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## **Title**

Krobohand: A 3D Printed Robotic Prosthetic Hand

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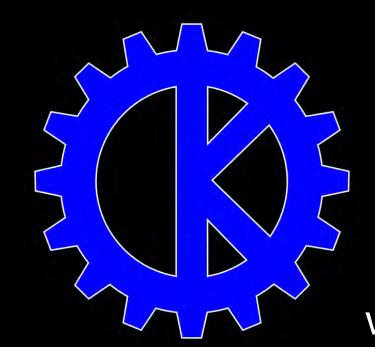
## **Authors**

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## **Publication Date**

2017-03-15

Peer reviewed



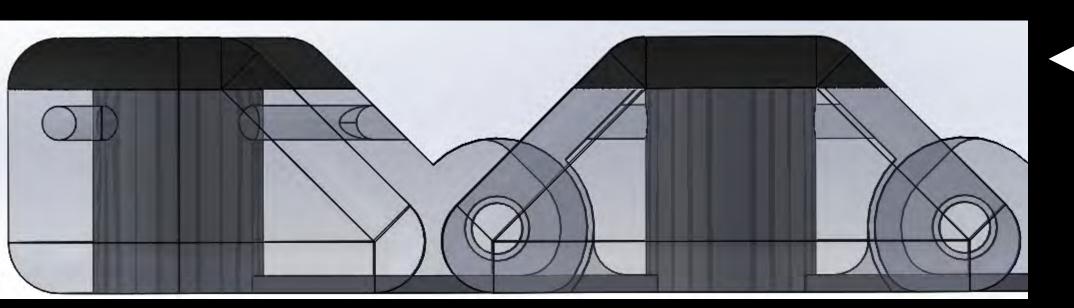
# Krobohand

School of Engineering

www.krobotech.com

A 3D Printed, Robotic Prosthetic Hand

gap in the upper limb prosthetic industry between cost and functionality of a prosthetic.



Joint Detail

- Side profile showing flexible tendon, grips, and core.

3-Point Flexural Test

## Design

Krobohand is both cost effective, as well as functionally viable. Fabrication techniques, as well as unique designs yield an innovative upper limb prosthetic.

## Innovation

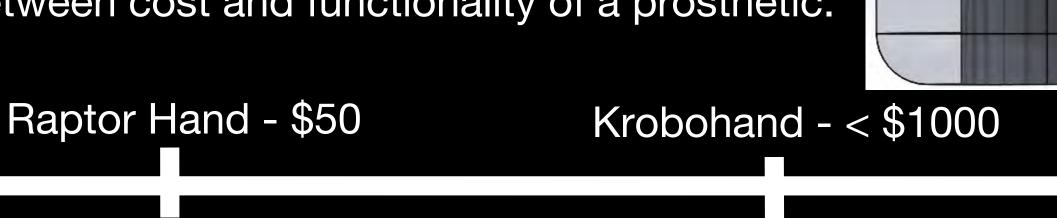
- 1.) Fully 3D Printed Joints, Lateral Joints.
- 2.) Flexible tendon as a stabilizing, restoring force, like the extensor tendon of a human.
- 3.) Grip on palm side printed from same material as the flexible tendon, finger pads.
- 4.) Electromyography for connection between prosthesis and amputee, to be non-invasive.

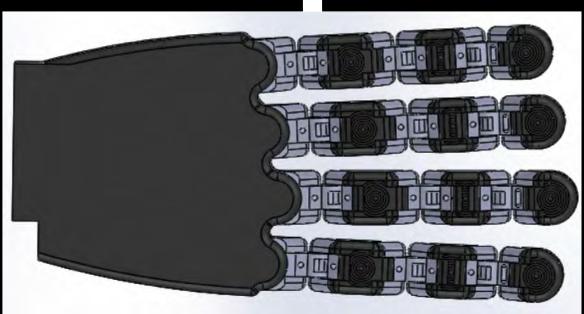
# Structural Testing

- 1.) Tensile Test Avg. F before failure: 0.38kN or 85 lbf., 31.75mm (1.25in.) ext.
- 2.) 3-Point Flexural Test Avg. F before failure: 0.83kN or ~180 lbf.

# Background

The Krobohand group recognized a significant







Split Hook - \$10,000



Tensile Test



# Goal

Bridge the gap in the upper limb prosthesis industry between cost and functionality.

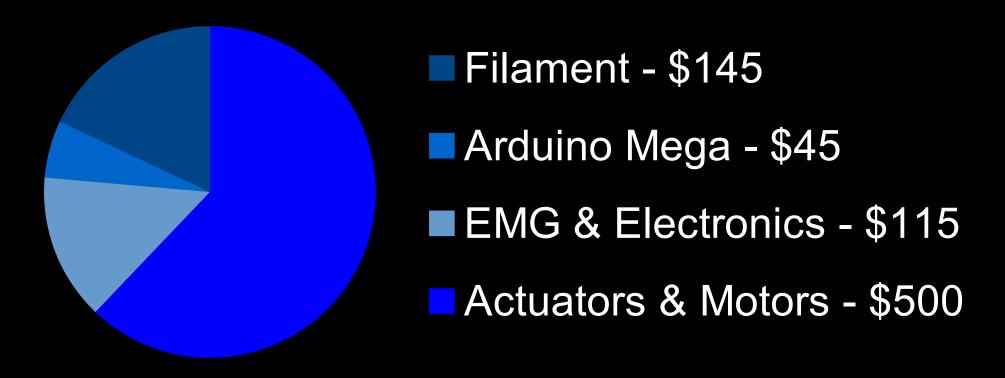
# Objectives

- 1.) Fabrication with dual material 3D Printing.
- 2.) Streamline process of connectivity between electromyographic sensors and amputee.
- 3.) Create a sleek, clean, and recognizable upper limb prosthesis.

# Electromyography

- 1.) MyoWare sensor connected to existing muscle groups.
- 2.) Signal interpreted by Arduino microcontroller (Uno or Mega), actuates motor.

# Budget: < \$1000 Total Cost







# The Team

- Ethan Kirkley
- Cameron Hunt
- Zepyoor Khechadoorian Kevin Wong
- Advisor: Dr. Reinkensmeyer