 . Dees and Tobias (1987) used the micro-mosaic electrode to study buoyancy-induced mass transfer at an upward-facing horizontal cathode. They observed both chaotic and regular fluctuations in the mass-transfer limited current to the electrode, sometimes occurring simultaneously on different

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parts of the electrode. They also demonstrated that, while the current to a single electrode element (of area 0.01 mm²) oscillated with a peak-to-peak amplitude as large as 83% of the average value, the current to the total electrode area (0.25 cm²) varied by only about 3%. Apparently, the current oscillations are averaged over a large area. McLarnon, Muller, and Tobias (1982) used electrochemical and optical techniques in the study of combined free and forced convection. They deposited copper from unsupported CuSO₄ and used interferometry to measure the resulting concentration profile.

The above investigators have demonstrated the usefulness of electrochemical techniques for inducing density-driven flows as well as for monitoring the resulting mass transfer. The major advantage of the electrochemical technique over the more-traditional thermal method of generating a density gradient is that, by controlling the surface condition electrically, a step change in surface concentration can be effected uniformly and rapidly. The mass-transfer rate to the surface is monitored as the resulting current. This electrochemical detection of the onset of convection by monitoring the Sherwood number is more precise than flow visualization techniques; the latter cannot discern the initial stages of convection.

An important aspect of this work is the application of the electrochemical technique to the study of a classic Bénard-Rayleigh stability problem in an experiment that allows spatial resolution of 100 μ m on the monitoring surface. This spatial resolution is achieved using a micro-mosaic electrode, which is designed to simulate a continuous surface. Fabricated on a 7.62-cm silicon wafer, it comprises a 10 x 10 array of 98- μ m square, electrically-isolated, platinum segments on 100- μ m centers. The problem we consider is the mass-transfer analog to the Bénard-

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Rayleigh problem of a fluid contained in a deep cell whose lower surface is heated impulsively to a constant temperature. A potential step is imposed, resulting in a limiting current for the reduction of an indicator ion; the concentration of this species instantaneously becomes zero at the electrode. As a consequence of the ionic species transport by diffusion and migration, the fluid density near the electrode surface is less than that of the fluid above. The problem is analyzed in terms of a Rayleigh number based on the penetration depth of the reactant ion concentration profile, and one based on the position and magnitude of the density maximum. We investigate the effects of the size and sensitivity of the sensing element on the critical Rayleigh number.

3. Stability of Impulsively-Heated Fluids

Two different approaches were followed in the early theoretical work on the stability of fluids with a time-dependent density profile (reviewed by Homsy (1973) and Jhaveri and Homsy (1982)). The first workers in this area (Lick, 1965; Currie, 1967) assumed that the disturbance grows much faster than the evolving diffusive profile, so that one can examine the marginal stability of the evolving base state at a given time. Their approach has been criticized in the literature as not valid; this "quasi-steady state" assumption is common in engineering practice, however, and can be used subject to scaling arguments which demonstrate its applicability. For the case of a sudden change in surface concentration (or temperature), the parameter that should be examined is the Schmidt (or Prandtl) number, the ratio of momentum diffusivity to mass (or thermal) diffusivity. One would not expect the

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quasi-steady state assumption to be valid for low values of the Schmidt number. In the case of a time-dependent surface condition, one would also not expect this type of analysis to be valid for high rates of surface heating. After extensive comparison of his own experimental data to the early theories, Davenport (1972) concluded that the problem with the quasi-steady state models is not with the quasi-steady state assumption itself, but that a destabilizing influence had been erroneously attributed to the bulk fluid. (For relatively deep pools, $\alpha t / h^2 < 0.1$, Currie's model predictions were a factor of 40 below Davenport's experimental results, even for high Prandtl number.)

The second early theoretical approach is that first used by Foster (1965a, 1968) and followed by several others (Elder (1968), Mahler *et al.* (1968), Mahler and Schechter (1970), and Gresho and Sani (1971)). In this approach the linear stability equations are integrated numerically and the growth rate of an initial velocity disturbance is followed in time. The onset time is determined as the time at which the magnitude of the disturbance has increased to a given multiple, or amplification, of the magnitude of the initial disturbance. The main objection to this approach is that the linearized equations may not be valid during the growth of the disturbance. In addition, the initial disturbance itself and the amplification factor at which one would presume that convection could be observed are somewhat arbitrary. Foster (1968) presented his results in terms of the times to achieve disturbance amplifications of 10 and 10⁸. Gresho and Sani (1971) used an amplification factor of 1000.

In a recent study, Jhaveri and Homsy (1980, 1982) report an elegant stability analysis of the problem which retains quadratic interactions and uses

thermodynamic fluctuations as the disturbances. Their stability analysis was conducted for a step change of temperature, and also for a linear change, at a free surface with a Prandtl number of 7. Their results are presented in terms of a timedependent, critical Rayleigh number Rat, which is the Rayleigh number based on total fluid depth multiplied by the dimensionless time; the total depth is removed from the problem with this scaling, and the Rayleigh number is based on a nominal penetration depth δ , where $\delta \equiv \sqrt{\alpha t}$. The time of onset of convection is defined as the time at which the thermal flux, or Nusselt number Nu, deviates from convection-free behavior by a given percentage. For a Prandtl number of 7, they found that the time-dependent Rayleigh number does not vary significantly if the Nusselt number deviation criterion is changed over a range of 1 to 10%. This result implies that the disturbance grows quickly relative to the evolution of the diffusive profile. Comparison of Jhaveri and Homsy's results at Pr = 7, for a step change at a free surface, to Foster's 1968 analysis shows that Jhaveri and Homsy's result of $Ra_t = 349$ (Nu variation of 5%) lies between Foster's limits of 61 (amplification = 10) and 630 (amplification $= 10^8$). (Jhaveri and Homsy's Rat corresponds to Foster's $t_c^{3/2}$.)

The early experimental investigations of this problem involved thermal studies (Spangenberg and Rowland (1961), Foster (1965b)), typically using evaporative cooling of water, for which the Prandtl number is approximately 7. In these experiments, neither surface temperature nor thermal flux is exactly constant; the surface temperature and evaporation rate are governed by the coupled mass and energy transfer at the surface. This type of experiment is also quite sensitive to trace impurities which affect the surface tension and hence the rigidity of the surface. How dramatic this effect can be for water was shown theoretically by Berg and Acrivos (1965), who found that trace contamination, as low as 1% of that required to form a close-packed monolayer, should stabilize a water layer up to a depth of 1 cm. The most important result from these early experiments with water is that, for a deep cell, $\delta/h < 0.3$, the critical time for onset of convection is independent of total fluid depth.

The absorption of an inert gas at a free surface overcomes some of the difficulties associated with evaporative cooling. Plevan and Quinn (1966), Blair and Quinn (1969), and Mahler and Schechter (1970) used this technique to investigate the onset of buoyancy-induced convection. In a gas absorption experiment, the surface boundary condition can be altered by changing the pressure of the absorbing gas above the liquid. The concentration of dissolved gas at the surface is directly proportional to the gas pressure; the constant of proportionality is the Henry's constant. A sudden change in surface concentration can be effected, and an analytic solution is obtained for the concentration profile. The density of the fluid is linearly dependent on the dissolved gas concentration over a wide range, so that the density profile can be derived as well. With this technique, the surface properties will be sensitive to the presence of trace impurities of surface-active agents in the fluid; the effect can be minimized (or maximized), however, through the choice of the gasliquid pairs.

Davenport and King (1974) conducted an extensive series of experiments with fluids covering a wide range of Prandtl numbers (0.7 to 8500). They contained the fluids between two plates and adjusted the heating rate to maintain either a constant lower plate temperature, or one which varied as a prescribed function of time. Results are presented in terms of the Rayleigh number based on the nominal penetration depth described above. They also used a Rayleigh number Ra_1 based on the equivalent linear-segment penetration depth originally proposed by Lick (1965):

$$l \equiv 2 \int_{0}^{\infty} \frac{(T - T^{\infty})}{(T^{0} - T^{\infty})} dy \quad , \tag{1}$$

which, for the case of constant surface temperature, is equal to $\frac{2}{\sqrt{\pi}}\sqrt{4\alpha t}$. When Davenport and King compared their results to Foster's model, they found that the apparent amplification factor at convection onset decreases as the Prandtl number increases. Their value of Ra₁ was independent of Prandtl number, and of total fluid depth, and was found to be approximately 1700, the critical Rayleigh number for the classic time-independent problem of a fluid contained between two rigid walls (Jeffreys, 1928).

The experimental procedure used in this study is closely related to the gas absorption experiments described above. In this study, an electrochemical technique is used to effect the change in surface concentration uniformly and rapidly. Our treatment of experimental results most closely parallels that of Davenport and King. We use a Rayleigh number based on penetration depth of the reacting species. The multi-component species problem that we encounter results in a density profile with a slight maximum so that we will also use a Rayleigh number based on the position and magnitude of the density maximum, as suggested by Bogar and Westwater (1967). The Schmidt number is high for the present case (~ 2300 , typical of aqueous solutions), so that the quasi-steady state analysis should be applicable.

4. Experimental

The micro-mosaic electrode used in this study has been described in the preceding chapter. In the experiments presented here, the cell holding the micro-mosaic is oriented horizontally with the electrode facing upward. The cell is shown in Figure 1. We impose a potential step to the potential region of limiting current for the reduction of Fe⁺³ to Fe⁺² from Fe₂(SO₄)₃ / H₂SO₄ solutions. Two different bulk solutions were used, 0.0484 M Fe₂(SO₄)₃ in 0.5 M H₂SO₄ (Solution 1) and 0.110 M Fe₂(SO₄)₃ in 1.0 M H₂SO₄ (Solution 2). The current responses of the electrode segments to the potential step are monitored and stored digitally.

Care was taken to ensure that the solution concentration was uniform and that the solution was quiescent prior to the start of an experiment. All cell parts were cleaned with distilled, deionized water and methanol. Reagent grade chemicals were used. Surface-tension driven flows were not a concern in our experiments, the electrode itself providing a rigid surface, so ultra-clean conditions were not a necessity. The cell temperature was monitored, but not controlled, in the experiments. Thermal effects due to heat generation are insignificant in our system. Even if all of the power dissipated in the system were released at the electrode surface, the density difference resulting from thermal effects would be less than 1% of that resulting from mass-transfer effects.

5. Analysis of the Base-State Profile

The description of a multi-component, electrochemical system is necessarily


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Figure 1. Electrochemical cell that holds the micro-mosaic electrode in horizontal orientation (From Dees, 1983).

more complex than that of a thermal system. This analysis is conducted to obtain an estimate for the surface concentration of each of the ions in solution. From the surface concentrations, we can calculate the solution density at the electrode surface. We also obtain the concentration and density profiles through the solution and the flux at the surface (current) as a function of time.

A potential step to the limiting-current regime involves a sudden change in electrode potential to a value at which the rate of reaction is limited only by the mass transfer of the reactant ion to the surface. This step in potential results in an instantaneous drop in the concentration of the reactant ion Fe⁺³ at the electrode. At the same time, the reaction product Fe⁺² starts to build up at the electrode. In the absence of convection, the region of depleted Fe⁺³ and enhanced Fe⁺² extends farther and farther into the solution with time, increasing the resistance for mass transport to the electrode surface. The concentrations of the major supportingelectrolyte species, H⁺ and SO $_4^{-2}$, are governed by diffusion and by migration in the electric field in such a way that solution electroneutrality is maintained.

The equation governing the one-dimensional mass transport of species i due to diffusion and migration is (Newman, 1973)

$$\frac{\partial c_i}{\partial t} = D_i \ \frac{\partial^2 c_i}{\partial y^2} + z_i \, u_i F \ \frac{\partial \left(c_i \ \frac{\partial \phi}{\partial y} \right)}{\partial y} \quad .$$
⁽²⁾

 u_i is the ionic mobility of species i and, for solutions dilute in species i, can be related to the diffusion coefficient by the Nernst-Einstein relation:

$$u_i = \frac{D_i}{RT} \quad . \tag{3}$$

The condition of electroneutrality is the other equation required to solve for the species concentrations and the potential, ϕ :

$$\sum_{i}^{4} z_i c_i = 0 \quad . \tag{4}$$

Initially, each species is at its bulk concentration,

$$c_i(0,y) = c_i^{\infty} \quad . \tag{5}$$

The boundary conditions at the electrode surface are

$$c_{Fe^{+8}}(t,0) \doteq 0 \tag{6}$$

and

$$D_{i}\left(\frac{\partial c_{i}}{\partial y} + \frac{z_{i}F}{RT}c_{i}\frac{\partial\phi}{\partial y}\right) = \frac{s_{i}}{s_{R}}D_{R}\left(\frac{\partial c_{R}}{\partial y} + \frac{z_{R}F}{RT}c_{R}\frac{\partial\phi}{\partial y}\right) \quad , \tag{7}$$

where R refers to the reactant species Fe⁺³, and s_i is the stoichiometric coefficient of species *i* when the electrode reaction is written as

$$\sum_{i} s_{i} M_{i} \rightarrow ne^{-} \qquad (8)$$

For a nonreacting species, s_i is zero. The electrode reaction in our case is

$$-\operatorname{Fe}^{+3} + \operatorname{Fe}^{+2} \to e^{-} \quad . \tag{9}$$

The net flux of each of the non-reacting ions, H ⁺ and SO $_{4}^{-2}$, is zero at the electrode surface. Far away from the electrode, the species concentrations are equal to their initial bulk values,

$$c_i(t,\infty) = c_i^{\infty} \quad . \tag{10}$$

For the H₂SO₄ concentration range of interest here (0.5 to 1.0 M) the dissociation of HSO₄⁻ is not complete. To account for the effect of bisulfate dissociation on solution density, the diffusion and migration equation (Eq. (2)) is written for the total hydrogen concentration $(c_{H^+} + c_{HSO_4})$ and for the total sulfate concentration $(c_{HSO_4} + c_{SO_4})$, following Hsueh and Newman (1971). This formulation of the conservation equations is valid provided the dissociation equilibrium reaction of HSO₄⁻ is fast. The boundary conditions of no net flux at the electrode (Eq. (7)) apply for the total hydrogen and total sulfate. Eq. (2) as written for Fe⁺³ and Fe⁺², with boundary conditions (6) and (7), and the electroneutrality equation apply as before. The additional equation required to solve for bisulfate concentration is the dissociation equilibrium,

$$\frac{c_{\rm H} + c_{\rm SO_4^{-2}}}{c_{\rm HSO_4^{-2}}} = K' \qquad (11)$$

The dependence of the thermodynamic dissociation constant K' on ionic strength, determined by Young *et al* (1959) from Raman spectra, is given by

$$K' = K \exp\left(\frac{5.29\sqrt{I_r}}{1 + 0.56\sqrt{I_r}}\right)$$
(12)

over a range of 0 to 3-M H₂SO₄, where $K = 1.04 \times 10^{-5} \text{ mol}/\text{cm}^3$ and the true ionic strength of the bulk solution I_r in mol/l is

$$I_r = 1/2 \sum_i 1000 c_i^{\infty} z_i^2 \quad . \tag{13}$$

The above set of equations describes the species transport in a quiescent solution. The equations may be transformed to ordinary differential equations using the similarity variable,

$$\eta \equiv \frac{y}{\sqrt{4D_R t}} \quad . \tag{14}$$

The transformed equations and boundary conditions are given in the Appendix. The set of transformed, coupled, ordinary differential equations was solved using the Galerkin finite-element method with linear basis functions and weighting functions.[†] The mesh was refined until the solution values remained unchanged to 5 significant figures. One thousand equally-spaced elements were used over a range of η from 0 to 4. Because the equations are nonlinear, a Newton-Raphson iterative technique was used. An IMSL Library subroutine (1982) was used to solve the linearized equations at each iteration. The solution was considered to be converged when the root mean square of the corrections to the previous iteration's values was less than 10^{-10} . The number of iterations required to achieve convergence depends on the initial guess, but usually no more than four were necessary, consuming 16 seconds of CPU time per iteration on a Vax 8600 computer.

The current is proportional to the derivative of the concentration of reactant ion at $\eta = 0$, which is a function of the diffusion coefficients and bulk. concentrations of all of the ions:

[†] A Fortran program that solves the same set of coupled equations using a finitedifference method is given in Newman (1973, pp. 423-24)

$$i = \frac{nFD_R}{s_R \sqrt{4D_R t}} \left(\frac{dc_R}{d \eta}\right)_{(\eta = 0)}$$
(15)

The solution to the above equations reduces to the Cottrell equation (Bard and Faulkner, 1980) for the current resulting from a potential step when the reactant is in an infinitely-supported solution. In such a case, transport of the reactant ion by migration is negligible, and $\left(\frac{dc_R}{d\eta}\right)_{(n=0)} = \frac{2c_R^{\infty}}{\sqrt{\pi}}$.

The reason for a density difference across the diffusion layer can best be seen by writing the electrode reaction as

$$\operatorname{Fe}_{2}(\operatorname{SO}_{4})_{3} + 2e^{-} \rightarrow 2\operatorname{FeSO}_{4} + \operatorname{SO}_{4}^{-2} \quad . \tag{16}$$

SO $_{4}^{-2}$ is transported away from the electrode and H ⁺ is transported to the electrode, maintaining electroneutrality. The net result is that the solution near the electrode is less dense than that in the bulk. The extent to which each of these two ions is accumulated or depleted at the electrode surface is a complex function of the diffusion coefficients and charges of *all* ionic species present in the electrolyte.

The density profile is obtained from the concentration profiles using

$$\rho = c_1 + \sum_i \alpha_i \ c_i \tag{17}$$

where α_i is the densification coefficient for species *i*. Since ionic species may occur only in the form of neutral pairs, the densification coefficient of any one of the ionic species may be set to zero without loss of generality. For convenience, SO $_4^{-2}$ is chosen because it is common to all of the neutral pairs; the densification effect of SO $_4^{-2}$ is then included with that of the associated cation. Since the major electrolyte species is H₂SO₄, the densification coefficients of H⁺ and HSO₄⁻ were obtained by a least-squares fit of H₂SO₄ solution density data (Weast, 1976) from 0.4 to 1.09 M. The densification coefficient for Fe⁺³ was estimated in two ways: (1) by least-squares fit of literature density information for pure Fe₂(SO₄)₃ solutions (Perry and Chilton, 1973), and (2) by fitting our own density measurements for the Fe₂(SO₄)₃/H₂SO₄ system. These two values differed by 4.2% An estimate for $\alpha_{\rm Fe^{+2}}$ was obtained using literature data (Perry and Chilton, 1973) for pure FeSO₄ solution densities.

The diffusion coefficients for H⁺, HSO $_{4}^{-}$ and SO $_{4}^{-2}$ were taken from literature data (Newman, 1973, p.230). The diffusion coefficient for Fe⁺³ was obtained from the initial part of the potential step experiment before convection onset (Eq. (10)). The product Fe⁺² diffusion coefficient was calculated from that of Fe⁺³ on the basis of published values (Dean, 1979) of the equivalent ionic conductances of the two ions.

6. Results and Discussion

Our main objective in solving the model presented in the previous section is to calculate the concentration profiles and density profile for the base state. Had we been depositing a metal from an unsupported electrolyte, rather than using a redox reaction, the equations would reduce to the thermal equations for which an analytic solution is available. The advantage of the redox system is that there are no surface-roughening effects, which commonly occur in metal deposition.

The concentration profile of the reactant ion is shown in Figure 2 for a

potential step using Solution 1. The equivalent, linear-segment penetration depth l_c was calculated from the mass-transfer analog to Eq. (1).

$$l_c \equiv 2 \int_0^\infty \frac{(c_R - c_R^\infty)}{(c_R^0 - c_R^\infty)} \, dy \quad .$$
 (18)

 l_c was found to correspond to a dimensionless distance η_c of 1.1492 for Solution 1 and 1.1498 for Solution 2. The density profile is calculated from the ion concentration profiles according to Eq. (17) and is shown in Figure 3 for Solution 1. There is a slight density maximum in the density profile (also noted by Selman and Newman, 1971), which occurs at η_m of 1.344 for Solution 1 and 1.340 for Solution 2. Surface and bulk concentrations and the parameters used in the model are given in Table 1.

An example of the current response of a single segment to a potential step to limiting current is given in Figure 4. The time to onset of convection is more clearly seen when the same data are plotted versus the inverse square root of time, as suggested by the similarity variable. This curve, shown in Figure 5, is typical of those obtained for most of the working segments. There are, however, some segments, each of which was adjacent to a non-working segment, for which the inverse-square-root-of-time plot exhibits significant curvature throughout the period before convection starts. Because of a non-functioning adjacent segment, the assumption of one-dimensional diffusion is invalid. An example is given in Figure 6. Although the onset of convection is still observable, these segments were not used in the determination of the critical Rayleigh number. Only those segments that showed no appreciable curvature and had straight-line correlation coefficients



Figure 2. Calculated concentration profile of reactant Fe $^{+3}$ following a potential step to limiting current. Dimensionless penetration length η_c is shown.



Figure 3. Calculated density profile following a potential step to limiting current for bulk Solution 1.

			Solution 1 Solution 2			
Species	$D_i \times 10^6$	α_i	$c_i^{\infty} \times 10^3$	$c_i^{0} \times 10^3$	$c_i^{\infty} \times 10^3$	$c_i^{0} \times 10^3$
	$\left(\frac{\mathrm{cm}^{2}}{\mathrm{sec}}\right)$	$\left(\frac{g}{\mathrm{mol}}\right)$	$\left(\frac{\mathrm{mol}}{\mathrm{cm}^{3}}\right)$	$\left(\frac{\mathrm{mol}}{\mathrm{cm}^{3}}\right)$	$\left(\frac{\mathrm{mol}}{\mathrm{cm}^{3}}\right)$	$\left(\frac{\mathrm{mol}}{\mathrm{cm}^{3}}\right)$
H +	93.12	16.99	0.63385	0.67393	1.30743	1.39528
HSO 🚽	13.3	56.12	0.36615	0.35552	0.69257	0.67224
SO_4^{-2}	10.65	0.0	0.27920	0.25496	0.63743	0.57977
Fe +2	5.135	141.65	0.0	0.09576	0.0	0.21825
Fe +3	4.351	160.34	0.0969	0.0	0.220	0.0
n an		$\rho^{\infty} = 1.0465$		$\rho^{\infty} = 1.0960$		
		$\rho^0 = 1.0446$		$\rho^0 = 1.0920$		
		$\rho^m = 1.0468$		$\rho^m = 1.0966$		

Table 1. Model Input Parameters and Surface Concentrations



Figure 4. Current response of a single segment following a potential step to limiting current.



Figure 5. Current response from Figure 4 plotted versus the inverse square root of time. The first (right) marker shows the last point used for calculating the diffusion coefficient. The second marker (left) shows the point of 5% deviation from linearity.



Figure 6. Current response of a single segment following a potential step to limiting current, showing curvature due to an adjacent non-working segment.

greater than 0.999 were used. Typically data from 50 to 60 segments were deemed acceptable.

The diffusion coefficient of Fe⁺³ was calculated from data obtained from each of 55 segments for an experiment using Solution 1. The average value is 4.335 $\times 10^{-6}$ cm²/sec, with a standard deviation of 0.32×10^{-6} cm²/sec. The total current response for all 55 segments from the same experiment is plotted versus time in Figure 7, and versus the inverse square root of time in Figure 8. The diffusion coefficient for Fe⁺³ from Figure 8 is 4.351×10^{-6} cm²/sec. The correlation coefficient for straight-line behavior up to the first marker is greater than 0.9999.

The critical Rayleigh number based on the concentration profile is

$$Ra_{l} \equiv \frac{\Delta \rho \ gl_{c}^{3}}{\rho^{\infty} \nu D_{R}} \quad , \tag{19}$$

where l_c , calculated from the model results (Eq. (18)), is

$$l_c = \eta_c \sqrt{4D_R t_c} \quad . \tag{20}$$

 $\Delta \rho$ is calculated from

$$\Delta \rho = \sum_{i} \alpha_{i} \left(c_{i}^{\infty} - c_{i}^{0} \right) \quad .$$
⁽²¹⁾

 t_c was identified as the time when a deviation greater than 5% occurred in the current (Sherwood number) versus inverse-square-root-of-time plot. The choice of a 5% deviation criterion is somewhat arbitrary; however, Jhaveri and Homsy (1982) predicted that the critical Rayleigh number should be fairly insensitive to this



Figure 7. Total of the current responses obtained from all 55 segments following a potential step to limiting current.



Figure 8. Inverse-square-root-of-time plot of the total current response obtained from all 55 segments following a potential step to limiting current.

The critical time for onset of convection was determined for each of the acceptable segments. The average value for Solution 1 is 30.8 seconds, with a standard deviation of 6.6 seconds. The corresponding Rayleigh number is 766, and l_c is 266 μ m. The critical time determined from the curve of the sum of all of the segments (Figures 7.8) is 33.3 seconds, which gives a Ra_l of 861 and l_c of 277 μ m.

Upon repeating the experiments using different electrodes, the measured onset times were 32.5, 32.9, and 34.1 seconds; the average value for the four runs is thus 33.2 seconds with a maximum deviation of 1.9 seconds. Blair and Quinn (1969) obtained an average onset time of 27 seconds with a range of 24 to 30 seconds in a typical set of gas-absorption experiments. The good reproducibility we observe is an indication of the precision of the electrochemical technique.

Three experiments were carried out using the more dense Solution 2. The average of the individual segments in one experiment was 20.5 with a standard deviation of 2.9 seconds. The onset time measured with the entire electrode was 21.9 in the same experiment. In repeated experiments, onset times for the entire electrode of 22.7, and 21.8 were measured. The average value, 22.1 seconds, corresponds to a penetration length l_c of 225 μ m and Ra₁ of 945.

The appropriate comparison of our data to theory would involve consideration of the model of Jhaveri and Homsy (1982); however, they did not analyze the problem with a rigid surface or for Prandtl number other than 7. The most direct comparison to theory that we can attempt is to consider Foster's (1968) limiting values obtained using amplification theory. Our Ra₁ values are very near those of Foster for $\Pr \rightarrow \infty$. He reports Ra₁ of approximately 900 for an amplification factor of 10 and approximately 5000 for an amplification factor of 10^8 . Davenport and King (1974) found that, with increasing Pr, their experimentallydetermined values of Ra₁ decreased to an amplification factor of 10 according to Foster's theory.

6.1. The Effect of a Density Maximum

The effect of a density maximum, which occurs in the multi-component diffusion problem encountered here, was first treated by Veronis (1963) in connection with the problem of thermal gradients in water near 3.98 °C confined between two boundaries. The topic remains a subject of current investigation (see Blake *et al.*, 1984, and references therein). The problem of determining the relevant length for such a system has not been resolved (see, for example, Merker *et al.*, 1979), and is even more complex for the semi-infinite system which we encounter. The linear-segment penetration depth was originally proposed (Lick, 1965) to represent an equivalent integrated buoyant force.

$$l \equiv 2 \int_{0}^{\infty} \frac{(\rho - \rho^{\infty})}{(\rho^{0} - \rho^{\infty})} dy \quad , \qquad (22)$$

and reduces to Eq. (1) when density can be treated as a linear function of temperature. Similarly, it would reduce to Eq. (18) if density were a linear function of c_R . The use of Eq. (22) when there is a density maximum results in the maximum contributing an artificial stabilization by *decreasing l*. Bogar and Westwater (1967) studied experimentally the conditions for convection onset in the melting of ice and found that the significant length for their analog to the problem

we encounter is the position of the density maximum. They also concluded that the correct density difference is the maximum density less the density at the lower boundary. The Rayleigh number defined in this way is

$$Ra_m \equiv \frac{\left(\rho^m - \rho^0\right) gl_m^3}{\rho^{avg} \nu D_R} \quad , \tag{23}$$

where $l_m \equiv \eta_m \sqrt{4D_R t_c}$ is the calculated position of the density maximum. There is no a priori way to relate the two lengths l_c and l_m ; l_c is a function of the diffusion coefficients, charges, and bulk concentrations of all of the species, while l_m is a function of all of the above and the densification coefficients. The critical Rayleigh number Ra_m according to Eq. (23) is 1829 for the Solution 1 experiments and 1718 Solution 2 experiments. Bogar and Westwater found that Ra_m for the analogous situation of melting ice was about 1700.

There has long been some uncertainty regarding the effect of the sensitivity of the monitoring technique on the critical Rayleigh number determined. With the micro-mosaic electrode we can conveniently investigate two effects: (1) the size of the sensing element relative to the that of the convective disturbance and (2) the effect of the chosen deviation criterion.

6.2. The Effect of the Size of the Sensing Element

Single electrode segments are 100 μ m square. According to traditional stability theory, the wavelength of the disturbance is of the order of twice the characteristic length, which for our case is l_c . Thus our sensing elements are significantly smaller than the wavelength of the disturbance. Together they form a

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cluster (1 mm square) of the same order as the disturbance, which is in turn surrounded by a larger "buffer" section. The effects of averaging on a large scale can be seen by simply comparing the time of the onset of convection for the individual segments to that for the larger cluster of segments, 30.8 versus 33.3 seconds. The longer time required until the onset of convection can be discernible for the larger cluster is the result of mass-transfer fluctuations being averaged on the larger scale.

Close inspection of Figure 4, the response of a single segment, and Figure 7, the response of the entire electrode, reveals another interesting point in regard to the effect of the size of the sensing element. Let us for the moment relax the 5%deviation criterion and consider instead the time until a major enhancement of the mass-transfer rate due to convection is established. This significant enhancement is the onset criterion one would probably detect in gas absorption experiments at a free surface without a very sensitive monitoring instrument. That the deviation from base-state behavior, according to our 5% criterion, significantly precedes any major enhancement in the current for the entire electrode can be seen in Figure 7. By contrast, the response for a single electrode element, shown in Figure 4, exhibits a significant increase in current immediately following the first deviation and much sooner than the entire electrode. If the Rayleigh number were based on the beginning of the sharp increase in current to the entire electrode (\sim 50 seconds), it would be a factor of approximately 1.9 higher than the one determined from the 5%criterion we used. For the single-electrode data, the Rayleigh number would increase considerably less, by a factor of 1.3.

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6.3. The Effect of the Chosen Deviation Criterion -

The effect of varying the Sherwood number deviation criterion from 5 to 10% was investigated using the total current for all of the segments, shown in Figure 8. Over this range of onset criteria, the critical time varied from 33.3 seconds (at 5%) to 37.6 seconds (at 10%), an increase of 13%. The consequent increase in the calculated Ra₁ is 20%. Jhaveri and Homsy (1982) predict that for Pr = 7 at a free surface, the measured Ra₁ would increase by only 4% if the flux criterion is changed from 5 to 10%. Since we have a very high Schmidt number (2300), we might expect less of an effect of the onset criterion than predicted by Jhaveri and Homsy. Inspection of Figure 7 shows a definite departure from the base-state behavior at the marker for 5% deviation; however, the current response is still somewhat flat before the convection dominates and a very strong increase is seen. If we consider the current response of a single segment, we might see a sharper increase (or decrease) at convection onset than in the case of the sum of all the segments, where some averaging will undoubtedly take place. Figure 9 illustrates the current response for a segment showing a sharp negative deviation from the base-state behavior. The first marker (to the right in the figure) shows the last point for the calculation of the slope and correlation coefficient. The second marker (to the left) shows the point of 5% deviation. The time of convection onset for this curve is 39.8 seconds for a 5% deviation and 43.1 seconds for a 10% deviation, an 8.3% increase. The corresponding effect on the Rayleigh number is an increase of 12.7%, closer to the predicted value, but still significantly higher. One reason why we might not expect a close comparison between our result and Jhaveri and Homsy's model is that the model was established for a free surface condition, which means that there is no



Figure 9. Current response of a single segment following a potential step to limiting current, showing a sharp decrease in Sh at the time of onset of convection.

shear stress at that surface to retard flow development.

It is of particular interest to consider the temporal and spatial variation of the direction of the change in mass transfer at the onset of convection. In the development of a cellular motion, we might expect to see areas where the initial deviation from the base-state current-time behavior is an enhanced transport rate and others where the rate is lowered. Indeed this was the case. In nearly every experiment, about two-thirds of the electrode surface showed a positive deviation, while a negative deviation occurred on the rest. The current to a segment showing a positive deviation is given in Figure 10, and that for a segment 100 microns away showing a negative deviation is given in Figure 11. The segment between these two, shown in Figure 12, underwent two slight negative deviations followed finally by a large increase in the current. The segmented area of the micro-mosaic electrode is too small to completely surround the entire area of segments showing the same type deviation. This distribution of deviations was not investigated in repeated experiments; however, all runs showed an overall *increase* in mass-transfer rate at the time of convection onset.

7. Conclusions

The use of a micro-mosaic electrode with an electrochemical redox system has been demonstrated in a study of the Benard-Rayleigh problem of onset of convection in a fluid with a time-dependent density profile contained in a deep cell. The electrochemical technique offers several advantages over thermal techniques, the most important one being the precise control of the surface condition. The well-



Figure 10. Current response of a segment following a potential step to limiting current, showing an *increase* in Sh at the time of onset of convection.



Figure 11. Current response of a segment that is 200 μ m from that shown in Figure 10, exhibiting a *decrease* in Sh at the time of onset of convection.



Figure 12. Current response of the segment between the two shown in Figures 10 and 11, showing two slight decreases, followed by a large increase in Sh at the time of convection onset.

controlled experiment lends itself to a thorough analysis of the time-dependent base state, the case of diffusion and migration into a semi-infinite column of electrolyte. In addition, the electrode serves as the monitoring device, allowing a precise detection of the onset of convection, the criterion for which is a percentage deviation of the Sherwood number (current) from base-state behavior.

The critical Rayleigh number Ra₁ for the problem of onset of convection at a rigid, conducting boundary, due to a step change in the surface condition, was found to be approximately 900, based on the equivalent, linear-segment concentration profile and using a deviation criterion of 5% in the Sherwood number. For the redox system employed here, we calculate a maximum in the density profile. The critical Rayleigh number Ra_m based on the position and magnitude of the density maximum is approximately 1750.

At sensing elements much smaller than the wavelength of the disturbance, a sharp increase (or decrease) in mass-transfer rate occurs immediately after the first deviation from convection-free behavior. Over a larger area, some averaging takes place and a significant enhancement of the mass-transfer rate does not occur until tens of seconds after the first deviation in the mass-transfer rate is detected. For these reasons the single-segment data are less sensitive to the choice of the criterion that defines the time of deviation from convection-free behavior than are the data obtained from the entire electrode. Ra₁ for single segments increased approximately 13% when the onset criterion was raised from a 5 to 10% deviation, while Ra₁ derived from the entire electrode increased by 20%.

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8. Chapter 4 Nomenclature

c _i	concentration of species i, mol $/\text{cm}^3$
c 1	constant in density equation, 0.9996457 g /cm 3
D _i	diffusivity of species i, cm 2 /sec
F	Faraday constant, 96,487 C/eq
h	total liquid depth, cm
i	current density, A/cm^2
I _r	true ionic strength of bulk solution, mol/l
K	dissociation constant at infinite dilution, mol /cm 3
K'	thermodynamic dissociation constant, mol /cm 3
l	linear-segment penetration depth, defined in Eq. (1), cm
l _c	linear-segment penetration depth, based on concentration, cm
l_m	linear-segment penetration depth, based on density profile, cm
n	number of electrons transferred in the electrode reaction
Nu	Nusselt number, dimensionless thermal energy flux
Pr	Prandtl number, $\nu/lpha$
R	universal gas constant, 8.3144 J/mol-K
Ra	Rayleigh number
s_i	stoichiometric coefficient of species i in the electrode reaction
Sc	Schmidt number, ν/D_R
Sh	Sherwood number, dimensionless mass flux
t	time, sec
T	temperature, K
u _i	mobility of species i, cm ² -mol/J-sec
y	vertical distance from electrode surface, cm
z _i	charge number of species i
α	thermal diffusivity, cm 2 /sec
α_i	densification coefficient of species i, g/mol

η similarity variable for semi-infinite diffusion
ϕ potential, volt
ν kinematic viscosity, cm ² /sec
ho density, g/cm ³

Subscripts and superscripts

Ra based on linear-segment penetration de	
	pth
m l, η, ρ at the density maximum Ra based on density maximum	
R limiting reactant	
t Ra based on nominal penetration depth δ	
0 at the electrode surface	
∞ in the bulk solution	

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10. Chapter 4 Appendix

The dependent variables in the equation for mass transport by diffusion and migration in a semi-infinite column of electrolyte (Eq. (2)) are made dimensionless as

$$\theta_i \equiv \frac{c_i}{c_R^{\infty}}$$

- (A-1)

$$\Phi \equiv \frac{\phi F}{RT} \quad . \tag{A-2}$$

Substituting these into Eq. (2) gives

$$\frac{\partial \theta_i}{\partial t} = D_i \ \frac{\partial^2 \theta_i}{\partial y^2} + z_i D_i \left(\frac{\partial \theta_i}{\partial y} \ \frac{\partial \Phi}{\partial y} + \theta_i \ \frac{\partial^2 \Phi}{\partial y^2} \right) . \tag{A-3}$$

Eq (A-3) is transformed to an ordinary differential equation using the similarity variable

$$\eta \equiv \frac{y}{\sqrt{4D_R t}} \quad , \tag{A-4}$$

and becomes

$$2\eta \frac{d\theta_i}{d\eta} + \frac{D_i}{D_R} \frac{d^2\theta_i}{d\eta^2} + \frac{D_i}{D_R} z_i \left(\frac{d\theta_i}{d\eta} \frac{d\Phi}{d\eta} + \theta_i \frac{d^2\Phi}{d\eta^2} \right) = 0$$
 (A-5)

The boundary conditions at $y = \infty$ and the initial conditions combine to give

$$\theta_i = \frac{c_i^{\infty}}{c_R^{\infty}} \tag{A-6}$$

$$\Phi = 0 \tag{A-7}$$

at $\eta = \infty$. The surface boundary conditions at $\eta = 0$ become

$$\theta_R = 0 \tag{A-8}$$

$$D_{i}\left(\frac{d\,\theta_{i}}{d\,\eta} + z_{i}\,\theta_{i}\,\frac{d\,\Phi}{d\,\eta}\right) = \frac{s_{i}}{s_{R}}D_{R}\left(\frac{d\,\theta_{R}}{d\,\eta} + z_{R}\,\theta_{R}\,\frac{d\,\Phi}{d\,\eta}\right) \tag{A-9}$$

The equation of electroneutrality (Eq. (4)) becomes

$$\sum_{i}^{4} z_i \theta_i = 0 \quad . \tag{A-10}$$

The equation for the dissociation of bisulfate is

$$\frac{\theta_{\rm H} + \theta_{\rm SO}}{\theta_{\rm HSO}} = \frac{K'}{c_R^{\infty}} \quad . \tag{A-11}$$

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Chapter 5. Observations of Bubble Growth and Disengagement

1. Abstract

Observations of galvanostatic growth and disengagement of hydrogen bubbles at a 127- μ m-diameter micro-electrode embedded in a large, coplanar, horizontal electrode in 1.0-M H₂SO₄ are reported. Time scales for the collapse of the contact area, bubble disengagement and rise are obtained using high-speed cinematography. The collapse of the contact area takes place in less than two miliseconds and precedes the actual disengagement by up to 180 miliseconds. Observations of hydrogen evolution in free convection along vertical platinum electrodes in 0.5-M H₂SO₄ are also reported. The average diameter and position relative to the electrode surface of rising bubbles both increase with current density.

2. Introduction

An understanding of the mechanism by which electrolytically evolved gas bubbles influence mass transfer to and from the electrode surface requires intimate familiarity with the dynamics of bubble nucleation, growth, coalescence, and detachment. Optical observations are not easy to make because electrolytically evolved bubbles are small (at most a few hundred microns following detachment), and the events of coalescence and separation from the surface are completed within 10^{-4} and 10^{-3} seconds. Further, the movements of swarms of bubbles surrounding a given bubble render any precise observation of a single bubble difficult. It should not therefore be surprising that there is a paucity of information in the literature regarding the dynamics of bubble phenomena.

Coehn and Neumann (1923) and Kabanow and Frumkin (1933) grew bubbles at very low rates and obtained bubble diameters at breakoff. They were concerned with the forces that determine the size of the largest bubble that can adhere to a solid support, and not with bubble growth rates or dynamics.

The first report of electrolytic bubble growth was that of Westerheide and Westwater (1961), who photographed hydrogen bubbles growing in sulfuric acid at a 127- μ m-diameter platinum micro-electrode encased in glass, using high-speed motion pictures. They found that the bubble diameter increased with the square root of time, indicating a mechanism of growth by diffusion from a supersaturated solution, according to the model of Scriven (1959). They also found that when two bubbles coalesced, the new bubble would sometimes jump off the electrode surface and return to it. They also recorded slip of bubbles along the electrode.
Observations of Bubble Growth

Glas and Westwater (1964) recorded the electrolytic growth of H₂, O₂, Cl₂ and CO₂ on platinum, nickel, copper, and iron electrodes with diameters from 127 to 508 μ m. Bubble diameters were found to increase with the square root of time, following Scriven's model. The largest diameters recorded were approximately 160 μ m. Bubble heights during growth were also measured, and contact angles were computed from the measured heights and maximum diameters, assuming the bubbles to be spherical segments. On this basis, it was concluded that the contact angle decreases with increasing bubble diameter. However, even for small, nearly spherical bubbles, a spherical segment is not a good approximation to its shape *if* one is trying to determine the contact angle. Any deviation from sphericity will be manifest in the shape of the bubble interface near the base (See Figure 2, Chapter 2).

Putt (1975) tried a different approach to observing bubble growth at vertical electrodes. He photographed H₂ and O₂ bubbles in 5-M KOH and 5-M H₂SO₄, at very short times (13-300 msec) after the start of electrolysis, through a glass window in the center of an opposing counter electrode. He also measured the sizes of free stream bubbles rising above the active electrode. Strong evidence has been presented by Putt showing the dense nucleation of bubbles following imposition of the current, subsequent rapid coalescence while still attached to the electrode surface, and eventual detachment of bubbles of uniform size. Hydrogen bubbles in H₂SO₄ also grew by sliding along the electrode surface, scavenging smaller bubbles in their paths. Steady-state flow of bubbles along the electrode was typically established within one second of the start of electrolysis. Putt concluded that the size of detaching bubbles at practical rates of gas evolution is governed by the dynamics of

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bubble interactions.

Cettou and Tobias (1981) combined Putt's technique with high-speed motion pictures and extended the range of electrode materials to include nickel 200, stainless steel 304, and electrodeposited gold. They used sulfuric acid, sodium sulfate and sodium hydroxide electrolytes. The density of bubbles nucleated per electrode area was found to vary with electrode material, electrolyte, and the gas evolved, being much higher, for example, with H₂ on nickel or stainless steel in H $_2$ SO $_4$ (1000/mm²) than in NaOH (150/mm²), and intermediate (600/mm²) for H $_2$ on gold in both electrolytes. Comparisons of bubble sizes at detachment to bubble sizes in the bulk at steady state, show that coalescence is the most important mode of bubble growth in H $_2$ SO $_4$ for both H $_2$ and O $_2$ on all electrode materials studied.

The other approach to viewing gas evolution has been to take photographs though the back side of a transparent metal or conductive metal-oxide electrode. Venczel (1970) vapor-deposited thin layers of platinum, chromium, nickel and gold on glass plates and observed H₂ bubbles in H₂SO 4. He found that bubble size is dependent on electrode material used: the coalescence of uniformly-sized bubbles on platinum and graphite electrodes forms large bubbles, and uneven growth on iron and copper (solid) electrodes results in bubbles separating before coalescence. Janssen and van Stralen (1981) evolved O₂ from KOH on transparent nickel electrodes and noted the important role of bubble coalescence in this system. Bubbles often slip across the electrode and coalesce into a larger bubble. Sides and Tobias (1985) observed this phenomenon during O₂ evolution in NaOH through transparent SnO₂ electrodes, and also noted the scavenging effect of large bubbles sliding along the electrode and coalescing with smaller bubbles in their paths, reported earlier by Putt (1975).

The objective of the present investigation is to characterize H₂ evolution in H_2SO_4 by obtaining a *profile* view of bubble formation on flat electrodes. We are interested in the shape and size of individual bubbles during growth and detachment, and the movements of bubbles following coalescence. We hope to learn whether scavenging bubbles that slide along the electrode and coalesce with smaller bubbles are actually attached to the surface. We are also interested in the distances from the electrode at which free stream bubbles rise, and the dependence of the size of such bubbles on current density.

The method used in the present study to observe individual bubble growth and detachment is to grow bubbles at constant current at an electrically-isolated micro-electrode embedded in a relatively large planar electrode. The recording of bubble growth and coalescence at vertical electrodes is accomplished using narrow platinum strip electrodes. By restricting the electrode dimension in the horizontal direction to a few milimeters, only a few columns of bubbles are able to form, allowing an unobstructed view of multiple-bubble phenomena to be recorded.

3. Disengagement and Growth of Single Bubbles Formed at Micro-Electrodes

3.1. Experimental

Hydrogen bubbles were produced at constant current at a horizontal, platinum, two-section electrode. The electrode was constructed by inserting a 127- μ m-diameter platinum wire through a hole drilled in the center of a 1 x 1 cm platinum sheet, filling the gap with epoxy, and facing the top surface. The epoxy ring separating the two electrodes is 50 to 75 μ m in width. The surrounding platinum electrode can be used as a second working electrode or as a reference electrode. The sectioned electrode fits into a plexiglass cell that has a platinum counter electrode, and a reference-electrode capillary built into the wall at the edge of the second working electrode. A schematic of the cell is shown in Figure 1.

The electrode was polished to 1 μ m with diamond paste, and rinsed with cyclohexane, methanol, de-ionized distilled water and the electrolyte, before being inserted in the cell. The central platinum electrode was polarized cathodically to generate hydrogen bubbles from 1-M H₂SO₄. Experiments were conducted in galvanostatic mode, using an EG&G PAR 173/176 potentiostat/galvanostat, and the potential waveforms were stored on a Nicolet 4094 digital oscilloscope. The data were transferred to an Hewlett-Packard HP9825T desktop computer, stored on floppy disk, and later transferred to a mainframe. A Redlake Hycam camera, capable of filming at rates up to 11,000 full frames per second, was used to record visual observations. Primary lighting was supplied by an optical fiber aimed directly into the microscope from behind the growing bubble; a second optical fiber lit the bubble from in front and above.



Figure 1. Electrochemical cell and equipment for observations of bubble growth at micro-electrodes.

3.2. Overpotential Measurements

The total potential, measured with respect to a mercury/mercurous sulfate reference, is shown in Figure 2 for bubble evolution rates of 100, 200, 500, and 1000 μ A. The corresponding current densities are quite high (0.79, 1.58, 3.95, and 7.89 A/cm²), owing to the small area of the active electrode. The thermodynamic component of the total potential is 0.64 V. Two features are readily apparent from the overpotential curves. First, there is a sharp increase in the overpotential just before bubble disengagement, which may be attributed to the bubble base, having grown to the electrode edge, obstructing the flow of current. This is supported by the increasing magnitude of the potential jump with current. Second, the frequency of bubble evolution is roughly proportional to the current, from which it can be inferred that the bubbles are nearly the same size at detachment.

3.3. Time Scale of Bubble Disengagement

The time scale of the events preceding the actual tearing loose of the bubble from its base was determined using high-speed cinematography. A series of frames from a 1500 frame-per-second movie of a hydrogen bubble growing at 200 μ A is shown in Figure 3. Times shown are relative to the first frame in the series; the bubble had been growing for approximately 25 seconds before this frame. The collapse of the contact area occurs in less than two miliseconds (frames 1-3). In the next 15 miliseconds (frames 4,5) the bubble rises slightly from its base and shifts horizontally. For a period of about 160 miliseconds, there is little bubble movement. It grows by coalescence with a series of small bubbles nucleated at its



Figure 2. Micro-electrode potential with respect to a mercury/mercurous reference electrode for currents of 100, 200, 500, and 1000 μ A.



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Figure 3. Bubble detachment from platinum micro-electrode in 1-M H $_2$ SO $_4$. Bubble had been growing at 200 μ A for 25 seconds before first frame shown here.

Observations of Bubble Growth

base. The tearing loose of the bubble from its base takes place between the sixth and seventh frames, almost 180 miliseconds after the collapse of the contact area. In another 8 miliseconds, the bubble has risen out of the frame (1mm height) and a new bubble is growing. The series of events is presented in a set of sketches, traced from the same film, in Figure 4. The asymmetric collapse of the contact area and subsequent horizontal movement can be more clearly seen in this presentation.

Tracings from movies of bubbles generated at 500 μ A are similar to those for 200 μ A; the time intervals, however, are considerably shorter. Figure 5 shows the disengagement of a hydrogen bubble grown at 500 μ A for roughly 11 seconds prior to the first contour. The time from the beginning of the decrease of the contact area to the detachment of the bubble is 15 miliseconds at this current density.

3.4. Rate of Bubble Growth

The radius of a bubble growing by diffusion in a uniformly supersaturated solution will increase with the square root of time, as shown by Scriven (1959). Bubble growth at micro-electrodes is different from that at macro-electrodes in that the only source of hydrogen is directly at the base of the bubble. It is possible for the bubble to capture all or most of the dissolved gas directly from the area at its base, rather than from the bulk liquid. If this is the case, the bubble radius should increase with the cube root of time. Figure 6 is a plot of the radius of a bubble grown at 500 μ A versus the cube root of time. The curve for 100% capture of dissolved hydrogen is also shown; it appears that the capture efficiency is almost 100%.



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Figure 4. Change in shape of bubble at time of detachment from platinum microelectrode in 1-M H $_2$ SO $_4$. Bubble had been growing at 200 μ A for 25 sec before first sketch. Times in miliseconds relative to curve 1: (2) 0.7, (3) 1.3, (4) 5.3, (5) 11, (6) 159, (7) 175, (8) 176, (9) 179, (10) 182, (11) 184.



XBL 876-10200



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Figure 6. Bubble radius plotted against the cube root of time. The dashed line is the calculated bubble radius assuming a spherical bubble and 100% hydrogen capture efficiency.

4. Hydrogen Evolution at Vertical Platinum Electrodes

4.1. Experimental

Hydrogen was evolved from 0.5-M H $_2$ SO $_4$ at vertical platinum strip electrodes 75 mm high and 1.3 mm wide. This electrode width proved small enough to allow an unobstructed side view of bubbles to be obtained. The platinum strips were encased in Plexiglas with epoxy. The entire piece fits into a small Plexiglas cell of dimensions 75 x 70 x 12 mm, shown in Figure 7. The electrodes were polished, and rinsed with methanol, de-ionized distilled water, and the electrolyte, prior to immersion in the cell.

4.2. Results

Three frames taken from a movie of hydrogen evolved at a rate of 14 mA /cm² at a vertical platinum electrode are shown in Figure 8. The scale of the frame is 1.1 x 1.4 mm. Coverage of the electrode area by attached bubbles is not high, and, periodically, a large bubble would slide along the electrode, coalescing with or causing the detachment of smaller bubbles. Bubbles on the surface are typically about 100 μ m in diameter; the largest bubbles observed at this current density were about 250 μ m in diameter. Bubbles rise at distances up to 600 μ m from the electrode.

Figure 9 includes three frames from a film of hydrogen evolution at vertical platinum electrodes at a current density of 28 mA /cm². The bubbles on the surface are somewhat larger than those at 14 mA /cm²; a typical diameter is 140



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Figure 7. Electrochemical cell and platinum electrodes for observing gas evolution at vertical macro-electrodes.

Observations of Bubble Growth



1.0 sec



1.5 sec



2.0 sec

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Figure 8. Three frames, 0.5 seconds apart, from a movie of hydrogen evolution at a vertical platinum electrode at a current density of 14 mA /cm². Each frame is 1.1 x 1.4 mm.

Chapter 5

0.5 sec



0.7 sec



0.9 sec

XBB 860-8670A

Figure 9. Three frames, 0.2 seconds apart, from a movie of hydrogen evolution at a vertical platinum electrode at a current density of $28 \text{ mA}/\text{cm}^2$. Each frame is 1.1 x 1.4 mm.

 μ m. A higher fraction of bubbles rise unattached and at greater distances from the electrode then at the lower current density. The largest bubble in this set of photographs is about 350 μ m in diameter.

5. Other Observations

The following qualitative observations of hydrogen evolution in sulfuric acid were also made:

1. Bubble size at detachment from a micro-electrode is independent of current density, and is larger than on a continuous electrode. This is presumably a result of the lack of convection or other disturbances that would be present were other bubbles growing or detaching nearby. The eventual bubble detachment is typically caused by a small secondary bubble coalescing into the base of the primary bubble.

2. The size of bubbles adhering to vertical electrodes increases with current density, while the number density of attached bubbles remains constant. The size of free stream bubbles generally increases with current density.

3. Periodically, in gas evolution along vertical electrodes, large bubbles (whose size appears to increase with current density) slide along the electrode, coalescing with adhering bubbles and exposing fresh electrode area. New bubbles are nucleated at previously occupied sites.

4. Coalescence in the free stream is very rare. A large bubble overtaking a smaller one usually slips around it. Only if the two bubbles' axes of motion are colinear, do two bubbles coalesce without being attached to the electrode.

6. Conclusions

Observations of galvanostatic growth and disengagement of hydrogen bubbles have been recorded using high-speed cinematography with a 127- μ m-diameter horizontal micro-electrode embedded in a large, coplanar electrode. In 1.0-M H ₂SO ₄ the collapse of the contact area takes place in less than two miliseconds and precedes the actual disengagement by up to 180 miliseconds. The total time for contact area collapse, bubble disengagement, and bubble rise to one diameter above the electrode decreases with increasing current density. Because of the bubble shielding the electrode area, a sharp increase in overpotential occurs just before the actual disengagement, at which time the overpotential drops. Hydrogen evolution has also been observed by high-speed cinematography in free convection along vertical platinum electrodes, 7.5 cm in height. At moderate current densities (15-30 mA /cm²) in 0.5-M H ₂SO ₄, bubble sizes after separation are in the range of 50 to 400 μ m in diameter, and, as they rise, they drift to distances up to 800 μ m away from the electrode surface. The average diameter and the path of rising bubbles both increase with current density.

7. Chapter 5 References

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Appendix A. Electrode Fabrication

Fifteen electrodes were received from Hewlett-Packard Laboratories in July, 1984. These electrodes were labeled HP-01 and numbered one through fifteen. In August of 1984, twenty electrodes were received from AT&T Bell Laboratories, labeled BL-01. Later in 1984, two more electrodes of the same materials and eleven electrodes of different materials, batch BL-02, were received. The following table shows the materials of construction of the three sets of electrodes. Appendix E shows the electrodes used in experiments and the operability before and after use.

	HP-01	BL-01	BL-02
base	(100)-Si	(100)-Si	(100)-Si
isolation	$1.5 \mu m \text{ SiO }_2/1500 \text{\AA Si }_3 \text{N}_4$	SiO ₂	SiO ₂
conductors	. 1200Å Al	5000Å TaSi _x	1µm Al
insulator	4500Å SiO 2	1250Å SiN:H	polyimide
electrode	300/600Å Cr/Pt	500/5000/500Å Ti/Pd/Au	500/5000/500Å Ti/Pd/Au
number	15	22	11
line widths	4-5.5 μm	6-13 μm	7-9 µm

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Appendix B. Dissolved Hydrogen Oxidation

In preliminary experiments on the nature of mass-transfer enhancement by bubble streams rising within the mass-transfer boundary layer, the bubble stream was generated at the lowest row in the 10×10 array of segments on the micromosaic electrode. Part of the motivation for this approach was the quantification of mass transfer due to multiple bubble streams, which could be generated at several segments in the bottom row. Anodic currents were measured over much of the segmented area in these experiments, obscuring any conclusions regarding masstransfer enhancement by the bubbles. It is believed that the anodic currents were the result of dissolved H₂ being oxidized at the mass-transfer monitoring segments. During a typical experiment, the entire electrode is polarized roughly 650 mV cathodic to the Fe $^{+3}/$ Fe $^{+2}$ redox potential, and the gas-evolving segment is polarized about 500 mV further cathodic. The Fe $^{+3}$ /Fe $^{+2}$ redox potential is 770 mV anodic to the normal hydrogen electrode, so the mass-transfer monitoring segments are "cathodic" for the Fe $^{+3}/$ Fe $^{+2}$ reaction, but "anodic" for the H $^+/$ H $_2$ reaction. This presents no problem as long as there is no significant amount of dissolved hydrogen that can be oxidized by these segments.

Experiments were performed to determine whether the hydrogen reaction was the cause of the anodic currents and to determine the area over which this reaction is likely to interfere with the indicator-ion reaction. This was accomplished by repeating the mass-transfer experiments in pure 0.5-M H $_2$ SO $_4$ with no Fe $^{+3}$ added. Once the magnitude of the anodic reaction of dissolved hydrogen was known, experiments could be performed under conditions that minimize this reaction. The results of the experiments conducted to determine the magnitude of the oxidation reaction of dissolved hydrogen are presented in the following.

Figure 1 shows the transient mass transfer to several segments directly above a single bubble-evolution site. The electrolyte is 0.0484-M Fe $_2(SO_4)_3$ in 0.5-M H $_2SO_4$, and the bubble evolution rate is 31 μ A. Segments within 300 μ m of the gas-evolving segment receive a net anodic current, the result of the combined oxidation of H $_2$ and reduction of Fe $^{+3}$. It is not until a height of 800 μ m above the gas-evolving segment that the mass-transfer rate reaches the background naturalconvection current of approximately 0.2 μ A (= 2 mA /cm²). Figure 2 shows the analogous experiment with no Fe $^{+3}$ added to the electrolyte, with *anodic* currents plotted as *positive*. The bubble evolution rate here is 28 μ A. The high anodic currents recorded show that the oxidation of dissolved hydrogen is indeed significant within 900 μ m of the gas-evolving segment. Figure 3 is the current distribution plot for the same run, also with anodic currents positive. The gas-evolving segment is the fifth from the left in the bottom (rear) row.

Figure 4 depicts the distribution of anodic current in an experiment similar to that shown in Figure 3, except that here the bubble stream was generated at the lowest of the satellite segments, 600 μ m below the lowest row of micro-electrodes, and in line with the sixth column of segments. It can be seen that this configuration minimizes the effect of the reaction of dissolved hydrogen on the mass-transfer rate to the segmented area of the micro-mosaic electrode. Most of the hydrogen not captured by the bubbles is oxidized at the buffer electrode, or is transported away



Figure 1. Current to several segments directly above the point of generation of a $31-\mu A$ bubble stream rising within the mass-transfer boundary layer. Parameter is distance above bubble-evolving segment. The electrolyte is 0.0484-M Fe $_2(SO_4)_3$ in 0.5-M H $_2SO_4$.



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Figure 2. Anodic current to several segments directly above the point of generation of a $28-\mu A$ bubble stream rising within the mass-transfer boundary layer, in 0.5-M H₂SO₄. Parameter is distance above bubble-evolving segment.



-- XBL 876-2924 --

Figure 3. Distribution of anodic current over the segmented portion of the micromosaic electrode when the bubble-evolution site is the fifth from the left in the lowest (rear) row. The bubble evolution rate is $28-\mu A$, and the electrolyte is 0.5-M H₂SO₄.

30 µA l but



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Figure 4. Distribution of anodic current over the segmented portion of the micromosaic electrode when the bubble-evolution site is 600 μ m below the bottom (rear) row and in line with the sixth column from the left. The bubble evolution rate is 30- μ A, and the electrolyte is 0.5-M H ₂SO ₄.

from the mass-transfer surface before it reaches the 10×10 array of monitoring electrodes. The average anodic current to the segmented area of the micro-mosaic is 0.16 mA /cm² for the run shown in Figure 4, compared to 0.75 mA /cm² for the run shown in Figures 2 and 3.

In all of the experiments presented in Chapter 3, in which the bubble stream was generated within the mass-transfer boundary layer, the bubbles were generated at the lowest of the satellite segments to minimize the effect of the oxidation of dissolved hydrogen.

Appendix C. Mass Transfer with Opposing Flows

Some of the preliminary experiments on the effect of bubble streams rising outside the mass-transfer boundary layer showed a destructive interference when the bubbles were rising at distances greater than 450 μ m from the micro-mosaic electrode. In the experiments described here, the bubble stream originated from a microelectrode positioned between 200 and 750 μ m from the micro-mosaic surface. These experiments were identical to those described in Chapter 3, except that a reference-electrode capillary extended from the top of the cell to the top of the active area of the micro-mosaic electrode. The reference-electrode capillary, as it was in these experiments, can be seen in Figure 3 of Chapter 3.

When the bubble stream originated at 200 or 300 μ m from the mass-transfer surface, the mass-transfer rate to the electrode was enhanced by the flow from the ascending bubbles. When the bubble stream was positioned at 450 μ m distance, however, the bubble stream had little effect on the mass-transfer rate, and at 750 μ m, the rising bubble stream actually caused a *decrease* in the mass-transfer rate. It was concluded that the reference-electrode capillary caused the upward laminar natural-convection along the electrode to deflect downward. In the absence of the capillary, the natural-convection flow would simply dissipate above the active electrode area.

Figure 1 shows the mass-transfer effect of the bubble stream, isolated from the total mass-transfer rate according to Equation 34 of Chapter 3, as a function of



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Figure 1. Mass-transfer effect of rising bubbles, averaged over the segmented portion of the electrode and over the time of data acquisition, corrected for the background natural-convection current, as a function of bubble evolution rate. Distance in μ m. H2: hydrogen evolution; O2: oxygen evolution.

bubble-evolution rate. Stream distances shown are 200, 300, 450, and 750 μ m relative to the micro-mosaic electrode, for both hydrogen (H2) and oxygen (O2). Figure 2 shows the mass-transfer rate plotted against stream position for various bubble currents. In both figures, the oxygen currents have been divided by two to give a volummetric rate equivalent to that of hydrogen. The use of Equation 34 when the bubble-induced convection opposes the free convection may not be strictly valid; however, the effect of bubble-stream position can be seen clearly in this presentation. The interference caused by the downflow can be seen by comparing Figures 1 and 2 to Figures 24 and 25 in Chapter 3, obtained after the cell was modified to eliminate the effect of the reference-electrode capillary.



Figure 2. Mass-transfer effect of rising bubbles, averaged over the segmented portion of the electrode, and corrected for the background natural convection current, as a function of bubble stream position. Currents in μA . H2: hydrogen evolution; O2: oxygen evolution.

Appendix D. Stability of the Micro-Mosaic Electrode

Two modes of deterioration of the micro-mosaic electrodes have been identified by photographic examination of used electrodes. One is the formation of a surface film on the electrode and the other is the dissolution of the metal used to enhance the adhesion of the electrode to the insulator. Figure 1 is a photograph at approximately $16 \times$ magnification of a used electrode that has what appears to be a surface film. Figures 2 and 3 show the same electrode at $55 \times$ and at roughly $110 \times$ magnification, respectively. This electrode, #HP01-08, was used for convectiononset experiments, but an unusually high number (33) of segments would not pass current. The segments in Figure 3 that appear the darkest were all working segments. What appears to be a patchy film on this electrode may be the product of an organic impurity in the electrolyte having been reduced at the electrode, or more likely, photoresist that was incompletely removed in processing.

Figure 4 shows electrode #HP01-07, which was immersed in the electrolyte for approximately five hours, but would not pass any current. This was a problem with several electrodes: either the oxide holes were incompletely etched, leaving the surface platinum segments electrically isolated from the aluminum conductors, or again, the photoresist was not removed properly. Since cleaning in organic solvents did not solve this problem, it is more likely that the oxide holes were not completely etched. This would help to explain the rapid deterioration of this particular electrode. Figure 5 is a closeup of the upper left corner of the electrode. There is a



Figure 1. Used micro-mosaic electrode #HP01-08, showing what appears to be a surface film, at approximately $16 \times$ magnification.



Figure 2. Used micro-mosaic electrode #HP01-08, with what appears to be a surface film, at approximately $55 \times$ magnification.



Figure 3. Used micro-mosaic electrode #HP01-08, which apparently has a surface film, at approximately $110 \times$ magnification.



Figure 4. Micro-mosaic electrode #HP01-07 after immersion in Fe $_2(SO_4)_3/H_2SO_4$ electrolyte for approximately five hours.


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Figure 5. Upper left corner of used micro-mosaic electrode shown in Figure 4, showing scalloped edge.

scalloped border along the outer edge of the 10×10 array of segments and along the inner edges of some of the segments. Figure 6 shows the top row of segments at still higher magnification (roughly 220 ×). The dark areas are places where the electrode material has peeled away from the oxide. A similar problem affecting one of the satellite segments of electrode #HP01-07 is shown at 550× magnification in Figure 7. The adhesion of the electrode to the oxide failed only in all areas that look like a scalloped border around the segments. Figure 8 shows this scalloping affect within segment [4,4] in Figure 5. What we believe we are seeing is an area where the chromium, used to enhance the adhesion of the platinum to the oxide, has been oxidized by the electrolyte. This type of deterioration would have been accelerated on a segment that, because of faulty manufacture, was not in contact with the aluminum conductor. In normal operation, the electrode is polarized to about 650 mV cathodic to the Fe $^{+2}/\text{Fe}$ $^{+3}$ equilibrium potential, which is still anodic to the chromium oxidation potential, but much less so than if the electrode were at open circuit.

The problem of oxidation of the less noble metal used for adhesion (Cr in the case of the Hewlett-Packard electrodes, and Ti in the Bell Labs electrodes) was foreseen by the researchers who made them, and both groups proposed solutions for future generations of electrodes. The Hewlett-Packard group suggested filling the grooves with silicon nitride as a final processing step. The Bell Labs group proposed using a lift-off metallization technique, which would allow the top electrode layers to cover the sides of the layers beneath, preventing exposure of the less noble metal to the electrolyte.



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Figure 7. One of the three satellite segments to the right of the 10×10 array of micro-electrodes in Figure 4, showing failure of adhesion of the electrode surface, at roughly $550 \times$ magnification.



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Figure 8. Segment [4,4] in Figure 5, showing edge where the chromium has been oxidized (roughly $550 \times$ magnification).

Electrode	Date used	Experiments	Hours in solution	Non-working segments initially	Non-working segments finally
BL01-10	2/21/85	022101-06	6	10	16
BL01-10	2/28/85	022801	2	would not pa	ss current
HP01-02	3/7/85	030701-04	14	16	29
HP01-03	3/10/85	031001-06	6	24	28
HP01-04	3/12/85	031201-06	5.5	4	5
HP01-05	3/16/85	031601-08	3 in H ₂ SO ₄	15	13
	, ,	031609-13	1 in Fe $_2(SO_4)_3$		
HP01-06	10/18/85	101801-04	8	29	25
HP01-07 ¹	10/20/85	102001-02	5	would not pa	ss current
HP01-09	10/21/85	102101-23	10	12	14
HP01-08 ²	3/11/86	031101-09	4	33	40
HP01-10	4/1/86			cell leaked	
BL01-12	6/8/86	060801-04	3	cell leaked	
HP01-11	9/24/86			would not pa	ss current
HP01-13	10/9/86		3.5	would not pa	ss current
HP01-04	10/10/86	101001-31	7.5	6	6

Appendix E. Electrode History

[1] Shown in Appendix D, Figures 4-8.

[2] Shown in Appendix D, Figures 1-3.

Appendix F. Chapter 2 Programs

The following programs were used for the calculations in Chapter 2. Program BUBCALC is used to calculate bubble shapes and stability. Program PLOTBUB reads the output files from BUBCALC and creates a plot file that is usable by Tell-a-graph.

Program BUBCALC

```
Program BUBCAL
    Implicit real*8 (a-h,o-z)
                       outfile
    character *10
                       BetaI, deltB, IND, UI, IPrint, IDraw, Beta
    common /par/
                       IBMax, INDR, IStab, LOUT
    common /par2/
    common /BUB/
                       Arcl, Cmass, RAR
    common /BUB2/
                       RmaxF, Vmax, Theta, Height, Radc, EMax
    LIN =
             3
    LOUT = 4
    open (unit=LIN, file='bubcal',
&
             defaultfile='[whitney.bubble].dat', status='old')
    Read (LIN, *) outfile
    open (unit=LOUT, file=outfile,
&
             defaultfile='[whitney.bubble].out', status='new')
    Read (LIN, *) ncase
    Do 100, J = 1, ncase
      Read (LIN, *) IND
      Read (LIN, *) Betal
                  *)
                       DeltB
      Read (LIN,
                  *) UI
      Read (LIN,
      Read (LIN, *) IPrint
      Read (LIN, *) IDraw
      Read (LIN, *) IBMax
      Read (LIN, *) INDR
      Read (LIN, *) IStab
       Call BUBSIZ
    Continue
    Stop
    End
                                                        BUBSIZ
    SUBROUTINE BUBSIZ
```

given contact angle, Theta, or radius of contact, Rc. Input parameters come through blocks param and param2. Common par contains: Betal, deltB, IND, UI, IPrint, IDraw, Beta Betal is an initial guess for Beta (<0 for bubbles). IND is 0 if final condition is Theta. 1 if final condition is Rc. 2 if final condition is Volume. UI is Theta if IND=0. Rc if IND=0. Rc if IND=0. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = -1 Prints beta, Theta, Rc, Height, Rmax, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 0 Prints nothing. If IDraw = 0 Prints and X's. IDraw is usually set at 0. Common par2 contains: IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. Other indicator variables: Contact and parama and param2.	с	Subroutine BUBSIZ finds maximum bubble size for a
 Input parameters come through blocks param and param?. Common par contains: BetaI, deltB, IND, UI, IPrint, IDraw, Beta BetaI is an initial guess for Beta (<0 for bubbles). IND is 0 if final condition is Theta. if final condition is Rc. if final condition is Volume. UI is Theta if IND=0. Rc if IND=1. Volume if IND=2. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints Beta, Theta, Rc, Height, Rmax, Volume. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par? contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. 	с	given contact angle, Theta, or radius of contact, Rc.
 Input parameters come through blocks param and param2. Common par contains: Betal, deltB, IND, UI, IPrint, IDraw, Beta Betal is an initial guess for Beta (<0 for bubbles). IND is 0 if final condition is Theta. 1 if final condition is Rc. 2 if final condition is Volume. UI is Theta if IND=0. Rc if IND=1. Yolume if IND=2. IPrint micrates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = -1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 0 Prints nothing. If IDraw = 1 Prints down and X's. IDraw indicates the down and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par2 contains: IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. Other indicator variables: 	c	
Common par contains: Betal, deltB, IND, UI, IPrint, IDraw, Beta Betal is an initial guess for Beta (<0 for bubbles). IND is 0 if final condition is Theta. 1 if final condition is Rc. 2 if final condition is Volume. UI is Theta if IND=0. Rc if IND=1. Volume if IND=2. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = -1 Prints beta, Theta, Rc, Height, Rmax, Volume. If IPrint = -1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. Draw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par? contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. Other indicator variables:	с	Input parameters come through blocks param and param2.
Common par contains: Betal, dettB, IND, UI, IPrint, IDraw, Beta Betal is an initial guess for Beta (<0 for bubbles). IND is 0 if final condition is Theta. 1 if final condition is Rc. 2 if final condition is Volume. UI is Theta if IND=0. Rc if IND=1. Volume if IND=2. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmaz, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. Draw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par? contains: IBMaz, INDR, Istab IBMaz is max number of times beta can be varied. If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. Other indicator variables:	c	
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 BetaI is an initial guess for Beta (<0 for bubbles). IND is 0 if final condition is Theta. if final condition is Rc. if final condition is Volume. UI is Theta if IND=0. Rc if IND=1. Volume if IND=2. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common parl contains: IBMax is max number of times beta can be varied. If INDR is an input indicator If INDR = 1, second occurences of contact angle are found. If INDR = 1, second occurences are sought. 	c	BetaI, deltB, IND, UI, IPrint, IDraw, Beta
 Beta[is an initial guess for Beta (<0 for bubbles). IND is 0 if final condition is Theta. 1 if final condition is Rc. 2 if final condition is Volume. UI is Theta if IND=0. Rc if IND=1. Volume if IND=2. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmaz, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 1 Prints Dothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par2 contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Other indicator variables: Other indicator variables:	с	
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<pre>2 if final condition is Volume. UI is Theta if IND=0. Rc if IND=1. Volume if IND=2. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. CIDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. Draw is usually set at 0. CE Beta is value of Beta for largest bubble meeting condition. CE IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results.</pre>	с	1 if final condition is Rc.
 UI is Theta if IND=0. Rc if IND=1. Volume if IND=2. IPrint indicates whether intermediate results should be printed. If IPrint = -1 Prints nothing. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par2 contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. 	c	2 if final condition is Volume.
Rc if $IND=1$. Volume if $IND=2$. C $Volume$ if $IND=2$. $IPrint indicates whether intermediate results should be printed.If IPrint = -1 Prints nothing.If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume.If IPrint = +1 Prints above plus Z's and X's FOREVERY BUBBLE.CIPrint = +1 Prints above plus Z's and X's FOREVERY BUBBLE.CIPrint is usually set at 0.CIDraw indicates whether Z's and X's should be printed forMAXIMUM SIZE BUBBLE.CIf IDraw = 0 Prints nothing.If IDraw = 1 Prints Z's and X's.CIf IDraw = 1 Prints Z's and X's.CIDraw is usually set at 0.CBeta is value of Beta for largest bubble meeting condition.CIBMax, INDR, IstabCIBMax is max number of times beta can be varied.CIf INDR = 0, only first occurences of contact angle are found.If INDR = 1, second occurences are sought.CIstab=(0,1) whether or not to print stability results.COther indicator variables:$	с	UI is Theta if IND=0.
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<pre>c If IPrint = -1 Prints nothing. If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume. If IPrint = +1 Prints above plus Z's and X's FOR EVERY BUBBLE. IPrint is usually set at 0. C IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. C Beta is value of Beta for largest bubble meeting condition. C Common par2 contains: IBMax, INDR, Istab C IBMax is max number of times beta can be varied. C INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. C Istab=(0,1) whether or not to print stability results. C Other indicator variables: C C INDE is an input indicator C Istab=(0,1) whether or not to print stability results.</pre>	с	IPrint indicates whether intermediate results should be printed.
c If IPrint = 0 Prints Beta, Theta, Rc, Height, Rmax, Volume. c If IPrint = +1 Prints above plus Z's and X's FOR c IPrint is ususally set at 0. c IPrint is ususally set at 0. c IPrint is ususally set at 0. c IDraw indicates whether Z's and X's should be printed for c IDraw indicates whether Z's and X's should be printed for c IDraw indicates whether Z's and X's should be printed for c IDraw indicates whether Z's and X's should be printed for c IDraw indicates whether Z's and X's should be printed for c IDraw = 0 Prints nothing. c If IDraw = 1 Prints Z's and X's. c IDraw is usually set at 0. c Beta is value of Beta for largest bubble meeting condition. c Common par2 contains: c IBMax, INDR, Istab c IBMax is max number of times beta can be varied. c If INDR = 0, only first occurences of contact angle are found. c If INDR = 1, second occurences are sought. c Istab=(0,1) whether or not to print stability results. c Other indicator variables:	с	If $IPrint = -1$ Prints nothing.
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cEVERY BUBBLE.cIPrint is usually set at 0.cIDraw indicates whether Z's and X's should be printed forcIDraw indicates whether Z's and X's should be printed forcIf IDraw = 0 Prints nothing.cIf IDraw = 1 Prints Z's and X's.cIDraw is usually set at 0.cBeta is value of Beta for largest bubble meeting condition.cCommon par2 contains:cIBMax, INDR, IstabcIBMax is max number of times beta can be varied.cINDR is an input indicatorcIf INDR = 0, only first occurences of contact angle are found.cIstab=(0,1) whether or not to print stability results.cOther indicator variables:	c	If $IPrint = +1$ Prints above plus Z's and X's FOR
c IPrint is usually set at 0. IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par2 contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Cother indicator variables: Cother indicator variables:	с	EVERY BUBBLE.
C IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. C Ommon par? contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. Other indicator variables:	с	IPrint is ususally set at 0.
c IDraw indicates whether Z's and X's should be printed for MAXIMUM SIZE BUBBLE. If IDraw = 0 Prints nothing. If IDraw = 1 Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par2 contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Cother indicator variables: Cother indicator variables:	с	
cMAXIMUM SIZE BUBBLE.cIf IDraw = 0 Prints nothing.cIf IDraw = 1 Prints Z's and X's.cIDraw is usually set at 0.cBeta is value of Beta for largest bubble meeting condition.cCommon par2 contains:cIBMax, INDR, IstabcIBMax is max number of times beta can be varied.cINDR is an input indicatorcIf INDR = 0, only first occurences of contact angle are found.cIstab= $(0,1)$ whether or not to print stability results.cOther indicator variables:	c	IDraw indicates whether $Z^{\prime}s$ and $X^{\prime}s$ should be printed for
c If $IDraw = 0$ Prints nothing. If $IDraw = 1$ Prints Z's and X's. IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. C Beta is value of Beta for largest bubble meeting condition. C Common par2 contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. C Other indicator variables: C Other indicator variables:	c	MAXIMUM SIZE BUBBLE.
$ \begin{array}{llllllllllllllllllllllllllllllllllll$	c	If IDraw = 0 Prints nothing.
 IDraw is usually set at 0. Beta is value of Beta for largest bubble meeting condition. Common par2 contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Cother indicator variables: 	c	If $IDraw = 1$ Prints Z's and X's.
Beta is value of Beta for largest bubble meeting condition. Common par2 contains: IBMax, INDR, Istab IBMax is max number of times beta can be varied. INDR is an input indicator If INDR = 0, only first occurences of contact angle are found. If INDR = 1, second occurences are sought. Istab=(0,1) whether or not to print stability results. Other indicator variables:	с	IDraw is usually set at 0.
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<pre>c INDR is an input indicator c If INDR = 0, only first occurences of contact angle are found. c If INDR = 1, second occurences are sought. c Istab=(0,1) whether or not to print stability results. c Other indicator variables: c C Istab = C I to the test is the second sec</pre>	с	IBMax is max number of times beta can be varied.
 c INDR is an input indicator c If INDR = 0, only first occurences of contact angle are found. c If INDR = 1, second occurences are sought. c Istab=(0,1) whether or not to print stability results. c Other indicator variables: c 	с	
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c If INDR = 1, second occurences are sought. c Istab=(0,1) whether or not to print stability results. c Other indicator variables: c	с	If $INDR = 0$, only first occurences of contact angle are found.
c Istab=(0,1) whether or not to print stability results. c Other indicator variables: c	с	If $INDR = 1$, second occurences are sought.
c Istab=(0,1) whether or not to print stability results. c Other indicator variables: c	с	• •
c c Other indicator variables: c	с	Istab = (0,1) whether or not to print stability results.
c Other indicator variables: c	с	
c and the second se	с	Other indicator variables:
	с	·
c Global indicators:	c	Global indicators:

с	IFAIL $= 1$ if current beta is too large and condition
с	can not be met. (Set at direction change if
с	NDIR = 2.)
c	If $=$ Number of times end condition could not be met.
с	IDONE = 1 if we have found maximum volume beta to three
c	sig figs. Going back for previous (best) beta.
c	IBETA = number of beta values used.
с	INBeta = number of stored end points.
c	
c	Indicators local to value of beta:
c	IDIR = sign of dx/ds.
с	NDIR = number of times IDIR has changed.
c	I2 = 0 at start of each beta because first
c	Runga–Kutta step is different.
с	IREE = 1 after first beta has been found.
c	INEXT = 0 at start of each beta, 1 immediately
c	after finding first theta. If INEXT
c	is 1, meeting theta boundary condition
c	is not checked.
c	
c	Other results are returned through common blocks.
c ·	
c	
c	Common BUB contains:
c	Arcl = Arc length of largest bubble,
c	Cmass = Z-value of center of mass of largest bubble
c	after release,
c	RAR = Radius of bubble after release.
с	
с	Common BUB2 contains:
с	RmaxF = Maximum radius of the largest bubble,
c	Vmax = Volume of largest bubble,
с	Theta = Contact angle of largest bubble,
с	Height = Height
с	Radc = Radius of contact.
c '	
с	·
с	Program by Gina Whitney, April 15, 1984.
с	
с	

Implicit real *8 (a-h,o-z)

dimension F(5), G(5), H(5), W(5), E(5), XK(5,4)

С

c c

901

dimension dimension dimension	X(2), Z(2), P(2500), Q(2500), TH(2500), V(2500) Bet(400), Thet(400), CRad(400), Heigh(400) Vo(400), Rma(400), Energ(400), Req7(400)
dimension	pittsV(400), PittsN(400), PittsR(400)
dimension	xmu(400), xkappa(400), xlambda(400)
common /pa common /pa common /Bl	r/ Betal, deltB, IND, UI, IPrint, IDraw, Beta r2/ IBMax, INDR, IStab, LOUT IB/ Arcl Cmass BAB
	IDO / Draw D. Vrance (D) to Habilt Dala DM a
common / D	B2/ RmaxF, Vmax, Ineta, Height, Radc, EMax
data Sqr	P. PI /1.414213562,3.141592654 /

Calculate constants, initialize Beta and set step size.

A = (Sqr2 - 1.0) / 2.0B = (2.0 - Sqr2) / 2.0C = -Sqr2 / 2.0D = 1.0 + Sqr2 / 2.0gamma = 72.8rho = 0.997= 980.0 gr rgog = rho * gr / gamma= dsqrt (1.d0 / rgog) xLc SS = 0.01DS = 0.01Beta = BetaIKMAX = 2500Write (LOUT, 901) IStab, IDraw, IND Format (i5, ' IStab', /, i5, ' IDraw', /, i5, ' If (IND . eq . 0) Then ThetaC = UIU = pi * UI / 180.0sinalf = sin (pi - U)U = sinalfWrite (LOUT, 902) ThetaC

IND')

```
902
             Format (f8.3, '
                                Criterion is contact angle')
           Elseif (IND . eq . 1)
                                 Then
             Rc = UI
             U = UI
             Write (LOUT, 903) Rc
  903
             Format (f8.5, '
                              Criterion is Radius of contact')
           Else
             Volc = UI
             U = UI
             Write (LOUT, 904) Volc
  904
             Format (e10.5, '
                               Criterion is Volume')
           Endif
с
   Set up headings for output.
С
С
           If (IPrint . gt . 0)
                                Then
             Write (LOUT, 910)
             Format ( /, 4x, 'Beta', 6x, 'Theta', 7x, 'Radc', 6x, 'Height', 5x,
  910
      1
              'Volume',6x, 'Rmax',11x, 'Z',12x, 'X',//)
           Endif
С
   Top of loop for first Beta.
С
   Initialize indicator variables for finding maximum Beta.
С
С
    99
           IBeta = 1
           NBRC1 = 0
           NBRC2 = 0
           INBeta = 0
           I4 = 0
           IDone = 0
           IFail = 0
С
    Top of loop for subsequent Betas.
С
   Initialize variables.
С
с
```

С

С

c c

С

c c

```
100
       R0 = sqrt ( abs ( Beta * gamma / ( rho * gr ) ) )
       If ( IBeta . GT . IBMax ) Go to 600
       Energy = 0.0
       Vol
              = 0.0
       Arcl = 0.0
       Cmass = 0.0
       X(1)
             = 0.0
       Z(1)
             = 0.0
       F(1)
             = 0.0
       G(1)
             = 0.0
       H(1)
             = 0.0
       W(1)
             = 0.0
       E(1)
             = 0.0
       P(1)
             = 0.0
       Q(1) = 0.0
       TH(1) = 180.0
       V(1) = 0.0
       Kount
               = 1
       KTemp = 1
       KTempd = 1
       IDir
              = 1
       NDir
               = 0
       I2
               = 0
       IREE
                = 0
       INEXT
                = 0
Go to 110 to begin Runge-Kutta calculations.
        Go to 110
Changing direction operation.
700
       If ( KTempd . ge . 3 ) Go to 720
```

 $\mathbf{215}$

Appendix F

```
С
С
   Decrease step size.
С
          DS = 0.1 * DS
          KTempd = KTempd + 1
          Go to 110
С
   Change direction.
С
С
  720
          IDir = -IDir
          NDir = NDir + 1
          G(1) = 1 - abs (1 - G(1))
          If (NDIR . eq . 1 ) Rmax = X(1)
          DS = SS
          KTempd = 1
          If (IND . eq . 1 . and . Rmax . lt . U) IFail = 1
          If (NDir . eq . 2) IFail = 1
          Go to 110
С
  Meeting condition operation.
С
С
  750
          If (KTemp. ge. 3) Go to 770
С
   Decrease step size.
с
С
          DS = 0.1 * DS
          KTemp = KTemp + 1
          Go to 110
с
   Condition met.
с
с
  770
          DS = SS
          KTemp = 1
          Go to 400
```

Chapter 2 Programs

```
¢
С
    Runge-Kutta Step
С
  110
          Do 230 I = 1, 4
с
   Check to see if getting time to switch direction.
С
С
          If (G(I). GT. 1) Go to 700
С
   Check to see if getting near stopping condition.
С
С
          If (INEXT . EQ . 1) Go to 160
          If (IND . ne . 0) Go to 140
С
   Check Theta.
С
С
          If ( IDir \cdot EQ \cdot -1 \cdot AND \cdot U \cdot EQ \cdot 1 ) Go to 400
          If ( IDir.EQ.-1 . AND . IREE.EQ.0 . AND . G(I).LT.U )
      &
                   Go to 750
          If ( IDir.EQ.-1 . AND . IREE.EQ.1 . AND . G(I).GT.U )
      &
                   Go to 750
          Go to 160
С
   Check Rc.
С
С
          If (IND . ne . 1) Go to 150
  140
          If (IREE . eq . 1 ) Go to 145
          If ( IDir . eq . 1 . AND . H(I) *R0 . gt . U ) Go to 750
          Go to 160
          If ( IDir . eq . -1 . AND . H(I) *R0 . lt . U ) Go to 750
  145
          Go to 160
С
   Check Volume.
с
С
          If ( (W(I)*pi*R0**3.0) . gt . U ) Go to 750
  150
```

Appendix F

```
С
С
   Proceed with calculation.
с
  160
          INEXT = 0
          If (I2 . ne . 0) Go to 180
С
C
   First time through.
с
          I_2 = 1
          XK(1,I) = DS
          Go to 190
С
С
   After first time through.
С
          XK(1,I) = DS * IDir * ((2.0 + Beta * F(I) - G(I) / H(I)))
  180
             * Sqrt (1.0 - G(I) * G(I))
      1
  190
          XK(2,I) = DS * G(I)
          XK(3,I) = DS * IDir * Sqrt (1.0 - G(I) * G(I))
          XK(4,I) = DS * G(I) * H(I) * H(I)
          XK(5,I) = DS * (2.0 * H(I) + dabs(beta) * H(I) * H(I)
             * F(I) * G(I)
      1
  200
          If (I.GT.1) Go to 210
          G(2) = G(1) + XK(1,1) / 2.0
          F(2) = F(1) + XK(2,1) / 2.0
          H(2) = H(1) + XK(3,1) / 2.0
          W(2) = W(1) + XK(4,1) / 2.0
          E(2) = E(1) + XK(5,1) / 2.0
          Go to 230
  210
          If (I.GT.2) Go to 220
          G(3) = G(1) + A * XK(1,1) + B * XK(1,2)
          F(3) = F(1) + A * XK(2,1) + B * XK(2,2)
          H(3) = H(1) + A * XK(3,1) + B * XK(3,2)
          W(3) = W(1) + A * XK(4,1) + B * XK(4,2)
          E(3) = E(1) + A * XK(5,1) + B * XK(5,2)
          Go to 230
  220
          If (I.GT.3) Go to 230
```

230 Continue

c End of Runge–Kutta. c

c Update and move things over. c

Kount = Kount + 1

X(2) = H(5) * R0Z(2) = F(5) * R0

CMass = CMass + (pi/2.0) * (Z(2) - Z(1)) * (Z(1) * X(1) * X(1) + Z(2) * X(2) * X(2)) X(1) = X(2) Z(1) = Z(2) G(1) = G(5) F(1) = F(5) H(1) = H(5) W(1) = W(5) E(1) = E(5) Y = Z(1) Vol = W(1) * pi * R0**3.0 Energy = E(1) * pi * gamma * R0 * R0

If (IDir . ne . -1) Go to 320

```
x5 = 0
          Go to 330
  320
          x5 = 180
  330
          P(Kount)
                    = X(1)
                    = Y
          Q(Kount)
          TH(Kount) = x5 - (180.0/pi) * IDir * Asin(G(1))
          V(Kount) = Vol
          Arcl = Arcl + DS * RO
С
   Check to see if condition not met.
С
С
  335
          If (IFail . NE . 1 ) Go to 340
          I4 = I4 + 1
          Go to 400
С
С
  Condition not yet satisfied.
с
  340
          If (Kount LT KMax)
                                     Go to 350
          Write (LOUT, 930) Kount
  930
          Format (10x, 'Step size too small ', I5, 'Steps')
          Go to 400
  350
          If (IND . ne . 0) Go to 370
С
  Check theta.
С
¢
          If ( IREE . ne . 0 ) Go to 360
          If ( IDir . eq . 1 . OR . G(1) . gt . U ) Go to 110
          Go to 400
  360
          If ( IDir . eq . 1 . OR . G(1) . lt . U ) Go to 110
          Go to 400
С
   Check Rc.
С
```

c 370 If (IND . ne . 1) Go to 380 If (IREE . eq . 1) Go to 375 If (IDir . eq . 1 . and . X(1) . lt . U) Go to 110 **Go to** 400 375 If (IDir . eq . 1) Go to 110 If (IDir . eq . -1 . and . X(1) . gt . U) Go to 110 **Go to** 400 С с Check volume. с 380 If (Vol. lt. U) Go to 110 С Met boundary condition. Print calculations. С С 400 If (KTemp. eq. 3) Go to 750 thetarad = TH(KOUNT) * pi / 180.d0Energy = Energy - rho * gr * Q(Kount) * Vol + 1 gamma * pi * P(Kount) ** 2.0 * cos(thetarad)PittsMu = 2.d0 / dsqrt(-Beta)PittsVol = Vol / (pi * xLc ** 3.0) PittsLam = P(KOUNT) / xLcPittsKap = Q(KOUNT) / xLcIf (IND . eq . 1 . and . TH(Kount) . gt . 170.) IDone = 1If (IND . eq . 2 . and . TH(Kount) . gt . 120.) IDone = 1If (IPrint . LT . 0) Go to 460 Store values с If $(IFail \cdot EQ \cdot 1)$ Go to 430 If (IDone . EQ . 1 . and . IND . eq . 0) Go to 430If (IND . eq . 1 . and . dabs(Beta) . ge . 0.05) DeltB = 0.01INBeta = INBeta + 1Bet(INBeta) = BetaThet(INBeta) = TH(KOUNT)Crad(INBeta) = P(KOUNT)Heigh(INBeta) = Q(KOUNT)Vo(INBeta) = Vol

	Rma(INBeta) = Rmax Energ(INBeta) = Energy
	PittsV(INBETA) = PittsVol PittsN(INBETA) = -3.0 * PittsVol/tan(thetarad) - PittsLam **3.0 PittsR(INBETA) = PittsLam *(PittsKap - PittsMu) + sin(thetarad) Req7(INBETA) = (PittsVol/PittsLam) - sin(thetarad) xMu(INBETA) = PittsMu xKappa(INBETA) = PittsKap xLambda(INBETA) = PittsLam
430	If (IPrint . EQ . 0) Go to 460
	If (IFail . EQ . 1) Go to 440
	If (IREE . EQ . 0 . AND . INDR . EQ . 1) Go to 460
440 940	Write (LOUT, 940) Format ()
If we's	re here, $IPrint = 1$ and we've found reentrant theta or gone to 90.
&	Write (LOUT, 960) Beta, TH(KOUNT), P(KOUNT), Q(KOUNT), Vol, RMax, Energy
450 950	Do 450, I = 1, Kount Write (LOUT, 950) TH(I), V(I), Q(I), P(I), -P(I) Format (11x, f11.7, 22x, f11.7, 11x, 3(2x,F11.7))
460	If (IFail . ne . 1) Go to 470 If (IND . ne . 1) Go to 500 If (Rmax . lt . U) Go to 500
If we' but no	re here, (IFAIL=1, IND=1, and IREE=1), we've found first Rc, t a second.
	$\begin{array}{l} \text{NBRC1} = \text{NBRC1} + 1 \\ \text{IFail} = 0 \\ \textbf{Go to } 495 \end{array}$
470	If (IND . eq . 2) Go to 495 If (IRFE eq INDR) Go to 490

222

С

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```
С
   If we're here we've found first theta or Rc and want to look for
С
С
   second.
с
          Energy = Energy + rho * gr * Q(Kount) * Vol -
      1
             gamma * pi * P(Kount) **2.0 * cos(thetarad)
          IREE
                 = 1
          INEXT = 1
          Go to 110
С
   Keep track of number of second Rc's found.
С
С
          If (IND.eq.1 . and . INDR.eq.1 ) NBRC2 = NBRC2 + 1
  490
          If (IDone . EQ . 1) Go to 600
  495
С
   Increase abs ( Beta ) and make a new bubble.
с
с
          Beta
                = Beta - DeltB
          IBeta = IBeta + 1
          Go to 100
С
   Criterion not met. Check if first time through.
С
с
  500
          If (IBeta . ne . 1 ) Go to 520
с
   First time through. Adjust abs ( Beta ).
с
с
          If ( IND . eq . 0 ) Go to 510
С
```

```
abs (Beta) too small for Rc or volume condition.
С
с
           Beta = Beta - DeltB
           Go to 99
С
   abs (Beta) too large for theta condition. Decrease abs (Beta).
С
С
  510
           Beta = Beta + DeltB
           Go to 99
С
   Check if first time condition not met.
С
с
          If (I4 . ge . 3 ) Go to 540
  520
с
   First time condition not met. Decrease abs ( Beta ) and DeltB to
С
   get more exact value of Beta.
С
с
           Beta = Beta + 0.9 * DeltB
           DeltB = 0.1 * DeltB
           IBeta = IBeta + 1
           IFail = 0
           Go to 100
С
   If we got here, we've not met condition for second time
С
   so we have Beta to 2 sig figs.
С
С
   Decrease Beta one more time to get previous bubble.
С
с
           IDone = 1
  540
           IFail = 0
           Beta = Beta + DeltB
           IBeta = IBeta + 1
           Go to 100
```

Chapter 2 Programs

С Finally done. Have largest equilibrium bubble to two sig figs С in Beta. Print results. Save final values to return. С С 600 If (IBeta . le . IBMax) Go to 605 Write (LOUT, 955) IBMax 955 Format (15, ' times — give up and go home') 605 Theta = TH (Kount) Height = Q (Kount) Rade = P (Kount) RMaxF = RMax VMax = Vol EMax = Energy = CMass / Vol CMass = (3.0 * Vol / (pi * 4.0)) ** (1.0/3.0)RAR Print out solutions. С If (IND . eq . 0) IABeta = (IBeta - 4) * 2 If (IND . eq . 1) IABeta = NBRC2*2 + NBRC1If (IND . eq . 2) IABeta = IBeta Write (LOUT, 957) IABETA 957 Format (i4, number of solutions', /) If (IABeta . eq . INBeta) Go to 610 Write (LOUT, 958) IABeta, INBeta 958 Format (' Number of Betas does not match, IABeta= ',I3,/ & 10x, INBeta = (.13)If (IND . eq. 1) Write (LOUT, 959) NBRC2, NBRC1 Format (' NBRC2= ',i3, ' NBRC1= ',i3) 959 Go to 655 610 If (IND . eq . 2 . OR . INDR . eq .0) Go to 640 If (IND . eq . 1) Go to 630 с с Print size results for theta case. с Write (LOUT, 900) 900 Format (/,x, 'Beta',2x, 'Theta',6x, 'Radc',7x, 'Height',6x, 'Volume',7x, 'Rmax',7x, 'Energy', / /) 1

```
IABeta = IABeta/2
           Do 620 I = 1, IABeta
             J = 2 I -1
  620
           Write (LOUT, 960) Bet(J), Thet(J), Crad(J), Heigh(J),
      &
                               Vo(J), Rma(J), Energ(J)
  960
           Format (f7.5,x,f6.3,x,e11.5,5(2x,e11.5))
           Do 625 I = 1, IABeta
             J = 2*(IABETA + 1) - 2*I
  625
           Write (LOUT, 960) Bet(J), Thet(J), Crad(J), Heigh(J),
      &
                               Vo(J),Rma(J),Energ(J)
С
С
       Print stability results for theta case.
С
           If (Istab . eq . 1)
                               Then
             Write (LOUT, 962)
  962
             Format ( //, 2x, 'Beta', 3x, 'mu', 4x, 'kappa', 4x, 'lambda',
      1
                5x, 'PittsV',6x, 'PittsN',6x, 'PittsR',6x, 'Eq7R',//)
           Do 626 I = 1, IABeta
                J = 2^{*}I - 1
                Write (LOUT, 961) Bet(J), xMu(J), xKappa(J), xLambda(J),
      &
                        PittsV(J), PittsN(J), PittsR(J), Req7(J)
  626
             Continue
  961
             Format (f6.4,x,f6.3,x,f6.4,5(2x,e10.4))
           Do 627 I = 1. IABeta
                J = 2*(IABETA + 1) - 2*I
                Write (LOUT, 961) Bet(J), xMu(J), xKappa(J), xLambda(J),
                        PittsV(J), PittsN(J), PittsR(J), Req7(J)
      &
  627
              Continue
           Endif
           Go to 655
С
С
       Print size results for Rc case.
С
  630
           Write (LOUT, 900)
           Do 633, I = 2*NBRC2, 2, -2
                                 Bet(I), Thet(I), Crad(I), Heigh(I),
  633
           Write (LOUT, 960)
      &
                               Vo(I), Rma(I), Energ(I)
           Do 635, I = 1, 2*NBRC2-1, 2
  635
           Write (LOUT, 960) Bet(I), Thet(I), Crad(I), Heigh(I),
```

С

c c

& Vo(I), Rma(I), Energ(I)If (IABeta . lt . 2*NBRC2+1) Go to 655 **Do** 637, I = 2*NBRC2+1, IABeta Write (LOUT, 960) Bet(I), Thet(I), Crad(I), Heigh(I), 637 & Vo(I), Rma(I), Energ(I)Go to 655 Print results for volume case or first case only for theta or Rc. Write (LOUT, 900) 640 **Do** 650, I = 1, IABeta 650 Write (LOUT, 960) Bet(I), Thet(I), Crad(I), Heigh(I), & Vo(I), Rma(I), Energ(I)If (IDraw . EQ . 0) Return 655 If (IND . eq . 0) Then Write (LOUT, 965) ThetaC, KOUNT 965 **Format** (//,10x, Max Bubble for Theta = ',f10.5,///,i5,' number of steps',/) & Elseif (IND . eq . 1) Then Write (LOUT, 970) Rc, KOUNT 970 **Format** (//,10x, Max Bubble for radius of contact = ',f10.6,& ///,i5, ` number of steps',/) Endif 680 Write (LOUT, 980) Format (17x, 'Z',10x, 'X', 10x, '-X', 8x, 'THETA', 9x, 980 & 'VOLUME') **Do** 690, I = 1, Kount Write (LOUT, 990) I, Q(I), P(I), -P(I), TH(I), V(I)690 **Format** (3x, I5, 5(2x,f10.6)) 990 Return End

Program PLOTBUB

Program PLOTBUB **Implicit Real***8 (a-h,o-z)

С С Program PLOTBUB prepares data files that are ready to plot on Tell-a-graph using the output file of BUBCALC.FOR and user input. С User supplies name of bubcalc output file, name of new plot С file and chooses from a menu of possible plots. с С С Program by Gina Whitney, May 1, 1987. С Dimension beta(400), Theta(400), Radc(400), Height(400) Dimension Volume(400), $\operatorname{Rmax}(400)$, $\operatorname{Energy}(400)$ Dimension xp(8,400)xMu(400), xKap(400), xLam(400), PittsV(400) Dimension Dimension PittsN(400), PittsR(400), Eq7R(400)Dimension z(2000), x(2000) Character *20 infile, outfile Character *40 xlab, ylab LIN = 3LOUT = 4100 **Call** GetFileName ('What is name of bubcalc.for output file?', & infile) If (infile . eq . ' ') Then Write (*,*) 'Try again' **Go to** 100 Endif **Call** ChInp ('What is name of the file to contain plot info?', & outfile) open (unit=LIN, file=infile, defaultfile='[whitney.bubble]', status='old') & open (unit=LOUT, file=outfile, defaultfile='[whitney.bubble]', status='new') & Read (LIN, *) IStab

С

С

Read (LIN, *) IDraw Read (LIN, *) IND **Read** (LIN, *) criterion Read (LIN, *) NBetas 105 Write (*,*) 'What do you want to plot?' Write (*,*) 'for Bubble shape parameters enter 1' If (IStab . eq . 1) Then Write (*, *) for Bubble stability parameters enter 2' Endif If (IDraw . eq . 1) Then Write (*,*) 'to draw maximum bubble enter 3' Endif Read (*, *) IChoice If (IChoice . lt . 3) Then If (IChoice . eq . 1) Go to 110 If (IChoice : eq . 2 . and . IStab . eq . 1) Go to 110 If (IChoice . eq . 3 . and . IDraw . eq . 1) Go to 110 Write (*,*) ' Bad choice, try again' Go to 105 Endif 110 Continue Skip the blank lines. **Do** 200, I = 1, IChoice *5 + (IChoice-1) *NBetas 200**Read** (LIN, 999) 999 Format () If (IChoice . eq . 1) Then **Do** 250, J = 1, NBetas **Read** (LIN, *) (xp(i,j), i=1,7)250 Continue 260Write (*,*) 'What do you want x to be?' Write (*,*) 'For beta enter 1' Write (*,*) 'For theta enter 2' Write (*,*) 'For Radc enter 3' Write (*,*) 'For height enter 4' Write (*,*) 'For volume enter 5' Write (*,*) 'For Rmax enter 6' Write (*,*) 'For energy enter 7' **Read** (*,*) NX

Write (*,*) 'What do you want y to be?' Write (*,*) 'For beta enter 1' Write (*,*) 'For theta enter 2' Write (*,*) 'For Radc enter 3' Write (*,*) 'For height enter 4' Write (*,*) 'For volume enter 5' Write (*,*) 'For Rmax enter 6' Write (*,*) 'For energy enter 7' **Read** (*,*) NY If (NX . eq . NY) Then Write (*, *) 'X = Y' **Go to** 260 Endif If (NX . gt . 7) Then Write (*,*) 'NX cannot be > 7' Go to 260 Endif If (NY . gt . 7) Then Write (*, *) 'NX cannot be > 7' **Go to** 260 Endif If $(NX \cdot eq \cdot 1) \cdot xlab = (<1.5m7)b''$ If (NX . eq . 2) xlab = $(<1.5m7)q^{"}$ If $(NX \cdot eq \cdot 3)$ xlab = (<1.5)Radius of Contact (cm)" If $(NX \cdot eq \cdot 4)$ xlab = (<1.5)Height (cm)" If (NX . eq . 5) xlab = (<1.5) Volume (cm < e.3h.8)3< exhxl.5))" If (NX . eq . 6) xlab = (<1.5)Maximum Radius (cm)" If $(NX \cdot eq \cdot 7)$ xlab = (<1.5)Energy (ergs)" If (NY . eq . 1) ylab = $(< m7)b^{"}$ If (NY . eq . 2) ylab = (< m7)q" If $(NY \cdot eq \cdot 3)$ ylab = 'Radius of Contact (cm)"' If $(NY \cdot eq \cdot 4)$ ylab = 'Height (cm)"' If (NY . eq . 5) ylab = 'Volume (cm < e.5h.8)3 < exhx))"' If $(NY \cdot eq \cdot 6)$ ylab = 'Maximum Radius (cm)"' If $(NY \cdot eq \cdot 7)$ ylab = 'Energy (ergs)"' Elseif (IChoice . eq . 2) Then

lseif (IChoice : eq : 2) Then Do 270, J = 1, NBetas Read (LIN,*) (xp(i,j), i=1,8) Continue

Write (*,*) 'What do you want x to be?' Write (*,*) 'For beta enter 1' Write (*,*) 'For mu enter 2' Write (*,*) 'For kappa enter 3' Write (*,*) 'For lambda enter 4' Write (*,*) 'For PittsV enter 5' Write (*,*) 'For PittsN enter 6' Write (*,*) 'For PittsR enter 7' Write (*,*) 'For Eq7R enter 8' **Read** (*,*) NX Write (*,*) 'What do you want y to be?' Write (*,*) 'For beta enter 1' Write (*,*) 'For mu enter 2Write (*,*) 'For kappa enter 3' Write (*,*) 'For lambda enter 4' Write (*,*) 'For PittsV enter 5' Write (*,*) 'For PittsN enter 6' Write (*,*) 'For PittsR enter 7' Write (*,*) 'For Eq7R enter 8' **Read** (*,*) NY If (NX . eq . NY) Then Write (*,*) 'X = Y' **Go to** 280 Endif If (NX . gt . 8) Then Write (*,*) 'NX cannot be > 8' **Go to** 280 Endif If (NY . gt . 8) Then Write (*,*) 'NX cannot be > 8' **Go to** 280 Endif If (NX . eq . 1) xlab = (< l.5m7)b" If $(NX \cdot eq \cdot 2) \times lab = (< l.5m7)m''$ If (NX . eq . 3) xlab = (<1.5m7)k''If (NX . eq . 4) xlab = $(<1.5m7)l^{"}$ If (NX . eq . 5) xlab = (<1.5)Reduced Volume" If (NX . eq . 6) xlab = $(<1.5)N^{"}$ If $(NX \cdot eq \cdot 7) x lab = (< l.5)R''$ If $(NX \cdot eq \cdot 8) \times lab = (<1.5)R$ from Eq. 7" If $(NY \cdot eq \cdot 1)$ ylab = (< m7)b''

```
If (NY . eq . 2) ylab = (-m7)m
          If (NY . eq . 3) ylab = (-m7)k^{*}
          If (NY . eq . 4) ylab = (< m7)l^{"}
          If (NY . eq . 5) ylab = 'Reduced Volume''
          If (NY \cdot eq \cdot 6) ylab = 'N"'
          If (NY \cdot eq \cdot 7) ylab = 'R"'
          If (NY \cdot eq \cdot 8) ylab = 'R from Eq. 7"'
        Elseif (IChoice . eq . 3)
                               Then
          Read (LIN, *) NSteps
          Read (LIN, 999)
          Read (LIN, 999)
          Do 300, J = 1, NSteps
             Read (LIN, *) I, Z(J), X(J)
300
          Continue
          xlab = (< l.5)x (cm)"
          ylab = 'z (cm)"
        Endif
Find max and min of data to be plotted.
        Xmina = 0.0
        Xmaxa = 0.0
        Ymina = 0.0
        Ymaxa = 0.0
        If (IChoice . lt . 3)
                             Then
          Do 320 J = 1, NBetas
             Xmina = Min (Xmina, xp(NX,J))
             Xmaxa = Max (Xmaxa, xp(NX,J))
             Ymina = Min (Ymina, xp(NY,J))
             Ymaxa = Max (Ymaxa, xp(NY,J))
320
          Continue
        Elseif (IChoice . eq . 3) Then
          Do 330 J = 1, NSteps
             Xmaxa = Max (Xmaxa, x(J))
330
          Continue
          Ymina = 0.0
          Ymaxa = Z(NSteps)
          Xmina = -Xmaxa
        Endif
```

С

С

Write (*,*) 'Minimum y is', Ymina Write (*,*) 'What is y min for plot?' **Read** (*,*) Ymin Write (*,*) 'Maximum y is', Ymaxa Write (*,*) 'What is y max for plot?' **Read** (*,*) Ymax Write (*,*) 'What is y step for plot?' **Read** (*,*) Ystep Write (*,*) 'Minimum x is', Xmina Write (*,*) 'What is x min for plot?' **Read** (*,*) Xmin Write (*,*) 'Maximum x is', Xmaxa Write (*,*) 'What is x max for plot?' **Read** (*,*) Xmax Write (*,*) 'What is x step for plot?' **Read** (*,*) Xstep С Write Tell-a-graph information. С Write (LOUT, 930) 930 Format ('gen plot.', /, 'legend is " ", height 0.2, ', & /; /; & style swiss light, shade pattern 2,', & legend frame off,', & legend box 0.5, 2.2, 4.0, 4.9, 1/, 1,1 & units is plot inches.') Write (LOUT, 932) 932 Format ('page border off.', & /, y room 2.') If (IChoice . gt . 0) Write (LOUT, 933) Format ('legend off.') 933 If (IChoice . eq . 1 . or . IChoice . eq . 3) Write (LOUT,934) **Format** ('title is "Bubble Shape"') 934 If (IChoice . eq . 2) Write (LOUT, 935) Format ('title is "Bubble Stability"') 935 If (IND . eq . 0) Write (LOUT, 936) Criterion Format ("Contact Angle of ',f3.0,' Degrees",', 936 & 1,1 height is 0.25,', & ratio 2,', /,' style is swiss light,', & /, & shade pattern 2.') /,

	If (IND . eq . 1) Write (LOUT, 937) Criterion
937	Format (' "Radius of Contact of ',f4.2,' cm",',
&	/,' height is 0.25,',
&	/, ratio 2 , ' ,
&	/,' style is swiss light,',
&	/,' shade pattern 2.')
	If (IND . eq . 2) Write (LOUT, 938) Criterion
938	Format ("Volume of ',f5.3,' cm < e.5h.7)3 < exhx)", ',
&	/, ' height is 0.25, ',
&	/, ' ratio 2, ',
&	/, style is swiss light, ,
&	/, ' shade pattern 2.')
	Write (LOUT, 941) xlab
941	Format ('x label is "',a40)
	Write (LOUT, 942)
942	Format (' height is 0.2,',
&	/, style is swiss light, ,
&	/,' shade pattern 2.')
	Write (LOUT, 943) ylab
943	Format ('y label is "',a34)
	Write (LOUT, 942)
	Write (LOUT,944) xmin, xmax, xstep, ymin, ymax, ystep
944	Format ('x min is',f7.3,', max',f7.3,', step'f7.3,'.'
&	/, 'y min is', $f7.3$, ', max', $f7.3$, ', step' $f7.3$, '.')
.	Write (LOUT, 945)
945	Format ('x origin is 2.5.',
&	/, y origin is 3.5.)
	If (Ichoice, ne. 3) Write (LOUT, 946)
946	Format ('x length is 4.'.
&	/. v length is 5.
	If (IChoice eq. 3) Write (LOUT, 947)
947	Format ('x length is 4.5.',
- &	/. 'y length is 4.5. ')
•	
	Write (LOUT, 948)
948	Format ('y tick is 2.',
&	$/, \mathbf{x}$ tick is 2. ⁽)
	Write (LOUT, 949)
949	Format ('y axis tick marks reversed.'.
&	/, x axis tick marks reversed.)
	If (IChoice . ne . 3) Then
	Write (LOUT, 950)
950	Format ('curve 1 texture 1.',

Chapter 2 Programs

c c

&	/,´curve 2 texture 5.´,
&	/, curve 1 symbol type 8.',
&	/, 'curve 2 symbol type 2.')
	Write (LOUT, 954)
954	Format ('every curve, color is no, thickness 2.'.
&	/ symbol count is 9999 ()
ũ	Flee
	W_{rite} (LOUT 051)
051	$\mathbf{F}_{\text{charge}} = \mathbf{F}_{\text{charge}} + \mathbf{F}_{cha$
901	FORMAL (every curve texture 1.)
055	write $(LOOI, 955)$
955	Format (every curve, color is no, thickness 2, ,
&	/,' symbol count is 0.')
	Endif
	Write (LOUT, 956)
956	Format ('input data.')
	Write (LOUT, 958)
958	Format ('"upper"')
	If (IChoice . lt . 3) Then
	Do 400, $J = 1$, NBetas /2
	Write (LOUT, *) $xp(NX,J)$, $xp(NY,J)$
400	Continue
	Write (LOUT, 960)
960	Format ('"lower"')
	Do 410 I — NBetag /2 \pm 1 NBetag
	W_{rite} (IOUT *) v_{r} (NV I) v_{r} (NV I)
410	$\mathbf{Continue} = (\mathbf{LOOI}, \mathbf{v}) \times \mathbf{p}(\mathbf{IX}, \mathbf{J}), \times \mathbf{p}(\mathbf{IVI}, \mathbf{J})$
410	Continue
	Elseit (IOnoice eq. 3) Inen
	Do 420, $J = 1$, NSteps
	Write (LOUT, *) $X(J)$, $Z(NSTEPS)-Z(J)$
420	Continue
	Write (LOUT, 960)
	Do 430, $J = 1$, NSteps
	Write (LOUT, $*$) -X(J), Z(NSTEPS)-Z(J)
430	Continue
	Endif
Write	subplate info
** / * tC	
061	Formet (and of data (
901 201	rormat (end of data. ,
ðZ O	/, subplot 1.,
X	/, gen plot.)
	Write (LOUT,944) xmin, xmax, xstep, ymin, ymax,

ystep

	Write (LOUT, 945) If (Ichoice . ne . 3) Write (LOUT, 946) If (IChoice . eq . 3) Write (LOUT, 947) Write (LOUT, 948)
963 &	If (Ichoice . ne . 3) Write (LOUT, 963) Format ('x axis offset 5, annotation off.', /,'y axis offset 4, annotation off.')
964 &	If (Ichoice . eq . 3) Write (LOUT, 964) Format ('x axis offset 4.5, annotation off.', /,'y axis offset 4.5, annotation off.')
965 &	Write (LOUT, 965) Format ('y axis mode reversed.', /,'y axis tick marks reversed.') Write (LOUT, 966)
966 &	Format ('title off.', /,'every curve symbol count is 0.') Write (LOUT, 956)
968 & &	Write (LOUT, 958) Write (LOUT, 968) Format (´ 0 0´, /,´end of data.´, / ´subplot 2.´)
~	Stop End

C Subroutine by Ken Jordan ********************** GetFileName c Used with permission.

SUBROUTINE GetFileName(Prompt,FileName) GetFileName

INTEGER Length CHARACTER *(*) Prompt,FileName LOGICAL FileExist

FileExist=.FALSE. **DO WHILE** (.NOT.FileExist)

CALL ChInp(Prompt,FileName)

CALL TrimCh(FileName) CALL StringLength(FileName,Length) IF (Length.EQ.0) RETURN &

INQUIRE(FILE=FileName,EXIST=FileExist) IF (.NOT.FileExist) WRITE(*,20) FileName END DO

20

FORMAT(X, 'Warning: Filename ',A<Length>,' doesn't exist.' ,/,X,' Please try again.',/)

END

RETURN

SUBROUTINE ChInp(PROMPT,VAR)

ChInp

c This subroutine prints the PROMPT and obtains a c character response in VAR

COMMON /EDITSUBS /DataEntered

CHARACTER *(*) PROMPT, VAR INTEGER Apostrophe LOGICAL DataEntered

WRITE(*,*) PROMPT(1:LEN(Prompt)) READ(*,100) VAR FORMAT(A)

100

IF (Var.EQ.' ') THEN DataEntered=.FALSE. ELSE DataEntered=.TRUE. END IF

200

Apostrophe=INDEX(Var, '`') IF (Apostrophe.NE.0) THEN Var(Apostrophe:Apostrophe)='`' GOTO 200 END IF

RETURN END

SUBROUTINE TrimCh(String)

TrimCh

CHARACTER *(*) String INTEGER Length,I

Length=LEN(String)

DO I=1,Length IF ((ICHAR(String(I:I)).LT.32) & .OR.(ICHAR(String(I:I)).EQ.255)) String(I:I)=´´ END DO

IF (String.EQ.' ') RETURN
IF (Length.LT.2) RETURN

DO WHILE (String(1:1).EQ. ' ') String(1:)=String(2:) **END DO**

RETURN END

SUBROUTINE StringLength(String,Length)

StringLength

CHARACTER *(*) String INTEGER Length

Length=LEN(String) DO WHILE((String(Length:Length).EQ. ´ ´).OR. & (String(Length:Length).EQ.CHAR(0))) Length=Length-1 IF (Length.EQ.0) RETURN END DO

RETURN END
Appendix G. Chapter 3 Programs

The following programs were used for the calculations in Chapter 3. Program RUNAVG reads a raw data file, usually RUN#.dat, as sent from the HP9825, and averages the current distribution over time. Output is put in RUN#.out. Program CHECK checks RUN#.out for bad segments. Program MICAVG averages over electrode area. Program ACROSS prepares a plot of the average current distribution across the electrode. Program CHANNEL prepares a plot of current to a segment versus time.

Program MICTAL is used to make current distribution plots of the micro-mosaic data using DISSPLA graphics. Program PLOTCYL plots the cuurent distribution due to a rising cylinder.

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Program RUNAVG

integer

Program RUNAVG

implicit real *8(a-h,o-z)

This program prepares an electrode plot frame which is the С average for an entire run or portion thereof. Two data files С are required. The first data file is RUNAVG.DAT in С directory /whitney.runstat/. It contains: С С Line ## of record variable С С 1 1 RUN, run # с 2 IPAR = 0, entire run used 1 С = 1, setting time window С = 2, setting scan limits C 3 if IPAR=1, TBegin, TEnd 1 с if IPAR=2, MBegin, MEnd С с с The second data file is 'Run #'.DAT in directory [whitney.bubdat]. It contains: С С Line # variable # of record С с 1 М, total # scans 1 С 2 TperP, time per point 1 С 3 Μ (T(I), I=1,M), time at start of scan С С 100 (D(I), I=1,100), channel assignments 4 С 5 M*100 V(M,I), voltage data с с с Program by Gina Whitney, August 20, 1985. С с С character *6 RUN real*8 T(1000), V(1000,100), Pot(100)

D(100)

Chapter 3 Programs

С

Read in data for averaging.

с

с

С

С

С

```
open (unit=3, file='runavg',
             defaultfile='[whitney.runstat].dat', status='old')
   &
        Read (3,900) RUN
        Format (A6)
900
        Read (3,901) IPAR
901
        Format(i3)
        If (IPAR \cdot eq \cdot 1)
                             Read (3,902) TBegin, TEnd
        Format (2f10.5)
902
        If (IPAR . eq . 2)
                             Read (3,903) MBegin, MEnd
        Format (2i5)
903
Now get the data for the run.
```

```
open (unit=4, file=RUN,
    &
             defaultfile='[whitney.bubdat].dat', status='old')
        open (unit=19, file=RUN,
             defaultfile='[whitney.runstat].out', status='new')
    &
        Read (4, *) M
        Read (4, *) TperP
        Do 100, I = 1, M
           Read (4, *) T(I)
100
         Continue
         Do 120, I = 1, 100
           Read (4, *) D(I)
120
         Continue
 Check input times.
        If (IPAR . eq . 0) Go to 200
         If (IPAR \cdot eq \cdot 1 \cdot and \cdot TBegin \cdot ge \cdot T(1) \cdot and \cdot
    &
                             TEnd . le . T(M) Go to 200
```

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С Find region of interest. с 200**If** (IPAR . eq . 0) **Go to** 300 If (IPAR . eq . 2) **Go to** 400 С Figure MBegin and MEnd for time-specified case. С С **Do** 220, I = 1, M If $(T(I) \cdot ge \cdot TBegin)$ Go to 240 220 Continue 240 MBegin = I - 1**Do** 260, I = MBegin, MIf $(T(I) \cdot gt \cdot TEnd)$ Go to 280 260 Continue 280 MEnd = I**Go to** 400 300 X = 1.0MBegin = 1MEnd = M400 If (MBegin . eq . 1) Go to 450 С Skip irrelevant info. с **Do** 420, I = 1, MBegin -1**Do** 420, L = 1, 100**Read** (4,999) 420 Continue 999 Format () 450 **Do** 470, L = 1, 100 Pot(L) = 0.0470 Continue с Read relevant info. с **Do** 500, I = MBegin, MEnd **Do** 500 L = 1, 100**Read** (4,930) V(I,L) Pot(L) = Pot(L) + V(I,L)500 Continue

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Chapter 3 Programs

930 **Format** (6x,f10.5) С Write average current distribution. С Write(19,940) RUN, MBegin, MEnd Format (' Run Number ', A6, ' Average current dist for scans ', 940 i5, ' through ', i5) & **Do** 520, L = 1, 100 Pot(L) = Pot(L) / float(MEnd + 1 - MBegin)Write (19,950) Pot(L) 520 Continue 950 **Format** (f10.5) Stop

243

End

Program CHECK

С

с

c c

С

c c c

с

PROGRAM CHECK

implicit real *8(a-h,o-z)

c This program skims a current distribution file and determines c how many of the electrode segments are anodic or not passing c current. Two data files are required. The first data file c is CHECK.DAT in directory [whitney.runstat]. It contains c the run number of the data file to check, RUN.

c The second data file is 'RUN'.out in directory [whitney.runstat]. c It contains:

Line # # of record variable 1 1 comment line 2 100 V(I,J), voltage data

c Program by Gina Whitney, March 20, 1986.

с

С

с

с

с

character *6 RUN real*8 VAN(100), VZIP(100), VMAX(100) IAN(100,2), IZIP(100,2), IMAX(100,2)integer LIN = 3LRUN = 4LOUT = 9Read in data for what run to check. open (unit=LIN, file='check', & defaultfile='[whitney.runstat].dat', status='old') Read (LIN,900) RUN 900 Format (A6) Now get the data for the run. open (unit=LRUN, file=RUN, & defaultfile='[whitney.runstat].out', status='old') open (unit=LOUT, file=RUN, & defaultfile= '[whitney.runstat].check ', status= 'new ') **Read** (LRUN,999) 999 Format () Write (LOUT,910) RUN 910 **Format** (5x, 'Electrode check for run number ',A6) KAN = 0KZIP = 0**Do** 100 I = 1, 10 **Do** 100 J = 1, 10Read (LRUN, *) V If (V . lt . -0.01) Then KAN = KAN + 1IAN(KAN,1) = IIAN(KAN,2) = JVAN(KAN) = VElseif $(abs(V) \cdot le \cdot 0.01)$ Then KZIP = KZIP + 1IZIP(KZIP,1) = I

	IZIP(KZIP,2) = J
	VZIP(KZIP) = V
	Elseif (V . ge . 1.25) Then
	KMAX = KMAX + 1
	IMAX(KMAX,I) = I
	IMAX(KMAX,2) = J $V(AX)(KMAX) = V$
	V(MAA(RIVIAA)) = V Endif
100	Continue
100	
	Write (LOUT,920) KAN
920	Format (5x,i5,' segments are anodic.')
	If (KAN . gt . 0) Then
	Do 200 K = 1, KAN M_{-1} (LOUT) t) LAN(K 1) LAN(K 2) MAN(K)
200	Write $(LOU1, *)$ IAN $(K, 1)$, IAN $(K, 2)$, VAN (K)
200	Endif
	Write (LOUT,930) KZIP
930	Format (5x,i5,' segments do not pass current.')
	If (KZIP . gt . 0) Then
	Do 300 K = 1, KZIP
200	$\mathbf{Write} (LOU1, *) IZIP(K, I), IZIP(K, 2), \forall ZIP(K)$
300	Endif
	Write (LOUT,940) KMAX
940	Format (5x, i5, ' segments pass maximum current.')
	If (KMAX . gt . 0) Then
	Do 400 K = 1, KMAX
400	Write $(LOUT, *)$ IMAX $(K,1)$, IMAX $(K,2)$, VMAX (K)
400	
	EBGII
	Stop
	End

Program MICAVG

PROGRAM MICAVG

c c

This program computes the average current distribution for an

						•	e-1 1	• •• •	
c c	(elect r od Inchitne	le plot. I u runstat]	t requi The	res two first is	input MICA V	jiles, both VCDAT	i in directi It include	ory
C C	l	wittite	j.i unotut j.	146	1101 10		G.DAI.	16 67664446	
c		Card #	⊑ # ö	f cards	•	Var	iable		
c		//	<i>i</i> 1 -	,					
c		1	1		RUN,	run	number		
с		2	1		NNot,	# se	gments no	ot averaged	!
с		3	N	Not	I,J	segme	nts not a	veraged	
с									
с		The se	cond data	file is	RUN.ou	it, the	output fi	le from the	e
с	1	progran	RUNAV	G.FOR.					
		Int Re: Ch	eger al aracter *6		LRUN, ZZ(10,1 RUN	LIN 0)			
		LR	IIN - 3						
	•	LIN	I = 7						
		LO	UT = 8						
c		***** (OPEN INI	PUT A	ND OU	TPUT	FILES.		
		ор	en (unit=	=LIN, f	ĭile =′m	icavg´,	,		
	& defaultfile='[whitney.runstat].dat', status='old')								
	Read (LIN, 900) RUN								
	900	ľ°O.	rmat (A6)					
	&	op z	en (unit= defaultfile=	=LRUN =´[whit	, file =1 ney.runs	RUN, tat].out	t', status	='old')	
		-			н. - И				
	905	Re Fo	ad (LRUN rmat ()	I, 905)					
	&	op z	en (unit = defaultfile=	=LOUT = ´ [whit	, file =1	RUN, tat].av	g', status	s='new')	
		W	rite (LOU	` T. 906) RUN	, ,	- /	,	
	906	Fo	rmat ('R	נווח חוו	, nber '	A6)			

Format (f10.4)

	Read (LIN, 920) NNot
920	Format (i3)
	Write (LOUT, 930) NNot
930	Format (i3, ' Segments not averaged')
	Sum = 0.0
	Do 100 I = 1,10
	Do 50 J = 1, 10
·	Sum = Sum + ZZ(I,J)
50	Continue
100	Continue
	If (NNot.eq.0) Go to 300
	Do 200 K = 1. NNot
	Read (LIN, 950) I,J
	Sum = Sum - ZZ(I,J)
	Write (LOUT, 940) I,J
200	Continue
300	CurDen = Sum *10.0 / (100.0 - float(NNot))
	Write (LOUT,960) CurDen
940	Format ('Segment #',2i3)
950	Format (2i3)
960	Format ('Average Current Density = ',f10.6,' $mA/cm2$ ')
	Stop
	End

Program ACROSS

С

c c

c c

PROGRAM ACROSS

Real	ZZ(10,10),	X(3)	,Z(10)
Character *6	RUN		

This program requires two data files. The first is across.dat in directory [whitney.runstat]. It contains:

of cards Variable

RUN 1 С 1 imess, whether or not to write I bub С 1 bubcur С C The second data file is RUN.save in directory (whitney.runstat). С с NNot. # segments not averaged 1 С С NNot I,J segments not averaged 10 JCol. Column number of separate column С 10 NRNot, Number of segments in JCol С to exclude с 10xNRNot IRow, JCol Segment to exclude С с The third data file is RUN.out in directory (whitney.runstat). C С LIN1 10 LIN 3 LRUN = 4LPLOT = 9open (unit=LIN1, file='across', & defaultfile='[whitney.runstat].dat', status='old') **Read** (LIN1, 900) RUN Read (LIN1, *) imess Read (LIN1, *) bubcur 900 Format (A6) open (unit=LRUN, file=RUN, & defaultfile='[whitney.runstat].out', status='old') open (unit=LIN, file=RUN, & defaultfile='[whitney.runstat].save', status='old') open (unit=LPLOT, file=RUN, & defaultfile='[whitney.runstat].across', status='new') NX = 10NY = 10С Write Tell-a-graph information. С с Write (LPLOT, 911) 911 Format ('gen plot.', & /, 'legend is "Legend", height 0.2, ',

style swiss light, shade pattern 2,', & & legend frame off,', & legend box 1.5,3.5,0.5,2.5,', Ϊ, & units is plot inches. () Write (LPLOT, 912) **912 Format** ('page border off.') Write (LPLOT, 913) 913 Format ('y room 2.') Write (LPLOT, 914) RUN Format ('title is "Run # ',A6,'"', 914 "Current Distribution Across Electrode", ', & & ratio 2,', & height is 0.35,', & style is swiss light,', & shade pattern 2.', /, & /, 'title off.') Write (LPLOT, 915) Format ('y label is "Current Density,', 915 i (mA/cm < e.8h.8)2 < hxex))", i& & height is 0.2,',style is swiss light,', & Ϊ,' & shade pattern 2.') Write (LPLOT, 916) **Format** ('x label is "<1.5)Horizontal Position (<m7)m<mx)m)", ', 916 & height is 0.2,',& style is swiss light,', /, 1,1 & shade pattern 2.') Write (LPLOT,917) 917 Format ('y min is 0, max 6, step 1.', /, x min is -500, max 500, step 500. ', & & /, 'cross off.') Write (LPLOT, 918) Format ('x origin is 2.5.', 918 & /, 'y origin is 3.5.') Write (LPLOT, 919) 919 Format ('x length is 4.', & /, 'y length is 5.') Write (LPLOT, 920) 920 Format ('y tick is 5.', & /, x tick is 5. () Write (LPLOT, 921) 921 **Format** ('y axis tick marks reversed.', & /, 'x axis tick marks reversed.') Write (LPLOT, 922) 922 Format ('curve 1 texture 1.',

Appendix G

/, 'curve 2 texture 2.', & & /, curve 3 texture 5.', /, 'curve 4 texture 14.') & If (imess . eq . 1) then Write (LPLOT, 923) bubcur **Format** ('msg 1 txt is "I<l.7h.7)bub <lxhx)= ',f4.1, 923 $(< m7)m < mx)A^{"}, (,$ & 1,' & style is swiss light,', & shade pattern 2,', /,' & height 0.2.') 1, Write (LPLOT, 924) 924 Format ('msg 1 connect LC, x = -450.0 y = 5.0', & units coordinate.') /, Endif Write (LPLOT, 926) 926 Format ('every curve, color is no, thickness 2.', & 1,1 symbol count is 0.') Write (LPLOT, 928) Format ('input data.') 928 Write (LPLOT, 929) 929 Format ('"curve 1"') **Read** (LRUN, 999) 999 Format () **Read** (LRUN, 935) ((ZZ(I,J), J=1,NY), I=1,NX) 935 **Format** (f10.4) **Do** 50 J = 1, 10 **Do** 50 I = 1, 10 If (ZZ(I,J) . lt . 0) ZZ(I,J) = 0.050 Continue Read (LIN, *) NNot Sum = 0.0**Do** 100 I = 1,10 **Do** 75 J = 1, 10 Sum = Sum + ZZ(I,J)75 Continue 100 Continue If (NNot.eq.0) Go to 300 **Do** 200 K = 1, NNot Read (LIN, *) I,J Sum = Sum - ZZ(I,J)

200

Continue

300	CurDen = Sum *10.0 / (100.0-float(NNot))
c**** No	ow begin column calculations.
	$\begin{array}{rcl} \text{NTCNot} &= & 0 \\ \text{SumTC} &= & 0.0 \end{array}$
	Do 500 K = 1, 10 Read (LIN, *) JCol Read (LIN, *) NRNot
	NTCNot = NTCNot + NRNot
400	$\begin{array}{l} {\rm Sum2} \ = \ 0.0 \\ {\rm Do} \ 400 \ {\rm I} \ = \ 1,10 \\ {\rm Sum2} \ = \ {\rm Sum2} \ + \ {\rm ZZ}({\rm I},{\rm JCol}) \\ {\rm Continue} \end{array}$
	If (NRNot.eq.0) Go to 490
450	Do 450 KK = 1, NRNot Read (LIN, *) IRow Sum2 = Sum2 - ZZ(IRow, JCol) Continue
490	SUMTC = SUMTC + Sum2 Sum2 = Sum2 *10.0 / (10.0-float(NRNot)) 7(Icol) = Sum2
500	Continue
590 600	$\begin{array}{llllllllllllllllllllllllllllllllllll$
	X(1) = 500. X(2) = 0.

251

 Write (LPLOT, 995) X(1), X(2)

 995
 Format (2f10.4)

С

c Write subplot2 info.

		Write (IPIOT 061)
061		Formet ('and of data '
901	0_	format (end of data. ,
	80	/, subplot I.,
	82	/, gen plot.)
		Write (LPLOT, 917)
		Write (LPLOT, 918)
		Write (LPLOT, 919)
		Write (LPLOT, 920)
		Write (LPLOT, 962)
962		Format ('x axis offset 5, annotation off.',
	&	/,'y axis offset 4, annotation off.')
		Write (LPLOT, 964)
964		Format ('y axis mode reversed.')
		Write (LPLOT, 965)
965		Format ('y axis tick marks reversed.')
		Write (LPLOT, 966)
966		Format ('title off.'.
	&	(, 'every curve symbol count is 0, ')
		Write (LPLOT, 928)
		Write $(LPLOT, 929)$
		Write (LPLOT 968)
890		Format $(1, 0, 0)$
500	8-	/ iend of data i
	8.	/ (subplot 9.1)
	æ	/, subplot 2. j
		S4
		scop

End

Program CHANNEL

PROGRAM CHANNEL

implicit real *8(a-h,o-z)

Chapter 3 Programs

This program prepares a channel plot for an electrode segment С vs time or 1 / sqrt(time) and calculates the Cottrell slope с from the file of raw data for the run. It is a simplified С version of POTSTEP.FOR. It does not require preRUN.dat С for potential step info. Two data files are required. С с The first is CHANNEL.DAT in directory [whitney.runstat]. С It contains: С С Line ## of record variable С с RUN, run # С 1 1 2 TPBegin, Time to begin plotting 1 С 3 1 TPEnd, Time to end plotting c 4 1 I J = segment of interestС с С The second data file is 'Run #'.DAT in directory [whitney.bubdat]. С It contains: С С Line ## of record variable С С с 1 1 М. total # scans TperP, time per point 2 1 С 3 М С (T(I), I=1,M), time atstart of scan С 100 (D(I), I=1,100), channelС . 4 asssignments С 5 M*100 V(M,I), voltage data С С Output files are RUN.chan in directory [whitney.runstat] for С slope info and RUN.chanIJ in directory [whitney.semtag] for С plot file. С С Program by Gina Whitney, October 23, 1985. с с С character *6 RUN character *25 DFILE real*8 T(1000), V(1000) integer D(100) LIN = 3LRUN = 4LOUT = 8

253

LPLOT = 9С Read in data for the run. С open (unit=LIN, file='channel', defaultfile='[whitney.runstat].dat', status='old') & Read (LIN, 900) RUN 900 Format (A6) open (unit=LOUT, file=RUN, & defaultfile='[whitney.runstat].chan', status='new') Read (LIN, *) TPBegin Read (LIN, *) TPEnd Read (LIN, *) I, J 903 Format (2i3) ICHAN = 10 * I + JС Now get the data for the run. С open (unit=LRUN, file=RUN, & defaultfile='[whitney.bubdat].dat', status='old') Encode (30, 907, DFILE) ICHAN 907 **Format** ('[whitney.runstat].chan',i3) ICHAN = ICHAN - 10908 Format (A25) Read (LRUN, *) M 905 Format (i5) Read (LRUN, *) TperP 906 **Format** (f15.9) **Do** 100, II = 1, M **Read** (LRUN, *) T(II) 100 Continue **Do** 120, II = 1, 100 Read (LRUN, *) D(II) 120 Continue 902 Format (i3)

```
С
с
   Check input times.
           If (TPEnd \cdot gt \cdot T(M))
                                     Go to 150
           If (TPBegin. lt . T(1))
                                    Go to 150
           Go to 200
  150
           Write (LOUT,910) T(1), T(M), TPBegin, TPEnd
  910
           Format (' Bad start or stop time',/
                                 ´,f10.5,´
      &
                      T(1) =
                                            T(M) = (,f10.5,/)
                      TPBegin = ',f10.5,' TPend = ',f10.5)
      &
           Stop
С
       Write Tell-a-graph information
с
С
  200
           open (unit=LPLOT, file=RUN,
      &
                  defaultfile=DFILE, status='new')
           Write (LPLOT, 911)
  911
           Format ('gen plot.',
                /, 'legend is "Legend", height 0.2, ',
      &
      &
                        style swiss light, shade pattern 2,',
                /,'
                        legend frame off,',
      &
                /,`
      &
                /,
                        legend box 1.5,3.5,0.5,2.5,',
      &
                        units is plot inches. ()
                /,
           Write (LPLOT, 912)
  912
           Format ('page border off.')
           Write (LPLOT, 913)
  913
           Format ('y room 2.')
           Write (LPLOT, 914) RUN, I, J
  914
           Format ('title is "Run # ',A6,'"',
                1.
                              "Segment # [',i2,',',i2,']",',
      &
                Ϊ,'
      &
                             height is 0.35,',
                  ,
                             style is swiss light,',
      &
                /,
      &
                             shade pattern 2.')
                /,
           Write (LPLOT, 915)
  915
           Format ('y label is "Cathodic Current (<m7)m<mx)A)", ',
      &
                             height is 0.2, ',
                /,
      &
                             style is swiss light,',
                /,
      &
                /,
                             shade pattern 2.')
           Write (LPLOT, 916)
  916
           Format ('x label is "Time (Seconds)",',
      &
                /,
                             height is 0.2,',
      &
                             style is swiss light,',
                /,
      &
                /,
                             shade pattern 2.')
           Write (LPLOT,917)
```

<pre>/, 'x min is 0, max 20, step 5.') te (LPLOT, 918) mat ('x origin is 2.5.', /, 'y origin is 3.5.') te (LPLOT, 919) mat ('x length is 4.', /, 'y length is 5.') te (LPLOT, 920) mat ('y tick is 5.', /, 'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /, 'x axis tick marks reversed.') te (LPLOT, 922) mat ('avage 1 texture 1')</pre>
<pre>te (LPLOT, 918) mat ('x origin is 2.5.', /,'y origin is 3.5.') te (LPLOT, 919) mat ('x length is 4.', /,'y length is 5.') te (LPLOT, 920) mat ('y tick is 5.', /,'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('avage 1 texture 1')</pre>
<pre>mat ('x origin is 2.5.', /,'y origin is 3.5.') te (LPLOT, 919) mat ('x length is 4.', /,'y length is 5.') te (LPLOT, 920) mat ('y tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('aveva 1 torture 1')</pre>
<pre>/, 'y origin is 3.5.') te (LPLOT, 919) mat ('x length is 4.', /, 'y length is 5.') te (LPLOT, 920) mat ('y tick is 5.', /, 'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /, 'x axis tick marks reversed.') te (LPLOT, 922) mat ('avage 1 tortuge 1')</pre>
<pre>te (LPLOT, 919) mat ('x length is 4.', /,'y length is 5.') te (LPLOT, 920) mat ('y tick is 5.', /,'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('avage 1 texture 1')</pre>
<pre>mat ('x length is 4.', /,'y length is 5.') te (LPLOT, 920) mat ('y tick is 5.', /,'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('avage 1 tortuge 1')</pre>
<pre>/, 'y length is 5.') te (LPLOT, 920) mat ('y tick is 5.', /, 'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /, 'x axis tick marks reversed.') te (LPLOT, 922) mat ('average 1 torture 1 ')</pre>
<pre>te (LPLOT, 920) mat ('y tick is 5.', /,'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('aveva 1 torture 1')</pre>
<pre>mat ('y tick is 5.', /,'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('aving 1 texture 1')</pre>
<pre>/,'x tick is 5.') te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('average 1 torture 1 ')</pre>
te (LPLOT, 921) mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922) mat ('average to taxture 1')
mat ('y axis tick marks reversed.', /,'x axis tick marks reversed.') te (LPLOT, 922)
/,'x axis tick marks reversed.') te (LPLOT, 922)
te (LPLOT, 922)
mat ('aunva 1 tavtura 1')
mas (curve i texture i.)
te (LPLOT, 923)
mat ('curve 2 texture 2.')
te (LPLOT, 924)
mat ('curve 3 texture 5.')
te (LPLOT, 925)
mat ('curve 4 texture 14.')
te (LPLOT, 926)
mat ('every curve, color is no, thickness 2.',
/, symbol count is 0.')
te (LPLOT, 928)
mat ('input data.')
te (LPLOT, 929)
mat ("curve 1"')

c c

20000 potometus enejo.

210	Do 290, MM = 1, M
	Do 290 I = 1, 100
	If (I. eq. ICHAN) Then
	Read (LRUN, 933) V(MM)
	Else
	Read (LRUN, 999)
	Endif
290	Continue
933	Format (6x,f10.5)
999	Format ()

С

c Initialize summations.

```
N = 0
sumx = 0.d0
sumy = 0.d0
sumxy = 0.d0
sumx2 = 0.d0
sumy2 = 0.d0
```

С

```
c Begin calculations.
```

```
Do 350, MM = 1, M
         Time = T(MM) + TperP * float(D(ICHAN)-1)
         If (Time . ge . TPBegin . and . Time . le . TPEnd)
                                                          Then
            Write (LPLOT, 935) Time, V(MM)
         Else
            Endif
935
         Format (2f10.6)
300
         If (Time . lt . TPBegin . or . Time . gt . TPEnd)
   &
         Go to 350
            sumx = sumx + Time
            sumy = sumy + V(MM)
            sumxy = sumxy + Time * V(MM)
            sum x2 = sum x2 + Time * Time
            sumy2 = sumy2 + V(MM) * V(MM)
            N = N + 1
350
       Continue
```

С

c Calculate slope and y-intercept.

```
yavg = sumy / float(N)
xnum = float(N) * sumxy - sumx * sumy
slope = xnum / (float(N) * sumx2 - sumx * sumx)
yint = sumy / float(N) - slope * sumx / float(N)
denom = (float(N) * sumx2 - sumx * sumx) *
(float(N) * sumy2 - sumy * sumy)
if (denom . gt . 0) then
r = xnum / sqrt(denom)
else
r = 0.0
endif
```

Write (LOUT, 940) yavg, slope

Appendix G

Format (' yavg = ',e15.9,/,'slope = (,e15.9)940 Write (LOUT, 945) yint y intercept = ',e15.9,' microamps') Format (' 945 Write (LOUT, 950) r correlation coefficient = ',e15.9) 950 Format (' c Write subplot2 info. с Write (LPLOT, 960) 960 Format ('end of data.', /, 'subplot 1.', & /, 'gen plot.') & Write (LPLOT, 917) Write (LPLOT, 918) Write (LPLOT, 919) Write (LPLOT, 920) Write (LPLOT, 962) Format ('x axis offset 5, annotation off.', 962 & /, y axis offset 4, annotation off.) Write (LPLOT, 964) 964 Format ('y axis mode reversed.') Write (LPLOT, 965) 965 Format ('y axis tick marks reversed.') Write (LPLOT, 966) 966 Format ('title off.', /, 'every curve symbol count is 0.') & Write (LPLOT, 928) Write (LPLOT, 929) Write (LPLOT, 968) Format (' 0 0', 968 & /, 'end of data.', & /, subplot 2.)Stop

End

Program MICTAL

PROGRAM MICTAL

с

***** Program for plotting micromosaic data using DISSPLA

258

```
***** on the talars printer.
с
       First data file is mictal.dat in directory [whitney.disspla].
с
       It contains:
С
С
       line
                       variable
С
С
            1
                      infile
С
с
       infile.dat contains:
С
С
            1
                      RUN, run #
С
            1
                      iarrow, =1 draw arrow showing bubble motion
С
            1
                      imess, =1 write time at bottom
с
            1
                      nlines, number of lines of message
С
            nlines
                      LmessN(10), nth lines message
С
                      irotate, rotates view (90 deg x irotate)
            1
С
                                counterclockwise by rotating
с
                                data block 90 deg clockwise
С
                      nkill.
                             number of segments to kill
            1
С
                            coordinates of segments to kill
. C
            nkill
                      i, j,
С
   The third data file is 'Run #'.OUT in directory (whitney.bubdat).
С
   It contains:
с
с
      # of lines
                         variable
С
с
                      V(M,I), voltage data
            M*100
С
с
С
   Program by Gina Whitney, November, 1986. Revised March, 1987.
С
с
с
dimension
                               ZMAT(22,22)
           character *10
                               infile
           character *6
                               RUN
                               dummy1, dummy2
           character *32
           dimension
                               ikill(10)
           dimension
                               Lmess1(8), Lmess2(8), IPKRAY(100)
           equivalence
                               (Lmess1,dummy1)
           equivalence
                               (Lmess2,dummy2)
```

data IXPTS /1/ data IYPTS /1/

LIN = 3

LDAT = 4LGRID = 7LOUT = 8open (unit=LIN, file='mictal', & defaultfile='[whitney.disspla].dat', status='old') Read (LIN, *) infile open (unit=LDAT, file=infile, & defaultfile='[whitney.disspla].dat', status='old') Read (LDAT, *) RUN Read (LDAT, *) Iarrow Read (LDAT, *) Imess Read (LDAT, *) nlines If (Nlines . gt . 0) Then **Read** (LDAT, *) dummy1 Endif If (Nlines . gt . 1) Then **Read** (LDAT, *) dummy2 Endif Read (LDAT, *) Irotate Read (LDAT, *) Nkill if (Nkill . gt . 0) Then **Do** 50 N = 1, Nkill Read (LDAT, *) I, J Ichan = 10 (I-1) + JIkill(N) = Ichan50 Continue Endif Now get the data from the run. open (unit=LGRID, file=RUN, & defaultfile='[whitney.runstat].out', status='old') ***** Read in data to contour. ***** Transform 10 * 10 grid to 22 * 22 ***** for use with unequal grid spacing. ***** First do the interior node values. Read (LGRID,999) **990**. Format () **Do** 200 I = 1, 10 J = 1, 10**Do** 200

С

С

С

с

с

```
Read (LGRID, 900)<sup>•</sup> ZVAL
               If (ZVAL \cdot LT \cdot 0.) ZVAL = 0.
               If (Nkill . gt .0) Then
                 Ichan = 10*(I-1) + J
                 Do 90 NN = 1, Nkill
                   If (Ichan \cdot eq \cdot Ikill(NN)) ZVAL = 0.0
   90
                 Continue
               Endif
               Do 100 II = 2*I, 2*I+1
                 Do 100 JJ = 2*J, 2*J+1
                   If (Irotate . eq . 0) ZMAT(II,JJ) = ZVAL
                   If (Irotate . eq . 1)
                                       ZMAT(JJ,23-II) = ZVAL
                   If (Irotate . eq . 2) ZMAT(23-II,23-JJ) = ZVAL
                   If (Irotate . eq . 3)
                                        ZMAT(23-JJ,II) = ZVAL
  100
               Continue
  200
          Continue
  900
          Format (E10.5)
       ***** Now zero the boundaries to obtain skirt effect.
С
          Do 300 I = 1, 22
            ZMAT(1,I) = 0.0
            ZMAT(22,I) = 0.0
             ZMAT(I,1) = 0.0
             ZMAT(I,22) = 0.0
  300
          Continue
       ***** Begin DISSPLA.
с
          Call TALARS
          Call NOBRDR
          Call PAGE (8.5, 11.0)
          Call PHYSOR (2.4,2.0)
          Call AREA2D (5.2,7.)
          Len = LINEST (IPKRAY, 100, 40)
          Call HEIGHT (0.2)
          CALL LINESP (2.0)
          CALL SWISSL
          Call MX1ALF ('STANDARD', '%')
          Call MX2ALF ('MATHE', '*')
          Call MX3ALF ('GREEK', '@')
          Call MX4ALF ('INSTRUCTION','!')
          Call NUMODE ('EQUAL')
          CALL SHDCHR (90., 1, .01, 1)
```

If (imess . eq . 1) Then CALL LINES (Lmess1, IPKRAY, 1) if (Nlines . gt . 1) CALL LINES (Lmess2, IPKRAY, 2) XW = XSTORY(IPKRAY,Nlines)YW = YSTORY(IPKRAY, Nlines)XL = 4.5 - XWYL = 6.5 - YWCALL STORY (IPKRAY, Nlines, XL, YL) Endif ***** Set up workbox area. Call VOLM3D (10.0, 10.0, 5.0) **Call** SETSPC (2.0, 2.0, 0.03) Call HEIGHT (0.25) **Call X3NAME** ('!L1.0A3%Vertical Dimension&',100) **Call Y3NAME** ('Horizontal Dimension&',100) Call Z3NAME ('Current (@m%A)&',100) **Call** VUABS (55.0, -25.0, 35.0) Call ZAXANG (90.0) Call INTAXS ***** Switch to virtual coordinates. Call XAXCTR Call YAXCTR **Call** YAXEND ('ENDS') Call GRAF3D (1., 1., 11., 1., 1., 11., 0., .1, .5) **Call** RESET ('SETSPC') ***** Calculate grid values for ZMAT(IXROW,IYCOL). **Call** SURTRN ('BOTH') ***** Draw surface. Call SURMAT (ZMAT, IXPTS, 22, IYPTS, 22, 0) If (larrow . eq . 1) then Call VECTR3 (-10, 6.5, 0.15, -5, 6.5, 0.15, 1001) Endif Call SURMAT (ZMAT, IXPTS, 22, IYPTS, 22, 0) **Call** ENDPL(0)

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С

с

с

С

Call DONEPL Stop End X3DMAT Function X3DMAT(IXROW) Dimension XTABLE(22) data XTABLE / 1.00, 1.01, 1.99, 2.01, 2.99, 3.01, 3.99, 4.01, & 4.99, 5.01, 5.99, 6.01, 6.99, 7.01, 7.99, 8.01, 8.99, 9.01, 9.99, 10.01, 10.99, 11.00 / & X3DMAT = XTABLE(IXROW)Return End Y3DMAT Function Y3DMAT(IYCOL) Dimension XTABLE(22) data XTABLE / 1.00, 1.01, 1.99, 2.01, 2.99, 3.01, 3.99, 4.01, & 4.99, 5.01, 5.99, 6.01, 6.99, 7.01, 7.99, 8.01, 8.99, 9.01, 9.99, 10.01, 10.99, 11.00 / & Y3DMAT = XTABLE(IYCOL)Return End

Program PLOTCYL

Program PLOTCYL **Character***64 outfile, geofile

C		
с	This program plo	ts the theoretical current distribution
с	due to a rising c	ylinder.
с		
с	It requires two d	ata files. The first is plotcyl.dat in
с	directory [whitney	.cylin]. It has:
с		
с	outfile,	name of output file for average value
с	geofile,	name of input file for geometric data
с	Dif,	diffusion coefficient of reactant
с	Cinf,	concentration of reactant in the bulk
с	dist,	distance of cylinder from electrode
с	rad,	radius of cylinder
с	mode,	= 1 equal volume (no liquid entrained)

```
= 2 equivalent drag
С
                     = 3 max liquid entrained
С
                     bubble current in microamps
           bubcur
С
           iarrow, =1 draw arrow showing bubble motion
С
           imess, =1 write time at bottom
С
           nlines, number of lines of message
С
           LmessN(10), nth lines message
с
С
С
   The second data file is geofile.dat.
                                     It contains the geometric
С
   information for the calculation.
С
С
   This program must be linked by using the command 'linkdis plotcyl'
С
   on this account.
С
С
dimension
                              ZMAT(22,22)
           dimension
                              Lmess1(8), Lmess2(8), IPKRAY(100)
           character *32
                              dummy1, dummy2
          equivalence
                              (Lmess1,dummy1)
          equivalence
                              (Lmess2,dummy2)
          DATA
                   F
                           /96486.7d0/
          DATA
                   gamma /0.892979511d0/
          DATA
                          /3.141592653d0/
                   pi
           RToP = 82.055d0 * 298.15d0 / 1.d0
          IXPTS = 1
          IYPTS = 1
С
   Open input files
с
          LIN1 = 3
           LIN2 = 4
          LOUT = 7
           open (unit=LIN1,file='plotcyl',
      &
             defaultfile= '[whitney.cylin].dat', status= 'old')
           read (LIN1, *) outfile
           read (LIN1, *) geofile
           open (unit=LIN2,file=geofile,
      &
             defaultfile=' whitney.cylin |.dat', status='old')
           open (unit=LOUT,file=outfile,
      &
             defaultfile='[whitney.cylin].dat', status='new')
           read (LIN1, *) Dif
```

С

c c

С

С

с

read (LIN1,*) Cinf read (LIN1, *) dist read (LIN1, *) rad read (LIN1, *) mode read (LIN1,*) bubcur Read (LIN1, *) Iarrow Read (LIN1, *) Imess **Read** (LIN1, *) nlines If (Nlines . gt . 0)Then Read (LIN1,*) dummy1 Endif If (Nlines . gt . 1) Then **Read** (LIN1, *) dummy2 Endif a = sqrt (dist*dist - rad*rad)eta = alog ((dist + a) / rad)Calculate Vc based on mode. Vdot = bubcur * RToP * 1.d-6 / (2.d0 * F)if (mode . eq . 1) then Vc = Vdot / (pi * rad * rad)elseif (mode . eq . 2) then Vc = Vdot / (pi * rad * rad) * 6.d0 * eta / (4.d0 * fun(rad / dist))elseif (mode . eq . 3) then Vc = 2.d0 * rad * rad * 980.d0 / (9.d0 * 0.01d0)else **write** (LOUT,990) 990 format ('bad mode') stop endif group = (2.d0 * a * Vc / (9.d0 * Dif * eta)) ** (1.d0/3.d0)factor = F *Dif * Cinf *(3.d0/2.d0) * group / (gamma * 10.d0)write (LOUT,920) factor 920 **format** ('factor = ',3x,d15.9) Read in geometry file and transform 10 * 10 grid to 22 * 22 for use with unequal grid spacing ***** FIRST DO THE INTERIOR NODE VALUES sum = 0.d0**DO** 200 I = 1, 10

```
DO 200 J = 1, 10
              READ (LIN2, *) ZVAL
              ZVAL = ZVAL * factor
              write (LOUT, *) ZVAL
              sum = sum + ZVAL
              DO 100 II = 2*I, 2*I + 1
                DO 100 JJ = 2*J, 2*J + 1
                   ZMAT(II, JJ) = ZVAL
          CONTINUE
  100
          CONTINUE
  200
         sum = sum / 100.d0
          write (LOUT,930) sum
         format (' averge current is ',d15.9,3x, 'microamps')
  930
      ***** Now zero the boundaries to obtain skirt effect.
         DO 300 I = 1, 22
            ZMAT(1,I)
                      = 0.0
            ZMAT(22,I) = 0.0
                       = 0.0
            ZMAT(I,1)
            ZMAT(I,22) = 0.0
  300
          CONTINUE
\mathbf{C}
         **** BEGIN DISSPLA
С
\mathbf{C}
          Call VT240
          Call NOBRDR
          Call PAGE(8.5, 11.0)
          Call PHYSOR (2.4, 2.0)
          Call AREA2D (5.2, 7.0)
          Len = LINEST (IPKRAY, 100, 40)
          Call HEIGHT (0.2)
          CALL LINESP (2.0)
          CALL SWISSL
          Call MX1ALF ('STANDARD', '+')
          Call MX2ALF ('MATHE', '*')
          Call MX3ALF ('GREEK', '@')
          Call MX4ALF ('INSTRUCTION','!')
          Call NUMODE ('EQUAL')
          CALL SHDCHR (90., 1, .1, 1)
          If (imess . eq . 1) Then
             CALL LINES (Lmess1, IPKRAY, 1)
            if (Nlines . gt . 1) CALL LINES (Lmess2, IPKRAY, 2)
```

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С

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XW = XSTORY(IPKRAY, Nlines)YW = YSTORY(IPKRAY,Nlines)XL = 4.5 - XWYL = 6.5 - YWCALL STORY (IPKRAY, Nlines, XL, YL) Endif ***** SET UP WORKBOX AREA **Call** VOLM3D (10.0, 10.0, 5.0) **Call** SETSPC (2.0, 2.0, 0.03) Call HEIGHT (0.25) Call X3NAME ('!L1.0A3+Vertical Dimension&',100) **Call** Y3NAME ('Horizontal Dimension&',100) Call Z3NAME ('Current (@m+A)&',100) **Call** VUABS (55.0, -25.0, 35.0) - Call ZAXANG (90.0) **Call** INTAXS ***** SWITCH TO VIRTUAL COORDINATES Call XAXCTR **Call** YAXCTR Call YAXEND ('ENDS') **Call** GRAF3D (1., 1., 11., 1., 1., 11., 0., .1, .5) Call RESET ('SETSPC') ***** CALCULATE GRID VALUES FOR ZMAT(IXROW,IYCOL) **Call** SURTRN ('BOTH') ***** DRAW SURFACE Call SURMAT (ZMAT, IXPTS, 22, IYPTS, 22, 0) If (larrow . eq . 1) then **Call** VECTR3 (-15, 7.5, 1.1, -10, 7.5, 1.1, 1001) Endif Call SURMAT (ZMAT, IXPTS, 22, IYPTS, 22, 0) **Call** ENDPL(0) Call DONEPL Stop End

)

```
Fun
    Function Fun(x)
    real*8
             х
    fun = 1.d0 - 9.d0 * x / 16.d0 + x * * 3.d0 / 8.d0 -
             x**4.d0*45.d0/256.d0 - x**5.d0/16.d0
 &
    Return
    End
                                                       X3DMAT
    FUNCTION X3DMAT(IXROW)
    Dimension XTABLE(22)
    data XTABLE / 1.00, 1.01, 1.99, 2.01, 2.99, 3.01, 3.99, 4.01,
                  4.99, 5.01, 5.99, 6.01, 6.99, 7.01, 7.99, 8.01,
&
                  8.99, 9.01, 9.99, 10.01, 10.99, 11.00 /
&
    X3DMAT = XTABLE(IXROW)
    Return
    End
                                                       Y3DMA T
    FUNCTION Y3DMAT(IYCOL)
    Dimension XTABLE(22)
    data XTABLE / 1.00, 1.01, 1.99, 2.01, 2.99, 3.01, 3.99, 4.01,
                  4.99, 5.01, 5.99, 6.01, 6.99, 7.01, 7.99, 8.01,
&
                  8.99, 9.01, 9.99, 10.01, 10.99, 11.00 /
&
    Y3DMAT = XTABLE(IYCOL)
    Return
    End
```

Program GEOM

С

Program GEOM

Implicit Real*8 (a-h,o-z) External fun Character*64 outfile Real*8 zfact(10), yfact(10)

c This program prepares a file containg the geometric portion
c of the current function due to a rising cylinder for use
c with the program plotcyl. This program must be linked with
c yint.

LIN = 3LOUT = 4

Open (**unit=**LIN, **file=**'geom',

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& defaultfile='[whitney.cylin].dat', status='old') **Read** (LIN, *) outfile **Open** (unit=LOUT, file=outfile, & defaultfile='[whitney.cylin].dat', status='new') Read (LIN, *) dist Read (LIN, *) rad a = dsqrt(dist * dist - rad * rad)**Do** 100 i = 1, 10z1 = 0.2d0 + dfloat(i-1)*0.01d0z2 = z1 + 0.01d0zfact(i) = (z2**(2.d0/3.d0) - z1**(2.d0/3.d0)) / (z2 - z1)y1 = -0.05d0 + dfloat(i-1)*0.01d0y2 = y1 + 0.01d0**Call** yint (y1, y2, a, fun, yfact(i))100 Continue **Do** 200 i = 1, 10**Do** 200 j = 1, 10fact = zfact(i) * yfact(j)Write (LOUT, *) fact 200 Continue Stop End yint SUBROUTINE yint(b1, b2, par, fun, val) Implicit Real*8 (a-h, o-z) External fun Uses Simpson's rule to integrate 'fun' from lower limit b1 to upper limit b2. Par is a parameter (optionally) used in 'fun'. Val is the returned value. m = 10xm = dfloat(m)h = (b2 - b1) / (2.d0 * xm)sum4 = 0.d0sum2 = 0.d0

Do 100 i = 1, m-1 xi = b1 + (2.d0 * dfloat(i) - 1.d0) * (b2 - b1)/(2.d0 * xm) xip = xi + h sum4 = sum4 + fun(xi,par)sum2 = sum2 + fun(xip,par)

100 Continue

&

```
\begin{array}{rl} xm &= b2 - h \\ sum4 &= sum4 + fun(xm,par) \\ val &= h/3.d0 * (fun(b1,par) + 4.d0*sum4 + 2.d0*sum2 \\ &\quad + fun(b2,par)) / (b2 - b1) \end{array}
```

Return End

Function fun(x,p1) Implicit real*8 (a-h, o-z) fun

fun = 1.d0 / (x*x + p1*p1) ** (1.d0/3.d0)End

Appendix H. Chapter 4 Programs

The following programs were used for the calculations in Chapter 4. Program FITRHO is used to fit the density of sulfuric acid to the concentration, while accounting for the incomplete dissociation of the bisulfate ion. Program SIMPFIT, a simplified version of FITRHO, is used to fit $FeSO_4$ and $Fe_2(SO_4)_3$ density information and is not listed here. Program NATFEM is a finite element code used to solve the coupled equations of ionic species transport and solution electroneutrality. The equations are given in the appendix of Chapter 4.

Program FITRHO

PROGRAM FITRHO Implicit Double Precision (a-h,o-z) Program FITRHO reduces density information for sulfuric acid to obtain the constants in the equation $= a + b(cH+) + c(cHSO_4-) + d(cSO_4=)$ rho User input file, FITRHO.dat, reads as follows: **#** OF LINES VARIABLE infile 1 1 outfile Second input file is 'infile.dat'. It contains: # OF LINES VARIABLE TITLE (A70) 1 Ν 1 1 Mode = 0, solve for all alphas = 1, set alpha SO4= to 0 = 2, set alpha SO_4 = and alpha HSO_4 - to 0 1 iplot = 1, plot density info = name of plot file 1 plotf 1 corr = correction for density to convert from sp.g. to density 1 indw = 1 if data is in wt%, 0 if in M. N Cacid(i), rho(i) TITLE is a comment up to 70 letters. N is the number of conc, rho data points. In order that the output specify the concentration range covered by the density data, the user should input the lowest concentration data point first and the highest last. However, the order of the data has no effect on the computation.

c c

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С **Program FITRHO** solves for a, b, c, d directly by minimizing С the sum of squares of the differences between the calculated С and experimental densities. С С Program by Gina Whitney, September 7, 1986 с С с **Common** / MAT /A(4,4), B(4) real*8 Cacid(100), rho(100), c(3,100)Character *70 TITLE Character *12 plotf, infile, outfile LIN1 = 3LIN - 4 _ LOUT = 7 LPLOT = 9open (unit=LIN1, file='FITRHO', & defaultfile='[whitney.natcon].dat', status='old') **Read** (LIN1, *) infile **Read** (LIN1, *) outfile open (unit=LIN, file=infile, & defaultfile='[whitney.natcon].dat', status='old') open (unit=LOUT, file=outfile, & defaultfile=' whitney.natcon.out', status='new') 50 Read (LIN, 900) TITLE 900 Format (A70) write (LOUT, 905) TITLE 905 **Format** (10x,A70) Read (LIN, *) N **If** (N.gt.100) **then** Write (LOUT, 915) N Format (5x, 'N = ',i3,' N cannot be greater than 100', /, 915 & 'change dimension statement for Cacid and rho') Stop Endif

```
Read (LIN, *) Mode
        Read (LIN, *) iplot
        Read (LIN,
                    *) plotf
        Read (LIN, *) corr
        Read (LIN, *) indw
        Do 100 i = 1, N
          Read (LIN, *) Cacid(i), rho(i)
        Continue
100
Correct density info for density of water (rho info in CRC
is in sp.g.)
        Do 110 i = 1, N
          rho(i) = rho(i) * corr
110
        Continue
        corrc = 98.08d0
        if (indw . eq . 1) then
          Do 120 i = 1, N
             Cacid(i) = Cacid(i) * rho(i) * 1000.d0 / corrc
120
          Continue
        endif
        Write (LOUT, 920)
920
        format ('
                             Kount
                                         CH
                                                  CHSO4-
                                                              CSO4=',
                    Cacid
    &
                          ion str
                                       xKp′)
 Calculate dissociation of Bisulphate at each concentration.
        Do 150 i = 1, N
        ct = Cacid(i)
        if (ct . lt . 1.e-10) then
          c1 = ct
          c2 = ct
           c3 = ct
           go to 140
        endif
        cFe = 0.d0
        CALL DISSOC(ct, cFe, c1, c2, c3, ierr, LOUT)
        if (ierr . eq . 1) then
           Write (LOUT, 930) i
930
           Format (' DISSOC did not converge, data point \#', i5)
           stop
```

С

c c

с

С
endif

150	Continue
	c(3,i) = c3
	c(2,i) = c2
140	c(1,i) = c1

c c

Initialize summations.

С

= 0.0d0sum1 sum2 = 0.0d0sum3 = 0.0d0= 0.0d0sum11 sum 12= 0.0 d0= 0.0d0sum13 sum 22= 0.0d0sum 23= 0.0d0sum33 = 0.0d0= 0.0d0sumr sumr1 = 0.0d0sumr2 = 0.0d0= 0.0d0sumr3

200 Continue

A(2,3) = sum 12A(3,2) = sum 12A(3,3) = sum22A(1,4) = sum3A(4,1) = sum3A(2,4) = sum13A(4,2) = sum 13A(3,4) = sum23A(4,3) = sum23A(4,4) = sum 33B(1) = sumrB(2) = sumr1B(3) = sumr2B(4) = sumr3nm = 4 - mode**CALL** MATINV(nm, Determ) if (determ . eq . 0) write (LOUT, 940) 940 format (' determ = 0') = B(1)cons = B(2)alphH alphBI = B(3) alphSO4 = B(4)**if** (mode . eq . 1) alphSO4 = 0.d0then **if** (mode . eq . 2) alphSO4 = 0.d0alphBI = 0.d0endif if (iplot . eq . 1) open (unit=LPLOT, file=plotf, & defaultfile='[whitney.natcon].dat', status='new') С Write Tell-a-graph information .C с Write (LPLOT, 911) Format ('gen plot. 911 /'legend is "", frame legend,', & & /'legend box 1.5,3.0,0.5,3, units plot inches,' & /'legend off.') Write (LPLOT, 912) Format ('page border off.') 912

		Write (LPLOT, 913)
913		Format ('title is "Sulfuric Acid Density",',
	&	/, style is swiss light, ,
	&	/, shade pattern 2, ,
	&	/,' height 0.35.')
	•	Write (LPLOT, 914)
914		Format ('y room 2.')
		Write (LPLOT, 916)
916		Format ('y label is "Density (g/cm <e.8)3<ex))",',<="" th=""></e.8)3<ex)>
	&	/, style is swiss light, ,
	&	/, shade pattern 2, ,
	&	/, ' height 0.2. ')
		Write (LPLOT, 917)
917		Format ('x label is " $<$ 1.5) $<$ h1.2)[$<$ hx)H $<$ l1.1)2 $<$ l.5)SO $<$ l1.1)',
	&	(4 < 1.5) < h1.2) < hx) (M), ', '
	&	/,' style is swiss light,',
	&	/,, shade pattern 2, $,$
	&	/,' height 0.2.')
		Write (LPLOT,918)
918		Format ('y min is 0.98, max is 1.08, step 0.02.',
	&	/'x min is 0, max 1.2, step 0.2.')
		Write (LPLOT, 919)
919	•	Format ('x origin is 2.5.',/,'y origin is 3.5.',
	&	/, x length is 4.0. $/$, y length is 5.0. $)$
001		Write $(LPLOI, 921)$
921		FORMAL (X tick is 2. ,/, y tick is 2.) \mathbf{W}_{it} (I DLOT (000)
000		Format ('x tick marks made assumed '
922	87	/ w tick marks mode reversed.
	æ	/, y tick marks mode reversed.) Write (I PI OT 022)
093		Format ('aurve 1 southard ')
940		Write (LPLOT 024)
094		Format ($(urve 2 texture 1)$
521	&	/ curve 3 texture 9'
	عد مد	/; curve A texture 5'
	80 87	/; curve 5 texture 14 ()
	æ	W_{rite} (LPLOT 025)
925		Format ('every curve color is no thickness 2 symbol count 0.'
020	&	/ curve 1 symbol count 1 ')
	æ	Write (LPLOT 926) 3-mode
926		Format ('comment is "Fitting' i3 (coefficient(s)" ()
		Write (LPLOT, 927)
927		Format ('input data.')
		Write (LPLOT, 928)
928		Format ('"data"')
2		

```
Do 252 i = 1, N
             Write (LPLOT, *) Cacid(i), rho(i)
  252
          Continue
          Write (LPLOT, 942)
          Format (' "fit"')
  942
   Check accuracy of fit.
с
          Emax = 0.0
          sumE = 0.0
          Do 300 i = 1, N
             rhoc = cons + alphH*c(1,i) + alphBI*c(2,i) + alphSO4*c(3,i)
             Write (LPLOT, *) Cacid(i), rhoc
             E = rho(i) - rhoc
             sumE = sumE + abs(E)
             if (abs(E).ge.Emax)
                                then
               Emax = abs(E)
               Nmax = i
             endif
           Continue
  300
          sumE = sumE * 100.0 / dfloat(N)
          Emax = Emax * 100.0
          Write (LPLOT, 944)
          Format (' end of data.')
  944
С
   Print results
С
С
           Write (LOUT, 950) N
           Write (LOUT, 960) Cacid(1), Cacid(N)
           Write (LOUT, 970) cons, alphH, alphBI, alphSO4
           Write (LOUT, 980) sumE
           Write (LOUT, 990) Emax, Cacid(Nmax)
           Format (5x, 'Result of density fit for', I3, ' points')
   950
           Format (5x, from Cacid = ', f10.4, ' to Cacid = ', f10.4)
   960
   970
           Format (10x, ' const = ',e15.7, /10x, ' alpha H = ',e15.7,
             /10x, Alpha bi = ',f15.7, /10x, alpha SO4= = ',e15.7)
      &
   980
           Format (5x, 'Average percent deviation = ',f15.8)
   990
           Format (5x, 'Max percent deviation = ',f15.8,' at Cacid = ',f10.4)
```

с

с

Chapter 4 Programs

stop End

&

С

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С С

С С

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С c С

С С С С С

С

DISSOC SUBROUTINE DISSOC(a, b, CH, CHSO4, CSO4, ierr, LOUT)

This subroutine calculates solution composition based on the equilibrium dissociation of bisulfate ion.

Input parameters are

a

b

concentration of H2SO4, concentration of Fe2(SO4)3,

Output parameters are

CH	concentration	of H+
CHSO4	concentration	of HSO4-
CSO4	concentration	of SO4=

С

Program by Gina Whitney, September 4, 1986

implicit real*8 (a-h,o-z)

xK = 0.0104d0err = 1.d-15Kmax = 20ierr = 0

CFe = 2.d0*b

if (a . le . 0) **then** write (LOUT,910) a stop endif format (' a cannot be less than 0, a = ', e15.6)

910

&

alph = (-(3.d0*b + a + xK) + dsqrt((3.d0*b + a + xK)))xK)**2.d0 - 4.d0*a*(3.d0*b-xK))) / (2.d0*a)

CH = a * (1.d0 + alph)CSO4 = 3.d0*b + a*alphCHSO4 = a * (1.d0 - alph) Μ

M

Appendix H

Kount = 1100 str = 0.5d0 * (CH + 4.d0*CSO4 + CHSO4 + 9.d0*CFe)sstr = dsqrt(str)xKp = xK * dexp(5.29d0*sstr / (1.d0 + 0.56d0*sstr))CoH = CHCoSO4 = CSO4CoHSO4 = CHSO4alph = (-(3.d0*b + a + xKp) + dsqrt((3.d0*b + a + xKp)))& xKp) **2.d0 - 4.d0 *a *(3.d0 *b-xKp))) / (2.d0 *a) CH = a * (1.d0 + alph)CSO4 = 3.d0*b + a*alphCHSO4 = a * (1.d0 - alph) $sum = ((CH-CoH)/CH)^{*2.d0} + ((CSO4-CoSO4)/CSO4)^{*2.d0}$ & + ((CHSO4-CoHSO4)/CHSO4)**2.d0Kount = Kount + 1 if (sum.gt.err) then if (Kount . le . Kmax) go to 100 endif if (Kount . gt . Kmax) then ierr = 1write (LOUT, 930) Kmax endif 930 format (/, No convergence, Kmax = (,i5)write (LOUT,940) a, Kount, CH, CHSO4, CSO4, str, xKp 940 format (f7.4,2x,i5,5(2x,e11.5)) Return End MATINV Subroutine MATINV(N,DETERM) Implicit Double Precision (a-h,o-z)

c Matrix inversion routine by John Newman.

 $\mathbf{280}$

С

Chapter 4 Programs

С

c c

c c

c Used with permission.

```
Common / MAT / B(4,4), D(4)
       dimension ID(4)
      determ = 1.0
       Do 1 I = 1, N
1
         ID(I) = 0
       Do 18 NN = 1, N
         Rmin = 1.1
Find the row which has the smallest ratio of the
  2nd largest element in the row to the largest element.
       Do 6 I = 1, N
        If (ID(I), NE, 0)
                          Go to 6
         Bnext = 0.0
         Bmax = 0.0
         Do 5 J = 1, N
           If (ID(J). NE. 0) Go to 5
           If (DABS(B(I,J)). LE. Bnext) Go to 5
           Bnext = DABS(B(I,J))
           If (Bnext. LT. Bmax) Go to 5
           Bnext = Bmax
           Bmax = DABS(B(I,J))
           JC = J
 5
         Continue
       If (Bnext. GE. Rmin *Bmax)
                                 Go to 6
         Rmin = Bnext/Bmax
         Irow = I
         Jcol = JC
 6
       Continue
       If (ID(JC), EQ.0) Go to 8
       Determ = 0.0
       Return
 8
       ID(Jcol) = 1
       If (Jcol. EQ. Irow) Go to 12
```

1

```
Do 10 J = 1, N
        Save = B(Irow, J)
        B(Irow,J) = B(Jcol,J)
         B(Jcol, J) = Save
10
      Continue
      Save
              = D(Irow)
      D(Irow) = D(Jcol)
      D(Jcol) = Save
      F = 1.0 / B(Jcol,J) * F
12
      Do 13 J = 1, N
         B(Jcol,J) = B(Jcol,J) * F
13
      D(Jcol) = D(Jcol) * F
      Do 17 I = 1, N
         If (I. EQ.Jcol) Go to 17
         F = B(I, Jcol)
         Do 16 J = 1, N
           B(I,J) = B(I,J) - F * B(Jcol,J)
16
         D(I) = D(I) - F * D(Jcol)
17
       Continue
       Continue
18
      Return
```

FITRHO Data File

End

Fitting H2SO4 density data from 0.4 to 1 M 12 data points 1 don't fit alphSO4 1 make plot file 0.998203d0 1 0.045d0 1.0302d0 0.050d0 1.0336d0 0.055d0 1.0370d0 0.060d0 1.0404d0 0.065d0 1.0438d0 0.070d0 1.0472d0

0.075d0	1.0506d0
0.080d0	1.0541d0
0.085d0	1.0575d0
0.090d0	1.0610d0
0.095d0	1.0645d0
0.100d0	1.0680d0

FITRHO Output File

		Fitting	H2SO4	density	data	from	0.4 t	to 1	Μ			•
Cacid	Kou	nt cH		cHSO4	ŀ-	cSO	4		ion st	r	xKp	
0.4718	14	0.59848E+	00	0.34515E	C+00	0.1266	7E+00	0 0	0.72515	5E+00	0.21964E-	+00
0.5260	14	0.66771E+	00	0.38422E	C+00	0.1417	4E+00	0 0).80946	3E+00	0.24633E-	+00
0.5805	14	0.73768E+	00	0.42326E	E+00	0.1572	1E+00	0 0).89489	9E+00	0.27399E-	+00
0.6353	15	0.80837E+	00	0.46226E	E+00	0.1730	5E+00	0 0).98142	2E+00	0.30262E-	+00
0.6905	15	0.87977E+	00	0.50124E	C+00	0.1892	7E+00	0 0).10690)E+01	0.33220E-	+00
0.7460	15	0.95189E+	00	0.54021E	E+00	0.2058	4E+00	0 0).11577	7E+01	0.36271E-	+00
0.8019	15	0.10247E+	01	0.57916E	C+00	0.2227	7E+00	0 0	0.12475	5E+01	0.39414E-	+00
0.8582	15	0.10983E+	01	0.61818E	C+00	0.2400	7E+00	0 0	0.13384	(E+01	0.42652E-	+00
0.9148	15	0.11725E+	01	0.65715E	E+00	0.2576	8E+00	0 0).14302	2E+01	0.45975E-	+00
0.9718	15	0.12475E+	01	0.69620E	E+00	0.2756	4E+00	0 0	0.15231	LE+01	0.49391E-	+00
1.0292	15	0.13231E+	01	0.73529E	C+00	0.2939	3E+00	0 0).16171	LE+01	0.52893E-	+00
1.0870	15	0.13995E+	01	0.77442E	E +00	0.3125	3E+00	0 0).17120)E+01	0.56480E-	+00
	Resi	ilt of den	sity fit	for 12	points							
	from	n Cacid =	= ().4718	to Ca	acid =	=	1	.0870			
		const	= 0.	9988335	E+00							-
		alpha	H =	0.1698	817E-0	D1						
		Alpha	bi —		0.0561	220						
		alpha	SO4 =	_	0.0000	000E-	-00					
	Ave	rage perce	nt devia	tion =		0.00	16061	9				
	Max	nercent	deviation	_	0	00329	005 a	nt C	lacid		0 0148	
		Porootto	~~~~	~	0	00000	a		acia		0.0140	

Program NATFEM

PROGRAM NATFEM

c Program NATFEM solves the diffusion and migration c problem for concentration and potential profiles in a c stagnant diffusion layer, or at a growing mercury drop

•	or in unsteady stagnant diffusion or at a rotating
c c	diek
C C	This program uses the finite element technique to
c c	solve the counled equations. This version uses a banded
C C	solver in the IMSI math library and must be linked with
	link nation eve incle /lib
	(which is included in forlink com on this account)
0	(which is included in jointheo.com, on this account.)
0	My area in the reduction of $F_{0}(9)$ ion in $HOSO(/F_{0}O(SO))$
c	Wy case is the reduction of $re+5$ ton in $n2504/rez(504)5$
0	The variables in this computation and:
c	The variables in this computation are. O(h) where h refers to both encodes number (i) and
c	dimensionless position or similarity variable
c	i — 1 io H +
C	i = 1 is 117
c	2 18 504 = 0
6	J is Fe+2
c	4 is re+5, the reactant The share variables are made dimensionless with $C(F_{0} \mid 0 \mid hulk)$
c	The above variables are made atmensionless with $O(FE+5, 000K)$.
c	$i = 5$ is almensionless potential, $FHI = phi^+F/RI$.
c	The mean column for walking of the should work allow
C	The program solves for values of the above variables
c	as junctions of the similarity variable, (D, \mathcal{O})
C .	eta = x / sqrt(4Dij(R)i),
c	in this case.
C	The management of the fight shows that the shows
С	The program uses the finite element method to solve
с -	Ficks second law for one-aimensional migration and
с	aijjusion in a stagnant measum and the equation of
C	electroneutrality. Finally, it calculates the
с	$aimensionless \ current,$
c	$i / \{ nFDij(R)CB(R) / [1000+S(R)*sqrt(4Dij(R)*t)] \}$
c	and [rho-rho(bulk)] / rho(bulk), the density
с	difference and delta, the boundary layer thickness.
c	
c	The program requires one data file, NATFEM.dat in
c	directory [whitney.natcon]. It contains:
c	
с	Number
c	of
c	lines variable
c	
c	1 Mode = 1 for Nernst stagnant diffusion
c	= 2 for growing Hg drop or
c	unsteady stagnant diffusion

= 3 for rotating disk с Neq = Number of unknowns (5 for this case) 1 С 1 CR0 = Concentration of reactant at electrode C 1 **IPLOTC** = 0 don't print concentration profile с 1 print dimensionless conc profile С **IPLOTR** = 0 don't print density profile 1 с 1 print density profile С 1 * blank* С С Name(I), Dif(I), zv(I), s(I), CB(I), alphap(I)Nvar-1 С С Mesh info: с С 1 = 1 for linear ntype С = 2 for quadratic С = 3 for Hermite cubics. С 1 the number of mesh regions (<=9)С nreg nel(i) # of elements in region i С nreg xmesh(i) region boundaries nreg+1С С i/o info: С С 1 resfile name of restart file с С 1 iopt indicator to print restart calculations 1 outres name of new restart file С С с Newton-Raphson info: с С 1 С err convergence tolerence 1 Kmax max number of Newton-Raphson iterations С 1 iNR print Newton-Raphson iterations С С Calculation info: С С 1 Ntime = Number of points at which to calculate С current, boundary layer thickness С and Rayleigh number С = time interval for above calculation 1 htime С ¢ С с С Program by Gina Whitney, May 5, 1986. С


```
implicit real*8 (a-h, o-z)
       character *20
                          resfile, outres
       character *6
                           Name(5)
       real*8
                           xlm(2)
       integer
                           R
       common / mesh
                           / ntype, nreg, xmesh(6), nel(5)
       common / nodes
                           / ne, nnodes, x(1001)
                           / c(5005)
       common / soln
       common / meshpar
                                     / ku, nnpe, nvpn, nfac
                            / \text{nveq}(10), \text{ nBC}(10), \text{ iBC}(10), \text{ valBC}(10),
       common / bc
    &
                              neqv
       common / param / neq, Dif(5), zv(5), s(5), CB(5), alphap(5)
       common / param2 / const, mode, nm1, nm2, R
       common / tfun
                           / phi(3,4), dphidz(3,4)
                            / w(3), z(3)
       common / gauss
Set values for Gauss points and weights (3 point adjusted for 0 to 1)
       z(1) = 0.5d0
       z(2) = (0.774596669241483 + 1.d0) / 2.d0
       z(3) = (-0.774596669241483 + 1.d0) / 2.d0
       w(1) = 4.d0 / 9.d0
       w(2) = 5.d0 / (9.d0 * 2.d0)
       \mathbf{w}(3) = \mathbf{w}(2)
       LIN = 3
       LOUT = 4
       LPLOTC = 7
       LPLOTR = 9
                = 10
       LRES
       LOUTRES = 11
       F
              = 96486.7d0
       FoRT = F / (8.314 * 298.15)
       open (unit=LIN, file='NATFEM',
   &
             defaultfile='[WHITNEY.NATCON].dat', status='old')
       Read (LIN, *) MODE
        Read (LIN,
                    *) Neq
                    *) CR0
       Read (LIN,
        Read (LIN, *) IPLOTC
       Read (LIN, *) IPLOTR
```

286

С

С

```
Nvar = Neq
        nm2 = Nvar-2
        nm1 = Nvar-1
        R
             = nm1
        Read (LIN, 999)
999
        Format ()
        Read (LIN, *) (Name(I),Dif(I), zv(I), s(I), CB(I), alphap(I),
                           I = 1, nm1
   &
        Read (LIN, *) ntype
        Read (LIN, *) nreg
        Do 110 j = 1, nreg
          Read (LIN, *) nel(j)
110
        Continue
        Do 120 j = 1, nreg+1
          Read (LIN, *) xmesh(j)
120
        Continue
        Read (LIN, *) resfile
        Read (LIN, *) iopt
        Read (LIN, *) outres
        Read (LIN, *) err
        Read (LIN,*) Kmax
        Read (LIN, *) iNR
        Read (LIN, *) Ntime
        Read (LIN, *) htime
        Name(Nvar) = ' Phi
        CB(Nvar) = 0.d0
        open (unit=LOUT, file='NATFEM',
           defaultfile='[WHITNEY.NATCON].out', status='new')
     &
        open (unit=LRES, file=resfile,
    &
           defaultfile='[WHITNEY.NATCON].dat', status='old')
 Calculate boundary conditions from input information.
```

neqv = 2*Nvar - 2

С

c

с

c Program bulk concentrations at infinity.

Do 130 i = 1, Nvar nveq(i) = i nBC(i) = 1 iBC(i) = 1 valBC(i) = CB(i)/CB(R)Continue

с

130

c Program concentration of reactant at electrode.

nveq(Nvar+1) = R nBC(Nvar+1) = 0 iBC(Nvar+1) = 1valBC(Nvar+1) = CR0/CB(R)

С

c Program flux of non-reacting ions.

Do 140 i = Nvar+2, 2*Nvar-2 nveq(i) = i - (Nvar+1) nBC(i) = 0 iBC(i) = 2 valBC(i) = 0.d0**Continue**

c

С

140

Define differences in problem types.

```
if (MODE . eq . 1) then
           Write (LOUT, 900)
           Const = 0.d0
           if (\text{xmesh}(\text{nreg}+1) \cdot \text{gt} \cdot 1.\text{d}0)
                                            Then
              Do 150 i = 1, nreg+1
                xmesh(i) = xmesh(i)/xmesh(nreg+1)
150
              Continue
           endif
         elseif (MODE . eq . 2)
                                  then
           Write (LOUT, 901)
           Const = 2.d0
         elseif (MODE . eq . 3)
                                  then
           Write (LOUT, 902)
           Const = 3.d0
         else
           Write (LOUT, 903) MODE
           Stop
         endif
900
         Format (' Nernst diffusion layer')
```

```
Format (' Planar diffusion or growing mercury drop')
  901
          Format (' Rotating disk')
  902
          Format (' Invalid mode, mode = ', i3)
  903
С
cc Calculate transference number of reacting ion.
          sum = 0.d0
          Do 160 i = 1, nm1
            sum = sum + zv(i) * zv(i) * CB(i) * Dif(i)
  160
          Continue
          tran = zv(R) * zv(R) * CB(R) * Dif(R) / sum
          Write (LOUT, 905) tran
          Format (/, Transference number of reacting ion = (,f15.9)
  905
С
cc Write input information.
          Write (LOUT, 906)
  906
          Format (/' Name
                                         Diff
                                                          Cbulk '
      &
                              alpha')
          Write (LOUT, *) (Name(I),Dif(I), CB(I), alphap(I),
      &
                             I = 1, Neq)
          Write (LOUT, 907) ntype
  907
          Format (/' Type of basis functions : ', i3)
          Write (LOUT, 908) nreg
  908
          Format (3x, i3, ' region(s)')
          Write (LOUT, 909)
          Format ('
  909
                           Node structure')
          Do 170 j = 1, nreg
            Write (LOUT, *) nel(j)
  170
          Continue
          Do 180 j = 1, nreg+1
             Write (LOUT, *) xmesh(j)
          Continue
  180
          Write (LOUT, 910)
                            Boundary condition info',
  910
          Format (/, '
      &
              1,'
                                                     iBC
                               nveq
                                           nBC
                                                              valBC')
          Do 190 j = 1, neqv
             Write (LOUT, *) nveq(j), nBC(j), iBC(j), valBC(j)
  190
          Continue
          Write (LOUT, 912) err
  912
          Format (/' Err = ',e15.8)
```

 Write (LOUT, 914) Kmax

 914
 Format (' Kmax = ', i4)

С

c Define differences in mesh types.

```
if (ntype . eq . 1) Then
            ku = 2
            nnpe = 1
            nvpn = 1
          elseif (ntype . eq . 2) Then
            ku = 3
            nnpe = 2
            nvpn = 1
          elseif (ntype . eq . 3)
                               Then
            ku = 4
            nnpe = 1
            nvpn = 2
          else
            Write (LOUT, 916) ntype
            Format (' Bad value for ntype, ',i5)
916
            Stop
          endif
          nfac == neq * nnpe * nvpn
```

c c Generate

Generate mesh points.

Call GENMESH(LOUT) nvart = neq * nvpn * (1 + nnpe*ne)

c Calculate initial guesses from restart file info.

Call RESTART (LRES, iopt, LOUT, neq)

c Calculate local phi's and dphidz's.

Call TFUNCT (ntype)

С

С

С

Call finite element routine. С

Call FINEL(nvart, err, Kmax, iNR, Kountnr, iconv, LOUT)

Write (LOUT, 917) Kountnr **Format** (/, 'Newton-Raphson Iterations: ', i5) 917

If (iconv. eq. 0) Then

918

&

Write (LOUT, 918) Kountnr, err, Kmax Format (/,' Newton-Raphson did not converge.', 1,1 Kountnr = ',i5,' err = ',e15.9,' Kmax = 1.15Stop Endif

amp = (c(neq *nvpn+R)-c(R)) / (x(2)-x(1))

с cc Convergence!

С

С

С c

С

Write to output restart file. С

open (unit=LOUTRES, file=outres, defaultfile='[WHITNEY.NATCON].dat', status='new') & Write (LOUTRES, *) nnodes **Do** 200 j = 1, nnodes Write (LOUTRES,919) x(j), (c(neq *nvpn *(j-1)+i), i=1, neq) 200 Continue 919 **Format** (2x, f7.4, 5(x, e11.4))Write dimensionless concentration profile. Ibeenhere = 0Ibeenhere95 = 0Open plot files. С If (IPLOTC . eq . 1) open (unit=LPLOTC, file='plotconf', & defaultfile='[WHITNEY.NATCON].dat', status='new') If (IPLOTR . eq . 1) open (unit=LPLOTR, file='plotrhof', & defaultfile='[WHITNEY.NATCON].dat', status='new')

c c

Write Tell-a-graph information.

		If (IPLOTR . eq . 1) Then
		Write (LPLOTR, 921)
921		Format (' page border off.')
000		Write (LPLOIR, 922) Format (1 title is "Density Brofile Following e"1)
922		Format (title is Density Frome Following a)
092		Format (' "Potential Stan into Limiting Current" '
920	8.	/ height 0.35 '
	æ &r	/, style is swiss light shade nattern 2 $'$)
	60	Write (LPLOTR 925)
925		Format (' v label is "Density $(g/cm < e.8)3 < ex)$)".
•=•	&	/.' height 0.2.'.
	&	/,' style is swiss light, shade pattern 2.')
		Write (LPLOTR, 927)
927		Format (' x label is "Dimensionless Distance, $< m7$)c", ',
	&	/,' height 0.2,',
	&	/,' style is swiss light, shade pattern 2.')
		Write (LPLOTR, 929)
929		Format (' x origin is 2.3.')
000		Write $(LPLOTR, 930)^{+}$
930		FORMAL (Y LICK IS 2.) Write (IPLOTE 931)
931		Format (' x tick is 2' /' frame axis' /' frame legend ')
001		Write (LPLOTR. 932)
932		Format (' curve 1 texture 1.',
	&	/, curve 2 texture 2.)
		Write (LPLOTR, 936)
936		Format (' every curve, color is no, thickness 2,'
	&	/, ' symbol count is 0.')
		Write (LPLOTR, 939)
939		Format (' comment is "Linear profile based on equiv force". ()
		Write (LPLOTR, 941)
941		Format (' input data.')
		Write (LPLOTR, 942)
942		Format (' "Calc"')
		Endif
		If (IPLOTC . eq . 1) Then
		Write (LPLOTC, 921)
		Write (LPLOTC, 924)
924		Format ('title is "Concentration Profile Following a"')
		Write (LPLOTC, 923)
		Write (LPLOTC, 926)

С

С

```
Format (' y label is "Concentration x 10 < e.8)3 < ex)',
926
                    ( \text{gmol}/\text{cm} < \text{e.8})3 < \text{ex} ) )"',
   &
                1,'
   &
                           height 0.2,',
                           style is swiss light, shade pattern 2.')
                /,
   &
           Write (LPLOTC, 927)
           Write (LPLOTC, 928)
           Format (' y min is 0.')
928
           Write (LPLOTC, 929)
           Write (LPLOTC, 930)
           Write (LPLOTC, 931)
           Write (LPLOTC, 932)
           Write (LPLOTC, 936)
           Write (LPLOTC, 940)
           Format (' comment is "Linear profile based on equiv area". ')
940
          Write (LPLOTC, 941)
          Write (LPLOTC, 942)
        Endif
 Initialize variables for integral calculation.
        rhoinf = 1.0465d0
        sume = 0.d0
        sumf = 0.d0
        sumc = 0.d0
        summ = 0.0d0
        etal = x(nnodes)
        etam = etal
        c1 = c(nfac *ne+R)
        ifirst = 0
        rho1 = rhoinf
        rhom = rhoinf
        If (IPLOTC.eq.1) Write (LPLOTC,947) etal,c(nfac *ne+R)*CB(R)
        If (IPLOTR.eq.1) Write (LPLOTR,947) etal, rho1
         Do 410 j = nnodes-1, 1, -1
           eta = x(j)
           If (IPLOTC . eq . 1)
    &
           Write (LPLOTC, 947) eta, c(neq *nvpn *(j-1)+R) * CB(R)
           drho = 0.d0
           Do 405 i = 1, nm1
              drho = drho + alphap(i) * (c(neq *nvpn *(j-1)+i) -
    &
              c(nfac *ne+i)) * CB(R)
405
           Continue
           rho = rhoinf * (1.d0 + drho)
```

```
С
   Looking for rhomax.
С
             If (rho . ge . rhom) Then
               If irst = 1
               rhom = rho
               etam = eta
               jm = j
             Endif
С
   Integral calculation.
с
          eta2 = eta
          rho2 = rho
               = (rho2 - rhoinf) * eta2
          v2
               = (rhol - rhoinf) * etal
          v1
          sume = sume + (v1 + v2)/2.d0 * (x(j+1)-x(j))
          sumf = sumf + ((rho1 + rho2)/2.d0 - rhoinf) * (x(j+1)-x(j))
          sumc = sumc + ((c(neq*nvpn*(j)+R) + c(neq*nvpn*(j-1)+R))/2.d0)
                    - c(nfac*ne+R)) * (x(j+1)-x(j))
      &
          if (rho. lt. rhom. and . if irst. gt. 0) Then
            summ = summ + ((rho1 + rho2)/2.d0 - rhom) * (x(j+1)-x(j))
          endif
          eta1 = eta2
          rho1 = rho2
С
   Plotting.
С
          If (IPLOTR . eq . 1) Write (LPLOTR, 947) eta, rho
          if (c(neq*nvpn*(j-1)+R) . lt . 0.9)
                                               Then
            if (Ibeenhere . eq . 0) Then
               c1 = c(neq *nvpn *(j-1)+R)
               e1 = eta
               Ibeenhere = 1
            endif
          endif
          if (c(neq*nvpn*(j-1)+R) . lt . 0.95)
                                                Then
            if (Ibeenhere95 . eq . 0) Then
               c195 = c(neq *nvpn *(j-1)+R)
               e195 = eta
               Ibeenhere95 = 1
             endif
          endif
```

if (Ibeenhere . eq . 0) Then c2 = c(neq *nvpn *(j-1)+R)e2 = etaendif if (Ibeenhere95 . eq . 0) Then c295 = c(neq *nvpn *(j-1)+R)e295 = etaendif 410 Continue 947 **Format** (2(2x,e15.9)) Then if (Ibeenhere . eq . 0) Write (LOUT, 950) 950 **Format** (' No crossing of conc = 0.9, check profile stuff') Go to 420 endif if (Ibeenhere95 . eq . 0) Then Write (LOUT, 952) 952 Format (' No crossing of conc = 0.95, check profile stuff') Go to 420 endif eta9 = e1 + (0.9 - c1) * (e2 - e1) / (c2 - c1)deltrat = eta9 * ampWrite (LOUT, 955) eta9, deltrat 955 Format (/, ' eta at (c = 0.9 *Cb) = ',f15.9,/ ratio of delta.9 to deltcur = (, f15.9, /)& eta95 = e195 + (0.95 - c195) * (e295 - e195) / (c295 - c195)deltrat = eta95 * ampWrite (LOUT, 958) eta95, deltrat 958 Format (/, ' eta at (c = 0.95 * Cb) = ',f15.9,/ & ratio of delta.95 to deltcur = (, f15.9, /)Write (LOUT, 960) 420 960 Format (Species · CBulk CZero Amp') potinf = c(nfac *ne+Nvar)/FoRTpotelec = c(Nvar)/FoRTWrite (LOUT, 962) amp, (Name(i), c(nfac*ne+i)*CB(R), & c(i) *CB(R), I=1,nm1Write (LOUT, 963) Name(NVar), potinf, potelec 962 **Format** (45x,e15.9, /(5x,A6,3x,e12.6,3x,e12.6))

963

Format (5x,A6,3x,e12.6,3x,e12.6)

drhoelec = 0.d0**Do** 500 i = 1, nm1drhoelec = drhoelec + alphap(i) * (c(i) - c(nfac*ne+i))* CB(R)& 500 Continue rhoelec = rhoinf * (1.d0 + drhoelec)xint = sume * 6.d0 / (rhoelec - rhoinf)If (xint . lt . 0) Then Write (LOUT, 966) 966 Format (' Cannot calculate etaint. Check solution') Else etaint = dsqrt(xint)Write (LOUT, 965) etaint 965 **Format** (/, ' Equivalent bouyant energy eta = ',e15.8) Endif etaintf = sumf * 2.d0 / (rhoelec - rhoinf)Write (LOUT, 968) etaintf 968 Format (/, 'Equivalent force eta = ',e15.8) etaintm = summ * 2.d0 / (rhoelec - rhom)Write (LOUT, 969) etaintm 969 **Format** (/, 'Equivalent eta based on max density = ',e15.8). etaintlm = summ * 2.d0 / (rhoelec - rhoinf)Write (LOUT, 971) etaintlm 971 Format (/,' Equivalent eta l sub m = (.e15.8)etaintc = - sumc * 2.d0 / (C(nfac*ne+R) - C(R))Write (LOUT, 970) etaintc 970 Format (/, ' Equivalent conc eta = (.e15.8) rhomd = rhom / rhoinfWrite (LOUT, 972) rhom, rhomd, etam 972 Format (/, ' Max density = ',e15.8, over rhoinf = ',e15.8, & & at eta = ',e15.8) Rast = 980.d0 * (rhoelec-rhoinf)/(rhoinf * 0.01d0 * Dif(R))Rastm = 980.d0 * (rhoelec-rhom)/(rhom *0.01d0 *Dif(R))

Write (LOUT,975) rhoinf, rhoelec, Rast, Rastm

```
Format (/,15x, 'rhoinf = ',f15.9, /,15x, 'rhoelec = ',f15.9,
975
               /.15x, 'Rast = '.e15.9, /.15x, 'Rastm = '.e15.9
   &
        Write (LOUT, 980)
        Format (/,x, 'Time',5x, 'Current',7x, 'delta',9x, 'Ra',9x, 'Ra max',
980
               8x, 'Ra c')
   &
        Do 550, i = 1, Ntime
           time = htime * dfloat(i)
           cur = F *Dif(R) *CB(R) *amp / (s(R) *dsqrt(4.d0 *Dif(R) *time))
           delta = dsqrt(4.d0*Dif(R)*time)
           Ra = Rast * delta ** 3.d0
           deltam = etam * dsqrt(4.d0*Dif(R)*time)
           Ram = Rastm * deltam ** 3.d0
           deltac = etaintc * dsqrt(4.d0*Dif(R)*time)
           Rac = Rast * deltac ** 3.d0
           Write (LOUT, 982) time, cur, delta, Ra, Ram, Rac
           Format (f5.1,5(2x,e11.5))
982
550
        Continue
        If (IPLOTR . eq . 1) Then
           Write (LPLOTR, 983)
           xx = 0.d0
           Write (LPLOTR, 947) xx, rhoelec
           Write (LPLOTR, 947) etaintlm, rhoinf
           xx = xmesh(nreg+1)
           Write (LPLOTR, 947) xx, rhoinf
           Write (LPLOTR, 984)
        Endif
983
        Format (' "linear eq"')
        Format (' end of data.')
984
        If (IPLOTC . eq . 1) Then
           Write (LPLOTC, 983)
           xx = 0.d0
           Write (LPLOTC, 947) xx, c(R) * CB(R)
           Write (LPLOTC, 947) etaintc, c(nfac *ne+R) * CB(R)
           xx = xmesh(nreg+1)
           Write (LPLOTC, 947) xx, c(nfac *ne+R) * CB(R)
           Write (LPLOTC, 984)
        Endif
        Stop
        End
```

GENMESH Subroutine GENMESH(LOUT) implicit real*8 (a-h, o-z)/ ntype, nreg, xmesh(6), nel(5)common / mesh common / nodes / ne, nnodes, x(1001)common / meshpar / ku, nnpe, nvpn, nfac ne = 0x(1) = xmesh(1)k = 1**Do** 200 i = 1, nreg ne = ne + nel(i)**Do** 150 ii = 1, nel(i)dx = (xmesh(i+1) - xmesh(i)) / dfloat(nel(i)*nnpe)**Do** 100 j = 1, nnpe $\mathbf{k} = \mathbf{k} + \mathbf{1}$ $\mathbf{x}(\mathbf{k}) = \mathbf{x}(\mathbf{k}-1) + \mathbf{d}\mathbf{x}$ 100 Continue Continue 150 200 Continue nshouldbe = ne*nnpe + 1nnodes = kIf (nnodes . ne . nshouldbe) Then Write (LOUT, 920) nnodes, nshouldbe 920 **Format** (/, ' Genmesh did not work, nnodes = ', i5, ś should be',i5) & Stop Endif Return End RESTART Subroutine RESTART(LRES, iopt, LOUT, neqr) implicit real *8 (a-h, o-z)**common** / mesh / ntype, nreg, xmesh(6), nel(5)**common** / nodes / ne, nnodes, x(1001)

```
common / soln / c(5005)
        common / meshpar / ku, nnpe, nvpn, nfac
        real*8
                  c1(5), c2(5)
        Read (LRES, *) nnodeso
        Read (LRES, *) x1, (c1(i), i = 1, neqr)
        Read (LRES, *) x2, (c2(i), i = 1, neqr)
        k = 2
        slop = 1.d-6
        Do 100 j = 1, nnodes
50
          If (x(j) \cdot le \cdot x2 + slop)
                                   Then
             Do 75 i = 1, neqr
                c(neqr *nvpn *(j-1)+i) = c1(i) + i
   &
                            (x(j)-x1) * (c2(i)-c1(i)) / (x2-x1)
 75
             Continue
             If (ntype . eq . 3) Then
                Do 80 i = 1, neqr
                  c(neqr *nvpn *(j-1)+neqr+i) = 0.d0
 80
             Continue
           Endif
           Go to 100
           Else
             x1 = x2
             Do 90 i = 1, neqr
                c1(i) = c2(i)
 90
             Continue
             \mathbf{k} = \mathbf{k} + \mathbf{1}
             If (k . gt . nnodeso)
                                    Then
                Write (LOUT, 900) k, nnodes, nnodeso
900
               Format (/, ' Restart did not work
                        k = ',i5,' nnodes = ',i5,' old nnodes = ',i5)
   &
                  1,1
                Stop
             Else
                Read (LRES, *) x2, (c2(i), i = 1, neqr)
                If (neqr. eq. 2) Read (LRES, *) x2, c2, T2
                Go to 50
             Endif
           Endif
100
        Continue
        If (iopt . eq . 1) Then
           Write (LOUT, 910)
910
           Format (/, '
                         Restart information ')
           Do 200 j = 1, nnodes
```

Appendix H

Write (LOUT,919) j, x(j), (c(neqr *nvpn *(j-1)+i), i=1, neqr) & **If** (ntype . eq . 3) Then Write (LOUT,919) $j_x(j)$, (c(neqr *nvpn *(j-1)+neqr+i), & i=1,neqrEndif 200 Continue Endif 919 **Format** (2x,i3,2x,f7.4,5(x,e11.4))Return End Subroutine FINEL(nvarf, errf, Kmaxf, iNRf, Kountnrf, FINEL & iconvf, LOUT) implicit real*8 (a-h, o-z)real*8 sk(5005,19), sf(5005), xl(2), con(4), dcdx(4)real*8 xwrk(50050) integer R, isld(5005)common / mesh / ntype, nreg, xmesh(6), nel(5)**common** / nodes / ne, nnodes, x(1001) / c(5005) **common** / soln common / meshpar / ku, nnpe, nvpn, nfac common / bc / nveq(10), nBC(10), iBC(10), valBC(10), neqv **common** / param / neq, Dif(5), zv(5), s(5), CB(5), alphap(5) common / param2 / const, mode, nm1, nm2, R / phi(3,4), dphidz(3,4)**common** / tfun common / gauss / w(3), z(3)С Calculate bandwidth and set up isld. С nbw = neq *4 -1nc = (nbw-1)/2. j = -nc**Do** 50 n = 1, nvarf isld(n) = jj = j + 150 Continue

с Initialize Newton-Raphson variables. С Kountnrf = 0If (iNRf . eq . 1) Write (LOUT, 910) Format (/, Newton-Raphson Convergence', 910 Norm. of Res.', /) & /, KountNR С Top of loop for Newton-Raphson. С 100 Kountnrf = Kountnrf + 1С Zero matrices. С **Do** 150 i = 1, nvarf sf(i) = 0.d0**Do** 150 j = 1, nbw sk(i,j) = 0.d0150 Continue С Begin element by element construction. С **Do** 300 i = 1, ne xl(1) = x(nnpe*(i-1)+1) $xl(2) = x(nnpe^{*}(i) + 1)$ dx = xl(2) - xl(1)eta0 = xl(1)**Do** 300 j = 1, 3 eta = eta0 + z(j) * dxZero local solution. c*c* **Do** 175 ii = 1, nm1 con(ii) = 0.d0dcdx(ii) = 0.d0175 Continue pot = 0.d0dpotdx = 0.d0С Calculate local solution. с **Do** 200 k = 1, kuindex = nfac * (i-1) + neq * (k-1)**Do** 190 ii = 1, nm1

```
con(ii) = con(ii) + phi(j,k) * c(index+ii)

dcdx(ii) = dcdx(ii) + dphidz(j,k) * c(index+ii) / dx

190

Continue

pot = pot + phi(j,k) * c(index+neq)

dpotdx = dpotdx + dphidz(j,k) * c(index+neq) / dx

200

Continue
```

С

c Loop over local rows.

	Do $300 l = 1, \ ku$
	l1 = nfac * (i-1) + neq * (l-1)
	Do 230 ii = 1, nm1
	sf(l1+ii) = sf(l1+ii) - w(j) * dx *
&	(-Dif(ii) / Dif(R) * dcdx(ii) *dphidz(j,l)/dx
&	+ const * eta **dfloat(Mode-1) * $dcdx(ii)$ * phi(j,l)
&	-zv(ii) * Dif(ii) / Dif(R) * con(ii) * dpotdx
&	\neq dphidz(j,l) / dx)
	sf(l1+neq) = sf(l1+neq) - w(j) * dx *
&	zv(ii)*con(ii) * phi(j,l)
,	Continue

c c

- 230

Loop over local columns. Shifted column = full column - isld(row).

Do 300 m = 1, ku m1 = nfac * (i-1) + neq * (m-1)**Do** 250 ii = 1, nm1 sk(l1+ii,m1+ii-isld(l1+ii)) = sk(l1+ii,m1+ii-isld(l1+ii))& + w(j) * dx *& (-Dif(i)/Dif(R) * dphidz(j,m) * dphidz(j,l)/(dx*dx))+ const *eta **dfloat(Mode-1) * dphidz(j,m) * phi(j,l)/dx & - zv(ii) * Dif(ii) / Dif(R) * phi(j,m) * dpotdx& & * dphidz(j,l) / dx) sk(l1+ii,m1+neq-isld(l1+ii)) = sk(l1+ii,m1+neq-isld(l1+ii))& + w(j) * dx *(-zv(ii) * Dif(ii) / Dif(R) * con(ii) * dphidz(j,m))& * dphidz(j,l) / (dx * dx)) **&** sk(l1+neq,m1+ii-isld(l1+neq)) = sk(l1+neq,m1+ii-isld(l1+neq))+ w(j) * dx * zv(ii) * phi(j,m) * phi(j,l)& 250 Continue 300 Continue

Chapter 4 Programs

С

С

c Adjust equations for boundary conditions.

Do 400
$$j = 1$$
, neqv

c Calculate equation number as if BC were an essential BC.

nneq = nBC(j) * nfac * ne + nveq(j)

c First program essential condition or natural for Hermite.

if (iBC(j) . eq . 1 . or . ntype . eq . 3) Then

c Adjust equation number if doing derivative condition c with Hermite.

if (iBC(j) . eq . 2) nneq = nneq + neq sf(nneq) = -c(nneq) + valBC(j) Do 350 i = 1, nbw sk(nneq,i) = 0.d0 Continue sk(nneq,nneq-isld(nneq)) = 1.d0

c Now natural condition.

c c 350

Now flux-matching condition for product.

 $\begin{array}{rcl} sf(nm2) &=& sf(nm2) \,+\, s(nm2)/s(R) \\ \& & & & * \, (c(neq *nvpn+R)-c(R))/(x(2)-x(1)) \\ & & sk(nm2,neq *nvpn+R-isld(nm2)) &=& sk(nm2,neq *nvpn+R-isld(nm2)) \\ \& & & - \, s(nm2)/s(R) \,/(x(2)-x(1)) \\ & & sk(nm2,R-isld(nm2)) &=& sk(nm2,R-isld(nm2)) \\ \& & & + \, s(nm2)/s(R) \,/(x(2)-x(1)) \end{array}$

```
С
   Solve for delta node values using library banded solver.
С
          Call LEQT1B (sk, nvarf, nc, nc, 5005, sf, 1, 5005, 0,
     &
                           xwrk, ier)
         if (ier . eq . 129) Write (LOUT, 930) Kountnrf
  930
         Format (
                    error in LEQT1B, Kounthr = (, i5)
С
   Check convergence and make corrections to c(i).
с
         sum = 0.d0
          Do 480 i = 1, nvarf
            sum = sum + sf(i) * sf(i)
            c(i) = c(i) + sf(i)
  480
          Continue
          sum = dsqrt(sum / dfloat(nvarf))
          If (iNRf . eq . 1) Write (LOUT, 940) Kountnrf, sum
  940
          Format (2x,i5,3x,e15.9)
          if (sum . le . errf)
                            Then
            iconvf = 1
   Convergence!
С
            Return
          endif
          if (Kountnrf . lt . Kmaxf) Go to 100
С
   (Damn).
С
          iconvf = 0
          Return
          End
TFUNCT
          Subroutine TFUNCT(nt)
          implicit real*8 (a-h, o-z)
          common / tfun
                             / phi(3,4), dphidz(3,4)
          common / gauss
                             / w(3), z(3)
```

100

200

```
If (nt . eq . 1)
                    Then
  Do 100 j = 1, 3
     phi(j,1) = 1.d0 - z(j)
     phi(j,2) = z(j)
     dphidz(j,1) = -1.d0
     dphidz(j,2) = 1.d0
   Continue
Elseif (nt . eq . 2)
                       Then
   Do 200 j = 1, 3
      phi(j,1) = 1.d0 - 3.d0 * z(j) + 2.d0 * z(j) * z(j)
      phi(j,2) = 4.d0 * z(j) * (1.d0 - z(j))
      phi(j,3) = z(j) * (-1.d0 + 2.d0*z(j))
     dphidz(j,1) = -3.d0 + 4.d0*z(j)
      dphidz(j,2) = 4.d0 - 8.d0 * z(j)
      dphidz(j,3) = -1.d0 + 4.d0*z(j)
   Continue
Elseif (nt . eq . 3)
                       Then
   Do 300 j = 1, 3
      phi(j,1) = 1.d0 - 3.d0 * z(j) * z(j) + 2.d0 * z(j) * 3.d0
     phi(j,2) = z(j) - 2.d0 * z(j) * z(j) + 1.d0 * z(j) * 3.d0
      phi(j,3) = 3.d0 * z(j) * z(j) - 2.d0 * z(j) * 3.d0
     phi(j,4) = -1.d0 * z(j) * z(j) + 1.d0 * z(j) * 3.d0
     dphidz(j,1) = - 6.d0 * z(j) + 6.d0 * z(j) * z(j)
     dphidz(j,2) = 1.d0 - 4.d0 * z(j) + 3.d0 * z(j) * z(j)
     dphidz(j,3) = 6.d0 * z(j) - 6.d0 * z(j) * z(j)
      dphidz(j,4) = -2.d0 * z(j) + 3.d0 * z(j) * z(j)
   Continue
```

300

Endif

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