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Bulk-solvent and overall scaling revisited: faster calculations, improved results. Corrigendum.

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Equations in Sections 2.3 and 2.4 of the article by Afonine *et al.* [Acta Cryst. (2013). D**69**, 625–634] are corrected.

In the article by Afonine *et al.* (2013) some improper notations and errors in several equations in Sections 2.3 and 2.4 have been corrected. We note that the *Computational Crystallography Toolbox* (Grosse-Kunstleve *et al.*, 2002) has been using the correct version of these equations since 2013. Updated versions of Section 2.3 and equations (42), (43) and (45) are given below.

2.3. Bulk-solvent parameters and overall isotropic scaling

Assuming the resolution-dependent scale factors $k_{\rm mask}(\mathbf{s})$ and $k_{\rm isotropic}(\mathbf{s})$ to be constants $k_{\rm mask}$ and $k_{\rm isotropic}$ in each thin resolution shell, the determination of their values is reduced to minimizing the residual

$$\sum_{\mathbf{s}} \{ |\mathbf{F}_{\text{calc}}(\mathbf{s}) + k_{\text{mask}} \mathbf{F}_{\text{mask}}(\mathbf{s}) |^{2} - [k_{\text{overall}} k_{\text{anisotropic}}(\mathbf{s}) k_{\text{isotropic}}]^{-2} F_{\text{obs}}^{2}(\mathbf{s}) \}^{2}, \quad (22)$$

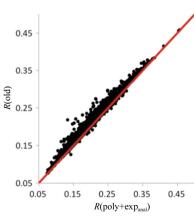
where the sum is calculated over all reflections \mathbf{s} in the given resolution shell, and k_{overall} and $k_{\text{anisotropic}}(\mathbf{s})$ are calculated previously and fixed. This minimization problem is generally highly over-determined because the number of reflections per shell is usually much larger than two.

Introducing $w_{\mathbf{s}} = |\mathbf{F}_{\text{mask}}(\mathbf{s})|^2$, $v_{\mathbf{s}} = \frac{1}{2} [\mathbf{F}_{\text{calc}}(\mathbf{s}) \mathbf{F}_{\text{mask}}^*(\mathbf{s}) + \mathbf{F}_{\text{calc}}^*(\mathbf{s}) \mathbf{F}_{\text{mask}}(\mathbf{s})]$, $u_{\mathbf{s}} = |\mathbf{F}_{\text{calc}}(\mathbf{s})|^2$, $I_{\mathbf{s}} = [k_{\text{overall}} k_{\text{anisotropic}}(\mathbf{s})]^{-2} F_{\text{obs}}^2(\mathbf{s})$ and $K = k_{\text{isotropic}}^{-2}$ and substituting them into (22) leads to the minimization of

$$LS(K, k_{\text{mask}}) = \sum_{s} [(k_{\text{mask}}^2 w_s + 2k_{\text{mask}} v_s + u_s) - KI_s]^2$$
 (23)

with respect to K and $k_{\rm mask}$. This leads to a system of two equations:

$$\begin{cases} \frac{\partial}{\partial K} \mathrm{LS}(K, k_{\mathrm{mask}}) = -2 \sum_{\mathbf{s}} [(k_{\mathrm{mask}}^2 w_{\mathbf{s}} + 2k_{\mathrm{mask}} v_{\mathbf{s}} + u_{\mathbf{s}}) - KI_{\mathbf{s}}]I_{\mathbf{s}} \\ = 0, \\ \frac{\partial}{\partial k_{\mathrm{mask}}} \mathrm{LS}(K, k_{\mathrm{mask}}) = 4 \sum_{\mathbf{s}} [(k_{\mathrm{mask}}^2 w_{\mathbf{s}} + 2k_{\mathrm{mask}} v_{\mathbf{s}} + u_{\mathbf{s}}) - KI_{\mathbf{s}}] \\ \times (k_{\mathrm{mask}} w_{\mathbf{s}} + v_{\mathbf{s}}) \\ = 0. \end{cases}$$





Developing these equations with respect to k_{mask}

$$\begin{cases} k_{\text{mask}}^{2} \sum_{\mathbf{s}} w_{\mathbf{s}} I_{\mathbf{s}} + 2k_{\text{mask}} \sum_{\mathbf{s}} v_{\mathbf{s}} I_{\mathbf{s}} + \sum_{\mathbf{s}} u_{\mathbf{s}} I_{\mathbf{s}} - K \sum_{\mathbf{s}} I_{\mathbf{s}}^{2} = 0, \\ k_{\text{mask}}^{3} \sum_{\mathbf{s}} w_{\mathbf{s}}^{2} + 3k_{\text{mask}}^{2} \sum_{\mathbf{s}} w_{\mathbf{s}} v_{\mathbf{s}} + k_{\text{mask}} \sum_{\mathbf{s}} (2v_{\mathbf{s}}^{2} + u_{\mathbf{s}} w_{\mathbf{s}} - K I_{\mathbf{s}} w_{\mathbf{s}}) \\ + \sum_{\mathbf{s}} u_{\mathbf{s}} v_{\mathbf{s}} - K \sum_{\mathbf{s}} I_{\mathbf{s}} v_{\mathbf{s}} = 0, \end{cases}$$

$$(25)$$

and introducing new notations for the coefficients, we obtain

$$\begin{cases} k_{\text{mask}}^2 C_2 + k_{\text{mask}} B_2 + A_2 - KY_2 = 0, \\ k_{\text{mask}}^3 D_3 + k_{\text{mask}}^2 C_3 + k_{\text{mask}} (B_3 - KC_2) + A_3 - KY_3 = 0. \end{cases}$$
(26)

Multiplying the second equation by Y_2 and substituting KY_2 from the first equation into the new second equation, we obtain a cubic equation with fixed coefficients

$$\begin{aligned} k_{\text{mask}}^{3}(D_{3}Y_{2}-C_{2}^{2}) + k_{\text{mask}}^{2}(C_{3}Y_{2}-C_{2}B_{2}-C_{2}Y_{3}) \\ + k_{\text{mask}}(B_{3}Y_{2}-C_{2}A_{2}-Y_{3}B_{2}) + (A_{3}Y_{2}-Y_{3}A_{2}) = 0. \end{aligned} (27)$$

The senior coefficient in equation (27) satisfies the Cauchy-Schwarz inequality:

$$D_3 Y_2 - C_2^2 = \sum_{s} w_s^2 \sum_{s} I_s^2 - \sum_{s} w_s I_s \sum_{s} w_s I_s > 0.$$
 (28)

Therefore, equation (27) can be rewritten as

$$k_{\text{mask}}^3 + ak_{\text{mask}}^2 + bk_{\text{mask}} + c = 0 (29)$$

and solved using a standard procedure.

The corresponding values of K are obtained by substituting the roots of equation (29) into the first equation in equation (26),

$$K = (k_{\text{mask}}^2 C_2 + k_{\text{mask}} B_2 + A_2) / Y_2.$$
 (30)

If no positive root exists, $k_{\rm mask}$ is assigned a zero value, which implies the absence of a bulk-solvent contribution. If several roots with $k_{\rm mask} \geq 0$ exist then the one that gives the smallest value of ${\rm LS}(K,k_{\rm mask})$ is selected.

If desired, one can fit the right-hand side of expression (10) to the array of k_{mask} values by minimizing the residual

$$\sum_{s} [k_{\text{mask}} - k_{\text{sol}} \exp(-B_{\text{sol}} s^2 / 4)]^2$$
 (31)

for all $k_{\rm mask} > 0$. This can be achieved analytically as described in Appendix A. Similarly, one can fit $k_{\rm overall} \exp(-B_{\rm overall} \, s^2/4)$ to the array of K values.

Equations (42), (43) and (45) in Section 2.4 of Afonine *et al.* (2013) are also updated as follows

$$\mathbf{b} = \left[\sum_{\mathbf{s}} I(\mathbf{s})I_1(\mathbf{s}_1), \dots, \sum_{\mathbf{s}} I(\mathbf{s})I_N(\mathbf{s}_N), 1\right]^t, \tag{42}$$

$$LS(K, k_{\text{mask}}) = \sum_{\mathbf{s}} \left\{ \left[\sum_{j=1}^{N} \alpha_j |\mathbf{F}_{\text{calc}}(\mathbf{s}_j) + k_{\text{mask}} \mathbf{F}_{\text{mask}}(\mathbf{s}_j)|^2 \right] - KI_{\mathbf{s}} \right\}^2,$$
(43)

$$LS(K, k_{\text{mask}}) = \sum_{s} \left[(k_{\text{mask}}^2 w_s + 2k_{\text{mask}} v_s + u_s) - KI_s \right]^2. \quad (45)$$

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