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Key Points:

- Identified five key sensitive parameters for methane emissions using the Sobol sensitivity analysis method
- Parameters linked to production and diffusion present the highest sensitivities despite apparent seasonal variation
- Fourteen out of nineteen model parameters exert negligible influence on methane emissions

Supporting Information:

Supporting Information may be found in the online version of this article.

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Machine Learning Driven Sensitivity Analysis of E3SM Land Model Parameters for Wetland Methane Emissions

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Abstract Methane (CH₄) is globally the second most critical greenhouse gas after carbon dioxide, contributing to 16%–25% of the observed atmospheric warming. Wetlands are the primary natural source of methane emissions globally. However, wetland methane emission estimates from biogeochemistry models contain considerable uncertainty. One of the main sources of this uncertainty arises from the numerous uncertain model parameters within various physical, biological, and chemical processes that influence methane production, oxidation, and transport. Sensitivity Analysis (SA) can help identify critical parameters for methane emission and achieve reduced biases and uncertainties in future projections. This study performs SA for 19 selected parameters responsible for critical biogeochemical processes in the methane module of the Energy Exascale Earth System Model (E3SM) land model (ELM). The impact of these parameters on various CH4 fluxes is examined at 14 FLUXNET- $CH₄$ sites with diverse vegetation types. Given the extensive number of model simulations needed for global variance-based SA, we employ a machine learning (ML) algorithm to emulate the complex behavior of ELM methane biogeochemistry. We found that parameters linked to $CH₄$ production and diffusion generally present the highest sensitivities despite apparent seasonal variation. Comparing simulated emissions from perturbed parameter sets against FLUXNET-CH₄ observations revealed that better performances can be achieved at each site compared to the default parameter values. This presents a scope for further improving simulated emissions using parameter calibration with advanced optimization techniques.

Plain Language Summary Methane is a critical greenhouse gas, and wetlands are the largest natural source of it. Accurately predicting methane emissions from wetlands is key to tackling climate change. But these predictions, made through computer models, are seldom spot-on. Why? Because there are many factors in the models that lead to uncertain predictions. A major source of this uncertainty arises from the empirical model parameters. Just as tuning a radio dial ensures clear reception, models need properly adjusted parameters for accurate predictions. A sensitivity analysis was performed to determine which parameters are most crucial for accurate predictions. Instead of running the complex numerical model every time, machine learning was employed to create a faster and simpler version. Using this approach, five parameters were pinpointed as particularly sensitive, significantly impacting the predictions. The comparison of model‐predicted methane emissions with real‐world measurements showed that the model performed well in some cases but needed tweaking in others. Refining these sensitive parameters with more real‐world observations could make better predictions in the future.

1. Introduction

Methane (CH₄) is the second most influential greenhouse gas after $CO₂$ and responsible for approximately 20% of the warming potential as a result of anthropogenic activities since the start of the Industrial Revolution (Etminan et al., [2016\)](#page-19-0). However, CH₄ is more powerful at trapping radiation. The warming potential of CH₄ is estimated to be 28 times higher than that of CO₂ over a 100-year period and is even more potent over a 20-year period, at 84 times higher (Bridgham et al., [2013](#page-19-0); IPCC, 2013). Atmospheric CH₄ concentrations have more than doubled since pre-industrial times, and this upward trend continues to persist (Dlugokencky et al., [2009;](#page-19-0) Jackson et al., [2020](#page-19-0); Nisbet et al., [2019\)](#page-20-0). In 2021, the estimated annual growth rate of atmospheric $CH₄$ concentration reached a record high since 1984 (Lan et al., [2023\)](#page-19-0) exceeding more than three times the average annual growth rate observed from 2007 to 2015 (Poulter et al., [2017](#page-20-0)). Such an increase significantly contributes to the radiative forcing of the atmosphere and further amplifies global warming. Moreover, $CH₄$ has a large natural emission component from permafrost in the northern latitudes. Thawing permafrost initiates a self‐reinforcing cycle: initial warming leads to

Visualization: Sandeep Chinta **Writing – original draft:** Sandeep Chinta **Writing – review & editing:** Xiang Gao, Qing Zhu

increased emissions, which in turn cause further warming and continued thaw. Despite methane's relatively short atmospheric lifetime of 12.4 years (Balcombe et al., [2018](#page-18-0)), its warming potential makes it an essential cog in the wheel for measures to reduce climate change (Shindell et al., [2012](#page-20-0)).

CH4 emissions originate from a broad spectrum of natural and anthropogenic sources. The substantial contributors among anthropogenic sources are agriculture, fossil fuel extraction, and livestock farming (Bridgham et al., [2006;](#page-19-0) Ciais et al., [2013;](#page-19-0) Jackson et al., [2020](#page-19-0); Kirschke et al., [2013](#page-19-0); Saunois et al., [2016](#page-20-0)). Wetlands contribute to more than 30% of total emissions and are the mostsignificant contributor to emissions among natural sources. Wetlands are diverse ecosystems consisting of swamps, marshes, and rice paddies, enabling CH₄ production through microbial metabolic processes within their anaerobic environments (Bodelier & Laanbroek, 2004 ; Turetsky et al., 2014). It is challenging to measure and accurately predict CH₄ emission from wetlands due to their intricate nature and spatiotemporal variability (Rosentreter et al., [2021\)](#page-20-0). In addition, the role of wetlands in the total CH_4 budget and their impact on inter-annual variability and changes in the CH_4 growth rate is still poorly understood (Poulter et al., [2017](#page-20-0)). This issue arises from various factors ranging from soil properties, temperature, vegetation types, and water table dynamics that control $CH₄$ production, consumption, and transfer in wetlands (Bousquet et al., [2006;](#page-19-0) Melton et al., [2013](#page-20-0)). Global warming could aggravate the $CH₄$ emissions from wetlands as they are susceptible to climatic conditions and land-use changes (Gurevitch $\&$ Mengersen, [2019\)](#page-19-0). To address climate change effectively, it is critical that we enhance our ability to model and predict wetland CH4 emissions. This requires comprehensive, process‐based models that encompass all relevant factors and processes.

Biogeochemistry models inherently introduce uncertainties in modeling CH4 emissions due to several factors. Model uncertainty arises because each biogeochemistry model simplifies real‐world processes through a combination of its structure, complexity, physics, usage, and the tuning of model parameters. These simplifications vary considerably among models, leading to a wide range of accuracies in representing methane emission processes. A large number of model parameters relating to diverse physical, biological, and chemical processes associated with CH4 dynamics induce parameter uncertainty. These parameters generally take fixed values, but they are not unambiguously known and usually must be prescribed based on the best available knowledge. Parameter uncertainty is commonly assessed by sensitivity analysis (SA) based on sampling within the theoretical, plausible ranges of parameters, which is the primary focus of this study (Müller et al., [2015;](#page-20-0) Ricciuto et al., [2021](#page-20-0); Riley et al., [2011](#page-20-0)). Other sources of uncertainty include spatial variability of wetlands, scarcity of observations for calibration, initial and boundary conditions, and meteorological forcing to drive the model (Papa et al., [2013;](#page-20-0) Xu et al., [2012](#page-20-0)).

SA quantifies the influence of different input parameters on the model's output, thus helping to identify which parameters significantly contribute to overall parameter uncertainty. Several studies (Chinta et al., [2021](#page-19-0); C. Wang et al., [2020](#page-20-0)) implemented SA in understanding parameter uncertainties in complex earth system models. Ricciuto et al. [\(2018](#page-20-0)) applied SA to the Energy Exascale Earth System Model (E3SM) land model (ELM) parameters with respect to carbon cycle output. Fisher et al. [\(2019](#page-19-0)) examined parameter controls on vegetation responses in the Community Land Model (CLM) using SA. Yuan et al. ([2021\)](#page-20-0) examined the effects of warming and elevated CO₂ on peatland CH_4 emissions using a similar approach. Ricciuto et al. [\(2021](#page-20-0)) used SA to show that production and substrate parameters are vital for regulating temporal patterns of surface CH₄ fluxes. Song et al. ([2020a,](#page-20-0) [2020b\)](#page-20-0) performed SA for a microbial functional group-based CH₄ model and observed that CH₄ emissions are sensitive to the parameters that regulate dissolved organic carbon and acetate production. However, a major challenge in SA is the computational demand for conducting a vast number of ELM simulations (the Monte Carlo method) to efficiently explore the parameter space. This approach is particularly infeasible for complex biogeochemistry models. To address this, machine learning (ML)-based emulators, also known as meta-models or surrogate models, which mimic complex earth system models, are employed. These emulators can approximate model behavior accurately with fewer simulations. Müller et al. ([2015](#page-20-0)) constructed an ML-based emulator using radial basis functions (Gutmann, 2001) for CH₄ parameter estimation in CLM4.5bgc. Dagon et al. ([2020\)](#page-19-0) also implemented an emulator using artificial neural networks (Gurney, [2018](#page-19-0)) in CLM biophysical parameter estimation. Emulators based on Gaussian process regression or kriging (Rasmussen & Williams, [2006](#page-20-0)) were also applied by Gao et al. [\(2021](#page-19-0)) to quantify the sensitivity of soil moisture to uncertain model parameters in CLM.

Although SA and ML have been successfully employed in various areas of earth system modeling, their potential in improving CH₄ emissions modeling still needs to be explored. Our study addresses several primary research

Table 1

Geographical and Vegetation Details of the Simulated FLUXNET‐CH4 Sites

questions, including: (a) which critical parameters dominate the sensitivity of various model-simulated $CH₄$ emissions? (b) what are temporal (seasonal vs. annual) and spatial (site-to-site or vegetation type to vegetation type) characteristics of such parametric sensitivity? and (c) is there any potential to improve model‐simulated methane emissions? We integrated various advanced techniques to tackle these scientific questions. SA is employed to examine the influence of different input parameters on various components of $CH₄$ emissions, while ML is used to emulate the ELM biogeochemistry model with feasible computational cost desired by global SA.

2. Methodology

2.1. FLUXNET‐CH4 Data for Wetland CH4 Emission

FLUXNET-CH₄ is a global network of sites that provides continuous, high-frequency, and quality-checked eddy covariance CH4 flux measurements (Delwiche et al., [2021](#page-19-0); Knox et al., [2019\)](#page-19-0). This data helps get a deeper understanding of the variability of CH_4 emissions worldwide and also help validate CH_4 emissions from biogeochemistry models. The network currently encompasses 81 sites across various vegetation types. From the initial 81 sites, we excluded crop sites due to the complexities introduced by irrigation management, such as quantifying the volume of water required for irrigation. Additionally, sites with less than 2 years of continuous observational data were omitted. Considering the computational expense of simulating all locations, we chose a subset of sites in our study with a diverse mix of vegetation types across various climate zone classifications.

Table 1 presents the list of 14 sites selected for this study, along with their locations and vegetation types. The geographical locations of these sites are presented on a map in Figure S1 of Supporting Information S1. The vegetation types include needleaf evergreen temperate tree (NETT, 4 sites), broadleaf deciduous temperate tree (BDTT, 1 site), broadleaf deciduous boreal shrub (BDBS, 1 site), arctic c3 grass (AC3G, 1 site), cool c3 grass (CC3G, 6 sites), and warm c4 grass (WC3G, 1 site). The PFT number corresponds to that specified in the ELM biogeochemistry model. The corresponding Köppen climate classification of the 14 FLUXNET-CH₄ sites is provided in Table S1 of Supporting Information S1.

2.2. Model Description and Parameter Selection

The Energy Exascale Earth System Model (E3SM) land model version 2 (ELMv2) (Golaz et al., [2022](#page-19-0)) is used in this study, which is branched from Community Land Model (CLM) version 4.5 (CLM4.5) (Oleson et al., [2013\)](#page-20-0). The model underwent several updates associated with the biogeochemical representation of global carbon, nitrogen, and phosphorus cycles (Zhu et al., [2019\)](#page-20-0). Some of the other relevant updates include the introduction of the multiple agent nutrient competition, dynamic allocation, modifications to the photosynthesis physiology

scheme, N₂ fixation, and phosphatase modules. Several studies (Golaz et al., [2019,](#page-19-0) [2022](#page-19-0); Ricciuto et al., [2018\)](#page-20-0) described these updates from CLM4.5 in great detail. The CH4 biogeochemistry model (Riley et al., [2011\)](#page-20-0) explicitly represents several processes, such as CH_4 production, ebullition, aerenchyma transport, aqueous and gaseous diffusion, CH4 oxidation, and mass balance for unsaturated and saturated soils with the following governing equation:

$$
\frac{\partial (RC)}{\partial t} = \frac{\partial F_D}{\partial z} + P(z,t) - E(z,t) - A(z,t) - O(z,t) \tag{1}
$$

where *R* represents gas in aqueous and gaseous phases, *C* represents the concentration of CH₄ with respect to water volume (mol m⁻³), F_D represents aqueous and gaseous diffusion (mol m⁻² s⁻¹), *P* represents CH₄ production (mol m⁻³ s⁻¹), *E* represents ebullition (mol m⁻³ s⁻¹), *A* represents aerenchyma transport (mol m⁻³ s⁻¹), *O* represents oxidation (mol m⁻³ s⁻¹), *z* represents vertical dimension (*m*), and *t* represents time (*s*). The model indirectly accounts for the role of wetland plant functional types (PFTs) in methane production by using heterotrophic respiration rates as a proxy. While wetland PFTs are not explicitly represented, their influence is captured through the impact they have on the soil's organic carbon content, which is a key determinant of heterotrophic respiration. This respiration, primarily driven by microbial activity decomposing organic matter, provides a substrate for methanogenesis. These rates, in turn, are adjusted for environmental factors like soil temperature, pH, and redox potential, which are critical in determining the actual availability of substrates for methane production, hence linking PFTs to methanogens. Ebullition occurs when the $CH₄$ partial pressure, as a function of temperature and depth below the water table, exceeds 15% of the local pressure. Bubbles are added to the saturated columns' surface flux and placed immediately above the water table interface in unsaturated columns. Aerenchyma transport is modeled as gaseous diffusion driven by a concentration gradient between the specific soil layer and the atmosphere and, if specified, by vertical advection with the transpiration stream. $CH₄$ oxidation is represented with double Michaelis–Menten kinetics (Arah & Stephen, [1998\)](#page-18-0), dependent on the gaseous $CH₄$ and $O₂$ concentrations. Gaseous diffusivity in soils depends on temperature-dependent molecular diffusivity, soil structure, porosity, and organic matter content. Aqueous diffusivity in the saturated part of the soil depends on temperature-dependent molecular diffusivity and porosity. Gaseous diffusion is assumed to dominate above the water table interface and aqueous diffusion below it.

These processes in the $CH₄$ biogeochemistry model are represented as functions of climate, vegetation, soil conditions, and empirical parameters. The default values of these parameters are typically assigned based on the best available knowledge from a limited experimental or theoretical investigation. The parameter selection in our study is based primarily on the 16 major parameters affecting ELM's methane biogeochemistry as identified by Riley et al. ([2011\)](#page-20-0). From this list, we exclude parameters related to pH and redox potential, as they are assigned static values and thus have a negligible impact on the temporal dynamics of CH₄ emissions. The seasonal inundation factor within the wetland inundation fraction parameterization is also omitted. The minimum and maximum thresholds to initiate and terminate ebullition are maintained at fixed values of 0.15. To simplify our calibration, we concentrate exclusively on *Ce*,max. We adopted 12 of the 16 parametersfrom Riley et al. ([2011\)](#page-20-0). As previously mentioned, ELM's CH4 production utilizes soil heterotrophic respiration flux as a proxy for methanogen CO_2 substrate availability. Therefore, it is crucial to also test the sensitivity of CH_4 emissions to soil respiration parameters. The selection of these respiration parameters is guided by Koven et al. ([2013](#page-19-0)), which includes all seven turnover parameters (representing substrate availability) of the century-type soil decomposition cascade. Table [2](#page-5-0) presents the 19 ELM parameters used in this study, which pertain to various processes such as production, substrate availability, ebullition, diffusion, aerenchyma transport, and oxidation. For parameters with an unknown uncertainty range, $\pm 50\%$ of the default value is used.

2.3. Numerical Experiment Design

Site-level single-point ELM simulations are performed for the 14 FLUXNET-CH₄ sites. Each simulation follows the same 3-step modeling protocol. In the first step, an accelerated spin-up (as described in Ricciuto et al. ([2018\)](#page-20-0)) is performed for 300 years with CO₂ concentration set to the value of the year 1901. Climatic Research Unit and Japanese reanalysis (CRU JRA) v2.2 data (Harris, [2021\)](#page-19-0) at a six-hourly frequency and $0.5^\circ \times 0.5^\circ$ resolution is used for meteorological forcing. For each site, forcing data from the nearest grid point is used. The forcing data and $N₂$ depositions are cycled over the years 1901–1920. The second step involves a regular spin-up for 200 years Wiley

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with the same CO_2 , N₂ deposition configuration and forcing data as in accelerated spin-up but without accelerating soil turnover. The third step is a 120-year transient run from 1901 to 2020. This step utilizes time-varying historical CO₂ concentrations and CRU JRA forcing data and nitrogen depositions of the years 1901–2020. Each three-step simulation, spanning from the accelerated spin-up to the transient run, took 6 CPU hr on a single core of an Intel Broadwell E5‐2697A v4 CPU (2.60 GHz), using approximately 4 GB of the 128 GB RAM allocated to a 32-core node. Five model output variables are considered for sensitivity analysis: $CH₄$ emission, $CH₄$ production, diffusive surface CH_4 flux, ebullition surface CH_4 flux, and aerenchyma surface CH_4 flux. The values of these fluxes are averaged for 2001–2020. CH₄ emission is the sum of diffusion, ebullition, and aerenchyma surface fluxes. To provide an overview of the methodology before discussing the details, Figure 1 presents a flowchart of the processes implemented in this study.

Figure 1. Flowchart of the methodology implemented showing the main steps and sequence of operations.

2.4. Gaussian Process Regression‐Based Emulators

Gaussian process regression (GPR), a machine learning algorithm, is employed to develop an emulator that approximates the model behavior. GPR is widely used as an emulator due to its robustness and flexibility (Rasmussen & Williams, [2006](#page-20-0); J. Wang, [2020\)](#page-20-0). This algorithm is particularly suitable when the relationship between inputs and output is complex and non-linear. Several studies (Baki et al., [2022b;](#page-18-0) Chinta & Balaji, [2020](#page-19-0); Gong et al., [2015;](#page-19-0) C. Wang et al., [2014](#page-20-0)) established the superiority of GPR as an emulator for earth system models compared to other ML algorithms. GPR is defined by the mean function, $m(x)$, and covariance function, $k(x,x')$, where x and x' are points in the input space. The expected value of the function at point x is given by the mean function, whereas the covariance function gives the correlation between the function values at two different points. For a Gaussian process $f(x) \sim GP(m(x), k(x, x'))$, the joint distribution of any finite number (*n*) of function values $f = [f(x_1), f(x_2),..., f(x_n)]^T$ follows a multivariate Gaussian distribution:

$$
P(f|X) = \mathcal{N}(f|\mu, K) \tag{2}
$$

where *X* is the observations or training data, $\mu = [m(x_1), m(x_2), ..., m(x_n)]^T$ is the mean vector, and *K* is the covariance kernel matrix with $K_{ij} = k(x_i, x_j)$.

The main advantage of GPR is the presence of a covariance function, which helps encode our assumptions about the function to be learned. The mean function is typically set to a constant value, often zero or the average of the training data. For our study, we standardize the outputs of ELM to have an average of zero. Standardization is done by computing the mean and standard deviation of the entire training data set, then subtracting the mean and dividing by the standard deviation for each data point. The resulting training data will have a mean of 0 and a standard deviation of 1. This step is crucial to ensure the stability and accuracy of our analysis. GPR has several options to choose from for a covariance kernel function. We employed one of the widely used kernel functions in our analysis, which combines a constant kernel with a radial basis function (RBF) kernel. This kernel function can be mathematically represented as:

$$
k(x, x') = \sigma_f^2 \exp\left(-\frac{1}{2\ell^2} ||x - x'||^2\right)
$$
 (3)

where *x* and *x'* represent two points in the input space, the two hyperparameters for this kernel are σ_f^2 (signal variance) and *l* (length-scale). The signal variance controls the average distance of function values from their mean, while the length scale determines the smoothness of the function. This kernel function provides the GPR with the flexibility to capture complex patterns in the data. The hyperparameters of the kernel function can be learned from the training data using such techniques as maximum likelihood estimation. Once validated, the trained GPR emulator can not only predict the corresponding output for a new point in the input space but also quantify the degree of uncertainty in this prediction. This is a decisive advantage of GPR over other ML algorithms.

Emulators were designed to take 19 parameter values as input and produce five CH₄ flux values as outputs. For each of the five $CH₄$ fluxes, an individual emulator was developed at every site, resulting in a total of five emulators per site. To generate the training data for emulators at each site, a total of 190 simulations were performed with different combinations of parameter values. The selection of 190 simulations aligns with the guidelines proposed by Loeppky et al. [\(2009\)](#page-20-0) that a training data size of 10 times the number of parameters (19) is sufficient to construct a robust emulator. The parameters were not altered individually but were collectively modified instead in each simulation to represent different scenarios within the model's parameter space. These 190 sets of parameter combinations were generated using Latin Hypercube Sampling (LHS), a technique that effectively and efficiently samples a multidimensional distribution of parameters (McKay et al., [1979](#page-20-0)) across given parameter ranges (Table [2](#page-5-0)). LHS is recognized as superior to simple random sampling, particularly in scenarios with a large number of dimensions (Iman et al., [1981\)](#page-19-0). It offers improved representativeness and efficiency in parameter sampling, ensuring a more uniform and thorough exploration of the parameter space.

The emulators were constructed using the training data from the 190 ELM simulations. A single prediction from a GPR emulator was achieved in just 0.72 milliseconds, in contrast to the 6 CPU hr required for the actual

simulation. To assess the adequacy of the emulator at untried points, an additional 50 sets of LHS parameter values are sampled, and corresponding ELM model simulations are performed at each site to test the performance and robustness of the constructed emulator. We use the coefficient of determination, R^2 , between the modelsimulated and emulator-estimated CH₄ fluxes as the evaluation metric. The closer to 1 the values are, the more accurate the emulator is. Once the emulator was validated, it was used for performing SA.

2.5. Sobol Sensitivity Analysis

The Sobol sensitivity analysis method (Sobol, [2001](#page-20-0)), a variance-based approach to identify the sensitive model parameters, is used in this study. This method was successfully implemented in several studies (Baki et al., [2022a](#page-18-0); Gao et al., [2021](#page-19-0); Reddy et al., [2023](#page-20-0); Ricciuto et al., [2018\)](#page-20-0) to conduct SA for various Earth system model parameters. The Sobol method decomposes the total variance in the model output, with each flux considered separately, into variances corresponding to input parameters. There are two essential features of this method. First, it is a global method, as the sensitivity is evaluated across the whole input parameter space. Second, this method can quantify the primary or first‐order effects of sensitivity for each parameter and the interaction effects between parameters. These features ensure a comprehensive understanding of the sensitivity analysis of the parameters is obtained.

The total output variance, *V*, is decomposed as

$$
V = \sum_{i=1}^{n} V_i + \sum_{1 < i < j < n} V_{i,j} + \dots + V_{123\ldots n} \tag{4}
$$

where n is the total number of parameters. The total output variance V is systematically decomposed into individual and interactive components. First, we account for the variances attributed to each parameter independently, denoted as *Vi* for the *i*th parameter. Then, we consider the variances resulting from the pairwise interactions between parameters, represented as *Vij* for the interactions between *i*th and *j*th parameters. This process hierarchically accounts for increasingly complex interactions among groups of parameters, culminating in $V_{123...n}$, which represents the variance from the interaction of all *n* parameters together. This method ensures that the total variance *V* encapsulates not only the individual effects of each parameter but also the collective influence of their interactions at different levels. As shown below, the Sobol indices are obtained by dividing the respective variances by the total variance.

$$
S_i = \frac{V_i}{V}; \quad S_{ij} = \frac{V_{ij}}{V}; \quad \dots; \quad S_{12...n} = \frac{V_{12...n}}{V}
$$
 (5)

where S_i is the Sobol index for the first-order (main) effect from the *i*th parameter. Total order Sobol index of *i*th parameter, which is the sum of its main and all interaction effects, S_{Ti} is given as:

$$
S_{Ti} = S_i + S_{ij} + \dots + S_{12 \dots i \dots n} \tag{6}
$$

Despite the detailed insights provided, this method requires multiple model runs to cover the entire parameter space for estimating the sensitivity indices accurately (Saltelli et al., [2008\)](#page-20-0). GPR emulators developed in the previous steps were used to evaluate the main and total sensitivity indices for the five $CH₄$ fluxes at different sites using the Sobol method. This decomposition of the total effects of each parameter into main and interaction effects is a critical attribute of the Sobol SA method, enhancing our understanding of parameter sensitivity across various contexts.

2.6. Metrics for Comparing Simulated Emissions With FLUXNET‐CH4 Measurements

It is important to understand how the simulated emissions from perturbed parameter sets compare with observed emissions. The model simulated monthly-averaged CH₄ emissions from the 190 parameter sets are compared against FLUXNET-CH₄ observations at each site, and root mean square error (RMSE) is evaluated.

$$
RMSE = \sqrt{\frac{\sum_{t=1}^{T} (sim^t - obs^t)^2}{T}}
$$
 (7)

where sim^t and obs^t are the simulated and observed values of monthly CH₄ emission from the simulated site at time *t*, respectively. *T* is the number of months. We calculated a normalized root mean square error (nRMSE) for each of the 190 initial sets of parameter values. This normalization was performed by comparing each nRMSE to the RMSE obtained from the default parameter run. The nRMSE for a given set, i , is computed as:

$$
nRMSE_i = \frac{RMSE_i}{RMSE_{def}}\tag{8}
$$

In this equation, $RMSE_i$ represents the RMSE for the specific set of parameter values, while $RMSE_{def}$ denotes the RMSE derived from the simulation with default parameter values. A parameter set with an nRMSE value less than one indicates improved performance (lower RMSE) in comparison to the default.

3. Results

3.1. Sensitivity Analysis ‐ Main Effects and Interaction Effects

Emulators for five CH₄ fluxes (CH₄ emission, CH₄ production, diffusive surface CH₄ flux, ebullition surface CH₄ flux, and aerenchyma surface CH_4 flux) were developed at each site using the initial 190 simulations. These emulators were then evaluated by comparing the emulator‐predicted fluxes with the ELM‐simulated counterparts from 50 independent test simulations at each site. We present results for one of the sites, specifically the CH-Cha site (PFT-13: Cool c3 grass), as shown in Figure [2.](#page-9-0) The emulators performed well for all the fluxes with R^2 values ranging from 0.84 to 0.95. Similarly, for fluxes at other sites, the emulators also performed reasonably well, with *R*² values above 0.80, as shown in Figure S2 of Supporting Information S1. Overall, the emulator captures well the model behavior for various fluxes across the entire parameter uncertainty space over the sites with different vegetation types and is considered to be accurate and robust. Therefore, the GPR‐based emulators can be reliably applied to derive the Sobol SA indices and further quantify the main and interaction effects of the fluxes relative to each parameter.

The main effect (first-order Sobol index) of a parameter represents the influence of that parameter alone on the considered flux, disregarding any interaction effects with other parameters. Heatmaps for two sites, CH‐Cha (PFT‐13: Cool c3 grass) and SE‐Deg (PFT‐12: Arctic c3 grass) are displayed in Figure [3](#page-10-0). Each cell of the heatmap represents the value of the main effect for its corresponding parameter (*x*‐axis) and flux (*y*‐axis), with the color intensity indicating the strength of the parameter sensitivity. The heatmaps for both sites were remarkably similar, reflecting parallel sensitivity trends across the parameters at these two sites. The CH₄ production parameters Q_{10} and f_{CH_4} (ratio between CH₄ and CO₂ production below the water table) displayed pronounced sensitivity for all fluxes. The diffusion parameter f_{D_0} (diffusion coefficient multiplier) was a predominantly sensitive parameter for diffusion, whereas the oxidation parameters *Ro*,max (maximum oxidation rate—wetlands) and K_{CH_4} (CH₄ half-saturation oxidation coefficient—wetlands) emerged as sensitive parameters for aerenchyma transport across these two sites. Apart from these five parameters, the remaining parameters had negligible in-fluences on all fluxes for these two sites. Results corresponding to other sites are presented in Section 3.2. Figure [4](#page-11-0) illustrates the total effect Sobol indices, encapsulating main (blue) and interaction effects (red), for various $CH₄$ fluxes relative to each parameter at the two sites mentioned above. The main effect values are the same as those represented in the heatmaps (Figure [3\)](#page-10-0). Main effects were more prominent than interaction effects for all parameters, highlighting the dominant influence that individual parameters exert on the different $CH₄$ fluxes. For all fluxes at these two sites, no parameter exhibited a higher interaction effect value compared to its main effect. Other sites share a similar characteristics of total effects (not shown).

3.2. Sensitivity for Multiple Sites Across Vegetation Types

Figure [5](#page-12-0) illustrates the distribution of main effect sensitivity indices for each parameter, corresponding to different CH₄ fluxes across the 14 FLUXNET-CH₄ sites. These boxplots comprehensively represent the variation

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Figure 2. Accuracy of the GPR model based on test data (50 independent simulations) for different CH₄ fluxes at the CH-Cha site (PFT-13: Cool c3 grass). The horizontal axis denotes the model output, and the vertical axis represents the GPR fit.

in sensitivity indices for multiple sites across vegetation types. The production parameter Q_{10} has the highest sensitivity among the parameters for all the fluxes, suggesting its significant role in modulating various $CH₄$ fluxes. *Q*¹⁰ also presents the overall largest variability (inter‐site spread) in sensitivity across all the fluxes except for emission, suggesting that the sensitivity of *Q*¹⁰ may be highly dependent on climate conditions (geographical locations) and vegetation types. Another production parameter f_{CH_4} was also found to be a fairly sensitive parameter for all the fluxes. In contrast to the earlier heatmaps for CH-Cha and SE-Deg (Figure [3](#page-10-0)) where f_{D_0} did not influence emission, it was a sensitive parameter with even higher sensitivity than *Q*¹⁰ for some sites. The diffusion flux was sensitive to the diffusion parameter (f_{D_0}) . Apart from these three parameters, other parameters like $R_{o,\text{max}}$, K_{CH_4} were sensitive parameters for aerenchyma. Additionally, z_r (e-folding depth for decomposition) was a sensitive parameter for some fluxes (Figures [5b,](#page-12-0) 5d, and [5e](#page-12-0)). Also, some parameters $(f_{D_0}$ and $R_{o,\text{max}}$ in Figure [5c](#page-12-0)) were sensitive at one or two sites, represented as outliers in the figure. It is important to note that roughly 13 parameters consistently showed negligible influence on various fluxes with little inter‐site variability. The heterogeneity of $CH₄$ flux dynamics and associated parametric sensitivities is underscored by the inter-site spread and the presence of outliers in sensitivity indices across the sites. These characteristics underline the heterogeneity of CH₄ flux dynamics and associated parametric sensitivities across the sites (vegetation types). Further examination of parametric sensitivities at additional sites with similar vegetation types may provide a more generalized understanding of these patterns.

3.3. Contribution of Parameters to Variance in CH4 Fluxes

Figure [6](#page-13-0) shows the contribution of different parameters to the variance in $CH₄$ fluxes at the 14 FLUXNET-CH₄ sites, grouped by the vegetation types. Only those parameters that contribute a minimum of 5% to the variance at any site have been included in the analysis. The results are in agreement with those shown in Figure [5,](#page-12-0) with the

Figure 3. Heat map of main effect sensitivity indices for different CH₄ fluxes (EM: Emission, PROD: Production, DIFF: Diffusion, EBUL: Ebullition, AERE: Aerenchyma) with respect to [1](#page-3-0)9 parameters (shown in Table 1) at (a) CH-Cha and (b) SE-Deg sites.

production parameters Q_{10} and f_{CH_4} , along with the diffusion parameter f_{D_0} being the most influential parameters for different CH₄ fluxes across multiple sites. Some sites had a combination of Q_{10} and f_{CH_4} as sensitive parameters for emission, whereas other sites had f_{D_0} and K_{O_2} as sensitive parameters. The production parameters Q_{10} and f_{CH_4} emerged as sensitive parameters for production at all sites. Apart from these two parameters, substrate availability parameters z_r , τ_{l2-l3} (turnover time of litter 2 and litter 3), and τ_{s2} (turnover time of soil organic matter 2) emerged as sensitive parameters for production at some sites. Theoretically, substrate availability plays an important role in methane production as it determines the quantity and rate at which methanogenic microbes produce methane in anaerobic conditions. The diffusion parameter f_{D_0} and the production parameters Q_{10} and f_{CH_4} emerged as sensitive parameters for diffusion at most of the sites. $R_{o,\text{max}}$ and z_r emerged as sensitive parameters for diffusion at some sites. Ebullition was sensitive to the production parameters Q_{10} and f_{CH_4} at most sites. Ebullition parameter, *Ce*,max (CH4 concentration to start ebullition), and aerenchyma parameters *R* (aerenchyma radius) and *Fa* (aerenchyma conductance multiplier) emerged as sensitive parameters for ebullition at some sites. Although *R* primarily affects aerenchyma, when aerenchyma and ebullition are dominant pathways for $CH₄$ to escape, a change in *R* will affect how much CH₄ is emitted through aerenchyma, and consequently, the amount of CH₄ left over for emission through ebullition. The production parameters Q_{10} and f_{CH_4} , oxidation parameters *Ro*,max, *KCH*⁴ and aerenchyma parameter *R* were sensitive parameters for aerenchyma at most of the sites.

Although some parameters are relevant to a particular process, they could still affect other processes through competition and feedback, depending on the coexistence of certain processes at the time of calculation. The sensitivity can be explained in groups. First, it is reasonable to see production-related parameters dominate the sensitivity because CH₄ production is the biggest flux and directly determines how much CH₄ will be available to emit. Then we see oxidation parameters sometimes show up as sensitive parameters because oxidation sometimes is ignorable (saturated condition) but sometimes could consume a large fraction of newly produced $CH₄$ (partially saturated). The third group is emission pathway parameters, ebullition, diffusion, and aerenchyma are three emission pathways determined by environmental conditions, vegetation activity, and vertical concentration

Figure 4. The main effects and interaction effects (differences between the total and main effects) of 19 parameters for different CH₄ fluxes for two sites CH-Cha (PFT-13: Cool c3 grass) and SE‐Deg (PFT‐12: Arctic c3 grass).

gradient. These three pathways are either dynamically competing or totally independent, depending on whether an emission pathway is favored under certain conditions like vegetation or climate zones.

Across all sites, the top 5 or 6 parameters (parameters with high sensitivity for a particular flux) typically accounted for over 90% of the variance in $CH₄$ fluxes. However, in certain instances, even fewer parameters were responsible for a substantial portion of the variance. Notably, 13–14 parameters consistently showed a negligible effect on the $CH₄$ fluxes across these sites. For the four sites characterized by PFT-1 vegetation (Needleleaf evergreen temperate tree), the sensitive parameters remained largely consistent. This consistency prevailed irrespective of the individual climate classifications of these sites (as detailed in Table S1 of Supporting

Figure 5. Boxplots showing the distribution of main effect sensitivity indices for each parameter across 14 FLUXNET-CH₄ sites. The boxplot shows the median (orange line), interquartile range, minimum, and maximum after excluding outliers. An outlier, represented by a circle, is a data value outside 1.5 times the interquartile range above the upper quartile and below the lower quartile.

Information S1). This observation implies that, for Needleleaf evergreen temperate tree sites, the climate classification has minimal impact on parameter sensitivity. In contrast, the six sites with PFT-13 vegetation (Cool C3 grass) displayed more variability. While the first three of these sites shared a common sensitivity pattern, the next three differed in their sensitivities. This variation can be linked to their respective climate classifications as the

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PFT-1: Needleaf evergreen temperate tree PFT-7: Broadleaf deciduous temperate tree PFT-11: Broadleaf deciduous boreal shrub PFT-12: Arctic c3 grass PFT-13: Cool c3 grass PFT-14: Warm c4 grass

Figure 6. Total effect sensitivity indices of parameters in the percentage of the variance in various CH₄ fluxes, grouped by vegetation types of 14 FLUXNET-CH₄ sites. Only those parameters with at least 5% contribution at any site are included. The height of each color represents the percentage of the total effect Sobol index of that parameter with respect to the sum of the total effect Sobol indices of all parameters at that site, namely, the percentage of the total variance in CH₄ fluxes attributable to that parameter, including its interactions with other parameters. The sites (each bar) in the subfigures are ordered as presented in Table [1](#page-3-0), which is PFT 1 (RU-Fy2, DE-SfN, CH‐Dav, US‐Ho1), PFT 7 (US‐Pfa), PFT 11 (RU‐Cok), PFT 12 (SE‐Deg), PFT 13 (DE‐Zrk, CH‐Cha, DE‐Hte, US‐OWC, US‐WPT, CN‐Hgu), PFT 14 (US‐MRM).

 K_O

Jan

Feb

Mar

Apr

May

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Figure 7. Monthly fluctuation in main effect sensitivity indices of parameters of CH₄ emission for 2 FLUXNET-CH₄ sites. Only those parameters with a minimum value of 0.05 for the main effect (first-order Sobol index) for at least 1 month at the specific site are included.

Jun

 0.2

Jul

first three sites are under a temperate climate, and the latter three are categorized as a continental climate. This suggests a stronger influence of climate classification on parameter sensitivity for Cool C3 grass sites.

 0.18

Aug

 0.17

Sep

 0.14

 Oct

 $\sqrt{ }$

Nov

 $\mathbf{0}$

Dec

In light of these findings, it is evident that while vegetation type plays a role in determining parameter sensitivity, climate classification can modulate this effect, especially for certain vegetation types. Further analysis of more sites with the same vegetation types, particularly for the vegetation types with only one site in our study, is necessary to gain a more solid understanding of how a combination of climate conditions and vegetation types affect parametric sensitivity.

3.4. Seasonal Characteristics of Parametric Sensitivity in CH4 Emission

Given the established seasonal variability in methane emissions from wetlands (Knox et al., [2021;](#page-19-0) Sakabe et al., [2021](#page-20-0); Zhang et al., [2020\)](#page-20-0), we are interested in how the parametric sensitivity of methane emissions fluctuates across months. Figure 7 shows the monthly variation in the main effects of selected parameters for methane emission at two FLUXNET-CH₄ sites, CH-Cha and SE-Deg Parameters with a minimum value of 0.05 for the main effect in at least 1 month were included.

A distinct pattern was observed for the monthly sensitive parameters. For CH-Cha (PFT-13: Cool c3 grass), the production parameters Q_{10} and f_{CH_4} were predominantly sensitive from December to March, whereas for SE-Deg (PFT‐12: Arctic c3 grass), their sensitivity extended from November to June. In contrast, during the remaining months, the sensitivity was primarily associated with f_{D_0} and K_{O_2} . The observed monthly fluctuations in parameter sensitivity can be linked to seasonal temperature variations, given that parameters Q_{10} and f_{D_0} are directly temperature-dependent (Riley et al., [2011](#page-20-0)). Other factors influencing the seasonal variation in methane emissions include gross primary productivity, ecosystem respiration, net ecosystem exchange, latent heat turbulent flux, soil temperature, water table depth, incoming shortwave radiation, and wind direction (Knox et al., [2021\)](#page-19-0). This periodic parameter sensitivity behavior on the month scale is distinctive from the 20‐year annual mean in which neither f_{D_0} nor K_{O_2} were dominant sensitive parameters (Figure [3](#page-10-0)). Long-term averages may obscure some

Figure 8. Parameters ranked according to their sensitivity of annually averaged CH₄ emission across 14 FLUXNET-CH₄ sites. The percentage values over each bar represent the normalized score for that parameter.

features inherent in a short temporal scale by smoothing out variations from changing parameter values over shorter durations. Examining monthly averages reveals nuanced parametric sensitivity patterns that might be missed in long‐term aggregates.

3.5. Parameter Ranking Based on CH4 Emission Flux Sensitivity

While Section [3.4](#page-14-0) underscores the nuances captured by examining monthly averages, Section 3.5 aims to complement this by offering a broader perspective. Here, we present the hierarchical ranking (Figure 8) of parametric sensitivities to CH_4 emission, derived from the 20-year average across all sites. Although this long-term aggregation potentially smooths over shortterm variations, as noted earlier, it serves a crucial different purpose. It allows us to capture overarching trends in parameter sensitivity across the 14 $FLUXNET-CH₄ sites corresponding to different vegetation types and climate$ zones. The total effect Sobol indices of parameters were averaged across all

sites to offer a comprehensive perspective on their overall influence across diverse vegetation types. This averaging allows for capturing the general trends in parameter sensitivity and can help in identifying parameters of universal importance. Furthermore, normalizing these averaged values ensures that the results are presented on a consistent scale from 0 to 100, facilitating comparisons. Five parameters Q_{10} , f_{D_0} , f_{CH_4} , z_r , and K_{O_2} - collectively accounted to approximately 95% of the normalized score, while all the remaining parameters show little to negligible effect on $CH₄$ emission.

3.6. Comparison of Simulated Emissions With FLUXNET‐CH4 Data

Sensitivity analysis was strictly a modeling exercise designed to understand how different parameters influence a model's output. Comparing the simulated emissions from perturbed parameter sets with observed emissions is essential. This comparison works as an elementary assessment that allows us to understand whether there exists a potential to improve the simulated emissions corresponding to observations by adjusting the parameter values within their ranges. We compared the average monthly ELM-simulated methane emissions from 190 parameter sets to FLUXNET-CH₄ observed emissions at each site (Figure [9a\)](#page-16-0). It is important to note that the observation data available at each site is not across the same timeline (Table S1 in Supporting Information S1). So, the simulated emissions were only compared for the available duration of observations for each site. The ELM simulations over-predicted (under-predicted) the emissions for ten (four) out of the 14 sites. All four sites that under-predicted the emissions belonged to PFT-13: Cool c3 grass. The magnitude of monthly averaged observed emissions varies greatly across sites. A larger range in the emissions resulting from perturbed parameter values indicates greater parameter uncertainty. This variability reflects how sensitive the model's output is to changes in the input parameters, and suggests that the model's predictions could be significantly affected by our confidence in those parameters. This variability in emissions is not uniform across sites. Some sites have higher variability whereas others have lower variability.

A comparison of nRMSE values (Figure [9b\)](#page-16-0) shows that there are always partial parameter sets at each site that have nRMSE values less than 1, indicating an improved performance with lower RMSE compared to using the default parameter values (see Section [2.6](#page-7-0) for details). The median nRMSE values were higher than 1 at some sites, such as CH-Dav, RU-Cok, and CN-Hgu, suggesting potential challenges in accurately predicting methane dynamics at these sites. In contrast, sites like US‐Ho1, SE‐Deg, and DE‐Hte‐Cha present lower median nRMSE values, indicating improved simulations of CH4 emissions over the default could be potentially achieved. The minimum nRMSE values, provided in brackets for each site, underscore the extent to which $CH₄$ emissions with alternative parameters may outperform those with the default at each site, for example, via parameter calibration We also analyze the distribution of RMSE and bias across 190 simulations at each site (Figures S3 and S4 in Supporting Information S1). The values of the identified sensitive parameters can be adjusted within their respective ranges (Table [2\)](#page-5-0) to minimize the difference between the model simulated and the observed $CH₄$ emissions at each FLUXNET-CH₄ site. This adjustment can be achieved systematically by employing an advanced optimization technique like Bayesian calibration (Gattiker et al., [2016f](#page-19-0); Kennedy & O'Hagan, [2001\)](#page-19-0).

Figure 9. (a) Box plots (190 ELM simulations) depicting the average monthly emission across 14 FLUXNET-CH₄ sites, grouped by their vegetation types. The boxplot shows the median (orange line), interquartile range, minimum, and maximum after excluding outliers and individual circles marking outlier data points. Average monthly emissions of observation (red) and default (green) parameter ELM simulations are also presented. (b) Same as (a) but for nRMSE. The green dashed line signifies an nRMSE value of 1, corresponding to the RMSE from the default parameter simulation for the respective site. The value in brackets below each site label denotes the minimum nRMSE value from a set of 190 simulations for that particular site.

4. Discussion

4.1. Key Parameters Influencing Methane Emission

Sensitivity analysis revealed that five parameters Q_{10} , f_{D_0} , f_{CH_4} , z_r , and K_{O_2} are among the most sensitive parameters for methane emissions from the chosen wetland sites. Q_{10} represents the temperature-dependent methane production. A higher *Q*¹⁰ suggests that an increase in temperature will lead to more methane

production and emissions. This, in turn, can indirectly enhance diffusion, as increased methane production creates larger concentration gradients. The parameter f_{CH_4} is the ratio between CH_4 and CO_2 production below the water table. A higher ratio means a greater dominance of methane in production and emission relative to $CO₂$. The diffusion coefficient multiplier, f_{D_0} , is equally important. This parameter directly alters the rate of methane movement through gas or liquid. A higher value of f_{0} suggests more rapid methane diffusion. As the methane transport increases, it could lead to higher emissions. The e‐folding depth, *zτ*, determines the depth at which microbial decomposition diminishes exponentially. A greater e-folding depth suggests methane production can happen deeper, possibly causing a delay in its release or changing emission patterns due to its travel through various soil and water layers. The parameter K_{O_2} indicates the oxygen concentration at which methane oxidation is halved. Higher K_{O_2} values suggest that more methane is oxidized into CO_2 , leading to reduced methane emissions. The minimal impact of the other parameters on CH₄ emissions indicates that while they might be important at specific sites, their overall contribution is less significant when averaged across all sites. This differentiation between universally influential parameters and those with localized effects can guide model developers to focus on the specific sensitive parameters for further improving CH₄ emission modeling based on different research objectives.

Numerous studies have highlighted the sensitive parameters influencing methane emissions. Müller et al. ([2015\)](#page-20-0) performed a one-at-a-time sensitivity analysis on 21 parameters within the CLM4.5bgc model, at 16 different sites comprising 6 wetlands and 10 rice paddies. Their findings pointed to Q_{10} , f_{CH_4} , and K_{O_2} as the most sensitive parameters across all sites, with f_{D_0} emerging as sensitive in three specific sites. Similarly, Riley et al. ([2011\)](#page-20-0) undertook a sensitivity analysis in the CLM4Me model, identifying Q_{10} , alongside oxidation and aerenchyma parameters, as critical for methane emission. Song et al. [\(2020a](#page-20-0), [2020b\)](#page-20-0) utilized the Sobol sensitivity analysis method for the Integrated Biosphere Simulator (IBIS) model, finding parameters related to production and oxidation to be most influential. Additionally, Zhu et al. ([2014\)](#page-20-0) conducted a sensitivity analysis on the TRIPLEX‐ GHG model, singling out Q_{10} as one of the most sensitive parameters among those examined. These studies collectively underscore the importance of certain key parameters across different models and environmental settings in determining methane emissions. Despite the variation in models, sensitivity analysis methods, and the environmental contexts of the sites considered, there is a consensus in our results and those of other studies regarding the high sensitivity of production and oxidation‐related parameters. In our study, the diffusion parameter f_{D_0} emerged as sensitive, which contrasts with its lesser sensitivity in some studies mentioned above. This highlights the nuanced differences in sensitivity analyses and the importance of considering a wide range of parameters and contexts to understand methane emission dynamics fully.

4.2. Scope for Parameter Optimization and Limitations

Adjusting the sensitive parameter values to reduce the simulation error with respect to observations using advanced optimization techniques like Bayesian calibration helps reduce parameter uncertainty. Bayesian calibration involves using Markov Chain Monte Carlo (MCMC) methods to draw multiple parameter samples from the prior distribution, which is usually a uniform distribution. GPR-based emulators are then developed to take the values of sensitive parameters as input and generate the corresponding emission values. The comparison of these outputs with FLUXNET-CH₄ observed emissions, facilitated through an objective function, aids in refining the parameters through an iterative approach (Chinta et al., [2023](#page-19-0)). After the end of the calibration process, the calibrated parameters are represented by their posterior distributions. Drawing samples from these distributions allows for ensemble simulations that more closely align with observed data. This process significantly improves the model's accuracy and reliability in simulating methane emissions and reduces uncertainty. This step, although not covered in our current study, suggests a significant potential for future research. This approach would foster greater confidence in future CH_4 emission projections, It is important to note that apart from parameter uncertainty, other sources of uncertainty such as uncertainties in forcing data, the accuracy of observational data, and inherent limitations within the model structure could also influence the simulated emissions. Along with aiming to reduce parameter uncertainty using Bayesian calibration, future research could further enhance the accuracy of model simulations by investigating these other forms of uncertainty. This comprehensive examination would contribute to a more robust and reliable modeling approach, ensuring that the simulations more accurately reflect real‐world complexities.

This study offerssignificant insights into the sensitivity analysis of methane emissions. However, several inherent limitations need consideration. The presented results may be dependent on the choice of meteorological forcing data. The spatial scale discrepancy between the model simulations (0.5°) and the point-based observations may also lead to some biases in the results. Despite its computational benefits, the emulator might not fully capture the complex and non-linear dynamics of the ELM biogeochemistry model, potentially leading to minor discrepancies between the emulator's predictions and the actual ELM‐simulated outputs. Additionally, using the Monte Carlo approach for generating large samples in the Sobol analysis introduces inaccuracies due to finite sample size (H. Wang et al., [2020](#page-20-0)). While the monthly fluctuations in parameter sensitivity were examined, the diurnal fluctuations were not explored. Notably, methane emissions exhibit significant diurnal variability (Knox et al., [2021\)](#page-19-0), which could present another layer of complexity to the analysis. Future analyses could consider incorporating a broader range of sites spanning diverse vegetation types. This would ensure a more exhaustive assessment of parameter sensitivity across different ecosystems. Errors from external factors outside the methane biogeochemistry model, like heterotrophic respiration and net primary productivity, impact simulated methane emissions (Riley et al., [2011](#page-20-0)), which in turn affects the sensitivity analysis results. Despite these limitations, the findings from this study offer significant insights into the parametric sensitivity of various $CH₄$ emissions.

5. Conclusions

This study carried out a sensitivity analysis of 19 ELM model parameters with respect to methane emission from natural wetlands at 14 FLUXNET‐CH4 sites with diverse vegetation types. Machine learning‐based emulators were employed to emulate the ELM model in consideration of computational demands. The GPR-based emulators were shown to represent the model simulations reasonably well across all the sites. These emulators were used to calculate the Sobol sensitivity indices for various CH₄ fluxes. Five parameters Q_{10} (CH₄ production), f_{D_0} (diffusion coefficient multiplier), f_{CH_4} (ratio between CH₄ and CO₂ production below the water table), z_r (efolding depth for decomposition), and K_{O_2} (O₂ half-saturation oxidation coefficient) were identified as sensitive parameters across various fluxes and sites. These five sensitive parameters accounted for approximately 95% of the total variance in emission. The remaining 14 parameters had negligible impact on emissions across all sites. Seasonal characteristics of parameter sensitivity to methane emissions showed specific features that long-term annual averages might overlook. The Comparison of the model simulations against FLUXNET-CH₄ observations revealed a potential for improving simulated emissions via parameter calibration. Future studies will focus on extending this sensitivity analysis to more FLUXNET-CH₄ sites to better understand how parametric sensitivities depend on vegetation types and climatic conditions. The identified sensitive parameters can be systematically adjusted to reduce the simulation error with respect to observed methane emissions using Bayesian calibration and ML‐based emulators. In addition, the availability of high‐quality observations from a diverse range of wetlands will greatly benefit this exercise.

Data Availability Statement

The E3SM code is available at https://github.com/E3SM-Project/E3SM (Golaz et al., [2022\)](#page-19-0). FLUXNET-CH₄ data is available for download at [https://fluxnet.org/data/fluxnet‐ch4‐community‐product/](https://fluxnet.org/data/fluxnet-ch4-community-product/) (Delwiche et al., [2021](#page-19-0); Knox et al., [2019\)](#page-19-0). CRU JRA v2.2 data is available at [https://catalogue.ceda.ac.uk/uuid/4bdf41fc10af4](https://catalogue.ceda.ac.uk/uuid/4bdf41fc10af4caaa489b14745c665a6) [caaa489b14745c665a6](https://catalogue.ceda.ac.uk/uuid/4bdf41fc10af4caaa489b14745c665a6) (Harris, [2021\)](#page-19-0). The data and code are available at [https://doi.org/10.5281/zenodo.](https://doi.org/10.5281/zenodo.12738074) [12738074](https://doi.org/10.5281/zenodo.12738074) (Chinta, [2024](#page-19-0)).

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