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SYS 3: Cyclops A Reconfigurable Low-power Platform for Distributed Image Sensing

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Cyclops: A Reconfigurable Low-power Platform for Distributed Image Sensing

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Distributed Image Sensing and Interpretation

Why Vision

- Vision as Sensing
- **Strong Modality to Disambiguate the Environment** Context, texture, Shape or change in Algori shape, Presence or absence, Displacement, Interaction, Color

Why Distributed •A Difficult Problem Reduces to Many Simpler Problems

- Multiple Views, Multiple Observations, Closer distances

- Avoid distance and scaling problems - Stronger Association of Objects with Cameras
- CMOS technology is cheap and low power
- -Integration Imaging and Computation

Why It is Important

Many Applications

Smart Environments, Traffic Monitoring, Activity Measurement, Security and Intrusion Detection, Precision Agriculture



Cyclops: A Reconfigurable Low Power Image Sensor



Cyclops

•Dedicated Computation, Low Power Frame Grabber, Memory and CMOS Imager •Sensor Device for Conventional Sensor Network Nodes such as Mote

 Custom Sensing through Reconfigurable Computing

Many Sensing Experiments have been Pursued



Research Direction

Coverage of a Network of Cyclops

•Given a bounded domain and partial knowledge of occlusions, find an optimal placement of camera nodes.

-NP-complete - related to Art Gallery Problem





Tiered Image Sensing Network

•A Cyclops Network

-Runs the Image Sensing Functionality through Declarative Query -Subnets of Cyclops at Different Frequencies

-High Speed Back Bone System





Dynamic Reconfiguration

- •Update Image Processing After Deployment
- -Respond to Environmental Variation (i.e. Change in luminance), Time -Update the Computation by Learning from the Data
- •Customize Computation by Configuring Image Processing Modules -SOS operating system
 - -Loadable Modules Encapsulate Image Processing Libraries



Actuated Network

- •Actuated Cyclops Network -Self Calibration of Camera Models,
 - -Self Configuration

Tiered Actuated Vision System



-Exploit Low Resolution Cameras to Locate Object in 3Dimensional Space Using Stereoscopy

-High Precision Pan-Tilt Camera for Object Recognition and Recording



Energy Optimized Function Evaluation

•Optimize Evaluation Performance vs. Power Consumption

-Depends on the Architecture of Processor

Simulation and Emulation Environment PP

- •Easy Configuration of the Imagers
- •Large Scale Data Collection
 - -Simulation vs. Scenarios (Collected Data)

Vision Network Deployment

•James San Jacinto Mountains Reserve •Micro-servers (4)

Nest Boxes (15)

-Occupancy, Territory, Egg Laying, Nest Building clutching or Hatching



-Reptile Size, Statistics, Activity vs. Environmental factors, Time

