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Title

SYS7: CENS Systems-Infrastructure Overview

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Systems Infrastructure Overview

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Introduction: Sensor network applications development/deployment is complex

Effective ENS requires end-to-end systems

- Sensor, sensor host, gateway, database, user interface
 - some COTS, some research, some reusable, some missing
- Development requirements different from deployment needs
- More complex than domain scientist is prepared to construct

Need to explore what's needed, what's not

- What software is common to all/most/some/few domains?
- What is reusable from previous distributed systems work?
- What is unique to embedded networked sensing?
 - What deployment management tools are required?

Accomplishments: Significant development/deployment in three domains + core foundation

Seismic

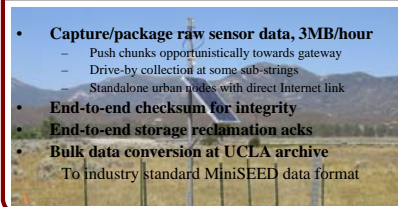
Task: Streaming Seismic Data in Hostile Long-haul Wireless Settings



Problem Description: End-to-end protocols are unsuitable for partially operable network

- String of 50 hard-to-access sensor stations
- Long-haul (5-15km) 802.11b links
 - Weather; forest; RF noise
- Limited power at each station
 - 10 days' worth of battery (+ solar)
- Limited per-station storage capacity
 - 40 station-days available

Solution: Hop-by-hop transport with end-to-end acks



- Capture/package raw sensor data, 3MB/hour
 - Push chunks opportunistically towards gateway
 - Drive-by collection at some sub-strings
 - Standalone urban nodes with direct Internet link
- End-to-end checksum for integrity
- End-to-end storage reclamation acks
- Bulk data conversion at UCLA archive
 - To industry standard MiniSEED data format

Micro-Climate

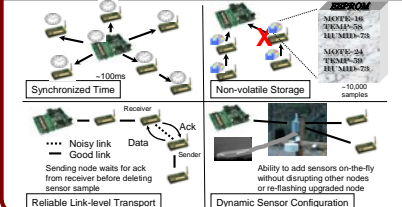
Task: Deploy several micro-climate/habitat embedded sensor networks



Problem Description: Prototype deployments showed need for enhanced disconnected behavior & flexible sensor configuration

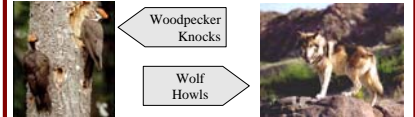
- Poor/no wireless connectivity is common, not rare
 - Can exist for extended periods (hours, days)
- Need sensor nodes to store many data samples
 - But have limited RAM; no useful concept of time
- Initial data results can motivate rearrangement of sensors, or additional sensors
 - Including new prototype sensors from sensor groups

Solution: Enhanced time, storage, transport, configuration svcs



Acoustic

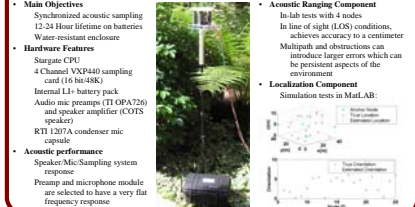
Task: Passive acoustic monitoring applications



Problem Description: Self-localization, self-calibration needed for collaborative acoustic monitoring

- Precise synchronization across sampled channels
 - Required for accurate direction of arrival (DOA)
- Acoustic localization system
 - Based on time of flight (TOF) of acoustic signals
- 3-D localization/orientation of microphone arrays
 - Required for 3-D target localization via bearing-crossing
 - Hard to obtain/maintain in field; bumping implies re-localization

Solution: Acoustic ENSBox: portable acoustic monitoring box



- Main Objectives
 - Synchronized acoustic sampling
 - 12-24 Hour lifetime on batteries
 - Water resistant enclosure
- Hardware Features
 - Sargate CPU
 - 4 Channel VXP440 sampling card (16 bit/48K)
 - Internal Li+ battery pack
 - Audio mix preamps (TI OPA726) and speaker amplifier (COTS speaker)
 - KTH 1207A condenser mic capsule
- Acoustic performance
 - Speaker/Mic/Sampling system response
 - Preamp and microphone module are selected to have a very flat frequency response
- Acoustic Ranging Component
 - In-lab tests with 4 nodes
 - In line of sight (LOS) conditions, achieves accuracy to a centimeter
 - Multipath and obstructions can introduce larger errors which can be persistent aspects of the environment
- Localization Component
 - Simulation tests in Matlab

Emstar

The Need: A software framework for design, development, deployment, and operation of heterogeneous ESNs

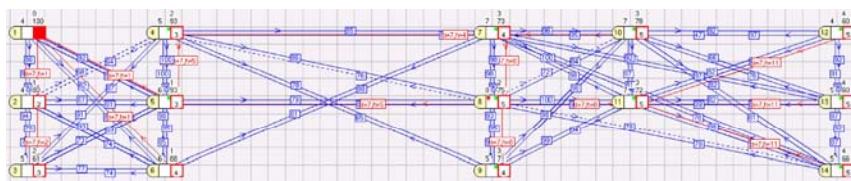
- Sensor network software tends to be monolithic
 - Need more component re-usability, without inflexible layered stack
- Sensor network systems tend to be language-specific
 - Difficult to leverage components from other ENS software systems
 - Integration of binary images not generally supported
- Sensor networks are notoriously invisible
 - Very difficult to 'see' inside an operational in-situ ESN

The Solution: The Emstar family of extensible/reusable tools, services, and libraries

- Tools (simulation, emulation, visibility)
 - EmSim/EmCee, EmRun, EmView/EmProxy
- Services (network, time, IPC,
 - Link/neighborhood estimation; time synchronization; routing; IPC device abstractions; HostMote/MoteNIC
- Libraries
 - General purpose utility routines; domain-specific routines

Status: Emstar is maturing from a single-lab tool, to a widely-adopted development environment.

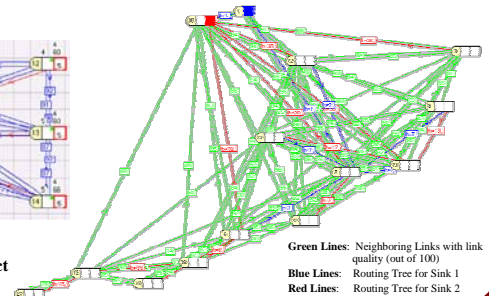
- Used by >100 active users (support list e-mail)
 - 21 universities, 11 companies, 11 countries, 5 continents
 - > 1,000 downloads April 1-June 15, 2005
- Major effort to improve documentation
 - Better how-to documents, tutorials, class materials
- Workshops at UCLA, ESN conferences
 - CS113; EE206; NSF u-grad internships; SECON05



Visualization tools examples

Can easily collect node-by-node data of various metrics
Can easily display in 2-D graphical form the ESN layout/metrics

Above: display of Boelter Hall ceiling testbed
Right: James Reserve systems research transect



Green Lines: Neighboring Links with link quality (out of 100)
Blue Lines: Routing Tree for Sink 1
Red Lines: Routing Tree for Sink 2