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STRUCTURAL ENGINEERING AND STRUCTURAL MECHANICS

DOT-DICE THE DETERMINATION OF TEMPERATURES WITHIN MASS CONCRETE STRUCTURES

by
EDWARD L. WILSON

A Computer Program

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DEPARTMENT OF CIVIL ENGINEERING UNIVERSITY OF CALIFORNIA BERKELEY, CALIFORNIA

STRUCTURES AND MATERIALS RESEARCH DEPARTMENT OF CIVIL ENGINEERING

Report No. 68-17

THE DETERMINATION OF
TEMPERATURES WITHIN
MASS CONCRETE STRUCTURES

A Report of an Investigation

by

Edward L. Wilson Associate Professor of Civil Engineering

to

Walla Walla District U.S. Engineers Office Contract DACW-68-67-C-0049

Structural Engineering Laboratory University of California Berkeley, California

December 1968

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INTRODUCTION

In the construction of mass concrete structures the hydrating cement releases heat which results in an increase in temperature shortly after placement of the concrete. Because of the low modulus of elasticity and the high creep rate at the early age concrete the compressive stresses associated with this initial temperature increase are small. However, the subsequent decrease in temperature after the modulus of elasticity has increased may cause large tensile stresses and produce structural cracking.

Various construction techniques can be used in order to limit temperature variations and to minimize cracking. However, existing methods of analysis for the evaluation of temperatures in mass concrete structures are inadequate because they cannot accurately represent these complex construction procedures.

The finite element method of analysis as applied to heat transfer can accurately represent many factors which previously have been neglected. Therefore, the purpose of this investigation was to modify the finite element method as applied to heat-transfer problems and to develop a technique for the evaluation of the temperature distribution in mass concrete structures. Based on this approach a general digital computer program was developed for mass concrete structures of arbitrary geometry constructed incrementally. Also, the effects of cooling pipes and insulation forms are considered by the program.

The advantages of the method, as compared to other numerical approaches, are numerous. The method is completely general with respect to geometry and material properties; complex bodies composed of many different materials are easily represented. Inherent in most numerical procedures is the solution of a set of linear equations for unknown mesh point temperatures. In the finite element method, the linear equations produce a symmetric positive-deffinite matrix in band form which is readily solved with a minimum of computer storage and time.

Previously, the complete thermal stress analysis of mass concrete structures has involved two separate phases. First, based on certain idealizations, the heat transfer problem is solved; then the resulting temperature distribution is used in connection with certain structural idealizations to determine the thermal stresses within the structure. In general, both of these phases involve the use of digital computers, and because different idealizations are used, a separate computer input must be prepared for each problem. In the proposed finite element approach the computer input can be made compatible with existing stress analysis programs; therefore, the computer input and the overall time necessary for the complete thermal stress analysis is reduced.

METHOD OF ANALYSIS

Previous application of the finite element method to heat transfer analysis has been based on a variational approach. [1] However, this formal mathematical method will not be utilized in this presentation, but a completely physical interpretation of the heat-transfer equations for a finite element system will be given. The basic equation which is developed at each node of the discrete finite element representation of the structure is of the following form:

If all nodes are considered, the above heat equilibrium can be written in matrix form as a set of first order differential equations.

$$\underline{C} \dot{\underline{T}(t)} + \underline{K} \underline{T(t)} = \underline{Q(t)}$$

where

 $\underline{\mathsf{C}}$ is defined as the heat capacity matrix

 \underline{K} is defined as the conductivity matrix

T(t) is a vector of the nodal point temperatures

 $\frac{\dot{T}(t)}{T(t)}$ is a vector of the time rate of change of the nodal point temperatures

Q(t) is a vector of the external heat rates which are supplied at the nodes (heat which is generated within the elements can be considered in this vector)

The basic assumptions required to develop this heat equilibrium equation will be given in the following sections.

Temperature Gradients

The basic element (sub-division) used in the idealization of a two-dimensional body is a triangle of arbitrary shape (figure 1). Since the thickness of the triangle may be different for each element, axisymmetric bodies are a special case of this formulation. The first step in the development of the heat transfer equations is to assume the following temperature distribution within each element:

$$T(x,y) = \beta_1 + \beta_2 x + \beta_3 y$$
 (2a)

If equation (2a) is evaluated at the three vertices and the resulting set of equations is solved, the following relationship for the constants β_1 , β_2 and β_3 is obtained:

$$\begin{bmatrix} \beta_{1} \\ \beta_{2} \\ \beta_{3} \end{bmatrix} = \frac{1}{\lambda} \begin{bmatrix} \cdots & \lambda & \cdots & 0 & \cdots & 0 & \cdots \\ \cdots & b_{j} - b_{k} & \cdots & b_{k} & \cdots & -b_{j} & \cdots \\ \cdots & a_{k} - a_{j} & \cdots & -a_{k} & \cdots & a_{j} & \cdots \end{bmatrix} \begin{bmatrix} \vdots \\ T_{i} \\ \vdots \\ T_{j} \\ \vdots \\ T_{k} \\ \vdots \end{bmatrix}$$
(2b)

where $\lambda = a_j b_k - a_k b_j$

or symbolically

$$\underline{\beta} = \underline{D} \, \underline{T} \tag{2c}$$

where $\underline{\mathsf{T}}$ is a vector of the temperatures at all the nodal points in the system.

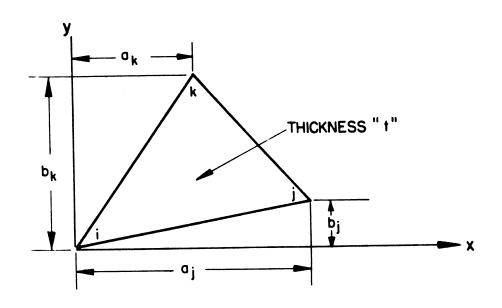


FIGURE I - TYPICAL TRIANGULAR ELEMENT

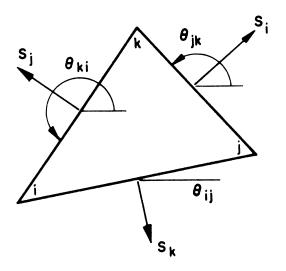


FIGURE 2 - NORMAL GRADIENTS AND REF - ERENCE ANGLES

Temperature Gradients (Continued)

The temperature gradients normal to the boundaries of the element are by definition

$$S_{N} = \frac{\partial T}{\partial N} \tag{3}$$

If equation (3) is evaluated at the three boundaries of the element, the following normal gradients are found:

$$\begin{bmatrix} S_{i} \\ S_{j} \\ S_{k} \end{bmatrix} = \begin{bmatrix} 0 & -\sin \Theta_{jk} & \cos \Theta_{jk} \\ 0 & -\sin \Theta_{ki} & \cos \Theta_{ki} \\ 0 & -\sin \Theta_{ij} & \cos \Theta_{ij} \end{bmatrix} \begin{bmatrix} \beta_{1} \\ \beta_{2} \\ \beta_{3} \end{bmatrix}$$

$$(4)$$

The angles Θ_{mn} are defined in figure 2. Equation (4) may be written in symbolic form as

$$\underline{S} = \underline{g} \underline{\beta} \tag{5}$$

Heat Flow

The rate of heat flow through a boundary is given by

$$q_N = k* A S_N$$

where k* is the conductivity of the material and A is the surface area of the boundary. Consequently, the heat flow, as shown in figure 3, through the three interior boundaries, which are one half the length of the sides, is

$$\begin{bmatrix} : \\ q_{i} \\ : \\ q_{j} \end{bmatrix} = \frac{k \times t}{2} \begin{bmatrix} : & : & : \\ \ell_{jk} & 0 & 0 \\ : & : & : \\ 0 & \ell_{ki} & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \ell_{ij} \end{bmatrix} \begin{bmatrix} s_{i} \\ s_{j} \\ s_{k} \end{bmatrix}$$

$$(6)$$

where t is the thickness of the element and ℓ_{mn} is the length of side mn. Equation (6) written symbolically is

$$\underline{q} = \underline{f} \underline{s} \tag{7}$$

The size of the vector $\underline{\mathbf{q}}$ is equal to the number of nodal points in the system; it will contain only three non-zero rows, however, since a typical element is connected to three nodal points.

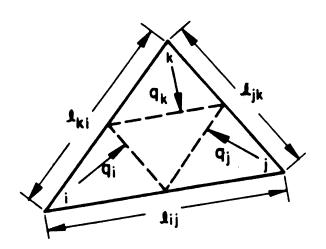


FIGURE 3 - HEAT FLOW VECTORS

Element Conductivity Matrix

Heat flow for a typical element m is expressed in terms of corner temperatures by combining equations (2), (5) and (7),

$$\underline{\mathbf{q}}^{\mathsf{m}} = \underline{\mathsf{K}}^{\mathsf{m}} \ \underline{\mathsf{T}} \tag{8}$$

where $\underline{k}^{\boldsymbol{m}}$ is defined as the "element conductivity matrix" and is given by

$$\underline{k}^{\mathsf{m}} = \underline{f} \ \underline{g} \ \underline{\mathsf{D}} \tag{9}$$

In terms of basic element dimensions and properties, equation (8) becomes

where
$$d = a_k - a_j$$

 $e = b_j - b_k$

Heat Flow Equilibrium Equations

For heat flow equilibrium, the rate at which heat is externally supplied to a region must be equal to the sum of the rate at which heat flows out of the region and the rate at which heat is stored within the region. For a finite element idealization the typical region in which heat equilibrium is required is shown in Figure 4.

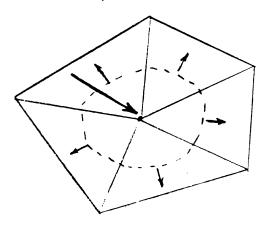


Figure 4 Region for Heat Flow Equilibrium

One-third of the volume of each triangular element is assumed to be associated with each node. Therefore, the approximate rate at which heat is stored in the region of a node will be the product of the time derivative of the temperature, the volume of the region and the specific heat of the material. The rate at which heat flows out of the region is the sum of the element heat flows which can be calculated from equation (10). The application of this procedure in the region of each nodal point yields equation (1); or

$$\underline{CT} + \underline{KT} = \underline{Q} \tag{11}$$

The heat capacity matrix \underline{C} is diagonal and the diagonal terms are given by

Heat Flow Equilibrium Equations (Continued)

$$C_{ij} = \sum \frac{1}{3} c_m V_m$$
 (11b)

where the summation is carried out over all elements attached to nodal point i. The specific heat \boldsymbol{c}_m and volume \boldsymbol{V}_m are associated with a typical element \boldsymbol{m} .

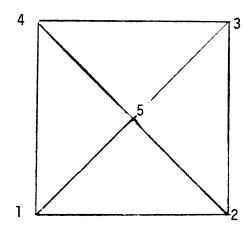
The conductivity matrix \underline{K} is given by the direct summation of element conductivities \underline{K}^{m} or

$$\underline{K} = \Sigma \underline{K}^{\mathbf{m}}$$
 (11c)

This direct summation of element conductivity matrices is similar to the combination of element stiffness matrices in the "direct stiffness" approach to stress analysis.

Quadrilateral Element

Four triangular elements can be combined to form a quadrilateral element as shown below:



The heat capacity term associated with nodal point 5 is assumed to be distributed to the four adjacent nodes. The 5 x 5 element conductivity matrix is reduced to a 4 x 4 matrix by the assumption that there is no external heat flow at node 5. Therefore, the typical term of the 4 x 4 quadrilateral conductivity matrix is given by

$$K_{ij}^* = K_{ij} - \frac{K_{i5}K_{5j}}{K_{55}}$$

This reduction procedure is similar to the "static condensation" method in structural analysis.

Insulated Boundary

The previously developed heat flow equilibrium equations can be modified to reflect surface heat transfer. The rate of heat flow across a boundary layer at the surface of the body is given by the following equation:

$$q = h(T_e - T_s)$$

where q = the rate of heat transferred to the surface element per unit area

h = the heat transfer coefficient for the surface

 T_s = the temperature of the surface

 T_{ρ} = the temperature of the external environment

If we consider a surface element between nodes i and j the rate at which heat is transferred to the nodes will be approximately

$$Q_{i} = \frac{hlt}{2} (T_{e} - T_{i})$$
 (12a)

$$Q_{j} = \frac{h \ell t}{2} (T_{e} - T_{j})$$
 (12b)

where t is the thickness of the element and ℓ is the distance between nodes i and j.

In order to satisfy total heat flow equilibrium at these boundary nodes equations (12a) and (12b) are added to equations (11). This will result in the following modifications to the conductivity and external heat flow matrices:

Insulated Boundary (Continued)

$$K_{ii}^{*} = K_{ii} + \frac{hlt}{2}$$

$$K_{jj}^{*} = K_{jj} + \frac{hlt}{2}$$

$$Q_{i}^{*} = Q_{i} + \frac{ht}{2} T_{e}$$

$$Q_{j}^{*} = Q_{j} + \frac{ht}{2} T_{e}$$

$$(13)$$

This procedure can be applied repeatedly for all insulated boundary elements.

Cooling Pipes -- Normal to Plane

If a cooling pipe is placed at a node point of a finite element system equation (11) can be modified to reflect this type of element.

The exact solution for the temperature distribution near a cooling pipe is shown in Fig. (5). The rate at which heat flows into the solid from the cooling pipe is given by

$$q = -2\pi t k r \frac{\partial T}{\partial r}$$
 (14)

where r is the distance from the center of the pipe, T is the temperature field, h is the conductivity and t is the thickness of the element. If this differential equation is integrated we find

$$q = \frac{2 + kt}{\log \left(\frac{a}{R}\right)} (T_w - T_a)$$
 (15)

where T_a is the temperature at a node point at distance a from the pipe, $T_{\rm W}$ is the temperature of the cooling water and R is the radius of the pipe.

The temperature distribution within the finite elements adjacent to the pipe is assumed to be linear. Therefore the heat flow away from the pipe at distance a/2 is given by

away from the pipe at distance a/2 is given by
$$q = -2\pi t k(\frac{s}{2}) \quad (\frac{a - T_0}{a}) = \pi t k \quad (T_0 - T_a) \quad (16)$$

where T_0 is the apparent temperature at the pipe in the finite element solution.

If equations (15) and (16) are combined and $\boldsymbol{T}_{\boldsymbol{a}}$ eliminated we obtain

$$q = H(T_w - T_a) \tag{17}$$

where

$$H = \frac{2\pi kt}{\text{Log[a]}-2}$$

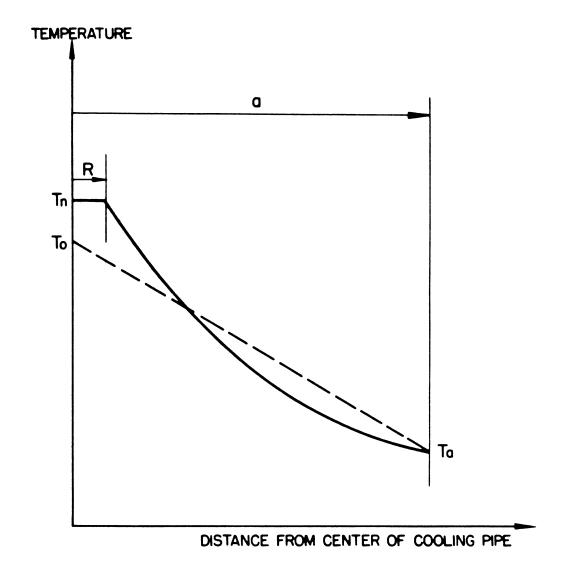


FIGURE 5 TEMPERATURE DISTRIBUTION NEAR COOLING PIPE.

Cooling Pipes -- Normal to Plane (Continued)

It is of interest to note that for an element size "a" of 7.4 times the radius of the pipe $Log \{\frac{a}{R}\} = 2$ and the value of H is infinite; therefore, for this element size the apparent temperature of the node T_0 is equal to cooling water temperature T_w . For other element size the correct value of H can be computed.

As in the case of insulated boundary the heat flow equilibrium equations can be modified to include the effect of a cooling pipe. At a typical nodal point i the following additions must be made to the conductivity and external heat flow matrices:

$$K_{ii}^{\star} = K_{ii}^{} + H$$

$$Q_{i}^{\star} = Q_{i}^{} + HT_{w}^{}$$
(18)

Temperature Boundary Conditions

At certain points in the system, the temperatures may be specified as a function of time. To allow for these boundary conditions, equation (11) is written in the following partitioned form:

$$\begin{bmatrix} \underline{Ca} & 0 \\ 0 & \underline{Cb} \end{bmatrix} \begin{bmatrix} \underline{\dot{T}a} \\ \underline{\dot{T}b} \end{bmatrix} + \begin{bmatrix} \underline{Kaa} & \underline{Kab} \\ \underline{Kba} & \underline{Kbb} \end{bmatrix} \begin{bmatrix} \underline{Ta} \\ \underline{Tb} \end{bmatrix} = \begin{bmatrix} \underline{Qa} \\ \underline{Qb} \end{bmatrix}$$
(19)

where \underline{Qa} , \underline{Tb} , and $\underline{\dot{T}b}$ are specified and \underline{Qb} and \underline{Ta} are the unknowns in the system. Equation (11a) may be rewritten as

$$\underline{Ca} \quad \underline{Ta} + \underline{Kaa} \quad \underline{Ta} + \underline{Q} \qquad (20)$$

where

$$Q = Qa - Kab Tb$$
 (21)

Equation (20) is now in a form which can be solved for the unknown nodal point temperatures. The matrix <u>Kaa</u> is always symmetric and positive-definite, and in most cases, it can be placed in band form. Therefore, large systems can be stored in most computers.

The Step-by-Step Solution Technique

Equation (20) is a set of first order linear differential equations which can be solved by a step-by-step method. At time "t" this set of equations is of the form

$$\underline{C} \, \dot{T}_t + \underline{K} \, T_t = Q_t \tag{22}$$

If the solution is known at the previous step in time $t-\Delta t$ and if the temperature at each node is assumed to vary linearly within the increment of time, the rate of change in temperature, \dot{T} , is given by

$$\dot{T}_{t} = \frac{1}{\Delta t} \left(T_{t} - T_{t-\Delta t} \right) \tag{23}$$

The substitution of equation (23) into equation (22) yields:

$$\underline{K}^* \underline{T}_t = \underline{Q}_t^* \tag{24}$$

where

$$\underline{K}^{*} = \underline{K} + \frac{1}{\Delta t} \underline{C}$$

$$\underline{Q}_{t}^{*} = \underline{Q}_{t} + \frac{1}{\Delta t} \underline{C} \underline{T}_{t-\Delta t}$$

Equation (24) can now be solved directly for the temperature at the end of the time increment. Since \underline{K}^* is not a function of time it can be formed once for a given geometry and triangularized. This triangularized matrix then can be used efficiently at each increment of time with different thermal load vector $\mathbb{Q}_{\mathbf{t}}^*$. The complete solution procedure is summarized in Table I.

TABLE I

SUMMARY OF STEP-BY-STEP SOLUTION METHOD

INITIAL CALCULATIONS

1. Form C and K

Eq. (11)

2. Modify for insulated boundaries and cooling pipes

Eqs. (13) and (18)

3. Modify for temperature boundary conditions

Eq. (21)

4. Form <u>K</u>*

$$\underline{K}^* = \underline{K} + \frac{1}{\Delta t} \underline{C}$$

5. Triangularize K*

FOR EACH TIME INCREMENT

1. Calculate Q*

Eq. (24)

$$Q^* = Q + \frac{1}{\Delta t} C T_{t-\Delta t}$$

2. Evaluate \underline{T}_t by solving

$$\underline{K}^* \underline{T}_t = \underline{Q}^*$$

3. Repeat for next time increment.

EXAMPLES

The validity of the finite element approach as applied to heat conductions has been demonstrated previously; therefore, comparison of the method with theoretical solutions will not be given. Only Examples of the method will be given.

Temperature Distribution During Incremental Construction

This example was selected to compare results of the present method with results of a finite difference method used by the Walla Walla District. The finite element idealization of the region to be studied is shown in figure 6. The temperatures at point A shown as a function of time are plotted in figure 7. The reason for the difference in the two techniques is because of the method used in the idealization of the cooling pipes. In the finite difference program the temperature of the node associated with the cooling pipe was set equal to the water temperature. This approach appears to be without theoretical justification since the diameter of the pipe is not taken into account. The results associated with the finite element program are based on a consistent idealization of the cooling pipe.

Calculation of Stresses From Temperatures

The temperature distribution obtained from the heat transfer program can be supplied to a finite element program for the evaluation of stresses as a function of time (2). This approach would be time-

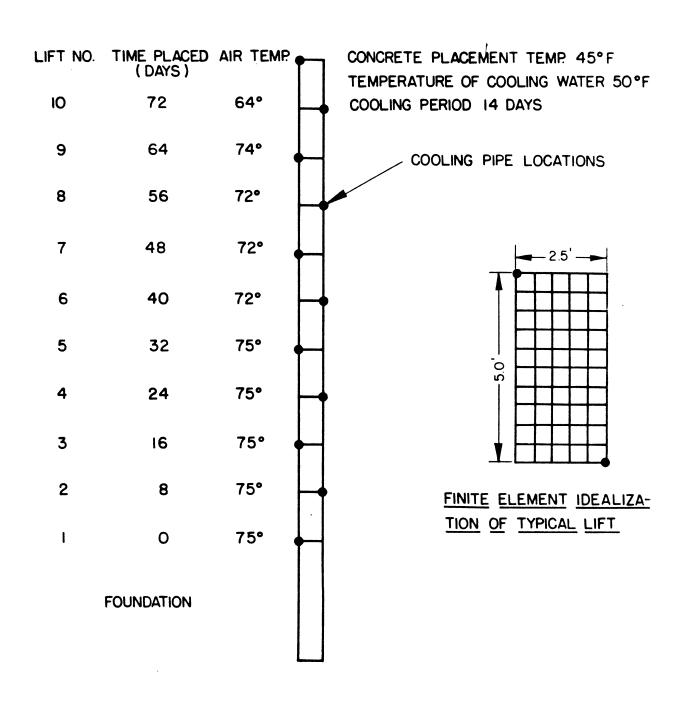


FIGURE 6 - EXAMPLE OF INCREMENTAL CONSTRUCTION

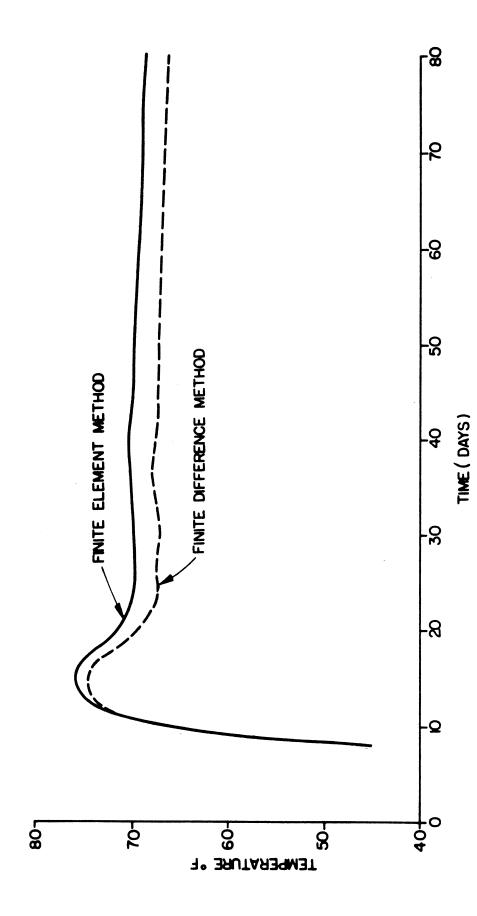


FIGURE 7 TEMPERATURE AT TOP OF LIFT NO. 2

Calculation of Stresses From Temperatures (Continued)

consuming and unnecessary for most mass concrete problems. An approximate method for the calculation of thermal stresses in confined mass concrete structures has been developed (3) and will be summarized here.

The maximum tensile stresses developed in a concrete structure constructed incrementally are generally near a lift surface and are in the horizontal direction. The change in the horizontal stress $\Delta\sigma$ at a point due to an instantaneous temperature change may be approximated by

$$\Delta \sigma = E \alpha \Delta T$$

where α is the thermal coefficient of expansion and E is the instantaneous modulus of elasticity. Of course, this is true only for this type of structure and because the concrete locally is in approximately a confined state. This incremental stress will relax with time, and its magnitude can easily be predicted. Tables 2 and 3 show stress histories for a one-degree (F) temperature drop applied at different ages for two different concrete mixes. These tables were computer generated and include the effects of the variation of modulus of elasticity with time.

With the aid of a table of this type, it is possible to predict readily the horizontal stresses as a function of time when the concrete is subjected to a known temperature history. In order to calculate the stress at any time, the effect of all the daily temperature changes must be added. Thus, if ΔT_1 , ΔT_2 --- and ΔT_m are the daily temperature changes which occur up to m days and C_{1m} , C_{2m} , --- and C_{mm} are the temperature stress influence coefficients for a concrete age of m days, then the total stress at age m is given by

TABLE 2 - Temperature Stress Influence Coefficients

	93	0	1.720	2.158	5.509	2.901	3.312	3.763	4.235	969.	5.162	5.609	6.012	6.451	6.938	7.395	7.801	8.232	8.693	9.143	9.576	10.032	10.515	11.006	11.512	12.07	12.740	13.646	15.148
	53	0	1.742	2.194	2.558	2,962	3.383	3.844	4.324	4.792	5.262	5.714	6.122	6.568	7.060	7.523	7.937	8.375	8.843	9.305	9.745	10.213	10.709	11.223	111.771	12,421	13.303	14.766	17.753
	28	0	1.764	2.232	5.609	3.026	3.459	3.928	4.416	4.891	5.366	5.823	6.238	6.690	7.188	7.657	8.078	8.524	000.6	9.₩6	9.923	10,405	10.992	11.475	12.109	12.970	14.398	17.317	24.217
	27	٥	1.787	2.271	2.663	3.093	3.537	4.016	4.512	\$	5.474	5.938	6.359	6.817	7.320	7.796	8.226	8.680	9.16	9.642	10.112	10.615	11.169	11.804	12.644	14.038	16.889	23.641	
	98	0	1.811	2.312	2.718	3.163	3.619	4.108	4.613	5.101	5.587	6.057	6.485	6.949	7.459	7.942	8.380	8.844	9.337	9.858	10.318	10.858	11.492	12.325	13.685	16.467	23.065		
	25	٥	1.837	2.355	2.776	3.236	3.704	4.204	4.718	5.213	5.705	6.181	6.617	7.088	7.604	8.09	8.545	9.015	9.520	10.030	10.557	11.175	12.001	13.339	16.052	22.489			
	77	0	1.963	2.399	2.837	3.313	3.793	4.304	4.827	5.330	5.828	6.311	6.754	7.232	7.755	8.253	3.711	9.197	9.719	10.263	10.867	11.674	12.990	15.642	21.913				
	23	0	1.891	2.446	2.900	3.392	3.885	4.408	4.941	5.451	5.957	6.447	6.837	7.383	7.913	8.420	8.891	9.395	9.950	10.567	11.355	6£9:टा	15.231	21.336					
	25	0	1.919	2.494	2.966	3.475	3.982	4.517	5.060	5.578	6.091	6.588	7.047	7.540	8.078	8.597	9.086	9.623	10.249	11.043	15.295	14.820	20.760						
	21	0	1.49	2.544	3.035	3.561	4.083	4.630	5.184	5.710	6.230	6.735	7.203	7.706	8.254	8.789	9.311	9.918	10.715	m	14.414	20,184	· ·						
	50	0	1.980	2.597	3.107	3.650	4.187	4.743	5.313	5.848	6.375	6,889	7.366	7.981	8.445	9.010	3.602	10.378	11.608	14.013	19.608 1								
	19	0	2.013	2.652	3.181	3.744	7.296	4.870	5.447	5.991	6.527	7.050	7.539	8.070	8.663	9.295	10.050	11.248	13.603	19.032	_								
3 (g	18	0	2.046	2.708	3.258	3.941	4.410	4.998	5.587	6.141	989.9	7.220	7.727	8.288	8.944	9.732	10.898	13.185	18.456										
SCY Concrete	17	0	2.031	2.767	3.339	3.942	4.523	5.130	5.732	6.297	6.923	7.404	7.91	8.565	9.373	10.556	12.775	17.879											
P. C.	16	0	2.118	2.859	3.422	4.047	4.650	5.268	5.885	6.462	7.034	7.614	8.213	8.988	10.178	_	17.303												
	15	0	2.155	2.892	3.509	4.155	4.777	5.412	6.045	6.640	7.240	7.880	8.626	9.773	11.938	16.727													
(2.75	14	0	2.194	2.958	3.598	4.268	4.910	5.563	6.217	6.841	7.500	8,280	9.388	11.484	16.151														
	13	0	2.234	3.026	3.691	4.385	5.049	5.726	6.411	7.04	7.889	9.016	11.043	15.575															
	12	0	2.276	3.096	3.787	4.507	5.198	5.910	959.9	7.473	8.604	10.613	14.998																
	11	0	2.318	3.168	3.885	4.639	5.367	6.142	7.022	8.167	10.152	14.422																	
	10	0	2.362	3.244	3.995	4.787	5.580	6.490	7.693	699.6	13.846																		
	6	0	2,408	3.354	4.116	4.975	5.903	7.136	9.153	13.270																			
	æ	0	2.457	3.415	4.271	5.264	6.512	9.56	12.69																				
	7							12.118																					
	9						11.464																						
	2					10.676																							
	.7				9.686																								
	~			8.36																									
		0	6.3																										
	1	٠ .	٥.	<u>.</u>	-	. 5	9.	-	٠	6.	01	<u> </u>	ä	£.	7.	-15	91-	-17	81.	-13	0,-	-21	-55	-23	₹.	.55	25-36	.27	-58
	l	Ó	-	~	<u></u>	. 	<u>ښ</u>	ف	-						<u> </u>								<u>র</u>	25	Ś	₹.	Ŕ	×6	27-28

TABLE 3 - Temperature Stress Influence Coefficients

2.118 3.110 3.110 4.526 4.533 5.333 5.703 6.818 7.721 7.721 8.566 8.989 9.440 9.440 9.440 9.440 11.340 11.340 11.893 11.341 11.893 2.346 2.360 2.360 3.178 3.178 4.612 5.021 5.021 5.021 5.020 6.529 6.529 6.529 6.529 6.529 6.529 6.529 6.529 17.363 10.039 10.039 10.039 11.655 11.3099 11.3099 2.176 2.260 2.360 3.248 3.248 3.248 4.297 4.297 4.297 7.043 7.043 7.043 7.043 9.728 9.264 9.728 11.216 11 2.206
2.206
2.506
2.507
3.320
3.320
3.320
5.510
5.510
6.008
6.369
6.369
6.753
7.163
7.163
8.966
9.409 10.370 10.889 11.523 12.424 13.942 13.942 17.126 2.236 2.236 3.393 3.393 3.393 3.393 3.393 5.718 6.116 6.116 6.118 6.118 8.219 8.683 9.109 9.109 9.109 9.109 11.187 11.1 % 2.268 3.040 3.040 3.168 4.565 4.565 7.410 5.823 6.225 6.225 6.225 7.400 7.400 7.400 7.400 9.728 8.352 8.352 10.254 10.254 10.254 10.254 10.254 10.254 10.254 10.254 10.254 10.254 10.254 10.254 10.255 10.255 10.255 10.256 10.2 2.300 2.733 3.102 3.545 4.118 4.118 5.084 5.084 5.931 6.713 7.112 7.112 8.489 8.969 2.733 3.167 3.168 3.684 4.1686 5.618 5.618 5.618 7.737 7.737 7.737 7.737 7.737 7.737 7.737 7.749 2.366 2.865 3.704 4.853 5.288 5.786 6.570 6.956 6.956 7.365 7.365 7.365 9.314 9.319 9.314 9.319 2.400 3.295 3.787 4.388 4.953 5.393 5.836 6.690 7.081 7.081 7.081 7.081 7.081 8.973 9.573 10.337 11.665 14.496 21.372 2.435 2.921 3.362 3.362 3.3870 4.482 5.505 5.506 5.948 6.385 6.385 6.385 8.607 7.211 7.635 8.607 8.607 10.017 11.305 10.017 2.471 3.430 3.430 3.430 5.159 6.062 6.062 6.303 7.346 7.784 8.272 8.252 2.507 3.021 3.502 4.603 5.266 5.721 6.180 6.629 7.707 7.491 7.491 7.958 8.514 8.514 9.514 Concrete) 2.544 3.073 3.571 4.132 5.376 5.336 6.737 7.211 7.211 7.211 7.211 7.211 7.211 7.211 7.211 7.211 7.211 7.211 7.211 3.125 3.643 3.643 4.222 5.484 5.952 6.894 7.375 7.888 8.592 9.793 12.330 SCY OF. 2.620 3.178 3.716 4.314 1.978 5.597 6.559 7.053 7.759 9.430 11.889 3.25 2.659 3.232 3.731 4.407 5.084 5.714 6.202 6.722 7.266 7.967 7.967 7.967 11.464 3.287 3.287 3.867 4.503 5.193 5.839 6.351 6.919 7.627 8.749 11.051 3.343 3.344 1.602 5.309 5.983 6.551 7.268 8.385 10.651 16.186 2.779 3.400 4.025 4.708 5.444 6.175 6.388 8.002 10.227 2.821 3.459 4.111 4.829 5.624 6.497 7.535 9.784 15.034 3.522 4.210 1.393 5.929 7.175 9.320 2.909 3.595 4.346 5.273 6.578 8.843 2.362 3.700 4.596 5.880 9.202 13.306 3.039 3.892 5.128 7.439 3.130 4.355 6.582 11.964 3.573 5.661 0.874 4.669 9.543 TIME OF LOADING - ONE DECREE F DECREASE

Calculation of Stresses From Temperatures (Continued)

$$\sigma_{m} = \Delta T_{1}C_{1m} + \Delta T_{2}C_{2m} + ---- \Delta T_{m}C_{mm}$$

$$\sigma_{r}$$

$$\sigma_{m} = \frac{m}{i=1} \Delta T_{i}C_{im}$$

Therefore, it is possible to calculate an approximate stress history for different placement and cooling schedules without the use of a complex digital computer program. Of course, this approximate technique may be applied only because the mass concrete is highly confined in the vicinity of the closely spaced cooling pipes.

The temperature history near the top of lift No. 2, Temperature Study No. 2, has been selected to illustrate the use of the approximate method (3). The temperature history for this case is shown in Fig. 8. The resulting approximate horizontal stresses versus time are shown in Fig. 9. For this case a typical calculation for the stress at age nine days is shown below:

DAY	TEMPERATURE (°F)	TEMP. DROP Δ ^T i	^C 19	^{Δσ} 9 ^{=ΔΤ} i ^C i9
0 1 2 3 4 5 6 7 8 9	45 70.5 73.1 74.4 75.1 75.5 75.5 75.5 75.4	-25.5 - 2.6 - 1.3 - 0.7 - 0.4 0 0 + 0.1 +13.3	0 2.863 3.522 4.210 4.993 5.929 7.175 9.320 14.458	0 - 7.5 - 4.6 - 2.9 - 2.0 0 + 0.9 +192.3
			$\sigma_9 = \sum_{i=1}^{9} \Delta T_i C_{i9} =$	+176.2

<u>Calculation of Stresses From Temperatures</u> (Continued)

The approximate nine-day stress of 176 psi agrees very well with the 168 psi obtained by the finite element analysis. As indicated by Fig. 9, comparison of the two methods is reasonable for the entire temperature history.

To illustrate the approximate method further, two hypothetical temperature histories were studied and are illustrated in Fig. 10.

Temperature History A represents typical behavior of surface concrete which is placed and exposed to 75°F atmospheric condition. Temperature History B represents a concrete which is surface-insulated for the first 7 days; therefore, the temperature change is essentially adiabatic. Fig. 11 illustrates the resulting horizontal stresses. In this case, the superiority of Temperature History B is clearly illustrated. Approximately one hour of hand calculation was required for this comparison. If, however, these tables were incorporated into the heat transfer program, these simple stress calculation could be conducted within a single computer program.

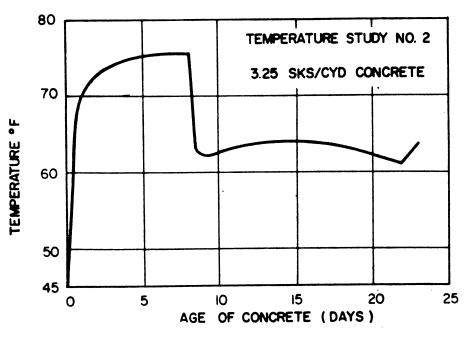


FIGURE 8 - TEMP. HISTORY NEAR TOP OF LIFT NO. 2

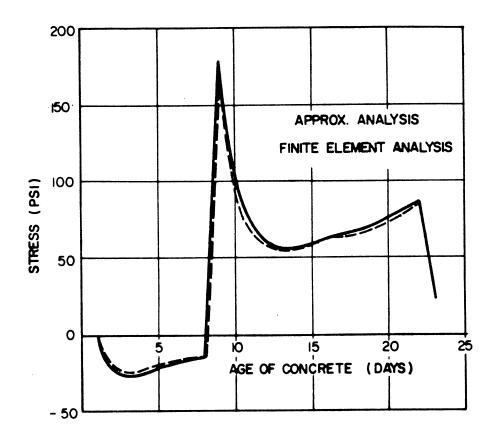


FIGURE 9 - HORIZONTAL STRESSES NEAR TOP OF LIFT NO. 2

- 30 -

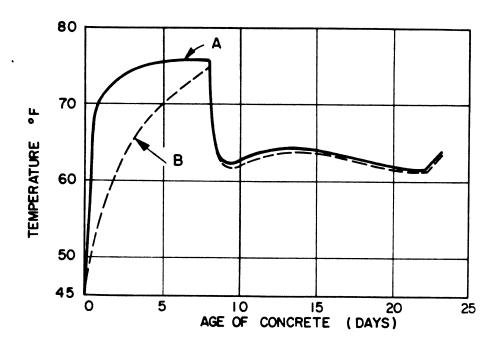


FIG. 10 HYPOTHETICAL TEMP. HISTORIES

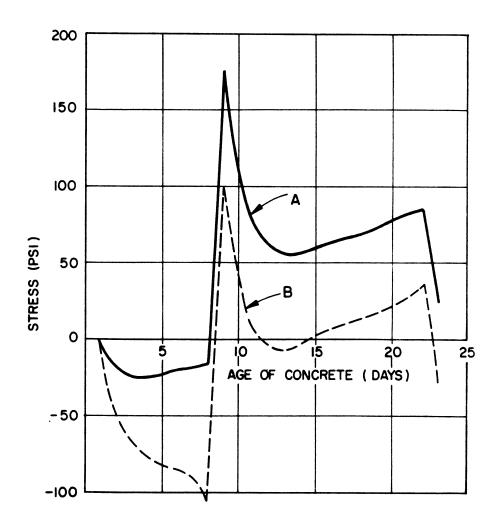


FIG. II STRESSES DUE TO HYPOTHETICAL TEMP. HISTORIES

- 31 -

FINAL REMARKS

A computer program which is based on the method of analysis presented in this report has been developed. A description on the use of this program and a Fortran IV listing is given in the Appendices of this report. The program is developed with particular reference to mass concrete structure of arbitrary geometry and construction sequence; however, it may be applied to many different types of problems involving time-dependent boundary conditions.

REFERENCES

- Wilson, E.L. and Nickell, R.E. "Application of the Finite Element Method to Heat Conduction Analysis", Nuclear Engineering and Design, Vol. 4 1966, pp. 276 - 286.
- Sandhu, R.S., Wilson, E.L. and Raphael, J.M. "Two-Dimensional Stress Analysis with Ineremental Construction and Creep", University of California Structural Engineering Laboratory Report No. 67-34, December 1967.
- 3. Raphael, J.M. and Wilson, E.L., "Maximum Temperature Stresses in Dworshak Dam", University of California Structural Engineering Laboratory Report 67-14, July 1967.

APPENDIX A DESCRIPTION OF INPUT DATA FOR COMPUTER PROGRAM

DESCRIPTION OF INPUT DATA FOR COMPUTER PROGRAM

The purpose of this computer program is to determine the temperature distribution as a function of time within a concrete structure as it is being constructed. Each lift of the structure may be placed at an arbitrary time and temperature. Insulation forms may be placed or removed from the concrete surfaces at any point in time. The external air temperature and temperature of the cooling water may also vary with time.

GENERAL INPUT DATA

The first step in the analysis is to select a finite element representation for the complete structure. All elements and nodal points are then numbered in two numerical sequences each starting with one. The following group of punched cards numerically defines the complete structure to be analysed:

A. <u>Identification Card - (72H)</u>

Columns 1 to 72 of this card contain information to be printed with results.

B. Control Card (515)

- Columns 1 5 Total number of nodal points
 - 6 10 Total number of elements
 - 11 15 Number of different materials
 - 16 20 Number of adiabatic temperature cards for each material
 - 21 25 Number of cards which describe the external temperature environment

GENERAL INPUT DATA (Continued)

C. Nodal Point Cards - (15, 5X, 3F10.0)

One card for each nodal point with the following information:

Columns 1 - 5 Nodal point number

11 - 20 X-ordinate

21 - 30 Y-ordinate

31 - 40 Temperature (for foundation points only)

Nodal point cards must be in numerical sequence. If cards are omitted, the omitted nodal points are generated at equal intervals along a straight line between the specified nodal points.

D. <u>Element Cards - (615, F10.0)</u>

One card for each element

Columns 1 - 5 Element number

6 - 10 Nodal point I

11 - 15 Nodal point J

16 - 20 Nodal point K

21 - 25 Nodal point L

26 - 30 Material identification number

31 - 40 Time of placement

Nodal point numbers (I,J, K and L) must be in counterclockwise order around each element. Maximum difference between nodal point numbers must be less than 27.

Element cards must be in element number sequence. If element cards are omitted, the program automatically generates the omitted information by incrementing the preceding I,J,K and L. The

GENERAL INPUT DATA (Continued)

information in column 26 to 40 for the generated cards is set equal to the values given on the preceding card. The last element card must always be supplied.

Triangular elements are also possible and are identified by repeating the last nodal point number (i.e., I, J, K, K).

E. Material Property Information

The following group of cards must be supplied for each different material.

First Card (115, 5X, 4F10.0)

Columns 1 - 5 Material identification number

11 - 20 Conductivity of material

21 - 30 Specific heat of material

31 - 40 Density of material

41 - 50 Time after placement when heat generation ceases

Adiabatic Temperature Cards (2F10.0)

Columns 1 - 10 Time

11 - 20 Temperature

The total number of these cards is specified in columns 16 to 20 of the control card.

F. External Temperature Environment Information (2F10.0)

The external temperature is specified at discrete points in time by a sequence of cards of the following form:

Columns 1 - 10 Time

11 - 20 External Temperature

The number of these cards is specified in columns 21 to 25 of the control card.

LIFT DATA

It is assumed that the structure does not exist at time zero. When a change takes place in the geometry of the structure, or the number of insulating elements, or the number and temperature of the cooling pipes, new lift data must be supplied.

A. Lift Data Control Card (615, 3F10.0)

Columns 1 - 5 Number of nodal points to be considered

6 - 10 Number of elements to be considered

11 - 15 Number of insulating elements to be added

16 - 20 Number of cooling pipes to be added

21 - 25 Number of time increments in time span

26 - 30 Output interval for print of temperatures

31 - 40 Time increment to be used in time span

41 - 50 Time at the beginning of time span

51 - 60 Placement temperature for all elements which are placed at the beginning of time span.

B. <u>Insulating Element Cards (215, 2F10.0)</u>

One card must be supplied for each surface element which is added to the system. The behavior of the surface element is governed by the following heat transfer equation:

$$q = h(T_e - T_s)$$

where

q = the rate of heat transferred to the surface element per unit of area

h = the heat transfer coefficient for the surface

 T_s = the temperature of the surface

 T_{ρ} = the temperature of the external environment

LIFT DATA (Continued)

Each card contains the following information:

Columns 1 - 5 Nodal point number I

6 - 10 Nodal point number J

11 - 20 Surface heat transfer constant h

21 - 30 Time when insulative element is to be removed

If the surface constant h is zero the previously defined insulating element associated with points I and J will be removed.

C. Cooling Pipe Cards (115, 5X, 3F10.0)

One card must be supplied for each cooling pipe which is added to the system. The rate at which heat, Q, is removed by the cooling pipe is given by the following equation:

$$Q = H (T_D - T_W)$$

where

H = an empirical constant

 T_p = the temperature in the concrete near the pipe

 T_w = the emperature of the cooling water

Each card contains the following information:

Columns 1 - 5 Nodal point number which defines the location of the pipe

11 - 20 Constant H

21 - 30 Temperature of cooling water

31 - 40 Time when cooling is to be stopped.

If the constant H is zero the previously defined cooling pipe at the specified nodal point is removed.

APPENDIX B

FORTRAN IV LISTING OF COMPUTER PROGRAM

```
PROGRAM MAIN(INPUT, OUTPUT, TAPES = INPUT, TAPE6 = OUTPUT)
C
     COMMON
              NUMEL, NCBH, NCPH, NUMMAT, NDT, INTER, DT, TIME, NUMNP, NUME,
       NUMQC, NUMET, PLTIME, R(500), X(500), Y(500), T(500), D(500), TT(500),
       1X(400,5),PLTM(400),VOL(400),HFD(12),LM(5),F(3,3),KX(4),S(5,5),
       XCOND(20),5PHT(20),DENS(20),QX(20,2,20),HSTOP(20),ET(20,2),
       1C(20), JC(20), HC(20), TMC(20), CL(20), IP(20), HP(20), TP(20), TMP(20)
     COMMON /SYMARG/ NUMN, MBAND, A (500, 27), Q (500)
READ AND PRINT OF CONTROL INFOMATION
C
HED, NUMNP, NUMEL, NUMMAT, NUMQC, NUMET
   50 RFAD
           (5,1000)
     WRITF (6,2011)
   58 WRITE (6,2000) HED, NUMNP, NUMEL, NUMMAT, NUMQC, NUMET
     READ OR GENERATE NODAL POINT INFORMATION
^******************************
     WRITE (6,2001)
     L=1
                     N, X(N), Y(N), TT(N)
   60 RFAD
          (5,1001)
      DIFF=N+1-L
      IF (N-L) 65,80,70
   65 WRITE (6,2020) N
     GO TO 60
   70 DX=(X(N)-X(L-1))/DIFF
      DY=(Y(N)-Y(L-1))/DIFF
      DP=(TT(N)-TT(L-1))/DIFF
   75 X(L)=X(L-1)+DX
      Y(L)=Y(L-1)+DY
      TT(L) = TT(L-1) + DP
   80 WRITE (6,2002) L,X(L),Y(L),TT(L)
      L=L+1
      IF (N-L) 90,80,75
   90 IF (NUMNP+1-L) 100,100,60
  100 CONTINUE
       READ AND PRINT OF ELEMENT PROPERTIES
      WRITE (6,2003)
      N = \cap
  103 READ (5,1002) M, (IX(M, I), I=1,5), PLTM(M)
  104 N=N+1
      IF (M-N) 107,107,105
  105 IX(N,1)=IX(N-1,1)+1
      IX(N,2) = IX(N-1,2)+1
      IX(N,3) = IX(N-1,3)+1
      IX(N,4) = IX(N-1,4)+1
      IX(N.5) = IX(N-1.5)
      PLTM(N)=PLTM(N-1)
  107 WRITE (6,2004) N,(IX(N,I), T=1,5),PLTM(N)
      IF (M-N) 108,108,104
  108 IF (NUMFL-N) 109,109,103
  109 CONTINUE
C
```

```
DO 115 N=1,20
     TMC(N) = 0.0
  115 TMP(N)=0.0
READ AND PRINT MATERIAL PROPERTIES AND ENVIRONMENT TEMP
\boldsymbol{C}
C*****************************
     DO 120 M=1.NUMMAT
     RFAD (5,1001) MT,XCOND(MT),SPHT(MT),DENS(MT),HSTOP(MT)
     WRITF(6,2018) MT
     WRITE(6,2006) MT, XCOND(MT), SPHT(MT), DENS(MT), HSTOP(MT)
     WRITE(6.2007)
     READ (5,1008)
                   ((QX(t,J,MT),J=1,2),t=1,NUMQC)
     WRITE(6,2008) ((QX(T,J,MT),J=1,2),T=1,NUMQC)
  120 CONTINUE
     IF(NUMET.FQ.O) GO TO 125
     RFAD (5,1008) ((FT(I,J),J=1,2),I=1,NUMFT)
     WRITF(6,2012) ((FT(I,J),J=1,2),I=1,NUMFT)
C
     FOR FACH INTERVAL OF TIME--SEVERAL TIME STEPS
125 TIME=0.0
     NCBH=0
     NCPH=0
     DO 130 N=1.NUMNP
  130 T(N)=0.0
\mathsf{C}
\mathsf{C}
     READ AND PRINT OF LAYER PROPERTIES
150 READ (5,1004) NUMN, NUME, NUMER, NUMER, NOT, INTER, DT, PLTIME, PLACET
     IF(NUMN.EQ.O) STOP
     WRITE(6,2005) NUMN, NUME, NUMCB, NUMCP, NDT, INTER, DT, PLTIME, PLACET
\boldsymbol{\mathsf{C}}
C
     ELIMINATE ALL INSULATING ELEMENTS AND COOLING PIPES WITH REMOVAL
\mathsf{C}
     TIME LESS THAN PLACEMENT TIME AND READ ADDITIONAL ONES
\mathbf{C}
     KK=n
     00 155 N=1,NCRH
     TECTMC(N).LF. PLTIME) GO TO 155
     KK = KK + 1
     IC(KK) = IC(N)
     JC(KK)=JC(N)
     HC(KK) = HC(N)
     TMC(KK) = TMC(N)
     CL(KK)=CL(N)
  155 CONTINUE
     NCBL=KK+1
     NCBH=KK+NUMCB
     IF(NUMCB.EQ.O) GO TO 160
     READ (5,1005) (IC(N), JC(N), HC(N), TMC(N), N=NCRL, NCRH)
     WRITF(6,2013) (IC(N), JC(N), HC(N), TMC(N), N=NCRL, NCRH)
 160 KK=0
     DO 165 N=1.NCPH
     TF(TMP(N).LF.PLTIMF) GO TO 165
     KK=KK+1
     IP(KK) = IP(N)
```

```
HP(KK) = HP(N)
       TP(KK) = TP(N)
       TMP(KK) = TMP(N)
  165 CONTINUE
       NCPL=KK+1
       NCPH=KK+NUMCP
       IF(NUMCP.EQ.O) GO TO 170
       READ (5,1006) (IP(N), HP(N), TP(N), TMP(N), N=NCPL, NCPH)
      WRITE(6,2014) (IP(N), HP(N), TP(N), TMP(N), N=NCPL, NCPH)
\boldsymbol{C}
C
      CHECK INCONSISTENCY OF LIFT INFORMATION AND REMOVAL OF INSULATING
C
      ELEMENTS AND/OR COOLING PIPES
170 KK=0
      YY=DT*NDT
      IF (NCBH. EQ. 0) GO TO 201
      DO 200 N=1,NCBH
      XX=TMC(N)-PLTIME
       IF(XX.LT.YY) KK=1
  200 CONTINUE
  201 IF(NCPH.FQ.0) GO TO 208
      DO 205 N=1,NCPH
      XX=TMP(N)-PLTIME
      IF(XX.LT.YY) KK=1
  205 CONTINUE
  208 IF(KK.NF.O) WRITE(6,2019)
      SET ALL NEW NODES TO PLACEMENT TEMPERATURE AND CONTACT SURFACE AT
\boldsymbol{C}
C
      AVERAGE TEMPERATURES
      DO 210 I=1.NUMN
      B(I)=0.0
  210 Q(I) = 0.0
      DO 220 N=1, NUME
      IF(PLTM(N).GT.PLTIME) GO TO 220
      DO 215 I=1,4
      II = IX(N, I)
      IF(PLTM(N).FQ.PLTIMF) R(II)=R(II)+PLACET
      IF(PLTM(N).LT.PLTIMF) R(II)=R(II)+T(II)
  215 Q(II) = Q(II) + 1.0
  220 CONTINUE
      DO 230 N=1, NUMN
      IF(Q(I).EQ.0.0) GO TO 230
      T(N) = B(N)/Q(N)
  230 CONTINUE
C
      CALL LAYER
      GO TO 150
C***
\mathbf{C}
C
      FORMAT STATEMENTS
 1000 FORMAT (1246/515)
 1001 FORMAT (15,5X,4F10.0)
 1002 FORMAT (615,F10.0)
```

```
1003 FORMAT (110,4F10.0)
1004 FORMAT(615,3F10.0)
1005 FORMAT(215,2F10.0)
1006 FORMAT(15,5X,3F10.0)
1008 FORMAT(2F10.0)
2000 FORMAT (1HO 12A6// 25HONUMBER OF NODAL POINTS-- 14/
   1 25H NUMBER OF ELEMENTS----- I4 /25H NUMBER OF MATERIALS---- I4/
    2 25H NUMBER OF QQ CARDS----- 14 /25H NO OF EXT TEMP CARDS---- 14)
2001 FORMAT (10HO N.P. N). 14X,1HX,14X,1HY,11X,4HTFMP)
2002 FORMAT (1110,3E15.6)
                                  K L MATERIAL PLACEMENT TIME)
2002 FORMAT (51H0
                  N
                             J
2004 FORMAT (515,110,F16.4)
2005 FORMAT (1H1 / 25HONUMBER OF NODAL POINTS-- 14/
    1 25H NUMBER OF ELEMENTS---- I4 / 25H NUMBER OF CONVECTION BC-I4/
    2 25H NUMBER OF COOLING PIPE-- 14 / 25H NUMBER OF INCREMENTS----14/
    3 25H OUTPUT INTERVAL----- 14 / 20H TIME INTERVAL---- E10.3/
   4 25H BEGINNING TIME---- FR.2/25H PLACEMENT TEMPERATURE---
    5 F8.21
                   M, 11x, 4HCOND, 11x, 4HSPHT, 11x, 4HDFNS, 4x, 26HTTMF HFAT
2006 FORMATIGHO
    1GENERATION STOPS/(16.3F15.6,F30.5))
2007 FORMAT(43HOADIARATIC TEMPERATURE RISE OF THE MATERIAL/ 9HO
                                                                  TIME
    1 4X,11HTEMPERATURE)
2008 FORMAT(F9.2,F15.6)
2009 FORMAT (440 M 14x 14K 14x 14C 14x 14D 14x 14Q/ (14,4F15.6))
2011 FORMAT (27H1TWO DIMENSIONAL PLANE BODY )
2012 FORMAT (31HOTEMPERATURE OF THE ENVIRONMENT) 9HO
    1 11HTEMPERATURE/(E9.2,F15.61)
2013 FORMAT(20HOINSHLATING FLEMENTS//5H
                                                                   TIME
                                                  J,14x,1HH,15H
                                         т,5н
    1 REMOVED/(215,2F15,6))
                                                                 TEMPER
2014 FORMAT(25HONFTAILS OF COOLING PIPES//5H T,14X,1HH,15H
    1ATURF,15H
               TIME REMOVED/(15,3F15.6))
2018 FORMAT(1H0,4X,15HMATERIAL TYPE -,13)
                                     WARNING ONLY/7X,76HNEW LIFT DATA
2019 FORMAT (35HO**** FRROR MESSAGE
    IIS NOT SUPPLIED EVEN THOUGH A CHANGE HAS OCCURED IN INSULATING!
    2 7X.52HELEMENTS AND/OR COOLING PIPES. CALCULATION PROCEEDS)
2020 FORMAT (10HOCARD ND. 14, 12H OUT OF DROFR )
2021 FORMAT (13HORAD CARD NO. 14)
     END
```

```
SUBROUTINE LAYER
      COMMON
                NUMEL, NCBH, NCPH, NUMMAT, NDT, INTER, DT, TIME, NUMNP, NUME,
        NUMQC, NUMET, PLTIME, R(500), X(500), Y(500), T(500), D(500), TT(500),
        IX(400,5), PLTM(400), VOL(400), HFD(12), LM(5), F(3,3), KX(4), S(5,5),
        XCOND(20), SPHT(20), DENS(20), QX(20,2,20), HSTOP(20), FT(20,2),
        IC(20), JC(20), HC(20), TMC(20), CL(20), IP(20), HP(20), TP(20), TMP(20)
      COMMON /SYMARG/ NUMN, MBAND, A (500, 27), Q (500)
C***************
      FORM CONDUCTIVITY MATRIX FOR COMPLETE BODY
DO 130 I=1, NUMN
      D(I) = 0.0
      B(I) = 0.0
      Q(I)=0.0
      DO 130 J=1,27
  130 A(I,J)=0.0
      MBAND=0
      ISTOP=0
\mathsf{C}
      DO 200 N=1 , NUME
      IF(PLTM(N).GT.PLTIME) GO TO 200
      MTYPE=IX(N.5)
      COND=XCOND(MTYPE)
C
\mathsf{C}
        >. FORM ELEMENT CONDUCTIVITY MATRIX
\mathbf{C}
      DO 150 I=1.5
      LM(I) = IX(N,I)
      DO 150 J=1.5
  150 S(I,J)=0.0
      I = LM(1)
      J=LM(2)
      K=LM(3)
      L=LM(4)
      LM(5)=I
\mathsf{C}
      XX = (X(I) + X(J) + X(K) + X(L)) / 4.
      YY = (Y(I) + Y(J) + Y(K) + Y(L)) / 4.
      VOL(N)=n.n
\boldsymbol{\mathsf{C}}
      DO 152 K=1,4
C
      I = LM(K)
      J=LM(K+1)
      IF (I-J) 135,152,135
  135 AJ=X(J)-X(I)
      AK = XX - X(I)
      BJ=Y(J)-Y(I)
      BK=YY-Y(I)
      C=BJ-BK
      DX=AK-AJ
C
      XLAM=AJ*BK-AK*BJ
```

```
IF(XLAM.GT.0.0) GO TO 136
      ISTOP=1
      WRITF(6,2003) N = 1
  136 VOL(N)=VOL(N)+XLAM*O.5
      COMM=.5*COND/XLAM
\mathsf{C}
      E(1.1)=C**2+DX**2
      E(1,2)=BK*C-AK*DX
      E(1,3) = -BJ*C+AJ*DX
      F(2,1)=F(1,2)
      F(2,2)=BK**2+\Delta K**2
      E(2,3) = -BJ*BK-AJ*AK
      F(3,1)=F(1,3)
      F(3,2)=F(2,3)
      E(3,3)=BJ**2+AJ**2
\boldsymbol{\mathsf{C}}
      KX(1)=K
      KX(2)=K+1
      IF (K-4) 145,140,145
  140 \text{ KX}(2)=1
  145 \text{ KX}(3) = 5
C
      DO 151 I=1.3
      II = K \times (I)
      DO 151 J=1.3
      JJ=KX(J)
  15] S([[,J])=S([[,J])+F([,J]*COMM
C
  152 CONTINUE
\mathsf{C}
      DO 155 I=1.4
      DO 155 J=1,4
  155 S(I,J)=S(I,J)-S(I,5)*S(J,5)/S(5,5)
\boldsymbol{C}
        3. ADD FLEMENT CONDUCTIVITY TO COMPLETE CONDUCTIVITY MATRIX
C
      VOL(N)=VOL(N) *SPHT(MTYPF)*DENS(MTYPF)*0.25
      DO 175 L=1,4
      I = LM(L)
      D(I)=D(I)+VOL(N)
      DO 175 M=1.4
      J=LM(M)-I+1
      TF (27-J) 157,158,158
  157 WRITE (6,2002) N
      GO TO 200
  158 [F(MRAND-J) 160,165,165
  160 MBAND=J
  165 IF(J) 175,175,170
  170 A(I,J)=A(I,J)+S(L,M)
  175 CONTINUE
\mathsf{C}
  200 CONTINUE
      IF(ISTOP.EQ.1) STOP
BOUNDARY CONDITIONS
C
```

```
IF(NCBH.EQ.A) GO TO 220
      DO 215 N=1,NCBH
      I = IC(N)
      J=JC(N)
      XL = SQRT((X(J) - X(I)) + + 2 + (Y(J) - Y(I)) + + 2)
      H=HC(N)*XL*0.25
      A(I_{\bullet}I) = A(I_{\bullet}I) + H
      A(J_{,1})=A(J_{,1})+H
      K = J - I + 1
      IF (K) 212,212,210
  210 A(I_{9}K)=A(I_{9}K)+H
      GO TO 215
  212 K=I-J+1
      A(J_{\bullet}K) = A(J_{\bullet}K) + H
  215 CL(N)=XL
  220 CONTINUE
C
C
      COOLING PIPES
C
      IF(NCPH.EQ.0) GO TO 225
      DO 224 N=1,NCPH
      I = IP(N)
      A(I,1) = A(I,1) + HP(N)
  224 B(I)=B(I)+HP(N)*TP(N)
  225 CONTINUE
\mathbf{C}
         TEMPERATURE BOUNDARY CONDITIONS
\boldsymbol{C}
      2.
C
      DO 300 N=1, NUMN
C
      IF(TT(N).EQ.0.0) GO TO 300
      DO 250 M=2.MBAND
      K=N-M+1
      IF(K) 235,235,230
  230 B(K)=B(K)-A(K,M)*TT(N)
      A(K_{\bullet}M) = 0.0
  235 L=N+M-1
      IF(NUMN-L) 245,240,240
  240 B(L)=B(L)-A(N,M)*TT(N)
  245 A(N,M)=0.0
  250 CONTINUE
      A(N,1)=1.0
      T(N) = TT(N)
  300 CONTINUE
C
C***
    SOLVE FOR NODAL POINT TEMPERATURES
C***********************
      FORM EFFECTIVE CONDUCTIVITY MATRIX FOR TIME INCREMENT
     DT2=1.0/DT
      DO 320 N=1, NUMN
      IF(A(N,1),FQ.0.0) A(N,1)=1.0
      IF(TT(N).NE.O.O) GO TO 320
```

```
D(N) = DT2*D(N)
      A(N,1) = A(N,1) + D(N)
  320 CONTINUE
      CALL SYMSOL(1)
C
      CALCULATE TEMPERATURE AT THE END OF EACH TIME INCREMENT
C
      LL=0
C
      DO 600 KK=1,NDT
\mathsf{C}
      DETERMINATION OF HEAT GENERATION
\boldsymbol{C}
      DO 395 N=1.NUME
      IF(PLTM(N).GT.TIME) GO TO 395
      MTYPE=IX(N,5)
      TX = TIME - PLTM(N)
      IF(TX.GF.HSTOP(MTYPF)) GO TO 395
      DO 385 L=1.NUMQC
       XZ=QX(L,1,MTYPF)-TX
       1F(XZ.GT.O.O) GO TO 386
  385 CONTINUE
  386 DIFF=QX(L,1,MTYPE)-QX(L-1,1,MTYPE)
       GRAD=(QX(L,2,MTYPE)-QX(L-1,2,MTYPE))/DIFF
       QQ=GRAD*VOL(N)
      DO 390 I=1,4
       TI = IX(N,T)
  390 Q(II) = Q(II) + QQ
  395 CONTINUE
C
       CONVECTION BOUNDARY CONDITION
C
C
       IF (NCBH. FQ. n) GO TO 410
       DO 400 N=1.NUMET
       XZ=ET(N,1)-TIME
       TF(XZ.GT.0.0) GO TO 401
  400 CONTINUE
  401 DIFF=FT(N,1)-ET(N-1,1)
       TFMP=FT(N,2)-((FT(N,2)-FT(N-1,2))*XZ)/DIFF
       DO 405 M=1, NCBH
       I = I \subset (M)
       J=JC(M)
       XZ=HC(M)*CL(M)*TEMP*0.5
       Q(I)=Q(I)+XZ
   405 Q(J)=Q(J)+XZ
   410 CONTINUE
C
        1. CALCULATE EFFECTIVE LOAD MATRIX
C
DO 450 I=1.NUMN
       Q(T) = Q(T) + P(T) + D(T) * T(T)
       JF(TT(I).NF.O.O) Q(I)=TT(I)
   450 CONTINUE
 C
        2. SOLVE FOR TEMPERATURES
 C
```

```
\mathsf{c}
      CALL SYMSOL(2)
\mathsf{C}
      DO 500 I=1 NUMN
      T(I)=Q(I)
  500 Q(I)=0.0
C
      TIME =TIME+DT
      LL=LL+1
      IF(LL-INTER) 600,550,550
  550 WRITE (6,2001) TIME, (N,T(N), N=1,NUMN)
      LL=n
\mathsf{C}
  600 CONTINUE
       RETURN
C
 2001 FORMAT (7HOT; MF = F14.6/(76,F14.6,76,F14.6,76,F14.6,76,F14.6,
     1 76,F14.6,16,F14.6))
 2002 FORMAT (23H BAND TOO LARGE-FL.NO.
                                              14)
 2003 FORMAT (34HOZERO OR NEGATIVE AREA ELEMENT NO. 15)
C
      END
```

```
SUBROUTINE SYMSOL (KKK)
\mathbf{C}
       COMMON /SYMARG/ NN, MM, A(500, 27), B(500)
C
       GO TO (1000,2000),KKK
C
       REDUCE MATRIX
C
 1000 DO 280 N=1,NN
       DO 260 L=2,MM
       C=A(N_*L)/A(N_*1)
       I = N+L-1
       IF(NN-I) 260,240,240
  240 J=0
       DO 250 K=L,MM
       J=J+1
  250 A(I,J)=A(I,J)-C*A(N,K)
  260 A(N,L)=C
  280 CONTINUE
       GO TO 500
\boldsymbol{\mathsf{C}}
C
       REDUCE VECTOR
C
 2000 DO 290 N=1,NN
       DO 285 L=2,MM
       I=N+L-1
       IF(NN-I) 290,285,285
  285 B(1)=B(1)-A(N+L)*B(N)
  290 B(N)=B(N)/A(N+1)
C
       BACK SUBSTITUTION
\mathsf{C}
\mathbf{C}
       N = NN
   300 N = N-1
       IF(N) 350,500,350
   350 DO 400 K=2.MM
       L = N+K-1
       IF(NN-L) 400,370,370
   370 B(N) = B(N) - A(N,K) * B(L)
   4nn CONTINUE
       GO TO 300
C
   500 RETURN
C
       END
```